

ON THE RETARDED LIÉNARD EQUATION

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ABSTRACT. We consider the equation $x'' + f(x)x' + g(x(t-h)) = 0$ in which f , g are continuous with $f(x) > 0$ for $x \in R$, h is a nonnegative constant, and $xg(x) > 0$ if $|x| \geq k$ for some $k \geq 0$. Necessary and sufficient conditions are given for boundedness of all solutions and their derivatives. When $k = 0$ we give necessary and sufficient conditions for all solutions and their derivatives to converge to zero.

We consider the retarded Liénard Equation

$$(1) \quad x'' + f(x)x' + g(x(t-h)) = 0$$

in which h is a nonnegative constant and g , f are continuous with $f(x) > 0$ for all $x \in R$; it is supposed that exist constants $k \geq 0$ and $N > 1$ such that

$$(2) \quad xg(x) > 0, \quad x \left(\int_0^x f(\xi) d\xi - Nhg(x) \right) > 0 \quad \text{if } |x| \geq k.$$

Equation (1), with or without delay, has attracted considerable attention for more than fifty years, particularly in the theory of asymptotic behavior of solutions (cf. [1–16]). In 1965 Burton [3] obtained the following result:

Theorem B. *Suppose that f and g are continuous with $f(x) > 0$, $xg(x) > 0$ if $x \neq 0$. Then the zero solution of (1) with $h = 0$ is globally asymptotically stable if and only if*

$$(3) \quad \int_0^{\pm\infty} [f(x) + |g(x)|] dx = \pm\infty.$$

Much effort has gone into the modification of signum conditions on f and g when boundedness of solutions is considered (cf. [4, 6, 12, 13, 14, 15]).

For the retarded equation (1), it is often assumed that

$$(4) \quad |g'(x)| \leq L \quad \text{for some constant } L > 0$$

and

$$(4^*) \quad xg(x) > 0 \quad (x \neq 0), \quad f(x) > hL$$

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in order to obtain the results on boundedness and stability (cf. [2, 9, 16]). It is clear that (2) is a generalization of (4*).

We consider the following questions: Is condition (3) still necessary and sufficient for boundedness and stability of solutions of (1)? For the case $h > 0$, is Theorem B still valid when condition (4) is not satisfied? We have an affirmative answer to these questions.

A system equivalent to (1) is

$$(5) \quad \begin{cases} x' = y \\ y' = -g(x(t-h)) - f(x)y. \end{cases}$$

Notice that condition (2) guarantees the global existence of solutions of system (5) for increasing t . Let R^+ , R denote the intervals $[0, +\infty)$ and $(-\infty, +\infty)$ respectively. If x or y is written without its argument then the argument is t . We also denote by $V'(t)$ the upper right-hand derivative of $V(t)$ with respect to t if no confusion occurs.

Theorem 1. *If (2) is satisfied, then all solutions of (5) are bounded if and only if (3) holds.*

Proof. Define $F(x) = \int_0^x f(\xi) d\xi$, $G(x) = \int_0^x g(\xi) d\xi$, and let $x(t) = x(t, \phi, y_0)$, $y(t) = y(t, \phi, y_0)$ be a solution of (5) with $\phi \in C([-h, 0], R)$, $x(\xi) = \phi(\xi)$ for $\xi \in [-h, 0]$, and $y(0) = y_0$; then $(x(t), y(t))$ exists on R^+ . We now define

$$V_0(t) = \left[y(t) + F(x(t)) - \int_{-h}^0 g(x(t+s)) ds \right]^2 + 2G(x(t)) \\ + N \int_{-h}^0 \int_{t+s}^t |g(x(\tau))|^2 d\tau ds + P$$

where $P = 2 \sup\{|G(\xi)| : |\xi| \leq k\}$; then

$$V'_0(t) \leq -2(F(x(t)) - Nh g(x(t)))g(x(t)) - (N-1)h|g(x(t))|^2 \\ - (N-1) \int_{-h}^0 |g(x(t+s))|^2 ds.$$

Next define

$$(6) \quad V_1(t) = V_0(t) + \frac{1}{2}(N-1)h \int_{-h}^0 |g(x(t+s))|^2 ds;$$

then

$$(7) \quad V'_1 \leq -2(F(x(t)) - Nh g(x(t)))g(x(t)) - \frac{1}{2}(N-1)h|g(x(t))|^2 \\ - (N-1) \int_{-h}^0 |g(x(t+s))|^2 ds \\ = -\frac{3}{2}(F(x) - Nh g(x))g(x) - \frac{1}{2N}(N-1)F(x)g(x) \\ - \frac{1}{2N}(F(x) - Nh g(x))g(x) - (N-1) \int_{-h}^0 |g(x(t+s))|^2 ds \\ \leq -(N-1)F(x)g(x)/2N \quad \text{if } |x| \geq k.$$

Now define

$$(8) \quad V_2(t) = |y(t)| + \int_{-h}^0 |g(x(t+s))| ds.$$

We then have

$$(9) \quad V_2'(t) \leq -f(x(t))|y(t)| + |g(x(t))|.$$

We will use the following constants

$$\begin{aligned} f_0 &= \min\{f(x) : |x| \leq k\}, & g^* &= \max\{|g(x)| : |x| \leq k\}, \\ F_0 &= \min\{F(k), |F(-k)|\}, & F^* &= \max\{F(k), |F(-k)|\}, \\ & & \gamma &= F_0(N-1)/4N. \end{aligned}$$

Finally we define

$$(10) \quad V(t) = V_1(t) + \gamma V_2(t);$$

then

$$(11) \quad \begin{aligned} V'(t) &\leq -2(F(x(t)) - Nh g(x(t)))g(x(t)) - \frac{1}{2}(N-1)h|g(x(t))|^2 \\ &\quad - (N-1) \int_{-h}^0 |g(x(t+s))|^2 ds - \gamma f(x)|y(t)| + \gamma |g(x)|. \end{aligned}$$

Choose $Q > k$ such that $3g^*F^* + 2Nh[g^*]^2 - \gamma f_0(Q-k) < -1$ and consider $|x(t)| + |y(t)| \geq Q$:

If $|x(t)| \geq k$ then

$$\begin{aligned} V'(t) &\leq -\frac{1}{2N}(N-1)F(x)g(x) - \gamma f(x)|y(t)| + \gamma |g(x)| \\ &\leq -\gamma f(x)|y(t)| - (N-1)F(x)g(x)/4N. \end{aligned}$$

If $|x(t)| < k$ then $|y(t)| \geq Q - k$ and

$$\begin{aligned} V'(t) &\leq 2|F(x)||g(x)| + 2Nh|g(x)|^2 + \gamma |g(x)| - \gamma f(x)|y(t)| \\ &\leq 2F^*g^* + 2Nh[g^*]^2 + \gamma |g^*| - \gamma f_0(Q-k) < -1. \end{aligned}$$

Thus

$$(12) \quad V'(t) < 0 \quad \text{if } |x(t)| + |y(t)| \geq Q.$$

Notice also that

$$\begin{aligned} V'(t) &\leq -2|F(x) - Nh g(x)||g(x)| - (N-1)h|g(x)|^2/4 \\ &\quad - (N-1) \int_{-h}^0 |g(x(t+s))|^2 ds + M, \end{aligned}$$

where $M = 4 \max\{|F(\xi) - Nh g(\xi)||g(\xi)| : |\xi| \leq k\} + (N-1)F_0^2/16hN^2$. If there exists $t_1 > 0$ such that $V(0) < V(t_1)$ and

$$V(t_1) = \max_{0 \leq s \leq t_1} V(s),$$

then

$$|x(t_1)| + |y(t_1)| < Q$$

and

$$\frac{1}{4}(N - 1)h|g(x(t_1))|^2 + (N - 1) \int_{t_1-h}^{t_1} |g(x(s))|^2 ds \leq M.$$

By (10) it follows that

$$\begin{aligned} V(t_1) &= \left[y(t_1) + F(x(t_1)) - \int_{t_1-h}^{t_1} g(x(s)) ds \right]^2 + 2G(x(t_1)) \\ &\quad + N \int_{-h}^0 \int_{t_1+s}^{t_1} |g(x(\nu))|^2 d\nu ds + \frac{1}{2}(N - 1)h \int_{t_1-h}^{t_1} |g(x(s))|^2 ds + P \\ &\quad + \gamma|y(t_1)| + \gamma \int_{-h}^0 |g(x(t+s))| ds \\ &\leq 2[y(t_1) + F(x(t_1))]^2 + 2 \left(\int_{-h}^0 g(x(t_1+s)) ds \right)^2 + 2G(x(t_1)) \\ &\quad + Nh \int_{t_1-h}^{t_1} |g(x(s))|^2 ds + \frac{1}{2}(N - 1)h \int_{t_1-h}^{t_1} |g(x(s))|^2 ds + P \\ &\quad + \gamma|y(t_1)| + \gamma \int_{-h}^0 |g(x(t_1+s))|^2 ds + \gamma h \\ &\leq 4|y(t_1)|^2 + 4|F(x(t_1))|^2 + 2h \int_{-h}^0 |g(x(t_1+s))|^2 ds + P \\ &\quad + 2|G(x(t_1))| + \frac{2hNM}{N - 1} + \gamma Q + \frac{\gamma M}{N - 1} + \gamma h \\ &\leq 4|F(x(t_1))|^2 + 2|G(x(t_1))| + P + 4Q^2 + \frac{2hM}{N - 1} \\ &\quad + \frac{2NhM}{N - 1} + \gamma Q + \frac{\gamma M}{N - 1} + \gamma h. \end{aligned}$$

Let $\bar{K} = \max\{|F(\xi)|^2 + |G(\xi)| : |\xi| \leq Q\}$; then

$$V(t_1) \leq 6\bar{K} + 4Q^2 + \frac{(2h + 2Nh + \gamma)M}{N - 1} + P + \gamma(Q + h) \stackrel{\text{def}}{=} B.$$

Hence,

$$V(t) \leq V(0) + B \quad \text{for all } t \in R^+.$$

Consequently, we have $|y(t)| \leq (V(0) + B)/\gamma$ and

$$\left| \int_0^{x(t)} f(\xi) d\xi \right| + \left| \int_0^{x(t)} |g(\xi)| d\xi \right| \leq B^* \quad \text{for some } B^* > 0.$$

By condition (3), it follows that $|x(t)|$ is bounded on R^+ . This proves that (3) is sufficient.

Now we show that (3) is necessary. Suppose that condition (3) fails. To be definite, we assume that

$$\int_0^{+\infty} [f(s) + |g(s)|] ds < +\infty.$$

Let $\phi \in C([-h, 0], R)$ and $\phi(\xi) > k$, $\xi \in [-h, 0]$, $x_0 = \phi(0)$. Define

$$\tilde{g} = \max\{g(\phi(\xi)) : \xi \in [-h, 0]\}$$

and

$$y_0 = 2 + h\tilde{g} + \int_{x_0}^{+\infty} [f(\xi) + g(\xi)] d\xi.$$

Let $(x(t), y(t))$ be the solution of (5) with $x(\xi) = \phi(\xi)$, $\xi \in [-h, 0]$ and $y(0) = y_0$. We claim that $y(s) > 1$ for all $s \in R^+$.

Now suppose that there exists $t_1 > 0$ such that $y(t_1) = 1$ and $y(s) > 1$ on $[0, t_1)$. Consequently, $x(t)$ is increasing on $[0, t_1)$.

Case 1. Suppose that $t_1 \leq h$. Integrate the second equation in (5) from 0 to t_1 to obtain

$$\begin{aligned} y(t_1) &= y_0 - \int_0^{t_1} g(x(s-h)) ds - \int_0^{t_1} f(x(s))x'(s) ds \\ &\geq y_0 - h\tilde{g} - \int_{x(0)}^{x(t_1)} f(\xi) d\xi \geq y_0 - h\tilde{g} - \int_{x_0}^{+\infty} f(\xi) d\xi > 1, \end{aligned}$$

a contradiction.

Case 2. Suppose that $t_1 > h$. Integrating the second equation in (5) from 0 to t_1 , we have

$$\begin{aligned} y(t_1) &= y_0 - \int_0^h g(x(s-h)) ds - \int_h^{t_1} (g(x(s-h)) ds - \int_0^{t_1} f(x(s))x'(s) ds \\ &\geq y_0 - h\tilde{g} - \int_0^{t_1-h} g(x(s)) ds - \int_0^{t_1} f(x(s))x'(s) ds \\ &\geq y_0 - h\tilde{g} - \int_0^{t_1-h} g(x(s))x'(s) ds - \int_0^{t_1} f(x(s))x'(s) ds \\ &\geq y_0 - h\tilde{g} - \int_{x_0}^{+\infty} g(\xi) d\xi - \int_{x_0}^{+\infty} f(\xi) d\xi > 1, \end{aligned}$$

a contradiction. Thus $y(t) > 1$ on R^+ and $x(t) \geq t + x_0 \rightarrow +\infty$ as $t \rightarrow +\infty$. This completes the proof of Theorem 1.

Theorem 2. *If (2) is satisfied with $k = 0$, then the zero solution of (5) is globally asymptotically stable if and only if (3) holds.*

Proof. Suppose (2) and (3) hold with $k = 0$. It is clear from the proof of Theorem 1 that the zero solution of (5) is stable. Let $(x(t), y(t))$ be any solution of (5) and $V_1(t)$ be defined in (6), then by (7) we have

$$V_1'(t) \leq -(N - 1)F(x(t))g(x(t))/2N.$$

This implies that $\lim_{t \rightarrow +\infty} \inf |x(t)| = 0$.

Now suppose that $\lim_{t \rightarrow +\infty} \sup |x(t)| = \lambda > 0$. Then there exist sequences $\{t_n\}$, $\{t'_n\}$ such that $0 < t_n < t'_n$, $t_n \rightarrow +\infty$ as $n \rightarrow +\infty$ and

$$|x(t_n)| = \frac{\lambda}{3}, \quad |x(t'_n)| = \frac{2\lambda}{3}, \quad \left(\frac{\lambda}{3}\right) < |x(t)| < \frac{2\lambda}{3} \quad \text{on } (t_n, t'_n).$$

Let

$$\tilde{F} = \min \left\{ F(\xi)g(\xi) \mid \frac{\lambda}{3} \leq |\xi| \leq \frac{2\lambda}{3} \right\}.$$

Thus for $t \geq t'_n$, we have

$$\begin{aligned} V_1(t) &\leq V_1(t_1) - (N-1) \int_{t_1}^t F(x(s))g(x(s)) ds/2N \\ &\leq V_1(t_1) - (N-1) \sum_{j=1}^n \int_{t_j}^{t'_j} F(x(s))g(x(s)) ds/2N \\ &\leq V_1(t_1) - (N-1)\tilde{F} \sum_{j=1}^n (t'_j - t_j)/2N. \end{aligned}$$

Since (2) and (3) hold, there exists a constant $B > 0$ such that

$$|x(t)| + |y(t)| \leq B \quad \text{for } t \geq t_0.$$

Hence,

$$\frac{\lambda}{3} = \frac{2\lambda}{3} - \frac{\lambda}{3} \leq \int_{t_j}^{t'_j} |x'(s)| ds \leq B(t'_j - t_j)$$

and

$$\lambda \leq 3B(t'_j - t_j) \quad \text{for } j = 1, 2, \dots$$

This yields

$$V_1(t) \leq V_1(t_1) - \frac{(N-1)\tilde{F}n\lambda}{6NB} \rightarrow -\infty \quad \text{as } n \rightarrow +\infty,$$

a contradiction. Therefore, $\lim_{t \rightarrow +\infty} |x(t)| = 0$.

By (6) and (7), it follows that $V_1(t) \rightarrow C \geq 0$ as $t \rightarrow +\infty$ for some constant C . Since $x(t) \rightarrow 0$ as $t \rightarrow +\infty$, we have $y^2(t) \rightarrow C$ as $t \rightarrow +\infty$. Now suppose $C > 0$. Then there exists a constant $T > 0$ such that $t \geq T$ implies $y^2(t) \geq C/2$. Without loss of generality, we may assume that $y(t) \geq (C/2)^{1/2}$ for $t \geq T$. Thus $x'(t) \geq (C/2)^{1/2}$ for $t \geq T$ so that $x(t) \geq x(T) + (C/2)^{1/2}(t - T) \rightarrow +\infty$ as $t \rightarrow +\infty$, a contradiction. This yields $\lim_{t \rightarrow +\infty} y(t) = 0$. The proof of Theorem 1 shows that condition (3) is necessary for the global asymptotic stability of zero solution of (5). This completes the proof of Theorem 2.

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