

## RECURSIVE CONDITION FOR POSITIVITY OF THE ANGLE FOR MULTIVARIATE STATIONARY SEQUENCES

A. MAKAGON, A. G. MIAMEE, AND B. S. W. SCHRÖDER

(Communicated by Stanley Sawyer)

ABSTRACT. In this note a recursive type condition for positivity of the angle between past and future for  $q$ -variate stationary sequences is provided. In the case  $q = 2$  it gives a simple different proof of a result due to Solev and Tserkhtsvadze on basicity of bivariate stationary sequences.

Let  $Z$  denote the set of all integers,  $C$  be the set of complex numbers and  $C^q$  be the Cartesian product of  $q$  copies of  $C$ . The elements of  $C^q$  will be identified with column vectors. By  $L^2(C^q)$  we will denote the Hilbert space of all  $C^q$  valued functions on  $(-\pi, \pi]$  that are square integrable w.r.t. the Lebesgue measure  $dt$ . Let  $X = \{X^k(n) \in H : n \in Z, k = 1, \dots, q\}$  be a  $q$ -variate ( $q < \infty$ ) stationary sequence in a Hilbert space  $H$ ; i.e. for every  $k, j = 1, \dots, q$ , the inner product  $(X^k(n), X^j(m))$  depends only on  $n - m$ . Let  $M(X) = \overline{\text{sp}}\{X^k(n) : k = 1, \dots, q, n \in Z\}$ ,  $M_+(X) = \overline{\text{sp}}\{X^k(n) : k = 1, \dots, q, n \geq 0\}$  and  $M_-(X) = \overline{\text{sp}}\{X^k(n) : k = 1, \dots, q, n < 0\}$ .

**Definition 1.** A stationary sequence  $X$  is said to be of *positive angle* iff

$$(1) \quad \sup\{|(x, y)| : x \in M_+(X), y \in M_-(X), \|x\| = \|y\| = 1\} < 1.$$

If a stationary sequence  $X$  has a spectral density  $F'$  w.r.t. the Lebesgue measure (cf. [4]), then any  $q \times q$  matrix  $G$  satisfying  $G(t)^*G(t) = F'(t)$ ,  $dt$ -a.e., will be called a *square root* of  $F'$ . Note that for every  $x \in C^q$ ,  $G(\cdot)x \in L^2(C^q)$ . From [7], Theorem 4.5, it follows that  $X$  is of positive angle iff there exists a constant  $C$  such that for every  $C^q$ -valued trigonometric polynomial  $f$

$$(2) \quad \int_{-\pi}^{\pi} |G(t)P_+f(t)|^2 dt \leq C \int_{-\pi}^{\pi} |G(t)f(t)|^2 dt$$

where  $P_+$  is the orthogonal projection in  $L^2(C^q)$  onto  $L^2_+(C^q) = \overline{\text{sp}}\{e^{in \cdot} e_k : n \geq 0, k = 1, \dots, q\}$ .

**Definition 2.** The class of all  $q \times q$  matrix valued functions  $G$  with  $G(\cdot)x \in L^2(C^q)$  for all  $x \in C^q$ , such that (2) holds true for some  $C$  and all  $C^q$ -valued trigonometric polynomials  $f$  will be denoted  $\mathcal{PA}(q)$ .

---

Received by the editors April 26, 1996 and, in revised form, December 4, 1996.

1991 *Mathematics Subject Classification.* Primary 60G12, 60G25.

*Key words and phrases.* Multivariate stationary sequence, prediction theory, positive angle.

This research was supported by ONR Grant No. N 00014 - 89 - J - 1824.

The second author was supported by Army Research Office grant DAAH 04-96-1-0027.

The third author was supported by ONR Grant No. N 00014 - 95 - 1 - 0660.

It is well known that if a  $q$ -variate stationary sequence  $X$  is of positive angle then the spectral measure  $F$  of  $X$  is absolutely continuous w.r.t. the Lebesgue measure. Therefore  $X$  is of positive angle iff there is a square root  $G$  of the spectral density of  $X$  such that  $G \in \mathcal{PA}(q)$ . If  $q = 1$  then in [2] it was proved that  $X$  is of positive angle iff  $F' = |G|^2$  satisfies the so-called  $A_2$  condition, i.e. there is a constant  $C$  such that for each interval or its complement  $I \subset (-\pi, \pi]$

$$(3) \quad \left( \int_I |G(t)|^2 dt \right) \left( \int_I |G(t)|^{-2} dt \right) \leq C|I|^2$$

where  $|I|$  is the length of  $I$ .

In 1986 Solev and Tserkhtsvadze [8] obtained necessary and sufficient conditions for positivity of the angle for full rank bivariate stationary sequences. The conditions were in terms of the coefficients of a triangular square root of  $F'$ . The main idea of [8] can be summarized as follows.

**Theorem 1** ([8]). *Let  $G = \begin{bmatrix} \sigma & 0 \\ \tau & r \end{bmatrix}$ . The following conditions are equivalent:*

1.  $G$  belongs to  $\mathcal{PA}(2)$ .
2.  $|\sigma|^2$  and  $|r|^2$  satisfy the  $A_2$  condition and the mapping

$$\mathcal{A} : f \longrightarrow \left( \tau P_+ \frac{1}{\sigma} - r P_+ \frac{\tau}{\sigma r} \right) f$$

*extends to a continuous operator in  $L^2(C)$ .*

3.  $|\sigma|^2$  and  $|r|^2$  satisfy the  $A_2$  condition and the two mappings

$$\mathcal{A}_- : f \longrightarrow r P_- \frac{\tau}{r} P_+ \frac{1}{\sigma} f,$$

$$\mathcal{A}_+ : f \longrightarrow r P_+ \frac{\tau}{r} P_- \frac{1}{\sigma} f$$

*extend to continuous operators in  $L^2(C)$ .*

Having the above lemma the analytic conditions for the positivity of the angle provided by Solev and Tserkhtsvadze follow readily from Fefferman's theorem on the conjugate space of  $H^1$  (see [1]).

Below we prove a version of the theorem above for the  $q$ -variate case. In particular this leads to a simpler proof of Theorem 1.

Recall that if  $X$  is of positive angle then  $X$  is so-called  $J_0$  regular ([6]) and hence the range of the spectral density  $F' = \frac{dF}{dt}$  is constant  $dt$ -a.e. and for each  $x$  in the range the function  $|G^\#(\cdot)x|^2$  is integrable (see e.g. [3], Section 5), where  $G^\#$  stands for the generalized inverse matrix. Therefore, without loss of generality we can assume that the sequence  $X$  has a density which is of full rank.

**Lemma 1.** *Suppose that  $G^{-1}$  exists  $dt$ -a.e. Then  $G \in \mathcal{PA}(q)$  if and only if the operator  $GP_+G^{-1}$  sending  $f(\cdot) \longrightarrow G(\cdot)P_+G^{-1}(\cdot)f(\cdot)$  is bounded in  $L^2(C^q)$ .*

*Proof.* If  $G \in \mathcal{PA}(q)$  then from the remark preceding the lemma it follows that  $G^{-1}(\cdot)x \in L^2(C^q)$  for all  $x \in C^q$ . Moreover the inequality (2) extends to all  $f$  such that  $G(\cdot)f(\cdot) \in L^2(C^q)$ . Letting in (2)  $f = G^{-1}g$ , where  $g$  is a trigonometric polynomial, we obtain

$$(4) \quad \int_{-\pi}^{\pi} |G(t)(P_+G^{-1}(t)g(t))|^2 dt \leq C \int_{-\pi}^{\pi} |g(t)|^2 dt.$$

So  $GP_+G^{-1}$  is bounded. Conversely, if (4) extends to  $L^2(C^q)$ , then letting  $g = Gf$ , where  $f$  is a trigonometric polynomial we obtain (2).  $\square$

**Theorem 2.** *Suppose that  $G(t) = [g_{ij}(t)]_{i,j=1,\dots,q}$  is an invertible lower triangular matrix for every  $t \in (-\pi, \pi]$ . Denote  $G^{-1}(t) = H(t) = [h_{ij}(t)]_{i,j=1,\dots,q}$ . Let  $G_u(t)$  and  $G_l(t)$  be the  $(q-1) \times (q-1)$  matrices obtained from  $G(t)$  by removing the  $q$ -th row and the  $q$ -th column, and the 1-st row and the 1-st column, respectively. Then  $G \in \mathcal{PA}(q)$  if and only if*

- i)  $G_u \in \mathcal{PA}(q-1)$ ,
- ii)  $G_l \in \mathcal{PA}(q-1)$ ,
- iii) the mapping  $f \rightarrow \sum_{j=1}^q g_{qj}P_+h_{j1}f$  extends to a continuous operator in  $L^2(C)$ .

*Proof.* Note that since we are working with lower triangular matrices  $H_u = (G_u)^{-1}$  and  $H_l = (G_l)^{-1}$ . Write  $G$  as a sum of two  $q \times q$  matrices

$$\begin{aligned}
 G &= \begin{bmatrix} \begin{bmatrix} G_u \\ 0 \dots 0 \end{bmatrix} & \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} \\ \begin{bmatrix} 0 & \dots & 0 \end{bmatrix} & \begin{bmatrix} g_{q1} & \dots & g_{qq} \end{bmatrix} \end{bmatrix} + \begin{bmatrix} \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} & \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} \\ \begin{bmatrix} g_{11} & \dots & g_{1q} \end{bmatrix} & \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} \end{bmatrix} \\
 &= \begin{bmatrix} 0 & \dots & 0 \\ \vdots & G_l & \\ 0 & & \end{bmatrix} + \begin{bmatrix} g_{11} & \dots & g_{1q} \\ \vdots & & \\ g_{q1} & \dots & g_{qq} \end{bmatrix}.
 \end{aligned}$$

If we write  $G^{-1}$  as

$$G^{-1} = \begin{bmatrix} h_{11} & \dots & 0 \\ \vdots & & \\ h_{q1} & \dots & 0 \end{bmatrix} + \begin{bmatrix} 0 & \dots & 0 \\ \vdots & & \\ 0 & \dots & 0 \end{bmatrix} + \begin{bmatrix} 0 & \dots & 0 \\ \vdots & & \\ 0 & \dots & 0 \end{bmatrix} + \begin{bmatrix} 0 & \dots & 0 \\ \vdots & & \\ 0 & \dots & 0 \end{bmatrix},$$

then we obtain that

$$\begin{aligned}
 GP_+G^{-1} \begin{bmatrix} f_1 \\ f_2 \\ \vdots \\ f_q \end{bmatrix} &= GP_+G^{-1} \begin{bmatrix} f_1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} + GP_+G^{-1} \begin{bmatrix} 0 \\ f_2 \\ \vdots \\ f_q \end{bmatrix} \\
 &= \begin{bmatrix} G_uP_+ \begin{bmatrix} h_{11}f_1 \\ \vdots \\ h_{q-1,1}f_1 \end{bmatrix} \\ \sum_{j=1}^q g_{qj}P_+h_{j1}f_1 \end{bmatrix} + \begin{bmatrix} 0 & \dots & 0 \\ \vdots & & \\ 0 & \dots & 0 \end{bmatrix} + \begin{bmatrix} 0 & \dots & 0 \\ \vdots & & \\ 0 & \dots & 0 \end{bmatrix}.
 \end{aligned}$$

Therefore  $GP_+G^{-1}$  is bounded in  $L^2(C^q)$  iff

- A)  $G_lP_+G_l^{-1}$  is bounded in  $L^2(C^{q-1})$ ,
- B)  $f \rightarrow G_uP_+ \begin{bmatrix} h_{11}f \\ \vdots \\ h_{q-1,1}f \end{bmatrix}$  is bounded from  $L^2(C)$  to  $L^2(C^{q-1})$  and
- C)  $f \rightarrow \sum_{j=1}^q g_{qj}P_+h_{j1}f$  is bounded in  $L^2(C)$ .

If now we write

$$G^{-1} = \left[ \begin{array}{c|c} \left[ \begin{array}{c} G_u^{-1} \\ 0 \dots \end{array} \right] & \begin{array}{c} 0 \\ \vdots \\ 0 \end{array} \\ \hline \begin{array}{c} h_{q1} \\ \dots \\ h_{qq} \end{array} & \begin{array}{c} 0 \\ \dots \\ h_{qq} \end{array} \end{array} \right],$$

then

$$GP_+G^{-1} \begin{bmatrix} f_1 \\ \vdots \\ f_q \end{bmatrix} = \begin{bmatrix} G_uP_+G_u^{-1} \begin{bmatrix} f_1 \\ \vdots \\ f_{q-1} \end{bmatrix} \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ \vdots \\ 0 \\ \sum_{j=1}^q g_{qj}P_+\phi_j \end{bmatrix} + \begin{bmatrix} 0 \\ \vdots \\ 0 \\ g_{qq}P_+ \sum_{j=1}^q h_{qj}f_j \end{bmatrix}$$

where  $\phi_j$  is the  $j$ -th coordinate of  $G_u^{-1} \begin{bmatrix} f_1 \\ \vdots \\ f_{q-1} \end{bmatrix}$ . This shows that if  $GP_+G^{-1}$  is

bounded in  $L^2(C^q)$  then  $G_uP_+G_u^{-1}$  is bounded in  $L^2(C^{q-1})$ , which combined with A) and C) and Lemma 1 proves the necessity of conditions i) - iii).

Conversely, suppose that the conditions i) - iii) hold. Since  $G_uP_+G_u^{-1}$  is bounded, its restriction

$$G_uP_+G_u^{-1} \begin{bmatrix} f \\ 0 \\ \vdots \\ 0 \end{bmatrix} = G_uP_+ \begin{bmatrix} h_{11}f \\ \vdots \\ h_{q-1,1}f \end{bmatrix}$$

is also bounded and we conclude that the conditions A), B) and C) are satisfied. Thus  $GP_+G^{-1}$  is bounded, which in view of Lemma 1 completes the proof.  $\square$

Solev and Tserkhtsvadze's Theorem 1 is a simple consequence of the theorem above. It is enough to note that under the assumptions of Theorem 1

$$G^{-1} = \begin{bmatrix} \frac{1}{\sigma} & 0 \\ -\frac{1}{r\sigma} & \frac{1}{r} \end{bmatrix}.$$

For the equivalence of the second and third conditions observe first that if  $\sigma, r \in \mathcal{PA}(1)$  then  $rP_- \frac{1}{r} = 1 - rP_+ \frac{1}{r}$  and similarly  $\sigma P_- \frac{1}{\sigma}$  is bounded and so  $\mathcal{A}_- = rP_- \frac{1}{r} \mathcal{A}$  and  $\mathcal{A}_+ = -\sigma P_- \frac{1}{\sigma} \mathcal{A}$  are bounded. Conversely, boundedness of  $\mathcal{A}_+$  and  $\mathcal{A}_-$  clearly implies the boundedness of  $\mathcal{A}$  for  $\mathcal{A} = \mathcal{A}_- - \mathcal{A}_+$ .

REFERENCES

1. Fefferman, C. (1971). Characterizations of bounded mean oscillation. Bull. Amer. Math. Soc. 77, 587-588. MR 43:6713
2. Hunt, R. A., Muckenhoupt, B. and Wheeden, R. L. (1973), Weighted norm inequalities for the conjugate function and Hilbert transform, Trans. Amer. Math Soc. 176, 227-251. MR 47:701
3. Makagon, A. and Salehi, H. (1989), Notes on infinite dimensional stationary sequences. Probability Theory on Vector Spaces IV, Lecture Notes in Math. 1391, Springer-Verlag, 200-238. MR 91i:60103

4. Masani, P. and Wiener, N. (1957-58), The prediction theory of multivariate stochastic processes I and II, Acta Math. 98, 111 - 150, and 99, 93 - 137. MR **20**:4323; MR **20**:4325
5. Miamee, A. G. (1986), On the Angle between Past and Future for Multivariate Stationary Stochastic Processes, J. Mult. Anal. 20, 205 - 219. MR **88f**:60074
6. Miamee, A. G. and Pourahmadi, M. (1987), Degenerate multivariate stationary processes: Basicity, Past and Future and Autoregressive Representation, Sankhya Ser A. 49, 316-334. MR **91b**:62185
7. Pousson, H. R. (1968). Systems of Toeplitz operators on  $H^2$ , II, Trans. Amer. Math. Soc. 133, 527 - 536. MR **37**:3377
8. Solev, V. N. and Tserkhtsvadze, K. A. (1986), A condition for a stationary vector sequence to be a basis (Russian), Zap. Nauchn. Sem. Leningrad. Otdel. Mat. Inst. Steklov. (LOMI) 153. MR **88b**:60096

DEPARTMENT OF MATHEMATICS, HAMPTON UNIVERSITY, HAMPTON, VIRGINIA 26668  
*E-mail address:* makagon@hua.jai.cs.hamptonu.edu

*E-mail address:* miamee@cs.hamptonu.edu

*Current address,* B. Schröder: Program of Mathematics and Statistics, Louisiana Technical University, Ruston, Louisiana 71272

*E-mail address:* Schroder@engr.LaTech.edu