

## A FINITE VERSION OF SCHUR'S THEOREM

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ABSTRACT. A necessary and sufficient condition for constancy of curvature in terms of umbilicity of small metric spheres is given.

The following is a remark on a paper of Kowalski in which he has investigated the "properties of hypersurfaces which are characteristic for spaces of constant curvature" and papers of Nomizu [3] and Nomizu and Leung [4]. This type of investigation goes back to Schur [5]. For other results of this type we refer to Cartan [1, Chapter V].

We follow the terminology of Kowalski [2]. By a 'metric sphere' in a Riemann manifold  $M$  we understand a subset consisting of points at a fixed distance from a fixed point. If the fixed distance is sufficiently small the metric sphere is a smooth hypersurface. Kowalski [2, Theorem 8] shows that if every sufficiently small metric sphere in  $M$  is totally umbilic and  $\dim M \geq 4$ , then  $M$  is conformally euclidean. We shall improve this result as follows:

**Theorem.** *Let  $M$  be a connected  $C^\infty$  Riemann manifold of dimension  $\geq 3$ . Then every sufficiently small metric sphere is totally umbilic iff  $M$  is of constant curvature.*

Total umbilicity of metric spheres is, roughly speaking, a finite version of the infinitesimal isotropy condition in Schur's well-known theorem: namely if  $M$  is a connected Riemann manifold of dimension  $\geq 3$  such that the sectional curvature depends only on the point (and not on the 2-plane section at the point) then the curvature is actually constant. For this reason we have referred to the above theorem as a finite version of Schur's theorem.

**Proof of the theorem.** First of all note that a space of constant curvature (without any dimension restrictions) has the stated property, cf. e.g., [2, Proposition 5]. (Alternately note that the property is "visibly" true in the Euclidean case, and since umbilicity is a conformally invariant notion, the property also holds in the spherical and hyperbolic cases.)

Let us now prove the converse. Suppose that every small hypersphere of  $M$  is totally umbilic. Fix a point  $P$  and a unit tangent vector  $e_1$  at  $p$ . Let  $\gamma$  be geodesic through  $p$  tangential to  $e_1$ . Choose a point  $q$  on  $\gamma$ ,  $q \neq p$ ,

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sufficiently close to  $p$  so that the hypersphere centered at  $q$  and passing through  $p$  is contained in a normal coordinate neighborhood around  $q$ . Now choose a moving frame  $\{e_1 \dots e_m\}$  in a neighborhood of  $p$  so that  $e_1$  is tangential to geodesics through  $q$ . Let  $\{\omega_1, \dots, \omega_m\}$  be the corresponding dual forms. They satisfy the structure equations

$$(1) \quad d\omega_a = \sum_{b=1}^m \omega_{ab}\omega_b, \quad d\omega_{ab} = \sum_{c=1}^m \omega_{ac}\omega_{cb} + \Omega_{ab}, \quad \omega_{ab} + \omega_{ba} = 0.$$

We have  $\omega_1 = dr$  where  $r$  is the radial parameter measured from  $q$ . Hence  $0 = d\omega_1 = \sum_{a=2}^m \omega_{1a}\omega_a$ . It follows that  $\omega_{1a}$  is a linear combination of  $\omega_2, \dots, \omega_m$  only. On the other hand,  $\omega_{1a}$  define the second fundamental forms of metric spheres centered at  $q$ ; hence by the total umbilicity of the metric spheres they must be of the form  $\omega_{1a} = \lambda\omega_a + \mu_a\omega_1$ , where  $\lambda, \mu_a$  are smooth functions. Combining these two observations we see that  $\mu_a = 0$  and so

$$\omega_{1a} = \lambda\omega_a.$$

Taking the exterior derivative and using the structure equations, we have

$$\begin{aligned} d\omega_{1a} &= d\lambda\omega_a + \lambda\omega_{a1}\omega_1 + \sum_{b \geq 2} \lambda\omega_{ab}\omega_b \\ &= \sum_{b \geq 2} \omega_{1b}\omega_{ba} + \Omega_{1a} = \lambda \sum_{b \geq 2} \omega_{ab}\omega_b + \Omega_{1a}. \end{aligned}$$

Consequently

$$\Omega_{1a} = d\lambda\omega_a + \lambda\omega_1\omega_{1a} = (\partial\lambda/\partial r + \lambda^2)\omega_1\omega_a + \text{other terms.}$$

This shows that at  $p$  the sectional curvature of the 2-plane spanned by  $e_1$  and  $e_a$  is  $-(\partial\lambda/\partial r + \lambda^2)$ . Since this expression is independent of  $a$ , it follows that the sectional curvature of the 2-plane containing  $e_1$  is the same. Since  $e_1$  is arbitrary, we see that all sectional curvatures at  $p$  are the same. If  $\dim M \geq 3$ , by the Schur theorem it follows that  $M$  is of constant curvature. A further use of Codazzi's equation implies that  $\lambda$  is in fact constant on a metric sphere. Q.E.D.

**Remark.** The above theorem, just as the Schur's theorem, of course, breaks down when  $\dim M = 2$ ; in fact any curve on a 2-dimensional manifold is trivially totally umbilic. In this case we can restore the theorem by making a stronger hypothesis.

**Theorem.** *Let  $M$  be a 2-dimensional connected Riemann manifold such that every sufficiently small metric sphere is of constant geodesic curvature; then  $M$  is of constant curvature.*

(In Kowalski's terminology constancy of geodesic curvature of a metric sphere is the same as a metric sphere being a  $U$ -sphere. So this theorem is

a partial improvement of [2, Theorem 3]. Converse of course is true and trivial.)

**Proof.** In the above notation, constancy of geodesic curvature means that the function  $\lambda$  is constant on metric spheres—hence it is a function of  $r$ . So the sectional curvature  $-(d\lambda/dr + \lambda^2)$  is constant (say  $c$ ) on a metric sphere (say  $s$ ). Now considering the metric spheres with centers on  $S$ , and continuing this way, we see that the set of points where the sectional curvature is  $c$  is open and closed. Since  $M$  is connected, it must be of constant curvature. Q.E.D.

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