

(O) and (L) (§I, Theorem 2), the sphere (G) having G for center and orthogonal to (Q) (§II, Theorem 1) is the second sphere of anti-similitude of (O) and (L); hence (G) is coaxial with these spheres.

THEOREM 3. *The four spheres having for centers the vertices of a tetrahedron and orthogonal to the quasi-polar sphere cut the spheres having for diameters the respective medians of the tetrahedron along four circles belonging to the same sphere, namely, the (G)-sphere of the tetrahedron.*

The sphere (A) having A for center and orthogonal to the sphere (Q) is coaxial with the spheres (G) and (AG_a), for the centers of these three spheres are collinear and all three are orthogonal to (Q). Similarly for the vertices B, C, D of (T).

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EUCLIDEAN CONCOMITANTS OF THE TERNARY CUBIC

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1. Introduction; construction of concomitants. In this paper we use the results of Cramlet [1] and the writer [2] to study the euclidean concomitants of the ternary cubic curve

$$T_{abc}X^aX^bX^c = 0,$$

where $a, b, c = 1, 2, 3$ and T_{abc} is symmetric. With tensor algebra as the medium of investigation all types of concomitants are readily constructed, and their geometric interpretations are also readily made in most cases. As is conventional in classical invariant theory, the word concomitant will be used as meaning rational integral concomitant unless stated to the contrary.

As a consequence of Theorem 3 in [2], we have the following theorem.

THEOREM I. *Every euclidean concomitant of the ground form $T_{abc}X^aX^bX^c$ ($a, b, c = 1, 2, 3$) is expressible by composition as a tensor of order zero with the use of the coefficient tensor T_{abc} , the variable coordinate tensors X^a and U_a , and the numerical tensors ϵ^{abc} , L_a , and E^{ab} .*

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The tensor ϵ_{abc} will not appear here since we are dealing with a ground form in X^a . In detail,

$$L_a = [0, 0, 1], \quad E^{ab} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

It is convenient to introduce the tensor A^{ab} , where

$$A^{ab} = \epsilon^{abc}L_c = \begin{bmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

Theorem 3 of [2] is the first fundamental theorem of euclidean invariant theory in tensor form, and Theorem I above is the particular form of it which we need here; this theorem constitutes a basis for the construction of concomitants.

2. Reduction of concomitants. In [2] an algebraically complete system of euclidean invariants for the cubic $T_{abc}X^aX^bX^c=0$ is given in tensor form. For the conic $C_{ab}X^aX^b=0$ the familiar algebraically complete system of three invariants is also an irreducibly complete system. But this is not true for the cubic. In this paper we shall find an irreducible system, complete through the fifth degree, of euclidean invariants for the cubic, and shall investigate geometric interpretation of these invariants in connection with other concomitants of the ground form. It is generally recognized that the problem of reduction of concomitants is more difficult than the problem of construction. See H. Weyl [3].

It is of interest to note that between the simple case of the conic and the situation for the general cubic is that of the degenerate cubic considered as the line $B_aX^a=0$ and the conic $C_{ab}X^aX^b=0$. They have the irreducibly complete system of eight invariants

$$\begin{aligned} I_1 &= B_aB_bE^{ab}, & I_2 &= C_{ab}C_{cd}C_{ef}\epsilon^{ace}\epsilon^{bdf}, & I_3 &= C_{ab}C_{cd}A^{ac}A^{bd}, \\ I_4 &= C_{ab}E^{ab}, & I_5 &= C_{ab}E^{ac}E^{bd}B_cB_d, & I_6 &= C_{ac}C_{bd}\epsilon^{abe}\epsilon^{cdf}B_eB_f, \\ I_7 &= C_{ab}C_{cd}\epsilon^{ace}A^{bd}B_e, & I_8 &= C_{ab}A^{ac}E^{bd}B_cB_d. \end{aligned}$$

Six of these are algebraically independent; they may be chosen as I_1, \dots, I_6 ; then I_7 and I_8 are expressible in terms of them by means of the syzygies

$$\begin{aligned} 3(I_7)^2 &\equiv 3I_3I_6 - 2I_1I_2I_4 - 2I_2I_5, \\ (I_8)^2 &\equiv I_1I_4I_5 - (I_5)^2 - \frac{1}{2}(I_1)^2I_3. \end{aligned}$$

The five invariants $I_2, I_3, I_6, I_7,$ and $C_{ab}A^{ac}A^{bd}B_cB_d$ form an irreducibly complete system of affine invariants for the line and conic. They were studied recently by Weitzenböck [4], who used the symbolic notation of his text [5].

We now state the second fundamental theorem in the detailed and explicit tensor form needed to investigate the relations on the concomitants constructed in accordance with the first fundamental theorem.

THEOREM II. *Every identity satisfied by the concomitants constructed by the first fundamental theorem for a set of ground forms in X^a can be established with the basic identities:*

- I den 1. $\epsilon^{abc}E^{de} \equiv \epsilon^{dbc}E^{ae} + \epsilon^{adc}E^{be} + \epsilon^{abd}E^{ce},$
- I den 2. $\epsilon^{abc}X^d \equiv \epsilon^{dbc}X^a + \epsilon^{adc}X^b + \epsilon^{abd}X^c,$
- I den 3. $\epsilon^{abc}\epsilon^{def} \equiv \epsilon^{dbc}\epsilon^{aef} + \epsilon^{adc}\epsilon^{bef} + \epsilon^{abd}\epsilon^{cef},$
- I den 4. $A^{ab}A^{cd} \equiv E^{ac}E^{bd} - E^{ad}E^{bc},$
- I den 4'. $E^{ac}E^{bd} \equiv A^{ab}A^{cd} + E^{ad}E^{bc},$
- I den 5. $A^{ab}E^{cd} \equiv A^{cb}E^{ad} + A^{ac}E^{bd},$
- I den 6. $A^{ab}X^c \equiv A^{cb}X^a + A^{ac}X^b + \epsilon^{abc}L_dX^d,$
- I den 7. $A^{ab}\epsilon^{cde} \equiv A^{cb}\epsilon^{ade} + A^{ac}\epsilon^{bde} + \epsilon^{abc}A^{de},$
- I den 8. $\epsilon^{abc}A^{de} \equiv \epsilon^{dbc}A^{ae} + \epsilon^{adc}A^{be} + \epsilon^{abd}A^{ce},$
- I den 9. $A^{ab}A^{cd} \equiv A^{cb}A^{ad} + A^{ac}A^{bd},$
- I den 10. $E^{ab}E^{cd}E^{ef} \equiv E^{ab}E^{cf}E^{ed} + E^{ad}E^{cb}E^{ef} - E^{ad}E^{cf}E^{eb} - E^{af}E^{cb}E^{ed} + E^{ad}E^{cf}E^{eb},$
- I den 11. $X^aE^{bc}E^{de} \equiv X^aE^{be}E^{dc} + E^{ac}X^bE^{de} - E^{ac}E^{be}X^d - E^{ae}X^bE^{dc} + E^{ae}E^{bc}X^d + \epsilon^{abd}A^{ec}L_fX^f.$

I den 2 may be established by expanding

$$\begin{vmatrix} \delta_1^a & \delta_2^a & \delta_3^a & X^a \\ \delta_1^b & \delta_2^b & \delta_3^b & X^b \\ \delta_1^c & \delta_2^c & \delta_3^c & X^c \\ \delta_1^d & \delta_2^d & \delta_3^d & X^d \end{vmatrix} \equiv 0,$$

and using

$$\epsilon^{abc} = \begin{vmatrix} \delta_1^a & \delta_2^a & \delta_3^a \\ \delta_1^b & \delta_2^b & \delta_3^b \\ \delta_1^c & \delta_2^c & \delta_3^c \end{vmatrix}.$$

Most of the other identities are consequences of I den 2 in rather obvious ways. We remark briefly about some not of this class. To obtain I den 4 consider

$$A^{ab} A^{cd} \equiv \epsilon^{ab3} \epsilon^{cd3} = \begin{vmatrix} \delta_1^a & \delta_2^a \\ \delta_1^b & \delta_2^b \end{vmatrix} \cdot \begin{vmatrix} \delta_1^c & \delta_1^d \\ \delta_2^c & \delta_2^d \end{vmatrix} \equiv \begin{vmatrix} E^{ac} & E^{ad} \\ E^{bc} & E^{bd} \end{vmatrix}.$$

Iden 10 may be obtained from the determinantal product

$$\begin{vmatrix} \delta_1^a & \delta_2^a & \delta_3^a \\ \delta_1^b & \delta_2^b & \delta_3^b \\ \delta_1^c & \delta_2^c & \delta_3^c \end{vmatrix} \cdot \begin{vmatrix} \delta_1^d & \delta_1^e & \delta_1^f \\ \delta_2^d & \delta_2^e & \delta_2^f \\ 0 & 0 & 0 \end{vmatrix} \equiv 0,$$

and Iden 11 from

$$\begin{vmatrix} \delta_1^a & \delta_2^a & \delta_3^a \\ \delta_1^b & \delta_2^b & \delta_3^b \\ \delta_1^c & \delta_2^c & \delta_3^c \end{vmatrix} \cdot \begin{vmatrix} \delta_1^d & \delta_1^e & X^1 \\ \delta_2^d & \delta_2^e & X^2 \\ 0 & 0 & X^3 \end{vmatrix} \equiv \epsilon^{abc} A^{de} L_f X^f.$$

That these identities constitute a reduction basis for the concomitants constructed by the first fundamental theorem may be seen by observing that they give the alternate ways of writing all types of products which arise.

3. An irreducible system, complete through the fifth degree, of euclidean invariants for the cubic $T_{abc} X^a X^b X^c$. We note that the cubic has only one "formal" invariant of the first degree, $T_{abc}\epsilon^{abc}$, and this vanishes identically due to the skew-symmetry of ϵ^{abc} ; so (i) for the cubic there is no invariant of the first degree.

We can construct three (and only three) invariants of the second degree:

$$A = T_{a_1 a_2 a_3} T_{b_1 b_2 b_3} E^{a_1 a_2} E^{b_1 b_2} E^{a_3 b_3}, \quad B = T_{a_1 a_2 a_3} T_{b_1 b_2 b_3} E^{a_1 b_1} E^{a_2 b_2} E^{a_3 b_3}, \\ C = T_{a_1 a_2 a_3} T_{b_1 b_2 b_3} A^{a_1 b_1} A^{a_2 b_2} E^{a_3 b_3}.$$

Invariants as $T_{a_1 a_2 a_3} T_{b_1 b_2 b_3} A^{a_1 b_1} A^{a_2 b_2} A^{a_3 b_3}$ and $T_{a_1 a_2 a_3} T_{b_1 b_2 b_3} A^{a_1 a_2} E^{b_1 b_2} E^{a_3 b_3}$ which vanish identically on the interchange of equivalent indices are not listed here, nor in similar circumstances in the future. In this connection one should keep in mind the skew-symmetry of ϵ^{abc} and of A^{ab} . The only identities applicable to A and B are Idens 4' and 10. The application of the latter to each of these merely gives $A \equiv A$ and $B \equiv B$. The application of Iden 4' to either of them results in $C \equiv A - B$. The only identities applicable to C are Idens 4 and 5. The first results in the relation just given, and the latter in $C \equiv C$. Thus $C \equiv A - B$ is the only relation on the invariants A, B, C . Therefore, (ii) for the cubic there are two irreducible invariants of the second degree, and these may be chosen as

$$II_1 = T_{a_1 a_2 a_3} T_{b_1 b_2 b_3} E^{a_1 a_2} E^{b_1 b_2} E^{a_3 b_3}, \quad II_2 = T_{a_1 a_2 a_3} T_{b_1 b_2 b_3} E^{a_1 b_1} E^{a_2 b_2} E^{a_3 b_3}.$$

Often we shall use the contracted notation

$${}^{(k)}T = T_{a_{11} a_{12} a_{13}} T_{a_{21} a_{22} a_{23}} \cdots T_{a_{k1} a_{k2} a_{k3}}.$$

To illustrate, $II_1 = {}_{(2)}T \cdot E^{a_1 a_2} E^{b_1 b_2} E^{a_3 b_3}$.

There are three invariants of the third degree to consider:

$$A = {}_{(3)}T \cdot A^{a_1 b_1} E^{b_2 c_1} A^{c_2 a_2} \epsilon^{a_3 b_3 c_3}, \quad B = {}_{(3)}T \cdot E^{a_1 c_1} E^{b_1 b_2} A^{c_2 a_2} \epsilon^{a_3 b_3 c_3},$$

$$C = {}_{(3)}T \cdot A^{a_1 b_1} A^{b_2 c_1} A^{c_2 a_2} \epsilon^{a_3 b_3 c_3}.$$

Applying Iden 5 to $A^{c_2 a_2} E^{b_1 b_2}$ of B , we get $B = -A - A$, or $B = -2A$. Applying Iden 4 to $A^{a_1 b_1} A^{b_2 c_1}$ of C , we obtain $C = A - B$. On application of the appropriate reduction formulas in all possible ways to A, B, C , it is found that there is no relation on these expressions other than the two given. Hence: (iii) For the cubic there is one irreducible invariant of the third degree, and this may be chosen as

$$III = (1/6) T_{a_1 a_2 a_3} T_{b_1 b_2 b_3} T_{c_1 c_2 c_3} A^{a_1 b_1} A^{b_2 c_1} A^{a_2 c_2} \epsilon^{a_3 b_3 c_3}.$$

The number of formal invariants which one can construct increases rapidly as the degree goes beyond three. Their consideration is facilitated by considering all invariants of a certain type together. (iv-1) For the cubic there is only one invariant of the fourth degree which contains the numerical tensor ϵ^{abc} four times, and this is irreducible, it being the well known projective invariant of the fourth degree

$$IV_1 = {}_{(4)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{a_2 b_2 d_1} \epsilon^{a_3 c_2 d_2} \epsilon^{b_3 c_3 d_3}.$$

There are six invariants of the fourth degree which contain factors like ϵ^{abc} twice, the remaining factors being like E^{ab} :

$$A = {}_{(4)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{a_2 b_2 c_2} E^{a_3 d_1} E^{b_3 d_2} E^{c_3 d_3}, \quad B = {}_{(4)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{a_2 b_2 c_2} E^{a_3 b_3} E^{c_3 d_1} E^{d_2 d_3},$$

$$C = {}_{(4)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{b_2 c_2 d_1} E^{a_2 a_3} E^{b_3 c_3} E^{d_2 d_3}, \quad D = {}_{(4)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{b_2 c_2 d_1} E^{a_2 a_3} E^{b_3 d_2} E^{c_3 d_3},$$

$$E = {}_{(4)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{b_2 c_2 d_1} E^{a_2 d_2} E^{a_3 d_3} E^{b_3 c_3}, \quad F = {}_{(4)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{b_2 c_2 d_1} E^{a_2 b_2} E^{c_3 d_2} E^{a_3 d_3}.$$

Applying the basic identities in all possible ways, we find that these invariants are connected by the relations

$$A \equiv D + 2F; \quad B \equiv E + 2F; \quad B \equiv C + 2D; \quad C \equiv 2D + E - 2F;$$

and only these. Therefore: (iv-2) For the cubic there are two irreducible invariants of the fourth degree which contain factors like ϵ^{abc} twice, the remaining factors being like E^{ab} , and these may be chosen as

$$IV_2 = {}_{(4)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{b_2 c_2 d_1} E^{a_2 a_3} E^{b_3 c_3} E^{d_2 d_3},$$

$$IV_3 = {}_{(4)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{b_2 c_2 d_1} E^{a_2 b_2} E^{c_3 d_2} E^{a_3 d_3}.$$

Like considerations lead us to the conclusions: (iv-3) For the cubic there is one irreducible invariant of the fourth degree which contains factors like ϵ^{abc} twice, the other factors being like E^{ab} , and this may be chosen as

$$IV_4 = {}_{(4)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{a_2 b_2 c_2} E^{b_3 c_3} E^{d_1 d_2} A^{a_3 d_3}.$$

(iv-4) For the cubic there is one irreducible invariant of the fourth degree whose numerical tensor product is composed entirely of factors like E^{ab} , except for one factor like A^{ab} , and this may be chosen as

$$IV_5 = {}_{(4)}T \cdot E^{a_1 a_2} A^{a_3 b_1} E^{b_2 c_2} E^{b_3 c_1} E^{c_3 d_1} E^{d_2 d_3}.$$

For invariants of the fourth degree constructed wholly with the aid of E^{ab} , there are five possibilities:

$$A = {}_{(4)}T \cdot E^{a_1 a_2} E^{a_3 b_1} E^{b_2 c_1} E^{b_3 c_2} E^{c_3 d_1} E^{d_2 d_3},$$

$$B = {}_{(4)}T \cdot E^{a_1 b_1} E^{a_2 b_2} E^{a_3 c_1} E^{b_3 d_1} E^{c_2 d_2} E^{c_3 d_3},$$

$$C = {}_{(4)}T \cdot E^{a_1 b_1} E^{a_2 c_1} E^{a_3 d_1} E^{b_2 c_2} E^{b_3 d_2} E^{c_3 d_3},$$

$$D = {}_{(4)}T \cdot E^{a_1 a_2} E^{a_3 b_1} E^{b_2 c_1} E^{b_3 d_1} E^{c_2 d_2} E^{c_3 d_3},$$

$$E = {}_{(4)}T \cdot E^{a_1 a_2} E^{a_3 b_1} E^{b_2 c_1} E^{b_3 d_1} E^{c_2 c_3} E^{d_2 d_3}.$$

Applying the identities 1–11 in all possible ways it is found that there are four and only four relations on these expressions; so: (iv-5) For the cubic there is only one irreducible invariant constructed wholly with the aid of E^{ab} , of the fourth degree, and this may be chosen as

$$IV_6 = {}_{(4)}T \cdot E^{a_1 a_2} E^{a_3 b_1} E^{b_2 c_1} E^{b_3 c_2} E^{c_3 d_1} E^{d_2 d_3}.$$

Then

$$B \equiv IV_6 + (1/2)(II_2)^2 - (1/2)(II_1)^2,$$

$$C \equiv IV_6 + II_1 \cdot II_2 - (II_1)^2,$$

$$D \equiv IV_6 + (1/2)II_1 \cdot II_2 - (1/2)(II_1)^2,$$

$$E \equiv IV_6 + (1/2)(II_1)^2 - (1/2)II_1 \cdot II_2.$$

All other invariants of the fourth degree are found to be reducible; so we may summarize as follows: (iv) For the cubic there are six irreducible invariants of the fourth degree, and these may be chosen as $IV_1, IV_2, IV_3, IV_4, IV_5, IV_6$.

In a similar manner it is found that: (v) For the cubic there are two irreducible invariants of the fifth degree, and these may be chosen as

$$V_1 = {}_{(5)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{a_2 b_2 c_2} \epsilon^{a_3 d_1 e_1} A^{d_2 e_2} E^{b_3 c_3} E^{d_3 e_3},$$

$$V_2 = {}_{(5)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{a_2 b_2 c_2} \epsilon^{a_3 d_1 e_1} A^{b_3 e_2} E^{d_2 d_3} A^{c_3 e_3}.$$

A typical reduction is that of $A = {}_{(5)}T \cdot \epsilon^{d_1 b_1 c_1} A^{a_1 b_2} E^{a_2 d_2} E^{c_2 c_3} E^{b_3 d_3} E^{a_3 e_1} E^{e_2 e_3}$. Iden 5 applied to $A^{a_1 b_2} E^{d_2 a_2}$ of A gives $A \equiv 4II_1 \cdot III - A$, or $A \equiv 2II_1 \cdot III$.

We may combine (i), (ii), (iii), (iv), (v) in the following theorem.

THEOREM III. *For the cubic $T_{abc}X^aX^bX^c$ ($a, b, c = 1, 2, 3$) there are eleven irreducible euclidean invariants of degree less than six, and these may be chosen as $II_1, II_2, III, IV_1, IV_2, IV_3, IV_4, IV_5, IV_6, V_1, V_2$.*

4. An irreducible system, complete through the fourth degree, of euclidean covariants for the cubic. There seems to have been no systematic study of euclidean covariants for the cubic curve of the third order. The best known are the Hessian, the polar conic of the line at infinity, and the Laplacian. We shall often speak of a covariant of degree i in T_{abc} and order j in X^a as a (i, j) covariant. The line at infinity is a $(0, 1)$ covariant, having for its equation $\mathfrak{L} = L_a X^a = X^3 = 0$.

4.1. *(i, 1) covariants.* For the cubic $T_{abc}X^aX^bX^c$ there is only one $(1, 1)$ covariant, and this is $L_1 = T_{abc}E^{ab}X^c$. There is no $(2, 1)$ covariant. There are four irreducible $(3, 1)$ covariants, and these may be chosen as

$$L_{31} = {}_{(3)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{a_2 b_2 c_2} E^{b_3 c_3} X^{a_3}, \quad L_{32} = {}_{(3)}T \cdot E^{a_1 b_1} E^{a_2 c_1} E^{c_2 c_3} E^{b_2 b_3} X^{a_3},$$

$$L_{33} = {}_{(3)}T \cdot A^{a_1 b_1} E^{a_2 c_1} E^{b_2 c_2} E^{b_3 c_3} X^{a_3}, \quad L_{34} = {}_{(3)}T \cdot A^{a_1 b_1} E^{a_2 c_1} E^{b_2 b_3} E^{c_1 c_2} X^{a_3}.$$

The other $(3, 1)$ covariants

$$A = {}_{(3)}T \cdot E^{a_1 b_1} E^{a_2 c_1} E^{b_2 c_2} E^{b_3 c_3} X^{a_3}, \quad B = {}_{(3)}T \cdot E^{a_1 b_1} E^{a_2 b_2} E^{b_3 c_1} E^{c_2 c_3} X^{a_3},$$

$$C = {}_{(3)}T \cdot A^{a_1 b_1} E^{a_2 b_2} E^{b_3 c_1} E^{c_2 c_3} X^{a_3}, \quad D = {}_{(3)}T \cdot E^{a_1 b_1} E^{a_2 b_2} A^{b_3 c_1} E^{c_2 c_3} X^{a_3},$$

are expressible in terms of the irreducible ones by the relations:

$$A \equiv L_{32} + (II_2 - II_1) + 2III \cdot \mathfrak{L},$$

$$B \equiv L_{32} + (1/2)(II_2 - II_1)L_1 + 2III \cdot \mathfrak{L},$$

$$C \equiv L_{33},$$

$$D \equiv L_{34} - L_{33}.$$

In like manner it is found that there is only one irreducible $(4, 1)$ covariant, and this may be chosen as

$$L_4 \equiv {}_{(4)}T \cdot \epsilon^{a_1 b_1 c_1} E^{a_2 b_2} E^{d_1 d_2} E^{b_3 c_2} E^{c_3 d_3} X^{a_3}.$$

Therefore we have this theorem.

THEOREM IV. *For the cubic there are seven irreducible (i, 1) euclidean covariants (i=0, 1, 2, 3, 4), and these may be chosen as $\mathfrak{L}, L_1, L_{31}, L_{32}, L_{33}, L_{34},$ and $L_4.$*

4.2. (i, 2) covariants. Obviously there is no (1, 2) covariant. There are four (2, 2) covariants:

$$A = {}_{(2)}T \cdot E^{a_1 b_1} E^{a_2 b_2} X^{a_3} X^{b_3}, \quad B = {}_{(2)}T \cdot A^{a_1 b_1} A^{a_2 b_2} X^{a_3} X^{b_3},$$

$$C = {}_{(2)}T \cdot A^{a_1 b_1} E^{b_2 b_3} X^{a_2} X^{a_3}, \quad D = {}_{(2)}T \cdot E^{a_1 b_1} E^{b_2 b_3} X^{a_2} X^{a_3}.$$

The expressions C and D contain no significant reducible factor, and consequently are irreducible. Iden 4 applied to $A^{a_1 b_1} A^{a_2 b_2}$ gives $B \equiv (L_1)^2 - A.$ This is the only relation that exists on A and B ; so (i) there are three irreducible (2, 2) covariants, and these may be chosen as

$$C_{21} = {}_{(2)}T \cdot A^{a_1 b_1} A^{a_2 b_2} X^{a_3} X^{b_3}, \quad C_{22} = {}_{(2)}T \cdot A^{a_1 b_1} E^{b_2 b_3} X^{a_2} X^{a_3},$$

$$C_{23} = {}_{(2)}T \cdot E^{a_1 b_1} E^{b_2 b_3} X^{a_2} X^{a_3}.$$

One may construct three (3, 2) covariants

$$A = {}_{(3)}T \cdot \epsilon^{a_1 b_1 c_1} A^{a_2 b_2} E^{c_2 c_3} X^{a_3} X^{b_3}, \quad B = {}_{(3)}T \cdot \epsilon^{a_1 b_1 c_1} A^{a_2 c_2} E^{b_2 c_3} X^{a_3} X^{b_3},$$

$$C = {}_{(3)}T \cdot \epsilon^{a_1 b_1 c_1} A^{b_2 c_2} E^{b_3 c_3} X^{a_2} X^{a_3}.$$

Applying Iden 5 to $A^{a_2 b_2} C^{c_2 c_3}$ of A we obtain $A \equiv 2B.$ Iden 6 applied to $A^{a_2 c_2} X^{b_3}$ of B gives $B \equiv C - B - L_{31} \cdot \mathfrak{L},$ or $2B \equiv C - L_{31} \cdot \mathfrak{L}.$ There is no other relation on these expressions. Therefore (ii) there is one irreducible (3, 2) covariant, and this may be chosen as

$$C_3 = {}_{(3)}T \cdot \epsilon^{a_1 b_1 c_1} A^{b_2 c_2} E^{b_3 c_3} X^{a_2} X^{a_3}.$$

(iii) By a similar procedure it is found that there are five irreducible (4, 2) covariants, and these may be chosen as

$$C_{41} = {}_{(4)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{a_2 b_2 c_2} E^{c_3 d_1} E^{d_2 d_3} X^{a_3} X^{b_3},$$

$$C_{42} = {}_{(4)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{a_2 b_2 d_1} E^{c_2 c_3} E^{d_2 d_3} X^{a_3} X^{b_3},$$

$$C_{43} = {}_{(4)}T \cdot \epsilon^{b_1 c_1 d_1} \epsilon^{b_2 c_2 d_2} E^{a_1 b_3} E^{c_3 d_3} X^{a_2} X^{a_3},$$

$$C_{44} = {}_{(4)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{a_2 b_2 c_2} E^{d_1 d_2} A^{c_3 d_3} X^{a_3} X^{b_3},$$

$$C_{45} = {}_{(4)}T \cdot \epsilon^{b_1 c_1 d_1} \epsilon^{b_2 c_2 d_2} E^{c_3 d_3} A^{b_3 a_1} X^{a_2} X^{a_3}.$$

Combining (i), (ii), and (iii) we have this theorem

THEOREM V. *For the cubic there are nine irreducible (i, 2) euclidean covariants (i=1, 2, 3, 4), and these may be chosen as $C_{21}, C_{22}, C_{23}, C_3, C_{41}, C_{42}, C_{43}, C_{44}, C_{45}.$*

Using the general methods of construction and reduction as we have above, we find that this theorem follows.

THEOREM VI. *For the cubic ($i = 1, 2, 3, 4$): (i) there are six euclidean irreducible ($i, 3$) covariants, and these may be chosen as*

$$\begin{aligned} T_{31} &= {}_{(3)}T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{a_2 b_2 c_2} X^{a_3} X^{b_3} X^{c_3}, \\ T_{32} &= {}_{(3)}T \cdot A^{a_1 b_1} E^{b_2 c_1} E^{c_2 c_3} X^{b_3} X^{a_2} X^{a_3}, \\ T_{33} &= {}_{(3)}T \cdot A^{b_1 c_1} E^{b_2 c_2} E^{a_1 c_3} X^{b_3} X^{a_2} X^{a_3}, \\ T_{41} &= {}_{(4)}T \cdot \epsilon^{a_1 b_1 c_1} E^{b_2 d_1} E^{c_2 d_2} E^{c_3 d_3} X^{b_3} X^{a_2} X^{a_3}, \\ T_{42} &= {}_{(4)}T \cdot \epsilon^{d_1 b_1 c_1} E^{b_2 c_2} E^{a_1 d_2} E^{c_3 d_3} X^{b_3} X^{a_2} X^{a_3}, \\ T &= T_{abc} X^a X^b X^c. \end{aligned}$$

(ii) *There are three irreducible ($i, 4$) covariants, and these may be chosen as*

$$\begin{aligned} Q_2 &= {}_{(2)}T \cdot E^{a_1 b_1} X^{a_2} X^{a_3} X^{b_2} X^{b_3}, \quad Q_{41} = {}_{(4)}T \cdot \epsilon^{b_1 c_1 d_1} \epsilon^{b_2 c_2 d_2} E^{a_1 d_3} X^{a_2} X^{b_2} X^{c_3}, \\ Q_{42} &= {}_{(4)}T \cdot \epsilon^{b_1 c_1 d_1} \epsilon^{b_2 c_2 d_2} A^{a_1 d_3} X^{a_2} X^{a_3} X^{b_3} X^{c_3}. \end{aligned}$$

(iii) *There are two irreducible quintics, and these may be chosen as*

$$\begin{aligned} R_3 &= {}_{(3)}T \cdot E^{a_1 c_1} A^{b_1 c_2} X^{a_2} X^{a_3} X^{b_2} X^{b_3} X^{c_3}, \\ R_4 &= {}_{(4)}T \cdot \epsilon^{a_1 c_1 d_1} E^{b_1 c_2} E^{d_2 d_3} X^{a_2} X^{a_3} X^{b_2} X^{b_3} X^{c_3}. \end{aligned}$$

(iv) *There is no irreducible covariant for $i < 5, j > 6$.*

5. Geometric interpretations. It should be understood that the general cubic curve given by the general equation of the third degree in X^a ,

$$T = T_{abc} X^a X^b X^c = 0,$$

($a, b, c = 1, 2, 3$ and T_{abc} symmetric) is under consideration here. For such cubic no invariant is zero, and no covariant vanishing identically, unless specifically stated so. The point $P_2 = T_{a_1 a_2 a_3} T_{b_1 b_2 b_3} \cdot \epsilon^{a_1 b_1 c_1} A^{a_2 b_2} E^{a_3 b_3} U_r = 0$ in expanded form is

$$\begin{aligned} &(T_{112} T_{123} + T_{122} T_{223} - T_{122} T_{113} - T_{123} T_{222}) U_1 \\ &(T_{122} T_{123} + T_{112} T_{113} - T_{112} T_{223} - T_{111} T_{123}) U_2 \\ &(T_{111} T_{112} - (T_{112})^2 - (T_{122})^2 + T_{112} T_{222}) U_3 = 0. \end{aligned}$$

Keeping this expanded form in mind, and examining the contents of the paper by Thomae [6], or that by Stuyvaert [7], we observe the truth of this theorem.

THEOREM VII. P_2 is the unique point whose polar conic is a circle.

When we speak of the polar of a point (or of the pole of a line), unless specified to the contrary, we mean with respect to the fundamental cubic T .

THEOREM VIII. (a) *The polar conic of P_2 is C_3 , and (b) C_3 is a circle.*

Obviously the polar conic of Y^a with respect to T has the equation $T_{abc}Y^aX^bX^c=0$. Let $Y^rU_r = T_{a_1a_2a_3}T_{b_1b_2b_3}\epsilon^{a_1b_1r}A^{a_2b_2}E^{a_3b_3}U_r$. Then (a) is evident, and (b) follows.

THEOREM IX. *Every covariant conic of the cubic T whose coefficients are of the third degree in T_{abc} is a circle.*

In §4.2 it was shown that one can construct three (3, 2) covariants, there designated by A, B, C , and that these are connected by the relations $A \equiv 2B$, and $2B \equiv C - L_{31} \cdot \wp$. By Theorem VIII, C_3 is a circle, and as a consequence of the relations just given A and B are also circles. Recall from §4 that there are no covariant conics of degree less than two, that there are covariant lines of the first and third degree, but none of the second, and further from §3 there is no invariant of degree less than two. As a consequence of these facts we conclude that every covariant conic Q of the third degree is of the form $Q \equiv k_1C_3 + k_2R$, where k_1 and k_2 are constants, and R is at most linear in X^a . But since C_3 is a circle, every such conic Q is a circle.

The condition that the polar conic of the point Y^a , $T_{abc}X^aX^bY^c$, be a rectangular hyperbola is that $(T_{11c} + T_{22c})Y^c = T_{abc}E^{ab}Y^c = 0$.

THEOREM X. *The line $L_1 = 0$ is the locus of points whose polar conics are rectangular hyperbolas.*

This line is called the Laplacian of the cubic. The cubic for which $L_1 \equiv 0$ has been studied by Brooks [8].

THEOREM X'. *The Laplacian of the Hessian $H = {}_{(3)}T \cdot \epsilon^{a_1b_1c_1}\epsilon^{a_2b_2c_2} \cdot X^{a_3}X^{b_3}X^{c_3} = 0$ is $L_{31} = 0$.*

Adapting the argument of White [9] to tensor notation, we find that the equation of the polar conic of the line $V_aX^a = 0$ with respect to T is

$$T_{a_1a_2a_3}T_{b_1b_2b_3}\epsilon^{a_1b_1p}\epsilon^{a_2b_2q}X^{a_3}X^{b_3}U_pU_q = 0.$$

If in this we replace U_p by $L_p = [0, 0, 1]$ and use $A^{ab} = \epsilon^{abc}L_c$, we have this next theorem.

THEOREM XI. *The polar conic of the line at infinity is $C_{21} = 0$.*

In like manner, we have this theorem.

THEOREM XI'. *The polar conic of the Laplacian is $C_{42} = 0$.*

The polar line of the point $Y^r U_r = 0$ with respect to $C_{21} = 0$ is

$$T_{a_1 a_2 a_3} T_{b_1 b_2 b_3} A^{a_1 b_1} A^{a_2 b_2} X^{a_3} X^{a_3} Y^{b_3} = 0.$$

In particular let $Y^r U_r = 0$ be P_2 . We have for the polar of P_2 with respect to C_{21}

$$\begin{aligned} K &= T_{a_1 a_2 a_3} T_{b_1 b_2 b_3} T_{c_1 c_2 c_3} T_{d_1 d_2 d_3} A^{a_1 b_1} A^{a_2 b_2} \epsilon^{c_1 d_1} b_1 A^{c_2 d_2} E^{c_3 d_3} X^{a_3} \\ &= 4III \cdot L_1 - {}_{(4)}T \cdot \epsilon^{d_1 b_1 c_1} A^{d_2 b_2} E^{d_3 b_3} E^{a_2 c_2} E^{a_3 c_3} X^{a_1} \text{ (by Iden 4)}. \end{aligned}$$

Using other identities we find that the last term is $2III \cdot L_1$; so $K \equiv 2III \cdot L_1$.

THEOREM XII. *The Laplacian of a cubic is the polar with respect to the polar conic of the line at infinity of the unique point whose polar conic is a circle.*

Rather evident are these theorems and corollary.

THEOREM XIII. *The polar conic of $T_{abc} E^{ab} A^{cr} U_r = 0$, the point at infinity on the Laplacian, is $C_{22} = 0$.*

COROLLARY. $C_{22} = 0$ is a rectangular hyperbola.

THEOREM XIV. *The polar conic of $T_{abc} E^{ab} E^{cr} U_r = 0$, the point at infinity in the direction perpendicular to the Laplacian, is $C_{23} = 0$.*

Taking the polar of $T_{abc} E^{ab} E^{cr} U_r = 0$ and $T_{abc} E^{ab} A^{cr} U_r = 0$, respectively, with respect to $C_{23} = 0$, we get these theorems.

THEOREM XV. *The diameter of the conic C_{23} conjugate to the direction perpendicular to the Laplacian is $L_{32} = 0$.*

THEOREM XVI. *The diameter of the conic C_{23} conjugate to the direction of the Laplacian is $L_{34} = 0$.*

The condition for two lines V_a and W_a to be perpendicular is that $V_a W_b E^{ab} = 0$, and the condition for them to be parallel is that $V_a W_b A^{ab} = 0$. From these a number of geometric facts follow quite directly:

A.1. The locus of points whose linear polars are parallel to the Laplacian is the conic $C_{22} = 0$.

2. The locus of points whose linear polars are perpendicular to the Laplacian is the conic $C_{23} = 0$.

3. The locus of points whose linear polars with respect to the Hessian are perpendicular to the Laplacian is the conic $C_{41} = 0$.

4. The locus of points whose linear polars with respect to the Hessian are parallel to the Laplacian is the conic $C_{44} = 0$.

5. The locus of points whose linear polars are perpendicular to the Laplacian of the Hessian is the conic $C_{43} = 0$.

6. The locus of points whose linear polars are parallel to the Laplacian of the Hessian is the conic $C_{45} = 0$.

7. The locus of points whose linear polars with respect to the fundamental cubic and the Hessian are perpendicular is the quartic $Q_{41} = 0$.

8. The locus of points whose linear polars with respect to the fundamental cubic and the Hessian are parallel is the quartic $Q_{42} = 0$.

9. The locus of points whose linear polars with respect to fundamental cubic and the quartic Q_2 are parallel is the quintic $R_3 = 0$.

10. The Laplacian of the fundamental cubic and the Laplacian of the Hessian are parallel if (and only if) $IV_4 = 0$, and they are perpendicular if

$$(4) T \cdot \epsilon^{a_1 b_1 c_1} \epsilon^{a_2 b_2 c_2} E^{b_3 c_3} E^{a_3 d_1} E^{d_2 d_3} \equiv IV_2 + 2IV_3 = 0.$$

11. The Laplacian and $L_{32} = 0$ are parallel if $IV_5 = 0$, and they are perpendicular if

$$(4) T \cdot E^{a_1 a_2} E^{a_3 b_1} E^{b_2 c_2} E^{b_3 c_3} E^{c_1 d_1} E^{d_2 d_3} \equiv IV_6 + (1/2)(II_1)^2 - (1/2)II_1 \cdot II_2 = 0.$$

The line $V_a X^a = 0$ is said to be minimal if $V_a V_b E^{ab} = 0$. Hence we have the following facts.

B.1. The Laplacian is a minimal line if (and only if) $II_1 = 0$.

2. The locus of points whose linear polars are minimal lines is the quartic $Q_2 = 0$.

Using the condition for incidence of the point V_a and the line Y^a , namely that $V_a Y^a = 0$, we get these statements.

C.1. P_2 , the unique point whose polar conic is a circle, lies on the Laplacian if $III = 0$.

2. P_2 lies on the Laplacian of the Hessian if $V_1 = 0$.

Not so direct is the next fact.

3. The line through P_2 and perpendicular to the Laplacian is $L_{33} = 0$.

6. Some concomitants in expanded form. We list a few typical concomitants in expanded form. These are obtained by carrying out the indicated summations in the tensor-invariant forms of the concomitants, using the defined values of the components of ϵ^{abc} , A^{ab} , and E^{ab} .

$$II_1 = T_{a_1 a_2 a_3} T_{b_1 b_2 b_3} E^{a_1 a_2} E^{b_1 b_2} E^{a_3 b_3} = (T_{111} + T_{122})^2 + (T_{112} + T_{222})^2,$$

$$II_2 = T_{a_1 a_2 a_3} T_{b_1 b_2 b_3} E^{a_1 b_1} E^{a_2 b_2} E^{a_3 b_3}$$

$$= (T_{111})^2 + 3(T_{112})^2 + 3(T_{122})^2 + (T_{222})^2,$$

$$III = (1/6)T_{a_1a_2a_3}T_{b_1b_2b_3}T_{c_1c_2c_3}A^{a_1b_1}A^{b_2c_2}A^{a_2c_2}e^{a_3b_3c_3}$$

$$= \begin{vmatrix} T_{111} & T_{112} & T_{113} \\ T_{211} & T_{212} & T_{213} \\ T_{221} & T_{222} & T_{223} \end{vmatrix},$$

$$IV_5 = {}_{(4)}T \cdot E^{a_1a_2}A^{a_3b_1}E^{b_2c_1}E^{b_3c_2}E^{c_3d_1}E^{d_2d_3}$$

$$\begin{aligned} &= 3(T_{111})^2T_{112}T_{122} + 2(T_{122})^3T_{222} + 3T_{111}(T_{122})^2T_{222} \\ &\quad + 6T_{111}T_{112}(T_{122})^2 + T_{111}(T_{222})^3 + 3T_{112}(T_{122})^3 \\ &\quad - 3T_{112}T_{122}(T_{222})^2 - 2T_{111}(T_{112})^3 - 3T_{111}(T_{112})^2T_{222} \\ &\quad - 6(T_{112})^2T_{122}T_{222} - (T_{111})^3T_{222} - 3(T_{112})^3T_{122}, \end{aligned}$$

$$\begin{aligned} L_1 &= T_{abc}E^{ab}X^c = (T_{111} + T_{112})X^1 + (T_{112} + T_{222})X^2 \\ &\quad + (T_{113} + T_{223})X^3, \end{aligned}$$

$$(1/2)C_{21} = T_{a_1a_2a_3}T_{b_1b_2b_3}A^{a_1b_1}A^{a_2b_2}X^{a_3}X^{b_3}$$

$$\begin{aligned} &= [T_{111}T_{122} - (T_{112})^2](X^1)^2 + [T_{111}T_{222} - T_{112}T_{122}]X^1X^2 \\ &\quad + [T_{112}T_{222} - (T_{222})^2](X^2)^2 \\ &\quad + [T_{122}T_{113} + T_{111}T_{223} - 2T_{112}T_{123}]X^1X^3 \\ &\quad + [T_{112}T_{223} + T_{113}T_{222} - 2T_{122}T_{123}]X^2X^3 \\ &\quad + [T_{113}T_{223} - (T_{123})^2](X^3)^2. \end{aligned}$$

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