

# A THEOREM ON CONVEX CONES WITH APPLICATIONS TO LINEAR INEQUALITIES<sup>1</sup>

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1. **Introduction.** This note is concerned with the convex cone associated with the two systems of linear inequalities

$$(1) \quad \sum_{j=1}^n a_{ij}x_j \geq 0, \quad i = 1, 2, \dots, m,$$

and

$$(2) \quad \sum_{j=1}^n a_{ij}x_j \geq 0, \quad i = 1, 2, \dots, m,$$

where the symbol  $\geq$  demands that the inequality ( $>$ ) hold for at least one value of  $i$ . For brevity these systems will be written (1)  $Ax \geq 0$  and (2)  $Ax \geq 0$ .

Interpreting  $(a_{i1}, \dots, a_{in})$  as a vector  $a_i$  in  $E_n$ , with initial point at the origin, we denote by  $A$  the convex cone generated by these  $m$  vectors and by  $A^*$  the polar cone, the vectors of which give the solutions of (1).

The purpose of this paper is to show that in general  $A \cdot A^* \neq 0$  and to characterize the cases in which  $A$  and  $A^*$  do intersect in the null vector. Some applications are then made to obtain theorems on the existence of, and methods of obtaining, solutions of (1) and (2).

2. **The main theorem.** Before proving the main theorem, two remarks are appropriate. First, the writer has previously given an entirely different proof of a special case of the theorem, in which it was assumed that  $A$  is not contained in an  $E_{n-1}$ . The statement of this case may be found in [2].<sup>2</sup> It is clear that Theorem 2.1 follows immediately from this special case. In [6] a stronger version has been proved under the assumption that  $A$  does not contain a straight line. Second, it will be seen that the proof given here does not require that the cone  $A$  be generated by finitely many vectors, but the applications to be made require this.

At the suggestion of the referee, we state and prove the theorem in a more general setting than is needed for the applications. The proof

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given is substantially that of the referee. If  $E$  is an inner-product space and  $A$  a convex cone with vertex  $0$  in  $E$ ,  $A^*$  denotes the set of  $x \in E$  such that  $(x, a) \geq 0$  for all  $a \in A$ .

**THEOREM 2.1.** *If  $E$  is a complete inner-product space and  $A$  a convex cone of  $E$  with vertex  $0$ , then  $A \cdot A^* = 0$  if and only if  $A$  is a linear subspace of  $E$ .*

**PROOF.** If  $A$  is a linear subspace,  $A^*$  is its orthogonal complement. If  $A$  is not a linear subspace, there is an  $a \in A$  for which  $-a$  is not in  $A$ . If  $b$  is the nearest point of  $A$  to  $-a$ , let  $c = a + b$ . Then  $c \in A$ .

Now the hyperplane through  $b$ , orthogonal to  $c$ , is a supporting plane of  $A$ , for otherwise  $A$  would have an element closer than  $b$  to  $-a$ . In other words,  $(y, c) \geq (b, c)$ , for each  $y$  of  $A$ . In particular  $(2b, c) = 2(b, c) \geq (b, c)$  and  $(0, c) = 0 \geq (b, c)$ . Thus  $(b, c) = 0$  and  $b \in A^*$ , proving the theorem.

We might pause at this point to mention a method of obtaining solutions of (2). If the rows of the matrix  $A$  form a set  $A_0$ , we may adjoin the sum of each two, obtaining a set  $A_1$ , repeat the process, obtaining  $A_2$ , and so on, obtaining vectors arbitrarily close to a solution.

**3. Some existence theorems.** In this section the foregoing discussion is applied to obtain theorems on the existence of solutions for a system of linear inequalities. A vector  $y$  is called positive if  $y_i > 0$  for each  $i$ , non-negative if  $y_i \geq 0$  for each  $i$  and  $y_i > 0$  for some  $i$ .

**THEOREM 3.1.** *The system (2) has a solution if and only if  $A \cdot A^* \neq 0$ .*

The proof being immediate from Theorem 2.2, we state the same result algebraically.

**COROLLARY.** *If (2) has a solution, it has one of the form  $x = A'y$ , where  $y$  is non-negative and  $A'$  is the transpose of the matrix  $A$ .*

**THEOREM 3.2.** *In order that (2) have a solution, it is necessary and sufficient that the system  $AA'y \geq 0$  have a non-negative solution.*

**PROOF.** First, if  $AA'y \geq 0$  has any solution at all, the relation  $x = A'y$  gives a solution of  $Ax \geq 0$ . On the other hand, if  $Ax \geq 0$  has a solution, the corollary to Theorem 3.1 states that it has one of the form  $x = A'y$ ,  $y$  non-negative, and this  $y$  is a solution of  $AA'y \geq 0$ .

It should be observed that this theorem is a strengthening of the result, in [1], that  $Ax \geq 0$  and  $AA'y \geq 0$  are either both consistent or both inconsistent.

COROLLARY. *If  $B$  is a symmetric positive semi-definite matrix,  $By \geq 0$  has a solution if and only if it has a non-negative one.*

COROLLARY. *A sufficient condition that (1) have a nontrivial solution is that  $AA'y \geq 0$  have a (non-negative) solution.*

COROLLARY. *If the rank of  $A$  is  $n$ , a necessary condition that (1) have a nontrivial solution is that  $AA'y \geq 0$  have a (non-negative) solution.*

In [3] and [7] a necessary and sufficient condition is given that a system of type (2) be solvable. Using Theorem 2 of [3] we can state the following theorem.

THEOREM 3.3.  *$AA'y \geq 0$  (and hence (2)) has a solution if and only if  $AA'y = 0$  has no positive solution.*

In [4] a method is given for determining whether or not a system of homogeneous linear equations has a positive solution. In the form given, however, the method does not seem feasible for purposes of computation.

An obvious necessary condition that  $AA'y = 0$  have a positive solution is that for any collection of rows of  $AA'$ , the  $m$  column sums be all zero or have a pair of terms of opposite sign. Hence a sufficient condition that  $AA'y \geq 0$  (and hence (2)) have a solution is that for some collection of rows of  $AA'$ , the  $n$  column sums form a non-negative set.

Having obtained a sufficient condition that  $AA'y \geq 0$  be solvable, we now derive a necessary condition. Denoting  $AA'$  by  $B = (b_{ij})$ , we know by Theorem 3.2 that if  $By \geq 0$  has a solution it has a non-negative one. Hence if  $By \geq 0$  has a solution, then the system

$$\begin{array}{r} b_{11}y_1 + \dots + b_{1m}y_m \geq 0, \\ \dots \dots \dots \dots \dots \dots \dots \dots, \\ b_{m1}y_1 + \dots + b_{mm}y_m \geq 0, \\ \quad \quad \quad y_1 \qquad \qquad \qquad \geq 0, \\ \dots \dots \dots \dots \dots \dots \dots \dots, \\ \qquad \qquad \qquad \qquad \qquad \qquad \qquad \qquad y_m \geq 0 \end{array}$$

also has a solution. Using the theorem just quoted from [3] and [7], this has a solution if and only if the system of equations

$$\begin{array}{r} b_{11}u_1 + \dots + b_{m1}u_m + u_{m+1} = 0, \\ \dots \dots \dots \dots \dots \dots \dots \dots, \\ b_{1m}u_1 + \dots + b_{mm}u_m + u_{2m} = 0 \end{array}$$

has no positive solution. In other words we have proved

**THEOREM 3.4.** *A necessary condition that  $AA'y \geq 0$  (and hence (2)) have a solution is that  $-AA'y = 0$  have no positive solution.*

In Theorem D 5, p. 50, of [5], a criterion is given for the existence of positive solutions of  $-By = 0$ .

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