

## A MAXIMUM PRINCIPLE FOR COMPRESSIBLE FLOW ON A SURFACE

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**ABSTRACT.** We show that the speed of a steady, irrotational, subsonic flow on a surface cannot attain its maximum at a point of positive Gauss curvature.

In his work on curvature and homology, Bochner [3] obtained a formula for the Laplacian of the norm of a harmonic form on an orientable Riemannian manifold in terms of the curvature of the manifold. In this paper we obtain a corresponding formula for  $\rho$ -harmonic forms which describe compressible flows and will use this result to show that a steady, irrotational subsonic fluid flow on a surface cannot attain its maximum speed at a point of positive Gaussian curvature.

**1. Compressible flows on a surface.** In the representation of a steady flow on an orientable surface  $M$  by a differential 1-form  $\omega = \omega_1 dx + \omega_2 dy$ , the requirement that the flow be irrotational (no circulation about curves homologous to zero) is expressed by the first order differential equation  $d\omega = 0$  when  $d$  is the exterior derivative. One says that the form is closed and this is equivalent to the existence locally of a single valued potential function. The requirement of conservation of mass leads to a second first order equation  $\delta(\rho\omega) = 0$  where  $\delta$  is the adjoint of  $d$  and  $\rho$  is the density. We shall recall the explicit expressions for these partial differential operators in §3 and only remark here that  $\delta$ , unlike  $d$ , depends on the Riemannian metric  $g_{ij}$  which we assume given on  $M$ .

We have called [5] a form  $\omega$  satisfying the system

$$d\omega = 0, \quad \delta\rho\omega = 0, \quad (1)$$

a  $\rho$ -harmonic form. If  $\rho$  is constant then the flow is incompressible and the system (1) simply expresses the well-known fact that an incompressible flow is described by a harmonic form.

**2. Subsonic flows.** Letting  $\langle \omega, v \rangle = g^{ij}\omega_i v_j$  denote the (pointwise) inner product induced by the Riemannian metric, we refer, for convenience, to the square of the norm  $Q = \langle \omega, \omega \rangle$  as the *speed* of the flow. From physical considerations we make the rather general assumptions (cf. [1]) that the density  $\rho$  of the fluid is a function of  $Q$  alone which is bounded above and

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below by positive constants and is such that the “mass velocity” is an increasing function of the speed for speeds below some critical speed. Specifically, in terms of  $Q$ , this is expressed by

$$\frac{d}{dQ} (\rho^2 Q) > 0 \quad \text{for } Q < Q_s, \quad (2a)$$

$$\frac{d}{dQ} (\rho^2 Q) \rightarrow 0 \quad \text{as } Q \nearrow Q_s. \quad (2b)$$

The quantity  $Q_s$  is called the *sonic speed*. At each point the flow (and the form representing it) is said to be *subsonic*, *sonic* or *supersonic* according as  $Q(\omega) < Q_s$ ,  $Q(\omega) = Q_s$  or  $Q(\omega) > Q_s$ .

Global existence, uniqueness and regularity questions for subsonic flows on compact manifolds and on compact manifolds with boundary have been discussed in other work [5], [7].

Generally speaking, as the “data” increases, the maximum speed attained by a subsonic flow increases towards the sonic speed  $Q_s$ . The location of the point(s) where the maximum speed is attained is thus clearly of some interest. In particular, given a (smooth) subsonic flow on a surface, one can ask whether there are differential geometric restrictions on the locations of points where the flow can attain its maximum speed. In what follows, we will verify a conjecture, made in [6] that the *maximum speed of a subsonic compressible flow cannot be attained at an interior point of positive Gaussian curvature*.

**3. The fundamental formula.** In terms of covariant derivatives  $\nabla_i$  we can write explicit local expressions for  $d$  and  $\delta$ . Since we deal only with manifolds of dimension 2, we need only describe their action on functions  $f$ , 1-forms  $\zeta = \zeta_i dx^i$  and 2-forms  $\Phi = \varphi_{ij} dx^i \wedge dx^j$  ( $i, j = 1, 2$ ).

$$df = \nabla_i f dx^i = \frac{\partial f}{\partial x^i} dx^i, \quad d\zeta = -\frac{1}{2} (\nabla_j \zeta_i - \nabla_i \zeta_j) dx^i \wedge dx^j, \quad d\Phi = 0, \quad (3a)$$

$$\delta f = 0, \quad \delta\zeta = -g^{ij} \nabla_i \zeta_j, \quad \delta\Phi = -g^{ij} \nabla_i \varphi_{jk} dx^k. \quad (3b)$$

Recall also that the Laplace-Beltrami operator (on functions or forms) is defined by

$$\Delta = d\delta + \delta d. \quad (3c)$$

Applied to functions, this can be written

$$\Delta f = -g^{jk} \nabla_k \nabla_j f = -\frac{1}{\sqrt{g}} \frac{\partial}{\partial x^i} \left( \sqrt{g} g^{ij} \frac{\partial f}{\partial x^j} \right) \quad \text{where } g = \det g_{ij}. \quad (3d)$$

For a form which is not necessarily harmonic, a modification of Bochner’s formula can be obtained as follows.

Since  $Q = g^{ab} \zeta_a \zeta_b$ , a direct computation yields

$$\begin{aligned} \Delta Q &= -g^{ij} \nabla_i \nabla_j Q = -g^{ij} \nabla_i (2g^{ab} \zeta_a \nabla_j \zeta_b) \\ &= -2g^{ij} g^{ab} (\nabla_i \zeta_a) (\nabla_j \zeta_b) - 2g^{ij} g^{ab} \zeta_a \nabla_i \nabla_j \zeta_b. \end{aligned}$$

Writing  $|\nabla \zeta|$  for the norm (induced by the Riemannian metric) of the tensor

$\nabla_k \zeta_l$  we obtain

$$-\frac{1}{2} \Delta Q = |\nabla \zeta|^2 + g^{ij} g^{ab} \zeta_a \nabla_i \nabla_j \zeta_b. \tag{4}$$

On the other hand,

$$\Delta \zeta = d\delta \zeta + \delta d\zeta = -g^{ij} \nabla_i \nabla_j \zeta_b dx^b + g^{kj} (\nabla_k \nabla_b \zeta_j - \nabla_b \nabla_k \zeta_j) dx^b$$

which, by the Ricci identity, can be written in terms of the Gaussian curvature  $K$

$$\Delta \zeta = -g^{ij} \nabla_i \nabla_j \zeta_b dx^b + K \zeta_b dx^b$$

so that

$$\langle \Delta \zeta, \zeta \rangle = -g^{ab} \zeta_a g^{ij} \nabla_i \nabla_j \zeta_b + K \langle \zeta, \zeta \rangle. \tag{5}$$

Combining (4) and (5) we obtain finally

$$-\frac{1}{2} \Delta Q(\zeta) + \langle \Delta \zeta, \zeta \rangle = |\nabla \zeta|^2 + KQ. \tag{6}$$

**4. The speed of a compressible flow.** If (6) is applied to a form  $\zeta = \rho\omega$ , where  $\rho = \rho(Q(\omega))$ , and it is observed that  $Q(\rho\omega) = \rho^2 Q(\omega) = \rho^2 Q$ , we obtain

$$-\frac{1}{2} \Delta \rho^2 Q + \langle \Delta \rho\omega, \rho\omega \rangle = |\nabla \rho\omega|^2 + \rho^2 KQ. \tag{7}$$

We now express the left-hand side of (7) as an operator on  $Q$ .

Writing  $-\frac{1}{2} \Delta \rho^2 Q = -\frac{1}{2}(\rho^2 + 2\rho\rho'Q)\Delta Q + a_0(x, y)Q_x + b_0(x, y)Q_y = L_1 Q$  we observe that the positivity of the term in parentheses is precisely the condition (2a) that the flow be subsonic. Consequently, for such a flow  $L_1$  is uniformly elliptic.

Assuming now that  $\omega$  is  $\rho$ -harmonic and using (1) we can write  $\Delta \rho\omega = \delta d\rho\omega = \delta(\rho' dQ \wedge \omega)$ . Assuming further that we have chosen isothermal coordinates, so that  $g_{ij} = \lambda \delta_{ij}$ , we have

$$\begin{aligned} \Delta \rho\omega &= \delta([\rho'\omega_2 Q_x - \rho'\omega_1 Q_y] dx dy) \\ &= \left[ \left( \frac{\rho'\omega_2}{\lambda} Q_x \right)_y - \left( \frac{\rho'\omega_1}{\lambda} Q_y \right)_y \right] dx + \left[ \left( \frac{\rho'\omega_1}{\lambda} Q_y \right)_x - \left( \frac{\rho'\omega_2}{\lambda} Q_x \right)_x \right] dy \\ &= \left[ \frac{\rho'\omega_2}{\lambda} Q_{xy} - \frac{\rho'\omega_1}{\lambda} Q_{yy} + a_1 Q_x + b_1 Q_y \right] dx \\ &\quad + \left[ \frac{\rho'\omega_1}{\lambda} Q_{yx} - \frac{\rho'\omega_2}{\lambda} Q_{xx} + a_2 Q_x + b_2 Q_y \right] dy \end{aligned}$$

where (for a fixed form  $\omega$ ) the coefficients  $a_i$  and  $b_i$  are functions of  $x$  and  $y$ . We have then

$$\begin{aligned} \langle \Delta \rho\omega, \rho\omega \rangle &= -\frac{\rho\rho'}{\lambda^2} [\omega_2^2 Q_{xx} - 2\omega_1\omega_2 Q_{xy} + \omega_1^2 Q_{yy}] \\ &\quad + a(x, y)Q_x + b(x, y)Q_y \\ &= L_2 Q. \end{aligned}$$

In order to investigate the ellipticity of the operator  $L = L_1 + L_2$  we

distinguish the two cases  $\rho'(Q) \leq 0$  and  $\rho'(Q) > 0$ . In the former case (which is the more interesting physically) it is immediately seen that  $L_2$  is degenerate elliptic and since  $L_1$  is uniformly elliptic it follows that  $L$  is uniformly elliptic. If, on the other hand,  $\rho' > 0$  we write

$$\begin{aligned} L_1 Q &= -\frac{1}{2} \rho^2 \Delta Q - \rho \rho' Q \Delta Q \\ &= -\frac{1}{2} \rho^2 \Delta Q + \rho \rho' [\lambda^{-1}(\omega_1^2 + \omega_2^2)] [\lambda^{-1}(Q_{xx} + Q_{yy})]. \end{aligned}$$

Then the principal part of  $(L_1 + L_2)Q$  is

$$-\frac{1}{2} \rho^2 \Delta Q + \frac{\rho \rho'}{\lambda^2} (\omega_1^2 Q_{xx} + 2\omega_1 \omega_2 Q_{xy} + \omega_2^2 Q_{yy}).$$

The first term is uniformly elliptic and the second degenerate elliptic, so that again  $L$  is uniformly elliptic. In either case we have the

LEMMA 1. *The speed  $Q$  of a  $\rho$ -harmonic form  $\omega$  satisfies a second order partial differential equation*

$$LQ = |\nabla \rho \omega|^2 + \rho^2 KQ. \tag{8}$$

*If  $\omega$  is subsonic, then  $L$  is uniformly elliptic. If  $K \geq 0$  on an open set  $U$ , then  $Q$  is a subsolution ( $LQ \geq 0$ ) of  $L$  on  $U$ .*

The equation (8) is the  $\rho$ -harmonic analogue of Bochner's fundamental formula for harmonic forms.

LEMMA 2. *If  $Q \not\equiv 0$  for a subsonic  $\rho$ -harmonic form  $\omega$  on  $M$  then the interior zeros of  $Q$  are isolated.*

PROOF. Since  $\omega = 0$  if  $Q = 0$  at a point, we have locally (writing  $\omega = p dx + q dy$ ) that  $p = 0$  and  $q = 0$ . On the other hand, writing (1) as a homogeneous uniformly elliptic system for  $p$  and  $q$ , it follows from the Bers-Nirenberg representation theorem that the zeros of such a system are isolated [2].

**5. The maximum principle.** Our main result is the

THEOREM. *The speed  $Q$  of a steady, compressible, irrotational subsonic flow  $\omega$  on an orientable surface  $M$  cannot have a relative maximum at a point of positive Gaussian curvature unless the flow is identically zero on  $M$ . If a relative maximum is attained at a point  $P$  of an open set of zero curvature, then the maximum is attained on the closure of the largest open connected set  $\Omega$  of zero curvature which contains  $P$  and the flow is parallel in  $\Omega$ .*

PROOF. If  $Q$  has a relative maximum at a point of some open set  $U$  (assumed without loss of generality to lie in a single coordinate patch of  $M$ ) and  $K \geq 0$  on  $U$  then  $LQ \geq 0$  on  $U$  by Lemma 1. By the Hopf maximum principle [4]  $Q$  cannot have a maximum in  $U$  unless it is constant. If on the one hand,  $K > 0$  on  $U$  then by (8) one sees immediately that  $Q \equiv 0$  on  $U$  which, by Lemma 2, is possible only if  $Q \equiv 0$  on  $M$ . On the other hand, if  $K = 0$  on  $\Omega$  then, again from (8), one has  $\nabla_i \rho \omega_a = 0$ . But  $\nabla_i \rho \omega_a = \rho \nabla_i \omega_a +$

$\omega_a \rho' \nabla_i Q$  and since  $\nabla_i Q = 0$  on  $\Omega$  because  $Q$  is constant there, we obtain the condition  $\nabla_i \omega_a = 0$  that  $\omega$  describes a parallel flow in  $\Omega$ .

As suggested by the theorem, the set on which the speed attains a maximum (unlike the set on which  $Q$  vanishes) need not consist of isolated points. In this connection we state the

**COROLLARY 1.** *Suppose  $Q$  attains a nonzero maximum on a subset  $\Lambda$  of  $M$ . Then  $\Lambda$  cannot be contained in a neighborhood  $N$  of curvature  $K \geq 0$  unless, in fact,  $K = 0$  on  $N$ .*

**PROOF.** By Lemma 1,  $LQ \geq 0$  in  $N$ . Then by the above theorem  $Q =$  constant in  $N$  which is impossible if  $N$  contains a point of curvature  $K > 0$ . A special case of the theorem is the well-known

**COROLLARY 2.** *A subsonic plane flow past an obstacle attains its maximum speed on the boundary of the obstacle or at infinity.*

In fact, on any surface with boundary whose curvature  $K \geq 0$ , the maximum speed must be attained on the boundary.

**6. Examples.** (i) The standard torus in  $\mathbf{R}^3$  is given parametrically by  $x = (b + a \cos u) \cos v, y = (b + a \cos u) \sin v, z = a \sin u$  with  $0 < a < b$  and  $0 \leq u, v \leq 2\pi$ . Its metric tensor is  $g_{11} = a^2, g_{12} = g_{21} = 0, g_{22} = (b + a \cos u)^2$  so that  $\sqrt{g} = a(b + a \cos u)$ . If we prescribe circulation  $c$  around the  $z$  axis (a representative curve would be  $u = \text{constant}, 0 \leq v \leq 2\pi$ ) and zero circulation along a curve  $v = \text{constant}, 0 \leq u \leq 2\pi$ , then the results of [5] ensure the existence of a unique subsonic  $\rho$ -harmonic form as long as  $0 \leq c < c_\rho$  for some critical circulation  $c_\rho$ . The speed of the flow tends somewhere to sonic speed as  $c \nearrow c_\rho$ . It is easily checked in this example that the form  $\omega = cdv/2\pi$  is subsonic  $\rho$ -harmonic for  $c < c_\rho$  and has the prescribed circulation. Its speed is given by  $Q = c^2/4\pi^2(b + a \cos u)^2$  which attains its maximum at  $u = \pi$ , a circle at every point of which the Gaussian curvature is negative.

Although the results of §5 apply only to subsonic flows, in this example for  $c = c_\rho$  we obtain a flow which is subsonic everywhere except on the "inner" circle ( $u = \pi$ ) where it is sonic. If  $c$  is increased beyond  $c_\rho$  we first obtain a transonic flow with a region of supersonic flow bounded by sonic lines ( $u = \pi \pm \theta_\rho$ ) and eventually a flow which is completely supersonic. The maximum is always attained on the circle  $u = \pi$ .

(ii) Consider now the torus obtained by subjecting the upper half ( $z > 0$ ) of the standard torus to a vertical displacement and then connecting the two halves by right circular cylinders. As above, it is not difficult to write down the  $\rho$ -harmonic form on the surface thus obtained having the circulations prescribed in example (i). The maximum speed will now be attained on a two dimensional set—the inner cylinder.

**ADDED IN PROOF.** A more detailed analysis of these examples has been made and will appear in [8]. We consider there *any* axiallysymmetric torus

and arbitrary circulations. A complete family of solutions (subsonic, transonic and supersonic) is obtained.

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