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## A NOTE ON LEAST COMMON LEFT MULTIPLES

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1. **Introduction.** Consider  $n$ -by- $n$  matrices  $A, B, \dots$  with elements in a principal ideal ring and recall the following definitions. If  $A = BC$ , then  $A$  is a *left multiple* of  $C$  and  $C$  is a *right divisor* of  $A$ . If  $A = RD$  and  $B = PD$ , then  $D$  is a *common right divisor* of  $A$  and  $B$ ; if, furthermore,  $D$  is a left multiple of every common right divisor of  $A$  and  $B$ , then  $D$  is a *greatest common right divisor* of  $A$  and  $B$ . If  $M = PA = QB$ , then  $M$  is a *common left multiple* of  $A$  and  $B$ ; if, furthermore,  $M$  is a right divisor of every common left multiple of  $A$  and  $B$ , then  $M$  is a *least common left multiple* of  $A$  and  $B$ . If  $FE = I$ , where  $I$  is the identity matrix, then  $E$  is a *unimodular* matrix. If  $E$  is unimodular, then  $EA$  is a *left associate* of  $A$ .

The basic tool in the following constructions is the theorem<sup>1</sup> that any given matrix  $A$  is the left associate of a uniquely determined matrix  $A_1$ , known as the Hermite canonical triangular form, having zeros above the main diagonal, having elements below the main diagonal in a prescribed residue class modulo the diagonal element above, having each diagonal element in a prescribed system of non-associates, and if a diagonal element is zero, having the corresponding row all zero.

C. C. MacDuffee has presented the following method,<sup>2</sup> due in essence to E. Cahen and A. Chatelet, for finding a greatest common

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<sup>1</sup> C. C. MacDuffee, *Matrices with elements in a principal ideal ring*, Bull. Amer. Math. Soc. vol. 39 (1933) pp. 570–573.

<sup>2</sup> C. C. MacDuffee, loc. cit. p. 573.

right divisor  $D$  and a least common left multiple  $M$  of two given matrices  $A$  and  $B$ . Consider  $2n$ -by- $2n$  matrices written in the form of  $n$ -by- $n$  blocks. Use the theory of the Hermite form, as applied to the  $2n$ -by- $2n$  matrices, to write the following equations.

$$(1) \quad \begin{pmatrix} R & S \\ P & Q \end{pmatrix} \begin{pmatrix} A & 0 \\ B & 0 \end{pmatrix} = \begin{pmatrix} D & 0 \\ 0 & 0 \end{pmatrix}, \quad \begin{pmatrix} R' & S' \\ P' & Q' \end{pmatrix} \begin{pmatrix} R & S \\ P & Q \end{pmatrix} = \begin{pmatrix} I & 0 \\ 0 & I \end{pmatrix},$$

$$\begin{pmatrix} A & 0 \\ B & 0 \end{pmatrix} = \begin{pmatrix} R' & S' \\ P' & Q' \end{pmatrix} \begin{pmatrix} D & 0 \\ 0 & 0 \end{pmatrix}.$$

Since first:  $A = R'D$  and  $B = P'D$ , and second:  $RA + SB = D$ , it follows that  $D$  is a greatest common right divisor of  $A$  and  $B$ , with no restrictions on  $A$  and  $B$ .

With the rather severe restriction that both  $A$  and  $B$  be nonsingular, it has been shown<sup>3</sup> that the matrix  $M = PA = -QB$ , obtained from (1), is a least common left multiple of  $A$  and  $B$ .

It is the purpose of this note to show by a different proof that the stated method for finding  $M$  is correct for a much larger set of matrices  $A$  and  $B$ —namely, whenever  $D$  is nonsingular, that is, whenever the row space of the union of  $A$  and  $B$  has the rank  $n$ , thus including, in addition to the case that both  $A$  and  $B$  are nonsingular, the case when either  $A$  or  $B$  is nonsingular and many other possibilities. Furthermore, in the exceptional case when  $D$  is singular, there is presented a method for finding an  $M$  that may be considered a natural modification of the method based on the equations (1). In conclusion it is noted that a theorem of E. Steinitz guarantees that both  $D$  and  $M$  are unique up to a unimodular left factor.

For completeness it should be noted that a method for finding the least common left multiple of two matrices when the matrices have elements in a field has been given by C. C. MacDuffee,<sup>4</sup> but the method is not applicable to the case where the elements are limited to a principal ideal ring.

**2. When  $D$  is nonsingular.** In terms of the notation explained in the introduction the following theorem may be stated:

**THEOREM 1.** *In the matrix equation*

$$\begin{pmatrix} R & S \\ P & Q \end{pmatrix} \begin{pmatrix} A & 0 \\ B & 0 \end{pmatrix} = \begin{pmatrix} D & 0 \\ 0 & 0 \end{pmatrix}$$

<sup>3</sup> C. C. MacDuffee, loc. cit. p. 574.

<sup>4</sup> C. C. MacDuffee, *Vectors and matrices*, Carus Monograph, 1943, pp. 100–102.

where the matrix involving  $R, S, P, Q$  is unimodular, the matrix  $D$  is in all cases a greatest common right divisor of  $A$  and  $B$ ; and if  $D$  is nonsingular, then the matrix  $M=PA=-QB$  is a least common left multiple of  $A$  and  $B$ .

That  $D$  is in all cases a greatest common right divisor has been shown above. To show that  $M$ , which is obviously a common left multiple of  $A$  and  $B$ , is a least common left multiple, let  $M_1=UA=-VB$  be any common left multiple of  $A$  and  $B$ . Use the matrices determined in (1) to write the following equations:

$$(2) \quad \begin{pmatrix} R & S \\ U & V \end{pmatrix} \begin{pmatrix} A & 0 \\ B & 0 \end{pmatrix} = \begin{pmatrix} D & 0 \\ 0 & 0 \end{pmatrix},$$

$$\begin{pmatrix} R & S \\ U & V \end{pmatrix} \begin{pmatrix} R' & S' \\ P' & Q' \end{pmatrix} \begin{pmatrix} D & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} D & 0 \\ 0 & 0 \end{pmatrix}.$$

Consider the most general solution of the equation

$$\begin{pmatrix} X & W \\ Y & T \end{pmatrix} \begin{pmatrix} D & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} D & 0 \\ 0 & 0 \end{pmatrix}.$$

Here  $W$  and  $T$  are arbitrary, but  $X$  and  $Y$  must be chosen so that

$$(3) \quad XD = D, \quad YD = 0.$$

Subject to the conditions (3) the following equations must hold:

$$\begin{pmatrix} R & S \\ U & V \end{pmatrix} \begin{pmatrix} R' & S' \\ P' & Q' \end{pmatrix} = \begin{pmatrix} X & W \\ Y & T \end{pmatrix}, \quad \begin{pmatrix} R & S \\ U & V \end{pmatrix} = \begin{pmatrix} X & W \\ Y & T \end{pmatrix} \begin{pmatrix} R & S \\ P & Q \end{pmatrix}.$$

In particular, it appears that  $U$  must have the form

$$(4) \quad U = YR + TP.$$

But under the hypothesis that  $D$  is nonsingular the only solution of  $YD=0$  is  $Y=0$ . Hence it follows in this case that  $U=TP$ ; then from  $M_1=UA=TPA=TM$  it follows that  $M=PA=-QB$  is indeed a least common left multiple of  $A$  and  $B$  and the proof of the theorem is complete.

**3. When  $D$  is singular.** If the matrix  $D$  is singular it is easy to construct examples in which the matrix  $PA$  of Theorem 1 is not a least common left multiple of  $A$  and  $B$ . Hence the construction proposed in the following theorem has some interest.

**THEOREM 2.** *Let  $A_1$  and  $B_1$  be the Hermite forms of  $A$  and  $B$ , respectively. In the matrix equation*

$$(1') \quad \begin{pmatrix} R^* & S^* \\ P^* & Q^* \end{pmatrix} \begin{pmatrix} A_1 & 0 \\ B_1 & 0 \end{pmatrix} = \begin{pmatrix} D & 0 \\ 0 & 0 \end{pmatrix}$$

where the matrix involving  $R^*$ ,  $S^*$ ,  $P^*$ ,  $Q^*$  is unimodular and the matrix involving  $D$  is in Hermite form, let it be agreed, since this is a possible procedure, that no operations are performed upon the rows corresponding to the zero rows of  $D$ . Then the matrix  $M^* = P^*A_1 = -Q^*B_1$  is a least common left multiple of  $A$  and  $B$ .

It follows readily that if  $E_1$  and  $E_2$  are unimodular, then a least common left multiple  $M^*$  of  $A_1 = E_1A$  and  $B_1 = E_2B$  is also a least common left multiple of  $A$  and  $B$ . First: from  $M^* = KA_1 = LB_1$  it follows that  $M^* = KE_1A = LE_2B$ ; second: from  $M_1 = UA = VB$  it follows that  $M_1 = UF_1A_1 = VF_2B_1$ , where  $F_1E_1 = I = F_2E_2$ , but since  $M^*$  is a least common left multiple of  $A_1$  and  $B_1$ , it follows that there exists a matrix  $G$  such that  $M_1 = GM^*$ . In particular  $A_1$  and  $B_1$  may be taken to be the Hermite forms of  $A$  and  $B$ , respectively.

In the equation (1') the \* notation has been adopted in describing the component blocks of the transforming matrix for two reasons: first: to indicate that the operations are to be made on the matrix involving  $A_1$  and  $B_1$  rather than  $A$  and  $B$ ; and second: to indicate that the operations are to be made in what may be described as one of the "simplest" ways. Certainly no zero row can appear in  $D$  unless it is also a zero row of  $A_1$  (the converse, of course, does not hold). Consequently, in obtaining the Hermite form involving  $D$ , it is quite unnecessary to operate on the rows ( $z$ ) which are zero rows of  $D$ , and this agreement results in a "simplest" transforming matrix. In fact the matrix  $R^*$  must have each of its rows ( $z$ ) all zero except for a 1 in the diagonal position. Furthermore, the most general matrix  $Y$  such that  $YD = 0$  must have the form  $Y = ZY^*$ , where  $Z$  is arbitrary but  $Y^*$  has a structure just like  $R^*$  in its rows ( $z$ ) and zero rows elsewhere. Thus  $Y^*R^* = Y^*$  and

$$(5) \quad YR^* = ZY^*R^* = ZY^* = Y.$$

As observed above  $A_1$  has zero rows in at least the rows ( $z$ ), hence from  $YD = 0$  it follows that  $YA_1 = 0$ , and from (5) it follows that

$$(6) \quad YR^*A_1 = YA_1 = 0.$$

Let  $M_1 = UA_1 = -VB_1$  be any common left multiple of  $A_1$  and  $B_1$ . Starting from (1') instead of (1), obtain the relations analogous to (2), (3), and (4). In particular, consider

$$(4') \quad U = YR^* + TP^*.$$

From (6) it follows that  $M_1 = UA_1 = (YR^* + TP^*)A_1 = TP^*A_1$ . Hence with  $M^* = P^*A_1 = -Q^*B_1$  it follows that  $M_1 = TM^*$  and that  $M^*$  is a least common left multiple of  $A_1$  and  $B_1$ . Automatically  $M^*$  is a least common left multiple of  $A$  and  $B$  and the proof of the theorem is complete.

It should be noted that Theorem 2 works in all cases and does not require  $D$  to be singular. However the construction of Theorem 1, when applicable, is much shorter, since the separate computation of  $A_1$  and  $B_1$  is avoided. A working procedure would be to start from  $A$  and  $B$  and compute  $D$  in Hermite form; if  $D$  has no zero rows, apply Theorem 1; if  $D$  has zero rows ( $z$ ), return to compute  $A_1$  and  $B_1$ , find  $D$  anew starting from  $A_1$  and  $B_1$  but not operating on the rows ( $z$ ), and then apply Theorem 2.

#### 4. Uniqueness.

LEMMA. *If  $A = UB$  and  $B = VA$ , then there exists a unimodular matrix  $E$  such that  $B = EA$ .*

This lemma has been proved by E. Steinitz<sup>5</sup> in a much more general setting—namely, for matrices whose elements are in a domain of integrity over the rational field, not necessarily a principal ideal ring. The proof is considerably simpler for the case of principal ideal rings. In fact by taking the proof for the case of matrices with elements in a field<sup>6</sup> and merely replacing the word nonsingular by the word unimodular, a suitable proof for the case of principal ideal rings is easily made.

THEOREM 3. *The greatest common right divisor  $D$  and the least common left multiple  $M$  of two given matrices  $A$  and  $B$  are uniquely determined up to unimodular left factors.*

If  $D$  and  $D_1$  are two greatest common right divisors of  $A$  and  $B$ , then each is a common left multiple of the other, say  $D = UD_1$  and  $D_1 = VD$ . Then by the lemma,  $D$  and  $D_1$  are left associates.

If  $M$  and  $M_1$  are two least common left multiples of  $A$  and  $B$ , then each is a common right divisor of the other, say  $M_1 = UM$  and  $M = VM_1$ . Then by the lemma,  $M$  and  $M_1$  are left associates.

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<sup>5</sup> E. Steinitz, *Math. Ann.* vol. 71 (1911) pp. 328–354.

<sup>6</sup> C. C. MacDuffee, *Vectors and matrices*, pp. 45–46.