
Contents

Preface	vii
Part 1. The Core of the Theory	
Chapter 1. Examples of Hyperbolic Dynamical Systems	3
§1.1. Anosov diffeomorphisms	4
§1.2. Anosov flows	8
§1.3. The Katok map of the 2-torus	13
§1.4. Diffeomorphisms with nonzero Lyapunov exponents on surfaces	23
§1.5. A flow with nonzero Lyapunov exponents	27
Chapter 2. General Theory of Lyapunov Exponents	33
§2.1. Lyapunov exponents and their basic properties	33
§2.2. The Lyapunov and Perron regularity coefficients	38
§2.3. Lyapunov exponents for linear differential equations	41
§2.4. Forward and backward regularity. The Lyapunov–Perron regularity	51
§2.5. Lyapunov exponents for sequences of matrices	56
Chapter 3. Lyapunov Stability Theory of Nonautonomous Equations	61
§3.1. Stability of solutions of ordinary differential equations	62
§3.2. Lyapunov absolute stability theorem	68
§3.3. Lyapunov conditional stability theorem	72

Chapter 4. Elements of the Nonuniform Hyperbolicity Theory	77
§4.1. Dynamical systems with nonzero Lyapunov exponents	78
§4.2. Nonuniform complete hyperbolicity	88
§4.3. Regular sets	91
§4.4. Nonuniform partial hyperbolicity	93
§4.5. Hölder continuity of invariant distributions	94
Chapter 5. Cocycles over Dynamical Systems	99
§5.1. Cocycles and linear extensions	100
§5.2. Lyapunov exponents and Lyapunov–Perron regularity for cocycles	105
§5.3. Examples of measurable cocycles over dynamical systems	109
Chapter 6. The Multiplicative Ergodic Theorem	113
§6.1. Lyapunov–Perron regularity for sequences of triangular matrices	114
§6.2. Proof of the Multiplicative Ergodic Theorem	120
§6.3. Normal forms of measurable cocycles	124
§6.4. Lyapunov charts	128
Chapter 7. Local Manifold Theory	133
§7.1. Local stable manifolds	134
§7.2. An abstract version of the Stable Manifold Theorem	137
§7.3. Basic properties of stable and unstable manifolds	147
Chapter 8. Absolute Continuity of Local Manifolds	155
§8.1. Absolute continuity of the holonomy map	157
§8.2. A proof of the absolute continuity theorem	161
§8.3. Computing the Jacobian of the holonomy map	167
§8.4. An invariant foliation that is not absolutely continuous	168
Chapter 9. Ergodic Properties of Smooth Hyperbolic Measures	171
§9.1. Ergodicity of smooth hyperbolic measures	171
§9.2. Local ergodicity	176
§9.3. The entropy formula	183

Chapter 10. Geodesic Flows on Surfaces of Nonpositive Curvature	195
§10.1. Preliminary information from Riemannian geometry	196
§10.2. Definition and local properties of geodesic flows	198
§10.3. Hyperbolic properties and Lyapunov exponents	200
§10.4. Ergodic properties	205
§10.5. The entropy formula for geodesic flows	210
 Part 2. Selected Advanced Topics	
Chapter 11. Cone Technics	215
§11.1. Introduction	215
§11.2. Lyapunov functions	217
§11.3. Cocycles with values in the symplectic group	221
Chapter 12. Partially Hyperbolic Diffeomorphisms with Nonzero Exponents	223
§12.1. Partial hyperbolicity	224
§12.2. Systems with negative central exponents	227
§12.3. Foliations that are not absolutely continuous	229
Chapter 13. More Examples of Dynamical Systems with Nonzero Lyapunov Exponents	235
§13.1. Hyperbolic diffeomorphisms with countably many ergodic components	235
§13.2. The Shub–Wilkinson map	246
Chapter 14. Anosov Rigidity	247
§14.1. The Anosov rigidity phenomenon. I	247
§14.2. The Anosov rigidity phenomenon. II	255
Chapter 15. C^1 Pathological Behavior: Pugh’s Example	261
Bibliography	267
Index	273