

# KLOOSTERMAN'S METHOD IN TAUBERIAN THEOREMS FOR $C_k$ SUMMABILITY<sup>1</sup>

JACOB KOREVAAR

1. Most proofs of the Tauberian theorem of Hardy and Landau which states that

$$(1) \quad \text{"} \sum a_n \text{ is } C_k \text{ summable"} + \text{"} na_n \leq M \text{"} \rightarrow \text{"} \sum a_n \text{ converges"}$$

(see [2, p. 121]) employ induction with respect to  $k$ , whereby the proof for arbitrary positive (whole)  $k$  is reduced to that for the case  $k = 1$ . In the preceding paper Knopp [5] shows, however, that induction works much more smoothly in the case of iterative methods such as  $H_k$  summability. Knopp then points out that one might use this fact together with the equivalence of the  $C_k$  and  $H_k$  methods in the proof of (1): if  $na_n \leq M$ , then  $C_k \rightarrow H_k \rightarrow H_1 \rightarrow C_1$ .

Kloosterman's method [3; 4] to prove (1) likewise has a more natural domain of application: it can be applied to integrals much more easily than to series as will be shown below. Moreover the analogue of (1) for integrals proved in this note contains (1) as a special case.

2. Let  $a(t)$  be defined for  $t \geq 0$  and integrable over every finite interval  $(0, x)$ ,  $x > 0$ . The integral  $\int a(t)dt$  is said to be  $C_k$  summable ( $k \geq 0$ ), to the value  $s$ , if

$$(2) \quad \begin{aligned} A_k(x) &= \int_0^x dt_1 \int_0^{t_1} dt_2 \cdots \int_0^{t_{k-1}} a(t)dt \\ &= \frac{x^k}{\Gamma(k+1)} \int_0^x a(t)(1-t/x)^k dt \sim \frac{x^k}{\Gamma(k+1)} s \quad (x \rightarrow \infty) \end{aligned}$$

(compare [2, p. 110]). Here the first expression for  $A_k(x)$  is of course to be used only if  $k$  is an integer.

With any series  $\sum a_n$  one may associate the step function  $a(t)$  defined by  $a(t) = a_n$  ( $n \leq t < n+1$ ,  $n = 0, 1, \dots$ ). The argument in [2, pp. 113-114] may be used to show that the assertions  $\sum a_n = s(C_k)$  and  $\int a(t)dt = s(C_k)$  are equivalent. Thus (1) is contained in the following (known) result (compare [2, p. 135]).

THEOREM. *If  $a(t)$  is real, if  $k > 0$  and*

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$$(3) \quad \int a(t)dt = s(C_k),$$

while

$$(4) \quad ta(t) \leq M \quad (t \geq 0),$$

then

$$(5) \quad \int_0^\infty a(t)dt = s.$$

3. The proof will be based on a formula which expresses the  $m$ th derivative  $f^{(m)}(x)$  of a function  $f(x)$  in terms of the differences  $\Delta^m f(x)$ ,  $\Delta^{m+1} f(x)$ ,  $\dots$ ,  $\Delta^n f(x)$ , where  $\Delta f(x) = f(x+h) - f(x)$ , etc. This formula occurs in the literature in a slightly weaker form, namely in A. A. Markoff's book [6, p. 21], and in Kloosterman's paper [4, Theorem 3]. Markoff's derivation can easily be modified so as to furnish the proof of the present lemma.

LEMMA. Let  $f(x)$  be real and have derivatives of order  $1, 2, \dots, n$  on  $(a, b)$ . Let the points  $x, x+nh$  be contained in  $(a, b)$ . Let  $0 \leq m \leq n$ . Then

$$(6) \quad h^m f^{(m)}(x) = B_m^m \Delta^m f(x) + \dots + B_m^n \Delta^n f(x) + B_m^{n+1} h^{n+1} \Phi,$$

where

$$(7) \quad B_m^p = \left\{ \frac{d^m}{dz^m} \binom{z}{p} \right\}_{z=0},$$

while  $\Phi$  can be written in the form

$$(8) \quad \Phi = \frac{f^{(n)}(x_2) - f^{(n)}(x_1)}{x_2 - x_1},$$

with  $x_1, x_2$  contained in the interval with end points  $x, x+nh$ .

4. PROOF OF THE THEOREM. As in the preceding paper one may assume that  $k$  is an integer  $\geq 1$ . Let  $\epsilon > 0$  be given. By (3) one can determine  $x_0$  such that

$$A_k(x) = (x^k/k!)s + \theta(x)\epsilon x^k \quad (-1 < \theta(x) < 1 \text{ for } x > x_0).$$

Now apply the lemma to  $f(x) = A_k(x)$ , taking  $n = m = k$ ,  $x > x_0$ ,  $0 < h < x/k$ . Note that, by (7),

$$B_k^k = 1, B_k^{k+1} = -k/2,$$

while by the definition of  $\Delta^k$ ,

$$\begin{aligned} \Delta^k A_k(x) &= h^k s + \epsilon \sum (-1)^{k-j} \binom{k}{j} \theta(x + jh)(x + jh)^k \\ &> h^k s - \epsilon \sum \binom{k}{j} (2x)^k = h^k s - \epsilon \cdot 4^k x^k. \end{aligned}$$

Furthermore by (8) and (4)

$$\Phi = \left\{ \int_{x_1}^{x_2} a(t) dt \right\} / (x_2 - x_1) \leq M/x.$$

Collecting results, one obtains from (6) the estimate

$$\begin{aligned} (9) \quad \int_0^x a(t) dt &= h^{-k} \Delta^k A_k(x) = 2^{-1} k h \Phi \\ &> s - \epsilon \cdot 4^k (x/h)^k - 2^{-1} k M h/x \quad (x > x_0). \end{aligned}$$

Choosing

$$h = \epsilon^{1/(k+1)} x$$

—for this choice of  $h$ ,  $kh$  will be less than  $x$  provided  $\epsilon$  is small enough —(9) takes the form

$$(10) \quad \int_0^x a(t) dt > s - C \epsilon^{1/(k+1)} \quad (x > x_0),$$

where  $C$  is independent of  $\epsilon$ . An estimate in the opposite direction may be obtained by taking, from the beginning,  $0 > h > -2^{-1}x/k$ . This completes the proof of (5).

5. In the above proof formula (6) was used only in the special case  $m = n = k$  (compare [3]). Various other (known) results may be derived from (6). For example, one finds by taking  $f(x) = A_k(x)$ ,  $0 < m \leq n = k$ , that the hypotheses  $a(x) = A_{-1}(x) < Mx^\alpha$  and  $A_k(x) = o(x^\beta)$  (with  $\beta - \alpha \leq k + 1$ ) imply the “convexity” estimate  $A_{k-m}(x) = o(x^\gamma)$  where  $\gamma = \{m\alpha + (k + 1 - m)\beta\} / (k + 1)$  (compare [1], where more general estimates are proved). Another example is the Tauberian theorem on  $C_k$  summable gap series [7].

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THE UNIVERSITY OF WISCONSIN