

HOMOTOPY EQUIVALENCES IN EQUIVARIANT TOPOLOGY

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ABSTRACT. Homomorphisms up to homotopy (higher homotopies that is) are generalized for the equivariant category. Homotopy equivalences have an inverse in this new category.

Introduction. In equivariant topology the notion of a homotopy equivalence presents a problem. Strictly within the equivariant category, homotopy equivalence seems to be too limited a concept,¹ e.g. the unit interval I (acting on itself as an H -space) is not of the same equivariant homotopy type as $\{1\}$ as a $\{1\}$ -space.

Some of the rather general tools used in homotopy theory of topological groups and H -spaces (e.g. studying classifying spaces) can also be used in equivariant homotopy theory. In this paper we use G_∞ -maps between G -spaces (as defined in 1.4, and similar to H_∞ -maps between H -spaces) to study a new notion of homotopy equivalence. Roughly speaking, if X and \bar{X} are G -spaces and if $f: X \rightarrow \bar{X}$ is a G -equivariant map and also an ordinary homotopy equivalence, then there exists a sequence of maps $g_n: \bar{X} \times (I \times G)^n \rightarrow X$ forming a G_∞ -map such that f and the maps $\{g_n\}$ form a pair of G_∞ -homotopy equivalences.

The complete theorem is stated in §2. The proof includes the proof of the corresponding theorem on H -spaces as stated in [2, Theorem 4.1] or in [1] as Proposition 1.17. We hope to convince the reader that this proof is not as messy as it is described by the authors of [1] on p. 13.

1. Definitions.

DEFINITION 1.1. An H -space G is a topological space with a continuous multiplication μ . We assume that μ is strictly associative. No unit element is needed.

DEFINITION 1.2. A topological space X is called a G -space, if G acts on X in a continuous and in an associative manner.

Multiplication and actions will be denoted by the usual juxtaposition.

DEFINITION 1.3. An H_∞ -map \underline{h} from G to \bar{G} of length r^2 is a sequence of continuous maps $h_n: G \times (I_r \times G)^n \rightarrow \bar{G}$ such that

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¹ C. N. Lee, A. Wasserman (see [5]), and T. Petrie have relatively simple examples of pairs of manifolds X and Y with S^1 -actions and an S^1 -map $f: X \rightarrow Y$ such that f is an ordinary homotopy equivalence. But there is no equivariant map $g: Y \rightarrow X$ which is a homotopy equivalence.

² We will mention the length of maps only if it is essential to the context.

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$$\begin{aligned}
 &h_n(g_0, t_1, \dots, t_n, g_n) \\
 &= \begin{cases} h_{n-1}(g_0, t_1, \dots, g_{i-1}g_i, \dots, t_n, g_n), & t_i = 0, \\ h_{i-1}(g_0, t_1, \dots, g_{i-1})h_{n-i}(g_i, \dots, g_n), & t_i = r, \end{cases} \quad n \geq 0,
 \end{aligned}$$

where $g_0, \dots, g_n \in G$ and $t_1, \dots, t_n \in I_r = [0, r] \subset \mathbf{R}$. If $r = 0$, the map h_0 is an ordinary homomorphism.

DEFINITION 1.4. Let X be a G -space, \bar{X} be a \bar{G} -space and let \underline{h} be an H_∞ -map from G to \bar{G} of length r . A G_∞ -map \underline{f} from X to \bar{X} of length r associated to \underline{h} is a sequence of maps $f_n: X \times (I_r \times G)^n \rightarrow \bar{X}$ such that

$$\begin{aligned}
 &f_n(x, t_1, g_1, \dots, t_n, g_n) \\
 &= \begin{cases} f_{n-1}(x, t_1, \dots, g_{i-1}g_i, \dots, t_n, g_n), & t_i = 0, \\ f_{i-1}(x, t_1, g_1, \dots, g_{i-1})h_{n-i}(g_i, \dots, t_n, g_n), & t_i = r, \end{cases} \quad n \geq 0.
 \end{aligned}$$

If $t_1 = 0$ we want of course

$$f_n(x, 0, g_1, t_2, \dots, g_n) = f_{n-1}(xg_1, t_2, \dots, g_n).$$

So G_∞ -maps formally differ from H_∞ -maps only in the first coordinate.

Composition of G_∞ -maps is defined the same way as for H_∞ -maps. If $n = 1$

$$(\bar{f} \circ \underline{f})_1(x, t_1, g_1) = \begin{cases} \bar{f}_0(f_1(x, t_1, g_1)), & 0 \leq t_1 \leq r, \\ \bar{f}_1(f_0(x), t_1 - r, h_0(y)), & r \leq t_1 \leq r + s, \end{cases}$$

which is the standard composition of homotopies. If $n > 1$ we have to form the composite of 2^n maps, each of which is defined on one of the 2^n rectangular boxes obtained from I_{r+s}^n by partitioning it with the hyperplanes $t_i = r$.

DEFINITION 1.5. Let X_1 be a G_1 -space, X_2 a G_2 -space, and X_3 a G_3 -space. Let \underline{h} be an H_∞ -map of length r from G_1 and G_2 and \bar{h} an H_∞ -map of length s from G_2 to G_3 . Also let \underline{f} be a G_∞ -map of length r from X_1 to X_2 associated to \underline{h} , and let \bar{f} be a G_∞ -map of length s from X_2 to X_3 associated to \bar{h} . We define $(\bar{f} \circ \underline{f})_n: X_1 \times (I_{r+s} \times G_1)^n \rightarrow X_3$ by

$$\begin{aligned}
 &(\bar{f} \circ \underline{f})_n(x, t_1, g_1, \dots, t_n, g_n) \\
 &= \bar{f}_j(f_{i_1}(x, t_1, g_1, \dots, t_{i_1}, g_{i_1}), t_{i_1+1} - r, h_{i_2-i_1-1}(\dots), \dots, \\
 &\qquad\qquad\qquad t_{i_j+1} - r, h_{n-i_j-1}(g_{i_j+1}, \dots, t_n, g_n)).
 \end{aligned}$$

Here $x \in X_1, g_i \in G_1$, and for every sequence of natural numbers $0 \leq i_1 < \dots < i_j < n$ ($j = 1, \dots, n$) we have $t_{i_1+1}, \dots, t_{i_j+1} \in [r, r + s]$, while $t_i \in [0, r]$ whenever $i - 1 \neq i_1, \dots, i_j$.

Composition formulas for H_∞ -maps can also be found in [2], [3] and [4].

We leave it to the reader to verify that the maps $\{(\bar{f} \circ \underline{f})_n\}$ form a G_∞ -maps associated to $\{(\bar{h} \circ \underline{h})_n\}$. The composition of G_∞ -maps is associative and together with the G -spaces they form a category.

DEFINITION 1.6. Let \underline{h}^0 and \underline{h}^1 be H_∞ -maps from G to \bar{G} , and let f^0 and f^1 be G_∞ -maps from X to \bar{X} associated to \underline{h}^0 and \underline{h}^1 respectively. If \underline{h}' ($0 \leq t \leq 1$) is a family of H_∞ -maps constituting an H_∞ -homotopy between

\underline{h}^0 and \underline{h}^1 , then a family \underline{f}^t ($0 \leq t \leq 1$) of G_∞ -maps from X to \bar{X} associated with \underline{h}^t is called a G_∞ -homotopy between \underline{f}^0 and \underline{f}^1 .

DEFINITION 1.7. A G_∞ -map \underline{f} from X to \bar{X} associated with the H_∞ -map \underline{h} from G to \bar{G} is called a G_∞ -homotopy equivalence if there exists an H_∞ -map \bar{h} from \bar{G} to G and a G_∞ -map \bar{f} from \bar{X} to X such that the respective compositions are G_∞ -homotopic (and H_∞ -homotopic respectively) to id_X and $\text{id}_{\bar{X}}$ associated to id_G and $\text{id}_{\bar{G}}$ respectively. The G_∞ -map \bar{f} associated with \bar{h} is called a homotopy inverse of \underline{f} associated with \underline{h} .

2. Theorems and proofs.

THEOREM. Let X be a G -space and \bar{X} be a \bar{G} -space. If \underline{h} is an H_∞ -map from G to \bar{G} such that h_0 is an ordinary homotopy equivalence, and if \underline{f} is a G_∞ -map from X to \bar{X} associated with \underline{h} such that f_0 is an ordinary homotopy equivalence, then \underline{f} is a G_∞ -homotopy equivalence.

REMARK. We construct both an inverse \bar{h} to \underline{h} and an inverse \bar{f} to \underline{f} associated with \bar{h} . However, the construction of \bar{f} works for any inverse of \underline{h} , and also for every homotopy inverse of f_0 .

Two special cases are of importance.

COROLLARY. If X and \bar{X} are G -spaces and $f: X \rightarrow \bar{X}$ is a G -equivariant map as well as an ordinary homotopy equivalence, then f is a G_∞ -homotopy equivalence associated to 1_G .

COROLLARY. If H and \bar{H} are H -spaces and $h: H \rightarrow \bar{H}$ is a strict homomorphism (or an H_∞ -map) as well as an ordinary homotopy equivalence, then h is an H_∞ -homotopy equivalence (see [2, Theorem 4.1] and [1]).

The second corollary is obtained by choosing $X = H$ and $\bar{X} = \bar{H}$.

PROOF. We will construct an H_∞ -map $\bar{h}: \bar{G} \rightarrow G$ which is an H_∞ -homotopy inverse to \underline{h} , and a G_∞ -map $\bar{f}: \bar{X} \rightarrow X$ associated to \bar{h} which is a G_∞ -homotopy inverse to \underline{f} . The construction is by induction.

$n = 0$: Let $f_0: \bar{X} \rightarrow X$ be an ordinary homotopy inverse to f_0 and $k_0: X \times I \rightarrow X$ be such that

$$k_0(x, t) = \begin{cases} x & \text{for } t = 0, \\ \bar{f}_0 f_0(x) & \text{for } t = 1, \end{cases} \quad x \in X.$$

Then, since f_0 and \bar{f}_0 induce isomorphisms on the relevant homotopy classes of maps (compare e.g. [2, p. 205]) we can choose $\bar{k}_0: \bar{X} \times I \rightarrow \bar{X}$ such that

$$\bar{k}_0(\bar{x}, t) = \begin{cases} \bar{x} & \text{for } t = 0, \\ f_0 \bar{f}_0(\bar{x}) & \text{for } t = 1 \end{cases}$$

in such a manner that there exists a map $u_0: X \times I^2 \rightarrow \bar{X}$ with

$$\begin{aligned} u_0(x, 0, s_2) &= f_0 k_0(x, s_2), \\ u_0(x, 1, s_2) &= \bar{k}_0(f_0(x), s_2), \end{aligned} \quad s_2 \in I, x \in X,$$

and

$$\begin{aligned}
 u_0(x, s_1, 1) &= f_0 \bar{f}_0 f_0(x) && \text{for all } s_1 \in I, x \in X. \\
 u_0(x, s_1, 0) &= f_0(x)
 \end{aligned}$$

We will call \bar{f}_0 together with (k_0, \bar{k}_0) and u_0 a compatible homotopy inverse to f_0 .

Similarly we choose a compatible homotopy inverse \bar{h}_0 together with homotopies (l_0, \bar{l}_0) and v_0 for the map h_0 (compare [2, p. 205]). We notice that this second choice is independent of the choice of \bar{f}_0 .

INDUCTION HYPOTHESIS. Assume we already constructed $(\bar{f}_0, \dots, \bar{f}_{n-1})$ as the first n functions of a G_∞ -homotopy inverse for f associated with $(\bar{h}_0, \dots, \bar{h}_{n-1})$, the n functions of an H_∞ -homotopy inverse of h . Furthermore assume that we constructed these functions as compatible inverses to (f_0, \dots, f_{n-1}) and (h_0, \dots, h_{n-1}) . For convenience sake we assume that all maps of f and h have length one. Also $\bar{f}_0, \dots, \bar{f}_{n-1}$ and $\bar{h}_0, \dots, \bar{h}_{n-1}$ are assumed to have length one. The homotopies $k_0, \dots, k_{n-1}, \bar{k}_0, \dots, \bar{k}_{n-1}, l_0, \dots, l_{n-1}$ and $\bar{l}_0, \dots, \bar{l}_{n-1}$ are to be of length two. The maps u_0, \dots, u_{n-1} and v_0, \dots, v_{n-1} are to have length three. These last maps shall satisfy the obvious boundary conditions as described in 1.3 and 1.4, in addition to the compatibility conditions.

Now we will construct $u_n: X \times (I_3 \times G)^n \times I^2 \rightarrow \bar{X}$. (The maps \bar{f}_n, k_n and \bar{k}_n will be defined in the process of this construction.) For our construction by induction u_n shall have the following properties.

$$(1) \quad u_n | X \times (I_3 \times G)^n \times I \times \{0\} = (\bar{e}_1 \circ f \circ e_1)_n \times \text{id}_I.$$

Here e_1 and \bar{e}_1 stands for the identity morphism of X and \bar{X} respectively with length 1. We observe that this part of u_n is already known.

$$(2) \quad u_n | X \times (I_3 \times G)^n \times I \times \{1\} = (f \circ \bar{f} \circ f)_n \times \text{id}_I.$$

The composition $(f \circ \bar{f} \circ f)_n$ contains the map \bar{f}_n only if $1 \leq t_i \leq 2$ (for $i = 1, \dots, n$). For these values of t_i we have

$$(f \circ \bar{f} \circ f)_n(x, t_1, g_1, \dots, g_n) = f_0 \bar{f}_n(f_0(x), t_1, h_0(g_1), \dots, t_n, h_0(g_n)).$$

The rest of $(f \circ \bar{f} \circ f)_n$ uses \bar{f}_k with $1 \leq k < n$. Because of this and the boundary properties of \bar{f}_n we know this part of u_n except when $1 < t_i < 2, i = 1, \dots, n$.

$$(3) \quad u_n | X \times (I_3 \times G)^n \times \{0\} \times I = (\bar{e}_{1-s_2} \circ f \circ k_{1+s_2})_n.$$

\bar{e}_{1-s_2} stands for the identity morphism of \bar{X} with length $1 - s_2$, and k_{1+s_2} stands for the homotopy k with length $1 + s_2$, where s_2 is the second coordinate of $I \times I$. From the composition rule for G_∞ -maps we see that this restriction of u_n is known except for $1 < t_i < 2$ when $s_2 = 1$, and $2 - s_2 < t_i < 3$ when $0 < s_2 < 1$ ($i = 1, \dots, n$), i.e. when

$$\begin{aligned}
 &u_n(x, t_1, g_1, \dots, t_n, g_n, 0, s_2) \\
 &= \begin{cases} f_0 \bar{f}_n(f_0(x), t_1, h_0(g_1), \dots, t_n, h_n(g_n)), & s_2 = 1, \\ f_0 k_{1+s_2, n}(x, t_1, \dots, t_n, g_n, s_2), & 0 < s_2 < 1. \end{cases}
 \end{aligned}$$

$$(4) \quad u_n|X \times (I_3 \times G)^n \times \{1\} \times I = (\bar{k}_{1+s_2} \circ f \circ e_{1-s_2})_n$$

which is known except for $1 < t_i < 2$ when $s_2 = 1$, and $0 < t_i < 1 + s_2$ when $0 < s_2 < 1$, i.e. when

$$u_n(x, t_1, g_1, \dots, t_n, g_n, 1, s_2) = \begin{cases} f_0 \bar{f}_n(f_0(x), t_1, h_0(g_1), \dots, t_n, h_0(g_n)), & s_2 = 1, \\ \bar{k}_{1+s_2, n}(f_0(x), t_1, h_0(g_1), \dots, t_n, h_0(g_n)), & 0 < s_2 < 1. \end{cases}$$

(5) $u_n|X \times \partial(I_3 \times G)^n \times I^2$ is defined by u_0, \dots, u_{n-1} and v_0, \dots, v_{n-1} according to the properties of G_∞ - and H_∞ -maps as described in 1.3 and 1.4. Hence this part of u_n is known.

To find all of u_n , we are going to use the following consequence of the homotopy extension property:

LEMMA. *If $A \subset X$ has the homotopy extension property and if $r: Y_1 \hookrightarrow Y_2: s$ are homotopy equivalences, then if $f_1: A \rightarrow Y_1$ is a map such that $r \circ f_1$ has an extension $g_2: X \rightarrow Y_2$, we know that f_1 has an extension $g_1: X \rightarrow Y_1$ by the homotopy extension property.*

We observe that the extension problem resulting from (3) is homeomorphic to extending a map, which is known on all of $Y \times \partial I^{n+1}$ with the exception of one face of $Y \times I^{n+1}$, to all of $Y \times I^{n+1}$. We extend, and use the lemma to obtain $K_{1+s_2}: X \times (I_{1+s_2} \times G)^n \times \{0\} \times I \rightarrow X$. For $s_2 = 1$ we see that K_{1+s_2} provides an extension of $\bar{f}_n \circ f_0$ from $X \times \partial([1, 2] \times G)^n$ to $X \times ([1, 2] \times G)^n$. To obtain the extension of $\partial \bar{f}_n: \bar{X} \times \partial([1, 2] \times \bar{G})^n \rightarrow X$ we use the following

LEMMA. *Given a homotopy equivalence $a: A \rightarrow \bar{A}$ a map $\partial c: \bar{A} \times \partial I^n \rightarrow \bar{B}$, and a map $w: A \times I^n \rightarrow \bar{B}$ that extends $\partial c(a \times 1)$, then ∂c extends to a map $c: \bar{A} \times I^n \rightarrow \bar{B}$ such that $c(a \times 1)$ is homotopic to w keeping the boundary fixed.*

Since on $X \times \partial([1, 2] \times G)^n \times \{1\} \times \{1\}$ we have

$$K_{1+s_2}(x, t_1, g_1, \dots, t_n, g_n, 1, 1) = \bar{f}_n(f_0(x), t_1, h_0(g_1), \dots, t_n, h_0(g_n)),$$

we obtain that $K_{1+s_2}|X \times ([1, 2] \times G)^n \times \{1\} \times \{1\}$ is homotopic to $\bar{f}_n \circ f_0 \times (1 \times h_0)^n$ relative to the boundary $X \times \partial([1, 2] \times G)^n \times \{1\} \times \{1\}$. We combine K_{1+s_2} with such a homotopy to obtain k_{1+s_2} , with $k_{1+s_2}|X \times ([1, 2] \times G)^n \times \{1\} \times \{1\} = \bar{f}_n \circ f_0 \times (1 \times h_0)^n$.

We now know u_n except on $X \times (I_3 \times G)^n \times I^2$ and the part of $X \times (I_3 \times G)^n \times \{1\} \times I$ with $0 < t_i < 1 + s_2$ and $0 < s_2 < 1$. This extension problem is homeomorphic to the problem of extending a map which is known on all of $Y \times \partial I^{n+2}$ with the exception of one face to all of $Y \times I^{n+2}$. Let U_n be such an extension. We have to use the second lemma once more to obtain \bar{k}_{1+s_2} . Again $\bar{k}_{1+s_2, n}(f_0 \times 1_I \times h_0 \times \dots \times h_0)$ is homotopic to the right restriction of U_n leaving the boundary fixed. We alter U_n by this homotopy and obtain u_n .

The construction of v_n, \bar{h}_n, l_n , and \bar{l}_n is completely analogous and is left to the reader.

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