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MONOTONIC DECAY OF SOLUTIONS OF PARABOLIC EQUATIONS WITH NONLOCAL BOUNDARY CONDITIONS*

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1. Introduction. In recent papers [3, 4] Day considered parabolic equations in one space dimension with boundary conditions

$$u(-a,t) = \int_{-a}^{a} f(x)u(x,t) \, dx, \qquad u(a,t) = \int_{-a}^{a} g(x)u(x,t) \, dx.$$

The solution u represents the entropy in a quasi-static theory of thermoelasticity; for a derivation of the model see [1, 2]. Day proved that if

$$\int_{-a}^{a} |f(x)| \, dx < 1, \qquad \int_{-a}^{a} |g(x)| \, dx < 1, \tag{1.1}$$

then the maximum modulus of the entropy is decreasing in time, that is,

$$U(t) = \max_{-a \leqslant x \leqslant a} |u(x,t)|$$
(1.2)

is decreasing in t. An example in [4] shows that if both inequalities in (1.1) are reversed, then, in general, U(t) may increase exponentially with t.

The proof of (1.2) is based on estimating integrals of the form $\int_{-a}^{a} P(x)u^{2m}(x,t) dx$ with suitably chosen P(x).

In this paper we extend the assertion (1.2) to general parabolic equations (in *n* dimensions) using a different and more general method based on the maximum principle. We also show that $U(t) \rightarrow 0$ exponentially fast as $t \rightarrow \infty$. Finally, we establish the strict monotonicity of U(t) for all t > 0; this implies, in particular, that U(t) does not vanish in finite time. For completeness we also prove the existence and uniqueness of u(x, t).

2. U(t) is decreasing. Let

$$A \equiv \sum_{i,j=1}^{n} a_{ij}(x) \frac{\partial^2}{\partial x_i \partial x_j} + \sum_{i=1}^{n} b_i(x) \frac{\partial}{\partial x_i} + c(x)$$

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be a uniformly elliptic operator in a bounded domain Ω in \mathbb{R}^n , that is,

$$\sum a_{ij}(x)\xi_i\xi_j \ge \mu |\xi|^2, \quad x \in \Omega, \, \xi \in \mathbf{R}^n,$$
(2.1)

where μ is a positive constant, and assume that, for some $0 < \alpha < 1$,

$$a_{ij}, b_i, c$$
 belong to $C^{\alpha}(\overline{\Omega}),$ (2.2)

$$c(x) \le 0, \tag{2.3}$$

for every
$$x \in \partial \Omega$$
 there exists a barrier for A; (2.4)

the last condition is satisfied if, for instance, $\partial \Omega$ is in C^2 or if Ω is convex.

Let f(x, y) be a continuous function defined for $x \in \partial \Omega$, $y \in \overline{\Omega}$, and assume that

$$\theta(x) \equiv \int_{\Omega} |f(x, y)| \, dy \leq \rho < 1 \quad \forall x \in \partial\Omega.$$
(2.5)

For any $0 < T \leq \infty$ set

$$\Omega_T = \Omega \times \{ 0 < t < T \}.$$

Consider the parabolic problem:

$$\frac{\partial u}{\partial t} - Au = 0 \quad \text{in } \Omega_{\infty}, \tag{2.6}$$

$$u(x,0) = u_0(x) \text{ if } x \in \Omega,$$
 (2.7)

$$u(x, y) = \int_{\Omega} f(x, y) u(y, t) \, dy \quad \text{if } x \in \partial\Omega, \, 0 < t < \infty,$$
(2.8)

where the initial data u_0 satisfies

$$u_0 \neq 0, \quad u_0 \in C(\overline{\Omega}). \tag{2.9}$$

THEOREM 2.1. There exists a unique solution u of (2.6)–(2.8) such that $u \in C(\overline{\Omega}_{\infty})$.

Proof. It suffices to prove existence and uniqueness in Ω_T , for any $T < \infty$. Define a sequence $u_m(x, t)$ inductively as follows: (i) $u_0(x, t) \equiv u_0(x)$; (ii) given u_m , let

$$\tilde{u}_{m+1}(x,t) = \int_{\Omega} f(x,y) u_m(y,t) \, dy \quad (x \in \partial \Omega)$$

and let u_{m+1} be the solution of

$$\left(\frac{\partial}{\partial t} - A\right)u_{m+1} = 0 \quad \text{in } \Omega_T,$$
$$u_{m+1} = \tilde{u}_{m+1} \quad \text{on } \partial\Omega \times (0, T),$$
$$u_{m+1}(x, 0) = u_0(x) \quad \text{if } x \in \Omega.$$

Conditions (2.1)–(2.4) ensure that u_{m+1} exists and is continuous in $\overline{\Omega}_T$ (provided the same is true of u_m). Further, since

$$\left(\frac{\partial}{\partial t} - A\right) (u_{m+1} - u_m) = 0 \quad \text{in } \Omega_T,$$

$$(u_{m+1} - u_m)(x, 0) = 0 \quad \text{if } x \in \Omega,$$

the maximum principle [5, Chapter 2] gives

$$\sup_{\Omega_{T}} |u_{m+1}(x,t) - u_{m}(x,t)| = \sup_{\substack{x \in \partial \Omega \\ 0 \le t \le T}} \left| \int_{\Omega} f(x,y) (u_{m}(y,t) - u_{m-1}(y,t)) \, dy \right| \\ \le \rho \sup_{\Omega_{T}} |u_{m} - u_{m-1}|, \qquad (2.10)$$

or

$$\sup_{\Omega_{T}} |u_{m+1} - u_{m}| \leq C\rho^{m} \quad \left(C = \sup_{\Omega_{T}} |u_{1} - u_{0}|\right)$$

It follows that $\{u_m\}$ is a uniform Cauchy sequence and, by standard theory [5], $u \equiv \lim u_m$ is the solution of (2.6)-(2.8).

Finally, if v is another solution then [cf. (2.10)]

$$\sup_{\Omega_T} |v-y| \leq \rho \sup_{\Omega_T} |v-u|,$$

giving $v \equiv u$.

Set

$$U(t) = \max_{x \in \overline{\Omega}} |u(x, t)|.$$
(2.11)

THEOREM 2.2. The function U(t) is monotone decreasing in t.

Proof. If the assertion is not true then there exists a $t_0 > 0$ and sequences of positive numbers $\varepsilon_m \downarrow 0$, $\delta_m \downarrow 0$ such that

$$\delta_m + \max_{x \in \overline{\Omega}} |u(x, t_0)| < \max_{x \in \overline{\Omega}} |u(x, t_0 + \varepsilon_m)|.$$
(2.12)

Without loss of generality we may assume that

$$\max_{x\in\overline{\Omega}}|u(x,t_0+\varepsilon_m)| = \max_{x\in\overline{\Omega}}u(x,t_0+\varepsilon_m) \ge -\min_{x\in\overline{\Omega}}u(x,t_0+\varepsilon_m).$$
(2.13)

Choose $x_m \in \Omega$ such that

$$u(x_m, t_0 + \varepsilon_m) > \max_{x \in \overline{\Omega}} u(x, t_0 + \varepsilon_m) - \delta_m.$$

Then, by (2.12)

$$u(x_m, t_0 + \varepsilon_m) > \max_{x \in \overline{\Omega}} |u(x, t_0)|.$$
(2.14)

Applying the strong maximum principle to u in $\Omega \times (t_0, t_0 + \varepsilon_m)$ and using (2.14) we conclude that there exist $y_m \in \partial \Omega$ and $\tilde{\varepsilon}_m \in (0, \varepsilon_m)$ such that

$$u(x_m, t_0 + \varepsilon_m) < u(y_m, t_0 + \tilde{\varepsilon}_m).$$
(2.15)

But, by (2.8) and (2.5),

$$\begin{split} u(y_m, t_0 + \tilde{\varepsilon}_m) &\leq \int_{\Omega} |f(y_m, x)| \bigg| \max_{x \in \overline{\Omega}} |u(x, t_0 + \tilde{\varepsilon}_m)| \bigg| dx \\ &\leq \rho \bigg\{ \max_{x \in \overline{\Omega}} |u(x, t_0)| + \eta_m \bigg\}, \end{split}$$

where $\eta_m \to 0$ by the continuity of *u*. Substituting this into (2.15) and recalling (2.14), we get

$$u(x_m, t_0 + \varepsilon_m) \leq \rho u(x_m, t_0 + \varepsilon_m) + \eta_m$$

or $(1 - \rho)u(x_m, t_0 + \varepsilon_m) \leq \eta_m$. Taking $m \to \infty$ we deduce, upon using (2.14), that

$$u(x, t_0) \equiv 0.$$
 (2.16)

By the uniqueness part of Theorem 2.1 it follows that u(x, t) = 0 if $t > t_0$, a contradiction to (2.12).

THEOREM 2.3. There exist positive constants C, γ such that

$$U(t) \leq C e^{-\gamma t} \quad \text{for all } t > 0. \tag{2.17}$$

Proof. Let $|u_0| \leq M$. The proof of existence shows that $|u_m| \leq M$ and therefore also $|u| \leq M$ in Ω_{∞} . Hence, if $y \in \partial \Omega$, t > 0,

$$|u(y,t)| \leq \int_{\Omega} |f(y,x)u(x,t)| dx \leq \rho M.$$

By standard results on the asymptotic behavior of the solution of parabolic equations [5, Chapter 6] it follows that

$$\limsup_{x\in\Omega,\ t\to\infty}|u(x,t)|\leqslant\rho M$$

Hence, if $\rho_* = (\rho + 1)/2$ then

$$|u(x,t)| \leq \rho_* M$$
 if $x \in \Omega$, $t > t_1$

for some large enough t_1 . Similarly, we obtain by induction

$$|u(x,t)| \leq (\rho_*)^m M \quad \text{if } t > mt_1,$$

so that

$$U(t) \leq (\rho_*)^m M \quad \text{if } mt_1 \leq t \leq (m+1)t_1.$$

It follows that

$$U(t) \leq \frac{M}{\rho_*} (\rho_0)^{m+1} \leq \frac{M}{\rho_*} (\rho_*)^{t/t_1}$$

from which (2.17) follows.

3. U(t) is strictly decreasing.

LEMMA 3.1. There exists a $0 < T_* \leq \infty$ such that U(t) is strictly decreasing if $0 < t < T_*$ and $U(t) \equiv 0$ if $t > T_*$.

Proof. Suppose U(t) is not strictly decreasing for all t > 0. Then there exist $0 < t_0 < t_1 < \infty$ such that

$$U(t) = U(t_0) = U(t_1)$$
 for all $t_0 < t < t_1$.

In order to prove the lemma it suffices to show that for any such t_0 , t_1 we have $U(t_1) = 0$. We shall assume that

$$U(t_1) > 0 \tag{3.1}$$

and derive a contradiction.

By the maximum principle we then have, for any $x \in \Omega$,

$$|u(x,t_1)| \leq \max\left\{\max_{\substack{y \in \partial \Omega, \ t_1 \leq s \leq t}} |u(y,s)|, \ \max_{\overline{x} \in \overline{\Omega}} |u(\overline{x},t_0)|\right\}$$
$$= \max_{t_0 \leq t \leq t_1} U(t) = U(t_1) = \max_{\overline{x} \in \overline{\Omega}} u(\overline{x},t_1)$$
$$= \max_{\substack{y \in \partial \Omega}} u(y,t_1) = u(y_1,t_1)$$
(3.2)

for some $y_1 \in \partial \Omega$, where for definiteness we have assumed that

$$U(t_1) = \max_{\bar{x} \in \bar{\Omega}} u(\bar{x}, t_1) \ge - \min_{\bar{x} \in \bar{\Omega}} u(\bar{x}, t_1).$$

Hence

$$u(y_{1}, t_{1}) = \int_{\Omega} f(y_{1}, x) u(x, t_{1}) dx \leq \rho \max_{x \in \overline{\Omega}} |u(x, t_{1})|$$

$$\leq \rho u(y_{1}, t_{1}).$$
(3.3)

Since $\rho < 1$ it follows that $u(y_1, t_1) = 0$ and, by (3.2), $U(t_1) = 0$, which contradicts (3.1).

In the sequel we impose the following additional conditions:

$$a_{ij} \in C^{1+\alpha}(\overline{\Omega}), \tag{3.4}$$

$$\partial \Omega$$
 is in $C^{2+\alpha}$, (3.5)

and there exists an extension of f into a function f(x, y) defined for all $x \in \overline{\Omega}$, $y \in \overline{\Omega}$ such that

$$f(x, y) \in C^{2+\alpha}(\overline{\Omega} \times \overline{\Omega}).$$
 (3.6)

We can clearly redefine f, if necessary, such that also

$$\theta(x) \equiv \int_{\Omega} |f(x, y)| \, dy \leq \rho_0 < 1 \quad \text{for all } x \in \overline{\Omega}.$$
(3.7)

LEMMA 3.2. For any $x \in \Omega$ the function u(x, t) is analytic in t, for $0 < t < \infty$.

Proof. Introduce the function

$$V(x,t) = u(x,t) - \int_{\Omega} f(x,y)u(y,t) \, dy.$$
 (3.8)

We can solve u in terms of U, at least formally, by

$$u(x,t) = V(x,t) + \sum_{m=0}^{\infty} \int_{\Omega} f^{(m)}(x,y) V(y,t) \, dy, \qquad (3.9)$$

where $f^{(0)}(x, y) = f(x, y)$ and

$$f^{(m)}(x, y) = \int_{\Omega} f^{(m-1)}(x, z) f(z, y) dz = \int_{\Omega} f(x, z) f^{(m-1)}(z, y) dz.$$
(3.10)

In view of (3.7)

$$\left|f^{(m)}(x, y)\right| \leq \rho_0 \sup_{z \in \Omega} \left|f^{(m-1)}(z, y)\right|,$$

from which we deduce that

$$\sup_{x, y} |f^{(m)}(x, y)| \leq C(\rho_0)^{m-1}.$$
(3.11)

It follows that the series $\sum f^{(m)}(x, y)$ is uniformly convergent; in fact, it even converges in the $C^{2+\alpha}(\overline{\Omega} \times \overline{\Omega})$ sense. We can thus write

$$u(x,t) = V(x,t) + \int_{\Omega} F(x,y)V(y,t) \, dy$$
 (3.12)

with F in $C^{2+\alpha}$.

The function V satisfies:

$$V_t - AV = -\int_{\Omega} f(x, y) u_t(y, t) \, dy + \int_{\Omega} \left(Af(x, y) \right) u(y, t) \, dy$$

= $-\int_{\Omega} f(x, y) \left[\sum a_{ij}(y) \frac{\partial^2 u}{\partial y_i \partial y_j} + \sum b_i(y) \frac{\partial u}{\partial y} + c(y) u \right] dy$
+ $\int_{\Omega} \left[\sum a_{ij}(x) \frac{\partial^2 f}{\partial x_i \partial x_j} + \sum b_i(x) \frac{\partial f}{\partial x_i} + c(x) f \right] u(y, t) \, dy.$

Writing

$$-\int_{\Omega} f(x, y) a_{ij}(y) \frac{\partial^2 u(y)}{\partial y_i \partial y_j} dy = -\int_{\partial \Omega} f(x, y) a_{ij}(y) v_i \frac{\partial u(y, t)}{\partial y_j} dS_y + \int_{\Omega} \frac{\partial}{\partial y_i} (f(x, y) a_{ij}(y)) \frac{\partial u(y, t)}{\partial y_j} dy$$

we see that

$$V_t - AV = G \quad \text{in } \Omega_{\infty}, \tag{3.13}$$

where

$$G = \sum \int_{\partial \Omega} \tilde{\alpha}_j(x, y) \frac{\partial u(y, t)}{\partial y_j} dS_y + \sum \int_{\Omega} \tilde{\beta}_j(x, y) \frac{\partial u(y, t)}{\partial y_j} dy + \int_{\Omega} \tilde{\gamma}(x, y) u(y, t) dy$$

and $\tilde{\alpha}_j$, $\tilde{\beta}_j$, $\tilde{\gamma}$ are in C^{α} . Substituting u and $\partial u / \partial y_j$ from (3.12) we find that

$$G = G(V) = \sum \int_{\partial \Omega} \alpha_j(x, y) \frac{\partial V(y, t)}{\partial y_j} dS_y + \sum \int_{\Omega} \beta_j(x, y) \frac{\partial V(y, t)}{\partial y_j} dy + \int_{\Omega} \gamma(x, y) V(y, t) dy, \quad (3.14)$$

where α_j , β_j , γ are in C^{α} .

Note that

$$V(x,t) = 0 \quad \text{if } x \in \partial\Omega, \ t > 0, \tag{3.15}$$

and

$$V(x,0) = V_0(x) \quad \text{if } x \in \Omega, \, V_0 \in C(\overline{\Omega}). \tag{3.16}$$

The parabolic problem (3.13), (3.15), (3.16) is not a standard one since G is a nonlocal (linear) operator of V. Nevertheless, one can still apply Schauder-type estimates in order to derive inductively that, for any $0 < T < \infty$, $1 \le m < \infty$,

$$|D_t^m V(y,t)| \le \frac{K_0 K^{m-1}}{t^{m-1+n/2}} \frac{m!}{m^2} \quad \text{in } \Omega_T,$$
(3.17)

with similar bounds on $D_t^{m-1}D_y^2 V(y,t)$ and on the corresponding Hölder coefficients. Indeed, in [6] we considered the parabolic problem

$$v_{yy} - v_t = v_y(1, t)v_y \quad \text{in } \{0 < y < 1, 0 < t < T\},\$$

$$v(0, t) = v(1, t) = 0 \quad \text{if } 0 < t < T,$$

and established estimates of the type (3.17). The proof can be extended to parabolic equations with variable coefficients in *n*-dimensional domains [and with $v_y(1, t)v_y$ replaced by G(V)]. In fact, the basic estimates from which one deduces (3.17) (for v) are the interior-boundary Schauder estimates stated in Theorem 1.1 of [6]. This theorem can be extended to general parabolic operators in general domains by a standard argument used to derive the Schauder estimates for variable coefficients and general domains, once they have been proven for constant coefficients in rectangular domains; see [5, Chapter 4]. Since the calculations are routine, we omit the details.

The assertion (3.17) now follows from the interior-boundary Schauder estimates in a way similar to that for v in [6].

From (3.17) and (3.12) we see that u(x, t) is analytic in t, for each $x \in \Omega$.

THEOREM 3.3. If (3.4)–(3.6) hold, then U(t) is strictly decreasing in t for all t > 0.

Proof. If the assertion is not true then, by Lemma 3.1, $u(x, t) \equiv 0$ for all $t > T_*$. By Lemma 3.2 it then follows that $u(x, t) \equiv 0$ in Ω_{∞} , a contradiction to $u_0 \neq 0$.

REMARK. Theorems 2.1–2.3 and Lemma 3.1 extend to the case where the coefficients of A also depend on t. Lemma 3.2 and Theorem 3.3 also extend to this case provided the coefficients are analytic in t.

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