

## SOME INTEGRAL FORMULAS FOR CLOSED HYPERSURFACES IN EUCLIDEAN SPACE

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**Introduction.** Let  $V^n$  be the orientable hypersurface twice differentiably imbedded in a Euclidean space  $E^{n+1}$  of  $n+1 \geq 3$  dimensions, and let  $k_1, \dots, k_n$  be the  $n$  principal curvatures at a point  $P$  of  $V^n$ . The  $r$ th mean curvature  $H_r$  of  $V^n$  at the point  $P$  is defined to be the  $r$ th elementary symmetric function of  $k_1, \dots, k_n$  divided by the number of terms, that is,

$$(1) \quad \binom{n}{r} H_r = \sum_{i_1 < \dots < i_r} k_{i_1} \cdots k_{i_r},$$

and  $H_0 = 1$ . Throughout this paper all Latin indices take the values  $1, \dots, n$ . Greek indices the values  $1, \dots, n+1$ , and we shall also follow the convention that repeated indices imply summation. Let  $p$  denote the oriented distance from a fixed point  $O$  in  $E^{n+1}$  to the tangent hyperplane  $\pi(P)$  of  $V^n$  at the point  $P$ , and let  $d\Omega$  be the area element of  $V^n$  at  $P$ . Let  $e_1, \dots, e_n$  be an oriented orthonormal frame in the tangent space of the hypersurface  $V^n$  at the point  $P$ , and denote by  $z_i$  the scalar product of  $e_i$  and the position vector of the point  $P$  with respect to the fixed point  $O$  in the space  $E^{n+1}$ . The purpose of this paper is to establish the following

**THEOREM.** *Let  $V^n$  be a closed orientable hypersurface twice differentiably imbedded in a Euclidean space  $E^{n+1}$  of  $n+1 \geq 3$  dimensions. Then*

$$(2) \quad n \int_{V^n} p^{m-1} (1 + p H_1) d\Omega - (m-1) \int_{V^n} p^{m-2} \sum_{i,j} a_{ij} z_i z_j d\Omega = 0,$$

$$(3) \quad n \int_{V^n} p^{m-1} (H_{n-1} + p H_n) d\Omega - (m-1) \int_{V^n} p^{m-2} H_n \sum_i z_i^2 d\Omega = 0,$$

where  $m$  is any real number, and  $a_{ij}$  the coefficients of the second fundamental form of the hypersurface  $V^n$  at a general point.

These formulas (2), (3) were obtained by Chern [2] for  $n=2$ , by Hsiung [3], [4] for  $m=1$  in a Euclidean space  $E^{n+1}$  as well as a Riemannian space  $R^{n+1}$ , and jointly by Hsiung and the author [5] in an affine space  $A^{n+1}$ .

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Let  $p'$  be the foot of the perpendicular from the fixed point  $O$  to the tangent hyperplane  $\pi(P)$ ,  $d_P$  the distance  $PP'$  and  $\rho_P$  the normal curvature of the hypersurface  $V^n$  in the direction  $PP'$ . Then  $OP + PP' = OP'$ . By taking scalar products of both sides of this vector equation with  $e_i$  we obtain  $z_i + e_i \cdot PP' = 0$ , which enables us to write  $-PP' = \sum_i z_i e_i$ . Hence we arrive at the following geometric meanings of the terms  $\sum_i z_i^2$ ,  $\sum_{i,j} a_{ij} z_i z_j$  in the formulas (3), (2):

$$d_p^2 = \sum_i z_i^2, \quad d_p^2 \rho_P = \sum_{i,j} a_{ij} z_i z_j.$$

**1. Preliminaries.** In a Euclidean space  $E^{n+1}$  of dimension  $n+1 \geq 3$  let us consider a fixed right-handed rectangular frame  $Ye_1 \cdots e_{n+1}$ , where  $Y$  is a point in the space  $E^{n+1}$ , and  $e_1, \dots, e_{n+1}$  are an ordered set of mutually orthogonal unit vectors such that its determinant is

$$(4) \quad |e_1, \dots, e_{n+1}| = 1,$$

so that

$$(5) \quad e_i e_j = \delta_{ij},$$

where  $\delta_{ij}$  are the Kronecker deltas. We also use  $Y$  to denote the position vector of the point  $P$  with respect to a fixed point  $O$  in the space  $E^{n+1}$ . Then we can have

$$(6) \quad dY = \omega^\alpha e_\alpha,$$

$$(7) \quad de_\alpha = \omega_\alpha^\beta e_\beta,$$

where  $d$  denotes the exterior differentiation, and  $\omega^\alpha, \omega_\alpha^\beta$  are Pfaffian forms. Since  $d^2 Y = d(dY) = d(de_\alpha) = 0$ , exterior differentiation of equations (5), (6), (7) gives

$$(8) \quad \omega_\alpha^\beta + \omega_\beta^\alpha = 0,$$

and the equations of structure of the group of proper motions in the space  $E^{n+1}$ :

$$(9) \quad d\omega^\alpha = \omega^\beta \wedge \omega_\beta^\alpha,$$

$$(10) \quad d\omega_\alpha^\beta = \omega_\alpha^\gamma \wedge \omega_\gamma^\beta,$$

where  $\wedge$  denotes the exterior product.

Let  $V^n$  be a hypersurface twice differentially imbedded in the space  $E^{n+1}$ . Consider the subfamily of frames  $Ye_1 \cdots e_{n+1}$  satisfying the conditions (i)  $Y \in V^n$ , (ii)  $e_1, \dots, e_n$  are vectors tangent to  $V^n$  at  $P$ . Then we have

$$(11) \quad \omega^{n+1} = 0,$$

and equations (9), (8) give

$$(12) \quad \omega^i \wedge \omega_i^{n+1} = 0.$$

By a lemma of E. Cartan [1, p. 11] on exterior algebra, equation (12) implies that for each value of  $i$

$$(13) \quad \omega_i^{n+1} = a_{ij}\omega^j,$$

with  $a_{ij} = a_{ji}$ . From equations (6), (7), (8), (13) it follows that at the point  $P$  of the hypersurface  $V^n$ , the first and second fundamental forms are respectively given by

$$(14) \quad dY \cdot dY = \sum_{i=1}^n (\omega^i)^2,$$

$$(15) \quad \Phi = -dY \cdot de_{n+1} = a_{ij}\omega^i\omega^j,$$

and the element of area is given by

$$(16) \quad d\Omega = \omega^1 \wedge \cdots \wedge \omega^n.$$

Thus the  $n$  principal curvatures  $k_1, \cdots, k_n$  of the hypersurface  $V^n$  at the point  $P$  are roots of the determinant equation

$$(17) \quad |a_{ij} - k\delta_{ij}| = 0.$$

In other words,  $k_1, \cdots, k_n$  are the characteristic roots of the matrix  $\|a_{ij}\|$ .

A principal minor of the matrix  $\|a_{ij}\|$  is a minor whose diagonal is part of the main diagonal of the matrix  $\|a_{ij}\|$ . From a theorem in linear algebra it is known that the  $r$ th elementary symmetric function of the characteristic roots of the matrix  $\|a_{ij}\|$  is equal to the sum of all  $r$ -rowed principal minors of the matrix  $\|a_{ij}\|$ . Hence  $C_{n,r}H_r$  defined by equation (1) is equal to the sum of all  $r$ -rowed principal minors of the matrix  $\|a_{ij}\|$ . In particular we have

$$(18) \quad nH_1 = \sum_{i=1}^n a_{ii},$$

$$(19) \quad H_n = |a_{ij}|,$$

$$(20) \quad nH_{n-1} = \sum_{i=1}^n A^{ii},$$

where  $A^{ii}$  is the cofactor of  $a_{ii}$  in the determinant  $|a_{ij}|$ .

**2. Proof of the Theorem.** Let us now consider the scalar products

$$(21) \quad \hat{p} = Ye_{n+1}, \quad z_\alpha = Ye_\alpha.$$

Geometrically,  $z_\alpha$  is the oriented distance from the origin  $O$  to the hyperplane  $P e_1 \cdots \hat{e}_\alpha \cdots e_{n+1}$ , where the circumflex over  $e_\alpha$  indicates the vector  $e_\alpha$  is to be deleted. In particular  $z_{n+1}$  will also be written as  $p$ . From equations (21), (7), (8), (13) follows immediately

$$(22) \quad d p = - \sum_i a_{ij} \omega^j z_i.$$

It is convenient to write equations (21) as

$$(23) \quad p = (-1)^n | Y, e_1, \dots, e_n |,$$

$$(24) \quad z_\alpha = (-1)^{\alpha-1} | Y, e_1, \dots, \hat{e}_\alpha, \dots, e_{n+1} |.$$

By means of the relation  $d^2 Y = d^2 e_{n+1} = 0$  and the ordinary rule for differentiation of determinants, we have the differential forms

$$(25) \quad \begin{aligned} & d(p^{m-1} | Y, e_{n+1}, dY, \dots, dY |) \quad (\text{where } dY \text{ occurs } (n-1) \text{ times}) \\ & = (m-1) p^{m-2} d p \wedge | Y, e_{n+1}, dY, \dots, dY | \\ & \quad (\text{where } dY \text{ occurs } (n-1) \text{ times}) \\ & - p^{m-1} | e_{n+1}, dY, \dots, dY | \quad (\text{where } dY \text{ occurs } n \text{ times}) \\ & + p^{m-1} | Y, d e_{n+1}, dY, \dots, dY |, \\ & \quad (\text{where } dY \text{ occurs } (n-1) \text{ times}), \\ & d(p^{m-1} | Y, e_{n+1}, d e_{n+1}, \dots, d e_{n+1} |) \\ & \quad (\text{where } d e_{n+1} \text{ occurs } (n-1) \text{ times}) \\ & = (m-1) p^{m-2} d p \wedge | Y, e_{n+1}, d e_{n+1}, \dots, d e_{n+1} | \\ & \quad (\text{where } d e_{n+1} \text{ occurs } (n-1) \text{ times}) \\ & + p^{m-1} | dY, e_{n+1}, d e_{n+1}, \dots, d e_{n+1} | \\ & \quad (\text{where } d e_{n+1} \text{ occurs } (n-1) \text{ times}) \\ & + p^{m-1} | Y, d e_{n+1}, \dots, d e_{n+1} | \\ & \quad (\text{where } d e_{n+1} \text{ occurs } n \text{ times}). \end{aligned}$$

Using the elementary identity  $C_{n,r} = n! / [(n-r)! r!]$  and equations (22), (6), (7), (8), (19), (20), (16), (23), (24), from equations (25), (26) we can easily obtain

$$(27) \quad \begin{aligned} & \frac{(-1)^{n-1}}{(n-1)!} d(p^{m-1} | Y, e_{n+1}, dY, \dots, dY |) \\ & \quad (\text{where } dY \text{ occurs } (n-1) \text{ times}) \\ & = n p^{m-1} (1 + p H_1) d\Omega - (m-1) p^{m-2} \sum_{i,j} a_{ij} z_i z_j d\Omega, \end{aligned}$$

$$\begin{aligned}
 & \frac{1}{(n-1)!} d(p^{m-1} | Y, e_{n+1}, de_{n+1}, \dots, de_{n+1} | ) \\
 (28) \quad & \qquad \qquad \qquad \text{(where } de_{n+1} \text{ occurs } (n-1) \text{ times)} \\
 & = np^{m-1}(H_{n-1} + p H_n) d\Omega - (m-1)p^{m-2} H_n \sum_i z_i^2 d\Omega.
 \end{aligned}$$

Application of Stokes' theorem to equations (27), (28) gives immediately the required formulas (2), (3).

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