

ZERO-ONE LAWS FOR STABLE MEASURES

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ABSTRACT. For any stable measure μ on a vector space, every measurable linear subspace has measure 0 or 1.

1. **Introduction.** It is known that for any Gaussian probability measure, a linear subspace has measure 0 or 1. This result has been extended to additive subgroups by Kallianpur [2]. Here we extend the zero-one law in a different direction, replacing "Gaussian" by "stable". We begin with some definitions.

Definition. Let S be a vector space over \mathbf{R} and let \mathcal{S} be a σ -algebra of subsets of S . We call (S, \mathcal{S}) a *measurable vector space* iff both the following hold:

(a) addition is jointly measurable from $S \times S$ into S ,

(b) scalar multiplication is jointly measurable from $\mathbf{R} \times S$ into S , for completed Lebesgue measure λ on \mathbf{R} .

Let S be a topological vector space and let \mathcal{T} be the σ -algebra of Borel sets (generated by the open sets). Then if S is metrizable and separable, (S, \mathcal{T}) is a measurable vector space, but it need not be so in general.

If (S, \mathcal{S}) is a measurable vector space and μ and ν are finite, countably additive measures on \mathcal{S} , then we have the convolution $\mu * \nu$ defined as usual by

$$(\mu * \nu)(A) = (\mu \times \nu) \{ \langle x, y \rangle : x + y \in A \}.$$

For any (S -valued) random-variable Z , let its probability distribution (law), defined on \mathcal{S} , be denoted by $\mathcal{L}(Z)$.

Given any vector space S and $c \in \mathbf{R}$, let $m_c(x) \equiv cx$ for all $x \in S$, and $\theta_s(x) = x + s$ for any $s \in S$.

Definition. Given a measurable vector space (S, \mathcal{S}) , a probability

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measure μ on \mathcal{S} will be called *stable* iff for any $A > 0$ and $B > 0$, and independent random variables X and Y with distribution μ , there is a $C > 0$ and an $s \in S$ such that

$$(1) \quad \begin{aligned} \mathcal{L}(C(A X + B Y) + s) &= \mu, \quad \text{i.e.} \\ [(\mu \circ m_A^{-1}) * (\mu \circ m_B^{-1})] \circ m_C^{-1} &= \mu \circ \theta_{-s}^{-1}. \end{aligned}$$

Definition. We say μ is *strictly stable* if we can always take $s = 0$ in (1). We call μ *symmetric* iff $\mu(-E) = \mu(E)$ for all $E \in \mathcal{S}$. We say μ is *stable of index γ* if we can always take $C = C_\gamma(A, B) \equiv (A^\gamma + B^\gamma)^{-1/\gamma}$.

A random variable will be called *stable* iff its distribution is stable, and likewise for symmetry, strict stability, and the index.

The zero-one law (Theorem 6 and corollary) and its proof depend only on the above definitions. The following material, however, will help to clarify the meaning of stability in infinite-dimensional spaces.

If $S = \mathbf{R}$, then, as is well known (cf. Loève [4, pp. 326–328]) every stable μ has some index $\gamma \in (0, 2]$, and the characteristic functions of stable laws of index γ are of the form $e^{\phi(u)}$ where

$$(2) \quad \begin{aligned} \phi(u) &= i\alpha u - b|u|^\gamma \{1 + ic(\text{sgn } u)\tan(\pi\gamma/2)\}, & \gamma \neq 1; \\ &= i\alpha u - b|u| \{1 + ic(\text{sgn } u)2\pi^{-1}\log|u|\}, & \gamma = 1, \end{aligned}$$

where $\alpha \in \mathbf{R}$, $b > 0$, $|c| \leq 1$, $\gamma \in (0, 2]$.

Simple calculations show that a stable μ with characteristic function having logarithm (2) is strictly stable iff $\alpha = 0$ for $\gamma \neq 1$, while for $\gamma = 1$ we have instead $c = 0$. Also, μ is symmetric iff $\alpha = c = 0$. μ has a finite mean iff $\gamma > 1$ (Feller [1, Vol. II., Theorem 1, p. 576]). Then the mean is 0 iff μ is strictly stable. Thus a strictly stable law may be called *centered* stable.

Theorem 1. Let (S, \mathcal{S}) be a measurable vector space and μ a symmetric stable measure on it. Then $\mu \circ \theta_{2s}^{-1} = \mu$ for every s appearing in (1).

Before proving this we note that in many cases it implies $s = 0$, i.e. μ is strictly stable. For example if S is a complete separable metric linear space and \mathcal{S} is the Borel sets, s must be 0. To prove that every symmetric stable μ is strictly stable it would suffice to show that $\mu \circ \theta_{2s}^{-1} = \mu$ implies $\mu \circ \theta_s^{-1} = \mu$, but we do not know whether this is true in general.

If \mathcal{S} is a “degenerate” σ -algebra, e.g. if it is the smallest σ -algebra for which one linear form ϕ is measurable, and S is more than one-dimensional, there exist $s \neq 0$ and μ such that $\mu \circ \theta_{us}^{-1} = \mu$ for all $u \in \mathbf{R}$.

Proof. Suppose (1) holds for some s . Then in the notation of the definition of stability, and letting $\mathcal{L}(Z)$ denote the distribution of Z , we have

$$\mathcal{L}(X - s) = \mathcal{L}(C(AX + BY)) = \mathcal{L}(-C(AX + BY)) = \mathcal{L}(-X + s) = \mathcal{L}(X + s),$$

so the conclusion follows.

If μ is a stable law on a measurable vector space (S, \mathfrak{S}) and ϕ is an \mathfrak{S} -measurable linear form on S , then $\mu \circ \phi^{-1}$ is clearly stable on \mathbf{R} . If μ has index γ , so does $\mu \circ \phi^{-1}$. If μ is strictly stable or symmetric, $\mu \circ \phi^{-1}$ has the same property.

It is known that on a complete metric linear space, any Borel measurable or even universally measurable linear form is continuous (theorems of Banach and Douady; cf. L. Schwartz [5, Lemme 2]). There exist such spaces, e.g. $L^p([0, 1], \lambda)$ for $0 \leq p < 1$, without any nonzero continuous linear forms, hence without nonzero measurable linear forms. On the other hand if X_n are independent strictly stable real random variables of the same index γ and f_n are functions in L^p with $\int |f_n|^p d\lambda \rightarrow 0$ fast enough as $n \rightarrow \infty$, then $\sum X_n f_n$ almost surely converges to an L^p -valued random variable whose distribution is clearly strictly stable of index γ . Thus stable measures on infinite dimensional spaces cannot always be treated in terms of characteristic functions nor measurable linear forms.

2. Linear forms. Let S be a real vector space and T a vector space of linear forms on S . Let $\mathfrak{S}(T)$ be the smallest σ -algebra for which all members of T are measurable.

Theorem 2. *Let S be a vector space and F a vector space of linear forms on S . Then $(S, \mathfrak{S}(F))$ is a measurable vector space.*

Let μ be a probability measure on $\mathfrak{S}(F)$. Then μ is strictly stable iff $\mu \circ t^{-1}$ is strictly stable for all $t \in F$.

Proof. To show that $(S, \mathfrak{S}(F))$ is a measurable vector space it is enough to show that for each $f \in F$, the maps $\langle s, t \rangle \rightarrow f(s + t)$ and $\langle x, s \rangle \rightarrow f(xs)$ are jointly measurable, which they clearly are.

As to the stability part, "only if" is clear, as above. To prove "if", suppose each $\mu \circ t^{-1}$ is strictly stable on \mathbf{R} . Let $\gamma(t)$ denote the index of t , i.e. $\mu \circ t^{-1}$. This is uniquely determined unless $\mu \circ t^{-1}$ is an atom at 0, and then t is stable of every index; we define $\gamma(t) = 2$ in this case.

For any $d \in (0, 2]$ let $F_d = \{t \in F : \gamma(t) \geq d\}$. Clearly $\gamma(t) = \gamma(ut)$ for any real $u \neq 0$. Hence if $t \in F_d$ then $ut \in F_d$ for all real u .

Suppose $t \in F_d$ and $\tau \in F_d$. Let X_1, X_2, \dots be independent with distribution μ , and $S_n = X_1 + \dots + X_n$. Then $\mathcal{L}(t(S_n)/n^{1/\gamma(t)}) = \mathcal{L}(t(X_1))$, and likewise for τ .

For any $\delta < d$, we have $(t + \tau)(S_n)/n^{1/\delta} \rightarrow 0$ in probability as $n \rightarrow \infty$. Thus either $\gamma(t + \tau) \geq d$ or $t + \tau = 0$ a.s. (μ), in which case we have set $\gamma(t + \tau) = 2 \geq d$. Hence F_d is a linear subspace of F .

For any two-dimensional subspace A of F , $\gamma_A \equiv \{\gamma(t) : t \neq 0, t \in A\}$ contains at most two points, since otherwise for some $t, \tau \in A$, $\gamma(t + \tau) < \gamma(t) < \gamma(\tau)$, contradicting the above for $d = \gamma(t)$.

Further, if γ_A contains two points $\delta < \kappa$, we can only have $\gamma = \kappa$ on a 1-dimensional subspace $B = F_\kappa \cap A$ of A . Let $t \in B, t \neq 0$, and $t(n) \in A \sim B, t(n) \rightarrow t$ in the usual topology of a plane. Then for any $u \in \mathbf{R}$,

$$\lim_{n \rightarrow \infty} |E e^{iut(n)}|^2 = |E e^{iut}|^2.$$

From (2) above we get

$$|E e^{iut(n)}|^2 = \exp(-c(n)|u|^\delta)$$

for some $c(n) > 0$, so we must have $c(n) \rightarrow 0$ and $t = 0$ a.s. (μ).

Since any two points of F belong to some two-dimensional space, it follows that for some $\gamma \in (0, 2]$, all $t \in F$ are strictly stable of index γ ; this includes the possibility $t = 0$ a.s.

Now we show μ is strictly stable of index γ .

Let $C = C_\gamma(A, B)$ and $\nu = \mathcal{L}(C(AX + BY))$ in (1). Since every t is strictly stable of index γ , we have $\nu \circ t^{-1} = \mu \circ t^{-1}$, and hence $\int e^{it} d\nu = \int e^{it} d\mu$.

By the uniqueness theorem for characteristic functions on finite-dimensional vector spaces, the joint distribution of any finite set $(t_1, \dots, t_n) \subset F$ is the same for ν as for μ . Now since ν and μ are defined on $\mathcal{S}(F)$, they are equal, i.e. (1) holds. Q.E.D.

Theorem 3. *Let S be a vector space and F a vector space of linear forms on S , and μ a probability measure on $\mathcal{S}(F)$. Then μ is symmetric iff $\mu \circ t^{-1}$ is symmetric for all $t \in F$; also μ is symmetric and stable iff $\mu \circ t^{-1}$ is symmetric and stable for all $t \in F$.*

Proof. This is an easy application of the previous theorem and method of proof. \square

Definition. Given a real vector space S and a vector space F of linear forms on S , we say (S, F) is a full pair iff every real linear form ϕ on F can be written $\phi(f) \equiv f(s)$ for some $s = s_\phi \in S$.

An example of a full pair is (\mathbf{R}^T, F) where \mathbf{R}^T is the set of all real-valued functions on a set T and F is the set of finite linear combinations of coordinate evaluations.

Theorem 4. *Suppose (S, F) is a full pair and μ is a probability measure on $(S, \mathfrak{S}(F))$ such that $\mu \circ f^{-1}$ is stable for all $f \in F$. Then μ is stable of some index $\gamma \in (0, 2]$, and if $\gamma \neq 1$ there is a unique $t \in S$ such that $\mu \circ \theta_t^{-1}$ is strictly stable.*

Proof. Let $\mu^-(E) \equiv \mu(-E)$ and let $\nu = \mu * \mu^-$. Then for every $f \in F$, $\nu \circ f^{-1}$ is symmetrically stable. Thus by Theorems 2 and 3, ν is symmetric and strictly stable of some index $\gamma \in (0, 2]$. It follows that for each $f \in F$, $\mu \circ f^{-1}$ is stable of index γ .

For each $f \in F$ there is some real number $k(f)$ such that if X and Y are independent with distribution μ , then for $C = C_\gamma(A, B)$,

$$(3) \quad \mathfrak{L}(f(C[AX + BY]) + k(f)) = \mathfrak{L}(f(X)).$$

Since a Borel probability measure on \mathbf{R} cannot equal a translate of itself, $k(\cdot)$ must be a linear form on F . By fullness there is some $s = s(A, B) \in S$ such that $k(f) = f(s)$ for all $f \in F$. As in the previous proof, it follows using characteristic functions that (1) holds, so μ is stable.

Now suppose $\gamma \neq 1$. For any $f \in F$, there is some unique number α such that $f(X) + \alpha$ is strictly stable, by the characterization of strictly stable laws in (2). If we let $t = 2^{1/\gamma}s(1, 1)/(2 - 2^{1/\gamma})$, then we must have $\alpha = f(t)$ by (1) with $A = B = 1$. Hence $f(X + t)$ is strictly stable. Thus by Theorem 2, $\mu \circ \theta_t^{-1}$ is strictly stable. Q.E.D.

If (S, F) is not a full pair, then at any rate there is a topology $\mathfrak{J}(S)$ on F such that (F, \mathfrak{J}) is a topological vector space and a linear form ϕ on F is \mathfrak{J} -continuous iff $\phi(f) \equiv f(s)$ for some $s \in S$. The weakest such topology is the weakest topology making each $f \rightarrow f(s)$ continuous; there may be others, as with infinite-dimensional Banach spaces and their duals.

Now let f_n be a sequence such that $f_n \rightarrow 0$ for \mathfrak{J} . Then $f_n \rightarrow 0$ pointwise on S , so in (3) we must have $k(f_n) \rightarrow 0$. Hence k is sequentially \mathfrak{J} -continuous.

Definition. We call (S, F) a *semifull pair* iff every sequentially $\mathfrak{J}(S)$ -continuous linear form on F is of the form $f \rightarrow f(s)$ for some $s \in S$.

For examples of semifull pairs, let (F, \mathfrak{U}) be any metrizable linear space and S the dual space of all continuous linear forms on F .

Theorem 5. = *Theorem 4 with "full" replaced by "semifull".*

3. The zero-one law for linear subspaces.

Lemma 1. *Let μ be a strictly stable measure on (S, \mathfrak{S}) . Let E be a μ completion measurable linear subspace of S . Let $E' = \{x | x \in S, E - x/r \text{ is}$*

μ completion measurable for all rational numbers $r > 0$. Then E' is completion measurable and $\mu(E') = 1$.

Proof. For every rational $r > 0$, there is a positive real number $t(r)$ such that $\mu \circ \mu \circ m_r^{-1} = \mu \circ m_{t(r)}^{-1}$ by (1). Now $E/t(r) = E$ is μ measurable, hence E is $\mu \circ m_{t(r)}^{-1}$ measurable. So for every r , \exists sets F_r, G_r in \mathcal{S} with $F_r \subset E \subset G_r$ and $\mu \circ m_{t(r)}^{-1}(G_r \sim F_r) = 0$. Let $F = \bigcup F_r, G = \bigcap G_r$, then we still have $\mu \circ m_{t(r)}^{-1}(G \sim F) = 0$ for all r .

We can write

$$\begin{aligned} \mu \circ m_{t(r)}^{-1}(G \sim F) &= \int_S \mu \circ m_r^{-1}((G - x) \sim (F - x))d\mu(x) \\ &= \int_S \mu((G/r - x/r) \sim (F/r - x/r))d\mu(x). \end{aligned}$$

Let $C_{r,x} = (G/r - x/r) \sim (F/r - x/r)$. It follows that for all $r, \mu\{x | \mu(C_{r,x}) = 0\} = 1$. Define $E'' = \{x | \mu(C_{r,x}) = 0 \text{ for all rational } r\}$ and conclude that E'' is in \mathcal{S} and $\mu(E'') = 1$. However, since $F/r - x/r \subset E/r - x/r \subset G/r - x/r$, we conclude that $E'' \subset E'$ and that E' is μ completion measurable with $\mu(E') = 1$. Q.E.D.

Definition. If μ is strictly stable, we shall say that μ is well behaved if for all $\alpha \in (0, 1)$ there is a $\beta \in (0, 1)$ with

$$(4) \quad (\mu \circ m_\alpha^{-1}) * (\mu \circ m_\beta^{-1}) = \mu.$$

It is easy to show that if μ is strictly stable of index γ then it is well behaved.

Theorem 6. Let μ be strictly stable and well behaved. Let E be a linear subspace of S , measurable for the completion of μ . Then $\mu(E) = 0$ or 1.

Proof. Suppose $\mu(E) > 0$. Take α and β so that (4) is satisfied with α rational. Let E' be defined as in the last lemma. Suppose $x \in E' \sim E$ with $\mu(E - x) > 0$. Then

$$\begin{aligned} \mu(E - \alpha x) &= [(\mu \circ m_\alpha^{-1}) * (\mu \circ m_\beta^{-1})](E - \alpha x) \\ &\geq (\mu \circ m_\alpha^{-1})(E - \alpha x)(\mu \circ m_\beta^{-1})(E) = \mu(E - x)\mu(E) > 0. \end{aligned}$$

So the cosets $E - \alpha x$ are all disjoint with measure bounded away from zero, as α ranges over the rationals. This is a contradiction so we conclude that $\mu(E - x) = 0$ for $x \in E' \sim E$.

Now take $A > 0$ and take $C = C(A, A)$ so that (1) holds with $A = B$. Letting $\delta = AC$, we have that (4) holds with $\alpha = \beta = \delta$. We compute

$$\mu(E) = (\mu \circ m_\delta^{-1}) * (\mu \circ m_\delta^{-1})(E).$$

By arguing as in the preceding lemma we can conclude that $E - x$ is $\mu \circ m_\delta^{-1}$ completion measurable for $\mu \circ m_\delta^{-1}$ almost all x and we can write

$$\begin{aligned} \mu(E) &= \int_S \mu((E - \delta x)/\delta) d\mu(x) \\ &= \int_E \mu(E - x) d\mu(x) = \int_E \mu(E - x) d\mu(x) = \mu(E)^2. \end{aligned}$$

Thus, $\mu(E) = 0$ or 1 . Q.E.D.

Corollary. *If E is a linear subspace of S with $E \in \mathcal{S}$, then for any stable measure μ we have $\mu(E) = 0$ or 1 .*

Proof. Define the measure $\bar{\mu}$ by setting $\bar{\mu}(G) = \mu(-G)$ for $G \in \mathcal{S}$. Define ν , the symmetrization of μ , by $\nu = \mu * \bar{\mu}$. It is clear that ν is strictly stable since for all $A, B > 0$, $\bar{\mu}$ satisfies (1) with $-s$ substituted for s . Now $\nu(E) \geq \mu(E)^2$. If $\mu(E) > 0 < \nu(E + x)$, $x \notin E$, let $T = \{\alpha: \nu(E + \alpha x) \geq \nu(E)\nu(E + x) > 0\}$. Then for any A, B, C in (1), CA and CB are in T as in Theorem 6. Thus the set of ratios of elements of T is infinite and so is T . So we conclude that $\nu(E) = 1$ as in the end of Theorem 6. But

$$\nu(E) = \int \mu(E + x) d\mu(x).$$

It follows that $\mu(E + x) = 1$ for μ almost all x in S . In particular $\mu(E + x) = 1$ for at least one x in E since $\mu(E) > 0$. Now $E = E + x$ for x in E , so $\mu(E) = 1$. Q.E.D.

We can extend Theorem 6 to sets E in \mathcal{S} which are only assumed to be rational linear subspaces of S (i.e., if $x, y \in E$ then $rx + sy \in E$ for any rational r, s).

Theorem 7. *Suppose μ is stable of index γ , where γ is rational. If E is an \mathcal{S} measurable rational linear subspace of S , then $\mu(E) = 0$ or $\mu(E) = 1$.*

Proof. By arguing as in the corollary to Theorem 6, we are reduced to considering the case when μ is symmetric and strictly stable. We assume $\gamma = p/q$ where p and q are integers. By Waring's theorem [3, p. 37] there exists a positive integer k such that any positive integer b can be written in the form $b = a_1^p + \dots + a_k^p$, where a_1, \dots, a_k are nonnegative integers. Now consider the equation

$$(5) \quad a^p = (a - 1)^p + a_1^p + \dots + a_k^p.$$

For any positive integer a , (5) has a positive solution in integers a_i . We define $r_0 = (a - 1/a)^q$, $r_1 = (a_1/a)^q$, \dots , $r_k = (a_k/a)^q$ and we let $F(a) = \sum_0^k r_i$. We conclude that $F(a) \rightarrow 1$ as a goes to infinity and hence the equation

$$(6) \quad 1 = r_0^\gamma + r_1^\gamma + \dots + r_k^\gamma$$

has infinitely many rational solutions and $\sum_0^k r_i$ can assume infinitely many values (unless $\gamma = 1$; then proceed as in Theorem 6).

Now $\mu = \mu \circ m_{r_0}^{-1} * \dots * \mu \circ m_{r_k}^{-1}$ for any solution of (6) and we compute

$$\begin{aligned} \mu(E + (r_0 + \dots + r_k)x) &\geq (\mu \circ m_{r_0}^{-1}(E + r_0x)) \dots (\mu \circ m_{r_k}^{-1}(E + r_kx)) \\ &= (\mu(E + x))^{k+1}. \end{aligned}$$

If x is not in E and $\mu(E + x) > 0$, this leads to a contradiction, so we conclude $\mu(E + x) = 0$ for all $x \notin E$. The same reasoning shows that $\mu \circ m_\alpha^{-1}(E + x) = 0$ for all $x \notin E$ and α rational.

Let now $\alpha > 0, \beta > 0, \theta > 0$ be real with $\alpha^\gamma + \beta^\gamma = \theta^\gamma$ and α rational. We claim that

$$(7) \quad \mu \circ m_\alpha^{-1}(E) \mu \circ m_\beta^{-1}(E) = \mu \circ m_\theta^{-1}(E).$$

This will follow if we show that the $(\mu \circ m_\alpha^{-1}) \times (\mu \circ m_\beta^{-1})$ product measure of the set $\{(x, y) | x \notin E, y \notin E, x + y \in E\}$ is 0. However, this product measure equals $\int_{E^c} \mu \circ m_\alpha^{-1}(E - y) d\mu \circ m_\beta^{-1}(y)$, which clearly is zero by the foregoing.

Now let r_1, \dots, r_k be any rational solution of (6) and define θ_j by $r_1^\gamma + \dots + r_j^\gamma = \theta_j^\gamma$ for all $1 \leq j \leq k$. We have

$$\mu \circ m_{\theta_2}^{-1}(E) = \mu \circ m_{r_1}^{-1}(E) \mu \circ m_{r_2}^{-1}(E).$$

Proceeding inductively by using (7), we conclude $\mu(E) = \prod_{1 \leq j \leq k} \mu \circ m_{r_j}^{-1}(E)$. However, $\mu(E) = \mu \circ m_{r_j}^{-1}(E)$ for all j so we conclude $\mu(E) = 0$ or 1. Q.E.D.

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