

# DIFFERENTIABLE OPEN MAPS<sup>1</sup>

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Let  $f: M^n \rightarrow N^n$  be a continuous function, where  $M^n$  and  $N^n$  are  $n$ -manifolds (without boundary). It will be implicitly assumed that the manifolds share the differentiability properties of  $f$ , e.g.,  $f \in C'$  implies that  $M^n$  and  $N^n$  are  $C'$  manifolds. The map  $f$  is called *open* if, whenever  $U$  is open in  $M^n$ ,  $f(U)$  is open in  $N^n$ ; it is *light* if, for every  $y \in N^n$ ,  $\dim(f^{-1}(y)) \leq 0$ .

For  $n=2$ , it is well-known that a nonconstant complex analytic function is open and light. Conversely, Stoilow proved that every light open map is locally, at each point, topologically equivalent [9, p. 198] to one of the canonical analytic maps  $g_d$ , defined by  $g_d(z) = z^d$  ( $d=1, 2, \dots$ ). If it is not assumed that  $f$  is light, however,  $f$  may be quite different from a  $g_d$ . R. D. Anderson in [1] (see also [2]) constructed an open map  $f: S^2 \rightarrow S^2$  such that, for each  $y \in S^2$ ,  $f^{-1}(y)$  is a nondegenerate continuum.

For  $n \geq 2$ , let  $F_{n,d}: E^n \rightarrow E^n$  be the canonical open map defined by:  $F_{n,d}(x_1, x_2, \dots, x_n) = (u_1, u_2, \dots, u_n)$ , where  $u_1 + iu_2 = (x_1 + ix_2)^d$  ( $i = \sqrt{-1}$ ) and  $u_j = x_j$  ( $j=3, 4, \dots, n; d=1, 2, \dots$ ). Since each  $F_{n,d}$  is a generalization of  $g_d$ , it is natural to wonder (for  $n \geq 3$ ) how much an arbitrary open map  $f$ , satisfying some additional condition, differs locally from one of them.

The *branch set*  $B_f$  is the set of points in  $M^n$  at which  $f$  fails to be a local homeomorphism (defined in [3]).

**THEOREM.** *Let  $f: M^n \rightarrow N^n$  be  $C^n$  and open ( $n \geq 2$ ), where  $M^n$  is compact or  $f$  is light. Then there exists a closed set  $E$ ,  $\dim E \leq n-3$ , such that, for each  $x$  in  $M^n - E$ , there exists a neighborhood of  $x$  on which  $f$  is topologically equivalent to one of the canonical maps  $F_{n,d}$  ( $d=1, 2, \dots$ ). Moreover,  $E$  is nowhere dense in  $B_f$  unless  $f$  is a local homeomorphism.*

In particular, for  $n=2$  we have the classical structure. In [4, p. 620, (4.3)] there is a 2-to-1 open map  $f: S^5 \rightarrow S^5$  for which  $B_f$  is not locally a manifold at any point (it is necessarily [4, p. 620, (4.2)] a 3-gm mod 2); thus *some* differentiability assumption is required above. There is a  $C^\infty$  open map  $f: E^2 \rightarrow E^2$  for which  $B_f$  is the  $y$ -axis; thus either compactness of the domain or lightness of the map is needed. An example  $f: E^3 \rightarrow E^3$  (or  $f: S^3 \rightarrow S^3$ ) given by E. Hemmingsen

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and the author in [4, p. 620, (3.3)] indicates the extent of possible pathology. There  $B_f$  has a Cantor set of point components, so that the exceptional set  $E$  in the Theorem is necessary ( $f$  can be shown to be topologically equivalent to a  $C^\infty$  map).

The following corollary is a generalization of the inverse function theorem. Let  $Z$  be the set of zeros of the Jacobian determinant.

**COROLLARY.** *If  $f: E^n \rightarrow E^n$ ,  $n \geq 3$ ,  $f \in C^n$ , and  $\dim Z \leq 0$ , then  $f$  is a local homeomorphism.*

**PROOF.** The map  $f$  is light, and its Jacobian determinant is either non-negative or nonpositive everywhere. Thus  $f$  is open [8], and the result follows from the Theorem. More generally, the conclusion holds if  $\dim(B_f) \leq 0$ .

A basic lemma for the proof of the Theorem follows. The set of points in  $M^n$  at which the Jacobian matrix has rank at most  $q$  is denoted by  $R_q$ .

**LEMMA.** *Let  $h: M^n \rightarrow N^p$ , where  $h \in C^n$  and  $M^n$  and  $N^p$  are  $n$ - and  $p$ -manifolds, respectively. Then  $\dim(f(R_q)) \leq q$ .*

In particular,  $\dim(h(M^n)) \leq n$ . The lemma is related to the theorem of A. P. Morse [6] on the image of the critical set of a real-valued function, and to Sard's Theorem [7]. If  $f$  is light, then [5, pp. 91–92]  $\dim(R_q) \leq q$ .

The proof of the Theorem employs Morse's Theorem, a uniform form of the implicit function theorem, and some results from [3]. Detailed proofs will appear elsewhere.

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