ERROR ESTIMATE OF A RANDOM PARTICLE BLOB METHOD FOR THE KELLER-SEGEL EQUATION

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Abstract. We establish an optimal error estimate for a random particle blob method for the Keller-Segel equation in $\mathbb{R}^d$ ($d \geq 2$). With a blob size $\varepsilon = h^\kappa$ ($1/2 < \kappa < 1$), we prove a rate $h|\ln h|$ of convergence in $\ell^p_h$ ($p > \frac{d}{1-\kappa}$) norm up to a probability $1 - hC|\ln h|$, where $h$ is the initial grid size.

1. Introduction

The vortex method was first introduced by Chorin in 1973 [6], which is one of the most significant computational methods for fluid dynamics and other related fields. The convergence of the vortex method for two- and three-dimensional inviscid incompressible fluid flows was first proved by Hald [13], Beale and Majda [2,3]. Then Anderson and Greengard [1] gave a simpler proof for the estimate of the consistency error. When the effect of viscosity is involved, the vortex method is replaced by the so-called random vortex method by adding a Brownian motion to every vortex. The convergence analysis of the random vortex method for the Navier-Stokes equation has been given by [11,19,20,23] in 1980s.

Generally speaking, there are two ways to set up the initial data. On one hand, some authors like Marchioro and Pulvirenti [20], Osada [23], Goodman [11] and [17] took the initial positions as independent identically distributed random variables $X_i(0)$ with common density $\rho_0(x)$. Specifically, Goodman proved a rate of convergence for the incompressible Navier-Stokes equation in two dimensions of the order $N^{-1/4} \ln N$, where $N$ is the number of vortices used in the computation. However, this Monte Carlo sampling method is very inefficient in the computation. On the other hand, Chorin’s original method assumed that initial positions of the vortices are on the lattice points $hi \in \mathbb{R}^2$ with mass $\rho_0(hi)h^2$. In particular, Long [19] achieved an almost optimal rate of convergence of the order $N^{-1/2} \ln N \sim h|\ln h|$ except an event of probability $h^{C'C}C'$; much of his technique will be adapted to this article. A similar probabilistic approach has been used on the Vlasov-Poisson system by [5]. Finally, we refer to the book [7] for theoretical and practical use of the vortex methods, and also refer to [8] for recent progress on a blob method for the aggregation equation.

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In this paper, we introduce a random particle blob method for the following classical Keller-Segel (KS) equation [14] in $\mathbb{R}^d$ ($d \geq 2$):

\begin{align}
\begin{cases}
\partial_t \rho = \nu \Delta \rho - \nabla \cdot (\rho \nabla c), & x \in \mathbb{R}^d, \ t > 0, \\
- \Delta c = \rho(t, x), \\
\rho(0, x) = \rho_0(x),
\end{cases}
\end{align}

(1.1)

where $\nu$ is a positive constant. This model is developed to describe the biological phenomenon chemotaxis. In the context of biological aggregation, $\rho(t, x)$ represents the bacteria density, and $c(t, x)$ represents the chemical substance concentration, which is given by a fundamental solution as follows:

\begin{align}
c(t, x) = \begin{cases}
C_d \int_{\mathbb{R}^d} \frac{\rho(t, y)}{|x - y|^{d-2}} \, dy, & \text{if } d \geq 3, \\
- \frac{1}{2\pi} \int_{\mathbb{R}^d} \ln |x - y| \rho(t, y) \, dy, & \text{if } d = 2,
\end{cases}
\end{align}

(1.2)

where $C_d = \frac{1}{d(d-2)\alpha_d}$ and $\alpha_d = \frac{\pi^{d/2}}{\Gamma(d/2 + 1)}$, i.e., $\alpha_d$ is the volume of the $d$-dimensional unit ball. We can recast $c(t, x)$ as $c(t, x) = \Phi \ast \rho(t, x)$ with Newton potential $\Phi(x)$, which can be represented as

\begin{align}
\Phi(x) = \begin{cases}
C_d \frac{|x|^{d-2}}{|x|^{d-2}}, & \text{if } d \geq 3, \\
- \frac{1}{2\pi} \ln |x|, & \text{if } d = 2.
\end{cases}
\end{align}

(1.3)

Furthermore, we take the gradient of the Newtonian potential $\Phi(x)$ as the attractive force $F(x)$. Thus, we have $F(x) = \nabla \Phi(x) = - C_\ast \frac{x}{|x|^d}$, $\forall \ x \in \mathbb{R}^d \setminus \{0\}$, $d \geq 2$, where $C_\ast = \frac{\Gamma(d/2)}{2\pi^{d/2}}$.

Now we consider the KS equation (1.1) under the following assumption.

**Assumption 1.** The initial density $\rho_0(x)$ satisfies:

1. $\rho_0(x)$ has a compact support $D$ with $D \subseteq B(R_0)$;
2. $0 \leq \rho_0 \in H^k(\mathbb{R}^d)$ for $k \geq \frac{3d}{2} + 1$.

In fact, the above assumption is sufficient for the existence of the unique local solution to (1.1) with the following regularity:

\begin{align}
\|\rho\|_{L^\infty(0, T; H^k(\mathbb{R}^d))} \leq C(\|\rho_0\|_{H^k(\mathbb{R}^d)}),
\end{align}

(1.4)

\begin{align}
\|\partial_t \rho\|_{L^\infty(0, T; H^{k-2}(\mathbb{R}^d))} \leq C(\|\rho_0\|_{H^k(\mathbb{R}^d)}),
\end{align}

(1.5)

where $T > 0$ only depends on $\|\rho_0\|_{H^k(\mathbb{R}^d)}$. The proof of this result is a standard process and it will be given in Appendix A. Denote $T_{\text{max}}$ to be the largest existence time, such that (1.4) and (1.5) are valid for any $0 < T < T_{\text{max}}$. As a direct result of the Sobolev imbedding theorem, one has $\rho(t, x) \in C^{k-d/2-1}(\mathbb{R}^d)$ for any $t \in [0, T]$. We define the drift term

\begin{align}
G(t, x) := \int_{\mathbb{R}^d} F(x - y) \rho(t, y) \, dy,
\end{align}

(1.6)
then \(-\Delta G(t, x) = \nabla \rho(t, x)\). By using the Sobolev imbedding theorem, one has

\[
\|G\|_{L^\infty(0, T; W^{k-\frac{d}{2}, \infty}(\mathbb{R}^d))} \leq C\|G\|_{L^\infty(0, T; H^{k+1}(\mathbb{R}^d))} \leq C(\|\rho_0\|_{H^k(\mathbb{R}^d)}),
\]

and

\[
\|\partial_t G\|_{L^\infty(0, T; W^{k-\frac{d}{2}-2, \infty}(\mathbb{R}^d))} \leq C(\|\rho_0\|_{H^k(\mathbb{R}^d)}).
\]

So \(G(t, x)\) is bounded and Lipschitz continuous with respect to \(x\) for \(k \geq d/2 + 1\) from (1.17) and the Sobolev imbedding theorem. Thus, the stochastic differential equation (SDE)

\[
X(t) = X(0) + \int_0^t \int_{\mathbb{R}^d} F(X(s) - y) \rho(s, y) dy ds + \sqrt{2\nu} B(t)
\]

has a unique strong solution \(X(t)\) by a basic theorem of SDE [22, Theorem 5.2.1], where \(X(0) = \alpha \in D\) and \(B(t)\) is a standard Brownian motion.

If we denote the fundamental solution of the PDE

\[
\begin{align*}
\left\{ u_t &= \nu \Delta u - \nabla \cdot (uG), \\
u(0, x) &= \delta_\alpha(x), \quad \alpha \in D,
\end{align*}
\]

(1.10)

to be \(g(t, x \leftarrow 0, \alpha)\), then it is the transition probability density of the diffusion process \(X(t)\), i.e., \(g(t, x \leftarrow 0, \alpha)\) is the density that a particle reached the position \(x\) at time \(t\) from position \(\alpha\) at time \(0\), and we have

\[
\rho(t, x) = \int_{\mathbb{R}^d} g(t, x \leftarrow 0, \alpha) \rho_0(\alpha) d\alpha.
\]

See Friedman [10, Theorem 5.4 on p. 149].

We take \(h\) as the grid size and decompose the domain \(D\) into the union of non-overlapping cells \(C_i = X_i(0) + [-h/2, h/2]^d\) with center \(X_i(0) = hi =: \alpha_i \in D\), i.e., \(D \subset \bigcup_{i \in I} C_i\), where \(I = \{i\} \subset \mathbb{Z}^d\) is the index set for cells. The total number of cells is given by \(N = \sum_{i \in I} \approx \frac{|D|}{h^d}\).

Suppose \(X_i(t)\) is the strong solution to (1.9), i.e.,

\[
X_i(t) = X_i(0) + \int_0^t \int_{\mathbb{R}^d} F(X_i(s) - y) \rho(s, y) dy ds + \sqrt{2\nu} B_i(t), \quad i \in I,
\]

(1.12)

with the initial data \(X_i(0) = \alpha_i = hi\) where \(B_i(t)\) are independent standard Brownian motions.

For any test function \(\varphi \in C_0^\infty(\mathbb{R}^d)\) and \(t \in [0, T]\), we define

\[
u(s, \alpha) = \int_{\mathbb{R}^d} \varphi(x) g(t, x \leftarrow s, \alpha) dx, \quad s \in [0, t].
\]

Then \(u(s, \alpha)\) is the solution to the following backward Kolmogrov equation:

\[
\begin{align*}
\partial_s u &= -\nu \Delta u - G \cdot \nabla u, \quad \alpha \in \mathbb{R}^d, \quad s \in [0, t], \\
u(t, \alpha) &= \varphi(\alpha).
\end{align*}
\]

Following the standard regularity estimate, we have

\[
\|u(s, \cdot)\|_{H^{d+1}(\mathbb{R}^d)} \leq C_T \|\varphi\|_{H^{d+1}(\mathbb{R}^d)}, \quad s \in [0, t].
\]

Moreover, on one hand, we have

\begin{equation}
\langle \varphi, \rho \rangle = \int_{\mathbb{R}^d} \varphi(x) \rho(x) dx = \int_{\mathbb{R}^d} \varphi(x) \int_D \rho_0(\alpha) g(t, x \leftarrow 0, \alpha) d\alpha dx = \int_D u(0, \alpha) \rho_0(\alpha) d\alpha.
\end{equation}

On the other hand, we define the empirical measure \( \mu_N(t) := \sum_{j \in I} \delta(x- X_j(t)) \rho_0(\alpha_j) h^d \), and define \( \mathbb{E}[\mu_N(t)] \) in the sense of the Pettis integral \([25]\), i.e.,

\begin{equation}
\langle \varphi, \mathbb{E}[\mu_N(t)] \rangle = \mathbb{E}[\langle \varphi, \mu_N(t) \rangle] = \sum_{j \in I} \int_{\mathbb{R}^d} \varphi(x) g(t, x \leftarrow 0, \alpha_j) dx \rho_0(\alpha_j) h^d = \sum_{j \in I} u(0, \alpha_j) \rho_0(\alpha_j) h^d.
\end{equation}

Combining (1.16) and (1.17), and using (2.1) from Lemma 2.8 we conclude that

\begin{equation}
|\langle \varphi, \mathbb{E}[\mu_N(t)] - \rho \rangle| = \left| \sum_{j \in I} u(0, \alpha_j) \rho_0(\alpha_j) h^d - \int_D u(0, \alpha) \rho_0(\alpha) d\alpha \right| \\
\leq Ch^{d+1} \| u(0, \cdot) \rho_0 \|_{W^{d+1,1}(\mathbb{R}^d)} \\
\leq Ch^{d+1} \| u(0, \cdot) \|_{H^{d+1}(\mathbb{R}^d)} \leq Ch^{d+1} \| \varphi \|_{H^{d+1}(\mathbb{R}^d)}
\end{equation}

which leads to

\begin{equation}
\| \mathbb{E}[\mu_N(t)] - \rho \|_{H^{-(d+1)}(\mathbb{R}^d)} \leq Ch^{d+1}.
\end{equation}

Our above error estimate (1.19) is in the weak sense (see \([12]\) for the concept). Recently, the error estimate in the strong sense up to a small probability was obtained by \([18]\). Therefore, the main task of this article is to establish the error estimate between \( X_i(t) \) and \( X_{i,\varepsilon}(t) \). Here \( X_{i,\varepsilon}(t) \) is the solution to the random particle blob method which we will describe below.

Introducing a random particle blob method for the KS equation as in \([19]\), we have the following system of SDEs:

\begin{equation}
X_{i,\varepsilon}(t) = X_{i,\varepsilon}(0) + \int_0^t \sum_{j \in I} F_\varepsilon(X_{i,\varepsilon}(s) - X_{j,\varepsilon}(s)) \rho_j h^d ds + \sqrt{2\nu} B_i(t), \quad i \in I,
\end{equation}

with the initial data \( X_{i,\varepsilon}(0) = \alpha_i = hi \) where

\begin{equation}
\rho_j = \rho_0(\alpha_j), \quad F_\varepsilon = F \ast \psi_\varepsilon, \quad \psi_\varepsilon(x) = \varepsilon^{-d} \psi(\varepsilon^{-1} x), \quad \varepsilon > 0.
\end{equation}

The choice of the blob function \( \psi \) is closely related to the accuracy of our method. Following \([16]\), we choose \( \psi(x) \geq 0, \psi(x) \in C_0^{2d+2}(\mathbb{R}^d) \),

\begin{equation}
\psi(x) = \begin{cases} 
C(1 + \cos \pi |x|)^{d+2}, & \text{if } |x| \leq 1, \\
0, & \text{if } |x| > 1,
\end{cases}
\end{equation}

where \( C \) is a constant such that \( \int_{\mathbb{R}^d} \psi(x) dx = 1 \).
For convenience, we will give the following notation for the drift term:

\[ G(t, x) := F * \rho = \int_{\mathbb{R}^d} F(x - y) \rho(t, y) dy, \]

(1.23)

\[ G^h_\varepsilon(t, x) := \sum_{j \in I} F_\varepsilon(x - X_j(t)) \rho_j h^d, \]

(1.24)

\[ \hat{G}^h_\varepsilon(t, x) := \sum_{j \in I} F_\varepsilon(x - X_{j, \varepsilon}(t)) \rho_j h^d. \]

(1.25)

Define the discrete \( \ell^p_h \) norm of a vector \( v = (v_i)_{i \in I} \) such that

\[ \|v\|_{\ell^p_h} = \|(v_i)_{i \in I}\|_{\ell^p_h} = \left(\sum_{i \in I} |v_i|^p h^d\right)^{1/p}, \quad p > 1. \]

(1.26)

Then we have the following main theorem.

**Theorem 1.1.** Suppose the initial density \( \rho_0(x) \) satisfies Assumption 1. Let \( T_{\max} \) be the largest existence time of the regular solution (1.4), (1.5) to KS equation (1.1). Assume that \( X_h(t) = (X_i(t))_{i \in I} \) is the exact path of (1.12) and \( X_{h, \varepsilon}(t) = (X_{i, \varepsilon}(t))_{i \in I} \) is the solution to the random particle blob method (1.20). We take \( \varepsilon = h^\kappa \) with any \( \frac{1}{2} < \kappa < 1 \) and \( p > \frac{d}{1-\kappa} \), then for all \( 0 < h \leq h_0 \) with \( h_0 \) sufficiently small, there exist two positive constants \( C \) and \( C' \) depending on \( T_{\max}, p, d, R_0 \) and \( \|\rho_0\|_{H^k(\mathbb{R}^d)} \), such that the estimate

\[ P\left( \max_{0 \leq t \leq T} \|X_{h, \varepsilon}(t) - X_h(t)\|_{\ell^p_h} < \Lambda h |\ln h| \right) \geq 1 - h^{CA|\ln h|} \]

holds for any \( \Lambda > C' \) and \( 0 < T < T_{\max} \).

**Remark 1.1.** For the Coulomb interaction case \( F = -\nabla \Phi(x) \), the above estimate holds for any \( T > 0 \), since the regular solution \( \rho \) exists globally.

To conclude this introduction, we present the outline of the paper. In Section 2, we give some essential lemmas including kernel, sampling, concentration and far field estimates. In Section 3, we give a proof of the consistency error at the fixed time \( t \in [0, T] \). Then we give a stability theorem in Section 4. Next, by using results from Sections 3 and 4, we conclude the proof of the convergence of the particle path in Section 5. In Appendix A, we give a sketch proof of the regularity \( \rho \in L^\infty(0, T; H^k(\mathbb{R}^d)) \). Finally, we extend our result to the particle system with regular force in Appendix B.

2. **Preliminaries on kernel, sampling, concentration and far field estimates**

**Notation.** The inessential constants will be denoted generically by \( C \), even if it is different from line to line.

First, we summarize some useful estimates about the kernel \( F_\varepsilon \) in (1.21) and its derivatives.
Lemma 2.1 (Pointwise estimates).

(i) \( F_\varepsilon(0) = 0 \) and \( F_\varepsilon(x) = F(x)h(\frac{|x|}{\varepsilon}) \) for any \( x \neq 0 \), where

\[
h(r) = \frac{2\pi^{d/2}}{\Gamma(d/2)} \int_0^r \psi(s)s^{d-1}ds;
\]

(ii) \( F_\varepsilon(x) = F(x) \) for any \( |x| \geq \varepsilon \) and \( F_\varepsilon(x) \leq \min\{C\frac{|x|}{\varepsilon^d}, |F(x)|\} \);

(iii) \( |\partial^\beta F_\varepsilon(x)| \leq C\varepsilon^{1-d-|\beta|}, \) for any \( x \in \mathbb{R}^d \);

(iv) \( |\partial^\beta F_\varepsilon(x)| \leq C\varepsilon|x|^{1-d-|\beta|}, \) for any \( |x| \geq \varepsilon \).

The estimates (i) and (ii) have been proved in [16, Lemma 2.1]. For (iii) and (iv), we can follow the argument of [2, Lemma 5.1] by making dimensional changes and using the definition of \( F_\varepsilon(x) \) in our this paper.

Lemma 2.2 (Integral estimates).

(i) \( \int_{|x| \leq R} |F_\varepsilon(x)|dx \leq CR, \forall \varepsilon < 1 \);

(ii) \( \|F_\varepsilon\|_{W^{1,q}(\mathbb{R}^d)} \leq C\varepsilon^{d/q+1-d-|\beta|}, \) for \( q > 1 \).

Lemma 2.2 is a direct result from Lemma 2.1.

Also, we will need the following sampling lemma, which is essential to our error estimate.

Lemma 2.3 ([1, Lemma 2.2]). Suppose that \( f \in W^{d+1,1}(\mathbb{R}^d) \), then

\[
(2.1) \quad \left| \sum_{i \in \mathbb{Z}^d} f(hi)h^d - \int_{\mathbb{R}^d} f(x)dx \right| \leq C_d h^{d+1} f \|W^{d+1,1}(\mathbb{R}^d).
\]

The proof of this lemma is based on the Poisson summation formula, which was given by Anderson and Greengard [1].

Since the initial positions \( X_i(0) \) are chosen on the lattice points instead of being chosen randomly, the following lemma is essential to our analysis.

Lemma 2.4. Let \( X(t, \alpha) \) be the solution of the following SDE under Assumption 1:

\[
X(t; \alpha) = X(0; \alpha) + \int_0^t G(s, X(s; \alpha))ds + \sqrt{2}\nu B_\alpha(t),
\]

with initial data \( X(0; \alpha) = \alpha \in D \) and \( B_\alpha(t) \) is the standard Brownian motion. Assume \( \{X_i(t)\} \) are solutions of the SDEs

\[
X_i(t) = X_i(0) + \int_0^t G(s, X_i(s))ds + \sqrt{2}\nu B_i(t), \quad i \in I,
\]

with initial data \( X_i(0) = \alpha_i = hi \in D \) and \( \{B_i(t)\} \) are independent standard Brownian motions. For functions \( f \in W^{d+1,q}(\mathbb{R}^d, \mathbb{R}^d) \) and \( \Gamma \in W_0^{d+1,q'}(\mathbb{R}^d, \mathbb{R}^d) \) with \( \text{supp} \ \Gamma = D \) and \( 1/q + 1/q' = 1 \), we have the following estimate for the quadrature error:

\[
(2.2) \quad \max_{0 \leq t \leq T} \left| \sum_{i \in I} \mathbb{E}[f(X_i(t))] \Gamma(\alpha_i)h^d - \int_D \mathbb{E}[f(X(t; \alpha))] \Gamma(\alpha)d\alpha \right| \\
\leq Ch^{d+1} \|f\|_{W^{d+1,q}(\mathbb{R}^d, \mathbb{R}^d)},
\]

where \( C \) depends only on \( d, \ d', \ T, \|\rho_0\|_{H^k(\mathbb{R}^d)} \) and \( \|\Gamma\|_{W_0^{d+1,q'}(\mathbb{R}^d, \mathbb{R}^d)} \).
Proof. To prove this lemma, for any $t \in [0, T]$, we define
\begin{equation}
\tag{2.3}
 u(s, y) = \int_{\mathbb{R}^d} f(x)g(t, x \leftarrow s, y)dx, \quad s \in [0, t].
\end{equation}
Then, one has
\begin{equation}
\tag{2.4}
 u(t, y) = f(y); \quad u(0, y) = \int_{\mathbb{R}^d} f(x)g(t, x \leftarrow 0, y)dx = \mathbb{E}[f(X(t; y))].
\end{equation}
Thus, $u(s, y)$ is the solution to the following backward Kolmogrov equation
\begin{equation}
\tag{2.5}
\begin{cases}
 \partial_s u = -\nu \Delta u - G \cdot \nabla u, & y \in \mathbb{R}^d, \quad s \in [0, t], \\
 u(t, y) = f(y).
\end{cases}
\end{equation}
Following the standard regularity estimate, we have
\begin{equation}
\tag{2.6}
 \|u(s, \cdot)\|_{W^{d+1, q}(\mathbb{R}^d)} \leq C \|f\|_{W^{d+1, q}(\mathbb{R}^d; \mathbb{R}^d)}, \quad s \in [0, t],
\end{equation}
where $C$ depends only on $d$, $d'$, $T$ and $\|G\|_{L^\infty(0, T; W^{d+1, s}(\mathbb{R}^d))}$.
Notice that $\Gamma(\alpha)$ has support $D$, and we can use Lemma 2.3 which leads to
\begin{equation}
\tag{2.7}
\begin{aligned}
 & \left| \sum_{\alpha_i} u(0, \alpha) \Gamma(\alpha) h^d - \int_D u(0, \alpha) \Gamma(\alpha) d\alpha \right| \\
 \leq & C h^{d+1} \|u(0, \alpha) \Gamma(\alpha)\|_{W^{d+1, 1}(\mathbb{R}^d)} \leq C h^{d+1} \|u(0, \alpha)\|_{W^{d+1, q}(\mathbb{R}^d)} \\
 \leq & C h^{d+1} \|f\|_{W^{d+1, q}(\mathbb{R}^d; \mathbb{R}^d)},
\end{aligned}
\end{equation}
where $C$ depends only on $d$, $d'$, $T$, $\|\rho_0\|_{H^k(\mathbb{R}^d)}$ and $\|\Gamma\|_{W^{d+1, q'}(\mathbb{R}^d; \mathbb{R}^d)}$.
Substitute $u(0, \alpha) = \mathbb{E}[f(X(t; \alpha))]$ in (2.7); then one has
\begin{equation}
\tag{2.8}
\begin{aligned}
 & \max_{0 \leq t \leq T} \left| \sum_{\alpha_i} \mathbb{E}[f(X(t; \alpha_i))] \Gamma(\alpha) h^d - \int_D \mathbb{E}[f(X(t; \alpha))] \Gamma(\alpha) d\alpha \right| \\
 \leq & C h^{d+1} \|f\|_{W^{d+1, q}(\mathbb{R}^d; \mathbb{R}^d)},
\end{aligned}
\end{equation}
where $C$ depends only on $d$, $d'$, $T$, $\|\rho_0\|_{H^k(\mathbb{R}^d)}$ and $\|\Gamma\|_{W^{d+1, q'}(\mathbb{R}^d; \mathbb{R}^d)}$. Since $X_i(t)$ and $X(t; \alpha_i)$ have the same distribution, we have
\begin{equation}
\tag{2.9}
\mathbb{E}[f(X_i(t))] = \mathbb{E}[f(X(t; \alpha_i))],
\end{equation}
which leads to our lemma. \hfill \Box

Next, we introduce the following concentration inequality, which is a reformation of the well-known Bennett’s inequality; it plays a very important role in the sequel analysis.

**Lemma 2.5.** Let $\{Y_i\}_{i=1}^n$ be $n$ independent bounded $d$-dimensional random vectors satisfying:
\begin{enumerate}[(i)]
\item $\mathbb{E}[Y_i] = 0$ and $|Y_i| \leq M$ for all $i = 1, \cdots, n$;
\item $\sum_{i=1}^n \text{Var}(Y_i) \leq V$ with $\text{Var}(Y_i) = \mathbb{E}[|Y_i|^2]$.
\end{enumerate}
If $M \leq C \frac{\sqrt{V}}{\eta}$ with some positive constant $C$, then we have

\begin{equation}
P \left( \left| \sum_{i=1}^{n} Y_i \right| \geq \eta \sqrt{V} \right) \leq \exp \left( -C' \eta^2 \right),
\end{equation}

for all $\eta > 0$, where $C'$ only depends on $C$ and $d$.

**Proof.** See Pollard [24, Appendix B] for a proof of Bennet’s inequality in case $d = 1$, which leads to

\begin{equation}
P \left( \left| \sum_{i=1}^{n} Y_i \right| \geq \eta \sqrt{V} \right) \leq 2 \exp \left[ -\frac{1}{2} B(M \eta V^{-\frac{1}{2}}) \right],
\end{equation}

where $B(\lambda) = 2 \lambda^{-2}[(1 + \lambda) \ln(1 + \lambda) - \lambda]$, $\lambda > 0$, $\lim_{\lambda \to 0^+} B(\lambda) = 1$, $\lim_{\lambda \to +\infty} B(\lambda) = 0$ and $B(\lambda)$ is decreasing in $(0, +\infty)$.

Since $M \leq C \frac{\sqrt{V}}{\eta}$ and $B(\lambda)$ is decreasing, one concludes that

\begin{equation}
P \left( \left| \sum_{i=1}^{n} Y_i \right| \geq \eta \sqrt{V} \right) \leq 2 \exp \left[ -\frac{1}{2} B(C) \eta^2 \right].
\end{equation}

Denote $S = \sum_{i=1}^{n} Y_i$; then for $d$-dimensional random vector $Y_i$, we have

\begin{equation}
P \left( |S| \geq \eta \sqrt{V} \right) \leq \sum_{j} P(|S_j| \geq \eta \sqrt{\frac{V}{d}}) \leq 2d \exp \left[ -\frac{1}{2d} B(C) \eta^2 \right] \leq \exp \left[ -C' \eta^2 \right],
\end{equation}

where $C'$ only depends on $C$ and $d$. \[\square\]

**Lemma 2.6.** For $i, j \in I$, let $M_{ij}^\ell = \max_{|y| \leq C_0} \max_{|\beta| = 1} |\partial^\beta \mathcal{F}_t(X_i(t) - X_j(t) + y)|$ with some positive constant $C_0$. We take $\varepsilon \geq h |\ln h|^{\frac{1}{2}}$, then there exist two positive constants $C, C_1$ depending on $T, d$ and $\|\rho_0\|_{L^\infty(\mathbb{R}^d)}$, such that

\begin{equation}
\begin{cases}
P \left( \sum_{j \in I} M_{ij}^\ell h^d \geq \Lambda |\ln \varepsilon| \right) \leq h^{C\Lambda |\ln h|}, & \text{for any } i \in I, \text{ if } \ell = 1, \\
P \left( \sum_{j \in I} M_{ij}^\ell h^d \geq \Lambda e^{-1} \right) \leq h^{C\Lambda |\ln h|}, & \text{for any } i \in I, \text{ if } \ell = 2,
\end{cases}
\end{equation}

hold true at any fixed time $t$ for any $\Lambda > C_1$.

This lemma can be obtained using the same approach as in [19, Lemma 9].

**Lemma 2.7** ([19, Lemma 10]). Assume $B(t)$ is a standard Brownian motion in $\mathbb{R}^d$. Then

\[ P \left( \max_{t \leq s \leq t + \Delta t} |B(s) - B(t)| \geq b \right) \leq C(\sqrt{\Delta t}/b) \exp(-C' b^2/\Delta t), \]

where $b > 0$ and the positive constants $C, C'$ depend only on $d$. 


Proof. We give the proof of $d = 1$; then the case $d \geq 2$ can be obtained easily. See Freedman [9, p. 18], then one has
\begin{equation}
P\left\{ \max_{1 \leq s \leq t + \Delta t} |B(s) - B(t)| \geq b \right\} \leq 2P\{ |B(\Delta t)| \geq b \} = 4P\{ |B(1)| \geq b/\sqrt{\Delta t} \}.
\end{equation}
Since $B(1) \sim N(0, 1)$, a simple computation leads to our lemma.

Finally, we introduce the following far field estimate:

**Lemma 2.8.** Assume that $X_i(t)$ is the exact solution to (1.12), for $R$ bigger than the diameter of $D$. Then we have
\begin{equation}
P(|X_i(t)| \geq R) \leq \frac{C}{R^2},
\end{equation}
where $C$ depends on $d$, $T$, $R_0$ and $\|\rho\|_{H^k(\mathbb{R}^d)}$.

**Proof.** Recall that $g(t, x \leftarrow 0, \alpha)$ is the solution to the following equation:
\begin{equation}
\begin{cases}
    u_t = \nu \Delta u - \nabla \cdot (uG), \\
    u(0, x) = \delta_\alpha(x), \quad \alpha \in D.
\end{cases}
\end{equation}
We denote the second moment estimate of $u$ as $m_2(t) = \int_{\mathbb{R}^d} |x|^2 u(t, x) dx$, then one has
\begin{equation}
\frac{d m_2(t)}{dt} = 2d + 2 \int_{\mathbb{R}^d} (x \cdot G) u dx
\end{equation}
\begin{align*}
&= 2d + 2C_s \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \frac{x \cdot (x - y)}{|x - y|^d} \rho(y) u(x) dy dx \\
&\leq 2d + 2C_s \int_{\mathbb{R}^d} |x| u(x) \left[ \int_{|x-y| \leq 1} \frac{\rho(y)}{|x - y|^{d-1}} dy + \int_{|x-y| > 1} \frac{\rho(y)}{|x - y|^{d-1}} dy \right] dx \\
&\leq 2d + C(\|\rho\|_{L^1}, \|\rho\|_{L^\infty}) (\|u\|_{L^1} + m_2(t)), \quad t \in (0, T].
\end{align*}

By using Gronwall’s inequality, we have
\begin{equation}
m_2(t) \leq e^{C_1 T} (m_2(0) + C_2 T), \quad t \in (0, T].
\end{equation}
Notice that $m_2(0) = \int_{\mathbb{R}^d} |x|^2 \delta_\alpha(x) dx \leq CR_0^2$, which leads to
\begin{equation}
m_2(t) \leq C_1 R_0^2 + C_2, \quad t \in [0, T],
\end{equation}
where $D$ satisfies $D \subseteq B(R_0)$ and $C_1$, $C_2$ depend on $d$, $T$, $\|\rho\|_1$, $\|\rho\|_\infty$. Now, we compute $P(|X_i(t)| \geq R)$, and one has
\begin{equation}
P(|X_i(t)| \geq R) = \int_{|x| \geq R} g(t, x \leftarrow 0, \alpha_i) dx \leq \frac{m_2(t)}{R^2}.
\end{equation}
Thus, we conclude the proof.

\begin{flushright}
\Box
\end{flushright}

3. Consistency error at the fixed time

In this section, we will achieve the following consistency estimate result at any fixed time. Recall the definition of $G(t, x)$, $G^\varepsilon(t, x)$ in (1.23) and (1.24), then we have the result as below.
Theorem 3.1. Assume that $X_i(t)$ is the exact path of $\{\xi_t\}$. Under the same assumption as in Theorem 1.1, there exist two constants $C, C' > 0$ depending only on $T, d, R_0$ and $\|\rho_0\|_{H^k(\mathbb{R}^d)}$, such that at any fixed time $t \in [0, T]$, we have

\[
P \left( \max_{i \in I} |G_{\varepsilon i}^h(t, X_i(t)) - G(t, X_i(t))| < \Lambda h \ln h \right) \geq 1 - \varepsilon C^{|\ln h|},
\]

for all $\varepsilon > C'$. 

Proof. For any fixed $x$ and $t$, we decompose the consistency error into the sampling error, the discretization error and the moment error as follows:

\[
|G_{\varepsilon i}^h(t, x) - G(t, x)| = \left| \sum_{j \in I} F_\varepsilon(x - X_j(t))\rho_j h^d - \int_{\mathbb{R}^d} F(x - y)\rho(t, y)dy \right|
\]

\[
\leq \left| \sum_{j \in I} F_\varepsilon(x - X_j(t))\rho_j h^d - \sum_{j \in I} \mathbb{E}[F_\varepsilon(x - X_j(t))]\rho_j h^d \right|
\]

\[
+ \left| \sum_{j \in I} \mathbb{E}[F_\varepsilon(x - X_j(t))]\rho_j h^d - \int_{\mathbb{R}^d} F_\varepsilon(x - y)\rho(t, y)dy \right|
\]

\[
+ \int_{\mathbb{R}^d} F_\varepsilon(x - y)\rho(t, y)dy - \int_{\mathbb{R}^d} F(x - y)\rho(t, y)dy \right| =: e_s(t, x) + e_d(t, x) + e_m(t, x).
\]

Step 1. For the moment error, it can be proved that

\[
e_m(t, x) \leq C_1\varepsilon^2.
\]

Indeed, if we rewrite $e_m(t, x) = \left| \int_{\mathbb{R}^d} [F_\varepsilon(y) - F(y)]\rho(t, x - y)dy \right|$, and from (i) in Lemma 2.1 then one has

\[
e_m(t, x) = \left| \int_{\mathbb{R}^d} [h(\frac{|y|}{\varepsilon}) - 1]F(y)\rho(t, x - y)dy \right|
\]

\[
= \varepsilon \left| \int_{\mathbb{R}^d} [h(|z|) - 1]F(z)\rho(t, x - \varepsilon z)dz \right|
\]

\[
= \varepsilon \left| \int_{\mathbb{R}^d} [h(|z|) - 1]F(z)[\rho(t, x - \varepsilon z) - \rho(t, x)]dz \right|
\]

\[
\leq C\varepsilon^2\|
abla \rho\|_{L^\infty} \int_0^1 r^2|1 - h(r)|dr \leq C_1\varepsilon^2,
\]

where $C_1$ depends only on $d, \|\rho_0\|_{H^k(\mathbb{R}^d)}$.

Step 2. For the discretization error $e_d(t, x)$, we notice that

\[
\int_{\mathbb{R}^d} F_\varepsilon(x - y)\rho(t, y)dy = \int_{\mathbb{R}^d} F_\varepsilon(x - y) \left( \int_{D} g(t, y; 0, \alpha)\rho_0(\alpha)d\alpha \right)dy
\]

\[
= \int_{D} \left[ \int_{\mathbb{R}^d} F_\varepsilon(x - y)g(t, y; 0, \alpha)d\alpha \right]\rho_0(\alpha)d\alpha
\]

\[
= \int_{D} \mathbb{E}[F_\varepsilon(x - X(t; \alpha))]\rho_0(\alpha)d\alpha.
\]
By applying Lemma 2.4 with \( f(y) = F_\varepsilon(x-y), \Gamma(\alpha) = \rho_0(\alpha) \), we obtain

\[
(3.6) \quad \sum_{j \in I} \mathbb{E}[F_\varepsilon(x - X_j(t))] \rho_j h^d - \int_D \mathbb{E}[F_\varepsilon(x - X(t; \alpha))] \rho_0(\alpha)d\alpha \leq Ch^{d+1}\|F_\varepsilon\|_{W^{d+1,q}(\mathbb{R}^d)} \leq C_2 h^{d+1}\varepsilon^{d/q-2d}.
\]

It follows from (3.5) and (3.6) that

\[
(3.7) \quad e_d(t, x) = \sum_{j \in I} \mathbb{E}[F_\varepsilon(x - X_j(t))] \rho_j h^d - \int_{\mathbb{R}^d} F_\varepsilon(x - y) \rho(t, y)dy \leq C_2 h^{d+1}\varepsilon^{d/q-2d},
\]

where \( C_2 \) only depends on \( T, d \) and \( \|\rho_0\|_{H^s(\mathbb{R}^d)} \).

**Step 3.** For the sampling error \( e_s(t, x) \), we will use Lemma 2.5 to give an estimate of \( e_s(t, x) = \left| \sum_{j \in I} Y_j \right| \), where

\[
(3.8) \quad Y_j = (F_\varepsilon(x - X_j(t)) - \mathbb{E}[F_\varepsilon(x - X_j(t))]) \rho_j h^d.
\]

It is obvious that

\[
(3.9) \quad \mathbb{E}[Y_j] = 0 \text{ and } |Y_j| \leq Ch^{d-1-d} =: M, \quad \text{for all } j \in I.
\]

Next, we will show that \( \sum_{j \in I} \text{Var} Y_j \) is uniformly bounded by some \( V \). Actually,

\[
(3.10) \quad \sum_{j \in I} \text{Var} Y_j = \sum_{j \in I} \left\{ \mathbb{E}[\|F_\varepsilon(x - X_j(t))\|^2] - |\mathbb{E}[F_\varepsilon(x - X_j(t))]|^2 \right\} \rho_j^2 h^{2d} \leq \sum_{j \in I} \mathbb{E}[\|F_\varepsilon(x - X_j(t))\|^2] \rho_j^2 h^{2d}.
\]

We apply Lemma 2.4 again with \( f(y) = |F_\varepsilon(x-y)|^2 = C|\partial^{d-1}F_\varepsilon(x-y)|, \Gamma(\alpha) = \rho_0(\alpha)^2 \). Then one has

\[
(3.11) \quad \sum_{j \in I} \mathbb{E}[\|F_\varepsilon(x - X_j(t))\|^2] \rho_j^2 h^{2d} - h^d \int_D \mathbb{E}[\|F_\varepsilon(x - X(t; \alpha))\|^2] \rho_0(\alpha)^2 d\alpha \leq Ch^d\|F_\varepsilon\|_{W^{2d,q}(\mathbb{R}^d)} h^{d+1} \leq Ch^{d+1}\varepsilon^{d/q-3d+1} h^d,
\]

which follows from Lemma 2.2 as we have done in (3.7).

Notice that

\[
(3.12) \quad \int_D \mathbb{E}[\|F_\varepsilon(x - X(t; \alpha))\|^2] \rho_0(\alpha)^2 d\alpha \\
= \int_D \int_{\mathbb{R}^d} |F_\varepsilon(x-y)|^2 g(t, y \leftarrow 0, \alpha) \rho_0(\alpha)^2 dyd\alpha \\
= \int_{\mathbb{R}^d} |F_\varepsilon(x-y)|^2 \left\{ \int_D g(t, y \leftarrow 0, \alpha) \rho_0(\alpha)^2 d\alpha \right\} dy,
\]

where \( g(t, y \leftarrow 0, \alpha) \) is the Green’s function. Notice also that

\[ u(t, x) := \int_D g(t, x \leftarrow 0, \alpha) \rho_0(\alpha)^2 d\alpha \]
is the solution of the following equation:

\[
\begin{aligned}
\partial_t u & = \nu \Delta u - \nabla \cdot (u \nabla c), \quad x \in \mathbb{R}^d, \ t > 0, \\
- \Delta c & = u(t, x), \\
u(0, x) & = \rho_0^2(x).
\end{aligned}
\]

(3.13)

So the $L^\infty$ norm of $u$ are bounded by $\|\rho_0\|_{H^k}$. Therefore, using Lemma 2.2 one has that (3.12) is bounded by

\[
C \int_{\mathbb{R}^d} |F_\varepsilon(x - y)|^2 dy = C\|F_\varepsilon\|^2_2 \leq C\varepsilon^{2-d}.
\]

(3.14)

Collecting (3.10), (3.11) and (3.14), we have

\[
\sum_j \operatorname{Var} Y_j \leq Ch^{d+1}\varepsilon^{d/q - d} + Ch^d\varepsilon^{2-d}
\]

(3.15)

\[
\leq Ch^d + \frac{\varepsilon^{2-d}}{2\varepsilon^{d-1}} =: V \quad (\text{by } \varepsilon = h^{\frac{q}{2q-d}}),
\]

where the constant $C$ depends only on $T, d$ and $\|\rho_0\|_{H^k(\mathbb{R}^d)}$.

For any $C_3 > 0$, we let $\eta = C_3|\ln h|$ in Lemma 2.5. In order to use Lemma 2.5 we need to verify that $M \leq C\frac{\sqrt{\nu}}{\eta}$, which leads to

\[
\frac{3q(2q-1)(q-1)}{2q^2} (|\ln h|)^{\frac{1}{q-1}} \leq \varepsilon.
\]

(3.16)

Since we choose $\varepsilon = h^{\frac{q}{2q-d}}$ with $q > 1$, (3.10) can be verified when $h$ is sufficiently small. Hence, it follows from the concentration inequality (2.10) that

\[
P\left( e_s(t, x) \geq C_3|\ln h| \sqrt{V} \right) \leq \exp[-C'C_3^2|\ln h|^2] \leq C''C_3|\ln h|,
\]

(3.17)

for some $C'' > 0$ depending only on $T, d$ and $\|\rho_0\|_{H^k(\mathbb{R}^d)}$.

Step 4. We take $\varepsilon = h^{\frac{q}{2q-d}}$ with any $q > 1$ and $h$ sufficiently small. Then

\[
C_1\varepsilon^2 + C_2h^{d+1}\varepsilon^{d/q - 2d} + C_3|\ln h| \sqrt{V} < C_4|\ln h|,
\]

(3.18)

where $C_4$ is bigger than a positive constant depending only on $T, d$ and $\|\rho_0\|_{H^k(\mathbb{R}^d)}$.

In summary, at any fixed $x$ and $t$, we have

\[
P(|G^h_\varepsilon(t, x) - G(t, x)| \geq 3C_4h|\ln h|)
\leq P(e_m(t, x) + e_d(t, x) + e_s(t, x) \geq 3C_4h|\ln h|)
\leq P(e_m(t, x) \geq C_4h|\ln h|) \cdot P(e_d(t, x) \geq C_4h|\ln h|) \cdot P(e_s(t, x) \geq C_4h|\ln h|)
\leq 0 + 0 + P(e_s(t, x) \geq C_4h|\ln h|) \leq h^{C''C_4|\ln h|},
\]

with some $C'' > 0$.

Step 5. For the lattice points $z_k = hk$ in ball $B(R)$ with $R = h^{-\gamma|\ln h|}$ ($\gamma$ will be determined later), it follows from inequality (3.19) that

\[
P\left( \max_k |G^h_\varepsilon(t, z_k) - G(t, z_k)| \geq 3C_4h|\ln h| \right)
\leq \sum_k P(|G^h_\varepsilon(t, z_k) - G(t, z_k)| \geq 3C_4h|\ln h|)
\leq C''''h^{-(1+\gamma|\ln h|)d} h^{C''''C_4|\ln h|} = C''''h^{-d+(C''''C_4-\gamma)d|\ln h|},
\]

(3.20)
which leads to
\[(3.21) \quad P \left( \max_{k} |G_{\epsilon}^{h}(t, z_{k}) - G(t, z_{k})| \geq C_{4}^{\prime} h | \ln h | \right) \leq h^{CC_{5}^{\prime} | \ln h |},\]
with some constant \( C > 0 \) provided that \( C^{\prime\prime} h - \gamma d > 0 \).

**Step 6.** For any fixed \( t \), denote the event \( U := \{ X_{i}(t) \in B(R) \} \). Then we know from Lemma 2.8 that \( P(U^{c}) \leq \frac{C}{h^{2q}} = Ch^{2(\gamma - 1) | \ln h |} \). Now, we do the estimate under event \( U \), and suppose \( z_{i} \) is the closest lattice point to \( X_{i}(t) \) with \( |X_{i}(t) - z_{i}| \leq h \).

We compute
\[(3.22) \quad |G_{\epsilon}^{h}(t, X_{i}(t)) - G(t, X_{i}(t))| \leq |G_{\epsilon}^{h}(t, X_{i}(t)) - G_{\epsilon}^{h}(t, z_{i})| + |G_{\epsilon}^{h}(t, z_{i}) - G(t, z_{i})| + |G(t, z_{i}) - G(t, X_{i}(t))| =: I_{1} + I_{2} + I_{3}.\]

Then \( P(I_{2} \geq C_{4}^{\prime} h | \ln h |) \leq h^{CC_{4}^{\prime} | \ln h |} \) follows from (3.21).

For \( I_{1} \), we have
\[(3.23) \quad I_{1} = \left| \sum_{j \in I} F_{\epsilon}(X_{i}(t) - X_{j}(t)) \rho_{j} h^{d} - \sum_{j \in I} F_{\epsilon}(z_{i} - X_{j}(t)) \rho_{j} h^{d} \right| = \left| \sum_{j \in I} \nabla F_{\epsilon}(X_{i}(t) - X_{j}(t) + \xi) \rho_{j} h^{d} \right| |X_{i}(t) - z_{i}| \leq C \sum_{j \in I} M_{ij}^{1} h^{d} h,\]
by applying the mean-value theorem. We take \( \epsilon = h^{\frac{1}{2q-1}} \) with any \( q > 1 \) and \( h \) sufficiently small; this ensures \( \epsilon \geq h | \ln h |^{\frac{1}{2}} \). Apply Lemma 2.6 for any \( C_{5} > CC_{2} \), one has
\[(3.24) \quad P(I_{1} \geq C_{5} h | \ln \epsilon |) \leq P \left( \sum_{j \in I} M_{ij}^{1} h^{d} \geq \frac{C_{5}}{C} | \ln \epsilon | \right) \leq h^{CC_{5}^{\prime} | \ln h |},\]
which leads to
\[(3.25) \quad P(I_{1} \geq C_{5} h | \ln h |) \leq h^{CC_{5}^{\prime} | \ln h |} \quad (\text{by } h \leq \epsilon),\]
with some \( C > 0 \).

For \( I_{3} \), since \( G(t, x) \) is smooth enough, one has
\[(3.26) \quad I_{3} = |\nabla G(t, z_{i} + \xi)\| z_{i} - X_{i}(t) \| \leq C_{6} h \leq C_{6} h | \ln h |,\]
by using the mean-value theorem.

Take \( C_{7} > \max\{C_{4}^{\prime}, C_{5}, C_{6}\} \), and collect the estimates of \( I_{1}, I_{2} \) and \( I_{3} \). Then one has
\[(3.27) \quad P \left( \max_{i \in I} \left| G_{\epsilon}^{h}(t, X_{i}(t)) - G(t, X_{i}(t)) \right| \geq 3C_{7} h | \ln h | \right) \leq NP(I_{1} + I_{2} + I_{3} \geq 3C_{7} h | \ln h |) \leq N h^{CC_{5}^{\prime} | \ln h |} + N h^{CC_{7} | \ln h |} + 0 \leq h^{CC_{7} | \ln h |},\]
with some \( C > 0 \) and \( C_{7} \) bigger than a positive constant depending only on \( T, d \) and \( \|\rho_{0}\|_{H^{\epsilon}(\mathbb{R}^{d})} \).

Until now, we have only proved that
\[(3.28) \quad P \left( \left\{ \max_{i \in I} \left| G_{\epsilon}^{h}(t, X_{i}(t)) - G(t, X_{i}(t)) \right| \geq C_{7} h | \ln h | \right\} \cap U \right) \leq h^{CC_{7}^{\prime} | \ln h |},\]
Hence, we have

\[
P\left( \max_{i \in I} \left| G_h(t, X_i(t)) - G(t, X_i(t)) \right| \geq C' h |\ln h| \right) 
\leq h^{C' \gamma |\ln h|} + P(U^c) \leq h^{C' \gamma |\ln h|} + Ch^{2 \gamma |\ln h|} \leq h^{C' \gamma |\ln h|}.
\]

Finally, we conclude the proof of this theorem by using \( P(A^c) = 1 - P(A) \). □

4. Stability estimate

In this section, we will focus on giving a proof of the stability estimate, which can be expressed as follows.

**Theorem 4.1 (Stability).** Under the same assumption as in Theorem 1.1. Denote the event

\[
B := \left\{ \max_{0 \leq t \leq T} \max_{i \in I} |X_i,\varepsilon(t) - X_i(t)| \leq \varepsilon \right\}.
\]

Then there exist two positive constants \( C, C' \) depending only on \( T, p, d, R_0 \) and \( \|\rho_0\|_{H^k(\mathbb{R}^d)} \), such that for any \( \Lambda > C' \), if we denote the event

\[
A := \left\{ \|\hat{G}_h^\varepsilon(t, X_{h,\varepsilon}(t)) - G_h^\varepsilon(t, X_h(t))\|_{\ell_p^h} < \Lambda \|X_{h,\varepsilon}(t) - X_h(t)\|_{\ell_p^h}, \forall t \in [0, T] \right\},
\]

the following stability estimate holds:

\[
P( A \cap B ) \geq 1 - h^{C' \gamma |\ln h|},
\]

where \( G_h^\varepsilon, \hat{G}_h^\varepsilon \) are defined in (1.24) and (1.25).

**Proof.** In order to prove (4.3), we divide \([0, T]\) into \( N'\) subintervals with length \( \Delta t = h^r \) for some \( r > 2 \) and \( t_n = nh^r, n = 0, \ldots, N' \). If we denote the events

\[
A_n := \left\{ \|\hat{G}_h^\varepsilon(t, X_{h,\varepsilon}(t)) - G_h^\varepsilon(t, X_h(t))\|_{\ell_p^h} \geq \Lambda \|X_{h,\varepsilon}(t) - X_h(t)\|_{\ell_p^h}, \exists t \in [t_n, t_{n+1}] \right\},
\]

\[
\tilde{A} := \left\{ \|\hat{G}_h^\varepsilon(t, X_{h,\varepsilon}(t)) - G_h^\varepsilon(t, X_h(t))\|_{\ell_p^h} \geq \Lambda \|X_{h,\varepsilon}(t) - X_h(t)\|_{\ell_p^h}, \exists t \in [0, T] \right\},
\]

then one has

\[
P(\tilde{A}) = P\left( \bigcup_{n=0}^{N'-1} A_n \right).
\]

So our main idea of this proof is to give the estimate of \( P(A_n) \) first.

Directly, we apply Lemma 2.7 and get

\[
P\left( \max_{n} \max_{t_n \leq t \leq t_{n+1}} |X_i(t) - X_i(t_n)| \geq Ch^r + \sqrt{2\nu h} \right)
\leq C' h^{r/2-1} \exp(-C'' h^{2-r}) \to 0,
\]
which leads to

\[
(4.8) \quad P \left( \max_n \max_{t_n \leq t \leq t_{n+1}} |X_i(t) - X_i(t_n)| \geq \varepsilon \right) \leq C'h^{r/2-1} \exp(-C''h^{2-r}) \to 0,
\]

provided that

\[
(4.9) \quad Ch^r + \sqrt{2}vh \leq \varepsilon.
\]

Again, (4.9) can be verified by our choice of \( \varepsilon = h^{2q-1} \) with \( h \) sufficiently small. Actually, (4.8) ensures that the position \( X_i(t) \) for \( t \in [t_n, t_{n+1}] \) is close to \( X_i(t_n) \).

For \( t \in [t_n, t_{n+1}] \), recalling the definition of drift term (1.24) and (1.25), we write

\[
(4.10) \quad \hat{G}^h_{\varepsilon}(t, X_{i,\varepsilon}(t)) - G^h_{\varepsilon}(t, X_i(t))
\]

\[=
\sum_{j \in I} \left[ F_\varepsilon(X_{i,\varepsilon}(t) - X_{j,\varepsilon}(t)) - F_\varepsilon(X_i(t) - X_j(t)) \right] \rho_j h^d
\]

\[=
\sum_{j \in I} \nabla F_\varepsilon(X_i(t_n) - X_j(t_n) + \xi_{ij}) \cdot (X_{i,\varepsilon}(t) - X_i(t) + X_j(t) - X_{j,\varepsilon}(t)) \rho_j h^d
\]

\[=
\sum_{j \in I} \nabla F_\varepsilon(X_i(t_n) - X_j(t_n) + \xi_{ij}) \cdot (X_{i,\varepsilon}(t) - X_i(t)) \rho_j h^d
\]

\[+ \sum_{j \in I} \nabla F_\varepsilon(X_i(t_n) - X_j(t_n) + \xi_{ij}) \cdot (X_j(t) - X_{j,\varepsilon}(t)) \rho_j h^d
\]

\[=: I_i + J_i,
\]

where the term \( \xi_{ij} \) is from the mean-value theorem, which may depend on the components \( X_{i,\varepsilon}(t), X_{j,\varepsilon}(t), X_i(t), X_j(t), X_i(t_n), X_j(t_n) \). Furthermore, from (4.8), one has

\[
(4.11) \quad P(\{|\xi_{ij}| < 4\varepsilon, \forall t \in [t_n, t_{n+1}]\} \cap \mathcal{B}) \geq 1 - C'h^{r/2-1} \exp(-C''h^{2-r}),
\]

We will give the estimates of \( I_i \) and \( J_i \) under the event \( A := \{\xi_{ij} : |\xi_{ij}| < 4\varepsilon, \forall t \in [t_n, t_{n+1}]\} \cap \mathcal{B} \) in the following steps 1–2.

**Step 1 (Estimate of \( I_i \)).** In order to do the estimate of \( I_i \), we first need to give the uniform bound of \( \sum_{j \in I} \nabla F_\varepsilon(X_i(t_n) - X_j(t_n) + \xi_{ij}) \rho_j h^d \). To do this, we are required to prove the uniform bound of \( \sum_{j \in I} \nabla F_\varepsilon(X_i(t_n) - X_j(t_n)) \rho_j h^d \).

We may write

\[
\sum_{j \in I} \nabla F_\varepsilon(x - X_j(t_n)) \rho_j h^d = \sum_j \mathbb{E}[\nabla F_\varepsilon(x - X_j(t_n))] \rho_j h^d
\]

\[+ \sum_{j \in I} [\nabla F_\varepsilon(x - X_j(t_n)) - \mathbb{E}[\nabla F_\varepsilon(x - X_j(t_n))] \rho_j h^d
\]

\[=: I_1 + I_2.
\]
For $I_1$, it can be estimated by Lemma 2.3 with $f(y) = ∇F_ε(x - y)$, $Γ(α) = ρ_0(α)$ as we have done before:

\begin{equation}
I_1 - \int_{\mathbb{R}^d} E[∇F_ε(x - X(t_n; α))] |ρ_0(α)| dα
\leq h^{d+1}∥F_ε∥_{W^{d+2, q}(\mathbb{R}^d)} \leq C h^{d+1}ε^{d/q - 2d - 1} \leq C \quad \text{(by } ε = h^{2/q - 1}),
\end{equation}

where $C$ depends on $T$, $d$, $∥ρ_0∥_{H^k(\mathbb{R}^d)}$. On the other hand, we notice that

\begin{equation}
\int_{\mathbb{R}^d} E[∇F_ε(x - X(t_n; α))] |ρ_0(α)| dα
= \int_{\mathbb{R}^d} F_ε(x - y) ∇ρ(t_n, y) dy
\leq ∥∇ρ∥_{L^∞} ∥F_ε∥_{L^1(B)} + ∥∇ρ∥_{L^1} ∥F_ε∥_{L^∞(\mathbb{R}^d/B)} \leq C,
\end{equation}

where $∥∇ρ∥_{L^1} \leq C(T, d, R_0, ∥ρ_0∥_{H^k(\mathbb{R}^d)})$ has been used and $B$ is the unit ball in $\mathbb{R}^d$. Actually, the proof of the estimate of $∥∇ρ∥_{L^1}$ can be done by using the standard semigroup method. We recall the heat semigroup operator $e^{tΔ}$ defined by

\begin{equation}
e^{tΔ}ρ := H(t, x) * ρ,
\end{equation}

where $H(t, x) = \frac{1}{(4πt)^{d/2}} e^{-|x|^2/4t}$ is the heat kernel. Then the solution to the KS equation (1.1) can be represented as

\begin{equation}
ρ = e^{tΔ}ρ_0 + \int_0^t e^{(t-s)Δ}(-∇ \cdot (ρ∇c)) ds.
\end{equation}

A simple computation leads to

\begin{equation}
∥∇ρ∥_{L^1} \leq C∥∇ρ_0∥_{L^1} + C(T)∥∇ · (ρ∇c)∥_{L^∞(0, T; L^1(\mathbb{R}^d))}.
\end{equation}

Furthermore, one has

\begin{equation}
∥∇ · (ρ∇c)∥_{L^1} = ∥∇ρ · ∇c - ρ^2∥_{L^1} \leq ∥∇ρ∥_{L^2}∥∇c∥_{L^2} + ∥ρ∥_{L^2}^2
\leq C(d)∥∇ρ∥_{L^2}∥ρ∥_{L^{2d/2}} + ∥ρ∥_{L^2}^2 \leq C(d, ∥ρ_0∥_{H^k}).
\end{equation}

Thus, we have $∥∇ρ∥_{L^1} \leq C(T, d, R_0, ∥ρ_0∥_{H^k(\mathbb{R}^d)})$. Combining (4.12) and (4.13), one concludes that

\begin{equation}
|I_1| \leq C_1(T, d, R_0, ∥ρ_0∥_{H^k(\mathbb{R}^d)}).
\end{equation}

To estimate $I_2$, let $I_2 = \sum_{j \in J} Y_j$:

\begin{equation}
Y_j = [∇F_ε(x - X_j(t_n))] - E[∇F_ε(x - X_j(t_n))] |ρ_j h^d.
\end{equation}

We have $E[Y_j] = 0$, $|Y_j| \leq C h^d ε^{-d} \leq C |ln h|^{-2} := M$ provided that

\begin{equation}
h |ln h|^{-\frac{q}{2}} \leq ε.
\end{equation}

Indeed, (4.20) can be verified since we choose $ε = h^{2/q - 1}$ with $1 < q$ and sufficiently small $h$.

Furthermore,

\begin{equation}
\sum_{j \in J} Var Y_j \leq \sum_{j \in J} E \left[ ∥∇F_ε(x - X_j(t_n))∥^2 \right] |ρ_j|^2 h^{2d}.
\end{equation}
We once again apply Lemma 2.4 with $f(y) = |\nabla F_\varepsilon(x - y)|^2 = C|\partial^{d+1} F_\varepsilon(x - y)|$, $\Gamma(\alpha) = \rho_0(\alpha)^2$:

\begin{equation}
(4.22) \quad \left| \sum_{j \in I} \mathbb{E} \left[ |\nabla F_\varepsilon(x - X_j(t_n))|^2 \right] \rho_j^2 h^{2d} - h^d \int_{\mathbb{R}^d} \mathbb{E} \left[ |\nabla F_\varepsilon(x - X(t_n; \alpha))|^2 \right] \rho_0(\alpha)^2 d\alpha \right| \leq C h^d h^{d+1} \varepsilon^{d/q-3d-1} \leq C |\ln h|^{-2} \quad \text{(by } \varepsilon = h^{2q^{-1}}),
\end{equation}

where the constant $C$ depends only on $T$, $d$ and $\|\rho_0\|_{H^k(\mathbb{R}^d)}$.

On the other hand, as we have done in (3.12) and (3.14), we have

\begin{equation}
(4.23) \quad \left| h^d \int_{\mathbb{R}^d} \mathbb{E} \left[ |\nabla F_\varepsilon(x - X(t_n; \alpha))|^2 \right] \rho_0(\alpha)^2 d\alpha \right| \leq C h^d \varepsilon^{-d} \leq C |\ln h|^{-2}.
\end{equation}

Hence, one has $\sum_j \text{Var} Y_j \leq C |\ln h|^{-2} =: V$.

For any $C_2 > 0$, we choose $\eta = C_2 |\ln h|$ in Lemma 2.5. It is easy to check that

\begin{equation}
(4.24) \quad M = C |\ln h|^{-2} \leq C \frac{\sqrt{V}}{\eta}.
\end{equation}

Thus, we can use Lemma 2.5 now, for any $C_2 > 0$:

\begin{equation}
(4.25) \quad P \left(|I_2| \geq C_2 |\ln h| \sqrt{C} |\ln h|^{-1} \right) = P \left(|I_2| \geq C_2 \sqrt{C} \right) \leq \exp \left\{ -C' C_2^2 |\ln h|^2 \right\} \leq h^{C'' C_2 |\ln h|}.
\end{equation}

We take $C_3 > C_1 + C_2 \sqrt{C}$; thus we have

\begin{equation}
(4.26) \quad P \left( \left| \sum_{j \in I} \nabla F_\varepsilon(x - X_j(t_n)) \rho_j h^d \right| \geq 2 C_3 \right) \leq P \left(|I_1| + |I_2| \geq 2 C_3 \right) \leq h^{C''' C_3 |\ln h|},
\end{equation}

with some $C''' > 0$. Hence, at the fixed time $t_n$,

\begin{equation}
\left| \sum_{j \in I} \nabla F_\varepsilon(x_i(t_n) - X_j(t_n)) \rho_j h^d \right| < C'_3,
\end{equation}

except for an event of probability less than $h^{C'_3 |\ln h|}$ with $C'_3$ bigger than a positive constant depending only on $T$, $d$, $R_0$ and $\|\rho_0\|_{H^k(\mathbb{R}^d)}$.

Notice that

\begin{equation}
(4.27) \quad \left| \sum_{j \in I} \left[ \nabla F_\varepsilon(x_i(t_n) - X_j(t_n) + \xi_{ij}) - \nabla F_\varepsilon(x_i(t_n) - X_j(t_n)) \right] \rho_j h^d \right| \leq \varepsilon^{C''''} \sum_{j \in I} M_{ij}^2 h^d.
\end{equation}
So one has

\[
\begin{align*}
(4.28) \quad & P \left( \left| \sum_{j \in I} \nabla F_\epsilon(X_i(t_n) - X_j(t_n) + \xi_{ij}) \rho_j h^d \right| \geq 2C'_3 \right) \\
\leq & P \left( \left| \sum_{j \in I} \nabla F_\epsilon(X_i(t_n) - X_j(t_n)) \rho_j h^d \right| + \varepsilon C''' \sum_{j \in I} M_{ij}^3 h^d \geq 2C'_3 \right) \\
\leq & P \left( \left| \sum_{j \in I} \nabla F_\epsilon(X_i(t_n) - X_j(t_n)) \rho_j h^d \right| \geq C'_3 \right) + P \left( \varepsilon C''' \sum_{j \in I} M_{ij}^3 h^d \geq C'_3 \right) \\
\leq & C_{CC'} |\ln h|,
\end{align*}
\]

where Lemma 2.6 has been used in the last inequality since we can choose \( C'_3 > C'''C'_3 \).

Recall \( I_i = \sum_{j \in I} \nabla F_\epsilon(X_i(t_n) - X_j(t_n) + \xi_{ij}) \cdot (X_i, \varepsilon(t) - X_i(t)) \rho_j h^d \); hence it follows from \((4.28)\) that

\[
(4.29) \quad P \left( \| (I_i)_{i \in I} \|_{\ell^p_h} \geq C''_3 \| X_h, \varepsilon(t) - X_h(t) \|_{\ell^p_h}, \exists \ t \in [t_n, t_{n+1}] \right) \leq h^{-C''_3 |\ln h|},
\]

with some \( C > 0 \) and \( C''_3 \) bigger than a positive constant depending only on \( T, d, R_0 \) and \( \| \rho_0 \|_{H^k(\mathbb{R}^d)} \).

**Step 2** (Estimate of \( J_i \)). At the fixed time \( t_n \), let \( Z_i \in \varepsilon \cdot Z^d \) be the closest lattice point to \( X_i(t_n) \). If there is more than one lattice point closest to \( X_i(t_n) \), then we choose an arbitrary one. We write

\[
J_i = \sum_{j \in I} \nabla F_\epsilon(Z_i - Z_j) \cdot e_j \rho_j h^d \\
\quad + \sum_{j \in I} \left[ \nabla F_\epsilon(X_i(t_n) - X_j(t_n) + \xi_{ij}) - \nabla F_\epsilon(Z_i - Z_j) \right] \cdot e_j \rho_j h^d \\
=: J_{1i} + J_{2i},
\]

where \( e_j = X_j(t) - X_j, \varepsilon(t) \). For each \( z_k = \varepsilon k, k \in \mathbb{Z}^d \), we define \( f_k \) to be the average of all \( e_j \rho_j h^d \) where \( X_j(t_n) \) is in the square \( Q_k = z_k + \left[ -\frac{\varepsilon}{2}, \frac{\varepsilon}{2} \right]^d \). Namely,

\[
f_k = \varepsilon^{-d} \sum_{X_j(t_n) \in Q_k} e_j \rho_j h^d,
\]

with convention of \( f_k = 0 \) if \( Q_k \) contains none of the \( X_j(t_n) \). Then one has

\[
(4.32) \quad \| (f_k)_{k \in \mathbb{Z}^d} \|_{\ell^p_h} \leq C_p \| (e_j \rho_j)_{j \in I} \|_{\ell^p_h},
\]

\[
(4.33) \quad P \left( \| (J_{1i})_{i \in I} \|_{\ell^p_h} \geq C_4 \| \sum_k \nabla F_\epsilon(z_{k'} - z_k) \cdot f_k e^d_{k'} \|_{\ell^p_h}, \exists \ t \in [t_n, t_{n+1}] \right) \leq h^{-C_4 |\ln h|},
\]

for some \( C > 0 \) and \( C_4 \) is bigger than a positive constant depending on \( T, p, d \) and \( \| \rho_0 \|_{H^k(\mathbb{R}^d)} \). The derivation of these two results can be achieved by the argument
in [19, p. 797]. In addition, it follows from Beale [3, pp. 47-48] that
\begin{equation}
(4.34) \quad \|\sum_k \nabla F_\varepsilon(z_{k'} - z_k) \cdot f_k \varepsilon^d)_{k' \in \mathbb{Z}^d} \|_{L^p_t} \leq C \|f_k\|_{\mathbb{Z}^d} \|e^p_t\|
\end{equation}
which implies
\begin{equation}
(4.35) \quad P\left(\|\mathcal{J}_{i_{t}}\|_{L^p_t} \geq C_4 \|e_j \rho_j\|_{L^p_t} \|e^p_t\|, \exists t \in [t_n, t_{n+1}] \right) \leq h^{CC_4|\ln h|},
\end{equation}
For \(\mathcal{J}_{2i}\), we use the mean-value theorem again,
\begin{equation}
(4.36) \quad \mathcal{J}_{2i} = \sum_{j \in I} \|\nabla^2 F_\varepsilon(X_i(t_n) - X_j(t_n) + \xi_{ij} + \xi'_{ij}) \cdot e_j \rho_j h^d,\]
where \(\xi''_{ij} = \xi_{ij} + (X_i(t_n) - Z_i) - (X_j(t_n) - Z_j)\). Since \(|\xi_{ij}| \leq \varepsilon, |\xi'_{ij}| \leq |\xi''_{ij}| \leq 3\varepsilon, then one has
\begin{equation}
(4.37) \quad |\mathcal{J}_{2i}| \leq \sum_{j \in I} 3M_j^2 \rho_j |h|^d.
\end{equation}
Applying the discrete version of Young’s inequality, we conclude that
\begin{equation}
(4.38) \quad \|\mathcal{J}_{2i}\|_{L^p_t} \leq 3\varepsilon \sum_{j \in I} M_j^2 h^d \|e_j \rho_j\|_{L^p_t} \|e^p_t\|.
\end{equation}
By Lemma [2.6] with \(C_0 = 4\), one has
\begin{equation}
(4.39) \quad P\left(\|\mathcal{J}_{i_{t}}\|_{L^p_t} \geq C_5 \|e_j \rho_j\|_{L^p_t} \|e^p_t\|, \exists t \in [t_n, t_{n+1}] \right) \leq h^{CC_5|\ln h|},
\end{equation}
with any \(C_5 > 3C_2\).
Recall (4.35) and (4.38), then we have
\begin{equation}
(4.40) \quad P\left(\|\mathcal{J}_{i_{t}}\|_{L^p_t} \geq 2C_6 \|e_j \rho_j\|_{L^p_t} \|e^p_t\|, \exists t \in [t_n, t_{n+1}] \right) \leq h^{CC_6|\ln h|},
\end{equation}
for any \(C_6 > C_4 + C_5\).
Step 3. Collecting the estimate of \(\mathcal{J}_i\) (4.29), the estimate of \(\mathcal{J}_i\) (4.40) and the definition of event \(A_n\) (4.4), one concludes that
\begin{equation}
(4.41) \quad P\left(A_n \cap A\right) \leq h^{CA|\ln h|}, \quad n = 0, \ldots, N' - 1,
\end{equation}
for some \(C > 0\) and \(\Lambda\) bigger than a positive constant depending on \(T, p, d, R_0\) and \(\|\rho_0\|_{H^k(\mathbb{R}^d)}\). Since (4.3) and (4.41), we have
\begin{equation}
(4.42) \quad P\left(A \cap A\right) = P\left(\bigcup_{n=0}^{N'-1} (A_n \cap A)\right) \leq N'h^{CA|\ln h|} = C'h^{r-1}h^{CA|\ln h|} \leq h^{CA|\ln h|},
\end{equation}
for some \(C > 0\). Finally, we have
\begin{equation}
(4.43) \quad P\left(A\right) \leq P\left(A \cap A\right) + P(A^c) \leq h^{CA|\ln h|} + C'h^{r/2-1} \exp(-C''h^{2-r}) \leq h^{CA|\ln h|},
\end{equation}
for some \(C > 0\) and \(\Lambda\) bigger than a positive constant depending on \(T, p, d, R_0\) and \(\|\rho_0\|_{H^k(\mathbb{R}^d)}\). Now, the proof of the stability theorem can be completed, since \(P\left(A^c\right) = 1 - P\left(A\right)\).
5. The Convergence Analysis and the Proof of Theorem 1.1

In order to prove the convergence of particle paths, we need to extend the consistency error to all time. It can be obtained by combining the consistency estimates for a finite number of times \(0 = t_0 < t_1 < \cdots < t_{N'} = T\) where \(\Delta t = h^r\) with \(r > 2\). We denote the following events:

\[
\begin{align*}
A_1^n & : \left\{ \max_{i \in I} \left| G^h_\varepsilon(t_n, X_i(t_n)) - G(t_n, X_i(t_n)) \right| < \Lambda_1 h | \ln h | \right\}, \\
A_2 & : \left\{ \max_{i \in I} \max_{t_n \leq t \leq t_{n+1}} \left| X_i(t) - X_i(t_n) \right| < C(h^r + \nu^{1/2} h) \right\}, \\
A_3 & : \left\{ \left\| G^h_\varepsilon(t, X_{h, \varepsilon}(t)) - G^h(t, X_h(t)) \right\|_{\ell^p_h} < \Lambda_3 \| X_{h, \varepsilon}(t) - X_h(t) \|_{\ell^p_h}, \forall t \in [0, T] \right\},
\end{align*}
\]

with \(\Lambda_1, \Lambda_3\) bigger than a constant depending only on \(T, p, d, R_0\) and \(\| \rho_0 \|_{H^k(\mathbb{R}^d)}\).

For all \(t \in [t_n, t_{n+1}]\), under the event \(A_1^n \cap A_2\), we obtain

\[
\begin{align*}
\left| X_i(t) - X_i(t_n) \right| & \leq C(h^r + \nu^{1/2} h) \quad \text{and the fact that } G(t, x) \text{ has bounded derivatives. Therefore}, \\
\max_{0 \leq t \leq T'} \frac{d}{dt} \left| G^h_\varepsilon(t, X_{h, \varepsilon}(t)) - G(t, X_h(t)) \right|_{\ell^p_h} & < (C + \Lambda_1) h | \ln h |,
\end{align*}
\]

under the event \(\bigcap_{n=0}^{N'} A_1^n \cap A_2\).

The convergence can be proved by the same argument as in [2,3]. Denote \(e_i(t) = X_{i, \varepsilon}(t) - X_i(t)\) and vector \(e(t) = (e_i)_{i \in I} = X_{h, \varepsilon}(t) - X_h(t)\). One has

\[
\frac{de_i}{dt} = \hat{G}^h_\varepsilon(t, X_{i, \varepsilon}(t)) - G(t, X_i(t))
\]

and the differential inequality

\[
\left\| \frac{de}{dt} \right\|_{\ell^p_h} \leq \left\| \hat{G}^h_\varepsilon(t, X_{h, \varepsilon}(t)) - G^h(t, X_h(t)) \right\|_{\ell^p_h} + \left\| G^h_\varepsilon(t, X_h(t)) - G(t, X_h(t)) \right\|_{\ell^p_h} < \Lambda_3 \| e(t) \|_{\ell^p_h} + (C + \Lambda_1) h | \ln h |,
\]

under the event \(\bigcap_{n=0}^{N'} A_1^n \cap A_2 \cap A_3\) by the stability Theorem 4.1 and the consistency estimate (5.3). It follows from (5.6) and the fact \(\frac{d}{dt} \left\| e \right\|_{\ell^p_h} \leq \left\| \frac{de}{dt} \right\|_{\ell^p_h}\), by using Gronwall’s inequality with \(e(0) = 0\), that

\[
\max_{0 \leq t \leq T} \| e(t) \|_{\ell^p_h} < C(T, \Lambda_1, \Lambda_3) h | \ln h | = \Lambda h | \ln h |,
\]

under the event \(\bigcap_{n=0}^{N'} A_1^n \cap A_2 \cap A_3\). Here we denote \(\Lambda := C(T, \Lambda_1, \Lambda_3)\).
To complete the proof, we need to justify the stability condition: $|e_i(t)| \leq \varepsilon$ for all $i$ and $0 \leq t \leq T$ under the event \( \bigcap_{n=0}^{N'} A_1^n \cap A_2 \cap A_3 \). Since \( h^d \max_{i \in I} |e_i(t)|^p \leq \left( \|e(t)\|_{\ell_h}^p \right)^p \), one has

\[
\max_{i \in I} |e_i(t)| \leq h^{-d/p} \|e(t)\|_{\ell_h}^p < Ch^{1-d/p} |\ln h| < \frac{\varepsilon}{2}, \quad \text{for } 0 \leq t \leq T,
\]

by choosing \( p > \frac{d(2q-1)}{q-1} \), \( \varepsilon = h^{\frac{q}{2q-1}} \) with \( q > 1 \), and \( h \) small enough. Hence, \( \max_{i \in I} |e_i| \) can hardly reach \( \varepsilon \). Thus if we denote \( (5.8) \) as event \( \mathcal{B} \), one has \( P((A_3 \cap \mathcal{B})^c) \leq h^{CA_3 |\ln h|} \) according to (4.3) in Theorem 4.1. From the discussion above, we have

\[
P \left( \max_{0 \leq t \leq T} \|X_{h,e}(t) - X_h(t)\|_{L_h^2} \geq \Lambda h |\ln h| \right) \leq P \left( \left( \bigcap_{n=0}^{N'} A_1^n \cap A_2 \cap A_3 \cap \mathcal{B} \right)^c \right)
\]

\[
= P \left( \bigcup_{n=0}^{N'} \left( A_1^n \cap A_2 \cap A_3 \cap \mathcal{B} \right)^c \right) \leq \sum_{n=0}^{N'-1} P((A_1^n)^c) + P(A_2^c) + P((A_3 \cap \mathcal{B})^c)
\]

\[
\leq Ch^{-r} h^{CA_1 |\ln h|} + C' h^{r/2-1} \exp(-C'' h^{r-r}) + h^{CA_3 |\ln h|} \leq h^{CA |\ln h|},
\]

where we have used (3.1) in Theorem 3.1 and (4.8). Finally, we denote \( \kappa = \frac{q}{2q-1} \); then the proof has been completed.

**APPENDICES**

**APPENDIX A. PROOF OF \( \rho \in H^k(\mathbb{R}^d) \) WITH INITIAL DATA \( \rho_0 \in L^1 \cap H^k(\mathbb{R}^d) \).**

**Theorem A.1.** Assume that the initial data \( \rho_0 \) satisfies

\[
0 \leq \rho_0 \in L^1 \cap H^k(\mathbb{R}^d) \quad \text{with } k > \frac{d}{2}.
\]

Then the KS system (1.1) has a local solution with the regularity

\[
\|\rho\|_{L^\infty(0,T; H^k(\mathbb{R}^d))} \leq C(\|\rho_0\|_{L^1 \cap H^k(\mathbb{R}^d)}), \quad \|\rho\|_{L^2(0,T; H^{k+1}(\mathbb{R}^d))} \leq C(\|\rho_0\|_{L^1 \cap H^k(\mathbb{R}^d)}),
\]

where \( T > 0 \) only depends on \( \|\rho_0\|_{L^1 \cap H^k(\mathbb{R}^d)} \).

**Proof.** We give a sketch of the proof here. By the weak Young’s inequality [15, p. 107], one has

\[
\|\nabla \varepsilon\|_2 \leq C \|x|^{-(d-1)}\|_{\frac{d}{d-1},w} \|\rho\|_{\frac{2d}{d+2}} \leq C \|\rho\|_{\frac{2d}{d+2}}.
\]

To estimate \( \|\rho\|_{\frac{2d}{d+2}} \), we multiply (1.1) by \( d\rho^{d-1} \) and integrate over \( \mathbb{R}^d \), which leads to

\[
\frac{d}{dt} \|\rho\|_{\frac{d}{d+1}}^2 + \frac{4(d-1)}{d} \|\nabla \rho^d\|_2^2 \leq (d-1) \|\rho\|_{\frac{d+1}{d+2}}^{d+1}.
\]

Let us recall the Gagliardo-Nirenberg inequality [21, p. 176, (2.3.50)]:

\[
\|\rho\|_q \leq C \|\nabla \rho\|_p^\theta \|\rho\|_r^{1-\theta},
\]

\[
\|\rho\|_q \leq C \|\nabla \rho\|_p^\theta \|\rho\|_r^{1-\theta},
\]
where \(1 \leq p, r \leq \infty, 0 \leq \theta \leq 1\), and \(\frac{1}{q} = \theta\left(\frac{1}{p} - \frac{1}{d}\right) + \frac{1 - \theta}{r}\). We choose \(q = \frac{2(d+1)}{d}\) and \(p = r = 2\); then one has

\[
\|\rho\|_{d+1}^{d+1} = \|\rho\|_{2}^{\frac{2(d+1)}{2(d+1)}} \leq C\|\nabla \rho\|_{2}^{\frac{d}{2}}\|\rho\|_{2}^{\frac{d+2}{2}}.
\]

Hence, by using the Young’s inequality, we obtain

\[
\frac{d}{dt}\|\rho\|_{d}^{d} \leq C(\|\rho\|_{d}^{\frac{d}{d+2}}\|\rho\|_{d}^{\frac{d+2}{d}}).
\]

Solving the above ordinary differential inequality, we know there exists a \(T_1 > 0\) depending on \(\|\rho_0\|_{L^1 \cap H^k(\mathbb{R}^d)}\), such that

\[
\|\rho\|_{L^\infty(0,T;L^d(\mathbb{R}^d))} \leq C(\|\rho_0\|_{L^1 \cap H^k(\mathbb{R}^d)}).
\]

Furthermore, as shown in [4], we know the mass conservation holds true:

\[
\|\rho\|_{1} = \|\rho_0\|_{1}.
\]

Hence, by applying the interpolation inequality \((1 \leq \frac{2d}{d+2} < d)\), we know that

\[
\|\rho\|_{\frac{2d}{d+2}} \leq C(\|\rho_0\|_{L^1 \cap H^k(\mathbb{R}^d)}),
\]

which leads to

\[
\|\nabla c\|_{2} \leq C(\|\rho_0\|_{L^1 \cap H^k(\mathbb{R}^d)}),
\]

for \(0 < t \leq T_1\).

A simple computation of system (1.1) shows that, for \(0 \leq |s| \leq k\),

\[
\frac{d}{dt}\|D^s \rho\|_{2}^{2} + \frac{1}{2}\|D^s \nabla \rho\|_{2}^{2} \leq \frac{1}{2}\|D^s (\rho \nabla c)\|_{2}^{2}.
\]

Using the Leibniz formula and Sobolev imbedding theorem, one concludes that

\[
\|D^s (\rho \nabla c)\|_{2} \leq \|\rho\|_{\infty}\|\nabla c\|_{H^k} + \|\rho\|_{H^k}\|\nabla c\|_{\infty} \leq C\|\rho\|_{H^k}\|\nabla c\|_{H^k}.
\]

Recall the fact that

\[
\|\nabla c\|_{H^k} \leq \|\rho\|_{H^k} + \|\nabla c\|_{2} \leq \|\rho\|_{H^k} + C(\|\rho_0\|_{L^1 \cap H^k(\mathbb{R}^d)}),
\]

which leads to

\[
\frac{d}{dt}\|\rho\|_{H^k}^{2} + \frac{1}{2}\|\rho\|_{H^{k+1}}^{2} \leq C(\|\rho_0\|_{L^1 \cap H^k(\mathbb{R}^d)})(1 + \|\rho\|_{H^k}^{2}).
\]

Solving the above ordinary differential inequality, there exists \(0 < T \leq T_1\) depending on \(\|\rho_0\|_{L^1 \cap H^k(\mathbb{R}^d)}\), such that

\[
\|\rho\|_{L^\infty(0,T;H^k(\mathbb{R}^d))} \leq C(\|\rho_0\|_{L^1 \cap H^k(\mathbb{R}^d)})
\]

and

\[
\|\rho\|_{L^2(0,T;H^{k+1}(\mathbb{R}^d))} \leq C(\|\rho_0\|_{L^1 \cap H^k(\mathbb{R}^d)}),
\]

which concludes our proof. \(\square\)
APPENDIX B. EXTENSION TO GENERAL REGULAR ATTRACTIVE FORCE $F$

In this section, we will extend our result to the particle system with interacting function $F$ regular enough, which satisfies

\[(B.1)\quad F \in H^{d+1}(\mathbb{R}^d).\]

We consider the regular solution $\rho$ of the following PDE:

\[
\begin{cases}
\partial_t \rho = \nu \Delta \rho - \nabla \cdot (\rho F \ast \rho), & x \in \mathbb{R}^d, \ t > 0, \\
\rho(0, x) = \rho_0(x),
\end{cases}
\]

with $\rho_0$ has a compact support $D$ with $D \subseteq B(R_0)$ and $0 \leq \rho_0 \in H^k(\mathbb{R}^d)$ with $k \geq d + 1$. Then $\rho$ has the following regularity for any $T > 0$:

\[(B.3)\quad \|\rho\|_{L^\infty(0, T; H^{d+1}(\mathbb{R}^d))} \leq C (T, \|\rho_0\|_{H^{d+1}(\mathbb{R}^d)}, \|F\|_{H^{d+1}(\mathbb{R}^d)})\]

and

\[(B.4)\quad \|G\|_{L^\infty(0, T; W^{d+1, \infty}(\mathbb{R}^d))} = \|F \ast \rho\|_{L^\infty(0, T; W^{d+1, \infty}(\mathbb{R}^d))} \leq C (T, \|\rho_0\|_{H^{d+1}(\mathbb{R}^d)}, \|F\|_{H^{d+1}(\mathbb{R}^d)}).
\]

Again we suppose the self-consistent process $X_i(t)$ satisfying

\[(B.5)\quad X_i(t) = X_i(0) + \int_0^t \int_{\mathbb{R}^d} F(X_i(s) - y) \rho(s, y) dy ds + \sqrt{2\nu} B_i(t), \quad i \in I,
\]

with the initial data $X_i(0) = \alpha_i$.

Since $F$ is regular enough, there is no need to mollify the force $F$ anymore. To be specific, we consider trajectories $\{\hat{X}_i(t)\}_{i \in I}$ satisfying the SDEs:

\[(B.6)\quad \hat{X}_i(t) = \hat{X}_i(0) + \int_0^t \sum_{j \in I} F(\hat{X}_i(s) - \hat{X}_j(s)) \rho_j h^d ds + \sqrt{2\nu} B_i(t), \quad i \in I,
\]

with initial data $\hat{X}_i(0) = \alpha_i$, and we denote

\[(B.7)\quad G^h(t, x) := \sum_{j \in I} F(x - X_j(t)) \rho_j h^d,
\]

\[(B.8)\quad \hat{G}^h(t, x) := \sum_{j \in I} F(x - \hat{X}_j(t)) \rho_j h^d.
\]

The extended result can be described in the following theorem.

**Theorem B.1.** Suppose the initial density $\rho_0(x)$ has a compact support $D$ with $D \subseteq B(R_0)$ and $0 \leq \rho_0 \in H^k(\mathbb{R}^d)$ with $k \geq d + 1$. For the attractive force $F$ satisfying \[(B.1)\] $F$, $\rho$ is the global regular solution to \[(B.2)\]. Assume that $X_h(t) = (X_i(t))_{i \in I}$ is the exact path of \[(B.5)\] and $\hat{X}_h(t) = \left(\hat{X}_i(t)\right)_{i \in I}$ is the solution to the particle system \[(B.6)\]. There exist two positive constants $C$ and $C'$ depending on $T, p, d, R_0, \|F\|_{H^{d+1}(\mathbb{R}^d)}$ and $\|\rho_0\|_{H^k(\mathbb{R}^d)}$ such that the following estimate holds:

$$P \left( \max_{0 \leq t \leq T} \|\hat{X}_h(t) - X_h(t)\|_{C^1_h} < \Lambda h |\ln h| \right) \geq 1 - h^{C |\ln h|},$$

for any $\Lambda > C'$, $p \geq 1$ and $T > 0$.

The idea of the proof of Theorem \[(B.1)\] can be done as before, which is the consistency and stability implying convergence.

Like we have done in Section 3, the consistency can be proved.
Theorem B.2. Under the same assumption as Theorem B.1, there exist two constants $C, C' > 0$ depending only on $T, d, R_0, \|F\|_{H^{d+1}(\mathbb{R}^d)}$ and $\|\rho_0\|_{H^k(\mathbb{R}^d)}$ such that at any fixed time $t \in [0, T]$, we have

\begin{equation}
(B.9) \quad P \left( \max_{i \in I} |G^h(t, X_i(t)) - G(t, X_i(t))| < \Lambda h |\ln h| \right) \geq 1 - h^{C_A |\ln h|},
\end{equation}

for all $\Lambda > C'$, where $G = F \ast \rho$ and $G^h$ is defined in (B.7). 

Proof. The proof is almost the same as the proof of Theorem 3.1. In this case, we have

\begin{equation}
(B.10) \quad |G^h(t, x) - G(t, x)| \leq \sum_{j \in I} F(x - X_j(t)) \rho_j h^d - \sum_{j \in I} \mathbb{E}[F(x - X_j(t))] \rho_j h^d
\end{equation}

\begin{equation}
= \sum_{j \in I} \mathbb{E}[F(x - X_j(t))] \rho_j h^d - \int_{\mathbb{R}^d} F(x - y) \rho(t, y) dy
\end{equation}

\begin{equation}
=: e_s(t, x) + e_d(t, x),
\end{equation}

and one can prove that

\begin{equation}
(B.11) \quad e_d(t, x) \leq Ch^{d+1}; \quad P(e_s(t, x) \geq \Lambda h |\ln h|) \leq h^{C_A |\ln h|}.
\end{equation}

Then this theorem can be proved similarly. \qed

As we have done in Section 4, we have the following stability result.

Theorem B.3. Under the same assumption as Theorem B.1, there exist a constant $C > 0$ depending only on $T, p, d, R_0, \|F\|_{H^{d+1}(\mathbb{R}^d)}$ and $\|\rho_0\|_{H^k(\mathbb{R}^d)}$ such that

\begin{equation}
(B.12) \quad \|G^h(t, \hat{X}_h(t)) - G^h(t, X_h(t))\|_{L^p_{\rho_h}} \leq C \|\hat{X}_h(t) - X_h(t)\|_{L^p_{\rho_h} \ L^\infty} \forall t \in [0, T],
\end{equation}

where $G^h, \hat{G}^h$ are defined in (B.7) and (B.8).

Proof. Instead of using Lemma 2.6, we have that $M^1_{i, j} = |\nabla F(X_i(t) - X_j(t) + y)| \leq C$ for any $t \in [0, T]$, which leads to

\begin{equation}
(B.13) \quad \sum_{j \in I} M^1_{i, j} h^d \leq C, \forall t \in [0, T].
\end{equation}

In addition, one has

\begin{equation}
(B.14) \quad \hat{G}^h(t, \hat{X}_i(t)) - G^h(t, X_i(t))
\end{equation}

\begin{equation}
= \sum_{j \in I} \left[ F(\hat{X}_i(t) - \hat{X}_j(t)) - F(X_i(t) - X_j(t)) \right] \rho_j h^d
\end{equation}

\begin{equation}
= \sum_{j \in I} \nabla F(X_i(t) - X_j(t) + \xi_{ij}) \cdot (\hat{X}_i(t) - X_i(t) + X_j(t) - \hat{X}_j(t)) \rho_j h^d
\end{equation}

\begin{equation}
= \sum_{j \in I} \nabla F(X_i(t) - X_j(t) + \xi_{ij}) \cdot (\hat{X}_i(t) - X_i(t)) \rho_j h^d
\end{equation}

\begin{equation}
+ \sum_{j \in I} \nabla F(X_i(t) - X_j(t) + \xi_{ij}) \cdot (X_j(t) - \hat{X}_j(t)) \rho_j h^d
\end{equation}

\begin{equation}
=: I_i + J_i.
\end{equation}
Hence, we have

\[(B.15) \quad |I_i| \leq C|\hat{X}_i(t) - X_i(t)|; \quad |J_i| \leq \sum_{j \in I} M_{i,j}^1 |X_j(t) - \hat{X}_j(t)| \rho_j h^d,\]

which concludes the proof. \(\square\)

Finally, combining Theorem [B.2] and Theorem [B.3] we can get Theorem [B.1] as we have done in Section 5.

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