

CONVEX SETS AND NEAREST POINTS. II¹

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1. Introduction. In 1935 Motzkin [5] showed that if S is a subset of the euclidean plane E and $z \in S$ then the set S_z of all points in E having z as a nearest point in S is closed and convex. In [7] this result was easily extended to inner product spaces of arbitrary dimension. In §2 of the present paper we show that *any* closed convex subset T of a complete inner product space E can be realized in such a manner, i.e. there exists a set S and a point $z \in S$ such that $T = S_z$. Further, it is true that if E is a normed linear space of dimension at least three then every closed convex subset T can be so realized *only* if E is a complete inner product space.

If A is a subset of a normed linear space E and x, y are in E we say that y is *point-wise closer* to A than is x provided $\|y - a\| < \|x - a\|$ for each $a \in A$. If x is such that no point of E is point-wise closer to A than is x we call x a *closest-point* to A . Fejér [1] has noted that in the euclidean plane the set $C(A)$ of all closest points to A is precisely $K(A)$, the closed convex hull of A . In applying this result, Fejér, and later Motzkin and Schoenberg [6], actually used a weaker version, which we will call *property (F)*: If $A \subset E$, then $C(A) \subset K(A)$. In §3 we show that property (F) characterizes complete inner product spaces of dimension at least three, while in two-dimensional spaces it is equivalent to strict convexity. We also extend Fejér's characterization of $K(A)$ to complete inner product spaces and show that it holds in strictly convex two-dimensional spaces if A is bounded.

2. Nearest-point sets. If S is a subset of a normed linear space E and if $z \in S$, S_z will denote the set $\{x: \|x - z\| = \inf_{y \in S} \|x - y\|\}$ of all points in E whose distance from S is attained at z . Using the alternative formulation $S_z = \{x: \|x - z\| \leq \|x - y\| \text{ for each } y \in S\}$ it is easy to see that S_z is always closed. In several papers [2; 3; 4] James has successfully exploited a concept of orthogonality which is defined as follows: We say that x is *orthogonal* to y (and write $x \perp y$) if $\|x\| \leq \|x - \lambda y\|$ for each $\lambda \in R$, where R is the real numbers. Note that this is equivalent to saying that x has the origin ϕ as a nearest point

Presented to the Society February 23, 1957; received by the editors July 12, 1957, and, in revised form, May 16, 1958.

¹ Work on this paper sponsored in part by the Office of Ordnance Research, U. S. Army, under contract DA-04-200-ORD-292.

² The author wishes to express his appreciation to Professor V. L. Klee for having read and criticized this paper.

in $Ry = \{\lambda y : \lambda \in R\}$, the line determined by y and ϕ (assuming $y \neq \phi$)—in other words, $x \in (Ry)_\phi$. That this is a generalization of the usual inner product space concept of orthogonality is easily verified, using the identity

$$(1) \quad \|x - \lambda y\|^2 = \|x\|^2 - 2\lambda(x, y) + \|y\|^2$$

by merely showing that in such a space $x \perp y$ if and only if $(x, y) = 0$. If L is a linear subset of E we write $L \perp y$ ($y \perp L$) provided $x \perp y$ ($y \perp x$) for each $x \in L$, and if M is linear, $L \perp M$ is defined in a similar way. Note that $x \perp y$ if and only if $Rx \perp Ry$.

James has proved a theorem [4, Theorem 4] which, after a slight extension, will be quite useful to us.

THEOREM 1 (JAMES). *Suppose E is a normed linear space of dimension at least three. Then E is a complete inner product space provided each hyperplane through the origin is orthogonal to some point $x \neq \phi$.*

PROOF. James has shown that the condition is sufficient to imply that E is an inner product space, so we need only show that E is also complete. Suppose $y \in F$, where F is the completion of E . Then the set $H = \{z : z \in F \text{ and } (z, y) = 0\}$ is a hyperplane in F and $H_0 = H \cap E$ is a hyperplane in E which contains ϕ . By hypothesis there exists $x \neq \phi$ such that $H_0 \perp x$. But, as noted previously, this implies that $(z, x) = 0$ for each $z \in H_0$. Hence, by continuity of the inner product and the fact that H_0 is dense in H , we have $(z, x) = 0$ for each $z \in H$. This implies that $y \in Rx \subset E$, so that $E = F$ is complete.

Note that if H is a hyperplane in an inner product space and x is a point of least norm in H then $x \in (H - x)_\phi$ or $x \perp H - x$.

We call a subset T of a normed linear space E a *nearest-point set* if there exists a set $S \subset E$ and a point $z \in S$ such that $T = S_z$. In [7] it was shown that every nearest-point set in E is closed and convex if and only if E is an inner product space. Here we consider the question: For what class of normed linear spaces is every closed convex set a nearest-point set? This is partially answered by the following theorem.

THEOREM 2. *In a complete inner product space E every closed convex set T is a nearest-point set.*

PROOF. If $T = E$, let $S = \{\phi\}$. Otherwise, $T = \bigcap_{H \in \mathfrak{H}} H'$ where \mathfrak{H} is the collection of all hyperplanes H such that H determines a closed half-space H' for which $T \subset H'$. Pick any point of T —we will suppose that it is the origin. For $H \in \mathfrak{H}$ let x_H be the point of least norm in H and define $S = \{2x_H : H \in \mathfrak{H}\} \cup \{\phi\}$. Since $x_H \perp H - x_H$ for each

$H \in \mathcal{H}$, we have $H' - x_H = \{y: (x_H, y) \leq 0\}$ or $H' = \{y: (x_H, y - x_H) \leq 0\}$. But, letting $z = y - x_H$, $(z, x_H) \leq 0$ if and only if $2(z, x_H) \leq -2(z, x_H)$ which is in turn equivalent to $\|z\|^2 + 2(z, x_H) + \|x_H\|^2 \leq \|z\|^2 - 2(z, x_H) + \|x_H\|^2$. This, however, is the same as $\|z + x_H\|^2 \leq \|z - x_H\|^2$ or $\|y\|^2 \leq \|y - 2x_H\|^2$. Thus, $H' = \{y: \|y\| \leq \|y - 2x_H\|\}$ and hence $T = \bigcap_{H \in \mathcal{H}} H' = \{y: \|y\| \leq \|y - 2x_H\| \text{ for each } H \in \mathcal{H}\} = \{y: \|y\| \leq \|y - z\| \text{ for each } z \in S\} = S_\phi$.

The above proof shows that for any $z \in T$ there exists a set $S(T, z)$ such that $T = S(T, z)_z$. Applying the (constructive) method of the proof to a specific example we find, with the aid of some elementary analytic geometry, that if T is the closed disc bounded by the curve $r = 2 \cos \theta$ then $S(T, \phi)$ is the area not inside the cardioid $r = 2(1 + \cos \theta)$. Note that we could omit from S any point not on the cardioid and still have $T = S_\phi$. We can, however, show that in a certain sense the set S can be taken to be unique. Suppose that T is a nearest-point subset of a normed linear space E ; then there exists $S \subset E$ and $z \in S$ such that $T = S_z$. Let \mathcal{S} be the collection of all sets S containing z such that $S_z = T$. Then, letting $Q(T, z) = \bigcup_{S \in \mathcal{S}} S$, we see that $Q(T, z)_z = \bigcap_{S \in \mathcal{S}} S_z = T$ so that $Q(T, z) \in \mathcal{S}$ and is the biggest member of \mathcal{S} . Henceforth, if a set T is a nearest-point set, $Q(T, z)$ will denote the set defined above. If there is no chance for confusion we will simply denote it by Q .

Suppose that $T = S_z$ for some S and $z \in S$. Then $Q(T, z) = \{x: \|x - y\| \geq \|z - y\| \text{ for each } y \in T\}$. For clearly $x \in Q$ implies $\|x - y\| \geq \|z - y\|$ for each $y \in T$; and if this latter is true, $T \subset [Q \cup \{x\}]_z \subset Q_z = T$ so that $[Q \cup \{x\}]_z = T$ and by the maximality property of Q , $x \in Q \cup \{x\} \subset Q$. Using this description of Q it is easy to see that Q is closed. Further, the set S constructed in the proof of Theorem 2 is actually equal to $Q(T, \phi)$, for $T = S_\phi$ implies that $S \subset \{x: \|x - y\| \geq \|y\| \text{ for each } y \in T\}$. Suppose that x is a point of the latter set, then the hyperplane $H = \{w: \|w - x\| = \|w\|\}$ passes through $(1/2)x$ and is orthogonal to Rx . Hence, if H' is the closed half-space determined by H which contains ϕ , $y \in T$ implies $\|y\| \leq \|y - x\|$ so that $y \in H'$ and thus $T \subset H'$. We have, then, that $H \in \mathcal{H}$ and that x is of the form $2x_H$ and is therefore in S .

It is natural to wonder if Q may be convex. Suppose that $T = Q_\phi$ and that Q is convex, then by Lemmas 3.1 and 4.1 of [7] T must be a convex cone with vertex ϕ . Using identity (1) it is easily verified that whenever T is a cone with vertex ϕ , $Q = \{x: (x, y) \leq 0 \text{ for each } y \in T\}$ and hence Q is also a convex cone with vertex ϕ (the dual or polar cone of T [8]). Thus, Q is convex if and only if both T and Q are convex cones with common vertex.

In what follows we show that the hypothesis in Theorem 2 that E be a complete inner product space is necessary, if the dimension of E is at least three.

THEOREM 3. *Suppose that E is a normed linear space of three or more dimensions and that every closed convex subset of E is a nearest-point set. Then E is a complete inner product space.³*

PROOF. Suppose H is a hyperplane in E which passes through the origin. By Theorem 1 we can conclude that E is a complete inner product space provided every such hyperplane is orthogonal to some $x \neq \phi$, i.e. provided $H \perp Rx$ for some $x \neq \phi$. Now, H is closed and convex so there exists a set S and a point $z \in S$ such that $H = S_z$. By the preceding discussion there exists a maximal set $Q(H, z)$ such that $H = Q_z$. If $Q = \{z\}$, $Q_z = H$ would be the entire space, contradicting the fact that H is a hyperplane. Pick $x \in Q \sim \{z\}$ and suppose $y \in H$ and $\lambda \in R \sim \{0\}$. Since $z \in H$, there exists $w \in H$ such that $y = \lambda(w - z)$. We know that $\|w - x\| \geq \|w - z\|$ hence $\|\lambda(w - x)\| \geq \|\lambda(w - z)\|$ or $\|y - \lambda(x - z)\| \geq \|y\|$. Therefore $H \perp R(x - z)$, which was to be shown.

What if E is two-dimensional and every closed convex subset of E is a nearest-point set? By somewhat lengthy arguments we have been able to show that this implies strict convexity of E , and that E is an inner product space provided we assume that E is smooth. We have been unable to show that the assumption of smoothness is necessary. This result indicates, however, that strict convexity alone does not imply that every closed convex subset of E is a nearest-point set, for such an implication would in turn imply the false statement that every smooth and strictly convex two-dimensional normed linear space is an inner product space.

3. Convex sets and closest points. We first prove Fejér's theorem (see introduction) in a more general setting.

THEOREM 4 (FEJÉR). *If A is a subset of a complete inner product space E , the closed convex hull $K(A)$ of A is the set $C(A)$ of closest points to A .*

PROOF. Suppose $x \notin K(A)$, then there exists a hyperplane H separating x from $K(A)$ such that $x \notin H$. Since E is complete we know that the distance from x to H is attained at some (unique) point of H . Without loss of generality we may assume that this point is the origin, so that $\|x\| \leq \|x - z\|$ for each $z \in H$. This says, then, that $x \perp H$ and hence $H \perp x$. Thus, if $a \in A$, there exists $z \in H \cap [a, x]$. Now,

³ We wish to thank the referee for suggesting changes which simplified the proof of this theorem, as well as the proof of Theorem 5.

$\|z\| < \|z-x\|$ and therefore $\|a\| \leq \|a-z\| + \|z\| < \|a-z\| + \|z-x\| = \|a-x\|$. Hence ϕ is point-wise closer to A than is x , giving $x \notin C(A)$.

Suppose $x \notin C(A)$, then there exists $y \in E$ which is point-wise closer to A than is x . The set $H = \{z: \|z-y\| = \|z-x\|\}$ is a hyperplane through $(1/2)(x+y)$ which determines a closed half-space $H' = \{z: \|z-y\| \leq \|z-x\|\}$ containing A . Hence $K(A) \subset H'$ and since $x \notin H'$, $x \notin K(A)$.

Defining property (F) as in the introduction, we now determine the class of spaces possessing the property.

THEOREM 5. *Suppose that E is a normed linear space of dimension at least three which possess property (F). Then E is a complete inner product space.*

PROOF. We again make use of Theorem 1. Suppose that H is a hyperplane through ϕ . If $x \notin H = K(H)$ then by assumption $x \notin C(H)$ and there must exist a point y such that $\|h-y\| < \|h-x\|$ for each $h \in H$. The line L determined by x and y must hit H at w , say. (For ϕ has a nearest point z in L , so if L were parallel to H , $h = x - z$ would be in H and have x as a nearest-point in L . In particular, h would not be closer to $y \in L$ than to x , a contradiction.) Now, $w = \alpha y + (1-\alpha)x$ for some $\alpha \neq 0$, so if $\lambda \neq 0$ and h is any point of H we have $\alpha\lambda^{-1}h + w \in H$ and $\|h - \lambda(x - y)\| = \|\lambda\alpha^{-1}[(\alpha\lambda^{-1}h + w) - x]\| > \|\lambda\alpha^{-1}[(\alpha\lambda^{-1}h + w) - y]\| = \|h + \beta\lambda(x - y)\|$, where we have let $\beta = \alpha^{-1}(1-\alpha)$. If $\beta = 0$ we have the inequality we are seeking; otherwise, we use the fact that $h \in H$ if and only if $\beta^{-1}h \in H$ to conclude, by induction, that $\|h - \lambda(x - y)\| > \|h + \beta^n\lambda(x - y)\|$ for each positive integer n . Setting $h = \phi$ shows that $|\beta| < 1$, so, taking the limit as $n \rightarrow \infty$, we have $\|h - \lambda(x - y)\| > \|h\|$. This shows that $H \perp (x - y)$ and hence we can conclude from Theorem 1 that E is a complete inner product space.

LEMMA 6. *If a normed linear space E has property (F) then E is strictly convex.*

PROOF. If E is not strictly convex there exist points x, y in E such that the distance from y to each point of the segment $[-x, x]$ is exactly 1. Let $A = [-y, y]$; then $x \notin A = K(A)$ and hence $x \notin C(A)$, by hypothesis. There must exist a point z in E which is point-wise closer to A than is x . Thus, $\|z-y\| < \|x-y\| = 1$ and $\|z+y\| < \|x+y\| = 1$ so $2 = \|2y\| = \|(-y) - y\| \leq \|-y-z\| + \|z-y\| < 2$, a contradiction.

THEOREM 7. *Suppose that E is a two-dimensional normed linear space. Then E possesses property (F) if and only if it is strictly convex.*

PROOF. Lemma 6 proves the necessity. Suppose E is strictly con-

vex and $A \subset E$. If $x \notin K(A)$ there exists a line L separating $K(A)$ from x such that $x \notin L$. We can suppose that $\phi \in L$ and that $L = Ry$ for some $y \neq \phi$. There exists a line M through ϕ such that $y \perp M$ [3, Theorem 2.2], so $M+x$ hits Ry at αy for some $\alpha \in R$. We will show that αy is point-wise closer to A than is x . Suppose $a \in A$, then $[a, x]$ hits Ry at βy , say. Now $M+x = M+\alpha y$ so $x-\alpha y \in M \sim \{\phi\}$ and hence, by strict convexity, $\|\beta y - \alpha y\| < \|(\beta y - \alpha y) - (x - \alpha y)\| = \|\beta y - x\|$. Then

$$\|a - \alpha y\| \leq \|a - \beta y\| + \|\beta y - \alpha y\| < \|a - \beta y\| + \|\beta y - x\| = \|a - x\|.$$

Hence $x \in C(A)$ and we have $C(A) \subset K(A)$.

In stating his theorem Fejér assumed that A was compact. This is an unnecessary restriction if we wish to prove his characterization of $K(A)$ in the euclidean plane, but it is interesting to note that if we merely assume that A is *bounded* we can prove his characterization in any two-dimensional strictly convex normed linear space.

THEOREM 8. *Suppose that A is a bounded subset of a strictly convex two-dimensional normed linear space E . Then $K(A) = C(A)$.*

PROOF. That $C(A) \subset K(A)$ follows from the strict convexity and Theorem 7. Suppose that $x \notin C(A)$, then there exists a point $y \in E$ such that $\|y - a\| < \|x - a\|$ for each $a \in A$. We can suppose without loss of generality that $x = \phi$. Now there exists a point $z \neq \phi$ such that $z \perp y$ [3] and hence $L \perp y$ for $L = Rz$. Letting L' be the closed half-space determined by L which does not contain y , we see that $\text{cl } A$, the closure of A , is contained in $E \sim L'$ as follows: Let $S = \{w: \|w - y\| \leq \|w\|\}$; then S is closed, contains A and hence contains $\text{cl } A$. Furthermore, if w is a point of L' , we can use strict convexity and the triangle inequality (as in the proof of Theorem 7) to show that $\|w\| < \|w - y\|$. Thus, $w \notin S$ so $S \subset E \sim L'$ and $\text{cl } A \subset E \sim L'$.

Since A is bounded, $\text{cl } A$ is compact and hence $\text{conv cl } A$, the convex hull of $\text{cl } A$, is closed. Thus, $K(\text{cl } A) = \text{conv cl } A$ and since $E \sim L'$ is convex, $\text{conv cl } A \subset E \sim L'$. We have, then, that $K(A) \subset K(\text{cl } A) \subset E \sim L'$, so that ϕ , being in $L \subset L'$, is not in $K(A)$. Therefore $C(A) = K(A)$ for any bounded set A .

It is possible to construct an example in which the above result fails for an unbounded set A .

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NOTE ON PRODUCTS IN Ext

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The objective of this note is to present an interrelation between the V-product in [1] and the composition product in [2; 3], which in turn gives a comparison of the cup-product with the composition product. Similar relations can be obtained also for other products involving Tor and (iterated) connecting homomorphisms.

We retain the notations in [1, Chapter XI]. The external product $V: \text{Ext}_{\Lambda \otimes \Sigma^*}(A, C) \otimes \text{Ext}_{\Sigma \otimes \Gamma^*}(A', C') \rightarrow \text{Ext}_{\Lambda \otimes \Gamma^*}(A \otimes_{\Sigma} A', C \otimes_{\Sigma} C')$ is defined in the situation $(\Lambda A_{\Sigma}, \Lambda C_{\Sigma}, \Sigma A'_{\Gamma}, \Sigma C'_{\Gamma})$ under the following assumption: (i) Λ, Γ, Σ are K -projective; (ii) $\text{Tor}_n^{\Sigma}(A, A') = 0$ for $n > 0$. To this situation we now add $(\Lambda B_{\Sigma}, \Sigma B'_{\Gamma})$ and (ii') $\text{Tor}_n^{\Sigma}(B, B') = 0$ for $n > 0$. For $a \in \text{Ext}_{\Lambda \otimes \Sigma^*}^p(A, B)$ and $b \in \text{Ext}_{\Lambda \otimes \Sigma^*}^q(B, C)$ the composition product $b \circ a$ lies in $\text{Ext}_{\Lambda \otimes \Sigma^*}^{p+q}(A, C)$. For $a' \in \text{Ext}_{\Sigma \otimes \Gamma^*}^{p'}(A', B')$ and $b' \in \text{Ext}_{\Sigma \otimes \Gamma^*}^{q'}(B', C')$, $b' \circ a'$ lies in $\text{Ext}_{\Sigma \otimes \Gamma^*}^{p'+q'}(A', C')$. ($b \circ a = a \circ b$ in the notation of [2].)

PROPOSITION 1. $(b \circ a)V(b' \circ a') = (-1)^{p a'}(bVb') \circ (aVa')$.

In fact let X, Y be $\Lambda \otimes \Sigma^*$ -projective resolutions of A, B respectively, and let X', Y' be $\Sigma \otimes \Gamma^*$ -projective resolutions of A', B' . Then $X \otimes_{\Sigma} X', Y \otimes_{\Sigma} Y'$ are $\Lambda \otimes \Gamma^*$ -projective resolutions of $A \otimes_{\Sigma} A', B \otimes_{\Sigma} B'$. We consider these resolutions as chain complexes with 0's in negative dimensions. Suppose that a, b, a', b' are respectively represented by maps $\alpha: X_p \rightarrow B, \beta: Y_q \rightarrow C, \alpha': X'_{p'} \rightarrow B',$ and $\beta': Y'_{q'} \rightarrow C'$. The map α

Received by the editors April 25, 1958.

¹ Work done while the author was engaged under contract NONR 2383.