SOME MAXIMUM PRINCIPLES IN SEMILINEAR ELLIPTIC EQUATIONS

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ABSTRACT. We develop maximum principles for functions defined on the solutions to a class of semilinear, second order, uniformly elliptic partial differential equations. These principles are related to recent theorems of Protter and Protter and Weinberger and to a technique initiated by Payne for the determination of gradient bounds on the solution of the equation.

1. Introduction. In [3] Payne introduced a technique, which utilizes a maximum principle for a function defined on solutions to an elliptic partial differential equation, in order to obtain bounds for the gradient of the solution of the relevant differential equation. Several authors have contributed to the growing literature developing this technique. In their work (see the references cited here, especially [7], and the references therein), the authors seek estimates on the solution, the gradient of the solution, or other quantities of physical importance and/or extend the method to more general elliptic or parabolic differential equations. Early in the development of this method, the results were obtained when the principal part of the elliptic equation was the Laplace operator.

Sperb [6] was the first to extend the results of Payne to a second order uniformly elliptic equation of the form

\[(a^{ij}(x)u_{, ij})_i + b^i(x)u_{, i} + c(x)f(u) = 0,\]

where the comma notation \(u_{, k}\) signifies partial differentiation with respect to the \(k\)th coordinate variable and the repeated index in a single term denotes summation over that index from 1 to \(n\). Sperb's extension depended heavily on differential geometric quantities and the Riemannian metric \(g^{ij}\) induced by the principal part of (1.1), on the coefficients in (1.1), and the geometry of the domain.

Sperb's development was greatly simplified by Protter [5] for general second order uniformly elliptic equations of the form

\[(a^{ij}(x)u_{, ij})_i + b^i(x)u_{, i} + f(u) = 0,\]

where by uniformly elliptic, we mean, the symmetric matrix \((a^{ij})\) is positive definite and satisfies the uniform ellipticity condition

\[(a^{ij}(x)\xi_i\xi_j \geq \lambda|\xi|^2, \quad x \in \Omega, \xi \in \mathbb{R}^n,\]

for some positive constant \(\lambda\). Protter showed that a certain function defined on solutions to (1.2) attains its maximum either on the boundary of the domain \(\Omega\) or at a critical point of the solution, i.e., where \(\text{grad} u = 0\).
In this work we use an inequality from [4] to obtain maximum principles for functions defined on the solutions to uniformly elliptic equations of the form

\[ a^{ij}(x)u_{,ij} + b^i(x)u_i - c(x)f(u) = 0. \]

We obtain principles in §2 which state that the maximum of the function cannot be attained in the interior of \( \Omega \) unless it is a constant and thus do not encounter the possibility of an occurrence at a critical point in the domain. In §3 we briefly illustrate the application of these principles for the determination of solution or gradient estimates.

2. Results. Let \( \Omega \) be a bounded domain in \( \mathbb{R}^n \), \( n \geq 2 \), and let \( u \) be a \( C^3 \) solution of the uniformly elliptic equation (1.4) in \( \Omega \).

We define the function

\[ P(x) = \frac{u_x u_y}{c(x)} + \gamma \int_0^u f(t) \, dt, \]

where \( \gamma \) is a positive constant to be determined and \( c(x) \geq c_0 > 0 \). By a straightforward computation, we have

\[
P_{,i} = 2c^{-1}u_x u_{,x} u_{,i} - c^{-2}u_x u_{,x} u_{,x,i} + c^{-1}u_x u_{,x,i} + \gamma f'(u)u_{,i},
\]

\[
P_{,ij} = 2c^{-1}u_x u_{,x} u_{,x,i} - c^{-2}u_x u_{,x} u_{,x,i,j} - c^{-2}u_x u_{,x} u_{,x,i} u_{,x,j} + c^{-2}u_x u_{,x} u_{,x,i} c_{,j} + \gamma f'(u)u_{,i,j} + \gamma f(u)u_{,ij},
\]

where \( f' \) denotes differentiation with respect to \( u \). We now write

\[ LP = a^{ij}P_{,ij} + b^iP_{,i}, \]

\[
= 2c^{-1}a^{ij}u_x u_{,x} u_{,x,i} + c^{-2}a^{ij}u_x u_{,x} u_{,x,i} - c^{-2}a^{ij}u_x u_{,x} u_{,x,i} + \gamma f'(u)u_{,i},
\]

\[
- 2c^{-2}a^{ij}u_x u_{,x} u_{,x,i} - c^{-2}a^{ij}u_x u_{,x} u_{,x,i} + c^{-2}a^{ij}u_x u_{,x} u_{,x,i} + c^{-3}a^{ij}u_x u_{,x} u_{,x,i} c_{,j} + \gamma f'(u)u_{,i,j} + \gamma f(u)u_{,ij}.
\]

We seek to make the right-hand side of (2.2) nonnegative. To handle the second and ninth terms, we differentiate (1.4) with respect to \( x_k \), multiply by \( 2c^{-1}u_{,k} \), and then solve for these terms. Hence we have

\[ 2c^{-1}a^{ij}u_{,k} u_{,x} u_{,x,i} + c^{-1}b^i u_{,k} u_{,x,i} \]

\[ = -2c^{-1}a^{ij}u_{,k} u_{,x} u_{,x,i} - c^{-1}b^i u_{,k} u_{,x,i} + 2c^{-1}f u_{,x} u_{,x,k} + 2f' u_{,x} u_{,x,k}. \]

We substitute (2.3) into (2.2) and combine appropriate terms to obtain

\[ LP = 2c^{-1}a^{ij}u_{,k} u_{,x} u_{,x,i} - 2c^{-1}a^{ij}u_{,k} u_{,x,i} - c^{-1}b^i u_{,k} u_{,x,i} + 2c^{-1}f u_{,x} u_{,x,k} + 2f' u_{,x} u_{,x,k} + 2c^{-1}f u_{,x} u_{,x,k} + 2c^{-1}f u_{,x} u_{,x,k} + 2c^{-3}u_{,k} u_{,x} a^{ij} c_{,i} c_{,j} + \gamma f'(u)u_{,j} u_{,i} + \gamma f(u)u_{,ij}.
\]

We shall now combine the fourth and tenth terms on the right side of (2.4) by

\[ \gamma cf^2 + 2c^{-1}f u_{,x} u_{,x,k} \]

\[ = (\gamma - 1)cf^2 + c^{-1} [cf^2 + 2f u_{,x} u_{,x,k} + (c^{-1}u_{,x} u_{,x,k})^2 - (c^{-1}u_{,x} u_{,x,k})^2] \]

\[ \geq (\gamma - 1)cf^2 + c^{-1} [cf + c^{-1}u_{,x} u_{,x,k}]^2 - c^{-3}|\nabla c|^2 u_{,x} u_{,x,k}. \]
To combine the first, second, and sixth terms on the right side of (2.4), we employ an inequality from [4]. Let \((A^{ij})\) be the matrix which is the inverse of the positive definite \((a^{ij})\) and let \((s^{kj})\) be an arbitrary \(n \times n\) matrix. Then since

\[
a^{ij}(u_{ik} + \frac{1}{2} A^{ip}s^{pk})(u_{jk} + \frac{1}{2} A^{jq}s^{qk}) \geq 0,
\]

one has the inequality

\[
s^{ki}u_{ki} \geq -a^{ij}u_{kj}u_{ki} - \frac{1}{4} A^{pq}s^{pk}s^{qk}
\]

for the arbitrary matrix \((s^{ki})\). Consequently we have

\[
2c^{-1}a^{ij}u_{kj}u_{ki} - 2c^{-1}a^{ki}u_{ij}u_{ki} - 4c^{-2}a^{ij}c_{j}u_{ki}k\]

\[
= 2c^{-1}\{a^{ij}u_{kj} - a^{ki}u_{ij} - 2c^{-1}a^{ij}c_{j}u_{ki}\}u_{ki}
\]

\[
\geq -(2c)^{-1}A^{pq}s^{pk}s^{qk},
\]

where we have chosen

\[
s^{ki} = -a^{ki}u_{kj} - 2c^{-1}a^{ij}c_{j}u_{ki}.
\]

We finally substitute (2.5) and (2.6) into the right side of (2.4) and rearrange terms so that

\[
P(x) \geq \{\gamma f^{'a^{ij}} + (2f^{' - c^{-2}Lc - c^{-3}|\nabla c|^2})\delta^{ij} - 2c^{-1}b_{j}
\]

\[
- (2c)^{-1}\{A^{pq}a^{pk}a^{qk} + 2c^{-1}A^{pi}a^{pj}c_{m} + 2c^{-1}A^{jq}a^{kl}c_{l}a^{qk}
\]

\[
+ 4c^{-2}A^{ij}a^{kl}a^{km}c_{m}\}u_{j}u_{i}
\]

\[
+ 2c^{-3}u_{k}u_{k}a^{ij}c_{j}c_{j} + (\gamma - 1)cf^{2} + c^{-1}[cf + c^{-1}u_{k}c_{k}]^{2},
\]

where \(\delta^{ij}\) is the Kronecker delta. Now for \(\gamma\) sufficiently large the right side can be made nonnegative as desired. We thus have the following.

**Theorem 1.** If \(u\) is a \(C^{3}\) solution of (1.4), where the coefficients \(a^{ij}, b^{i} \in C^{1}(\Omega)\), \(c \in C^{2}(\Omega)\) and \(c(x) \geq c_{0} > 0\) and the function \(f \in C^{1}(\Omega)\) has a derivative which is bounded below by \(f^{'}(u) \geq \alpha > 0\), then there exists a positive constant \(\gamma\) sufficiently large (\(\delta \geq 1\)) such that

\[
P(x) = \frac{u_{k}u_{k}}{c(x)} + \gamma \int_{0}^{u} f(t) dt
\]

cannot attain its maximum value in \(\Omega\) unless it is a constant.

As in [5], one would like to weaken the requirement that the derivative of \(f\) have a positive lower bound. Before doing such, we note that by an entirely similar analysis as in Theorem 1, motivated by the function introduced in [2], one can deduce

**Theorem 2.** If \(u\) is a \(C^{3}\) solution of

\[
a^{ij}(x)u_{ij} + b^{i}(x)u_{i} + c(x)f(u) = 0,
\]

where the coefficients \(a^{ij}, b^{i} \in C^{1}(\Omega)\), \(c \in C^{2}(\Omega)\) and \(c(x) \geq c_{0} > 0\) and the function \(f \in C^{1}(\Omega)\) is such that \(uf(u) \leq 0\) and \(f^{'}\) is bounded above, then there exists a positive constant \(\gamma\) sufficiently large such that

\[
Q(x) = \frac{u_{k}u_{k}}{c(x)} + \gamma u^{2} - 2 \int_{0}^{u} f(t) dt
\]

cannot attain its maximum value in \(\Omega\) unless it is a constant.
We note that the only difference in demonstrating the nonnegativity of \(LQ\) is that one need not add and subtract 1 as done in (2.5) since the term \(cf^2\) occurs as a consequence of the placement of the parameter in \(Q\). We also note that no specific lower derivative bound on \(f\) is called for and that the coefficient of the nonlinear term in (2.8) is positive.

Now let us seek to weaken the requirement on \(f'\) in Theorem 1, where \(u\) is a \(C^3\) solution of (1.4).

We define the function

\[
R(x) = \frac{u_{,k}u_{,k}}{c(x)} + \gamma \int_0^{\varphi(u)} f(t) \, dt,
\]

where \(\gamma\) is a positive constant to be determined, \(\varphi(u)\) is a function to be determined, and \(c(x) \geq c_0 > 0\). We compute \(R_{,i}\) and \(R_{,ij}\) as before, where we use a prime to indicate differentiation with respect to the argument and we let \(\overline{f} = \overline{f}(u) = f(\varphi(u))\). Then as in (2.2) we form

\[
(2.10) \quad LR = 2c^{-1}a^{ij}u_{,k_j}u_{,k_i} + 2c^{-1}a^{ij}u_{,k_i}u_{,k_j} - 2c^{-2}a^{ij}u_{,k_i}u_{,k_j}c_{,j}
- 2c^{-2}a^{ij}u_{,k_i}c_{,i}u_{,k_j}c_{,j} + 2c^{-3}a^{ij}u_{,k_i}c_{,j}c_{,i}c_{,j}
+ \gamma f'\varphi^2u_{,j}u_{,i} + \gamma f\varphi'\varphi u_{,j}u_{,i} + \gamma f\varphi'\varphi u_{,j}u_{,i}
+ 2c^{-1}b_iu_{,k}u_{,k_i} - c^{-2}b_iu_{,k}u_{,k_i}c_{,i} + \gamma f\varphi'\varphi u_{,i}.
\]

Using (2.3) and collecting terms, we can write

\[
(2.11) \quad LR = 2c^{-1}a^{ij}u_{,k_j}u_{,k_i} - 2c^{-1}a^{ij}u_{,k_i}u_{,k_j} - 2c^{-1}b_iu_{,k_i}u_{,i}
+ 2c^{-1}u_{,k}c_{,k} + 2f'_{,k}u_{,k} - 4c^{-2}a^{ij}u_{,k_i}c_{,j}u_{,k}c_{,i}c_{,j} - c^{-2}u_{,k}u_{,k}c_{,k}
+ 2c^{-3}u_{,k}u_{,k}a^{ij}c_{,i}c_{,j} + (\gamma f'\varphi^2 + \gamma f\varphi'\varphi')u_{,j}u_{,i} + \gamma c\varphi'\varphi f.
\]

We note that we can again use (2.6) on the first, second, and sixth terms of (2.11). It only remains to use the tenth term to balance the "undesirable" fourth term of (2.11). We achieve this by assuming \(\varphi'\overline{f} \geq \alpha^2 > 0\) and calculating

\[
(2.12) \quad \gamma c\varphi'\overline{f} + 2c^{-1}u_{,k}c_{,k} = (\gamma - 1)c\varphi'\overline{f}f + c\varphi'\overline{f}f + 2c^{-1}u_{,k}c_{,k}
\geq (\gamma - 1)c\varphi'\overline{f}f + c^{-1}[c^2\varphi'^2 + 2u_{,k}c_{,k}
+ (c\alpha)^{-2}(u_{,k}c_{,k})^2 - (c\alpha)^{-2}(u_{,k}c_{,k})^2] \geq (\gamma - 1)c\varphi'\overline{f}f + c^{-1}c\alpha + (c\alpha)^{-1}u_{,k}c_{,k}^2
- c^{-3}\alpha^{-2}|f|^2|\nabla c|^2u_{,k}u_{,k}.
\]

We now substitute (2.6) and (2.12) into (2.11) and collect terms. Assuming \(\varphi'\overline{f} + \varphi'' \geq \beta > 0\), this results in

\[
(2.13) \quad LR \geq \{\gamma \beta a^{ij} + (2f' - c^2Lc - c^{-3}\alpha^{-2}|f|^2|\nabla c|^2)\delta^{ij} - 2c^{-1}b_{ij}
- (2c)^{-1}[A^p q a^{pk} a^{,q}_{,i} + 2c^{-1}A^p a^{q}_{,j} a^{km} c_{,m}
+ 2c^{-1}A^{ij} a^{kl} c_{,l} a^{,q}_{,k} + 4c^{-2}A^{ii} a^{kl} c_{,l} a^{km} c_{,m}]u_{,j}u_{,i}
+ 2c^{-3}u_{,k}u_{,k}a^{ij}c_{,i}c_{,j} + (\gamma - 1)c\alpha^2 + c^{-1}c\alpha + (c\alpha)^{-1}u_{,k}c_{,k}^2\}u_{,j}u_{,i}.
\]

It is clear that the right side of (2.13) can be made nonnegative for a \(\gamma\) chosen
sufficiently large. Thus we have

**Theorem 3.** If \( u \) is a \( C^3 \) solution of (1.4), where the coefficients \( a^{ij}, b^i \in C^1(\Omega), c \in C^2(\Omega) \), and \( c(x) \geq c_0 > 0 \) and the function \( f \in C^1(\mathbb{R}) \) is bounded and has its first derivative bounded below, and if there exists a function \( \varphi \) such that

\[
\varphi' f \geq \alpha^2 > 0, \quad \int \varphi'^2 + \int \varphi'' \geq \beta > 0,
\]

then there exists a positive constant \( \gamma \) sufficiently large (\( \gamma \geq 1 \)) such that

\[
R(x) = \frac{u_k u_k}{c(x)} + \gamma \int_0^{\varphi(u)} f(t) \, dt
\]

cannot attain its maximum value in \( \Omega \) unless it is a constant.

We note that nontrivial \( f \) and \( \varphi \) which satisfy the conditions in Theorem 3 for a solution which is bounded below are \( f(u) = \arctan u^2 + 1 \) and \( \varphi(u) = e^u \). We also note that the first condition in (2.14) precludes Theorem 3 from strictly containing Theorem 1 inasmuch as it implies that \( f(u) \neq 0 \), which was not hypothesized in Theorem 1.

**3. Bounds.** For an application of Theorem 1, we consider the nonlinearity \( f(u) = u^3 + u \). We note that the integral term in \( P(x) \) is nonnegative since \( f(0) = 0 \) here. If we let \( x_0 \) be a point on \( \partial \Omega \) at which \( P(x) \) attains its maximum, then we obtain from \( P(x) \leq P(x_0) \) that

\[
\frac{|\nabla u(x)|^2}{c(x)} \leq \frac{|\nabla u(x_0)|^2}{c(x_0)} + \gamma \left[ \frac{1}{4} u^4(x_0) + \frac{1}{2} u^2(x_0) \right]
\]

for any \( x \in \overline{D} \). Moreover, it follows from \( P(x) \leq P(x_0) \) that

\[
|u(x)| \leq \left[ \frac{1}{2 \gamma c_0} |\nabla u(x_0)|^2 + \frac{1}{2} u^4(x_0) + u^2(x_0) \right]^{1/4}
\]

with this \( f \). It is conceivable that a better solution estimate may be obtained by taking the fourth root, i.e.,

\[
|u(x)| \leq \left[ \frac{4}{\gamma c_0} |\nabla u(x_0)|^2 + u^4(x_0) + 2u^2(x_0) \right]^{1/4}.
\]

The above estimates apply to any nontrivial solution of (1.4) with \( f \) as given. More generally, for any \( f \) which satisfies the condition of Theorem 1, if \( f(0) = 0 \) and if one imposes homogeneous Dirichlet boundary conditions on \( u \), then one can deduce the gradient estimate

\[
|\nabla u(x)| \leq K |\nabla u(x_0)|, \quad K^2 = \frac{1}{c_0} \max_{D} c(x)
\]

where \( x_0 \) is some point on \( \partial \Omega \) at which \( P(x) \) attains its maximum.

For a physical application, we consider the single, irreversible, steady-state reaction studied in [1]. There the scalar problem for the concentration is formulated as

\[
(3.1) \quad \Delta u - k^2 f(u) = 0, \quad \text{in } \Omega, \quad u = 1, \quad x \in \partial \Omega, \quad u \geq 0, \quad x \in \Omega,
\]
where $k^2$ is a positive constant and where $f$ has the properties $f: [0, \infty) \to [0, \infty)$, $f(0) = 0$, $f(1) = 1$, $f \in C^1$, $f > 0$, $f$ monotone increasing on $(0, \infty)$. Clearly, $f(u) = \frac{1}{2}(u^3 + u)$ has such properties.

In Lemma 3.1 of [1] a gradient bound, namely,

$$|\nabla u(x)|^2 \leq 2k^2 \int_{m}^{u(x)} f(t) \, dt,$$

is given in terms of the value of $u$ at $x$ and $m = \min u(x)$ when the average curvature of the boundary is nonnegative. By Theorem 1 with $\gamma = 1$ and without the restriction on the geometry, we obtain

$$|\nabla u(x)|^2 \leq |\nabla u(x_0)|^2 + k^2 \int_{0}^{1} f(t) \, dt,$$

which could possibly be a better estimate. In fact, however, for a solution $u$ of (3.1) it can be shown (let $\gamma = 0$ in Theorem 1) that $|\nabla u(x)| \leq |\nabla u(x_0)|$ for $x_0$ some point of $\partial \Omega$ since $|\nabla u|^2$ takes its maximum on the boundary.

We have only briefly indicated how the principles here can be utilized to obtain estimates. We refer the reader to Sperb's text [7] for other applications of principles of the type presented here.

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