-NOTES-

ON A SPECIAL BOLZA VARIATIONAL PROBLEM, AND THE MINIMIZATION OF SUPERAERODYNAMIC HYPERSONIC NOSE DRAG*

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Instead of a definite integral, let the following expression be given:

$$D = G(y_0, y_l) + \int_0^l F(y, y', x) dx, \qquad (1)$$

where G is a known function of y_0 and y_t , y_0 and y_t may or may not be specified. It is desired to find the optimum function y(x) that minimizes expression (1). This is a special case of the Bolza problem [1].

The variation of (1) is easily obtained as follows:

$$\delta D = D(y^*) - D(y)$$

$$= G_{v_0} \delta y_0 + G_{v_1} \delta y_1 + [F_{v'} \delta y]_0^t + \int_0^t [F_v - (F_{v'})'] \delta y \, dx \qquad (2)$$

$$= [G_{v_0} - (F_{v'})_0] \delta y_0 + [G_{v_1} + (F_{v'})_t] \delta y_t + \int_0^t [F_v - (F_{v'})'] \delta y \, dx.$$

To insure vanishing of δD , it is clear that:

(i) throughout the interval 0 < x < l, Euler's variational equation must be satisfied:

$$\varphi = (F_{\nu'})' - F_{\nu} = 0 \tag{3}$$

(ii) at both ends of the interval, the following end conditions must be met:

$$\delta y_0 = 0$$
, or $\psi_0 = G_{\nu_0} - (F_{\nu'})_0 = 0$,
 $\delta y_l = 0$, or $\psi_l = G_{\nu_l} + (F_{\nu'})_l = 0$. (4)

The condition of minimization is then furnished by

(iii) the Legendre second variational inequality:

$$F_{y'y'} > 0, \qquad 0 < x < l.$$
 (5)

Our generalization evidently lies in the inclusion of G term outside the integral, and the corresponding broadened end conditions (4). Indeed, if G is constant, or disappears from (1), then the end conditions simply reduce to the following conventional form for calculus of variations [2, 3, 4], i.e.

$$\delta y_0 = 0, \text{ or } (F_{\nu'})_0 = 0,$$

$$\delta y_l = 0, \text{ or } (F_{\nu'})_l = 0.$$
(6)

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In case

$$G(y_0, y_l) = \int_{0-}^{0+} F(y, y', x) dx + \int_{1-}^{1+} F(y, y', x) dx,$$

(1) reduces to following single integral:

$$D = \int_{0^{-}}^{t^{+}} F(y, y', x) dx \tag{7}$$

which is, on the one hand, an immediate extension of the ordinary calculus of variations to include Stieltjes integral at the ends; and on the other hand, a special case of our present formulation.

The present generalization of the variational problem has, in fact, arisen as a result of the search for optimum nose curve that minimizes the superaerodynamic hypersonic drag of an axially symmetric body. The problem is usually so formulated that the nose length l and base radius y_l are both given, while the tip radius y_0 may or may not be specified, depending on the situation. By using meridianial coordinates, x axial and y radial, the nose drag has been shown to be given by following integral [5]:

$$D = 2\pi\rho V^2 \int_{0^-}^{t} \{1 + cy'(1 + y'^2)^{-1/2}]yy' dx$$

$$= \pi\rho V^2 \Big\{ y_i^2 + c \Big[y_0^2 + 2 \int_{0}^{t} yy'(1 + y'^2)^{-1/2} dx \Big] \Big\},$$
(8)

where c is a constant determined by the ratios of solid surface and gas temperature, and of body and molecular speed. It is easy to see that this drag formula is indeed of type (1), with

$$G = y_0^2 + (y_1^2/c), F = 2yy'(1 + y'^2)^{-1/2}$$
 (9)

and end conditions:

$$\delta y_i = 0$$

$$\delta y_0 = 0, \text{ or } \psi_0 = G_{\nu_0} - (F_{\nu'})_0 = 0.$$
(10)

As already pointed out, an optimum solution must be that of Euler's variational equation, which, by putting (9) into (3), takes the following form:

$$y'' = -y'^{2}(1 + y'^{2})/y(2 - y'^{2}).$$
 (11)

Its solution, in parametric form, has been obtained, by simple quadrature and use of relations y'' = y'dy'/dy and y'' = dy'/dx, as follows [6]:

$$y = c_1 (1 + y'^2)^{3/2} / y'^2,$$

$$x = \frac{c_1}{3} \left\{ \frac{2(1 + y'^2)^{1/2}}{y'^3} - \frac{(1 + y'^2)^{1/2}}{y'} + 3 \ln \left[(1 + y'^2)^{1/2} + y' \right] \right\} + c_2.$$
(12)

On putting (9) into (5), the second variational inequality then requires:

$$F_{y'y'} = 2 - y'^2 > 0$$
, i.e. $y' < (2)^{1/2}$ (13)

Differential equation (11) shows there are two branch curves merging at cuspidal

point $y' = (2)^{1/2}$; solution (12) shows that the axis y = 0 can not be reached, and y grows indefinitely both as y' approaches zero and infinity. The correct branch of curve is thus specified by requirement (13) which, together with (12), imposes the following limitations on the admissible values of y':

$$0 < y' < (2)^{1/2}, \quad y'' < 0.$$
 (14)

Now the tip condition $\psi_0 \delta y_0 = 0$ becomes:

(i) For specified y_0 : $\delta y_0 = 0$. In this case, in view of the limitations on the admissible values of y', it is evident that with prescribed nose length l and base radius y_l , there is a lower bound for admissible tip radius y_0 , below which no solution exists. Within its admissible range, it is easy to see that specification of x_0 , y_0 , x_l , y_l , uniquely determines the four unknowns C_1 , C_2 , y'_0 and y'_l , by the four independent equations from parametric solution (12).

(ii) For unspecified y_0 :

$$\psi_0 = G_{y_0} - (F_{y'})_0 = y_0[1 - y_0'(2 + y_0'^2)(1 + y_0'^2)^{-3/2}] = 0.$$
 (15)

Although it is easy to see that both $y_0 = 0$ and $y'_0 = \infty$ are solutions of (15), neither of them can be fulfilled by our solution (12), with finite l and non-vanishing y_l . However, a plot of ψ_0 against y'_0 (Fig. 1) shows that the curve crosses axis $\psi_0 = 0$ at $y'_0 = 0.7862 < (2)^{1/2}$ Thus, with unspecified y_0 , y'_0 can be determined through condition (15). Actual construction of the optimum curve then amounts to specifying x_0 , x_l , y'_0 (through $\psi_0 = 0$), and y_l , from which four unknowns y_0 , y'_l , C_1 , C_2 , are determined by four independent equations from parametric solution (12).

It is interesting to note that in this case y_0 corresponding to $y'_0 = 0.7862$ is usually greater than the least admissible value of y_0 which corresponds to $y'_0 = (2)^{1/2}$. This implies that with a given finite nose length l, reducing the tip radius beyond y_0 corresponding to $y'_0 = 0.7862$ actually has an adverse effect. To see this point, it is best to

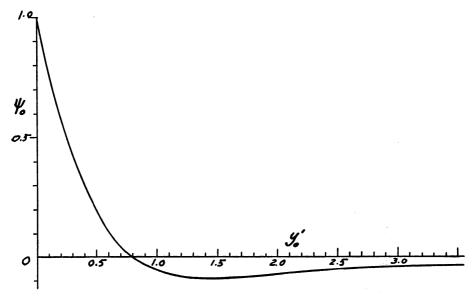


Fig. 1.

refer to Fig. 1, which shows clearly that both for $y_0(y_0')$ greater and smaller than y_0 (.7862), we will have $\psi_0 \delta y_0 > 0$, i.e., $\delta D > 0$.

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NOTE ON THE SOLUTION OF THE NEUTRON DIFFUSION PROBLEM BY AN IMPLICIT NUMERICAL METHOD*

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It is of interest that the implicit, numerical method of Baker and Oliphant [1, 2] for the solution of time-dependent heat-flow problems in rectangular regions may be usefully extended to obtain the solution of the time-independent neutron-diffusion equation

$$\nabla D(r)\nabla\varphi - \chi(r)\varphi + S(r) = 0 \tag{1}$$

for the neutron density φ . In the original work of [1], to obtain an accurate solution, even asymptotically, it was necessary to take Δt small. This choice was necessary because of the occurrence of a term in a higher order space derivative multiplied by Δt . We will herein make a slight modification to remove this defect. Let us rewrite (1) as (for the two-dimensional case)

$$\beta\varphi + \nabla^{2}\varphi + \frac{1}{\beta} \frac{\partial^{4}\varphi}{\partial x^{2} \partial y^{2}} = \alpha^{-2} \frac{\partial\varphi}{\partial t} + \beta\varphi + \frac{1}{\beta} \frac{\partial^{4}\varphi^{*}}{\partial x^{2} \partial y^{2}} + \left(\frac{\chi(r)}{D(r)} - \mu\right)\varphi^{*} + \mu\varphi - \frac{S(r)}{D(r)} + \frac{\nabla D \cdot \nabla\varphi^{*}}{D(r)},$$
(2)

where

$$\varphi = \varphi^*, \qquad \frac{\partial \varphi}{\partial t} = 0,$$
 (3)

and

$$\mu = \min_{r} \left[\chi(r) / D(r) \right]. \tag{4}$$

To obtain the solution of (1) via (2) and (3) we must advance the time until the asymptotic solution of (2) is obtained. In [1], we described for the special case, D, a constant, how to guess φ^* , and then use (2) to calculate φ_{cal} . by solving the left-hand side and then how to compute a new guess, φ^{**} , by means of

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