# A SHORT PROOF OF A THEOREM OF PLANS ON THE HOMOLOGY OF THE BRANCHED CYCLIC COVERINGS OF A KNOT 

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Let $K \subset S^{3}$ be a (tame) knot, with complement $C=S^{3}-K$, and let $\tilde{C}$ be the infinite cyclic covering of $K$, i.e. the covering of $C$ corresponding to the commutator subgroup of $\pi_{1}(C)$. The group of covering translations of $\tilde{C}$ is $H_{1}(C)$, which is infinite cyclic by Alexander duality; this gives an action of $\boldsymbol{Z}$ on $H_{1}(\widetilde{C})$, and so $H_{1}(\widetilde{C})$ becomes a $\Lambda$ module, where $\Lambda$ is the integral group ring of $\boldsymbol{Z}$. We identify $\Lambda$ with the ring of polynomials in a single variable $t$, (positive and negative powers of $t$ being allowed), with integral coefficients. (See [4].)

The $k$-fold branched cyclic covering of $K, M_{k}(k \geqq 1)$ is defined by taking the covering of $C$ corresponding to the kernel of the composition:

$$
\pi_{1}(C) \rightarrow H_{1}(C) \cong Z \rightarrow Z_{k}
$$

and branching about $K$. (For more details, see [1], [4].) $M_{k}$ is a closed, orientable 3-manifold: for example, $M_{1}$ is just $S^{3}$.

If $M(t)=\left(m_{i j}(t)\right), m_{i j}(t) \in \Lambda$, is a presentation matrix for $H_{1}(\widetilde{C})$ as a $\Lambda$-module, then it can be shown that a presentation matrix for $H_{1}\left(M_{k}\right)$ ( $k>1$ ) as an abelian group is obtained by substituting for each entry $m_{i j}(t)$, which is some finite formal sum, $\sum_{\nu} \alpha_{\nu} t^{\nu}$, say, the $k \times k$ block $\sum_{\nu} \alpha_{\nu} T_{k}^{\nu}$, where the summation indicates ordinary matrix addition, and $T_{k}$ is the $k \times k$ matrix:

$$
\left(\begin{array}{cccccc}
0 & 1 & 0 & 0 & \cdots & 0 \\
0 & 0 & 1 & 0 & \cdots & 0 \\
0 & 0 & 0 & 1 & \cdots & 0 \\
\vdots & & & \ddots & \vdots \\
0 & 0 & 0 & 0 & \cdots & i \\
1 & 0 & 0 & 0 & \cdots & 0
\end{array}\right)
$$

[^0](and $T_{k}^{0}$ is defined to be the $k \times k$ identity matrix). (See [2], [4].) Call the matrix obtained from $M(t)$ in this way $M\left(T_{k}\right)$.

Now a geometrical description of $\tilde{C}$, in terms of an orientable surface spanning $K$, shows that we may take $M(t)$ to be of the form $t V-V^{T}$, where $V$ is a $2 h \times 2 h$ matrix over $\boldsymbol{Z}$ ( $h \geqq$ the genus of $K$ ) and $V^{T}$ is the transpose of $V$. (See [1], [6].) $M\left(T_{k}\right)$ is then $2 h k \times 2 h k$, but Seifert showed (see [1], [6]) that it is in fact equivalent (in the sense of presenting the same abelian group) to a $2 h \times 2 h$ matrix, $F_{k}$ say. In [5], Plans shows that this $F_{k}$ can be expressed in terms of two matrices $P_{k}$ and $Q_{k}$, which in turn are defined by certain recurrence relations analogous to those defining the Fibonacci numbers. These facts are used to effect a diagonalisation of $F_{k}$, from which some interesting general conclusions about $H_{1}\left(M_{k}\right)$ are drawn, perhaps the most striking being the following:

Theorem (Plans). If $k$ is odd, then $H_{1}\left(M_{k}\right)$ is a direct double, i.e. $H_{1}\left(M_{k}\right) \cong G \oplus G$, for some $G$.

The proof given in [5] is rather long and involved, and it is the purpose of this note to show that, although $F_{k}$ is smaller than $M\left(T_{k}\right)$, the above result actually follows very easily from an examination of the big matrix.

Proof. $M(t)=t V-V^{T}$. So by a suitable sequence of row interchanges and column interchanges, $M\left(T_{k}\right)$ can be brought into the form:

$$
\left(\begin{array}{ccccccc}
-V^{T} & V & 0 & 0 & \cdots & 0 & 0 \\
0 & -V^{T} & V & 0 & \cdots & 0 & 0 \\
0 & 0 & -V^{T} & V & \cdots & 0 & 0 \\
\vdots & & & . & \cdot & \vdots & \vdots \\
\vdots & & & \cdot & . & . & \vdots \\
\vdots & & & & . & \vdots & . \\
0 & 0 & 0 & 0 & \cdots & -V^{T} & \dot{V} \\
V & 0 & 0 & 0 & \cdots & 0 & -V^{T}
\end{array}\right)
$$

a $k \times k$ matrix of $2 h \times 2 h$ blocks.
Now if $k$ is odd, $k=2 r+1$ say, a further sequence of row interchanges gives a matrix in which the rows of blocks occur in the order (numbering them according to their positions in the old matrix): $r+1, r+2, \cdots, 2 r+1,1,2, \cdots, r$. It is easy to see that this new matrix is skew-symmetric. We illustrate the case $k=7$ :

$$
\left(\begin{array}{ccccccc}
0 & 0 & 0 & -V^{T} & V & 0 & 0 \\
0 & 0 & 0 & 0 & -V^{T} & V & 0 \\
0 & 0 & 0 & 0 & 0 & -V^{T} & V \\
V & 0 & 0 & 0 & 0 & 0 & -V^{T} \\
-V^{T} & V & 0 & 0 & 0 & 0 & 0 \\
0 & -V^{T} & V & 0 & 0 & 0 & 0 \\
0 & 0 & -V^{T} & V & 0 & 0 & 0
\end{array}\right)
$$

But it is well known (see for example [3, p. 52]) that any skewsymmetric $2 n \times 2 n$ matrix over $\boldsymbol{Z}$ is equivalent to a block diagonal matrix of the form:

$$
\sum_{i=1}^{n}\left(\begin{array}{ll}
a_{i} & 0 \\
0 & a_{i}
\end{array}\right) \quad\left(a_{i} \geqq 0\right)
$$

and hence presents a direct double.

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[^0]:    AMS 1970 subject classifications. Primary 55A10, 55A25.
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