

CLASSIFICATION OF QUINTIC EUTACTIC FORMS

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ABSTRACT. From the classical Voronoi algorithm, we derive an algorithm to classify quadratic positive definite forms by their minimal vectors; we define some new invariants for a class, for which several conjectures are proposed. Applying the algorithm to dimension 5 we obtain the table of the 136 classes in this dimension, we enumerate the 118 eutactic quintic forms, and we verify the Ash formula.

1. INTRODUCTION

In a given dimension n , there are only finitely many *eutactic* quadratic forms up to equivalence. This was first shown by Avner Ash ([Ash1]) by means of Morse theory: he gave a new interpretation of eutactic forms as the nondegenerate critical points of the function $\det(Q)/m(Q)^n$ on the symmetric positive definite forms, where $m(Q)$ is the minimum of Q on integral nonzero vectors and $\det(Q)$ is its determinant. He also proved in [Ash2] a “mass formula with signs” relating the orders of the automorphism groups of all integrally unequivalent eutactic forms. In a recent paper ([BM]), A.-M. Bergé and J. Martinet gave another proof of Ash’s theorem together with a method for the enumeration of eutactic forms: they classify the positive definite forms by the sets of their minimal vectors into a finite set of so called *minimal classes* or *cells* ordered *via* inclusion; they enlarge the notion of eutaxy by taking off the convexity it involves; and they eventually characterize in their classes the weakly eutactic forms as the ones (if any) at which the Hermite function $\gamma(Q) = m(Q)/\det(Q)^{1/n}$ assumes its minimum (ensuring, by the convexity of this function, their uniqueness up to equivalence).

So the complete enumeration of eutactic forms can be based on the classification of forms, then on the study of the Hermite constant in each class. It was done up to dimension 4 by Bergé and Martinet using combinatorial methods and starting from the bottom, i.e., from classes of forms having exactly n independent minimal vectors (looking for eutaxy, one need only consider forms whose minimal vectors span the space \mathbb{R}^n , see §3).

Actually, the cell classification as well as the determination of the minimum of γ had been done previously for $n \leq 4$ by W. I. Štogrin in [Sto], a paper of which Bergé and Martinet were not aware. However, [Sto] does not contain any interpretation in terms of eutaxy.

The combinatorial going-up method theoretically leads to the classification of n -dimensional perfect forms (forms entirely determined by their minimum and their

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minimal vectors) whose classes are the top vertices of the graph of minimal classes. So it is no wonder that the combinatorial way becomes prohibitively laborious from dimension 5 on.

The main aim of this paper is to describe an algorithm to obtain the graph of all minimal classes in a given dimension.

This algorithm is derived from the well-known Voronoi algorithm for perfect forms, and starts from the perfect forms and the configuration of their minimal vectors. A refinement of the Voronoi theory (Theorem 2.4) asserts that by removing in a convenient manner some vectors from these configurations we obtain all classes of minimal vectors, going down step by step from perfect classes. Actually, such a method could produce thousands of subsets S of \mathbb{Z}^n (430 at the first step in the five-dimensional case), and it is important to be able to decide just which pairs of subsets are in the same orbits under $\mathrm{GL}_n(\mathbb{Z})$ (and so correspond to equivalent forms). This question is discussed in the algorithmic Section 4.

Note that in Section 2 we introduce an efficient (and easy to check) invariant for a class, derived from the notion of characteristic determinants introduced by Korkine and Zolotareff: in the column “Spect” of Table 3 below for the five-dimensional case, we can point out very few coincidences.

Actually, the best invariant to identify a class is the unique (up to equivalence) weakly eutactic forms it usually contains. As it realizes the minimum of the Hermite function in the class (and therefore is algebraic), we can use a gradient method to get a good approximate of its matrix, and finish its determination by some LLL-algorithm. We ascertain the results, and decide whether the form is indeed eutactic, by a formal calculation of its eutactic coefficients. In order to compare eutactic forms having the same field of definition (and identify their classes), we had to adapt the usual algorithm to formal calculations over number fields.

Section 3 is devoted to weakly eutactic forms, and in particular gives partial answers to questions by A. Ash (in private discussions): the conjugates of such a form (when it is not rational) are studied in Proposition 3.4, and a connection between classes without weakly eutactic forms and classes with weakly eutactic noneutactic forms arises in Theorem 3.2. This correspondence, together with results for dimension five, suggest another Euler relation, involving all classes instead of that of eutactic forms. Such a relation has just been proved by Christophe Bavard.

We also prove in Section 3 that each weakly eutactic form achieves the maximal automorphism group in its class, i.e., the stabilizer in $\mathrm{GL}_n(\mathbb{Z})$ of the set S of minimal vectors (“group of S ”). This group is a good invariant of the class (its order, together with the “spectrum” alluded to above, allows us to identify the 5-dimensional classes). Anyhow, as the motivation for this work was to check Ash’s mass formula, we had to compute it even in the algebraic case by using an algorithm adapted to formal calculations.

The last section presents the complete results for quintic forms. Starting from the three known perfect forms and their Voronoi domains, this algorithm produces 136 minimal classes listed with their invariants in Table 3, and 118 eutactic forms (for the rational ones, see Table 4). This enumeration cannot contain a unique error as it confirms Ash’s formula!

The amount of calculation increases rapidly with the dimension and, moreover, the perfect forms are known only up to dimension 7 (and out of reach beyond, as we know more than ten thousand 8-dimensional perfect forms). Moreover, the ratio of

eutactic forms to perfect forms for dimension 5 makes us believe that there should exist many eutactic forms in dimensions greater than 5.

2. MINIMAL CLASSES

Let us recall some definitions and notation. A positive definite quadratic form in n variables

$$Q(x) = \sum_{1 \leq i, j \leq n} a_{ij} x_i x_j, \quad x = {}^t(x_1, x_2, \dots, x_n) \in \mathbb{Z}^n,$$

can be identified with its $n \times n$ symmetric positive definite matrix $A = (a_{ij})$ with real entries, and we have $Q(x) = {}^t x A x$. Note that $Q(x)$ can be interpreted as the trace of the matrix $A x {}^t x$. We introduce on the N -dimensional vector space V of $n \times n$ symmetric matrices with real entries, where

$$N = n(n + 1)/2,$$

the inner product

$$\langle A, B \rangle = \text{Tr}(AB),$$

so that we have

$$Q(x) = \langle A, x {}^t x \rangle.$$

Two forms Q and Q' will be said to be *integrally equivalent* if there is a matrix U in $GL(n, \mathbb{Z})$ and a positive scalar λ such that $Q'(x) = \lambda Q(Ux)$, or matrixially $A' = \lambda {}^t U A U$. We denote by $\text{Aut}(Q) = \text{Aut}(A)$ the stabilizer of A in $GL_n(\mathbb{Z})$.

The minimum $m(Q) = m(A)$ on integral vectors is attained on a finite subset $S(Q) = S(A)$ of \mathbb{Z}^n . We denote by $s = |S(Q)|/2$ the number of pairs $\pm x$ of minimal vectors.

The form Q is said to be *perfect* if the matrices $x {}^t x$, $x \in S(Q)$, span the whole space V .

2.1 Definition. We call two forms Q and Q' *minimally equivalent* if there is a form integrally equivalent to Q' with same set of minimal vectors as Q .

Two integrally equivalent forms are therefore minimally equivalent, and the notions of minimal and integral equivalences coincide if and only if the forms are perfect.

Since $S({}^t U A U) = U^{-1} S(A)$, we can attach to each minimal class an orbit of a finite subset S of \mathbb{Z}^n under $GL_n(\mathbb{Z})$. Conversely, such an orbit corresponds to one class at most.

By using reduction arguments, one can prove that there are only finitely many classes (cf [BM]).

Inclusion induces a partial ordering on the set of classes:

2.2 Definition. Let \mathcal{C}_1 and \mathcal{C}_2 be two minimal classes. We note $\mathcal{C}_1 \prec \mathcal{C}_2$ if there exists $A_1 \in \mathcal{C}_1$ and $A_2 \in \mathcal{C}_2$ with $S(A_1) \subset S(A_2)$.

Let A be a symmetric positive definite matrix with set of minimal vectors S and minimum $m = 1$. Its minimal class \mathcal{C} can be represented up to integral equivalence by the set of symmetric positive definite matrices

$$\mathcal{C}_S = \{M \mid S(M) = S \text{ and } m(M) = 1\}.$$

By abuse of language we shall often refer to this set as the class of A .

It is an open convex polyhedron in the linear variety

$$\{M \mid \forall x \in S \langle M, x^t x \rangle = 1\} = A + Y,$$

where Y is the orthogonal complement to the vector subspace X spanned by the $x^t x$, $x \in S$.

The dual polyhedron of the class \mathcal{C}_S is the convex hull \mathcal{D}_S of the $x^t x$, $x \in S$, which is the classical *Voronoi domain* common to all matrices $A \in \mathcal{C}_S$. Its dimension in the N -dimensional space V of symmetric $n \times n$ real matrices

$$r = \dim(\mathcal{D}_S) = \text{codim}(\mathcal{C}_S)$$

is called the *rank of perfection* of the class \mathcal{C} of A (it is indeed an invariant for \mathcal{C}). From the description of \mathcal{C}_S we see that the rank of perfection is a strictly increasing function on the set of minimal classes. We have $r \leq N$, and equality holds if and only if the class is perfect. Thus the dimension $N - r$ of the class \mathcal{C}_S will be referred to as the *defect of perfection*.

In what follows, we will focus on the classes for which there are positive definite matrices in the corresponding Voronoi domain:

2.3 Definition. We call the classes associated to sets S spanning \mathbb{R}^n *well rounded*.

Voronoi proved ([Vor]) that the Voronoi domain of a given symmetric positive definite matrix A is an r -dimensional face of the Voronoi domain of some perfect form P . It follows that it is the intersection of $N - r$ hyperplane faces of the domain of P (an algorithm for these faces is given in subsection 4.1). So, the minimal class \mathcal{C}_S can be parametrized as follows:

$$\mathcal{C}_S = \{P + t_1 F_1 + t_2 F_2 + \cdots + t_{N-r} F_{N-r}\},$$

where $F_1, F_2, \dots, F_{N-r} \in V$ are orthogonal to hyperplane faces of the Voronoi domain of P , and the $t_i \in \mathbb{R}$ satisfy a finite set of linear inequalities.

It can be proved (see [Mar]) that *the closure $\overline{\mathcal{C}}$ of the minimal class \mathcal{C} of A is the union of the classes \mathcal{C}' over \mathcal{C} ($\mathcal{C} \prec \mathcal{C}'$)*, and we represent it by the convex set

$$\overline{\mathcal{C}} = \{M \mid S \subset S(M) \text{ and } m(M) = 1\},$$

whose extremal edges are just the perfect forms in this set (whose number is finite).

From Voronoi theory we can deduce the following property of the ordered graph of minimal classes.

2.4 Theorem (cf. [Mar]). *Let \mathcal{C} and \mathcal{C}' be two minimal classes with respective ranks t and t' , such that $\mathcal{C} \prec \mathcal{C}'$. Then there exists a finite sequence $\mathcal{C}_0 = \mathcal{C} \prec \mathcal{C}_1 \prec \cdots \prec \mathcal{C}_r = \mathcal{C}'$ for which \mathcal{C}_i has rank of perfection $t + i$.*

Proof. Let A in \mathcal{C} and A' in \mathcal{C}' be matrices scaled to minimum 1, with corresponding Voronoi domains $\mathcal{D}(A) \subset \mathcal{D}(A')$. There exists a hyperplane face \mathcal{F} of $\mathcal{D}(A')$ containing $\mathcal{D}(A)$ and a matrix A'' such that $\mathcal{D}(A'') = \mathcal{F}$ (this is a basic idea of the Voronoi algorithm for quadratic forms: if F is a nonzero vector orthogonal to \mathcal{F} in the half-space containing $\mathcal{D}(A')$, then any matrix $A'' = A' + \epsilon F$ with $\epsilon > 0$ small enough fits). Then the rank of perfection of the class $\mathcal{C}(A'')$ is just $t' - 1$. This proves the theorem inductively. \square

It follows that *our algorithm, which involves the determination of all hyperplane faces of a given Voronoi domain, starting from all inequivalent perfect matrices, provides all minimal classes in a given dimension n .*

The stabilizer $\text{Aut}(S)$ in $\text{GL}_n(\mathbb{Z})$ of a finite set $S \subset \mathbb{Z}^n$ is a finite group when S spans \mathbb{R}^n . When $S = S(A)$ is the set of minimal vectors of a symmetric positive definite matrix A , $\text{Aut}(S)$ stabilizes the convex \mathcal{C}_S and its closure, and is an invariant for the minimal class \mathcal{C} of A up to conjugacy under $\text{GL}_n(\mathbb{Z})$. It will be referred to as the *automorphism group* of the class.

The automorphism group $\text{Aut}(A)$ of any matrix A in \mathcal{C}_S is a subgroup of $\text{Aut}(S)$. Actually, when the latter is finite, it can be realized via the usual arithmetic mean tool:

2.5 Proposition. *Let \mathcal{C}_S be a well-rounded minimal class, A an element of \mathcal{C}_S (resp. $\overline{\mathcal{C}_S}$), and*

$$M = \frac{1}{|\text{Aut}(S)|} \sum_{U \in \text{Aut}(S)} {}^tUAU$$

its arithmetic mean.

- (1) $M \in \mathcal{C}_S$ (resp. $\overline{\mathcal{C}_S}$).
- (2) $\text{Aut}(M) = \text{Aut}(S)$ (resp. $\text{Aut}(M) \supset \text{Aut}(S)$).
- (3) $\det(M) \geq \det(A)$, and equality holds if and only if $M = A$ (hence $\text{Aut}(A) = \text{Aut}(S)$ (resp. $\text{Aut}(A) \supset \text{Aut}(S)$)).

Proof. The first assertion is just the convexity of the class \mathcal{C}_S and of its closure. The inclusion $\text{Aut}(M) \supset \text{Aut}(S)$ is trivial, and implies equality when M lies in the class \mathcal{C}_S itself, since its automorphism group is then a subgroup of $\text{Aut}(S)$. The strict logarithmic concavity of the determinant (cf. [CS]) implies (3), as the equivalent matrices in the mean sum have the same determinant. □

Again, from the strict logarithmic concavity of the determinant, it follows that the determinant assumes its maximum value in $\overline{\mathcal{C}_S}$ in a unique matrix. From 2.5 we obtain:

2.6 Corollary. *The matrix $A \in \overline{\mathcal{C}_S}$ at which the determinant attains its maximum in $\overline{\mathcal{C}_S}$ is such that*

$$\text{Aut}(A) \supset \text{Aut}(S)$$

(and equality holds when A lies in \mathcal{C}_S).

2.7 Remark. Note that the number of forms integrally equivalent to A in the set \mathcal{C}_S is just the index of $\text{Aut}(A)$ in $\text{Aut}(S)$. Actually this convex set is not a fundamental domain of the class with respect to the integral equivalence unless the group $\text{Aut}(A)$ is constant in the class.

2.8 Two more invariants. Let us introduce for the class \mathcal{C}_S two new invariants useful for the computation of its automorphism group and its identification.

The first one comes from the characteristic determinants of order n extracted from S : for any subset $\{x_1, x_2, \dots, x_n\} \subset S$, the absolute value of its determinant (a nonnegative integer bounded by the absolute constant $\gamma_n^{n/2}$) is invariant under sign-changes and permutations of the x_i 's. So we define the *determinant spectrum* of the class \mathcal{C} to be the system of integers (n_0, n_1, \dots, n_k) , $k = \lceil \gamma_n^{n/2} \rceil$, where n_i is the number of subsets $\{\pm x_1, \pm x_2, \dots, \pm x_n\}$ of S for which $\det(x_1, x_2, \dots, x_n) = \pm i$ (we have $\sum_i n_i = \binom{s}{n}$). the inequality $n_1 > 0$ means that the lattices of the class possess a basis of minimal vectors. Note that each n_i is an increasing function on the set of classes. For instance the perfect class associated to the root lattice \mathbb{A}_n is

TABLE 1. Determinant spectrums of perfect forms in dimension 6

form	s	\mathbf{n}_0	\mathbf{n}_1	\mathbf{n}_2	\mathbf{n}_3	\mathbf{n}_4
P_6^1	36	1101072	798984	46656	1080	0
P_6^2	27	165690	127224	3024	72	0
P_6^3	30	365720	220800	7240	0	15
P_6^4	22	45493	28830	288	2	0
P_6^5	21	32984	21056	224	0	0
P_6^6	21	33607	20501	156	0	0
P_6^7	21	37457	16807	0	0	0

characterized by $n_i = 0$ if $i > 1$ and $n_1 \neq 0$ (actually, $n_1 = (n + 1)^{n-1}$, as proved by Roland Bacher using Cayley's formula for graphs). We also have computed this invariant for the senary perfect forms, confirming a result of Watson [W] (corrected by Martinet). In order of decreasing density, and with the terminology of [CS], we obtain Table 1.

A class is given by a subset S of \mathbb{Z}^n , identified with a $n \times s$ integral matrix, defined up to permutation and sign-changes. The second invariant, suggested by Roland Bacher, is the integral $n \times n$ matrix

$$T = S^t S = \sum_{x \in S} x^t x.$$

T only depends on the set S , has the same rank as S , so it is positive definite for well-rounded classes.

2.9 Proposition (A.-M. Bergé). *Let \mathcal{C}_S be a well-rounded minimal class. We have the equality*

$$\text{Aut}(S) = \text{Aut}(T^{-1}).$$

Proof. We introduce the signed-permutation group G_n of order $2^n n!$

$$G_n = \{V \in \text{GL}_n(\mathbb{Z}) \mid {}^t V V = I_n\}.$$

The group of the class is just

$$G = \text{Aut}(S) = \{U \in \text{GL}_n(\mathbb{Z}) \mid \exists V \in G_s, US = SV\}$$

(the matrix V corresponds to permutations and sign-changes). The inclusion

$$\text{Aut}(S) \subset \text{Aut}(T^{-1}) = \{{}^t U \mid U \in \text{Aut}(T)\}$$

is trivial. Conversely, if $U \in \text{Aut}(T^{-1})$, we have $S'^t S' = S^t S$ if $S' = US$. Let A be an element of \mathcal{C}_S . We have

$$\langle S'^t S', A \rangle = \sum_{x' \in S'} x' A^t x' = \langle S^t S, A \rangle = \sum_{x \in S} x A^t x = s$$

(using the fact that the vectors in S are minimal vectors of norm 1 of A), so S' must be a permutation of S up to sign-change and there exists V in G_s such that $US = S' = SV$. \square

3. EUTAXY

Let us recall the definition of *weak eutaxy* ([BM]):

A symmetric positive definite matrix (or form) A is said to be *weakly eutactic* if the inverse matrix A^{-1} lies in the space spanned by the symmetric matrices $x^t x$, $x \in S(A)$: there are real numbers ρ_x (the *eutaxy coefficients* in [CS]) such that

$$A^{-1} = \sum_{x \in S(A)} \rho_x x^t x.$$

By averaging, we can assume that ρ_x is constant along the orbits under $\text{Aut}(A)$.

Forms for which there exists a system of nonnegative eutaxy coefficients are called *semi-eutactic* in [CS]; they are precisely those for which the inverse matrix A^{-1} lies in the Voronoi domain of A . The form is said to be *eutactic* when there exists a system of *strictly positive* eutaxy coefficients.

Note that every perfect form is weakly eutactic.

We begin by two easy and well-known properties of weakly eutactic forms or matrices, which are useful for the classification of weakly eutactic forms. The first one implies that, if we are searching for weakly eutactic forms, we need only consider well-rounded classes (see §2). The second one asserts that among the n -dimensional weakly eutactic forms there are disconnected ones, arising from lower dimensions:

- 3.1 Proposition.** (1) *Let Q be a weakly eutactic positive definite quadratic form. Then the set $S(Q)$ of its minimal vectors contains n independent vectors.*
 (2) *The orthogonal sum of two eutactic (resp. weakly eutactic) forms of dimensions p and p' with the same minimum is a eutactic (resp. weakly eutactic) $p + p'$ -dimensional form.*

Proof. (1) Let A be the matrix of Q . A eutactic relation $A^{-1} = \sum_{x \in S(A)} \rho_x x^t x$ is just a decomposition of the adjoint form $y \mapsto {}^t y A^{-1} y$ of Q into a sum of squares of the linear forms $y \mapsto {}^t y x$, $x \in S(A)$, whose rank is equal to $\text{rank}(S(A))$. (Actually, the set of x 's with $\rho_x > 0$ in the above relation must span \mathbb{R}^n .)

(2) We have $S(Q + Q') = S(Q) \cup S(Q')$, and the adjoint of $Q + Q'$ is equal to the orthogonal sum of the adjoints of Q and Q' . □

Now we will investigate the connection between minimality of the Hermite invariant and eutaxy, making precise the characterization of weak eutaxy given in [BM] and providing a new proof of it.

3.2 Theorem. *Let \mathcal{C} be a minimal class of n -dimensional positive definite quadratic forms and $\overline{\mathcal{C}} = \cup_{\mathcal{C}' \succ \mathcal{C}} \mathcal{C}'$ its closure.*

- (1) *The weakly eutactic forms in \mathcal{C} (if any) are just those at which the Hermite invariant assumes its minimum in $\overline{\mathcal{C}}$.*
- (2) *In each minimal class \mathcal{C} , there is at most one weakly eutactic form up to integral equivalence. More precisely, there is at most one weakly eutactic positive definite quadratic form with prescribed minimum and set of minimal vectors.*
- (3) *Let Q be a weakly eutactic form in \mathcal{C} with eutaxy coefficients $\rho_x, x \in S(Q)$. Then any class obtained from \mathcal{C} by removing minimal vectors of Q with non-positive coefficients ρ_x has no weakly eutactic form.*
- (4) *If the least dense of the weakly eutactic forms in $\overline{\mathcal{C}} \setminus \mathcal{C}$ is eutactic, then \mathcal{C} contains weakly eutactic forms.*

For instance, a class of defect one is a Voronoi neighbouring path between two perfect forms. If these two perfect forms are extreme (hence eutactic), we conclude from (4) that the path contains a weakly eutactic form. This holds up to dimension 5. In dimension 6, Theorem 3.2 (4) applies in all cases, except for the neighbouring paths from the extreme sextic form P_6^1 (twice), P_6^2, P_6^3 to the sextic semi-eutactic perfect form P_6^4 ; actually, the class from P_6^2 to P_6^4 is unique without a weakly eutactic form: thus among the 18 classes with defect 1, 17 contain a weakly eutactic form.

Proof of Theorem 3.2. We work in the Euclidean space of the symmetric $n \times n$ matrices equipped with the inner product $\langle A, B \rangle = \text{Tr}(AB)$. We normalize symmetric positive definite matrices to the same minimum m , thus we are looking for the maxima of the determinant. The differential of this function at A is the linear form $F \mapsto \det(A)\langle A^{-1}, F \rangle$.

As usual the class \mathcal{C} of A will be represented by the polyhedron \mathcal{C}_S (see Section 2), ($S = S(A)$) spanning an affine variety $A+Y$, where Y is the orthogonal complement to the vector space X spanned by the $x^t x$, $x \in S(A)$. Denoting by $\det|_{\overline{\mathcal{C}}}$ the restriction to $\overline{\mathcal{C}_S}$ of the determinant and using its strict logarithmic concavity, we have the following equivalences:

$$\det(A) = \max_{\overline{\mathcal{C}}}(\det) \iff \text{diff}_A(\det)|_{\overline{\mathcal{C}}} = 0 \iff \forall F \in Y, \langle A^{-1}, F \rangle = 0 \iff A^{-1} \in X,$$

where the right-hand side condition is just the weak eutaxy of A . □

So far we have proved (1) and (2) from concavity again.

From now on, we will assume that A is a weakly eutactic symmetric positive definite matrix, and

$$A^{-1} = \sum_{x \in S} \rho_x x^t x,$$

a relation of weak eutaxy.

Let $B \neq A$ be a symmetric positive definite matrix with minimum m as stated before. We then have, for all $x \in S$,

$$\langle x^t x, B \rangle = m + \epsilon_x$$

with $\epsilon_x \geq 0$ and $\epsilon_x = 0$ if and only if $x \in S(B)$. It follows that

$$\langle A^{-1}, B \rangle = \sum_{x \in S} \rho_x m + \sum_{x \in S} \rho_x \epsilon_x = n + \sum_{x \in S} \rho_x \epsilon_x.$$

We first assume

$$S(B) \supset \{x \in S \mid \rho_x > 0\}.$$

The term $\sum_{x \in S} \rho_x \epsilon_x$ is then nonpositive, since ϵ_x vanishes for any $x \in S$ such that $\rho_x > 0$. So we have

$$\text{Tr}(A^{-1}B) \leq n.$$

Now, by simultaneously diagonalizing A and B and applying the arithmetic-geometric mean inequality, we have

$$\det(A^{-1}B) < \left(\frac{1}{n} \text{Tr}(A^{-1}B)\right)^n$$

(equality would imply that the matrix $A^{-1}B$ is scalar, and therefore, from the normalization, $A = B$). It follows that, under our hypothesis, $\det(B) < \det(A)$. We can now prove (3). Let \mathcal{C}' be a minimal class obtained by removing from S some x with $\rho_x \leq 0$. Any form in \mathcal{C}' can be represented up to equivalence by a matrix $B \neq A$ satisfying

$$S \supset S(B) \supset \{x \in S \mid \rho_x > 0\},$$

and therefore satisfies $\det(B) < \det(A)$. As A lies in $\overline{\mathcal{C}'}$ (from $S \supset S(B)$), we conclude from (1) that B is not weakly eutactic.

We now assume

$$(S) \quad \{x \in S \mid \rho_x \leq 0\} \subset S(B) \text{ and } S \not\subset S(B).$$

The sum $\sum_{x \in S} \rho_x \epsilon_x$ is then positive (since $\epsilon_x = 0$ if $\rho_x \leq 0$ and $\epsilon_x > 0$ for some $x \in S$), and so is the differential $F \mapsto \text{Tr}(A^{-1}F)$ at A of the determinant at $F = B - A$:

$$\langle A^{-1}, F \rangle = \langle A^{-1}, B \rangle - n = \sum_{x \in S \mid \rho_x > 0} \rho_x \epsilon_x.$$

Thus any matrix M close enough to A on the path from A to B satisfies $\det(M) > \det(A)$. Now let \mathcal{C} be as in (4), represented by \mathcal{C}_S , and let A realize the maximum of the determinant in $\overline{\mathcal{C}_S}$. If A were not in \mathcal{C}_S , it would be eutactic (from hypothesis (4)), and thus then for any $B \in \mathcal{C}_S$ the above condition (S) would hold for a convenient system of ρ_x , so A would not be a maximum of the determinant in the path from A to B contained in $\overline{\mathcal{C}}$, a contradiction. This completes the proof of the theorem.

We can state again Corollary 2.6 in terms of eutaxy:

3.3 Corollary. *The automorphism group of a weakly eutactic positive definite quadratic form is exactly the automorphism group of the class, i.e., the stabilizer $\text{Aut}(S)$ in $\text{GL}_n(\mathbb{Z})$ of the set S of its minimal vectors.*

We deduce from Section 2 that when searching for the weakly eutactic matrix in a class \mathcal{C}_S , we need only consider the matrices of \mathcal{C}_S belonging to the linear variety (defined over \mathbb{Q})

$$V^{\text{Aut}(S)} = \{M \mid {}^tUMU = M, U \in \text{Aut}(S)\}$$

of $n \times n$ real matrices fixed by $\text{Aut}(S)$.

A weakly eutactic matrix is of course algebraic (i.e., has algebraic entries when conveniently scaled), since it is the unique solution in its class for the vanishing of the differential of the determinant. We can give some information about the field of definition.

- 3.4 Proposition.** (1) *The real conjugates of a weakly eutactic matrix A (if any) are not positive definite.*
 (2) *If the intersection $V^{\text{Aut}(S)} \cap \overline{\mathcal{C}_S}$ is reduced to a single matrix A , then A is rational, lies in \mathcal{C}_S , and is weakly eutactic.*
 (3) *If this intersection is a segment, the weakly eutactic matrix which realizes the maximum of determinant in $\overline{\mathcal{C}_S}$ is defined over a totally real number field.*

Proof. To prove (1), let A' be any real positive definite matrix in $\mathbb{R}\mathcal{C}_S$ where the differential of the determinant vanishes (for instance a conjugate of A), and let $\varepsilon > 0$ be small enough for the matrices $A_t = tA + (1 - t)A'$ to be positive definite on the

interval $I = [-\varepsilon, 1 + \varepsilon]$. The logarithm of the determinant of A_t , a strictly concave function on I , has at least two extrema (at $t = 0$ and $t = 1$), a contradiction. For (2), apply Corollary 3.3 and note that $V^{\text{Aut}(S)} \cap \mathcal{C}_S$ contains rational matrices (by $\text{Aut}(S)$ -averaging a rational matrix of the class). It only remains to establish assertion (3). $V^{\text{Aut}(S)} \cap \overline{\mathcal{C}_S}$ can be parametrized as follows:

$$A_t = B + tF, \quad t \in [a, b],$$

with B and F rational and B positive definite. The parameter $t_0 \in [a, b]$ corresponding to the considered weakly eutactic matrix is a root of the derivative of the rational polynomial

$$\det(A_t) = \det(B) \det(I_n + tB^{-1}F).$$

By simultaneously diagonalizing B and F , one sees that the eigenvalues of the matrix $B^{-1}F$ are real. Let us denote by $\lambda_1, \dots, \lambda_p$ the nonzero ones. We then have

$$\det(A_t) = \det(B) \prod_{1 \leq i \leq p} (1 + t\lambda_i).$$

Thus, the roots of this polynomial being all real, so are the roots of its derivative from which we conclude that t_0 is totally real (and with degree at most $\text{rank}(F) - 1$). \square

3.5 Remark. Up to dimension 5, all weakly eutactic matrices are defined over a totally real number field. However, examples of nontotally real matrices occur from dimension 6 onwards.

4. ALGORITHMS

4.1 Algorithm for minimal classes. The algorithm consists in the enumeration of all inequivalent rank $(r-1)$ -classes under a given rank r -class \mathcal{C}_S , starting from a perfect form P and stopping when $\text{rank}(S) = n$. The dual problem of construction of the hyperplane faces of the r -dimensional associated Voronoi domain \mathcal{D}_S is a classical problem of linear programming, the heaviest step of the Voronoi algorithm. The use of the group of automorphisms of S (or of a subgroup) is crucial to lowering the number of integrally equivalent faces produced: a new class is obtained by taking a certain subset $T \subset S$ away, and all classes corresponding to elements of the $\text{Aut}(S)$ -orbit of T (up to sign-changes) are integrally equivalent. For instance, when $r = s$, the hyperplane faces are obtained by removing one vector, and there is a one-to-one correspondence between the $\text{Aut}(S)$ -orbits of vectors and $\text{Aut}(S)$ -orbits of the opposite faces. (Of course, two faces may be integrally but not $\text{Aut}(S)$ -equivalent.) An accurate description of the different types of faces in the case of dimension 5 is given in the next section.

We now describe a parametrization of the classes under P conforming to our step-by-step descending path in the graph of minimal classes. We adapt to the Voronoi domain of P the following more general linear programming:

Let (V, \langle, \rangle) be a Euclidean space, \mathcal{D} the convex hull of a finite subset D of V , N its dimension, and let

$$\mathcal{D}_0 = \mathcal{D} \supset \mathcal{D}_1 \supset \dots \supset \mathcal{D}_{k-1} \supset \mathcal{D}_k$$

be a descending chain of convex polyhedrons such that \mathcal{D}_i is a hyperplane face of \mathcal{D}_{i-1} . We inductively construct a sequence $\mathcal{F}_1, \mathcal{F}_2, \dots, \mathcal{F}_i, \dots, \mathcal{F}_k$ of $(N-1)$ -dimensional faces of the polyhedron \mathcal{D} such that for $i = 1, 2, \dots, k$,

$\mathcal{D}_i = \mathcal{F}_1 \cap \mathcal{F}_2 \cap \dots \cap \mathcal{F}_i$. Actually, we represent a face \mathcal{F} of \mathcal{D} by a so-called face-vector F , namely a vector orthogonal to the face such that $\langle F, v \rangle > 0$ for all $v \in \mathcal{D} \setminus \mathcal{F}$. We then have to determine a sequence $(F_1, \dots, F_i, \dots, F_k)$ of face-vectors of \mathcal{D} such that, for $i = 1, 2, \dots, k$, $\{F_1, F_2, \dots, F_i\}$ is a base of the subspace \mathcal{D}_i^\perp orthogonal to \mathcal{D}_i .

Algorithm. Let $D_i = D \cap \mathcal{D}_i$ be the subset of D whose convex hull is \mathcal{D}_i , and define by induction

$$F_i = \sum_{j=1}^{i-1} m_{i,j} F_j + f_i \quad (i = 1, \dots, k),$$

where $f_i \in X_{i-1}$ is a face-vector for the face \mathcal{D}_i of the convex set \mathcal{D}_{i-1} , and

$$m_{i,j} = - \min_{v \in \mathcal{D}_{j-1} \setminus \mathcal{D}_j} \frac{\langle \sum_{h=j+1}^{i-1} m_{i,h} F_h + f_i, v \rangle}{\langle F_j, v \rangle} \quad (j = i - 1, \dots, 1).$$

Since we can avoid the general algorithm in dimension up to 5 (see section 5), we just sketch the proof. Let us assume that F_1, \dots, F_{i-1} is a suitable basis of \mathcal{D}_{i-1}^\perp and let F_i be defined as above: for all $v \in V$ we have

$$\langle F_i, v \rangle = \sum_{j=1}^{i-1} m_{i,j} \langle F_j, v \rangle + \langle f_i, v \rangle.$$

We first note that, for $v \in \mathcal{D}_{i-1}$, all terms vanish except $\langle f_i, v \rangle$, which is (by construction) > 0 on $\mathcal{D}_{i-1} \setminus \mathcal{D}_i$ and $= 0$ on \mathcal{D}_i . So $F_i \in \mathcal{D}_i^\perp \setminus \mathcal{D}_{i-1}^\perp$ and F_1, \dots, F_i is a basis of \mathcal{D}_i^\perp .

It remains to check that F_i^\perp is a face of \mathcal{D} . For $j \in \{1, \dots, i - 1\}$ and $v \in \mathcal{D}_{j-1} \setminus \mathcal{D}_j$, we then have

$$\langle F_i, v \rangle = \sum_{k=j}^{i-1} m_{i,k} \langle F_k, v \rangle + \langle f_i, v \rangle,$$

which is ≥ 0 by choice of $m_{i,j}$ and vanishes for at least one vector $v_{j-1} \in \mathcal{D}_{j-1} \setminus \mathcal{D}_j$; so the hyperplane F_i^\perp is spanned by \mathcal{D}_i and v_0, v_1, \dots, v_{i-2} ; as $\langle F_i, v \rangle$ is ≥ 0 on \mathcal{D} we conclude that F_i is a face-vector of \mathcal{D} .

4.2 Algorithm for the group of a class. As usual, the well-rounded class is given by a subset S of \mathbb{Z}^n , identified with an $n \times s$ integral matrix of rank n . To compute the group $\text{Aut}(S)$, we have just, by Proposition 2.9, to compute the group of the integral matrix $\text{Aut}(S^t S)$. Note that if A is the weakly eutactic matrix A in the class (see subsection 4.3), we have also $\text{Aut}(S) = \text{Aut}(A)$ (Corollary 3.3). To compute the group of an integral definite positive matrix A is a very classical problem (see [PS] for instance). To deal with matrices defined over a number field K , we readily adapted the former algorithm to formal computation. This algorithm is much less efficient than the classical one, so in the irrational case, we use the first matrix.

4.3 Algorithm for the weakly eutactic form. Let

$$\mathcal{C}_S = \{A_t = P + t_1F_1 + \dots + t_kF_k \quad t = (t_1, \dots, t_k) \in \mathcal{T}\}$$

be the parametrization of the class \mathcal{C}_S derived from subsection 4.1, where \mathcal{T} is a convex polyhedron spanning \mathbb{R}^k (whose boundary is difficult to make precise—we generally only know that it contains the origin). The determinant function

$$d(t_1, t_2, \dots, t_k) = \det(A_t)$$

is a polynomial with rational coefficients and degree at most n ; it attains its maximum at the unique solution $\theta = (t_1, \dots, t_k) \in \overline{\mathcal{T}}$ of the algebraic system

$$(S) \quad \begin{cases} \frac{\partial d}{\partial t_1}(t_1, \dots, t_k) = 0, \\ \frac{\partial d}{\partial t_2}(t_1, \dots, t_k) = 0 \\ \dots \dots \dots \\ \frac{\partial d}{\partial t_k}(t_1, \dots, t_k) = 0, \end{cases}$$

whose direct exact resolution (using for instance the MAPLE function “solve”) is becoming rather tedious for high values of k . Moreover, it provides all solutions of (S) (as rational numbers or roots of polynomials) as well as some extra polynomials, among which it remains to select the correct one, namely the one leading to a matrix A_t in the class (or its boundary). (Note that every solution of (S) corresponds to a symmetric matrix A_t such that $\langle A_t, x^t x \rangle = 1, x \in S$ and whose adjoint belongs to the span of the $x^t x, x \in S$.) The best candidate $t = (t_1, t_2, \dots, t_k) \in \mathbb{R}^k$ is experimentally the closest to the origin, and to guarantee its accuracy it suffices to ascertain that the corresponding matrix A_t has minimum 1 and is in our class by computing its minimal vectors. In the algebraic case, we use a close rational approximation: to make the check more rigorous, we could eliminate the other real solutions of (S) by calculations of the signs of the principal determinants of the associate matrices (see Proposition 3.4), noting that the partial minors of order k not only should be positive, but greater than γ_k^k .

Actually, to the exact resolution we preferred the classical *gradient method* which efficiently provides an approximate solution in \mathcal{T} (if any). We look for the maximum of a convex function, and if this maximum exists in an open convex set, the algorithm converges to this solution. We search for a good enough approximation to obtain when necessary (by the “algdep” PARI function based on LLL algorithm) an irreducible polynomial f defining the number field $K = \mathbb{Q}(\theta)$. It remains to check the accuracy of this solution θ by formal computation of a basis of the systems of eutactic coefficients in K (this is the classical determination of the kernel of a matrix with entries integral or polynomial modulo f).

When the gradient algorithm gives an erratic solution, we conclude that the determinant attains its maximum on the least dense of the weakly eutactic forms on the boundary of the class.

4.4 Identification of a class. In the above sections, we attached to a minimal class, represented by the set \mathcal{C}_S of matrices with minimum 1 and set of minimal vectors S , some invariants: the number $2s$ of minimal vectors, the rank of perfection, the determinant spectrum, the order of its automorphism group, the weakly eutactic matrix in its closure where the determinant attains its maximum, with its number

field and density, and finally the invariants of the integral matrix $T = S^tS$. If they coincide for two classes \mathcal{C}_{S_1} and \mathcal{C}_{S_2} , we must look for a matrix U in $\text{GL}_n(\mathbb{Z})$ such that $US_1 = S_2V$, where V is a permutation and sign-changes $s \times s$ matrix: this is with minor modifications the problem alluded to in subsection 4.2, but here we stop with the first convenient matrix U (if any). Note that if we choose to compare two weakly eutactic matrices, we must be careful with formal calculations in the algebraic case: if A and B are two matrices with entries in two isomorphic number fields defined by two distinct polynomials f and g , we first have to find all automorphisms σ from $\mathbb{Q}(\alpha)$ to $\mathbb{Q}(\beta)$ (where α and β are roots of f and g); for each σ , we obtain, by substituting β by $\sigma(\alpha)$, two matrices over the same field $\mathbb{Q}(\alpha)$, and we look for integral equivalence between them in the usual method. Of course, we know from Proposition 3.4 (1) that there is at most one solution σ .

5. QUINTIC FORMS

5.1 Perfect Voronoi domains in dimension 5. We used here well-known results on low-dimensional forms (see [Mar], chap. VII, §7). The notation is that of [CS1].

We start the algorithm with the 3 perfect forms in dimension 5: A_5 , A_5^3 and D_5 . They are obtained by the classical Voronoi algorithm, beginning with

$$A_5 = \left(\sum_{1 \leq i \leq 5} x_i \right)^2 + \sum_{1 \leq i \leq 5} x_i^2.$$

The automorphism groups of the forms A_5 and A_5^3 act transitively on their sets of minimal vectors, so they have only (up to integral equivalence) one neighbour, which is

$$D_5 = A_5 - 2x_1x_2.$$

The form D_5 has 20 pairs ($\pm v$) of minimal vectors. Rejecting one of each pair and writing the others in a convenient order, we obtain the matrix

$$S(D_5) = \begin{pmatrix} 1 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 & 1 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 0 & 0 & 1 & 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 & 0 & -1 & 0 & 0 & -1 & 0 & 0 & 1 & 1 & 0 & -1 & 0 & 0 & -1 \\ 0 & 0 & 0 & 1 & 0 & 0 & -1 & 0 & 0 & -1 & 0 & -1 & 0 & 1 & 0 & -1 & 0 & -1 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & -1 & 0 & 0 & 0 & -1 & 0 & -1 & 0 & -1 & 0 & -1 \end{pmatrix}.$$

So all classes with rank up to 14 can be obtained from D_5 . The 400 faces of the Voronoi domain of D_5 are divided into 4 orbits leading to forms integrally equivalent to A_5 , $D'_5 \sim D_5$, A_5^3 , $E_5 \sim D_5$, respectively. More precisely we have

$$A_5 = D_5 + 2x_1x_2,$$

$$D'_5 = D_5 + 2(x_1x_2 - x_3x_4),$$

$$A_5^3 = D_5 + (x_1x_2 - x_3x_4 - x_3x_5 - x_4x_5),$$

$$E_5 = D_5 - 2x_1x_3.$$

When going from D_5 to one of these neighbours, we remove from $S(D_5)$ 6 vectors except in the last case—let us call it *special*—where we take off 4 vectors, keeping the 12 minimal vectors spanning the D_4 section $x_3 = 0$ of D_5 . The four corresponding inequivalent classes of rank 14 contain a eutactic form

$$D_5 + \frac{3}{2}x_1x_2,$$

$$D_5 + (x_1x_2 - x_3x_4),$$

$$D_5 + \frac{5 - \sqrt{10}}{5}(x_1x_2 - x_3x_4 - x_3x_5 - x_4x_5),$$

$$D_5 - x_1x_3.$$

Note that the last eutactic form has $s = 16 > 15 = n(n+1)/2$ pairs of minimal vectors, and is not extreme. This is the minimal negative answer to a question by Coxeter: *Is every eutactic form with $s \geq n(n+1)/2$ extreme?* (see [Ba]). Its class is the only nonperfect one with $s \geq 16$.

Now, to obtain the complete graph of minimal classes in dimension 5, we can restrict ourselves to classes under the perfect class of D_5 and have to distinguish two kinds of classes. In those for which $r = s$ are easy to compute, we remove from the set $S(C)$ one minimal vector, up to the isometry group of the class (or the group of an element of the class). Those for which $s > r$ are a little bit more complicated to deal with; they belong to a class we shall call “special”. Actually, they satisfy $s = r + 2$, for they correspond to lattices having a section similar to the D_4 -lattice, for which $s = 12$ and $r = 10$. Note that this section is unique: a lattice with two sections L_1 and L_2 isometric to \mathbb{D}_4 must have at least $18 = 12 + 12 - 6$ pairs of minimal vectors (the 3-dimensional lattice $L_1 \cap L_2$ having at most 6 minimal vectors). The subset of the 12 minimal vectors of the section D_4 is therefore invariant under the automorphism group of the class. In order to obtain the classes under a special class \mathcal{C}_S , we remove from the set S either one minimal vector out of the D_4 -section (producing a special class), or 3 minimal vectors in the D_4 -section spanning a hexagonal plane or having mutual product 1 (corresponding to the two orbits of faces of the Voronoi domain of D_4). Taking into account the action of the group of the class on these subsets (only one orbit in the special case), we obtain a unique sequence of well-rounded special classes

$$b_{11} \prec l_{12} \prec i_{13} \prec d_{14} \prec \text{class } (D_5)$$

(the class b_{11} has $A_1 \perp D_4$ as a eutactic form, so its group is $C_2 \times \text{Aut}(D_4)$, with 2304 elements, the biggest one after $\text{Aut}(D_5) = \text{Aut}(D_5^*) = \text{Aut}(A_1^5)$), and only two nonspecial classes c_{13} and g_{13} which could not be produced from nonspecial classes.

5.2 Results. Our algorithm for minimal classes was implemented on a Sun Sparc station under UNIX system environment. The computation times are very short, except for the determination of the field of definition of the eutactic form when a high degree is involved.

We conclude this paper with Table 3 giving the list of the well-rounded minimal classes in dimension 5 and their invariants, and Table 4 displaying the matrices of the rational weakly eutactic forms. The algebraic matrices and the automorphism groups can be requested from the author.

Let us give a few statistics and comments on our results.

There are 136 minimal classes in dimension 5, and no coincidence of their invariants. Among these classes, only 127 have a weakly eutactic form, among which 118 are eutactic.

Let us recall that there are, respectively, 1, 2, 5, 18 classes in dimension 1, 2, 3, 4, all of them with eutactic forms except two in dimension 4 (one with a semi-eutactic form and, as foreseen from Theorem 3.2 (3), a class below without any

TABLE 2. Statistics on eutaxy in dimension 5

rk	#cl	Weakly eutactic form				Degree of number field						
		e	se	we	no	1	2	3	4	5	9	
15	3	3				3						
14	4	4				3	1					
13	9	9				5	3	1				
12	16	15	1			8	4	3	1			
11	23	19	2	1	1	9	9	2		1		1
10	25	20		2	3	9	10	2	1			
9	23	19	1	1	2	11	7	1	1	1		
8	16	13	1		2	7	6	1				
7	10	9			1	7	2					
6	5	5				5						
5	2	2				2						
Total	136	118	5	4	9	69	42	10	3	2		1

weakly eutactic form). In dimension 5, the ratio of classes with eutactic forms is nearly the same, but negative eutaxy coefficients appear here in ranks 9, 10, and 11.

From Proposition 3.1 we know that our classification yields the classification in lower dimensions. Twenty disconnected weakly eutactic forms (of course eutactic indeed except one) appear in ranks up to 11 (the maximal rank in dimension 4 is 10). Their classes are the least dense in their rank.

Among the 127 weakly eutactic forms, only 69 are rational, the others are defined over *totally real number fields* with degrees up to nine. Note that the nine weakly eutactic noneutactic forms except one (t_{11} which is defined over the field $\mathbb{Q}(\sqrt{13})$) are rational. To save space, we will not describe the field of definition of weakly eutactic forms when the degree is greater than 2. We will content ourselves with the single example of the field K of degree 9. It has discriminant $2^4 \cdot 3^2 \cdot 17^2 \cdot 81037273 \cdot 3535337303$, and can be defined by the polynomial

$$x^9 - 2x^8 - 150x^7 + 174x^6 + 5763x^5 - 3564x^4 - 82450x^3 + 18548x^2 + 387552x + 18432.$$

(The computation of the corresponding eutactic form required an accuracy of about 450 digits. For the 5 degree polynomial of the class w_{11} we needed about 100 digits, and for all other classes, less than 50 digits.) Table 2 summarizes these results.

When looking at the index n_1 of the determinant spectrums in Table 3 below, we see that each well-rounded class except one (the class a_5 of the eutactic lattice D_5^* dual of D_5) has a basis of minimal vectors. More precisely we have (see [Mar]):

Proposition. *Let A be a positive definite quadratic form in dimension less than or equal to five, such that $S(A)$ contains n independent minimal vectors. Then the sublattice of \mathbb{Z}^n generated by $S(A)$ in \mathbb{Z}^n is equal to \mathbb{Z}^n except for the class of D_5^* where the index is 2 and $s = 5$. When the index is one, we can extract from $S(A)$ a basis of \mathbb{Z}^n .*

5.3 Ash's formula. Let us recall Ash's formula for n -dimensional eutactic forms:

$$\sum_A \frac{(-1)^{i(A)}}{|\text{Aut}^+(A)|} = \chi(\text{SL}_n(\mathbb{Z})),$$

where A ranges over all integrally inequivalent eutactic forms in dimension n . Here i is the defect of perfection of the form and χ is the Euler-Poincaré characteristic of a group (note that $\chi(\text{SL}_n(\mathbb{Z})) = 0$ for $n \geq 3$). The sign $+$ means that only direct equivalence is considered, but when the dimension is odd and greater than or equal to 3, we may consider the full group $\text{Aut}(A)$ as defined in Section 2. Our calculations of automorphism groups (see Table 3) allow us to check Ash's formula for dimension 5, i.e., the vanishing of an alternating sum of 118 terms:

$$\begin{aligned} & \frac{1}{1440} + \frac{1}{3840} + \frac{1}{1440} \\ & - \left(\frac{1}{96} + \frac{1}{32} + \frac{1}{96} + \frac{1}{96} \right) \\ & + \left(\frac{1}{24} + \frac{1}{32} + \frac{1}{32} + \frac{1}{8} + \frac{1}{8} + \frac{1}{32} + \frac{1}{72} + \frac{1}{24} + \frac{1}{72} \right) \\ & - \left(\frac{1}{48} + \frac{1}{72} + \frac{1}{8} + \frac{1}{8} + \frac{1}{24} + \frac{1}{96} + \frac{1}{32} + \frac{1}{4} + \frac{1}{8} + \frac{1}{4} + \frac{1}{192} + \frac{1}{8} + \frac{1}{8} + \frac{1}{24} + \frac{1}{72} \right) \\ & + \left(\frac{1}{480} + \frac{1}{2304} + \frac{1}{8} + \frac{1}{32} + \frac{1}{48} + \frac{1}{4} + \frac{1}{24} + \frac{1}{16} + \frac{1}{8} + \frac{1}{8} + \frac{1}{16} + \frac{1}{8} + \frac{1}{48} + \frac{1}{4} + \frac{1}{4} + \frac{1}{20} + \frac{1}{4} + \frac{1}{96} + \frac{1}{8} \right) \\ & - \left(\frac{1}{48} + \frac{1}{288} + \frac{1}{64} + \frac{1}{16} + \frac{1}{16} + \frac{1}{8} + \frac{1}{8} + \frac{1}{8} + \frac{1}{20} + \frac{1}{32} + \frac{1}{4} + \frac{1}{24} + \frac{1}{24} + \frac{1}{20} + \frac{1}{8} + \frac{1}{8} + \frac{1}{4} + \frac{1}{4} + \frac{1}{16} + \frac{1}{1440} \right) \\ & + \left(\frac{1}{32} + \frac{1}{576} + \frac{1}{32} + \frac{1}{96} + \frac{1}{16} + \frac{1}{48} + \frac{1}{32} + \frac{1}{8} + \frac{1}{16} + \frac{1}{8} + \frac{1}{8} + \frac{1}{24} + \frac{1}{144} + \frac{1}{96} + \frac{1}{8} + \frac{1}{64} + \frac{1}{24} + \frac{1}{8} + \frac{1}{8} \right) \\ & - \left(\frac{1}{384} + \frac{1}{192} + \frac{1}{32} + \frac{1}{32} + \frac{1}{96} + \frac{1}{32} + \frac{1}{24} + \frac{1}{48} + \frac{1}{16} + \frac{1}{64} + \frac{1}{24} + \frac{1}{16} + \frac{1}{24} \right) \\ & + \left(\frac{1}{128} + \frac{1}{576} + \frac{1}{576} + \frac{1}{48} + \frac{1}{96} + \frac{1}{144} + \frac{1}{96} + \frac{1}{96} + \frac{1}{48} \right) \\ & - \left(\frac{1}{576} + \frac{1}{384} + \frac{1}{480} + \frac{1}{1440} + \frac{1}{240} \right) \\ & + \left(\frac{1}{3840} + \frac{1}{3840} \right) \\ & = 0. \end{aligned}$$

Remark. Theorem 3.2 states that to any class \mathcal{C} without a weakly eutactic form corresponds a class $\mathcal{C}' \succ \mathcal{C}$ with a weakly eutactic form which is not eutactic (namely the class of the less dense form in $\overline{\mathcal{C}}$). In the five-dimensional case, this correspondence happens to be one-to-one, with consecutive defects and the same automorphism groups. Thus from the Ash formula we can deduce a “mass formula” for the five-dimensional well-rounded *minimal classes* (instead of eutactic forms)

$$\sum_{\mathcal{C}} \frac{(-1)^{i(\mathcal{C})}}{|\text{Aut}(\mathcal{C})|} = \chi(\text{SL}_n(\mathbb{Z})).$$

Actually, a general proof of this formula has just been given to me by Christophe Bavard ([Bv]). In this second formula for $n = 5$ we have 18 more terms $-\frac{1}{32} + \left(\frac{1}{64} + \frac{1}{16} + \frac{1}{32}\right) - \left(\frac{1}{64} + \frac{1}{64} + \frac{1}{16} + \frac{1}{96}\right) + \left(\frac{1}{32} + \frac{1}{768} + \frac{1}{64} + \frac{1}{96}\right) - \left(\frac{1}{192} + \frac{1}{32} + \frac{1}{768}\right) + \frac{1}{192} = 0$.

TABLE 3. The index in our notation for the classes is the rank of perfection, and the classes of the same rank are ordered in ascending order of the minimal Hermite invariant γ in the class (or its boundary). In the fourth column we give the order g of the automorphism group of the class, and in the fifth the determinant spectrum $[n_0, n_1, n_2]$ of the class. In the sixth column we specify the existence of a weakly eutactic form in the class (“e” means eutactic, “se” semi-eutactic, and “we” the other types), and the name of remarkable or disconnected forms (in the last case, a notation like $E(a_8^4)$ refers to the weakly eutactic form in the 4-dimensional class labelled a_8 in [BM]). If there is no weakly eutactic form in the class, we refer to the one in the boundary at which the minimum of density is attained. In the last column, we give the number field over which the corresponding eutactic form is defined, or only its degree when it is greater than 2.

class	s	γ	g	Spect	Eut	Field
a_{15}	15	1.39765	1440	[1707 , 1296 , 0]	e (A_5)	\mathbb{Q}
b_{15}	15	1.44596	1440	[1485 , 1512 , 6]	e (A_5^3)	\mathbb{Q}
c_{15}	20	1.51571	3840	[7792 , 7552 , 160]	e (D_5)	\mathbb{Q}
a_{14}	14	1.38629	96	[1138, 864, 0]	e	\mathbb{Q}
b_{14}	14	1.39765	32	[1048, 952, 2]	e	\mathbb{Q}
c_{14}	14	1.43378	96	[990, 1008, 4]	e	$\mathbb{Q}(\sqrt{10})$
d_{14}	16	1.44955	96	[2364, 1986, 18]	e	\mathbb{Q}
a_{13}	13	1.36851	24	[747, 540, 0]	e	\mathbb{Q}
b_{13}	13	1.37737	32	[711, 576, 0]	e	$\mathbb{Q}(\sqrt{172})$
c_{13}	13	1.39190	32	[702, 584, 1]	e	\mathbb{Q}
d_{13}	13	1.39958	8	[674, 612, 1]	e	$\mathbb{Q}(\sqrt{33})$
e_{13}	13	1.40816	8	[669, 616, 2]	e	deg 3
f_{13}	13	1.41229	32	[653, 632, 2]	e	\mathbb{Q}
g_{13}	13	1.41933	72	[648, 636, 3]	e	\mathbb{Q}
h_{13}	13	1.42376	24	[624, 660, 3]	e	$\mathbb{Q}(\sqrt{57})$
i_{13}	15	1.43096	72	[1716, 1275, 12]	e	\mathbb{Q}
a_{12}	12	1.33656	48	[492, 300, 0]	e	\mathbb{Q}
b_{12}	12	1.35096	72	[468, 324, 0]	e	\mathbb{Q}
c_{12}	12	1.35096	8	[456, 336, 0]	e	\mathbb{Q}
d_{12}	12	1.36334	8	[432, 360, 0]	e	deg 3
e_{12}	12	1.36511	24	[429, 363, 0]	e	\mathbb{Q}
f_{12}	12	1.36979	96	[408, 384, 0]	e	\mathbb{Q}
g_{12}	12	1.37646	32	[400, 392, 0]	e	$\mathbb{Q}(\sqrt{10})$
h_{12}	12	1.38353	4	[424, 367, 1]	e	$\mathbb{Q}(\sqrt{385})$
i_{12}	12	1.38936	8	[411, 380, 1]	e	$\mathbb{Q}(\sqrt{145})$
j_{12}	12	1.39206	4	[400, 391, 1]	e	deg 3
k_{12}	12	1.39765	32	[414, 376, 2]	se	\mathbb{Q}
l_{12}	14	1.39765	192	[1267, 728, 7]	e	\mathbb{Q}
m_{12}	12	1.40248	8	[402, 388, 2]	e	deg 4
n_{12}	12	1.40680	8	[382, 408, 2]	e	$\mathbb{Q}(\sqrt{73})$
o_{12}	12	1.41377	24	[366, 424, 2]	e	deg 3
p_{12}	12	1.41714	72	[369, 420, 3]	e	\mathbb{Q}

Table 3 (continued)

class	s	γ	g	Spect	Eut	Field
a_{11}	11	1.26191	480	[337, 125, 0]	e $(A_4 \perp A_1)$	\mathbb{Q}
b_{11}	13	1.31951	2304	[972, 312, 3]	e $(D_4 \perp A_1)$	\mathbb{Q}
c_{11}	11	1.31951	8	[277, 185, 0]	e	\mathbb{Q}
d_{11}	11	1.31951	64	[270, 192, 0]	se	\mathbb{Q}
e_{11}	11	1.31951	16	[282, 180, 0]	se	\mathbb{Q}
f_{11}	11	1.33333	32	[264, 198, 0]	e	\mathbb{Q}
g_{11}	11	1.33624	48	[262, 200, 0]	e	$\mathbb{Q}(\sqrt{7})$
h_{11}	11	1.33932	4	[253, 209, 0]	e	$\mathbb{Q}(\sqrt{3})$
i_{11}	11	1.34843	24	[246, 216, 0]	e	$\mathbb{Q}(\sqrt{73})$
j_{11}	11	1.34843	16	[238, 224, 0]	e	$\mathbb{Q}(\sqrt{73})$
k_{11}	11	1.35481	8	[237, 225, 0]	e	$\mathbb{Q}(\sqrt{33})$
l_{11}	11	1.35686	8	[231, 231, 0]	e	deg 3
m_{11}	11	1.36845	16	[255, 206, 1]	e	$\mathbb{Q}(\sqrt{97})$
n_{11}	11	1.37013	8	[245, 216, 1]	e	$\mathbb{Q}(\sqrt{2})$
o_{11}	11	1.37152	48	[249, 212, 1]	e	$\mathbb{Q}(\sqrt{145})$
p_{11}	11	1.37630	4	[235, 226, 1]	e	\mathbb{Q}
q_{11}	11	1.37906	4	[231, 230, 1]	e	deg 3
r_{11}	11	1.38528	20	[215, 246, 1]	e	\mathbb{Q}
s_{11}	11	1.38570	4	[219, 242, 1]	e	deg 9
t_{11}	11	1.39466	16	[228, 232, 2]	we	$\mathbb{Q}(\sqrt{13})$
u_{11}	11	1.39765	32	[212, 248, 2]	- $[k_{12} \text{ se}]$	\mathbb{Q}
v_{11}	11	1.40206	96	[195, 266, 1]	e	\mathbb{Q}
w_{11}	11	1.40214	8	[204, 256, 2]	e	deg 5
a_{10}	10	1.24573	48	[177, 75, 0]	e $(E(b_9^4) \perp A_1)$	\mathbb{Q}
b_{10}	10	1.25878	288	[171, 81, 0]	e $(E(a_9^4) \perp A_1)$	\mathbb{Q}
c_{10}	10	1.28878	64	[152, 100, 0]	e	\mathbb{Q}
d_{10}	10	1.28878	16	[153, 99, 0]	e	\mathbb{Q}
e_{10}	10	1.28878	16	[148, 104, 0]	e	\mathbb{Q}
f_{10}	10	1.28878	64	[156, 96, 0]	we	\mathbb{Q}
g_{10}	10	1.30813	8	[141, 111, 0]	e	$\mathbb{Q}(\sqrt{3})$
h_{10}	10	1.30813	8	[138, 114, 0]	e	$\mathbb{Q}(\sqrt{3})$
i_{10}	10	1.31668	8	[137, 115, 0]	e	$\mathbb{Q}(\sqrt{13})$
j_{10}	10	1.31951	64	[124, 128, 0]	- $[d_{11} \text{ se}]$	\mathbb{Q}
k_{10}	10	1.31951	16	[132, 120, 0]	- $[e_{11} \text{ se}]$	\mathbb{Q}
l_{10}	10	1.31951	20	[131, 121, 0]	e	$\mathbb{Q}(\sqrt{5})$
m_{10}	10	1.33206	32	[126, 126, 0]	e	$\mathbb{Q}(\sqrt{19})$
n_{10}	10	1.33249	4	[122, 130, 0]	e	deg 3
o_{10}	10	1.34216	24	[117, 135, 0]	e	\mathbb{Q}
p_{10}	10	1.34416	24	[117, 135, 0]	e	$\mathbb{Q}(\sqrt{57})$
q_{10}	10	1.35610	20	[130, 121, 1]	e	$\mathbb{Q}(\sqrt{13})$
r_{10}	10	1.35994	8	[131, 120, 1]	e	$\mathbb{Q}(\sqrt{13})$
s_{10}	10	1.36331	8	[126, 125, 1]	e	deg 3
t_{10}	10	1.36788	4	[119, 132, 1]	e	deg 4
u_{10}	10	1.37437	4	[110, 141, 1]	e	$\mathbb{Q}(\sqrt{193})$
v_{10}	10	1.38201	16	[102, 149, 1]	e	$\mathbb{Q}(\sqrt{73})$
w_{10}	10	1.38316	1440	[90, 162, 0]	e $(A_5^2 = (A_5^3)^*)$	\mathbb{Q}
x_{10}	10	1.39022	96	[114, 136, 2]	we	\mathbb{Q}
y_{10}	10	1.39466	16	[98, 152, 2]	- $[t_{11} \text{ we}]$	\mathbb{Q}

Table 3 (continued)

class	s	γ	g	Spect	Eut	Field
a_9	9	1.21673	32	[86, 40, 0]	e $(E(b_8^4) \perp A_1)$	\mathbb{Q}
b_9	9	1.21673	576	[78, 48, 0]	e $(A_3 \perp A_2)$	\mathbb{Q}
c_9	9	1.23499	32	[81, 45, 0]	e $(E(a_8^4) \perp A_1)$	$\mathbb{Q}(\sqrt{3})$
d_9	9	1.25878	96	[72, 54, 0]	e	\mathbb{Q}
e_9	9	1.25878	16	[71, 55, 0]	e	\mathbb{Q}
f_9	9	1.25878	32	[74, 52, 0]	se	\mathbb{Q}
g_9	9	1.25878	768	[78, 48, 0]	we	\mathbb{Q}
h_9	9	1.27542	48	[70, 56, 0]	e	\mathbb{Q}
i_9	9	1.28603	32	[66, 60, 0]	e	$\mathbb{Q}(\sqrt{13})$
j_9	9	1.28603	8	[65, 61, 0]	e	$\mathbb{Q}(\sqrt{13})$
k_9	9	1.28603	16	[62, 64, 0]	e	$\mathbb{Q}(\sqrt{13})$
l_9	9	1.28878	64	[62, 64, 0]	-	$[f_{10} \text{ we}]$
m_9	9	1.30136	8	[60, 66, 0]	e	\mathbb{Q}
n_9	9	1.30734	8	[57, 69, 0]	e	deg4
o_9	9	1.32108	24	[51, 75, 0]	e	$\mathbb{Q}(\sqrt{6})$
p_9	9	1.33790	144	[45, 81, 0]	e	\mathbb{Q}
q_9	9	1.34540	96	[65, 60, 1]	e	\mathbb{Q}
r_9	9	1.34978	8	[59, 66, 1]	e	$\mathbb{Q}(\sqrt{73})$
s_9	9	1.35401	64	[57, 68, 1]	e	\mathbb{Q}
t_9	9	1.35492	24	[57, 68, 1]	e	$\mathbb{Q}(\sqrt{41})$
u_9	9	1.35815	8	[53, 72, 1]	e	deg3
v_9	9	1.36650	8	[45, 80, 1]	e	deg5
w_9	9	1.39022	96	[53, 72, 1]	-	$[x_{10} \text{ we}]$
a_8	8	1.14870	384	[40, 16, 0]	e $(A_3 \perp A_1^2)$	\mathbb{Q}
b_8	8	1.18840	192	[32, 24, 0]	e $(E(a_5^3) \perp A_2)$	\mathbb{Q}
c_8	8	1.18840	32	[35, 21, 0]	e $(E(c_7^4) \perp A_1)$	\mathbb{Q}
d_8	8	1.18840	192	[36, 20, 0]	se $(E(b_7^4) \perp A_1)$	\mathbb{Q}
e_8	8	1.21412	32	[32, 24, 0]	e $(E(a_7^4) \perp A_1)$	$\mathbb{Q}(\sqrt{13})$
f_8	8	1.24573	96	[28, 28, 0]	e	\mathbb{Q}
g_8	8	1.24573	32	[26, 30, 0]	e	\mathbb{Q}
h_8	8	1.24573	24	[27, 29, 0]	e	\mathbb{Q}
i_8	8	1.25878	32	[24, 32, 0]	-	$[f_9 \text{ se}]$
j_8	8	1.25878	768	[24, 32, 0]	-	$[g_9 \text{ we}]$
k_8	8	1.26867	48	[24, 32, 0]	e	$\mathbb{Q}(\sqrt{33})$
l_8	8	1.28160	16	[21, 35, 0]	e	$\mathbb{Q}(\sqrt{7})$
m_8	8	1.28428	64	[20, 36, 0]	e	$\mathbb{Q}(\sqrt{5})$
n_8	8	1.34027	24	[23, 32, 1]	e	$\mathbb{Q}(\sqrt{241})$
o_8	8	1.34492	16	[20, 35, 1]	e	$\mathbb{Q}(\sqrt{3})$
p_8	8	1.35434	24	[15, 40, 1]	e	deg3

Table 3 (continued)

class	s	γ	g	Spect	Eut	Field
a_7	7	1.12195	128	[13, 8, 0]	e $(E(a_3^3) \perp A_1^2)$	\mathbb{Q}
b_7	7	1.12195	576	[12, 9, 0]	e $(A_2^2 \perp A_1)$	\mathbb{Q}
c_7	7	1.17607	576	[9, 12, 0]	e $(A_2 \perp A_3^*)$	\mathbb{Q}
d_7	7	1.17607	48	[10, 11, 0]	e $(E(b_6^4) \perp A_1)$	\mathbb{Q}
e_7	7	1.18840	192	[9, 12, 0]	- $[d_8 \text{ se}]$	
f_7	7	1.22251	96	[7, 14, 0]	e	\mathbb{Q}
g_7	7	1.23281	144	[6, 15, 0]	e	\mathbb{Q}
h_7	7	1.24501	96	[5, 16, 0]	e	$\mathbb{Q}(\sqrt{89})$
i_7	7	1.33211	96	[6, 14, 1]	e	\mathbb{Q}
j_7	7	1.33746	48	[4, 16, 1]	e	$\mathbb{Q}(\sqrt{409})$
a_6	6	1.05922	576	[3, 3, 0]	e $(A_2 \perp A_1^3)$	\mathbb{Q}
b_6	6	1.11032	384	[2, 4, 0]	e $(A_3^* \perp A_1^2)$	\mathbb{Q}
c_6	6	1.15415	480	[1, 5, 0]	e $(A_4^* \perp A_1)$	\mathbb{Q}
d_6	6	1.19247	1440	[0, 6, 0]	e (A_5^*)	\mathbb{Q}
e_6	6	1.32691	240	[0, 5, 1]	e	\mathbb{Q}
a_5	5	1.00000	3840	[0, 1, 0]	e (A_1^5)	\mathbb{Q}
b_5	5	1.31950	3840	[0, 0, 1]	e (D_5^*)	\mathbb{Q}

TABLE 4. This table gives the upper entries α_{ij} of the rational weakly-eutactic matrices in the corresponding class.

class	α_{11}	α_{12}	α_{13}	α_{14}	α_{15}	α_{22}	α_{23}	α_{24}	α_{25}	α_{33}	α_{34}	α_{35}	α_{44}	α_{45}	α_{55}
A_5	2	1	1	1	1	2	1	1	1	2	1	1	2	1	2
A_5^3	4	1	2	2	2	4	2	2	2	4	1	1	4	1	4
D_5	2	0	1	1	1	2	1	1	1	2	1	1	2	1	2
a_{14}	8	3	4	4	4	8	4	4	4	8	4	4	8	4	8
b_{14}	4	1	2	2	2	4	2	2	2	4	2	2	4	1	4
d_{14}	4	0	1	2	2	4	2	2	2	4	2	2	4	2	4
a_{13}	6	3	3	3	3	6	3	3	4	6	3	4	6	4	8
c_{13}	4	0	2	1	1	4	2	2	2	4	1	2	4	2	4
f_{13}	16	4	9	8	8	16	9	8	8	18	9	9	16	4	16
g_{13}	6	0	3	4	2	6	3	3	3	6	3	3	8	4	6
i_{13}	6	0	3	3	2	6	3	3	4	6	3	4	6	4	8
a_{12}	4	2	2	2	2	4	2	2	2	4	2	3	4	3	6
b_{12}	8	4	4	4	4	6	3	3	4	6	3	4	6	4	8
c_{12}	18	9	9	12	10	18	9	12	13	18	12	13	24	16	26
e_{12}	4	2	2	2	3	6	3	3	4	4	2	3	4	2	6
f_{12}	10	5	5	4	6	10	4	5	6	10	5	6	10	6	12
k_{12}	8	1	4	4	3	8	4	3	4	8	4	4	8	1	8
l_{12}	4	0	2	2	2	4	2	2	2	4	2	3	4	3	6
p_{12}	10	-5	-5	4	2	10	4	-5	2	10	1	-4	10	-4	10
a_{11}	2	1	1	1	0	2	1	1	0	2	1	0	2	0	2
b_{11}	2	1	-1	1	0	2	-1	1	0	2	0	0	2	0	2
c_{11}	12	6	6	8	7	12	6	8	7	12	8	10	16	12	20
d_{11}	4	2	2	2	2	4	2	3	3	4	3	3	6	4	6
e_{11}	12	6	6	8	6	12	6	8	9	12	8	9	16	8	18
f_{11}	8	5	4	6	6	14	7	9	9	8	6	6	12	6	12
p_{11}	100	25	50	60	51	100	50	60	66	100	60	66	120	36	132
r_{11}	10	2	5	4	6	10	4	5	6	10	5	6	10	3	12
v_{11}	8	-4	-3	3	2	8	3	-3	2	8	2	-3	8	-3	8
a_{10}	6	3	3	-2	0	6	3	1	0	6	1	0	6	0	6
b_{10}	4	0	0	0	0	4	2	-1	2	4	1	1	4	1	4
c_{10}	4	2	3	3	3	4	3	3	3	6	4	5	6	5	8
d_{10}	8	6	4	6	5	12	6	8	7	8	6	7	12	9	14
e_{10}	8	4	4	4	4	8	4	6	5	8	6	7	12	9	14
f_{10}	4	2	2	2	2	4	2	3	3	4	3	3	6	3	6
o_{10}	12	3	6	4	7	12	6	6	9	12	3	9	12	2	18
w_{10}	3	1	1	-1	-1	3	-1	1	-1	3	-1	1	3	1	3
x_{10}	12	1	6	5	5	12	6	5	5	12	6	6	12	1	12
a_9	4	2	2	0	0	4	2	-1	0	4	1	0	4	0	4
b_9	2	1	1	0	0	2	1	0	0	2	0	0	2	1	2
d_9	14	7	5	9	7	8	4	6	5	8	6	7	12	9	14
e_9	24	12	12	18	15	16	8	10	9	16	14	15	28	21	30
f_9	12	9	6	6	6	14	7	5	6	8	4	6	8	6	12
g_9	6	3	3	3	3	4	2	3	3	4	3	3	6	3	6
h_9	6	3	3	3	3	6	3	5	4	6	4	5	10	7	10
m_9	36	18	12	24	18	36	18	24	21	36	20	28	48	34	56
p_9	6	3	3	3	3	5	2	2	3	5	2	3	5	3	6
q_9	6	0	2	2	3	6	3	3	3	6	3	4	6	1	8
s_9	8	2	5	5	5	8	5	5	5	10	6	7	10	3	12

Table 4 (continued)

class	α_{11}	α_{12}	α_{13}	α_{14}	α_{15}	α_{22}	α_{23}	α_{24}	α_{25}	α_{33}	α_{34}	α_{35}	α_{44}	α_{45}	α_{55}
a_8	2	1	1	0	0	2	1	0	0	2	0	0	2	0	2
b_8	4	2	0	0	0	4	0	0	0	4	2	-1	4	1	4
c_8	8	4	-2	1	0	8	2	-1	0	8	2	0	8	0	8
d_8	4	2	-1	-1	0	4	1	1	0	4	1	0	4	0	4
f_8	18	9	9	9	9	12	6	10	8	12	8	10	20	14	20
g_8	12	6	8	10	9	12	10	8	9	20	14	17	20	17	26
h_8	12	6	9	7	8	12	9	11	10	18	12	15	22	17	24
a_7	4	2	-1	0	0	4	1	0	0	4	0	0	4	0	4
b_7	2	1	0	0	0	2	0	0	0	2	1	0	2	0	2
c_7	6	3	0	0	0	6	0	0	0	6	2	-2	6	2	6
d_7	6	3	-1	1	0	6	1	-1	0	6	2	0	6	0	6
f_7	8	4	7	5	6	8	5	7	6	14	8	11	14	11	16
g_7	9	3	6	4	5	9	6	8	7	12	8	10	16	12	17
i_7	24	0	9	11	11	24	12	12	12	24	15	15	30	4	30
a_6	2	1	0	0	0	2	0	0	0	2	0	0	2	0	2
b_6	3	1	-1	0	0	3	1	0	0	3	0	0	3	0	3
c_6	4	1	-1	1	0	4	1	-1	0	4	1	0	4	0	4
d_6	5	-1	-1	-1	-1	5	-1	-1	-1	5	-1	-1	5	-1	5
e_6	20	1	9	10	10	20	12	11	11	24	15	15	26	5	26
a_5	5	3	-2	-2	-2	5	-2	-2	-2	4	0	0	4	0	4
b_5	1	0	0	0	0	1	0	0	0	1	0	0	1	0	1

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