

ON LAMÉ'S SIX EQUATIONS CONNECTED WITH  
TRIPLY ORTHOGONAL SYSTEMS  
OF SURFACES.

BY J. E. WRIGHT, M.A.

LAMÉ\* has shown for a triply orthogonal system of surfaces given by the parameters  $\rho, \rho_1, \rho_2$  that if the square of the element of length is given by  $ds^2 = H^2 d\rho + H_1^2 d\rho_1^2 + H_2^2 d\rho_2^2$ , where  $H, H_1, H_2$  are certain functions of  $\rho, \rho_1, \rho_2$ , then  $H, H_1, H_2$  must satisfy the following system of equations :

$$\frac{\partial^2 H}{\partial \rho_1 \partial \rho_2} = \frac{1}{H_1} \frac{\partial H}{\partial \rho_1} \frac{\partial H_1}{\partial \rho_2} + \frac{1}{H_2} \frac{\partial H}{\partial \rho_2} \frac{\partial H_2}{\partial \rho_1} \quad (1)$$

and two others of the same type; (2), (3)

$$\frac{\partial}{\partial \rho_1} \left( \frac{1}{H_1} \frac{\partial H}{\partial \rho_1} \right) + \frac{\partial}{\partial \rho} \left( \frac{1}{H} \frac{\partial H_1}{\partial \rho} \right) + \frac{1}{H_2} \frac{\partial H}{\partial \rho_2} \frac{\partial H_1}{\partial \rho_2} = 0 \quad (4)$$

with two others of this type. (5), (6)

Also if  $V$  is a function of  $x, y, z$  for which

$$\frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = 0,$$

he has shown that

$$\frac{\partial}{\partial \rho} \left( \frac{H_1 H_2}{H} \frac{\partial V}{\partial \rho} \right) + \frac{\partial}{\partial \rho_1} \left( \frac{H_2 H}{H_1} \frac{\partial V}{\partial \rho_1} \right) + \frac{\partial}{\partial \rho_2} \left( \frac{H H_1}{H_2} \frac{\partial V}{\partial \rho_2} \right) = 0.$$

If the system of coordinates  $\rho, \rho_1, \rho_2$  is isothermal, this equation must be satisfied by  $V = \rho$ , or by  $V = \rho_1$ , or by  $V = \rho_2$ . Hence  $H_1 H_2 / H = Q^2$ , where  $Q$  is a function of  $\rho_1$  and  $\rho_2$  only. Similarly  $H_2 H / H_1 = Q_1^2$ , and  $H H_1 / H_2 = Q_2^2$ , where  $Q_i$  is a function not involving the variable  $\rho_i$ . Hence  $H = Q_1 Q_2$ ,  $H_1 = Q_2 Q$ ,  $H_2 = Q Q_1$ . The six equations given above transform into six in the variables  $Q$ . Lamé † gives a solution of

\* *Leçons sur les coordonnées curvilignes* (1859), pp. 76, 78.

† *Loc. cit.*, p. 99.

these equations by first finding a solution of equations (1), (2), (3) and using this to solve the remainder. He makes the statement that his solution of the first three equations is the most general possible \* ; this statement is obviously inaccurate and it seems of interest to give a complete solution of the equations. The solution of the first three equations, or rather a comparison of two different solutions, leads to a curious result in the theory of elimination.

Equation (1) becomes

$$Q \frac{\partial Q_2}{\partial \rho_1} \frac{\partial Q_1}{\partial \rho_2} = Q_1 \frac{\partial Q_2}{\partial \rho_1} \frac{\partial Q}{\partial \rho_2} + Q_2 \frac{\partial Q_1}{\partial \rho_2} \frac{\partial Q}{\partial \rho_1}, \quad (7)$$

with similar expressions for (2) and (3). Multiply (7) by  $\partial Q_1 / \partial \rho$ , and the transformed expression for (3) by  $\partial Q_1 / \partial \rho_2$ , and add. The result is

$$Q_1 \left[ \frac{\partial Q_2}{\partial \rho} \frac{\partial Q}{\partial \rho_1} \frac{\partial Q_1}{\partial \rho_2} + \frac{\partial Q_1}{\partial \rho} \frac{\partial Q_2}{\partial \rho_1} \frac{\partial Q}{\partial \rho_2} \right] = 0.$$

Hence unless all the  $Q$ 's vanish identically

$$\frac{\partial Q_2}{\partial \rho} \frac{\partial Q}{\partial \rho_1} \frac{\partial Q_1}{\partial \rho_2} + \frac{\partial Q_1}{\partial \rho} \frac{\partial Q_2}{\partial \rho_1} \frac{\partial Q}{\partial \rho_2} = 0. \quad (8)$$

Assume that none of the derivatives in (8) vanish identically and write

$$K = -\frac{\partial Q}{\partial \rho_1} / \frac{\partial Q}{\partial \rho_2}, \quad K_1 = -\frac{\partial Q_1}{\partial \rho_2} / \frac{\partial Q_1}{\partial \rho}, \quad K_2 = -\frac{\partial Q_2}{\partial \rho} / \frac{\partial Q_2}{\partial \rho_1}.$$

Equation (8) becomes  $KK_1K_2 = 1$ , where  $K_i$  is a function not involving  $\rho_i$ . By taking logarithms and differentiating with respect to two of the variables  $\rho$ , it is easy to prove that the most general values for the  $K$ 's are

$$K = \frac{a_2}{a_1}, \quad K_1 = \frac{a}{a_2}, \quad K_2 = \frac{a_1}{a},$$

where  $a$  is a function of  $\rho$  only and similarly  $a_1$  and  $a_2$  are functions of  $\rho_1$  and  $\rho_2$  alone respectively.

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\* Loc. cit., p. 100, line 23.

If we put  $\int ad\rho = \sigma$ , with similar values for  $\sigma_1$  and  $\sigma_2$ , we deduce that  $Q$  is a function of  $\sigma - \sigma_2$  only,  $Q_1$  a function of  $\sigma_2 - \sigma$  only, and  $Q_2$  a function of  $\sigma - \sigma_1$  only. Substitute these values in (7) and it readily reduces to

$$\frac{Q}{Q'} + \frac{Q_1}{Q_1'} + \frac{Q_2}{Q_2'} = 0.$$

Hence

$$\frac{Q}{Q'} = n(\sigma_1 - \sigma_2), \quad \frac{Q_1}{Q_1'} = n(\sigma_2 - \sigma), \quad \frac{Q_2}{Q_2'} = n(\sigma - \sigma_1),$$

where  $n$  is a constant, and therefore

$$Q = c(\sigma_1 - \sigma_2)^{1/n}, \quad Q_1 = c_1(\sigma_2 - \sigma)^{1/n}, \quad Q_2 = c_2(\sigma - \sigma_1)^{1/n}, \quad (A)$$

where  $c, c_1, c_2$  are constants. This is the most general solution, provided none of the derivatives in (8) vanish. If, however, for example,  $\partial Q_2/\partial\rho_1 = 0$ , then either  $\partial Q_2/\partial\rho = 0$ , or  $\partial Q/\partial\rho_1 = 0$ , or  $\partial Q_1/\partial\rho_2 = 0$ . Equation (7), however, shows that  $\partial Q_2/\partial\rho_1 = 0$  implies either  $\partial Q/\partial\rho_1 = 0$  or  $\partial Q_1/\partial\rho_2 = 0$ .  $\partial Q_2/\partial\rho_1 = 0$ ,  $\partial Q_1/\partial\rho_2 = 0$  lead to the solution

$$Q_1 = f(\rho), \quad Q_2 = cf(\rho), \quad Q = \phi(\rho_1, \rho_2), \quad (B)$$

where  $f$  and  $\phi$  are arbitrary functions of their arguments and  $c$  is a constant.  $\partial Q_2/\partial\rho_1 = 0$ ,  $\partial Q/\partial\rho_1 = 0$  lead to the solution

$$Q_2 = f(\rho), \quad Q = \phi(\rho_2), \quad Q_1 = F(Q, Q_2), \quad (C)$$

where  $F$  is homogeneous and of unit degree in  $Q_1, Q_2$ . These types (A), (B), (C) are the only three types of solution.

We now proceed to the integration of the equations in a different manner. Write  $\log Q = \lambda$ ,  $\log Q_1 = \lambda_1$ ,  $\log Q_2 = \lambda_2$ . Equations (1), (2), (3) become

$$\frac{\partial\lambda_2}{\partial\rho_1} \frac{\partial\lambda_1}{\partial\rho_2} = \frac{\partial\lambda_2}{\partial\rho_1} \frac{\partial\lambda}{\partial\rho_2} + \frac{\partial\lambda}{\partial\rho_1} \frac{\partial\lambda_1}{\partial\rho_2} \quad (9)$$

and two similar equations.

Write  $\lambda_1 - \lambda_2 = \omega, \lambda_2 - \lambda = \omega_1, \lambda - \lambda_1 = \omega_2$  and (9) becomes

$$\frac{\partial \omega_1}{\partial \rho_1} \frac{\partial \omega_2}{\partial \rho_2} - \frac{\partial \omega_1}{\partial \rho_2} \frac{\partial \omega_2}{\partial \rho_1} = 0,$$

or

$$J \begin{pmatrix} \omega_1 & \omega_2 \\ \rho_1 & \rho_2 \end{pmatrix} = 0.$$

Hence the equation implies the existence of a relation,  $f(\omega_1, \omega_2, \rho) = 0$ . Exactly similarly there are relations

$$f_1(\omega_2, \omega, \rho_1) = 0, \quad f_2(\omega, \omega_1, \rho_2) = 0.$$

From these equations, together with  $\omega + \omega_1 + \omega_2 = 0$ , it is easy to deduce that either  $\rho, \rho_1, \rho_2$  do not any of them occur explicitly in  $f, f_1, f_2$  or if, for example,  $\rho$  occurs in  $f$ , it is easy to prove that either  $\rho_1$  is absent from  $f_1$ , or  $\rho_2$  from  $f_2$ . The latter case is thus reduced to the former, for if one relation of the type  $f(\omega, \omega_1) = 0$  exist, then two others of that type also exist in virtue of the relation  $\omega + \omega_1 + \omega_2 = 0$ .

Substituting for the  $\omega$ 's in terms of the  $Q$ 's, we immediately deduce that the solution is equivalent to the statement that a homogeneous relation  $F(Q, Q_1, Q_2) = 0$  exists among the  $Q$ 's.

Combining the two solutions we have the following theorem connected with the theory of elimination :

*Let  $F(Q, Q_1, Q_2) = 0$  be any homogeneous relation. It is possible to express  $Q$  as a function of two variables  $\rho_1$  and  $\rho_2$ ,  $Q_1$  as a function of two variables  $\rho_2$  and  $\rho$ , and  $Q_2$  as a function of the variables  $\rho$  and  $\rho_1$ , in two cases only :*

(A) *If  $F$  is of the form  $aQ^n + a_1Q_1^n + a_2Q_2^n$ , where  $a, a_1, a_2$  are constants.\**

(C) *If  $F$  is general, and e. g.  $Q$  is a function of  $\rho_1$  only, and  $Q_1$  a function of  $\rho$  only.*

It is not difficult to complete the solution of the equations (1), . . . , (6). It may readily be shown that for case (A) (4), (5), and (6) are not satisfied unless  $n = \frac{1}{2}$ , and then

$$\sigma = A \wp \left( \frac{\rho + a}{\sqrt{c}}, g_2, g_3 \right) + B,$$

$$\sigma_1 = A \wp \left( \frac{\rho_1 + a_1}{\sqrt{c_1}}, g_2, g_3 \right) + B,$$

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\* This includes (B).

$$\sigma_2 = A \varphi \left( \frac{\rho_2 + a_2}{\sqrt{c_2}}, g_2, g_3 \right) + B,$$

where the  $a$ 's, the  $g$ 's,  $A$  and  $B$  are constants.

For case (c) the complete solution is

$$\begin{aligned} Q_1 &= a \operatorname{cosec} (b\rho_2 + c), & Q_2 &= a' \operatorname{cosec} (b'\rho_1 + c'), \\ Q &= A [\operatorname{cosec}^2 (b\rho_2 + c) - \operatorname{cosec}^2 (b'\rho_1 + c')]^{\frac{1}{2}}, \end{aligned}$$

where  $A, a, a', b, b', c, c'$  are constants such that

$$a^2 b'^2 + a'^2 b^2 = 0.$$

In case (B)

$$Q_1 = \frac{1}{a\rho + b}, \quad Q_2 = \frac{k}{a\rho + b},$$

where  $a, b, k$  are constants, and  $Q$  is a function of  $\rho_1$  and  $\rho_2$  which satisfies the equation

$$\left( k^2 \frac{\partial^2}{\partial \rho_2^2} + \frac{\partial^2}{\partial \rho_1^2} \right) \log Q + a^2 Q^2 = 0.$$

Of these three types of solution, the first is the same as that given by Lamé.\* He gives it in different form, and his method of obtaining it is different. He falls into the error of imagining that the most general solution of the *first* three of his equations corresponds to the case of  $n = \frac{1}{2}$ , and it happens that this error is largely corrected because the *second* three equations require this limitation in case (A); case (B), however, escapes his notice.

The surfaces corresponding to the three solutions are readily obtained. (A) gives a system of confocal quadrics, and (C) a system of confocal spheroids with their axial planes. (B) gives a system of concentric spheres, and the conical surfaces obtained by joining the common centre to any set of isothermal lines on one of them.

BRYN MAWR,  
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\* Loc. cit., p. 104.