AN APPLICATION OF THE NOTIONS OF "GEN-ERAL ANALYSIS" TO A PROBLEM OF THE CALCULUS OF VARIATIONS.

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THE object of the following note is to give an illustration of the unifying power of Professor E. H. Moore's methods of "General Analysis" * by showing that a certain theorem of the calculus of variations and a certain theorem of analytic geometry are special cases of one and the same theorem of general analysis.

The theorem of the calculus of variations is the so-called fundamental lemma for isoperimetric problems,[†] viz.,

THEOREM I. "If

(1)
$$\mu_0(\eta) \equiv \int_{x_1}^{x_2} \left[M_0(x)\eta(x) + N_0(x)\eta'(x) \right] dx = 0$$

for all functions $\eta(x)$ which are (a) of class C' on $[x_1x_2]$, (b) vanish at x_1 and x_2 , and (c) satisfy the m conditions

(2)
$$\mu_i(\eta) \equiv \int_{x_1}^{x_2} \left[M_i(x)\eta(x) + N_i(x)\eta'(x) \right] dx = 0$$

(*i* = 1, 2, ..., *m*),

then there exist m constants c_1, c_2, \dots, c_m such that

(3)
$$\mu_0(\eta) + c_1 \mu_1(\eta) + c_2 \mu_2(\eta) + \dots + c_m \mu_m(\eta) = 0$$

for all functions $\eta(x)$ satisfying conditions (a) and (b).

The functions $\dot{M}(x)$, $\dot{N}(x)$ are supposed to be continuous on $[x_1x_2]$.

The theorem of analytic geometry is the well known

^{*}Compare E. H. Moore, "On a form of General Analysis with applications to linear differential equations and integral equations," Atti del IV congresso internazionale dei Mathematici, vol. 2, p. 98; and "Introduction to a form of General Analysis," in The New Haven Mathematical Colloquium, Yale University Press, New Haven, 1910.

[†]Compare for instance Bolza, Vorlesungen über Variationsrechnung, p. 462, footnote 1, and the references given there.

THEOREM II. "If, in a plane and in homogeneous coordinates,

(1')
$$U_0 \equiv A_0 x + B_0 y + C_0 z = 0$$

is the equation of a straight line passing through the point of intersection of the two non-coinciding * lines

(2')
$$U_1 \equiv A_1 x + B_1 y + C_1 z = 0$$
, $U_2 \equiv A_2 x + B_2 y + C_2 z = 0$,
then there exist two constants λ_1 , λ_2 such that

$$U_0 \equiv \lambda_1 U_1 + \lambda_2 U_2.$$

§ 1. The General Theorem.

Let p be a general parameter \dagger ranging over a set \mathfrak{P} of elements; these elements may be any mathematical entities whatever: real or complex numbers, pairs, triples, etc., of such numbers, even infinite sets of numbers; functions of one or several variables; systems of functions; points, curves, surfaces; etc., etc.

Along with the set \mathfrak{P} we consider the set \mathfrak{O} of all possible systems $(a_1, a_2; p_1, p_2)$ of a pair of real numbers a_1, a_2 and a pair of elements p_1 , p_2 of \mathfrak{P} , and we suppose that a correspondence has been established by which to every element of \mathfrak{Q} corresponds a unique element of \mathfrak{P} which we denote by \ddagger

$$F(a_1, a_2; p_1, p_2).$$

We shall then say that a real single-valued function § $\mu(p)$ defined on \mathfrak{P} is "linear as to F," if

(4)
$$\mu[F(a_1, a_2; p_1, p_2)] = a_1 \mu(p_1) + a_2 \mu(p_2)$$
 on \mathbb{Q} ,

i. e., for every combination $(a_1, a_2; p_1, p_2)$ of \mathbb{Q} .

Then the following theorem holds:

THEOREM III. If

$$\mu_0(p), \ \mu_1(p), \ \cdots, \ \mu_m(p)$$

^{*} We may omit the word "non-coinciding " if we replace " point of intersection of " by " point or points common to." † Compare Moore, "Introduction etc.," § 1 ; I use throughout this section

Moore's notation.

¹ In Moore's terminology F is a "function on \mathfrak{D} to \mathfrak{P} ," "Introduction etc.," § 4. § Compare Moore, "Introduction etc.," § 5; if \mathfrak{A} denotes the set of all real numbers, $\mu(p)$ is in Moore's terminology a "function on \mathfrak{P} to \mathfrak{A} ."

^{||} This generalization of Theorem I has been suggested to me by a remark in § 177 of Hadamard's Lecons sur le calcul des variations, Paris, 1910.

are m + 1 real single-valued functions of p, defined on \mathfrak{P} , which satisfy the following two conditions:

A) they are linear as to F,

B) the equation
$$\mu_0(p) = 0$$

holds for every element of \mathfrak{P} which satisfies simultaneously the m equations

(2")
$$\mu_1(p) = 0, \ \mu_2(p) = 0, \ \cdots, \ \mu_m(p) = 0,$$

then there exist m real numbers c_1, c_2, \dots, c_m , independent of p, such that

(3")
$$\mu_0(p) + c_1\mu_1(p) + \cdots + c_m\mu_m(p) = 0$$
 on \mathfrak{P} ,

i. e., for every element of \mathfrak{P} .

Proof: We notice first that there always exist elements of \mathfrak{P} which do satisfy the *m* equations (2''); for $F(0, 0; p_1, p_2)$ is an element of \mathfrak{P} for any two elements p_1, p_2 of \mathfrak{P} , and on account of A)

$$\mu_i[F(0, 0; p_1, p_2)] = 0, \quad (i = 1, 2, \dots, m).$$

Further we observe that if we define

$$F[1, a_3; F(a_1, a_2; p_1, p_2), p_3] = F(a_1, a_2, a_3; p_1, p_2, p_3)$$

and generally

(5)
$$F[1, a_n; F(a_1, a_2, \dots, a_{n-1}; p_1, p_2, \dots, p_{n-1}), p_n]$$

= $F(a_1, a_2, \dots, a_n; p_1, p_2, \dots, p_n),$

then $F(a_1, a_2, \dots, a_n; p_1, p_2, \dots, p_n)$ is again an element of \mathfrak{P} , and, if (4) is satisfied, then also

(6)
$$\mu[F(a_1, a_2, \dots, a_n; p_1, p_2, \dots, p_n)]$$

= $a_1\mu(p_1) + a_2\mu(p_2) + \dots + a_n\mu(p_n).$

After these preliminary remarks we distinguish two cases : Case I: The *m* equations (2'') are satisfied for every *p* of \mathfrak{P} . Then according to *B*)

$$\mu_0(p) = 0 \text{ on } \mathfrak{P}.$$

Hence we may write

$$\mu_0(p) + 0 \cdot \mu_1(p) + 0 \cdot \mu_2(p) + \dots + 0 \cdot \mu_m(p) = 0 \quad \text{on } \mathfrak{P},$$

and the theorem is proved with the particular values $c_1 = 0$, $c_2 = 0, \dots, c_m = 0$.

² Case II: The *m* equations (2'') are not all satisfied for every *p* of \mathfrak{P} .

Then there exists a definite integer $n \ (1 \le n \le m)$ such that in the determinant

$$\Delta = |\mu_i(p_k)| \qquad (i, k = 1, 2, \dots, m)$$

at least one minor of degree n is different from zero for some special system p_1, p_2, \dots, p_m , whereas (for n < m) all minors of degree n + 1 vanish identically, that is, for every choice of the m elements p_1, p_2, \dots, p_m . In order to fix the ideas we suppose that the minor

(7)
$$\Delta_0 = |\mu_g(p_h)| \neq 0 \quad (g, h = 1, 2, \dots, n).$$

Let now p be any element of \mathfrak{P} and p_1, p_2, \dots, p_n the n special elements for which $\Delta_0 \neq 0$; then

$$q = F(1, a_1, a_2, \dots, a_n; p, p_1, p_2, \dots, p_n)$$

is an element of \mathfrak{P} , and according to A)

(8)
$$\mu_{j}(q) = \mu_{j}(p) + a_{1}\mu_{j}(p_{1}) + \dots + a_{n}\mu_{j}(p_{n})$$
$$(j = 0, 1, 2, \dots, m).$$

On account of (7) we can so determine a_1, a_2, \dots, a_n that

(9)
$$\mu_1(q) = 0, \ \mu_2(q) = 0, \ \cdots, \ \mu_n(q) = 0.$$

If n < m, it follows from the identical vanishing of the minors of degree n + 1 of the determinant Δ , p taking the place of p_{n+1} , that also

(10)
$$\mu_{n+1}(q) = 0, \ \mu_{n+2}(q) = 0, \ \cdots, \ \mu_m(q) = 0.$$

Hence for n < m as well as for n = m, q is an element of \mathfrak{P} which satisfies the m equations (2") and therefore it satisfies according to B) also the equation

(11)
$$\mu_0(q) = 0.$$

But from the n + 1 equations (9) and (11) it follows, if we write the $\mu_i(q)$'s in their explicit form (8), that the determinant

(12)
$$|\mu_j(p), \mu_j(p_1), \cdots, \mu_j(p_n)| = 0$$
 $(j = 0, 1, 2, \cdots, n).$

If now we expand this determinant according to the elements of the first column, the coefficient of $\mu_0(p)$ is the determinant Δ_0 and therefore different from zero, and this determinant as well as the remaining coefficients of the expansion is *independent of p*. Hence if we divide by Δ_0 , we obtain equation (3") with $c_{n+1} = 0, c_{n+2} = 0, \dots, c_m = 0$, and this equation holds on \mathfrak{P} , since p was any element of \mathfrak{P} . Thus our theorem is proved.*

§ 2. Theorems I and II as Special Cases of Theorem III.

In order to obtain Theorem I as a special case of Theorem III, we identify the set \mathfrak{P} with the totality of all functions $\eta(x)$ of class C' on $[x_1x_2]$ which vanish at x_1 and x_2 , and define

(13)
$$F(a_1, a_2; \eta_1, \eta_2) = a_1 \eta_1 + a_2 \eta_2.$$

If a_1 , a_2 are two constants and $\eta_1(x)$, $\eta_2(x)$ two functions of \mathfrak{P} , $a_1\eta_1(x) + a_2\eta_2(x)$ again belongs to \mathfrak{P} and the "functions"

$$\mu_{j}(\eta) = \int_{x_{1}}^{x_{2}} [M_{j}(x)\eta(x) + N_{j}(x)\eta'(x)] dx \quad (j = 0, 1, \dots, m)$$

are "linear as to F," since

(14)
$$\mu_j(a_1\eta_1 + a_2\eta_2) = a_1\mu_j(\eta_1) + a_2\mu_j(\eta_2).$$

For this special choice of the set \mathfrak{P} , the operator F, and the functions μ_{i} , Theorem III becomes identical with Theorem I.

More generally we may take for \mathfrak{P} the totality of all functions $\eta(x)$ of class C' on $[x_1x_2]$ which satisfy any given system of conditions provided only that these conditions are *linear*, *i. e.*, such that they are satisfied by $a_1\eta_1 + a_2\eta_2$ whenever they are satisfied by η_1 and η_2 , two functions of class C' on $[x_1x_2]$. We thus obtain a generalization of Theorem I indicated by Hadamard.[†]

On the other hand, to obtain Theorem II as a special case of Theorem III, we identify the set \mathfrak{P} with the totality of all triples p = (x, y, z) formed with three independent variables x, y, z,

^{*} I had originally thought it necessary to add to the assumptions A) and B) of the theorem the further assumption that $\Delta \neq 0$ for some system p_1, p_2, \dots, p_m ; I am indebted to Professor Moore for calling my attention to the fact that this assumption may be omitted, as well as for other valuable suggestions.

[†]loc. cit., §176.

each ranging over all real values, and define, in Cayley's set notation,

(15)
$$F(a_1, a_2; p_1, p_2) = a_1(x_1, y_1, z_1) + a_2(x_2, y_2, z_2), i. e., \equiv (a_1x_1 + a_2x_2, a_1y_1 + a_2y_2, a_1z_1 + a_2z_2).$$

 $F(a_1, a_2; p_1, p_2)$ belongs again to \mathfrak{P} , however the numbers a_1, a_2 and the triples $p_1 = (x_1, y_1, z_1)$ and $p_2 = (x_2, y_2, z_2)$ may be chosen.

With this definition of F, the functions

(19)
$$\mu_j(p) = A_j x + B_j y + C_j z, \quad (j = 0, 1, 2)$$

are "linear as to F."

If n = 2, there exists at least one pair of triples (x_1, y_1, z_1) , (x_2, y_2, z_2) for which the determinant

$$\begin{vmatrix} A_1 x_1 + B_1 y_1 + C_1 z_1, & A_2 x_1 + B_2 y_1 + C_2 z_1 \\ A_1 x_2 + B_1 y_2 + C_1 z_2, & A_2 x_2 + B_2 y_2 + C_2 z_2 \end{vmatrix} \neq 0.$$

This means geometrically, if we interpret x, y, z as homogeneous coordinates of a point in a plane, that the two lines

(20)
$$A_1x + B_1y + C_1z = 0, A_2x + B_2y + C_2z = 0$$

do not coincide.

Theorem III then specializes into Theorem II.

The assumption n = 1 leads to the trivial case alluded to on page 403, footnote *.

In like manner the corresponding theorems on pencils and bundles of planes and their generalizations to spaces of higher dimensions follow immediately as special cases from Theorem III.

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