

## BOUNDARY VALUE PROBLEMS FOR FIRST-ORDER DIFFERENTIAL EQUATIONS

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ABSTRACT. Conditions sufficient to guarantee existence and uniqueness of solutions to multipoint boundary value problems for the first-order differential equation  $y' = h(t, y)$  are given when  $h$  fails to be Lipschitz along a solution of  $y' = h(t, y)$  and the initial-value problem thus has nonunique solutions.

It is well known that the initial value problem for the first-order differential equation  $y' = h(t, y)$  does not generally have a unique solution if  $h$  fails to be Lipschitz in  $y$ . This raises the possibility, for non-Lipschitz  $h$ , of well-posedness of problems that would be overspecified if  $h$  satisfied a Lipschitz condition; in particular, of the reasonableness of problems that would normally be associated with higher-order equations [1, 3]. Here we examine existence and uniqueness of solutions to two- and multi-point boundary value problems when  $y' = h(t, y)$  has a solution  $y = a(t)$  along which  $h$  fails to be Lipschitz. Making the change of variable  $y - a(t) \rightarrow y$ , we may without loss of generality assume that  $h$  vanishes when  $y = 0$  and that  $h$  is not Lipschitz in any neighborhood of  $y = 0$ . We treat first the case of separable variables  $h(t, y) = g(t)f(y)$  and then use a comparison theorem to treat the more general case.

Let  $b > 0$  and consider the boundary value problem

$$(1) \quad y' = g(t)f(y), \quad y(0) = -A, \quad y(b) = B$$

when  $A > 0, B > 0, g > 0$ , and  $yf(y) < 0$  for  $y \neq 0$ . Then  $y' < 0$  for  $y > 0$  and  $y' > 0$  for  $y < 0$ , from which it is clear that the problem has no solution. Similarly there is no solution if  $yf(y) > 0$  for  $y \neq 0$ . Thus if solutions are to exist in general, then the right-hand side cannot change sign.

It is interesting to note that, since the two-point boundary value problem

$$y'' = \lambda y^{1/2}, \quad y(0) = y(b) = A > 0$$

has a unique nonnegative solution for each  $b > 0$  and this solution vanishes on an interval when  $\lambda$  is sufficiently large [2], the following considerations do not extend to higher-order equations.

**THEOREM 1.** *Let  $A, B \geq 0$  and let  $f \geq 0$  be continuous on  $[-A, B]$  and vanish on  $(-A, B)$  precisely at  $\alpha_1 < \alpha_2 < \dots < \alpha_{k+1} = 0 < \dots < \alpha_n$ . Let  $g > 0$  be continuous on  $[0, b]$ . Then there is no solution of the two-point boundary value problem (1) unless the improper integral*

$$(2) \quad \int_{-A}^B \frac{d\zeta}{f(\zeta)}$$

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exists. If this integral converges, (1) has continuously differentiable solutions if and only if there exist  $T_1$  and  $T_2$  in  $[0, b]$  satisfying

$$(3) \quad \int_0^{T_1} g(s) ds = \int_{-A}^0 \frac{d\zeta}{f(\zeta)}, \quad \int_{T_2}^b g(s) ds = \int_0^B \frac{d\zeta}{f(\zeta)},$$

and

$$(4) \quad T_1 \leq T_2.$$

PROOF. We show first the necessity of these conditions. Suppose  $y(t)$  is a solution of (1) and set  $\alpha_0 = -A$ ,  $\alpha_{n+1} = B$  ( $f$  may or may not vanish at these points). On each  $(\alpha_i, \alpha_{i+1})$ ,  $f \neq 0$ . Define

$$\begin{aligned} t_i &= \sup\{t: y(t) < \alpha_i\}, & i &= 1, 2, \dots, n+1, \\ s_i &= \inf\{t: y(t) > \alpha_i\}, & i &= 0, 1, \dots, n. \end{aligned}$$

Then  $f(y(t)) \neq 0$  on  $(s_i, t_{i+1})$ . Let  $\varepsilon, \delta > 0$  be sufficiently small. Dividing the differential equation by  $f(y(t))$ , integrating from  $s_i + \varepsilon$  to  $t_{i+1} - \delta$ , and passing to the limit as  $\varepsilon, \delta \rightarrow 0$  yields

$$\int_{\alpha_i}^{\alpha_{i+1}} \frac{d\zeta}{f(\zeta)} = \int_{y(s_i)}^{y(t_{i+1})} \frac{y'(t) dt}{f(y(t))} = \int_{s_i}^{t_{i+1}} g(t) dt, \quad i = 0, \dots, n.$$

Thus the improper integral (2) converges. It also follows that

$$\int_{-A}^0 \frac{d\zeta}{f(\zeta)} = \sum_{i=0}^k \int_{s_i}^{t_{i+1}} g(t) dt \leq \int_0^{t_{k+1}} g(t) dt;$$

hence there exists a  $T_1 \leq t_{k+1}$  such that the first equality of (3) holds. In the same way, there exists  $T_2 \geq t_{k+1}$  such that the second equality of (3) obtains. The necessity of the hypotheses follows.

To show sufficiency, let  $\hat{y}$  be the maximal solution of the initial value problem  $y' = g(t)f(y)$ ,  $y(0) = -A$ ; we shall show that  $\hat{y}(T_1) = 0$ . Let  $\alpha_i$ ,  $i = 0, \dots, n+1$ , be as before; then convergence of the improper integral (2) guarantees the existence of the improper integrals

$$\int_{\alpha_i}^{\alpha_{i+1}} \frac{d\zeta}{f(\zeta)}, \quad i = 0, \dots, n.$$

Since  $T_1$  satisfying (3) exists, there also exist  $t_1 < t_2 < \dots < t_{k+1} \leq T_1$  such that

$$\sum_{i=1}^j \int_{\alpha_{i-1}}^{\alpha_i} \frac{d\zeta}{f(\zeta)} = \int_0^{t_j} g(s) ds \quad (j = 1, \dots, k+1);$$

set  $t_0 = 0$ .

Let  $y_i$  ( $i = 0, \dots, k$ ) be the maximal solution of the initial value problem

$$y_i'(t) = g(t)f(y_i(t)), \quad y_i(t_i) = \alpha_i;$$

we shall show first that  $y_i$  is defined on  $[t_i, t_{i+1}]$  and  $y_i(t_{i+1}) = \alpha_{i+1}$ . To this end let  $y_{i,\varepsilon}$ , for all sufficiently small  $\varepsilon > 0$ , be the maximal solution of

$$(5) \quad y_{i,\varepsilon}' = g(t)f(y_{i,\varepsilon}) + \varepsilon, \quad y_{i,\varepsilon}(t_i) = \alpha_i + \varepsilon.$$

If  $y_i$  is defined on  $[t_i, s_i)$ , then for any  $\delta > 0$ ,  $y_{i,\varepsilon}$  exists for  $t_i \leq t \leq s_i - \delta$  for all sufficiently small  $\varepsilon$ , and  $y_{i,\varepsilon} \downarrow y_i$  as  $\varepsilon \downarrow 0$  [4]. Suppose that  $y_i(t) \equiv \alpha_i$  on  $[t_i, \bar{t}_i]$  with  $\bar{t}_i > t_i$  and  $\bar{t}_i$  small enough that  $\theta$  defined by

$$\int_{\alpha_i}^{\theta} \frac{d\zeta}{f(\zeta)} = \int_{\bar{t}_i}^{\bar{t}_i} g(t) dt$$

exists and satisfies  $\theta < \alpha_{i+1}$ ; this is guaranteed by the existence of (2). Since  $g > 0$ ,  $\theta > \alpha_i$ . For  $\varepsilon_0 > 0$  sufficiently small, the maximal solution  $y_{i,\varepsilon}$  of (5) exists on  $[t_i, \bar{t}_i]$  for  $0 < \varepsilon \leq \varepsilon_0$ . By further reducing  $\bar{t}_i$  and  $\theta$ , if necessary, we may assume that  $y_{i,\varepsilon}(t) < \alpha_{i+1}$  for  $0 < \varepsilon \leq \varepsilon_0$  and  $t \in [t_i, \bar{t}_i]$ . Then  $\alpha_i < y_{i,\varepsilon}(t) < \alpha_{i+1}$  on  $(t_i, \bar{t}_i)$ , so  $f(y_{i,\varepsilon}(t)) > 0$  there, and we get from (5) that

$$\int_{t_i}^{\bar{t}_i} \frac{y'_{i,\varepsilon}(t) dt}{f(y_{i,\varepsilon}(t))} > \int_{t_i}^{\bar{t}_i} g(t) dt$$

and hence that

$$\int_{\alpha_i}^{y_{i,\varepsilon}(\bar{t}_i)} \frac{d\zeta}{f(\zeta)} > \int_{\alpha_i + \varepsilon}^{y_{i,\varepsilon}(\bar{t}_i)} \frac{d\zeta}{f(\zeta)} > \int_{t_i}^{\bar{t}_i} g(t) dt.$$

Thus  $y_{i,\varepsilon}(\bar{t}_i) > \theta$  for  $0 < \varepsilon \leq \varepsilon_0$ , whence  $y_i(\bar{t}_i) = \lim_{\varepsilon \rightarrow 0} y_{i,\varepsilon}(\bar{t}_i) \geq \theta > \alpha_i$ , a contradiction. We have therefore shown that  $y_i(t) = \alpha_i$  only for  $t = t_i$ .

Suppose now that  $\alpha_i < y_i(t) < \alpha_{i+1}$  for  $t_i < t < s$ . Then  $f(y_i(t)) > 0$ , so we get that

$$\int_{y_i(t_i + \varepsilon)}^{y_i(s - \delta)} \frac{d\zeta}{f(\zeta)} = \int_{t_i + \varepsilon}^{s - \delta} g(t) dt$$

for sufficiently small  $\varepsilon, \delta > 0$ . Passing to the limit as  $\varepsilon \rightarrow 0, \delta \rightarrow 0$ , we have that

$$\int_{\alpha_i}^{y_i(s-)} \frac{d\zeta}{f(\zeta)} = \int_{t_i}^s g(t) dt.$$

But we have

$$\int_{\alpha_i}^{\alpha_{i+1}} \frac{d\zeta}{f(\zeta)} = \int_{t_i}^{t_{i+1}} g(t) dt.$$

Therefore if  $s < t_{i+1}$ , then  $y_i(s-) < \alpha_{i+1}$  and  $y_i$  can be extended to the right of  $s$ . So  $s \geq t_{i+1}$ . But the unique solution to

$$\int_{\alpha_i}^{\theta} \frac{d\zeta}{f(\zeta)} = \int_{t_i}^{t_{i+1}} g(s) ds$$

is  $\theta = \alpha_{i+1}$ . Therefore  $y_i(t_{i+1}) = \alpha_{i+1}$ .

We have shown that on each interval  $[\alpha_i, \alpha_{i+1}]$  the maximal solution  $y_i$  of  $y'_i = g(t)f(y_i)$ ,  $y_i(t_i) = \alpha_i$  exists and satisfies  $y_i(t_{i+1}) = \alpha_{i+1}$ . Since  $f(\alpha_i) = 0$  for  $i = 1, \dots, k$ , we have easily that  $y'_i(\alpha_i-) = y'_i(\alpha_{i+1}+) = 0$  ( $i = 1, \dots, k$ ) and  $y'_0(\alpha_1-) = 0$ . It follows that  $\hat{y}_1$  defined by

$$\hat{y}_1(t) = y_i(t), \quad t_i \leq t < t_{i+1},$$

is the maximal solution of  $y' = g(t)f(y)$ ,  $y(0) = -A$  on  $[0, T_1)$  and  $\hat{y}_1(T_1-) = \hat{y}'_1(T_1-) = 0$ .

In the same way we conclude there exists the minimal solution of

$$\hat{y}'_2(t) = g(t)f(\hat{y}_2(t)), \quad \hat{y}_2(b) = B$$

defined on  $(T_2, b]$  and satisfying  $\hat{y}_2(T_2+) = \hat{y}'_2(T_2+) = 0$ . Therefore, since  $T_1 \leq T_2$ ,

$$(6) \quad y(t) \equiv \begin{cases} \hat{y}_1(t), & 0 \leq t < T_1, \\ 0, & T_1 \leq t \leq T_2, \\ \hat{y}_2(t), & T_2 < t \leq b, \end{cases}$$

defines a classical solution of (1), proving the theorem.

**COROLLARY 1.** *If  $f$  and  $g$  are as in the theorem and  $\int_0^\infty g = \int_{-\infty}^0 g = \infty$ , then the two-point boundary problem (1) has a solution for each  $A, B \geq 0$  provided  $b$  is sufficiently large (depending on  $A$  and  $B$ ).*

The following result is an easy extension to the multi-point boundary value problem. It is interesting to compare it with corresponding results for higher-order Lipschitz equations [3].

**COROLLARY 2.** *Let  $f$  and  $g$  satisfy the hypotheses of the theorem. Let  $C_i \in (\alpha_i, \alpha_{i+1})$  for  $i = 1, \dots, n - 1$  and  $0 < t_1 < \dots < t_{n-1} < b$  be given. Then the boundary value problem*

$$y' = g(t)f(y), \quad y(0) = -A, \quad y(t_1) = C_1, \dots, y(t_{n-1}) = C_{n-1}, \quad y(b) = B$$

*has a solution if and only if there exist sequences  $\{T_i\}$  and  $\{S_i\}$  such that*

$$0 < T_1 \leq S_1 < t_1 < T_2 \leq S_2 < t_2 < \dots \leq S_n < b$$

*and*

$$\begin{aligned} \int_{-A}^{\alpha_1} \frac{d\zeta}{f(\zeta)} &= \int_0^{T_1} g(t) dt, & \int_{\alpha_i}^{C_i} \frac{d\zeta}{f(\zeta)} &= \int_{S_i}^{t_i} g(t) dt, \\ \int_{C_i}^{\alpha_{i+1}} \frac{d\zeta}{f(\zeta)} &= \int_{t_i}^{T_{i+1}} g(t) dt & (i = 1, \dots, n - 1), \\ \int_{\alpha_n}^B \frac{d\zeta}{f(\zeta)} &= \int_{S_n}^b g(t) dt. \end{aligned}$$

The following theorem establishes conditions under which the two-point boundary value problem has a unique solution. Extension to the multi-point problem is straightforward and will be omitted.

**THEOREM 2.** *Let the hypotheses of Theorem 1 hold and, in addition, suppose that  $f$  vanishes on  $[-A, B]$  only at zero and that  $f$  is locally Lipschitz on  $[-A, 0) \cup (0, B]$ . Then the solution of the two-point boundary value problem (1) is unique.*

**PROOF.** Since  $f$  is locally Lipschitz, the standard existence-uniqueness theorem forces uniqueness of the solutions  $\hat{y}_1$  and  $\hat{y}_2$  constructed in the proof of Theorem 1;  $T_1$  and  $T_2$  are also unique. Since any solution of the differential equation is nondecreasing, the solution  $y(t)$  of the boundary value problem given by (6) is now seen to be unique.

**EXAMPLE.** Let  $g(t) \equiv 1$ ,  $f(y) \equiv |y|^\alpha$ . Then (1) has no solution unless  $0 < \alpha < 1$ . For  $0 < \alpha < 1$ , the two-point boundary value problem (1) has a solution, which is unique, if and only if  $(1 - \alpha)b \geq A^{1-\alpha} + B^{1-\alpha}$ .

We now turn to existence of solutions of the two-point boundary value problem for  $y' = h(t, y)$ ; this will be established by means of a comparison theorem. A similar result for the multi-point problem is easily established along the same lines.

The following lemma is well known; a proof may be found in [4].

LEMMA. Let  $g$  be continuous on  $E$ , an open set in  $\mathbf{R}^2$ , and let the maximal solution  $u(t)$  of

$$(7) \quad u' = g(t, u), \quad u(t_0) = u_0$$

exist on  $[t_0, t_0 + a)$ . Let  $v(t)$  be continuous on  $[t_0, t_0 + a)$  with  $(t, v(t)) \in E$  for  $t \in [t_0, t_0 + a)$ , and suppose that

$$v'(t) \leq g(t, v(t)), \quad v(t_0) \leq u_0 \quad (t_0 < t < t_0 + a).$$

Then

$$v(t) \leq u(t) \quad \text{for } t_0 \leq t < t_0 + a.$$

Let the minimal solution  $w(t)$  of (7) exist on  $(t_0 - a, t_0]$ . Let  $v(t)$  be continuous on  $(t_0 - a, t_0]$  with  $(t, v(t)) \in E$  for  $t \in (t_0 - a, t_0]$ , and suppose that

$$v'(t) \leq g(t, v(t)), \quad v(t_0) \geq u_0 \quad (t_0 - a < t < t_0).$$

Then

$$v(t) \geq w(t) \quad \text{for } t_0 - a < t \leq t_0.$$

With the aid of this result, we can easily prove the following comparison theorem.

THEOREM 3. Let the two-point boundary value problem

$$z' = \tilde{h}(t, z), \quad z(0) = -\tilde{A}, \quad z(b) = \tilde{B},$$

where  $\tilde{A} \geq 0, \tilde{B} \geq 0$ , possess a solution  $z(t)$ , not necessarily unique. Suppose that

- (i)  $0 \leq A \leq \tilde{A}, 0 \leq B \leq \tilde{B}$ ,
- (ii)  $h$  is continuous on an open set  $E$  containing  $[0, b] \times [-\tilde{A}, \tilde{B}]$ ,
- (iii)  $h(t, 0) \equiv 0$  for  $t \in [0, b]$ ,
- (iv)  $h(t, u) \geq \tilde{h}(t, u)$  on  $E$ .

Then the boundary value problem

$$(8) \quad y' = h(t, y), \quad y(0) = -A, \quad y(b) = B$$

has a solution.

PROOF. Let  $y_1$  be the maximal solution of the initial value problem

$$y' = h(t, y), \quad y(0) = -A.$$

Since  $z$  solves

$$z(0) = -\tilde{A} \leq -A, \quad z'(t) = \tilde{h}(t, z(t)) \leq h(t, z(t)),$$

we have from the first part of the Lemma that  $z(t) \leq y_1(t)$  as far to the right of zero as  $y_1$  exists. Let

$$t_1 = \min\{t \in [0, b] : z(t) = 0\}.$$

Since the maximal solution  $y_1$  can be extended until it leaves the set  $[0, b] \times [-A, B]$ , there must exist  $T_1 \leq t_1$  such that  $y_1(T_1) = 0$ . From the differential equation (8) we get that  $y_1'(T_1-) = 0$ .

Let  $y_2(t)$  be the minimal solution of the terminal value problem

$$y_2' = h(t, y_2), \quad y_2(b) = B$$

and let

$$t_2 = \max\{t \in [0, b] : z(t) = 0\}.$$

Necessarily  $t_2 \geq t_1$ . By the second part of the Lemma we have that  $y_2(t) \leq z(t)$  as far to the left of  $b$  as  $y_2$  exists; as before it follows that there is a  $T_2 \geq t_2$  such that  $y_2$  is defined on  $[T_2, b]$  and  $y_2(T_2) = y_2'(T_2+) = 0$ . Since  $T_2 \geq T_1$ , it follows that

$$y(t) \equiv \begin{cases} y_1(t), & 0 \leq t < T_1, \\ 0, & T_1 \leq t \leq T_2, \\ y_2(t), & T_2 < t \leq b, \end{cases}$$

is a classical solution of the two-point boundary value problem (8).

This comparison theorem can be used both to prove existence and to prove nonexistence of solutions of the two-point boundary value problem. As an example of the former, the following result is immediate.

**COROLLARY.** *Let  $f, g, A, B, b$  satisfy the hypotheses of Theorem 1, and let*

$$h(t, y) \geq g(t)f(y),$$

*where  $h$  also satisfies hypotheses (ii)–(iii) of Theorem 3. Then the boundary value problem (8) has at least one solution.*

**THEOREM 4.** *Let  $A, B > 0$ ; let  $h(t, y) \geq 0$  for  $(t, y) \in [0, b] \times [-A, B]$  and vanish precisely when  $y = 0$ ; let  $h$  be continuous on  $[0, b] \times [-A, B]$  and locally Lipschitz on  $[0, b] \times ([-A, 0) \cup (0, B])$ . Then the two-point boundary value problem*

$$y' = h(t, y), \quad y(0) = -A, \quad y(b) = B$$

*cannot have two distinct solutions.*

The proof does not differ materially from that of Theorem 2 and so will be omitted, as will the extension to multi-point problems.

**REMARK.** The simple technique employed here can be applied readily to other forms of boundary conditions; for example, to the integral conditions imposed in [5].

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