

AN EXTENSION OF ALEXANDROFF'S MAPPING THEOREM

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1. Introduction. Alexandroff's fundamental mapping theorem (Überführungssatz) is a basic tool of combinatorial topology. By its use, many mapping theorems for rather general topological spaces can be shown to be consequences of the corresponding theorems for polytopes. It is especially useful in proving imbedding theorems and approximation theorems.

The chief purpose of this paper is to determine the precise conditions under which this fundamental theorem holds. It will be shown that the theorem holds in full generality, that is, for all coverings, if and only if the space is both paracompact and normal. If the space is normal, the theorem holds for all coverings which have locally finite refinements and for no others.

2. Terminology. The mapping theorem of Alexandroff concerns mappings of a space into the nerve of a covering.

By a *mapping* we mean a continuous transformation. By a *space* we mean a topological space, in general not satisfying any separation axiom. By a *covering* we mean a covering of the space by a finite or infinite collection of open sets.

The *nerve* of a covering $\mathfrak{U}: \{U_\alpha\}$ is a simplicial polytope, with vertices u_α in 1-1 correspondence with the nonempty sets U_α of the covering, such that $u_\alpha, u_\beta, \dots, u_\gamma$ are vertices of a simplex of the nerve if and only if the corresponding sets $U_\alpha, U_\beta, \dots, U_\gamma$ have a common point. We assume that the nerve is realized as a topological space in one of the following ways. The *natural nerve* $N(\mathfrak{U})$ is the nerve realized with the natural metric: $\rho(x, y) = (\sum (x_\alpha - y_\alpha)^2)^{1/2}$, where x_α, y_α are barycentric coordinates of x and y . The *geometric nerve* $G(\mathfrak{U})$ is the nerve realized with the geometric topology of Lefschetz [10, p. 9]:¹ the stars of the vertices of repeated regular subdivisions form a basis for the open sets of $G(\mathfrak{U})$. It is known [12] that $G(\mathfrak{U})$ is a metrizable space. The natural and geometric topologies coincide if and only if the nerve is locally of finite dimension [11, footnote 4].

Following Dieudonné, we call a covering \mathfrak{U} of a space R *locally finite*²

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¹ Numbers in brackets refer to the bibliography at the end of the paper.

² Locally finite = neighborhood-finite. "Locally finite" has been used by Lefschetz to mean star-finite.

if each point of R has a neighborhood meeting only a finite number of sets of \mathfrak{U} . A covering \mathfrak{B} is called a refinement of \mathfrak{U} if every set of \mathfrak{B} is contained in some set of \mathfrak{U} . A space R is called *paracompact* (see [4]) if every covering of R has a locally finite refinement. A covering of a space R is called *point-finite* if each point of R is contained in only a finite number of sets of the covering. Clearly, every locally finite covering is point-finite.

A mapping f of a space R into the nerve of a covering \mathfrak{U} is called *canonical* with respect to \mathfrak{U} if the inverse image of the star³ of each vertex of the nerve is contained in the corresponding set of \mathfrak{U} ; in symbols: $f^{-1}(\text{St}u_\alpha) \subset U_\alpha$. If \mathfrak{U} is point-finite, the finite collection of sets U_α containing a point p of R correspond to the vertices u_α of a simplex in the nerve which we call the simplex $\sigma(p)$ determined by p . It can be shown [5, p. 202] that a mapping f of R into the nerve of a point-finite covering \mathfrak{U} is canonical with respect to \mathfrak{U} if and only if each point p of R is mapped into the closure of the simplex determined by p , that is, $f(p) \in \bar{\sigma}(p)$. Another equivalent formulation in the case of point-finite coverings is given by Lefschetz [10, p. 40].

3. Sufficient conditions. The mapping theorem of Alexandroff, as modified by Kuratowski and Lefschetz, states the existence, under certain conditions, of canonical mappings of a space into the nerve of a covering.

(a) *If \mathfrak{U} is a locally finite covering of a normal space R there is a canonical mapping of R into the natural nerve of \mathfrak{U} .*

This form of Alexandroff's theorem is proved in [5, Theorem 1.1]. Alternatively, the proof by Lefschetz [10, pp. 45–46] for star-finite coverings can easily be extended to locally finite coverings by using Dieudonné's theorem [4, Theorem 6] that every point-finite covering $\{U_\alpha\}$ of a normal space can be shrunk to a covering $\{V_\alpha\}$ such that, for each α , the closure of V_α is contained in U_α .

(b) *If a covering \mathfrak{U} of a normal space R has a locally finite refinement there is a canonical mapping of R into the natural nerve of \mathfrak{U} .*

PROOF. Let $\mathfrak{B} = \{V_\beta\}$ be a locally finite refinement of $\mathfrak{U} = \{U_\alpha\}$. For each V_β choose one of the sets U_α such that $V_\beta \subset U_\alpha$. Each V_β thus corresponds to a unique set U_α containing it. Let W_α be the union of all the sets of \mathfrak{B} which correspond to U_α . Each V_β is in some W_α ; hence $\mathfrak{B} = \{W_\alpha\}$ is a covering of R . Since \mathfrak{B} is locally finite, so is \mathfrak{B} . If $(w_\alpha, w_\beta, \dots, w_\gamma)$ is a simplex of $N(\mathfrak{B})$, there is a point

$$p \in W_\alpha W_\beta \cdots W_\gamma \subset U_\alpha U_\beta \cdots U_\gamma,$$

³ The star of a vertex v is the union of all simplexes having v as a vertex. The star of a vertex is an open set in either topology.

and hence $(u_\alpha, u_\beta, \dots, u_\gamma)$ is a simplex of $N(\mathfrak{U})$. Thus there is a simplicial mapping π of $N(\mathfrak{B})$ into $N(\mathfrak{U})$ which maps each vertex w_α into the corresponding vertex u_α . Clearly π is a 1-1 mapping of $N(\mathfrak{B})$ onto a subpolytope of $N(\mathfrak{U})$. If w_α exists, $\pi^{-1}\text{St}u_\alpha = \text{St}w_\alpha$; otherwise $\pi^{-1}\text{St}u_\alpha = 0$. By (a) there is a canonical mapping g of R into $N(\mathfrak{B})$. Then, if $f = \pi g$, f is a mapping of R into $N(\mathfrak{U})$. If w_α exists,

$$f^{-1} \text{St } u_\alpha = g^{-1}\pi^{-1} \text{St } u_\alpha = g^{-1} \text{St } w_\alpha \subset W_\alpha \subset U_\alpha.$$

Otherwise, $f^{-1} \text{St } u_\alpha = 0 \subset U_\alpha$. Hence f is a canonical mapping of R into $N(\mathfrak{U})$.

(c) *If \mathfrak{U} is an arbitrary covering of a paracompact normal space R , there is a canonical mapping of R into the natural nerve of \mathfrak{U} .*

PROOF. Since R is paracompact, \mathfrak{U} has a locally finite refinement. Hence, by (b), a canonical mapping exists.

4. Necessary conditions; main theorems. We pass now to consideration of some necessary conditions for the existence of canonical mappings.

(d) *If there exists a canonical mapping f of a space R into the natural nerve of a covering \mathfrak{U} , then \mathfrak{U} has a locally finite refinement.*

PROOF. The natural complex $N(\mathfrak{U})$ can be shown to be a paracompact normal (metric) space [6, Theorem 2]. Hence, the covering $\{\text{St } u_\alpha\}$ of $N(\mathfrak{U})$ by the stars of its vertices has a locally finite refinement $\{V_\beta\}$. Then $\{f^{-1}V_\beta\}$ is a locally finite covering of R . Since V_β is contained in some $\text{St } u_\alpha$, $f^{-1}V_\beta \subset f^{-1} \text{St } u_\alpha \subset U_\alpha$. Hence $\{f^{-1}V_\beta\}$ is a refinement of \mathfrak{U} .

(e) *Let R be a space such that for every covering \mathfrak{U} of R there is a canonical mapping of R into the natural nerve of \mathfrak{U} . Then R is a paracompact normal space.*

PROOF. By (d), the existence of a canonical mapping into $N(\mathfrak{U})$ implies that \mathfrak{U} has a locally finite refinement. Hence every covering \mathfrak{U} of R has a locally finite refinement, that is, R is paracompact. Since, in particular, there is a canonical mapping of R into the nerve of each covering by two open sets, R is normal (see [10, p. 45]).

THEOREM 1. *There exists a canonical mapping of a normal space R into the natural nerve of a covering \mathfrak{U} if and only if \mathfrak{U} has a locally finite refinement.*

PROOF. This follows immediately from (b) and (d).

THEOREM 2. *There exists a canonical mapping of a space R into the natural nerve of an arbitrary covering if and only if R is paracompact and normal.*

PROOF. This follows immediately from (c) and (e).

5. Dimension. Alexandroff's original theorem was partly, and indeed mainly, a theorem of dimension theory. The dimension-theoretic content of the extended (and modified) theorem is indicated by Theorem 3.

The *dimension* of a normal space R , $\dim R$, is defined as follows: $\dim R \leq n$ means that every finite covering of R has a finite refinement of order not greater than $n+1$.

Let K be a simplicial polytope. Let σ^n be an n -simplex of K , $\bar{\sigma}^n$ its closure, and S^{n-1} its boundary. If f maps R into K , let $A = f^{-1}S^{n-1}$ and let $f|A$ be the mapping f restricted to A . If $f|A$ cannot be extended to a mapping of $f^{-1}\bar{\sigma}^n$ into S^{n-1} , the mapping f of R into K is called *essential* in the closed simplex $\bar{\sigma}^n$. Thus, if f is essential in $\bar{\sigma}^n$, $f|A$ cannot be extended to a mapping of $R \cap f^{-1}\bar{\sigma}^n$ into S^{n-1} . It can be seen that a mapping f of R into K is essential in $\bar{\sigma}^n$ if and only if, for some subset B of R , $f|B$ is essential in $\bar{\sigma}^n$ and $f(B) \subset \bar{\sigma}^n$.

THEOREM 3. *If \mathfrak{U} is a covering of a normal space R and if any canonical mapping of R into $N(\mathfrak{U})$ exists, then, for some canonical mapping f of R into $N(\mathfrak{U})$, the image $f(R)$ is a subpolytope K of $N(\mathfrak{U})$, $\dim K \leq \dim R$, and f is essential in every closed simplex of K .*

PROOF. By (d), the existence of a canonical mapping of R into $N(\mathfrak{U})$ implies that \mathfrak{U} has a locally finite refinement \mathfrak{B} . It can be shown [5, Lemma 3.4] that every locally finite covering \mathfrak{B} of a normal space R has a locally finite refinement $\mathfrak{W}: \{W_\beta\}$ such that there is a mapping ϕ of R onto $N(\mathfrak{W})$ with the following properties: ϕ is essential in every closed simplex of $N(\mathfrak{W})$ and $\phi^{-1} \text{St } w_\beta = W_\beta$ for every β .

Since \mathfrak{B} is a refinement of \mathfrak{U} there exists a simplicial transformation⁴ π of $N(\mathfrak{W})$ into $N(\mathfrak{U})$ which maps w_β into u_α where U_α is a set of \mathfrak{U} containing W_β . We may assume that π is continuous on each finite subpolytope of $N(\mathfrak{W})$. Since \mathfrak{B} is locally finite, each point $p \in R$ has a neighborhood U meeting only a finite number of sets of \mathfrak{B} , and hence $\phi(U)$ is contained in a finite subpolytope of $N(\mathfrak{W})$. Then $\pi\phi$ maps a neighborhood of an arbitrary point p continuously. Hence $\pi\phi$ is continuous. Let $f = \pi\phi$.

If $\pi\phi(p) \in \text{St } u_\alpha$, then $\phi(p) \in \text{St } w_\beta$ for some w_β mapped into u_α . Hence, $p \in \phi^{-1} \text{St } w_\beta = W_\beta \subset U_\alpha$. Thus $f^{-1} \text{St } u_\alpha \subset U_\alpha$. Therefore, f is a canonical mapping.

Let K be the image polytope $\pi N(\mathfrak{W}) \subset N(\mathfrak{U})$. Since $\phi(R) = N(\mathfrak{W})$, $f(R) = \pi\phi(R) = \pi N(\mathfrak{W}) = K$. Thus f is a mapping of R onto K .

⁴ See, for example [5, footnote 13].

Let σ^n be an n -simplex of K . Since $\pi N(\mathfrak{B}) = K$, there is some simplex σ^m of $N(\mathfrak{B})$ such that $\pi\sigma^m = \sigma^n$. There is some n -face σ_1^n of σ^m which is mapped onto σ^n . (If $m = n$, $\sigma_1^n = \sigma^m$.) Since ϕ is essential in every closed simplex of $N(\mathfrak{B})$, ϕ is essential in σ_1^n and hence there is a subset B of R such that $\phi(B) \subset \sigma_1^n$ and $\phi|B$ is essential in σ_1^n . Since π maps σ_1^n homeomorphically onto σ^n , $\pi\phi|B$ is essential in σ^n . Hence $\pi\phi$ is essential in σ^n . It follows [5, Corollary 3.6] that $\dim R \geq n$; hence each simplex of K has dimension not greater than $\dim R$. Thus $f = \pi\phi$ is essential in each closed simplex of K and $\dim K \leq \dim R$. This completes the proof.

6. Lefschetz' geometric nerve. It will now be shown that in any theorem on canonical mappings the geometric nerve can be replaced by the natural nerve, or the natural by the geometric.

THEOREM 4. *Let \mathfrak{U} be a covering of a space R . There exists a canonical mapping of R into the geometric nerve $G(\mathfrak{U})$ if and only if there is a canonical mapping of R into the natural nerve $N(\mathfrak{U})$.*

PROOF. First, let f be a canonical mapping of R into $N(\mathfrak{U})$. Let the vertices of $N(\mathfrak{U})$ be $\{u_\alpha\}$ and let those of $G(\mathfrak{U})$ be $\{a_\alpha\}$. It is known [10, p. 21, (9.9)] that the barycentric mapping ϕ of $N(\mathfrak{U})$ onto $G(\mathfrak{U})$ which maps u_α onto a_α is continuous. Let $g = \phi f$. Then, since $\phi^{-1} \text{St } a_\alpha = \text{St } u_\alpha$,

$$g^{-1} \text{St } a_\alpha = f^{-1} \phi^{-1} \text{St } a_\alpha = f^{-1} \text{St } u_\alpha \subset U_\alpha.$$

Hence g is a canonical mapping of R into $G(\mathfrak{U})$.

Conversely, let g be any canonical mapping of R into $G(\mathfrak{U})$. The natural nerve of the covering $\{\text{St } a_\alpha\}$ of $G(\mathfrak{U})$ by the stars of its vertices may be identified with $N(\mathfrak{U})$. It can be shown that $G(\mathfrak{U})$ is a paracompact normal (metrizable) space [6, Theorem 2]. Hence, by (c), there is a mapping ψ of $G(\mathfrak{U})$ into $N(\mathfrak{U})$ canonical with respect to the covering $\{\text{St } a_\alpha\}$. Thus $\psi^{-1} \text{St } u_\alpha \subset \text{St } a_\alpha$. Let $f = \psi g$. Then

$$f^{-1} \text{St } u_\alpha = g^{-1} \psi^{-1} \text{St } u_\alpha \subset g^{-1} \text{St } a_\alpha \subset U_\alpha.$$

Hence f is a canonical mapping of R into $N(\mathfrak{U})$.

Applying Theorem 4 to Theorems 1 and 2, we have:

COROLLARY 1. *There exists a canonical mapping of a normal space R into the geometric nerve of a covering \mathfrak{U} if and only if \mathfrak{U} has a locally finite refinement.*

COROLLARY 2. *There exists a canonical mapping of a space R into the geometric nerve of an arbitrary covering if and only if R is paracompact and normal.*

It likewise follows from Theorem 4 that the theorems of Lefschetz on canonical mappings into geometric nerves hold also for mappings into natural nerves. In particular, using his notion of "analytic" covering and his fundamental mapping theorem [10, p. 41], we have:

COROLLARY 3. *There exists a canonical mapping of a space R into the natural nerve of a point-finite covering \mathfrak{U} if and only if \mathfrak{U} is analytic.*

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