

ISOTHERMIC SURFACES AND THE GAUSS MAP

BENNETT PALMER

(Communicated by David G. Ebin)

ABSTRACT. We give a necessary and sufficient condition for the Gauss map of an immersed surface M in n -space to arise simultaneously as the Gauss map of an anti-conformal immersion of M into the same space. The condition requires that the lines of curvature of each normal section lie on the zero set of a harmonic function. The result is applied to a class of surfaces studied by S. S. Chern which admit an isometric deformation preserving the principal curvatures.

1. Introduction. The classical Gauss map of a surface in \mathbf{R}^3 assigns to a point the unit normal vector to the surface. For a surface in \mathbf{R}^N the Gauss map assigns to a point the tangent plane which may be identified with a point in a quadric $Q^{N-2} \subset \mathbf{C}P^{N-1}$.

In recent years several papers have discussed the determination of a surface by its Gauss map. The results of K. Kenmotsu [6] show that a smooth map from a Riemann surface R to the 2-sphere, satisfying an integrability condition, factors through a conformal immersion

$$(1.1) \quad X: R \rightarrow M^2 \subset \mathbf{R}^3$$

as the Gauss map. Kenmotsu's integrability condition explicitly involves the conformal structure of R and a real valued function h which is to be the mean curvature of M .

In [3] Hoffman and Osserman give conditions on a map

$$(1.2) \quad g: R \rightarrow Q^{N-2}$$

involving only the complex structure of R , which are necessary and sufficient for the map to arise as the Gauss map of a conformal immersion

$$(1.3) \quad X: R \rightarrow \mathbf{R}^N.$$

Their results essentially imply that a conformal immersion of a Riemann surface R into \mathbf{R}^N is determined by its Gauss map, provided the mean curvature is not identically zero at some point.

Since a single map as in (1.2) determining multiple conformal immersions is in general excluded, a natural question to consider is when such a map arises simultaneously as the Gauss map of both a conformal and anti-conformal immersion. This question turns out to have a simple geometric answer which requires the following definition:

DEFINITION. A surface $M \subset \mathbf{R}^N$ is *isothermic* if, locally, there exist a pair of harmonic functions u_1, u_2 such that the lines of curvature of each smooth section of

Received by the editors December 1, 1987.

1980 *Mathematics Subject Classification* (1985 *Revision*). Primary 53A05; Secondary 53C42.

the normal bundle are contained in a level set $u_j = \text{const}$. This is a generalization of a classical definition which can be found in [2].

THEOREM I. *Let*

$$(1.4) \quad g: R \rightarrow Q^{N-2}$$

be the Gauss map of a conformal immersion of an orientable surface M :

$$(1.5) \quad X: R \rightarrow M \subset \mathbf{R}^N.$$

Then there exists an anti-conformal immersion

$$(1.6) \quad \tilde{X}: R \rightarrow \tilde{M} \subset \mathbf{R}^N$$

such that the following diagram commutes

$$\begin{array}{ccc} R & \xrightarrow{g} & Q^{N-2} \\ & \searrow \tilde{X} & \nearrow \text{Gauss Map} \\ & & \tilde{M} \end{array}$$

if and only if M is isothermic. The surface \tilde{M} is unique (modulo similarity transformations of \mathbf{R}^N) provided M is not totally umbilic.

There are abundant examples of isothermic surfaces. We list a few.

- (1) Constant mean curvature surfaces in \mathbf{R}^3 .
- (2) Surfaces of revolution in \mathbf{R}^3 .
- (3) Constant mean curvature surfaces $M^2 \subset S^3 \subset \mathbf{R}^4$.

In addition, we note the following properties of isothermic surfaces which when combined with the above furnish more examples:

- (1) $f(M)$ is isothermic if M is isothermic and $f: \mathbf{R}^N \rightarrow \mathbf{R}^N$ is conformal.
- (2) If $X: R \rightarrow M \subset \mathbf{R}^N$ is isothermic then

$$\underbrace{X \oplus X \oplus \dots \oplus X}_k: M \rightarrow \mathbf{R}^{Nk}$$

is isothermic.

In part 4 we apply the main result to a class of surfaces studied by S. S. Chern in [1]. These are surfaces of nonzero mean curvature which admit a nontrivial isometric deformation preserving the principal curvatures. We show first that these surfaces are isothermic and second that the surface \tilde{M} described above has the property that its mean curvature is the reciprocal of a harmonic function.

2. Preliminaries. Let R be a simply connected Riemann surface and

$$(2.1) \quad X: R \rightarrow M \subset \mathbf{R}^3$$

a smooth, conformal immersion. We assume M is orientable. After choosing a complex coordinate $z = u_1 + iu_2$ on R , the metric induced by (2.1) has an expression

$$(2.2) \quad ds_M^2 = e^\rho |dz|^2$$

for a smooth function $\rho = \rho(z)$ on R . Locally on M we may choose an orthonormal frame $\{\xi^r\}_{r=3,\dots,N}$ for the normal bundle $N(M)$. Differentiating ξ^r defines

$$(2.3) \quad d\xi^r = -A_r(\cdot) + \nabla_{(\cdot)}^\perp \xi^r.$$

The terms on the right-hand side are respectively the tangential and normal components of $d\xi^r$. At each point of M , $-A_r$ is a selfadjoint endomorphism of the tangent plane. Its eigenvalues β_j^r ; $j = 1, 2$ are the principal curvatures of ξ^r . The corresponding eigenvectors are the principal directions and their integral curves are the lines of curvature. These curves exist away from the ξ^r umbilics which are those points of M where $\beta_1^r = \beta_2^r$.

The second fundamental forms are defined by

$$(2.4) \quad \Pi_p^r(X, Y) = ds_M^2(X, A_r(Y)), \quad X, Y \in T_pM.$$

The trace of Π^r is twice the r th mean curvature

$$(2.5) \quad h^r = \frac{1}{2}(\beta_1^r + \beta_2^r).$$

On R , Π^r has an expression

$$(2.6) \quad \Pi^r = 2 \operatorname{Re} \left(\frac{\phi^r}{2} dz \otimes dz + h^r \frac{e^\rho}{2} dz \otimes d\bar{z} \right).$$

The quantities

$$(2.7) \quad q^r \equiv \phi^r dz \otimes dz$$

define invariant quadratic differentials on M . Under change of complex coordinate

$$(2.9) \quad z_1 = z_1(z), \quad \frac{dz_1}{d\bar{z}} = 0,$$

q^r transforms according to

$$(2.10) \quad q^r = \phi^r dz \otimes dz = \phi^r \left(\frac{dz}{dz_1} \right)^2 dz_1 \otimes dz_1;$$

that is

$$(2.11) \quad \phi_1^r = \phi^r \left(\frac{dz}{dz_1} \right)^2.$$

The zeros of q^r are precisely the ξ^r umbilics. See [5] for details.

The quantities defined above appear as coefficients of the structural equations for the immersion

$$(2.12) \quad \begin{cases} X_{zz} = \rho_z X_z + \frac{1}{2} \sum_r \phi^r \xi^r, \\ X_{z\bar{z}} = \frac{e^\rho}{2} \sum_r h^r \xi^r, \\ \xi_z^r = -h^r X_z - \phi^r e^{-\rho} X_{\bar{z}} + \sum_t S_r^t \xi^t, \end{cases}$$

(and their conjugates) where S_r^t are defined by

$$(2.13) \quad \nabla_z^\perp \xi^r = \sum_{t=3}^N S_r^t \xi^t.$$

The well-known integrability conditions of (2.12) are the Gauss equation

$$(2.14) \quad \rho_{z\bar{z}} = \frac{1}{2} \sum_r (\phi^r \bar{\phi}^r e^{-\rho} - (h^r)^2 e^\rho),$$

the Codazzi equations

$$(2.16) \quad (\phi^r)_{\bar{z}} + \sum_t \phi^t (\bar{S}_t^r) = e^\rho (h^r)_z + \sum_t e^\rho h^t S_t^r$$

and the Ricci equations

$$(2.17) \quad \text{Im} \left\{ (S_r^t)_{\bar{z}} - \frac{e^{-\rho}}{2} \phi^r \bar{\phi}^t + \sum_{l=3}^N S_r^l \bar{S}_l^t \right\} = 0, \quad 3 \leq r, t \leq N.$$

We define the Gauss map of

$$(2.18) \quad X: R \rightarrow M \subset \mathbf{R}^N$$

following [2]. Consider the quadratic

$$Q^{N-2} = \{[\zeta] \in \mathbf{C}P^{N-1} | \zeta \cdot \zeta = 0\}.$$

Here [] denotes equivalence class. Since X is conformal, one has

$$(2.19) \quad X_z \cdot X_z = 0$$

and we define the Gauss map

$$(2.20) \quad \begin{aligned} g: M &\rightarrow Q^{N-2}, \\ p &\rightarrow [X_z], \end{aligned}$$

where p is a point on M with coordinate z . We will also use g to denote this map pulled back to R via X . Many details and interesting properties of g may be found in [3 and 4].

3. Main result. The proposition below gives simple coordinate-dependent criteria for a surface to be isothermic.

PROPOSITION 3.1. *M is isothermic if and only if locally there exists an isothermal parameter $z = u + iu_2$ with*

$$(3.1) \quad \text{Im } \phi^r(z) = 0, \quad r = 3, \dots, N.$$

PROOF. Assume (3.1) holds and write

$$(3.2) \quad \Pi^r = \sum_{i,j=1,2} L_{ij}^r du_i \otimes du_j.$$

An easy computation shows

$$(3.3) \quad \phi^r = \frac{L_{11} - L_{22}}{2} - iL_{12}$$

so that (3.2) implies

$$(3.4) \quad \Pi^r = L_{11}^r du_1 \otimes du_1 + L_{22}^r du_2 \otimes du_2$$

and the lines of curvature are the coordinate curves.

On the other hand suppose u_1, u_2 are harmonic functions such that the lines of curvature are contained in a level set $\{u_j = \text{const.}\}$. Since the lines of curvature intersect orthogonally, u_1 and u_2 are harmonic conjugates. Define

$$(3.5) \quad z_1 = u_1 \pm iu_2,$$

the sign chosen so that $z_1 = z_1(z)$ is holomorphic. The lines of curvature are the solutions of

$$(3.6) \quad \operatorname{Im} \phi^r dz^2 = 0$$

(see [5] for details). Since ∇u_1 (resp. ∇u_2) is tangent to the level curves $u_2 = \text{const.}$ (resp. $u_1 = \text{const.}$), (3.6) implies

$$(3.7) \quad \operatorname{Im} \phi^r dz \otimes dz(\nabla u_j, \nabla u_j) = 0.$$

Using

$$(3.8) \quad \nabla u_j = 2e^{-\rho}(u_{j\bar{z}}X_z + u_{jz}X_{\bar{z}}), \quad j = 1, 2,$$

this gives

$$(3.9) \quad \operatorname{Im} \phi(u_{j\bar{z}})^2 = 0, \quad j = 1, 2.$$

The Cauchy-Riemann equations applied to u_1, u_2 give

$$(3.10) \quad u_{1\bar{z}} = -iu_{2\bar{z}}$$

and we find

$$\begin{aligned} 0 &= \operatorname{Im} \phi^r \cdot (u_{1\bar{z}}^2 - u_{2\bar{z}}^2 \pm 2u_{1\bar{z}}^2) \\ &= \operatorname{Im} \phi^r \cdot (u_{1\bar{z}}^2 - u_{2\bar{z}}^2 \mp 2iu_{1\bar{z}}u_{2\bar{z}}) \\ &= \operatorname{Im} \phi^r \cdot (u_{1\bar{z}} \mp iu_{2\bar{z}})^2 \\ &= \operatorname{Im} \phi^r \left(\frac{d\bar{z}_1}{d\bar{z}} \right)^2 \\ &= \operatorname{Im} \phi^r \left(\frac{dz}{dz_1} \right)^2 \left| \frac{dz_1}{dz} \right|^2. \end{aligned}$$

Therefore

$$(3.11) \quad \operatorname{Im} \phi^r \left(\frac{dz}{dz_1} \right)^2 = 0$$

and by Proposition (3.1) the coordinate $u_1 \pm iu_2$ is as required.

PROOF OF THEOREM I. Let

$$(3.12) \quad g: R \rightarrow Q^{N-2} \subset \mathbb{C}P^{N-1}$$

represent the Gauss map of

$$(3.13) \quad X: R \rightarrow M \subset \mathbb{R}^N.$$

The existence of \tilde{X} is equivalent to the existence of a smooth \mathbb{C} -valued function f on R such that

$$(3.14) \quad e^f X_z = \tilde{X}_{\bar{z}}$$

i.e.,

$$(3.15) \quad [\tilde{X}_{\bar{z}}] = [X_z] \in Q^{N-2}.$$

The differential equation (3.14) for \tilde{X} will be integrable provided

$$(3.16) \quad \operatorname{Im}(\partial_z e^f X_z) = 0.$$

Using (2.12) this becomes

$$\begin{aligned} 0 &= \operatorname{Im} \left\{ e^f (f_z + \rho_z) X_z + e^f \sum_r \frac{1}{2} \phi^r \xi^r \right\} \\ &= \operatorname{Im} \left\{ (f_z + \rho_z) \tilde{X}_{\bar{z}} + e^f \sum_r \frac{1}{2} \phi^r \xi^r \right\}. \end{aligned}$$

Note that the structural equations (2.12) applied to the immersion \tilde{X} imply

$$(3.17) \quad f_z + \rho_z = 0$$

so we can write

$$(3.18) \quad f = \bar{g} - \rho$$

with $g_{\bar{z}} = 0$. (g is holomorphic.) This gives for all r ,

$$(3.19) \quad \operatorname{Im} e^{\bar{g}} \phi^r = 0.$$

Define a new isothermal coordinate

$$(3.20) \quad z_1 = \int^z e^{g/2} d\xi.$$

Then the transformation rule (2.11) for ϕ^r gives

$$(3.21) \quad \phi_1^r = e^{-g} \phi^r$$

and so (3.19) implies

$$(3.22) \quad \operatorname{Im} \phi_1^r = 0$$

and M is isothermic.

Conversely if $\operatorname{Im} \phi^r = 0$ for all r then define

$$(3.23) \quad \tilde{X}_{\bar{z}} = e^{-\rho} X_z$$

and one easily checks using (2.12) that

$$(3.24) \quad \operatorname{Im} \partial_z (e^{-\rho} X_z) = \operatorname{Im} \left(e^{-\rho(1/2)} \sum_r \phi^r \xi^r \right) = 0.$$

For the uniqueness of \tilde{M} , note that by [4] Theorem 2.3 the Gauss map of \tilde{M} ,

$$(3.25) \quad \tilde{g} = [\tilde{X}_{\bar{z}}] = [e^f X_z]$$

determines the immersion \tilde{X} (mod similarities) provided $\tilde{X}_{\bar{z}z} \neq 0$. However,

$$\tilde{X}_{\bar{z}z} = e^f \left((f_z + \phi_z) X_z + \sum_r \frac{\phi^r}{2} \xi^r \right).$$

The right-hand side cannot vanish identically unless $\phi^r \equiv 0$, $r = 3, \dots, N$, which is the totally umbilic case.

4. Application to a class of surfaces. In [1] S. S. Chern classified the umbilic free surfaces $M \subset \mathbf{R}^3$ which admit a nontrivial isometric deformation preserving the principal curvatures. Besides the classical examples of constant mean curvature surfaces, Chern found a second class of Weingarten surfaces with the property that the conformal metric

$$d\hat{s}^2 = \|\nabla h\|^2 (h^2 - K)^{-1} ds_M^2$$

has constant Gaussian curvature $\hat{K} = -1$. We will show these surfaces are isothermic and show the surfaces \tilde{M} obtained by Theorem I have an interesting property.

THEOREM II. *Let M be an umbilic free, nonminimal, surface in \mathbf{R}^3 admitting a nontrivial isometric deformation preserving the principal curvatures. Then*

(i) M is isothermic;

(ii) *If \tilde{M} is the surface obtained via Theorem I, the mean curvature \tilde{h} of \tilde{M} satisfies*

$$(4.1) \quad \tilde{\Delta} \left(\frac{1}{\tilde{h}} \right) = 0 \quad (\tilde{\Delta} \text{ is the Laplace-Beltrami operator on } \tilde{M}).$$

REMARK. If $h \equiv \text{const.}$ on M then the above result is well known. The surface \tilde{M} also has constant mean curvature so (4.1) holds trivially.

Following [1], introduce an orthonormal moving frame $\{e_1, e_2, e_3\}$ along M with e_1, e_2 the principal directions and e_3 the unit normal. Let ω_j be the dual one forms and as usual define ω_{ij} by

$$(4.2) \quad d\omega_i = \omega_{ij} \wedge \omega_j.$$

By choice of frame we have:

$$(4.3) \quad \omega_{13} = a\omega_1, \quad \omega_{23} = c\omega_2$$

where $a > c$ are the principal curvatures. Next introduce the one form

$$(4.4) \quad \theta_1 = \frac{2dh}{a - c}$$

Let α_1 be the symmetry of θ_1 with respect to the principal directions:

$$(4.5) \quad \alpha_1 = \theta_1 - 2 \left(\frac{2}{a - c} e_2(h) \right) \omega_2.$$

Let $*$ denote the Hodge star operator

$$(4.6) \quad *\omega_1 = \omega_2, \quad *\omega_2 = -\omega_1$$

and define

$$(4.7) \quad \theta_2 = *\theta_1, \quad \alpha_2 = *\alpha_1.$$

The Codazzi equations on M can be used to show (see [1])

$$(4.9) \quad d \log(a - c) = \alpha_1 + 2*\omega_{12}.$$

In addition we note the important formulas

$$(4.10) \quad \begin{array}{ll} \text{(a)} & d\alpha_1 = 0, \\ \text{(b)} & d\alpha_2 \wedge \alpha_2, \end{array}$$

which gives $\hat{K} = -1$ in the case $h \neq \text{const.}$

PROOF OF THEOREM III. We first show M is isothermic. By (4.9) and (4.10a) we have

$$(4.12) \quad d^* \omega_{12} = 0.$$

Locally we can define a function ρ by

$$(4.13) \quad {}^* \omega_{12} = \frac{-d\rho}{2}.$$

Define

$$(4.14) \quad du_j = e^{-\rho/2} \omega_j, \quad j = 1, 2.$$

Then (4.13) together with the structural equations (4.2) imply $ddu_j = 0$. The coordinates u_1, u_2 have the necessary property of Proposition 3.1 and M is isothermic.

We assume by the remark that $h \neq \text{const.}$ Using (3.23) we compute fundamental quantities on \tilde{M} denoted with "tilde",

$$(4.15) \quad \begin{aligned} \text{(i)} \quad & \tilde{\omega}_1 = e^{-\rho} \omega_1, & \tilde{\omega}_2 &= -e^{-\rho} \omega_2, \\ \text{(ii)} \quad & \tilde{a} = e^\rho a, & \tilde{c} &= -e^\rho c, \\ \text{(iii)} \quad & \tilde{h} = e^\rho \left(\frac{a - c}{2} \right). \end{aligned}$$

The Hodge star operator of \tilde{M} gives

$$(4.16) \quad \tilde{*} \tilde{\omega}_1 = \tilde{\omega}_2, \quad \tilde{*} \tilde{\omega}_2 = -\tilde{\omega}_1$$

which gives using (4.15(i))

$$(4.17) \quad \tilde{*} \omega_1 = -\omega_2, \quad \tilde{*} \omega_2 = \omega_1.$$

By (4.15(iii)), equation (4.1) is equivalent to

$$0 = d^{\tilde{*}} d(e^{-\rho}(a - c)^{-1}).$$

Compute

$$\begin{aligned} d^{\tilde{*}} d(e^{-\rho}(a - c)^{-1}) &= -d^{\tilde{*}} e^{-\rho} [(a - c)^{-1} d\rho - (a - c)^{-1} d \log(a - c)] \\ &= -d^{\tilde{*}} e^{-\rho} [(a - c)^{-1} d\rho - (a - c)^{-1} (\alpha_1 - d\rho)] \quad (\text{by (4.9), (4.13)}) \\ &= d^{\tilde{*}} e^{-\rho} (a - c)^{-1} \alpha_1 \\ &= -de^{-\rho} (a - c)^{-1} \alpha_2 \quad (\text{by (4.5), (4.18)}) \\ &= e^{-\rho} [(a - c)^{-1} d\rho \wedge \alpha_2 + (a - c)^{-1} d \\ &\quad \cdot \log(a - c) \wedge \alpha_2 + (a - c)^{-1} d\alpha_2] \\ &\quad \quad \quad (\text{by (4.9), (4.10b)}) \\ &= e^{-\rho} [(a - c)^{-1} d\rho \wedge \alpha_2 + (a - c)^{-1} d \\ &\quad \cdot (\alpha_1 - d\rho) \wedge \alpha_2 - (a - c)^{-1} \alpha_1 \wedge \alpha_2] \\ &= 0. \end{aligned}$$

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DEPARTMENT OF MATHEMATICS, UNIVERSITY OF CALIFORNIA, SANTA CRUZ, CALIFORNIA 95064