SYSTEMS OF DIFFERENTIAL EQUATIONS SUBJECT TO MILD INTEGRAL CONDITIONS

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Abstract. It is shown that solutions of a system \( x' = f(t, x) \) approach constant vectors as \( t \to \infty \), under assumptions which do not require that \( \| f(t, x) \| \leq w(t, \| x \|) \), where \( w \) is nondecreasing in \( \| x \| \), and which permit some or all of the integral smallness conditions on \( f \) to be stated in terms of ordinary—rather than absolute—convergence. Estimates of the order of convergence are given.

Theorems which imply that solutions of a system

\[ (1) \quad x' = f(t, x) \]

approach constant vectors as \( t \to \infty \) are usually obtained by assuming that

\[ (2) \quad \| f(t, x) \| \leq w(t, \| x \|), \]

where \( w \) is decreasing in \( r \) for \( r > 0 \), and subject to some integral condition such as

\[ (3) \quad \int_{r}^{\infty} w(t, r) \, dt < \infty, \quad r \geq 0; \]

for examples, see [1, 4, 6]. Sometimes, instead of (3), it is required that the equation \( r' = w(t, r) \) have a bounded positive solution on some half-line \([t_0, \infty)\); for example, see [2]. Clearly, any integral condition like (3) requires absolute convergence, and there are systems for which no majorizing function \( w \) as in (2) is increasing in \( \| x \| \). Here we present results which do not require this kind of bound on \( f \), and are based on integral conditions involving ordinary—that is, not necessarily absolute—convergence of some of the improper integrals in question. Moreover, our results include information on the order of convergence of solutions of (1).

Throughout this paper the norm \( \| \| \) of a vector or matrix is the sum of the absolute values of its elements, and \( W \) and \( K \) are as in the following assumption. The motivation for this definition will become clear after the statement of the main theorem (Remark 1, below).

Assumption A. The \( n \times n \) matrix function \( W \) is continuously differentiable and invertible on \([T, \infty)\) for some \( T > 0 \), and

\[ (4) \quad \int_{t}^{\infty} \| W(t)(W^{-1}(s))'\| \, ds \leq K < \infty, \quad t \geq T. \]

Received by the editors January 18, 1982 and, in revised form, April 12, 1982; presented to the Society, March 17, 1982.

1980 Mathematics Subject Classification. Primary 34C11, 34D10.
Henceforth we assume that \( t > T \). Notice that

\[
\int_T^\infty \| (W^{-1}(s))' \| \, ds < \infty
\]

and so

\[
\lim_{t \to \infty} W^{-1}(t) \text{ exists (finite)},
\]

because of (4).

**Lemma 1.** If \( q \) is a continuous \( n \)-vector function on \([T, \infty)\) and \( \int_T^\infty W(t)q(t) \, dt \) converges, then \( \int_T^\infty q(t) \, dt \) converges, and

\[
\int_T^\infty W(t)q(t) \, dt = W^{-1}(t)p(t), \quad t > T,
\]

where

\[
\rho(t) = \sup_{t \to \infty} \| \int_T^\infty W(s)q(s) \, ds \|.
\]

**Proof.** With

\[
p(t) = \int_T^\infty W(s)q(s) \, ds,
\]

integration by parts yields

\[
\int_T^\infty q(s) \, ds = \int_T^\infty W^{-1}(s)W(s)q(s) \, ds = -W^{-1}(s)p(s) \bigg|_T^T + \int_T^\infty (W^{-1}(s))'p(s) \, ds.
\]

From (6), (8), and (9),

\[
\| (W^{-1}(s))' p(s) \| \leq \rho(T) \| (W^{-1}(s))' \|, \quad s \geq T,
\]

and \( \lim_{t \to \infty} W^{-1}(t)p(t) = 0 \); hence, because of (5), we can let \( t \to \infty \) in (10) and obtain

\[
\int_T^\infty q(s) \, ds = W^{-1}(t)p(t) + \int_T^\infty (W^{-1}(s))'p(s) \, ds.
\]

Multiplying by \( W(t) \) and invoking (4), (8), and (9) yields (7).

**Definition 1.** For \( T > 0 \), let \( H(T) \) he the Banach space of continuous \( n \)-vector functions \( h \) on \([T, \infty)\) such that \( Wh \) is bounded, with the norm

\[
N(T; h) = \sup_{t > T} \| W(t)h(t) \|.
\]

If \( M > 0 \), let

\[
H_M(T) = \{ h \in H(T) \mid N(T; h) \leq M \}.
\]

The following is our main theorem:

**Theorem 1.** For a given vector \( c \), suppose there are constants \( M > 0 \) and \( T_0 > 0 \) such that \( f \) is continuous on

\[
\Omega = \{ (t, x) \mid t \geq T_0, \| W(t)(x - c) \| < M \}.
\]
and the integral
\[ J(t; h) = \int_{t}^{\infty} W(s)f(s, c + h(s)) \, ds, \quad t \geq T, \]
converges if \( h \in H_M(T) \) and \( T \geq T_0 \). Suppose also that
\[ \|J(t; h_1) - J(t; h_2)\| \leq \delta N(T; h_1 - h_2), \quad t \geq T, \]
whenever
\[ h_1, h_2 \in H_M(T) \quad \text{with} \quad T \geq T_0, \]
where
\[ 0 < \delta < 1/(1 + K). \]
Then (1) has a solution \( x_0 \) which is defined for \( t \) sufficiently large and satisfies
\[ \lim_{t \to \infty} W(t)(x_0(t) - c) = 0; \]
moreover, if \( x_1 \) is any solution of (1) such that
\[ \lim_{t \to \infty} W(t)(x_1(t) - c) = 0, \]
then
\[ x_1(t) = x_2(t) \]
for \( t \) sufficiently large.

Remark 1. In our examples, \( W = \text{diag}[w_1, \ldots, w_n] \) with \( w_i > 0 \) and \( w'_i > 0 \), in which case (4) holds with \( K = n \), and (17) implies that the components of \( x_0 \) approach \( c \) at possibly different rates. We state and prove our theorems under the more general Assumption A because this does not complicate the proofs and the more general formulation may be useful in some applications.

Proof of Theorem 1. If \( h \in H_M(T) \) with \( T \geq T_0 \), then
\[ \|J(t; h)\| \leq \|J(t; h) - J(t; 0)\| + \|J(t; 0)\| \leq \delta M + \|J(t; 0)\|, \]
from (14) with \( h_1 = h \) and \( h_2 = 0 \). Now choose \( T_1 \geq T_0 \) so that
\[ \delta M + \sup_{t \geq T_1} \|J(t; 0)\| \leq M/(1 + K), \]
which is possible because of (16) and the convergence of \( J(t; 0) = \int_{t}^{\infty} W(s)f(s, c) \, ds \). From (20) and (21),
\[ \|J(t; h)\| \leq M/(1 + K) \quad \text{if} \quad t \geq T_1 \quad \text{and} \quad h \in B_M(T_1). \]
If \( h \in H_M(T_1) \), define \( \tilde{h} = \mathcal{F} h \) by
\[ \tilde{h}(t) = -\int_{t}^{\infty} f(s, c + h(s)) \, ds, \quad t \geq T_1. \]
From (13) and Lemma 1 with \( q(t) = f(t, c + h(t)) \), \( \tilde{h} \) is defined and satisfies the inequality
\[ \|W(t)\tilde{h}(t)\| \leq (1 + K)\sup_{h \geq t} \|J(t; h)\|, \quad t \geq T_1. \]
From this and (22), \( \|W(t)\tilde{h}(t)\| \leq M, \quad t \geq T_1 \). Therefore, \( \tilde{h} \in H_M(T_1) \); that is, \( \mathcal{F} \) transforms \( H_M(T_1) \) into itself.
Now suppose $h_i \in B_M(T_i)$ and $\hat{h}_i = \mathbb{S}_h h_i$ ($i = 1, 2$). Then Lemma 1 with 
\[ g(t) = f(t, c + h_1(t)) - f(t, c + h_2(t)) \]
implies that 
\[ \|W(t)(\hat{h}_1(t) - \hat{h}_2(t))\| \leq (1 + K)\|J(t; h_1) - J(t; h_2)\|, \quad t \geq T_1, \]
and so, from (11) and (14) (with $T = T_1$), 
\[ N(T_1; \hat{h}_1 - \hat{h}_2) \leq \delta(1 + K)N(T_1; h_1 - h_2). \]
Hence, from (16), $\mathbb{S}_h$ is a contraction mapping of $H_M(T_1)$ into itself, and therefore there is an $h_0$ in $H_M(T_1)$ such that $h_0 = \mathbb{S}_h h_0$; that is, 
\[ h_0(t) = -\int_t^\infty f(s, c + h_0(s))\, ds, \quad t \geq T_1. \]
From Lemma 1 with $q(t) = f(t, c + h_0(t))$, $\lim_{t \to \infty} W(t)h_0(t) = 0$. Therefore, the function $x_0 = c + h_0$ satisfies (1) and (17).

If $x_1$ satisfies (1) and (18), then $h_1 = x_1 - c$ is in $H_M(T_2)$ for some $T_2 \geq T_1$, and 
\[ h_1(t) - h_0(t) = \int_t^\infty \left[ f(s, c + h_0(s)) - f(s, c + h_1(s)) \right] \, ds, \quad t \geq T_2. \]
By an argument like that which led to (23), 
\[ N(T_2; h_1 - h_0) \leq \delta(1 + K)N(T_2; h_1 - h_0), \]
which implies that $h_1(t) = h_0(t)$ for $t \geq T_2$, because of (16). This implies (19) for $t \geq T_2$, and completes the proof.

We now apply Theorem 1 to the system 
\[ x' = A(t)\psi(x) + g(t), \quad t > 0. \]
First we need the following definition:

**Definition 2.** A vector $c$ is a Lipschitz point of a vector function $\psi$ if there are constants $\rho, \lambda > 0$ such that $\psi(x)$ is defined whenever 
\[ \|x - c\| \leq \rho \]
and 
\[ \|\psi(x_1) - \psi(x_2)\| \leq \lambda\|x_1 - x_2\| \]
if $\|x_i - c\| \leq \rho, i = 1, 2$.

**Theorem 2.** Suppose $A$ is an $n \times m$ matrix function and $g$ is an $n$-vector function, both continuous on $[0, \infty)$, and $c$ is a Lipschitz point of the $m$-vector function $\psi$. Suppose also that 
\[ \int_0^\infty W(t)\left[ A(t)\psi(c) + g(t) \right] \, dt \]
converges and 
\[ \int_0^\infty \|W(t)A(t)\| \|W^{-1}(t)\| \, dt < \infty. \]
Then the conclusions of Theorem 1 hold for (24).
Proof. Let
\begin{equation}
\sigma = \sup_{t > T} \|W^{-1}(t)\|,
\end{equation}
which is finite because of (6). Let \( \delta \) be any number that satisfies (16), let \( \lambda \) be as in (26), and choose \( T_0 \) so that
\begin{equation}
\int_{T_0}^{\infty} \|W(s)A(s)\| \|W^{-1}(s)\| \, ds \leq \frac{\delta}{\lambda},
\end{equation}
which is possible because of (28). Henceforth, let \( t \geq T_0 \). Finally, let
\begin{equation}
M = \rho / \sigma,
\end{equation}
with \( \rho \) as in (25). We will show that \( T_0 \) and \( M \) satisfy the requirements of Theorem 1, for
\begin{equation}
f(t, x) = A(t)\psi(x) + g(t).
\end{equation}
We must first show that \( f \) is continuous on \( \Omega \) as defined in (12). If \( (t, x) \in \Omega \), then
\begin{equation}
\|x - c\| \leq \|W^{-1}(t)\| \|W(t)(x - c)\| \leq \sigma M = \rho,
\end{equation}
because of (29) and (31). Since \( \rho \) is continuous for all \( x \) satisfying (25), while \( A \) and \( g \) are continuous on \([0, \infty)\), it follows that \( f \) is continuous on \( \Omega \), and \( f(t, c + h(t)) \) is continuous on \([T, \infty)\) if \( h \in H_{\infty}(T) \) with \( T \geq T_0 \). Moreover, if (15) holds, then
\begin{align*}
\|\psi(c + h_1(t)) - \psi(c + h_2(t))\| &\leq \lambda \|h_1(t) - h_2(t)\| \\
&\leq \lambda \|W^{-1}(t)\| \|W(t)(h_1(t) - h_2(t))\| \\
&\leq \lambda \|W^{-1}(t)\| N(T; h_1 - h_2),
\end{align*}
where we have used (11) and (26). This and (30) imply that
\begin{equation}
\int_{T}^{\infty} W(s)A(s)[\psi(c + h_1(s)) - \psi(c + h_2(s))] \, ds \leq \delta N(T; h_1 - h_2),
\end{equation}
\( t \geq T \).

With \( f \) as in (32), the functional \( J \) in (13) becomes
\begin{equation}
J(t; h) = \int_{t}^{\infty} W(s)[A(s)\psi(c + h(s)) + g(s)] \, ds.
\end{equation}
From the convergence of (27), \( J(t; 0) \) exists. This and the convergence of the integral in (33) with \( h_1 = h \) and \( h_2 = 0 \) imply that \( J(t; h) \) exists for all \( h \in H_{\infty}(T) \), if \( t \geq T \geq T_0 \). Knowing this, we can conclude from (33) that (14) holds whenever (15) does. This completes the proof of Theorem 2.

Stronger results are available for a linear system
\begin{equation}
x' = A(t)x + g(t), \quad t > 0.
\end{equation}
We omit the proof of the following theorem, which is similar to that of Theorem 2.

Theorem 3. Suppose the \( n \times n \) matrix function \( A \) and the \( n \)-vector function \( g \) are continuous on \([0, \infty)\),
\begin{equation}
\int_{t}^{\infty} \|W(t)A(t)W^{-1}(t)\| \, dt < \infty,
\end{equation}
and

\[ \int_0^\infty W(t)[A(t)c + g(t)] \, dt \]

converges for a given constant vector \( c \). Then (34) has a unique solution \( x_0 \) which satisfies (17).

The next theorem follows easily from this and elementary properties of linear systems.

**Theorem 4.** Suppose \( A \) and \( g \) are continuous on \([0, \infty)\), (35) holds, and \( \int_0^\infty W(t)A(t) \, dt \) and \( \int_0^\infty W(t)g(t) \, dt \) converge. Then (34) has a unique solution which satisfies (17) for any given constant vector \( c \), and every solution of (34) satisfies (17) for some \( c \).

Theorem 4 with \( W = I \) contains a result of Brauer [1, Lemma 2], who assumed that \( \int_0^\infty \|A(t)\| \, dt < \infty \) and \( \int_0^\infty \|g(t)\| \, dt < \infty \).

In the following examples, \( c = \text{col}[\alpha_1, \alpha_2] \) and \( x_1 \) and \( x_2 \) are the components of a solution vector \( x \).

**Example 1.** The system

\[ \begin{bmatrix} x_1' \\ x_2' \end{bmatrix} = \frac{4 \sin t}{t^4(x_1 - x_2)^2} \begin{bmatrix} 1 & 2 & -t \\ t^2 & t & -1 \end{bmatrix} \begin{bmatrix} x_1^2 \\ x_1 x_2 \\ x_2^2 \end{bmatrix} + \frac{\sin t}{t^3} \begin{bmatrix} 1 \\ 1 - t \end{bmatrix}, \quad t > 0, \]

is of the form (24). If \( W = \text{diag}[t^q, t^{q-1}] \) with \( q \geq 1 \), then (28) holds. If \( \alpha_1 \neq \alpha_2 \), then \( c \) is a Lipschitz point of \( \psi \) in (37), and (27) converges if \( q < 3 \). Therefore, Theorem 2 implies that (37) has a solution such that

\[ x_1(t) = \alpha_1 + o(t^{-q}), \quad x_2(t) = \alpha_2 + o(t^{-q+1}) \]

for all \( q < 3 \), provided \( \alpha_1 \neq \alpha_2 \). If \( \alpha_1 = -\alpha_2 \neq 0 \), then (27) converges for \( q < 4 \), and so (38) holds for all \( q < 4 \).

**Example 2.** For the linear system

\[ \begin{bmatrix} x_1' \\ x_2' \end{bmatrix} = \begin{bmatrix} 2t^{-2} \sin t & 3t^{-1} \\ t^{-3} \sin t & t^{-3} \sin t \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} 6t^{-1} \\ -2t^{-3} \end{bmatrix}, \]

(35) holds if \( W = \text{diag}[t^q, t^{q+1}] \) with \( q \geq 0 \), and (36) converges if \( \alpha_1 \) is arbitrary, \( \alpha_2 = -2 \), and \( q < 1 \). Hence, from Theorem 3, (39) has a solution such that

\[ x_1(t) = \alpha_1 + o(t^{-q}), \quad x_2(t) = -2 + o(t^{-q+1}) \]

for all \( q < 1 \). If \( \alpha_1 = -\alpha_2 = 2 \), then (36) converges if \( q < 2 \), and so (40) holds for all \( q < 2 \) if \( \alpha_1 \) is even.

**Example 3.** We now exhibit a system \( x' = A(t)x \) whose solutions all tend rapidly to constant vectors, even though \( \int_0^\infty \|A(t)\| \, dt = \infty \). To this end, we first observe that \( \int_0^\infty t^{\nu+1}\sin(e^t) \, dt \) converges for all \( \nu \) if \( \mu < 1 \); if \( \mu = 0 \), it converges conditionally if \( \nu \leq -1 \), and absolutely if \( \nu < -1 \). (To see this, substitute \( \tau = e^t \).

Now consider the system

\[ \begin{bmatrix} x_1' \\ x_2' \end{bmatrix} = \sin(e^t) \begin{bmatrix} at^{-3/2} \\ bt^{-1/2} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}. \]
where \(a, b, c, d\) are constants and \(b \neq 0\), so that \(\int^\infty \|A(t)\| \, dt = \infty\), and let \(W = \text{diag}[e^{\mu t}, e^{\mu t}]\) with \(0 \leq \mu < 1\). Here \(\int^\infty W(t)A(t) \, dt\) converges and (35) holds; hence, Theorem 4 implies that if \(\alpha_1\) and \(\alpha_2\) are arbitrary, then (41) has a solution such that
\[
x_1(t) = \alpha_1 + o(e^{-\mu t}), \quad x_2 = \alpha_2 + o(t^{-1}e^{-\mu t})
\]
for all \(\mu < 1\).

**Example 4.** Suppose \(a, b, f \in C(0, \infty)\) and \(z_1\) and \(z_2\) are solutions of
\[
z'' + a(t)z = 0, \quad t > 0.
\]
with wronskian \(\omega \neq 0\). Then \(y\) satisfies
\[
y'' + a(t)y = b(t)y + f(t), \quad t > 0.
\]
if and only if
\[
y^{(r)} = x_1z_1^{(r)} + x_2z_2^{(r)}, \quad r = 0, 1.
\]
where
\[
\begin{bmatrix}
x_1' \\
x_2'
\end{bmatrix} = \frac{b}{\omega} \begin{bmatrix}
-z_1z_2 & -z_2' \\
z_1' & z_2'
\end{bmatrix} \begin{bmatrix}
x_1 \\
x_2
\end{bmatrix} + \frac{f}{\omega} \begin{bmatrix}
-z_2 \\
z_1
\end{bmatrix}.
\]

Let \(\alpha_1\) and \(\alpha_2\) be given constants, define \(g = b(\alpha_1z_1 + \alpha_2z_2) + f\), and suppose \(w \in C(0, \infty)\) is such that \(w > 0\), \(w' > 0\), and the integrals \(\int^\infty wgz_i \, dt\) \((i = 1, 2)\) converge. Suppose also that \(\int^\infty |b| (|z_1| + |z_2|)^2 \, dt < \infty\). Then, applying Theorem 3 with \(W = wz\) to (45) shows that (43) has a solution which satisfies (44), with
\[
x_i(t) = \alpha_i + o(1/w(t)), \quad i = 1, 2.
\]
The special case of this with \(w = 1\) and \(f = 0\) is known [5].

**Example 5.** If (42) is nonoscillatory, we may choose \(z_1\) and \(z_2\) so that \(z_2/z_1\) tends monotonically to infinity [3, p. 357]. Then it is useful to apply Theorem 3 to (45) with
\[
W = \text{diag}[(z_2/z_1)^q, (z_2/z_1)^{q+1}] \quad (q \geq 0).
\]
For example, if \(a = -1\) in (42), so that (43) becomes
\[
y'' - y = b(t)y + f(t), \quad t > 0,
\]
we take \(z_1 = e^{-t}\) and \(z_2 = e^t\) in (44) and (45), and
\[
W = \text{diag}[e^{2qt}, e^{2q+1t}] \quad (q \geq 0).
\]
Theorem 3 then implies that if \(\int^\infty |b(t)| \, dt < \infty\) and \(\alpha_1\) and \(\alpha_2\) are constants such that
\[
\int^\infty e^{2qt} [b(t)(\alpha_1 + \alpha_2 e^{2t}) + f(t)e^t] \, dt
\]
converges, then (46) has a solution \(y\) such that
\[
y^{(r)}(t) = (-1)^r \alpha_1 e^{-r} + \alpha_2 e^t + o(e^{(2q+1)t}), \quad r = 0, 1.
\]
This implies several results previously obtained under stronger integral conditions.
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