

ON AN INTEGRAL FORMULA FOR CLOSED
 HYPERSURFACES OF THE SPHERE

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ABSTRACT. In a compact oriented hypersurface M^n of the sphere S^{n+1} the integral formula $\int_{M^n} \nabla K_r dV = n \int_{M^n} (K_r K_1 - K_{r+1}) e dV$ is proved where K_r is the r th mean curvature, e is the unit normal of M^n in S^{n+1} . Some applications are considered.

1. Let S^{n+1} be the unit sphere in a euclidean space E^{n+2} and $x: M^n \rightarrow S^{n+1}$ be an isometric immersion of a compact oriented Riemannian manifold M^n of dimension n into S^{n+1} . Let $F(M^n)$, $F(S^{n+1})$ and $FE^{(n+2)}$ be the bundles of orthonormal frames of M^n , S^{n+1} and E^{n+2} respectively. Let B be the set of elements $b = (p, e_1, \dots, e_n, e, x(p))$ such that $(p, e_1, \dots, e_n) \in F(M^n)$, $(x(p), e_1, \dots, e_n, e) \in F(S^{n+1})$ and $(x(p), e_1, \dots, e_n, e, x) \in FE^{(n+2)}$ with coherent orientations. $dx(e_i)$ is identified with e_i , $i=1, 2, \dots, n$. Define $\tilde{x}: B \rightarrow FE^{(n+2)}$ by $\tilde{x}(b) = (x(p), e_1, \dots, e_n, e, x)$.

By the structure equations of E^{n+2} and the pullback by \tilde{x} we may write

$$(1.1) \quad dx = \sum \omega_i e_i, \quad de = \sum \theta_i e_i$$

with $\theta_i = k_i \omega_i$. Where $i=1, 2, \dots, n$; k_1, \dots, k_n are principal curvatures of M^n in S^{n+1} at p . de does not have component in the x direction is easily followed from $d(e \cdot x) = 0$.

2. Let $|\cdot, \dots, \cdot|$ denote the combined operation of the vector product and exterior product ([1], [3], [4]). Put

$$(2.1) \quad \Delta_r = | \underset{(r \text{ times})}{de, \dots, de}, \underset{(n-r-1 \text{ times})}{dx, \dots, dx}, e, x |.$$

Then

$$\begin{aligned} (-1)^{n-1} d\Delta_r &= | \underset{(r+1 \text{ times})}{de, \dots, de}, \underset{(n-r-1 \text{ times})}{dx, \dots, dx}, x | \\ &\quad - | \underset{(r \text{ times})}{de, \dots, de}, \underset{(n-r \text{ times})}{dx, \dots, dx}, e | \end{aligned}$$

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Using (1.1) and straight computation we have

$$|de, \dots, de, dx, \dots, dx, x| = -n! K_{r+1}e \, dV$$

(r+1 times) (n-r-1 times)

and

$$|de, \dots, de, dx, \dots, dx, e| = n! K_r x \, dV$$

(r times) (n-r times)

where $dV = \omega_1 \wedge \dots \wedge \omega_n$ is the volume element in M^n and K_r is the r th mean curvature of M^n in S^{n+1} defined by the elementary symmetric functions of k_1, \dots, k_n as follows:

$$\binom{n}{r} K_r = \sum_{j_1 < \dots < j_r} k_{j_1} k_{j_2} \dots k_{j_r} \quad (1 \leq r \leq n).$$

Thus

$$(2.2) \quad d\Delta_r = (-1)^n n! (K_{r+1}e + K_r x) \, dV,$$

and by Stokes' theorem we have

$$(2.3) \quad \int_{M^n} (K_{r+1}e + K_r x) \, dV = 0, \quad r = 1, 2, \dots, n-1.$$

This integral formula (2.3) has been obtained by Reilly [5].

3. Substituting (1.1) in the right side of (2.1) yields [1]

$$(3.1) \quad \Delta_r = (-1)^{n+1} r! (n-r-1)! \sum_{i=0}^r (-1)^i \binom{n}{r-i} K_{r-i} *U_i$$

where $*$ is the Hodge star operation and

$$U_i \stackrel{\text{def}}{=} \sum_j (k_j)^i \omega_j e_j,$$

$$*U_i = \sum_j (-1)^{j-1} (k_j)^i \omega_1 \wedge \dots \wedge \hat{\omega}_j \wedge \dots \wedge \omega_n e_j,$$

$i=0, 1, \dots, n$. Using (3.1) to calculate $d\Delta_r$, we have

$$d\Delta_r = (-1)^{n+1} r! (n-r-1)! \left[\binom{n}{r} dK_r \wedge *dx + \binom{n}{r} K_r d(*dx) + \sum_{i=1}^r (-1)^i \binom{n}{r-i} d(K_{r-i} *U_i) \right].$$

It is easy to show that

$$dK_r \wedge *dx = \nabla K_r \, dV,$$

$$d(*dx) = -n(K_1 e + x) \, dV.$$

Hence we have

$$(3.2) \quad d\Delta_r = (-1)^{n+1}r!(n-r-1)! \cdot \left[\binom{n}{r} \nabla K_r dV - n \binom{n}{r} K_1 K_r e dV - n \binom{n}{r} K_r x dV + \sum_{i=1}^r (-1)^i \binom{n}{r-i} d(K_{r-i} * U_i) \right].$$

On the other hand by (3.1) and (2.2) we obtain

$$dx \cdot \Delta_r = (-1)^{n+1}r!(n-r-1)! \sum_{i=0}^r \left[(-1)^i \binom{n}{r-i} K_{r-i} \sum_j (k_j)^i \right] dV, \\ x \cdot d\Delta_r = (-1)^n n! K_r dV.$$

From $x \cdot \Delta_r = 0$ it follows $0 = d(x \cdot \Delta_r) = dx \cdot \Delta_r + x \cdot d\Delta_r$, and hence

$$(3.3) \quad r \binom{n}{r} K_r - \sum_{i=1}^r (-1)^i \binom{n}{r-i} K_{r-i} \sum_j (k_j)^i = 0.$$

This is the well-known identity of Newton.

Since $d(K_r * dx) = \nabla K_r dV - n K_r (K_1 e + x) dV$, one obtains by the Stokes' theorem

$$\int_{M^n} [\nabla K_r - n K_r (K_1 e + x)] dV = 0.$$

Together with (2.3) we have the following theorem.

THEOREM. *Let M^n be a compact oriented hypersurface in S^{n+1} , K_r be the r th mean curvature of M^n in S^{n+1} , e be the unit normal of M^n in S^{n+1} . Then*

$$(3.4) \quad \int_{M^n} \nabla K_r dV = n \int_{M^n} (K_r K_1 - K_{r+1}) e dV.$$

4. The following are some applications of the theorem.

COROLLARY 1. *In the theorem suppose, furthermore, that there is a fixed vector a in E^{n+2} such that the function $a \cdot e$ is of the same sign on M^n , $K_i > 0$ for $i=1, \dots, r$, $1 \leq r \leq n-1$, and K_r is constant. Then M^n is a hypersphere in S^{n+1} .*

PROOF. Under the assumption we have that $K_r K_1 - K_{r+1} = 0$. The same argument as in [4, p. 731] yields $k_1 = k_2 = \dots = k_n$ at all points of M^n . Hence M^n is a hypersphere in S^{n+1} .

COROLLARY 2. *In the theorem suppose, furthermore, that M^n is minimal in S^{n+1} and that there is a fixed vector a in E^{n+2} such that the function $a \cdot e$ is of the same sign on M^n . Then M^n is totally geodesic.*

PROOF. By the assumptions and (3.4) it implies that $K_1=K_2=0$. So $k_i=0$ ($i=1, 2, \dots, n$) and M^n is totally geodesic. This result is known [2, p. 33].

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