

## THE SMITH INVARIANTS OF A MATRIX SUM

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**ABSTRACT.** A divisibility relation is proved relating the invariant factors of a sum of integral matrices.

Let  $R$  be a principal ideal domain, that is, a commutative ring without zero divisors in which every ideal is principal. Let  $A$  be a matrix over  $R$ . It is well known [1] that for the relation "equivalence of matrices," namely  $A \rightarrow UAV$  where  $U, V$  are invertible matrices over  $R$ , there exists a complete set of invariants, the *invariant factors* of  $A$ . If  $A$  is  $n \times n$ , its invariant factors are elements  $h_1(A), \dots, h_n(A)$  of  $R$  satisfying the divisibility conditions  $h_1(A) | \dots | h_n(A)$ . Very much, in fact, almost full information is now available [2] about the restrictions imposed upon the invariant factors of matrices  $A, B, C$  when it is required that  $C = AB$ . Nothing, however, seems to be known about the behavior of invariant factors when matrices are added, and the objective of this paper is to obtain a result along these lines.

**THEOREM 1.** *Let  $A, B, C = A + B$ , be matrices over  $R$ , with invariant factors*

$$h_1(A) | \dots | h_n(A), \quad h_1(B) | \dots | h_n(B), \quad h_1(C) | \dots | h_n(C),$$

*respectively. Let the invariant factors of*

$$D = \text{diag}(h_1(A), \dots, h_n(A), h_1(B), \dots, h_n(B))$$

*be  $h_1(D) | \dots | h_{2n}(D)$ . Then*

$$h_i(D) | h_i(C), \quad i = 1, \dots, n.$$

**PROOF.** Let  $D_A = \text{diag}(h_1(A), \dots, h_n(A))$ . Unimodular matrices  $U_1, U_2, V_1, V_2$  over  $R$  exist such that

$$A = U_1 D_A V_1, \quad B = U_2 D_B V_2.$$

Then the matrix

$$M = \begin{bmatrix} U_1 & U_2 \\ 0 & I \end{bmatrix} \begin{bmatrix} D_A & 0 \\ 0 & D_B \end{bmatrix} \begin{bmatrix} V_1 & 0 \\ V_2 & I \end{bmatrix} = \begin{bmatrix} C & \cdot \\ \cdot & \cdot \end{bmatrix}$$

is  $2n \times 2n$ , has the same invariant factors as  $D$  and has  $C$  as an  $n \times n$  submatrix. Now, a recent result of the author [3] asserts that invariant factors  $h_1(M) | h_2(M) | \dots$  of a matrix  $M$  and the invariant factors of a submatrix  $C$

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satisfy

$$h_i(M) | h_i(C), \quad i = 1, 2, \dots$$

Since here  $h_i(M) = h_i(D)$ , the proof is complete.

In fact, further information about invariant factors of submatrices is given in [3]. However, this additional information yields nothing in the present case, although it will yield additional information about the invariant factors of  $A, B, A + B$ , when  $A$  and  $B$  are rectangular matrices.

As an application of Theorem 1, we prove an explicit inequality relating the invariant factors of  $A, B, A + B$ .

**THEOREM 2.** *Let the invariant factors of  $A, B, C = A + B$ , be as defined in the statement of Theorem 1. Then*

$$\text{gcd}(h_i(A), h_j(B)) | h_{i+j-1}(A + B)$$

for any indices  $i, j$  with  $1 \leq i, j \leq n, i + j - 1 \leq n$ , where  $\text{gcd}$  denotes greatest common divisor.

**PROOF.** It suffices to prove that  $\text{gcd}(h_i(A), h_j(B)) | h_{i+j-1}(D)$ , and for this we may focus attention upon elementary divisors for one prime  $p$ , i.e., upon one prime factor  $p$  of  $h_n(A)h_n(B)$ . Let

$$p^{e_i} || h_i(A), p^{f_j} || h_j(B), p^{g_i} || h_i(D)$$

be the exact powers of  $p$  appearing in  $h_i(A), h_j(B), h_i(D)$ , respectively;  $e_1 \leq \dots \leq e_n, f_1 \leq \dots \leq f_n, g_1 \leq \dots \leq g_{2n}$ . The power on  $p$  in the  $t$ th determinantal divisor of  $D$  is then

$$g_1 + \dots + g_t = \min_{\substack{r,s \\ r+s=t}} (e_1 + \dots + e_r + f_1 + \dots + f_s). \tag{1}$$

We wish to prove that  $\min(e_i, f_j) \leq g_{i+j-1}$ . From (1) we certainly have

$$g_1 + \dots + g_{i+j-1} = e_1 + \dots + e_r + f_1 + \dots + f_s \tag{2}$$

for certain  $r, s$  with  $r + s = i + j - 1$ . We cannot have both  $r < i$  and  $s < j$ , so suppose  $s \geq j$ . Using (1) again, we have

$$g_1 + \dots + g_{i+j-2} \leq e_1 + \dots + e_r + f_1 + \dots + f_{s-1}. \tag{3}$$

Combining (2) and (3), we obtain  $g_{i+j-1} \geq f_s \geq f_j \geq \min(e_i, f_j)$ . The proof is complete.

In many instances, Theorem 2 gives no information since  $h_i(A), h_j(B)$  are often relatively prime. This, however, is not a failure of Theorem 2 because there are many instances in which the invariant factors of  $A + B$  can be quite arbitrary even when those of  $A$  and  $B$  are fixed. For example, if  $x|y$  and

$$A = \begin{bmatrix} 1 & x \\ 0 & 1 \end{bmatrix}, \quad B = \begin{bmatrix} -1 & 0 \\ y & -1 \end{bmatrix},$$

then  $h_1(A) = h_2(A) = 1, h_1(B) = h_2(B) = 1, h_1(C) = x, h_2(C) = y$ , with  $x, y$  quite arbitrary. However, Theorem 2 does cover nontrivially the following sort of situation: If prime  $p|h_1(A)$  and  $p|h_1(B)$  then  $p$  must divide each element of  $A$  and  $B$ , therefore also each element of  $C$ , and so  $p$  necessarily is a divisor of  $h_1(C)$ .

The subscript  $i + j - 1$  is the smallest for which Theorem 2 is true. Indeed, take  $R = Z$ , and set

$$A = I_{i-1} \dot{+} (2) \dot{+} 2I_{j-1} \dot{+} 2I_{n-i-j+1},$$

$$B = -2I_{i-1} \dot{+} (2) \dot{+} -I_{j-1} \dot{+} 2I_{n-1-j+1}$$

where  $I$  denotes an identity matrix and  $\dot{+}$  direct sum. Then  $h_i(A) = 2$ ,  $h_j(B) = 2$ , but  $h_{i+j-2}(C) = 1$ .

#### REFERENCES

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