

WHITNEY PROPERTY IN TWO DIMENSIONAL SOBOLEV SPACES

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ABSTRACT. For $p > 1$, we prove that all the functions of $W_{\text{loc}}^{2,p}(\mathbb{R}^2)$ satisfy the Whitney property; i.e., if $u \in W_{\text{loc}}^{2,p}(\mathbb{R}^2)$ is such that $\nabla u = 0$ (in the sense of capacity) on a connected set $K \subseteq \mathbb{R}^2$, then u is constant on K .

1. INTRODUCTION

This paper deals with the Whitney property for Sobolev functions. In a regular context, a function $u \in C^k(\mathbb{R}^N)$, $k \geq 1$, is said to have the *Whitney property* if the following holds: for every connected set $K \subseteq \mathbb{R}^N$ such that $\nabla u(x) = 0$ for every $x \in K$, u is constant on K .

The Whitney property is clearly implied by the assumption that the set of critical values of u (namely the image of critical points) has zero measure. The problem of estimating the M -dimensional measure of the critical values of a function $u \in C^k(\mathbb{R}^N, \mathbb{R}^M)$ is the main object of the so-called *Morse-Sard Theorem*: it turns out [20] that if $k > \max\{N - M, 0\}$, then the M -dimensional Lebesgue measure of the critical values of u is zero. In the pioneering paper [22], Whitney constructed a function $u \in C^1(\mathbb{R}^2, \mathbb{R})$ which is not constant on a connected set of critical points. This example can be generalized to an N -dimensional setting proving that the requirement $k > \max\{N - M, 0\}$ in the Morse-Sard Theorem is sharp.

The problem of weakening the differentiability assumption in the Morse-Sard theorem has been addressed in several papers: we refer the reader to the articles of Bates [4], [5] and of Norton [18], where the cases of $u \in C^{N-M}(\mathbb{R}^N, \mathbb{R}^M)$, $N > M$, with $D^{N-M}u$ belonging to the family of Hölder continuous functions or to the Zygmund class are considered.

The Morse-Sard Theorem in the context of Sobolev spaces has been studied by De Pascale in [11] (see also [6] for some related results). He considers functions $u \in W_{\text{loc}}^{k,p}(\mathbb{R}^N, \mathbb{R}^M)$ with $N > M$, $k = N - M + 1$ and $p > N$: in this setting u has a C^1 representative by the Sobolev Embedding Theorem, so that the set of critical values is classically defined, and he proves that it has zero M -dimensional measure. In the case $M = 1$ and $N = 2$, this result implies that a function $u \in W_{\text{loc}}^{2,p}(\mathbb{R}^2)$ with $p > 2$ satisfies the Whitney property.

In this paper we discuss the Whitney property for Sobolev functions $u \in W_{\text{loc}}^{2,p}(\mathbb{R}^2)$ with $1 < p \leq 2$. This situation is critical for De Pascale [11], and the Morse-Sard

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theorem has an open issue (functions are not anymore C^1). Nevertheless, these functions admit continuous representatives, while their gradients, as elements of $W_{\text{loc}}^{1,p}(\mathbb{R}^2, \mathbb{R}^2)$, admit *quasicontinuous representatives* which are well defined up to sets with c_p -capacity zero (see Section 2 for the precise definitions). As a consequence, we consider sets K which are contained in the set of critical points of $u \in W_{\text{loc}}^{2,p}(\mathbb{R}^2)$, up to a set of zero capacity, i.e. $\nabla u(x) = 0$ for c_p -q.e. $x \in K$.

The main result of the paper consists in proving that all the functions of $W_{\text{loc}}^{2,p}(\mathbb{R}^2)$ with $1 < p \leq 2$ have the Whitney property in the following sense (see Theorem 4.3): if $K \subseteq \mathbb{R}^2$ is a connected set, and $u \in W_{\text{loc}}^{2,p}(\mathbb{R}^2)$ is such that $\nabla u = 0$ c_p -q.e. on K , then u is constant on K . In the case $p = 2$ and for compact connected sets K , the result was stated (without proof) by Sverák in [21]. Our approach is based on methods from potential theory for Sobolev maps and on a duality argument which is proper of the two dimensional context.

First, we consider the case in which K is bounded and connected, and $u \in W^{2,p}(\mathbb{R}^2)$. Using capacity properties of connected sets in the plane, and using p -fine continuity properties of functions in $W^{1,p}$ (see Lemma 4.1), we prove that it is not restrictive to consider K closed, i.e. compact. For some bounded open set Ω containing K , we prove that for every function $v \in W^{1,2}(\Omega \setminus K)$ we have (see Theorem 4.3 in Section 4)

$$(1.1) \quad \int_{\Omega \setminus K} R \nabla u \cdot \nabla v \, dx = 0$$

where R denotes a rotation of 90 degrees counterclockwise. The Whitney property follows since (1.1) turns out to imply (without any restriction for ∇u on K) the fact that u is constant on K (see Lemma 2.1). Notice that this certainly would be the case if ∂K were smooth enough to perform an integration by parts. In fact, since $R \nabla u$ is divergence free, the left-hand side of (1.1) reduces to an integration of the tangential derivative $D_\tau u$ on $\partial \Omega \cup \partial K$ against (the trace of) v , and so $D_\tau u$ should vanish since v is arbitrary. Here we prove that (1.1) implies that u is constant on K assuming only that K is connected, and with no other geometric restrictions on its shape.

Second, the case of an arbitrary connected set K is obtained by means of a slicing argument in polar coordinates, and employing classical Sard's theorem for the periodic one dimensional slicings in association with the first step. We emphasize at this point that the passage from bounded to unbounded sets K is not of a topological nature, and we give an example of a continuous function which is constant on all bounded connected subsets of an unbounded connected set K , but which is not constant on the set K .

The paper is organized as follows. In Section 2 we recall some basic facts concerning capacity for Sobolev spaces and some results employed in the proofs of the main theorems. In Section 3 we derive some properties of connected sets in relation with capacity which are essential in the proofs of the main results contained in Section 4.

2. NOTATION AND PRELIMINARIES

In this section we introduce the basic notation and recall some notions employed in the rest of the paper, which we give in a general N -dimensional setting even though our main result is two dimensional.

If $\Omega \subseteq \mathbb{R}^N$ is open and $1 \leq p \leq +\infty$, we denote by $L^p(\Omega)$ the usual space of p -summable functions on Ω with norm indicated by $\|\cdot\|_p$. $W^{1,p}(\Omega)$ will denote the Sobolev space of functions in $L^p(\Omega)$ whose gradient in the sense of distributions belongs to $L^p(\Omega, \mathbb{R}^N)$, and we denote by $W_0^{1,p}(\Omega)$ the closure in $W^{1,p}(\Omega)$ of smooth functions with compact support in Ω . With $W_{\text{loc}}^{1,p}(\mathbb{R}^N)$ we denote the space of function whose restriction to every relatively compact open set $\Omega \subseteq \mathbb{R}^N$ belongs to $W^{1,p}(\Omega)$.

If $E \subseteq \mathbb{R}^N$, we denote by E^c its complementary set, and by $|E|$ its N -dimensional Lebesgue measure. For $x \in \mathbb{R}^N$ and $r > 0$ we denote by $B_{x,r}$ the open ball with center x and radius r . Finally, by a curve γ connecting two points $x, \xi \in \mathbb{R}^N$ we mean a *continuous* function $\gamma : [a, b] \rightarrow \mathbb{R}^N$ such that $\gamma(a) = x$ and $\gamma(b) = \xi$: we will denote by $\gamma_{[x,\xi]}$ the compact and connected image $\gamma([a, b])$.

Capacity. For convenience, we recall the definition of c_p -capacity we use in the estimates of the Wiener criterion, but we refer the reader to [15] for details concerning capacity, quasi and fine continuity. Let Ω be a bounded open set and K a compact subset of Ω . We set

$$(2.1) \quad c_p(K, \Omega) := \inf \left\{ \int_{\mathbb{R}^N} |\nabla \varphi|^p + |\varphi|^p dx : \varphi \in C_c^\infty(\Omega), \varphi \geq 1 \text{ on } K \right\},$$

and extend this definition to open and arbitrary sets by interior and exterior approximation, respectively. Properties holding quasi-everywhere (written c_p -q.e.) are properties which hold in the complement of a set of zero capacity (recall that if $E \subseteq \Omega \cap \Omega'$, we have $c_p(E, \Omega) = 0$ if and only if $c_p(E, \Omega') = 0$, so that the notion of a set of zero capacity is independent of Ω , and we can write simply $c_p(E) = 0$).

Throughout the paper, we will identify a Sobolev function with its quasi-continuous representative. Notice that for $p > N$, the continuous representative of u (which exists by the Sobolev Embedding Theorem) is precisely the quasi-continuous representative.

A representation result. We will use often the following representation result whose proof relies on the Helmholtz decomposition of L^2 (see [10, Lemma 3.6] or [13, Lemma 3.4]).

Lemma 2.1. *Let $\Omega \subseteq \mathbb{R}^2$ be open and bounded, and let $q \geq 2$. Let $\psi \in L^q(\Omega, \mathbb{R}^2)$ be such that*

$$\int_{\Omega} \psi \cdot \nabla u \, dx = 0 \quad \text{for every } u \in W^{1,2}(\Omega).$$

Then there exists $\phi \in W^{1,q}(\mathbb{R}^2)$ constant on the connected components of Ω^c (in the case $q = 2$, constant c_2 -quasi-everywhere) and such that

$$\nabla \phi = R\psi \quad \text{in } \Omega,$$

where $R(a, b) := (-b, a)$ denotes a rotation of 90 degrees counterclockwise.

3. CONNECTED SETS AND CAPACITY

In this section we briefly justify that a connected set K in \mathbb{R}^N is “large” in the sense of c_p -capacity; i.e., if $\text{diam}K > 0$, $x \in K$ and $0 < r < \frac{1}{2}\text{diam}K$ we have

$$(3.1) \quad \frac{c_p(K \cap \overline{B}_{x,r}, B_{x,2r})}{c_p(\overline{B}_{x,r}, B_{x,2r})} \geq \frac{c_p([0, 1] \times \{0\}^{N-1}, B_{0,2})}{c_p(\overline{B}_{0,1}, B_{0,2})}.$$

Notice that the right-hand side of (3.1) is strictly positive for $p > N - 1$, and this justifies the expression “large in the sense of c_p -capacity”.

Inequality (3.1) was obtained in [8] in the case $N = 2$ and K compact, and extended in [9, Lemma 5.2] for arbitrary N . In this section we justify (3.1) for sets K which are only connected. We use the following inequality (see [9]) concerning the capacity of curves. Let us consider a curve $\gamma_{[x,\xi]} \subseteq \overline{B}_{x,r}$ in \mathbb{R}^N with extremes x and ξ , such that $\xi \in \partial B_{x,r}$. Then

$$(3.2) \quad c_p(\gamma_{[x,\xi]}, B_{x,2r}) \geq c_p([x, \xi], B_{x,2r})$$

where $[x, \xi]$ denotes the segment with extremes x and ξ . The proof of this result relies on the Steiner symmetrization (see [7]).

Proposition 3.1. *Let $K \subset \mathbb{R}^N$ be a connected set with $\text{diam}K > 0$. Then for all $x \in K$ and $0 < r < \frac{1}{2}\text{diam}K$ inequality (3.1) holds true.*

Proof. Let $x \in K$. We have to evaluate $c_p(K \cap \overline{B}_{x,r}, B_{x,2r})$. Recall that the capacity of $K \cap \overline{B}_{x,r}$ is the infimum of the capacity of all open sets in $B_{x,2r}$ which contain $K \cap \overline{B}_{x,r}$. Let $U \subseteq B_{x,2r}$ be such an open set, and let U_1 be the connected component of U containing x . We claim that

$$(3.3) \quad U_1 \cap \partial B_{x,r} \neq \emptyset.$$

In fact by contradiction, since $x \in U_1$ and U_1 is connected, we get $U_1 \subseteq B_{x,r}$. As a consequence we have that

$$(K \setminus \overline{B}_{x,r}) \cap \partial U_1 = \emptyset.$$

Clearly, since U contains $K \cap \overline{B}_{x,r}$ and $\partial U_1 \subseteq \partial U$, we have

$$(K \cap \overline{B}_{x,r}) \cap \partial U_1 = \emptyset,$$

so that we can write

$$K = (K \cap U_1) \cup (K \setminus \overline{U_1}),$$

which contradicts the fact that K is connected.

Taking into account (3.3), we can find $\xi_r \in U_1$ with $|\xi_r - x| = r$. Since U_1 is arcwise connected, there exists a continuous curve $\gamma_{[x,\xi_r]}$ contained in U_1 and joining x and ξ_r . By Lemma 3.2 we deduce that

$$c_p(U \cap \overline{B}_{x,r}, B_{x,2r}) \geq c_p(U_1 \cap \overline{B}_{x,r}, B_{x,2r}) \geq c_p(\gamma_{[x,\xi_r]} \cap \overline{B}_{x,r}, B_{x,2r}) \geq c_p([x, \xi_r], B_{x,2r}),$$

where $[x, \xi_r]$ denotes the segment joining x and ξ_r . We obtain

$$(3.4) \quad \frac{c_p(U \cap \overline{B}_{x,r}, B_{x,2r})}{c_p(\overline{B}_{x,r}, B_{x,2r})} \geq \frac{c_p([x, \xi_r], B_{x,2r})}{c_p(\overline{B}_{x,r}, B_{x,2r})}.$$

Since

$$\frac{c_p([x, \xi_r], B_{x,2r})}{c_p(\overline{B}_{x,r}, B_{x,2r})} = \frac{c_p([0, 1] \times \{0\}^{N-1}, B_{0,2})}{c_p(\overline{B}_{0,1}, B_{0,2})},$$

the result follows by taking the infimum over U in (3.4). □

From Proposition 3.1 we get the Wiener-type formula (3.5) for K : the limitations $N - 1 < p \leq N$ come from the fact that the result is trivial for $p > N$ since points have positive c_p -capacity, while inequality (3.1) (which we use to derive the result) gives no useful information for $p \leq N - 1$ since segments have zero c_p -capacity.

Proposition 3.2. *Let $K \subseteq \mathbb{R}^N$ be a connected set with $\text{diam}K > 0$, $x \in K$ and let $N - 1 < p \leq N$. Then*

$$(3.5) \quad \int_0^1 \left(\frac{c_p(K \cap B_{x,t}, B_{x,2t})}{c_p(B_{x,t}, B_{x,2t})} \right)^{\frac{1}{p-1}} \frac{dt}{t} = +\infty.$$

Proof. Let $\lambda \in]0, 1[$. Then we have the inequalities

$$c_p(K \cap B_{x,t}, B_{x,2t}) \geq c_p(K \cap \overline{B_{x,\lambda t}}, B_{x,2t}) \geq C_\lambda c_p(K \cap \overline{B_{x,\lambda t}}, B_{x,2\lambda t}),$$

where the last one comes by means of a rescaling argument for a suitable constant $C_\lambda > 0$. Taking into account that $c_p(\overline{B_{x,\lambda t}}, B_{x,2\lambda t}) = c_p(B_{x,\lambda t}, B_{x,2\lambda t})$, the result follows immediately from (3.1) since the right-hand side is strictly positive for $N - 1 < p \leq N$. \square

In fact a connected set K with positive diameter in \mathbb{R}^N is *uniformly p -thick* for $N - 1 < p \leq N$ (see [15, Section 6.41]). A similar notion has been studied in [17] and is referred to as *uniform fatness*.

4. THE MAIN RESULT

In order to prove the Whitney property in the Sobolev space context $W_{\text{loc}}^{2,p}(\mathbb{R}^2)$, we need some preliminary lemmas.

Lemma 4.1. *Let K be a connected subset of \mathbb{R}^2 . Let $1 < p \leq 2$ and let $v \in W_{\text{loc}}^{1,p}(\mathbb{R}^2)$ be such that $v = 0$ c_p -q.e. on K . Then $v = 0$ c_p -q.e. on \overline{K} .*

Proof. We have to show that $v(x) = 0$ for c_p -q.e. $x \in \overline{K} \setminus K$, where as usual we identify v with its quasicontinuous representative. Since v is quasicontinuous, by [16, Theorem 1.4] we have that v is *p -finely continuous* up to a set of c_p -capacity zero. This means that there exists a set A with $c_p(A) = 0$ such that for every $x \in \mathbb{R}^2 \setminus A$ there exists a set E with

$$(4.1) \quad \int_0^1 \left(\frac{c_p(E \cap B_{x,t}, B_{x,2t})}{c_p(B_{x,t}, B_{x,2t})} \right)^{\frac{1}{p-1}} \frac{dt}{t} < +\infty$$

such that (see [14, Theorem 3.17 and Corollary 3.18])

$$(4.2) \quad v(x) = \lim_{y \rightarrow x, y \notin E} v(y).$$

Let us show that $v(x) = 0$ for every $x \in \overline{K} \setminus (K \cup A)$. In view of (4.2), in order to get the conclusion it suffices to prove that there exists a sequence $y_n \in K \setminus (E \cup A)$ with $y_n \rightarrow x$, where E is the exceptional set relative to x . By contradiction, let us assume that there exists $\varepsilon > 0$ such that

$$(K \setminus (E \cup A)) \cap B_{x,\varepsilon} = \emptyset$$

so that

$$(4.3) \quad K \cap B_{x,\varepsilon} \subseteq E \cup A.$$

Since K is connected, one can use Proposition 3.2 and since the critical behavior of the integral is near $t = 0$, we obtain

$$\int_0^1 \left(\frac{c_p((K \cap B_{x,\varepsilon}) \cap B_{x,t}, B_{x,2t})}{c_p(B_{x,t}, B_{x,2t})} \right)^{\frac{1}{p-1}} \frac{dt}{t} = +\infty.$$

From (4.3), recalling that $c_p(A) = 0$, we get that

$$\int_0^1 \left(\frac{c_p(E \cap B_{x,t}, B_{x,2t})}{c_p(B_{x,t}, B_{x,2t})} \right)^{\frac{1}{p-1}} \frac{dt}{t} = +\infty,$$

which means that E does not satisfy (4.1), contradicting the assumption. The proof is thus concluded. \square

Notice that Lemma 4.1 has a natural extension to \mathbb{R}^N provided that $N - 1 < p \leq N$.

Lemma 4.2. *Let $\Omega \subseteq \mathbb{R}^2$ be an open bounded connected set with Lipschitz boundary, and let $K \subseteq \Omega$ be compact. Let $1 < p \leq 2$ and let $\Psi \in W_0^{1,p}(\Omega \setminus K, \mathbb{R}^2)$ with $\operatorname{div} \Psi = 0$. Then for every $v \in W^{1,2}(\Omega \setminus K)$ we have*

$$(4.4) \quad \int_{\Omega \setminus K} \Psi \cdot \nabla v \, dx = 0.$$

Proof. Notice that by the Sobolev Embedding Theorem we get that $\Psi = (A, B) \in L^{p^*}(\Omega \setminus K, \mathbb{R}^2)$, where p^* is the Sobolev exponent $p^* = \frac{2p}{2-p} > 2$, so that the integral in (4.4) is well defined (for $p = 2$, $\Psi \in L^q(\Omega \setminus K, \mathbb{R}^2)$ for every $q < +\infty$). In order to prove (4.4), using a truncation argument, it is not restrictive to assume that

$$v \in W^{1,2}(\Omega \setminus K) \cap L^\infty(\Omega \setminus K).$$

For every $n \in \mathbb{N}$ let us define

$$K_n := \left\{ x \in \mathbb{R}^2 : d(x, K) \leq \frac{1}{n} \right\},$$

where $d(\cdot, K)$ denotes the distance function from K . Since $\Psi \in W_0^{1,p}(\Omega \setminus K, \mathbb{R}^2) \subseteq W_0^{1,p}(\Omega, \mathbb{R}^2)$, we can find a sequence $(\Psi_n)_{n \in \mathbb{N}}$ such that $\Psi_n \in C_c^\infty(\Omega \setminus K_n, \mathbb{R}^2)$, and

$$(4.5) \quad \Psi_n \rightarrow \Psi \quad \text{strongly in } W^{1,p}(\Omega, \mathbb{R}^2).$$

By the Sobolev Embedding Theorem we have that Ψ_n is bounded in $L^{p^*}(\Omega, \mathbb{R}^2)$ (for $p = 2$, Ψ_n is bounded in $L^q(\Omega, \mathbb{R}^2)$ for every $q < +\infty$), and from (4.5) we get by interpolation that for every $p \leq r < p^*$ (for every $p \leq r < +\infty$ if $p = 2$)

$$(4.6) \quad \Psi_n \rightarrow \Psi \quad \text{strongly in } L^r(\Omega, \mathbb{R}^2).$$

Let us fix $v \in W^{1,2}(\Omega \setminus K) \cap L^\infty(\Omega \setminus K)$. We get by (4.6) (choosing $2 < r < p^*$) and integrating by parts

$$\int_{\Omega \setminus K} \Psi \cdot \nabla v \, dx = \lim_{n \rightarrow +\infty} \int_{\Omega \setminus K_n} \Psi_n \cdot \nabla v \, dx = \lim_{n \rightarrow +\infty} \int_{\Omega \setminus K_n} \operatorname{div} \Psi_n \cdot v \, dx = 0,$$

since $\operatorname{div} \Psi_n \rightarrow \operatorname{div} \Psi = 0$ strongly in $L^p(\Omega)$. We conclude that (4.4) holds, so that the proof is concluded. \square

Notice that Lemma 4.2 still holds for $p > 2$ since $W^{1,p}(\Omega \setminus K)$ is contained in $W^{1,2}(\Omega \setminus K)$. We are now in a position to prove the main result of the paper.

Theorem 4.3. *Let K be a connected subset of \mathbb{R}^2 , and let $u \in W_{\text{loc}}^{2,p}(\mathbb{R}^2)$ with $1 < p \leq 2$ be such that $\nabla u = 0$ c_p -q.e. on K . Then (the continuous representative of) u is constant on K .*

Proof. By Lemma 4.1 we can assume that K is closed. We divide the proof into two steps.

Step 1 (K is bounded). If we fix Ω to be an open, bounded and connected set in \mathbb{R}^2 such that $K \Subset \Omega$, upon multiplying u by a smooth cut-off function, we may assume without restriction that $u = 0$ outside Ω . In particular we have that $u \in W^{2,p}(\Omega)$.

Let R denote a rotation of 90 degrees counterclockwise. From the assumption we have that

$$R\nabla u := (g_1, g_2) \in W^{1,p}(\Omega, \mathbb{R}^2) \quad \text{with} \quad R\nabla u = 0 \text{ } c_p\text{-q.e. on } K,$$

so that by [15, Theorem 4.5] (see also [3])

$$R\nabla u \in W_0^{1,p}(\Omega \setminus K, \mathbb{R}^2).$$

Moreover $R\nabla u$ has zero divergence. By Lemma 4.2 we get that for every $v \in W^{1,2}(\Omega \setminus K)$,

$$\int_{\Omega \setminus K} R\nabla u \cdot \nabla v \, dx = 0.$$

By the Sobolev Embedding Theorem, we have that $R\nabla u \in L^{p^*}(\Omega \setminus K, \mathbb{R}^2)$ ($R\nabla u \in L^q(\Omega \setminus K, \mathbb{R}^2)$ for every $q < +\infty$ if $p = 2$), so that by Lemma 2.1 we get that there exists $\phi \in W^{1,p^*}(\mathbb{R}^2)$ with ϕ constant on K such that

$$R\nabla u = R\nabla \phi \quad \text{on } \Omega,$$

so that

$$u = \phi + \text{constant} \quad \text{on } \Omega.$$

Since ϕ is constant on K , the conclusion follows, and Step 1 is concluded.

Step 2 (K is unbounded). Let us employ polar coordinates (r, ϑ) , i.e., let us identify a point in \mathbb{R}^2 with the complex number $re^{i\vartheta}$. It is not restrictive to assume that $0 \in K$. Since K is unbounded, for every $r > 0$ we have that $K \cap \partial B_r(0) \neq \emptyset$: let us set

$$(4.7) \quad K_r := \{\vartheta \in [0, 2\pi] : re^{i\vartheta} \in K\}.$$

We claim that we can find a sequence $r_n \nearrow +\infty$ with

$$(4.8) \quad u(K) = \bigcup_{n \in \mathbb{N}} u(K \cap \partial B_{r_n}(0)),$$

and such that setting $u_n(\vartheta) := u(r_n e^{i\vartheta})$ we have

$$(4.9) \quad u_n \in W^{2,p}(S^1)$$

and

$$(4.10) \quad u'_n(\vartheta) = 0 \quad \text{for a.e. } \vartheta \in K_{r_n}.$$

Then the conclusion follows by the absolute continuity of u_n , which in view of (4.10) implies that $\mathcal{L}^1(u_n(K_{r_n})) = 0$ for every $n \in \mathbb{N}$. In fact by (4.8) we deduce that

$$\mathcal{L}^1(u(K)) \leq \sum_{n=0}^{+\infty} \mathcal{L}^1(u_n(K_{r_n})) = 0.$$

Since $u(K)$ is an interval, we get that $u(K) = \{c\}$ for some $c \in \mathbb{R}$, and the Whitney property follows.

In order to conclude the proof, we need to prove claims (4.8), (4.9) and (4.10). Let us start considering (4.8). Let $x \in K$, and let $r > 0$ be such that $x \in B_r(0)$. Let us consider for $\delta > 0$,

$$K^\delta := \{x \in \mathbb{R}^2 : d(x, K) < \delta\}.$$

We have that K^δ is open and connected (since K is connected), and since K is unbounded, there exists $\xi_r^\delta \in K^\delta \cap \partial B_r(0)$. Let γ_r^δ be a curve in K^δ connecting x and ξ_r^δ : up to replacing ξ_r^δ with the first point in which γ_r^δ intersects $\partial B_r(0)$, we can assume that $\gamma_{r,[x,\xi_r^\delta]}^\delta \subseteq K^\delta \cap \overline{B}_r(0)$. As $\delta \rightarrow 0$, we have that up to a subsequence,

$$\gamma_{r,[x,\xi_r^\delta]}^\delta \rightarrow \gamma_r \quad \text{in the Hausdorff metric,}$$

where $\gamma_r \subseteq K \cap \overline{B}_r(0)$ is a compact and connected set such that $x, \xi_r \in \gamma_r$ for some $\xi_r \in K \cap \partial B_r(0)$ (for the details concerning the Hausdorff metric we refer the reader to [19]). Since $\nabla u = 0$ c_p -q.e. on γ_r , by Step 1 we get that u is constant on γ_r . In particular $u(x) = u(\xi_r)$. In other words, we have proved that the value of u at x can be recovered from the values of u on $\partial B_r(0)$. Thus we conclude that for every $r_n \nearrow +\infty$ equality (4.8) holds.

Claims (4.9) and (4.10) follow by the standard theory of slicing properties of Sobolev functions (see e.g. [12, Section 4.9]): for a.e. $\bar{r} > 0$ we have that the function $u_{\bar{r}}(\vartheta) := u(\bar{r}e^{i\vartheta})$ belongs to $W^{2,p}(S^1)$ and is such that for a.e. $\vartheta \in [0, 2\pi]$,

$$(4.11) \quad u'_{\bar{r}}(\vartheta) = \nabla u(\bar{r}e^{i\vartheta}) \cdot \frac{e_{\vartheta}}{\bar{r}},$$

where $e_{\vartheta} := (-\sin \vartheta, \cos \vartheta)$. Recall that by [12, Section 4.7.2, Theorem 4] we have that for every $E \subseteq \mathbb{R}^2$ and $q \geq 1$,

$$c_q(E) = 0 \implies \mathcal{H}^s(E) = 0 \quad \text{for every } s > 2 - q.$$

In particular for $1 < p \leq 2$,

$$(4.12) \quad c_p(E) = 0 \implies \mathcal{H}^1(E) = 0.$$

Since $\nabla u = 0$ c_p -q.e. on K , by (4.11) and (4.12) we have that $u'_{\bar{r}}(\vartheta) = 0$ for a.e. $\vartheta \in K_{\bar{r}}$. Then claims (4.9) and (4.10) are proved, and the proof is concluded. \square

Remark 4.4. The proof of Step 1 of Theorem 4.3, which is based on Lemmas 4.2 and 2.1, can be summarized as follows.

- (1) We consider the vector field $g := R\nabla u$, which is divergence free and vanishes c_p -q.e. on K .
- (2) We approximate g (in the L^2 -norm) by smooth divergence free vector fields $(g_n)_{n \in \mathbb{N}}$ vanishing on neighborhoods of K .
- (3) From g_n we construct a sequence of functions $(u_n)_{n \in \mathbb{N}}$ such that u_n converges in $W^{1,p}$ to u and u_n is constant on K (since $\nabla u_n = R^{-1}g_n$). As a consequence, u turns out to be constant on K .

Clearly point (1), that is, associating a divergence free vector field to ∇u , can be carried out easily in even dimensions. Also the approximation of point (2) holds in higher dimensions since it is based on the Helmholtz decomposition of L^2 . Point (3) is however essentially two dimensional, and we do not know any operation similar to R^{-1} which associates, in higher dimensions, the gradient of a function to a divergence free vector field.

Remark 4.5. Under the assumptions of Theorem 4.3, the result of De Pascale [11] cannot be applied since $1 < p \leq 2$. Moreover, the proof of our result relies on arguments strictly connected to the notion of the p -fine topology, which are different from those used in [11].

Remark 4.6. The key point in the proof of Step 2 of Theorem 4.3 is the use of the absolute continuity for the regular one dimensional sections of u which gives nontrivial information on $u(K)$ in view of (4.8). A decomposition with countably many sections such as in (4.8) still holds if K is no more connected but has a countable number of connected components, but it clearly fails in the general case.

Remark 4.7. Notice that in Step 2 of the proof of Theorem 4.3 we used the fact that $u \in W_{loc}^{2,p}(\mathbb{R}^2)$ to carry over a dimensional reduction through slicing in polar coordinates and we used absolute continuity on the countably many sections needed (see (4.9) and (4.10)). Thus to get the conclusion for the case that K is unbounded we needed an “energetic” argument (the Sobolev regularity) together with the Whitney property for bounded connected sets (which we proved in Step 1). We remark that we cannot get the conclusion using simply topological arguments, i.e., using only Step 1 and the continuity of u . In fact we can consider the following example.

Let $C := [0, 1] \setminus \bigcup_{n=1}^{\infty} E_n$ be the usual Cantor set contained in $[0, 1]$, where E_n is the union of the middle-third intervals, i.e.,

$$E_1 =]1/3, 2/3[, \quad E_2 =]1/9, 2/9[\cup]7/9, 8/9[\quad \dots$$

and so on. Let $E_n := \bigcup_{k=1}^{k_n} I_k^n$ with $I_k^n =]a_k^n, b_k^n[$. For every k , let $\gamma_k^n : I_k^n \rightarrow \mathbb{R}$ be a continuous function such that

$$\liminf_{x \rightarrow a_k^n} \gamma_k^n(x) = -\infty, \quad \limsup_{x \rightarrow a_k^n} \gamma_k^n(x) = +\infty,$$

and

$$\liminf_{x \rightarrow b_k^n} \gamma_k^n(x) = -\infty, \quad \limsup_{x \rightarrow b_k^n} \gamma_k^n(x) = +\infty.$$

Let $\Gamma_k^n \subseteq I_k^n \times \mathbb{R}$ be the image of γ_k^n . For every $n \in \mathbb{N}$ let us set

$$H^n := \bigcup_{k=1}^{k_n} \Gamma_k^n,$$

and let

$$K := (C \times \mathbb{R}) \cup \bigcup_{n \in \mathbb{N}} H^n.$$

We have that $K \subseteq \mathbb{R}^2$ is closed and connected. Let us consider $u(x, y) = f(x)$, where f is the usual Cantor-Vitali function (see e.g. [2, Example 1.67]). The function u (which has *bounded variation* (see [2]) but does not belong to $W_{loc}^{2,p}$) is constant on every bounded and connected set $H \subseteq K$, but it is not globally constant on K .

Remark 4.8. We conclude the section by noticing an extension of a result proved by Sverák [21] (see Lemma 5.2 and the Remark on page 548) in the case $p = 2$: the proof relies on Lemma 4.2.

Let Ω be an open bounded set in \mathbb{R}^2 such that the number of connected components of $\mathbb{R}^2 \setminus \Omega$ is finite. Then for every $p \in]1, +\infty[$ the space

$$V(\Omega) := \{\Psi \in W_0^{1,p}(\Omega, \mathbb{R}^2) : \operatorname{div} \Psi = 0\}$$

coincides with the closure in $W_0^{1,p}(\Omega, \mathbb{R}^2)$ of

$$\mathcal{V}(\Omega) := \{\Psi \in C_c^\infty(\Omega, \mathbb{R}^2) : \operatorname{div} \Psi = 0\}.$$

In order to prove this result, it suffices to check that every $\Psi \in V(\Omega)$ is a limit in the topology of $W^{1,p}(\Omega, \mathbb{R}^2)$ of elements of $\mathcal{V}(\Omega)$. Let B be an open ball such that $\overline{\Omega} \subseteq B$, and let us set $K := \overline{B} \setminus \Omega$. We have that K has a finite number of connected components.

Let us consider the case $1 < p < 2$. By Lemma 4.2 we get for every $v \in W^{1,2}(B \setminus K)$,

$$\int_{B \setminus K} \Psi \cdot \nabla v \, dx = 0.$$

Notice that by the Sobolev Embedding Theorem we have $\Psi \in L^{p^*}(B \setminus K, \mathbb{R}^2)$, where p^* is the Sobolev exponent $p^* = \frac{2p}{2-p} > 2$. By Lemma 2.1 we deduce that there exists $\phi \in W^{1,p^*}(\mathbb{R}^2)$ constant on the connected components of K such that

$$(4.13) \quad \Psi = R\nabla\phi \quad \text{on } B \setminus K,$$

where R denotes a rotation of 90 degrees counterclockwise. We get that $\phi \in W^{2,p}(\mathbb{R}^2)$. Since K has a finite number of connected components, we can find a function $h \in C_c^\infty(B)$ whose gradient vanishes in a neighborhood of K and such that it coincides with ϕ on K . Let us consider the function $\theta := \phi - h \in W_0^{2,p}(B \setminus K)$. Then, by [1, Theorem 9.1.3], there exists $\theta_j \in C_c^\infty(B \setminus K)$ such that

$$\theta_j \rightarrow \theta \quad \text{strongly in } W_0^{2,p}(B \setminus K).$$

Let us define the functions

$$\Psi_j = R\nabla\theta_j + R\nabla h.$$

Recalling that $B \setminus K = \Omega$, by construction we have $\Psi_j \in C_c^\infty(\Omega, \mathbb{R}^2)$, $\operatorname{div} \Psi_j = 0$ and

$$\Psi_j \rightarrow R\nabla\phi = \Psi \quad \text{strongly in } W_0^{1,p}(\Omega, \mathbb{R}^2),$$

so that the result follows.

The case $p \geq 2$ follows the same lines as the case $1 < p < 2$: it suffices to take into account that by the Sobolev Embedding Theorem, Ψ is either an L^q -function for every $1 \leq q < +\infty$ or a Hölder continuous function so that the representation formula (4.13) with $\phi \in W^{2,p}(\mathbb{R}^2)$ still holds.

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