

FIXED POINTS OF FINITE GROUPS OF FREE GROUP AUTOMORPHISMS

TAD WHITE

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ABSTRACT. We construct an equivariant collection of contractions of the compactified Culler-Vogtmann outer space \bar{X}_n . As a consequence, we prove that any finite subgroup of the outer automorphism group of a free group fixes a contractible subset of \bar{X}_n .

1. INTRODUCTION

Culler and Vogtmann [CV] initiated a study of the outer automorphism group $\text{Out}(F_n)$ of the free group F_n on n letters by constructing a space X_n upon which $\text{Out}(F_n)$ acts properly discontinuously. This space, which has since come to be known as the “outer space”, consists of projective classes of free minimal actions of F_n on simplicial metric trees, where two such trees are identified if they are equivariantly isometric. The quotient of each such tree by such an action is a finite marked metric graph in which each vertex has valence ≥ 3 . Here, “metric” means that each edge has a length, and a “marking” is a preferred homotopy equivalence of the wedge R_n of n circles to this graph. One thus has two possible views of X_n ; these are interchangeable. The group $\text{Out}(F_n)$ acts in the obvious way: one represents an automorphism of F_n as a self-map of R_n and precomposes the marking with this map.

Culler and Vogtmann showed that X_n is a finite-dimensional contractible space and that the $\text{Out}(F_n)$ -action has finite stabilizers and finite quotient. Furthermore, X_n has a natural compactification \bar{X}_n in which the boundary consists of certain actions of F_n on \mathbf{R} -trees with cyclic edge stabilizers. It is known that \bar{X}_n is contractible; this was first shown by Steiner [St] and, independently, by Skora [Sk]. Skora’s technique was to construct a path between two \mathbf{R} -trees, given a morphism between them. (A *morphism* is a map such that each segment in the domain \mathbf{R} -tree contains an initial arc which is mapped isometrically.) In this paper we generalize Skora’s methods to prove the following theorem:

Theorem. *Let \mathcal{Z} be the space of nontrivial semisimple actions of F_n on \mathbf{R} -trees. Then there is a continuous deformation $F : X_n \times \mathcal{Z} \times I \rightarrow \mathcal{Z}$ such that*

$$(1) \quad F(T_0, T_1, 0) = T_0;$$

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- (2) $F(T_0, T_1, 1) = T_1$;
- (3) $F(T_0, T_0, t) = T_0$ for all t ; and
- (4) F is equivariant under the diagonal action of $\text{Out}(F_n)$ on $X_n \times \mathcal{X}$.

The result also holds if we replace \mathcal{X} by the compactification $\overline{X}_n \subset \mathcal{X}$ of X_n . An immediate consequence is the following:

Corollary. *The subset X_G (resp. \overline{X}_G) of X_n (resp. \overline{X}_n) fixed by a finite subgroup G of $\text{Out}(F_n)$ is contractible.*

2. PRELIMINARIES

Group actions on R-trees. An **R-tree** is a metric space such that any two points are joined by a unique embedded arc, which is isometric to a finite interval in the real line. For a general exposition of the theory of group actions on **R-trees**, see, for example, [CM].

Let $G \times T \rightarrow T$ be an action of a finitely generated group G on an **R-tree**. The metric on T will be denoted by d or d_T as the context requires. The *translation length function* $l(g)$ determined by the action is the map $l : G \rightarrow \mathbf{R}$ defined by $l(g) = \min_{x \in T} d(x, gx)$. The *characteristic set* of g is $T_g = \{x \in T \mid d(x, gx) = l(g)\}$. Since $l(g) = l(xgx^{-1})$ for all $g, x \in G$, we may consider l as a real-valued function on the set C of conjugacy classes in G . Actions of G on **R-trees** T and T' are *projectively equivalent* if there is an equivariant homeomorphism from T to T' such that the induced pull-back metric on T differs from the original metric by a nonzero multiplicative constant.

An action is *irreducible* if no finite set of ends of T is invariant under G and *dihedral* if G interchanges a pair of ends. The action is *semisimple* if it is irreducible, dihedral, or trivial.

We now describe a topology, due to Paulin [P], on the space of actions of G on **R-trees**. An ε -*approximation* between two compact metric spaces K and L is a subdirect product $R \subset K \times L$ (i.e., the relation R surjects onto both K and L) such that if $x_0 R y_0$ and $x_1 R y_1$, then $|d(x_0, x_1) - d(y_0, y_1)| < \varepsilon$. Following Gromov [G], define $d_G(K, L) < \varepsilon$ if there exists an ε -approximation between K and L . More generally, suppose X is a G -metric space (i.e., a metric space with an associated G -action) and that P is a finite subset of G . An ε -approximation is P -*equivariant* if whenever $g \in P$, $x \in K$, $gx \in K$, $y \in L$, and $x R y$, then $gy \in L$ and $gx R gy$.

Now fix a compact $K \subset X$, a finite subset P of G , and $\varepsilon > 0$. Paulin [P] defines the basic neighborhood $U(X, K, P, \varepsilon)$ to be the collection of G -metric spaces Y such that there exists a compact $L \subset Y$ and a P -equivariant ε -approximation from K to L and uses these as a neighborhood base for a topology on G -metric spaces.

Skora [Sk] generalizes this to define a topology on a space \mathcal{E} of equivariant maps between G -metric spaces. We give the definitions here for completeness. If $\phi : X \rightarrow X'$ and $\psi : Y \rightarrow Y'$ are maps, an ε -*approximation* from ϕ to ψ is a pair of relations (R, R') such that

- (1) R and R' are ε -approximations from X to Y and from X' to Y' respectively; and
- (2) $x R y$ implies $\phi(x) R' \psi(y)$.

We endow a product $X \times X'$ with the uniform metric:

$$d((x_0, x'_0), (x_1, x'_1)) = \max\{d(x_0, x_1), d(x'_0, x'_1)\}.$$

Given ε -approximations R from X to Y and R' from X' to Y' , one sees that (R, R') is an ε -approximation from $X \times X'$ to $Y \times Y'$, where (R, R') is the product of R and R' as subsets of $X \times Y$ and $X' \times Y'$ respectively.

The notion of P -equivariance extends naturally to the case of ε -approximations between maps. Skora defines a topology on a space \mathcal{E} of equivariant maps between G -metric spaces as follows: Let $K \times K'$ be a compact subset of $X \times X'$, P a finite subset of G , and $\varepsilon > 0$. The basic neighborhood $U(\phi, K \times K', P, \varepsilon)$ of ϕ is the set of all maps $\psi : Y \rightarrow Y'$ in \mathcal{E} such that for some compact $L \times L' \subseteq Y \times Y'$, there is a P -equivariant, closed ε -approximation from $\phi|_K$ to $\psi|_L$. \mathcal{E} is then given the topology generated by these basic open sets.

A universal bundle. Fix a group G and a space \mathcal{X} of actions of G on \mathbf{R} -trees. In this section we introduce a bundle over \mathcal{X} which should be thought of as an analogue of the universal Teichmüller bundle over Teichmüller space. Although it is essentially a notational convenience, this bundle will be useful in describing some constructions later and in dealing with the assorted group actions which arise.

Definition 2.1. Let \mathcal{X} be a space of G -actions on \mathbf{R} -trees. The *tree bundle* $\mathcal{T}(\mathcal{X})$ over \mathcal{X} is the space $\{(T, x) \mid T \in \mathcal{X} \text{ and } x \in T\}$. If the \mathbf{R} -trees are simplicial, we further define the *vertex bundle* $\mathcal{V}(\mathcal{X})$ over \mathcal{X} to be the space $\{(T, v) \mid T \in \mathcal{X} \text{ and } v \text{ is a vertex of } T\}$. There is a natural G -action on each fiber of these bundles.

$\text{Aut}(G)$ acts naturally on $\mathcal{T}(\mathcal{X})$ by permuting the fibers. If we fix a group action $G \times T \rightarrow T$ in \mathcal{X} and $\phi \in \text{Aut}(G)$, we can define the image of this action under ϕ by precomposing:

$$G \times T \xrightarrow{\gamma} T \mapsto G \times T \xrightarrow{\gamma \circ (\phi \times \text{id})} T.$$

In $\mathcal{T}(\mathcal{X})$, then, we define $\phi(T, x) = (T', x')$ if there exists an isometry of pointed spaces $f : (T, x) \rightarrow (T', x')$ which induces ϕ in the sense that the following diagram commutes:

$$\begin{array}{ccc} G \times T & \longrightarrow & T \\ \phi \times f \downarrow & & f \downarrow \\ G \times T' & \longrightarrow & T' \end{array}$$

This action restricts to an action on $\mathcal{V}(\mathcal{X})$. Note that the “vertical” action of G on the fibers is simply the restriction of the $\text{Aut}(G)$ action to $\text{Inn}(G)$, and since $\text{Inn}(G)$ acts trivially on the base space, we recover the standard $\text{Out}(G)$ action on \mathcal{X} .

Finally, there is a natural topology on the tree bundle.

T and T' are close if there exists an approximating relation R between large compact subsets of T and T' , such that R is equivariant with respect to a large finite subset of G . Hence two points (T, x) and (T', x') in the

bundle are close if xRx' for such a relation R . We endow the vertex bundle with the topology it inherits from the tree bundle.

3. WEIGHTED LENGTH FUNCTIONS

Throughout this section, G denotes a finitely generated group. All actions of G are assumed to be minimal.

We now generalize the notions of translation length function and characteristic set. Let G act on T , and let λ be a real-valued function on G . The *weighted length function* $f_\lambda : T \rightarrow \mathbf{R}$ is defined to be $\sup_{g \in G} \lambda(g)d(x, gx)$. We define the *length* of λ to be the infimum of f_λ : $l(\lambda) = l_T(\lambda) = \inf_{x \in T} f_\lambda(x)$. (We will omit the subscript if the tree is clear from the context.) The *characteristic set* of λ is $T_\lambda = \{x \in T \mid f_\lambda(x) = l(\lambda)\}$.

Remarks. 1. For a general function λ , it may happen that $l(\lambda) = \infty$ and that $T_\lambda = T$. We will eventually restrict our attention to functions λ for which this does not occur, but remark that the definitions still make sense in this case.

2. Skora [Sk] considers the case in which λ is the characteristic function of a finite generating set of G . The arguments here have a slightly different flavor, since the weighting functions now have infinite support.

3. The standard translation length $l(g)$ of a group element g is recovered in this context by taking λ to be the function taking the value 1 at g and 0 elsewhere. Just as $l(g)$ is invariant under conjugacy in G , the length $l(\lambda)$ is invariant under the "inner" action of G on \mathbf{R}^G by conjugation.

There is a natural action of $\text{Aut}(G)$ on \mathbf{R}^G : given $\lambda \in \mathbf{R}^G$ and an automorphism ϕ of G , one can define $\phi(\lambda) = \lambda \circ \phi^{-1}$. The following lemma is immediate.

Lemma 3.1. *If $\phi \in \text{Aut}(G)$, $\lambda \in \mathbf{R}^G$, and f is an isometry from (T, v) to (T', v') inducing ϕ as in the preceding section, then:*

- (1) $l_{f(T)}(\lambda) = l_T(\phi(\lambda))$, and
- (2) $T_{\phi(\lambda)} = f(T_\lambda)$.

In other words, the generalized notions of length function and characteristic set are equivariant. \square

For the remainder of this section, we shall assume G acts freely on a simplicial \mathbf{R} -tree T (and hence $G = F_n$). We now choose, for each point of T , a weighting function on G :

Definition. Let $G \times T \rightarrow T$ be a free simplicial action. For any $x \in T$, define a weighting function $\lambda_{T,x} : G \rightarrow \mathbf{R}$ by $\lambda_{T,x}(g) = 1/d_T(x, gx)$ if $g \neq \text{id}$, and $\lambda_{T,x}(\text{id}) = 0$.

Then, for any semisimple action $G \times T' \rightarrow T'$, we let $f_{T,x} : T \rightarrow \mathbf{R}$ denote the weighted length function corresponding to $\lambda_{T,x}$:

$$f_{T,x}(y) = \sup_{g \in G} \lambda_{T,x}(g)d(y, gy) = \sup_{g \in G - \{\text{id}\}} \frac{d_{T'}(y, gy)}{d_T(x, gx)}.$$

We first analyze the behavior of the function $f_{T,x}$ on T . A priori, the supremum defining $f_{T,x}$ may not even be finite, so this is the first issue to be dealt with.

Lemma 3.2. *Suppose that G acts irreducibly on T . Then for each $x \in T$, the function $f_{T,x} : T \rightarrow \mathbf{R}$ is:*

- (1) *finite;*
- (2) *proper; and*
- (3) *has a unique minimum at x .*

Proof. (1) Fix $y \in T$. Then for any $g \in G$,

$$d(y, gy) \leq d(x, y) + d(x, gx) + d(gx, gy) = d(x, gx) + 2d(x, y),$$

so that $\lambda_{T,x}(g)d(y, gy) \leq 1 + 2d(x, y)/d(x, gx)$. But the action on T is free and simplicial, so $d(x, gx)$ is uniformly bounded away from zero for all $g \neq \text{id}$. Thus $\lambda_{T,x}(g)d(y, gy)$ is uniformly bounded in g , and thus $f_{T,x}(y) < \infty$.

(2) Let y be any point in T other than x . By the minimality of T , we can choose an element g of G such that x lies on the segment joining y to the axis of G . For such a g , $d(y, gy) = d(x, gx) + 2d(x, y)$. Hence $f_{T,x}(y)$ increases with $d(x, y)$. This also proves (3). \square

We shall require the following lemma:

Lemma 3.3. *Let $\lambda : G \rightarrow \mathbf{R}$ be a real-valued function. Suppose that $G \times T \rightarrow T$ is a free simplicial action such that the weighted length function f_λ is finite and proper on T . Then f_λ is finite and proper for any semisimple action of G on an \mathbf{R} -tree T' .*

Proof. Let $h : T \rightarrow T'$ be an edgewise-linear equivariant map. We use h to relate the behavior of f_λ on T' to its behavior on T . Since T has compact quotient, h is L -Lipschitz for some $L > 0$. Furthermore, h is onto, since the action on T' is minimal. Let $z \in T$ be an h -preimage of $y \in T'$. Then $d_{T'}(y, gy) \leq Ld_T(z, gz)$ for any $g \in G$. Thus $f_{\lambda'}(y) \leq Lf_\lambda(z)$. By the preceding lemma, f_λ is finite on T , so it is finite on T' . That $f_{\lambda'}$ is proper follows as in the preceding lemma. \square

Definition 3.4. Let Λ denote the set of real-valued functions λ on G such that the weighted length function $f_\lambda(x)$ is a proper, real-valued function for a free action of G on a simplicial \mathbf{R} -tree T . Since any two such actions are equivariantly quasi-isometric, the preceding lemma implies that Λ is independent of the choice of T . We remark that the weighted length function is automatically convex for each $\lambda \in \Lambda$, as each function $d_T(x, gx)$ is convex.

Remark. The correspondence $(T, x) \mapsto \lambda_{T,x}$ gives a continuous map from the tree bundle $\mathcal{T}(X_n)$ to \mathbf{R}^G . Lemma 3.2 thus says that the image of this map is contained in Λ .

Now suppose $\lambda \in \Lambda$, and let T be an \mathbf{R} -tree equipped with a semi-simple action of G . Since f_λ is convex and proper on T , its characteristic set T_λ is a nonempty compact subtree of T . We can then choose a “base point” $b(T, \lambda)$ in T by selecting the “center” of T_λ ; that is, the unique point y such that the ball at y of radius $(\text{diam } T_\lambda)/2$ is contained in T_λ . Hence $b(\cdot, \lambda)$ may be thought of as a section of the tree bundle $\mathcal{T}(\mathcal{X})$. The following shows that these sections are continuous and vary continuously with λ .

Proposition 3.5. *Let $G = F_n$ and Λ be as above. Let \mathcal{X} denote the space of semisimple actions of G on \mathbf{R} -trees and $\mathcal{T}(\mathcal{X})$ be the tree bundle over \mathcal{X} . Then the associated base point function $b : \mathcal{X} \times \Lambda \rightarrow \mathcal{T}(\mathcal{X})$ is continuous.*

The proof is essentially identical to that of Proposition 5.2 in [Sk]. More generally, if G is a finitely generated group, \mathcal{X} a space of actions of G on \mathbf{R} -trees, and Λ a collection of weight functions on G such that f_λ is finite and proper for each $\lambda \in \Lambda$ and each action in \mathcal{X} , then the same result holds.

Lemma 3.6. *b is equivariant under the action of $\text{Aut}(F_n)$ on $\mathcal{X} \times \Lambda$.*

Proof. This follows immediately from Lemma 3.1. \square

4. PATHS BETWEEN \mathbf{R} -TREES

In this section we take G to be the free group F_n of a fixed rank n . Recall [CV] that “outer space” is the space X_n of projective classes of minimal free actions of F_n on simplicial \mathbf{R} -trees. A map from a simplicial \mathbf{R} -tree to an arbitrary \mathbf{R} -tree is *transverse* if it is linear on each 1-simplex.

If f is any function, we will denote by $\mathcal{D}(f)$ and $\mathcal{R}(f)$ the domain and range of f .

Proposition 4.1. *Let \mathcal{X} be a space of nontrivial irreducible actions of F_n on \mathbf{R} -trees, and let $\mathcal{C} = \mathcal{C}(X_n, \mathcal{X})$ be the space of all equivariant transverse maps from simplicial \mathbf{R} -trees to elements of \mathcal{X} . Then there is a map $B: X_n \times \mathcal{X} \rightarrow \mathcal{C}$ such that $\mathcal{D}(B(Y, T)) = Y$, $\mathcal{R}(B(Y, T)) = T$, and $B(Y, Y) = \text{Id}_Y$ for all $Y \in X_n \cap \mathcal{X}$, $T \in \mathcal{X}$. Furthermore, B is equivariant with respect to the diagonal action of $\text{Out}(F_n)$ on $X_n \times \mathcal{X}$.*

Proof. Given $Y \in X_n$ and $T \in \mathcal{X}$, we use the base point map to define the image of a vertex v of Y : $B(Y, T)(v) = b(T, \lambda_{Y,v})$. Now extend the domain of $B(Y, T)$ to all of Y by mapping linearly on the edges of Y . Now $\lambda_{Y,v}$ is continuous, so $B(Y, T)$ is continuous by Lemma 3.3 and Proposition 3.5. $B(Y, T)$ is equivariant under $\text{Aut}(F_n)$ by Lemma 3.6. Finally, by Lemma 3.2, the weighted length function $f_{Y,v}$ on Y has a unique minimum at v , so $B(Y, Y)$ is the identity on the vertices of Y and hence on all of Y by linearity. \square

Remark. In the above proposition, it is essential that the action on the source \mathbf{R} -tree be free. If any $g \in F_n$ has a fixed point in Y , it is impossible in general to construct an equivariant map from Y to T .

Recall [Sk] that an (equivariant) *morphism* between \mathbf{R} -trees is an (equivariant) map such that each segment in the source \mathbf{R} -tree has a nontrivial initial segment which is mapped isometrically onto its image. Given a surjective morphism $\phi: T_0 \rightarrow T_1$, Skora constructs morphisms ϕ_{st} for $0 \leq s \leq t \leq 1$ such that $\phi_{01} = \phi$, $\phi_{st} \circ \phi_{rs} = \phi_{rt}$, and $\phi_{rs} = \text{id}$ whenever $\phi = \text{id}$. We will need the following result:

Proposition 4.2 [Sk, 4.8]. *Let G be a group, \mathcal{X} the space of all actions of G on \mathbf{R} -trees, and $\mathcal{C}(\mathcal{X})$ the space of all morphisms between elements of \mathcal{X} . Then the function*

$$\mathcal{C}(\mathcal{X}) \times \{(s, t) \mid 0 \leq s \leq t \leq 1\} \rightarrow \mathcal{C}(\mathcal{X})$$

defined via $(\phi, (s, t)) \mapsto \phi_{st}$ is continuous. Furthermore, this map is equivariant with respect to the natural action of $\text{Out}(F_n)$ on $\mathcal{C}(\mathcal{X})$.

Hence a morphism between two \mathbf{R} -trees determines a canonical path between them. We now improve Proposition 4.1 to promote $B(Y, T)$ to a morphism:

Proposition 4.3. *Let \mathcal{X} be the space of nontrivial semisimple actions of F_n on \mathbf{R} -trees, and let $\mathcal{E} = \mathcal{E}(\overline{X}_n, \mathcal{X})$ be the space of all equivariant transverse morphisms from elements of \overline{X}_n to elements of \mathcal{X} . Then there is a map $M : X_n \times \mathcal{X} \rightarrow \mathcal{E}$ such that the following hold for all $Y \in X_n, T \in \mathcal{X}$:*

- (1) $\mathcal{R}(M(Y, T)) = T$;
- (2) $\mathcal{D}(M(Y, T))$ is a simplicial \mathbf{R} -tree contained in the closure of the simplex of X_n containing Y ;
- (3) if T is a free simplicial action, so is $\mathcal{D}(M(Y, T))$;
- (4) $M(Y, Y) = \text{Id}_Y$; and
- (5) M is equivariant under the diagonal action of $\text{Out}(F_n)$.

Proof. For each 1-simplex σ in Y , $B(Y, T)$ maps σ linearly into T , dilating by some nonnegative number μ . Multiply the metric on σ by μ . Let Y' be the tree obtained from Y in this way. $B(Y, T)$ then induces a morphism $M(Y, T)$ from Y' to T . M clearly varies continuously with Y and T , and the conclusions all follow immediately from the corresponding properties of B . \square

Theorem 4.4. *There is a continuous function $F : X_n \times \overline{X}_n \times I \rightarrow \overline{X}_n$ such that*

- (1) $F(T_0, T_1, 0) = T_0$;
- (2) $F(T_0, T_1, 1) = T_1$;
- (3) $F(T_0, T_0, t) = T_0$ for all t ; and
- (4) F is equivariant under the diagonal action of $\text{Out}(F_n)$ on $X_n \times \overline{X}_n$.

Proof. Let $\phi = M(T_0, T_1)$ be the morphism from Proposition 4.3. (Since T_1 is a minimal action, ϕ is surjective.) There is a natural path in \overline{X}_n from T_0 to $T_2 = \mathcal{D}(M(T_0, T_1))$, since T_2 is in the closure of the simplex of X_n containing T_0 . Applying Proposition 4.2 to ϕ , we obtain a continuous path of nontrivial semisimple actions from T_2 to T_1 , given by $\alpha(t) = \mathcal{R}(\phi_{0t})$, $0 \leq t \leq 1$. This path will not in general be contained in the set \mathcal{X} of minimal actions. However, $[l(\alpha(t))]$ is a path from T_2 to T_1 which is contained in \mathcal{X} (by our identification) and, in fact, is contained in \overline{X}_n [Sk, Theorem 6.7]. The composition of these two paths gives a natural path in \overline{X}_n from T_0 to T_1 . If $M(T_0, T_0)$ is the identity morphism, F is the trivial path at T_0 . Since the morphism $M(T_0, T_1)$ is equivariant under the action of $\text{Out}(F_n)$, so is the path from T_0 to T_1 , and by Proposition 4.2, it varies continuously with T_0 and T_1 . \square

5. FINITE GROUPS OF AUTOMORPHISMS

Theorem 5.1. *The subset X_G (resp. \overline{X}_G) of X_n (resp. \overline{X}_n) fixed by a finite subgroup G of $\text{Out}(F_n)$ is contractible.*

Proof. By a theorem of Culler [Cu], G has a fixed point T_0 in X_n . By Theorem 4.4, we have a natural path from T_0 to any other fixed point T_1 . This path is contained in X_n (resp. \overline{X}_n) if T_1 is. By equivariance, each such path is fixed under $\text{Out}(F_n)$. Since these paths vary continuously with T_1 , we can contract X_G (resp. \overline{X}_G) continuously along these paths to the point T_0 . \square

Remarks. 1. The same argument shows that the fixed point set of any finite subgroup of $\text{Out}(F_n)$ in the space of all nontrivial semisimple actions of F_n on \mathbf{R} -trees is contractible.

2. For a finite subgroup G of $\text{Out}(F_n)$, Krstić and Vogtmann [KV] construct a subcomplex L_G of X_n on which the centralizer $C(G)$ acts with finite stabilizers and finite quotient. Their main result is the contractibility of L_G and hence an upper bound on the vcd of $C(G)$. Since L_G is an equivariant deformation retract of the fixed set X_G , Theorem 5.1 yields an alternate route to the contractibility of L_G .

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DEPARTMENT OF MATHEMATICS, UNIVERSITY OF CALIFORNIA, LOS ANGELES, CALIFORNIA 90024
 Current address: Department of Mathematics, University of California, Riverside, California 92521

E-mail address: tadpole@ucrmath.ucr.edu