

HAMILTON'S GRADIENT ESTIMATES  
AND LIOUVILLE THEOREMS  
FOR FAST DIFFUSION EQUATIONS  
ON NONCOMPACT RIEMANNIAN MANIFOLDS

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ABSTRACT. Let  $M$  be a complete noncompact Riemannian manifold of dimension  $n$ . In this paper, we derive a local gradient estimate for positive solutions of fast diffusion equations

$$\partial_t u = \Delta u^\alpha, \quad 1 - \frac{2}{n} < \alpha < 1$$

on  $M \times (-\infty, 0]$ . We also obtain a theorem of Liouville type for positive solutions of the fast diffusion equation.

1. INTRODUCTION

In this paper we study the fast diffusion equation (FDE for short)

$$(1.1) \quad \partial_t u = \Delta u^\alpha,$$

where  $\alpha \in (0, 1)$ . FDE arises in the study of fast diffusions, in particular in diffusion in plasma ([3]), in thin liquid film dynamics driven by Van der Waals forces ([7], [8]), and in models of gas-kinetics ([4]). It also arises in geometry: the case  $\alpha = \frac{n-2}{n+2}$  in dimensions  $n > 3$  describes the evolution of a conformal metric by the Yamabe flow ([18]); the case  $\alpha = 0$ ,  $n = 2$  describes the Ricci flow on surfaces ([10], [6], [16]). Precisely, we can find the relationship from  $\partial_t u = \Delta(\frac{1}{\alpha}u^\alpha) = \operatorname{div}(u^\alpha \frac{\nabla u}{u})$  and  $\operatorname{div}(\frac{\nabla u}{u}) = \operatorname{div}(\nabla \log u) = \Delta \log u$ . We refer the reader to the book by Daskalopoulos-Kenig ([5]) and the references therein for more about FDE.

As a nonlinear problem, the mathematical theory of FDE is based on a priori estimates. In 1979, Aronson and Bénilan obtained a celebrated second-order differential inequality of the form ([1])

$$\sum_i \frac{\partial}{\partial x^i} (\alpha u^{\alpha-2} \frac{\partial u}{\partial x^i}) \geq -\frac{\kappa}{t}, \quad \kappa := \frac{n}{n(\alpha-1)+2},$$

which applies to all positive solutions of (1.1) defined on the whole Euclidean space on the condition that  $\alpha > 1 - \frac{2}{n}$ .

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There are few results about FDE on manifolds. In 2008, Lu, Ni, Vázquez and Villani studied the FDE on manifolds ([13]) and got a local Aronson-Bénilan estimate. We do not state their result here. What we will do in this paper is to get Hamilton's gradient estimates. First, let us recall what Hamilton's result is:

**Theorem** (Hamilton [9]). *Let  $\mathbf{M}$  be a closed Riemannian manifold of dimension  $n \geq 2$  with  $\text{Ricci}(\mathbf{M}) \geq -k$  for some  $k \geq 0$ . Suppose that  $u$  is any positive solution to the heat equation with  $u \leq M$  for all  $(x, t) \in \mathbf{M} \times (0, \infty)$ . Then*

$$\frac{|\nabla u|^2}{u^2} \leq \left(\frac{1}{t} + 2k\right) \log \frac{M}{u}.$$

*Hamilton's estimate tells us that when the temperature is bounded we can compare the temperature of two different points at the same time.*

In 2006, P. Souplet and Qi S. Zhang ([14]) generalized Hamilton's estimate to complete noncompact Riemannian manifolds. In 2007, B. Kotschwar ([11]) used Hamilton's estimate and obtained a global gradient estimate for heat kernels on complete noncompact manifolds. In 2010, M. Bailesteanu, X. Cao and A. Pulemotov ([2]) generalized Souplet and Zhang's result to Ricci flow. Also in 2010, on complete noncompact Riemannian manifolds, J. Wu ([15]) obtained a localized Hamilton-type gradient estimate for the positive smooth bounded solutions to the nonlinear diffusion equation  $u_t = \Delta u - \nabla \phi \cdot \nabla u - au \log u - bu$ , where  $\phi$  is a  $C^2$  function and  $a \neq 0$  and  $b$  are two real constants. We would like to remark here that this equation was also studied by Y. Yang in ([17]), where they derived a parabolic gradient estimate.

In this paper, we consider the positive solution for FDE (1.1). Like what they did for the heat equation, we derive a similar Hamilton's estimate for FDE. Inspired by the inequality of Aronson and Bénilan, we let  $\alpha > 1 - \frac{2}{n}$  throughout this paper. Note that the pressure  $\tilde{v} := \frac{\alpha}{\alpha-1} u^{\alpha-1} < 0$ ,

$$\partial_t \tilde{v} = (\alpha - 1) \tilde{v} \Delta \tilde{v} + |\nabla \tilde{v}|^2.$$

Conveniently, we let  $v = -\tilde{v}$ . Then  $v > 0$  and satisfies

$$(1.2) \quad \partial_t v = (1 - \alpha)v \Delta v - |\nabla v|^2.$$

Our main result is the following:

**Theorem 1** (Gradient estimates). *Let  $\mathbf{M}$  be a Riemannian manifold of dimension  $n \geq 2$  with  $\text{Ricci}(\mathbf{M}) \geq -k$  for some  $k \geq 0$ . Suppose that  $v$  is any positive solution to the equation (1.2) in  $Q_{R,T} \equiv B(x_0, R) \times [t_0 - T, t_0] \subset \mathbf{M} \times (-\infty, \infty)$ . Suppose also that  $v \leq M$  in  $Q_{R,T}$ . Then there exists a constant  $C = C(\alpha, \mathbf{M})$  such that*

$$\frac{|\nabla v|}{v^{1/2}} \leq CM^{1/2} \left( \frac{1}{R} + \frac{1}{\sqrt{T}} + \sqrt{k} \right)$$

*in  $Q_{\frac{R}{2}, \frac{T}{2}}$ .*

As an application, we get the following Liouville type theorem:

**Corollary 1.1** (Liouville type theorem). *Let  $M$  be a complete, noncompact manifold of dimension  $n$  with nonnegative Ricci curvature. Let  $u$  be a positive ancient solution to the equation (1.1) with  $1 - \frac{2}{n} < \alpha < 1$  such that  $\frac{1}{u(x,t)} = o([d(x) + \sqrt{|t|}]^{\frac{2}{1-\alpha}})$ . Then  $u$  is a constant.*

2. PROOF OF THEOREM 1

Let  $w \equiv \frac{|\nabla v|^2}{v^\beta}$ ,  $\beta > 0$  to be determined.

We will derive an equation for  $w$ . First notice that

$$\begin{aligned}
 w_t &= \frac{2v_i v_{it}}{v^\beta} - \beta \frac{v_i^2 v_t}{v^{\beta+1}} \\
 &= \frac{2v_i((1-\alpha)v\Delta v - |\nabla v|^2)_i}{v^\beta} - \beta \frac{v_i^2((1-\alpha)v\Delta v - |\nabla v|^2)}{v^{\beta+1}} \\
 &= 2(1-\alpha) \frac{v_i^2 v_{jj}}{v^\beta} + 2(1-\alpha) \frac{v_i v_{jji}}{v^{\beta-1}} - 4 \frac{v_i v_{ij} v_j}{v^\beta} \\
 (2.1) \quad &\quad - \beta(1-\alpha) \frac{v_i^2 v_{jj}}{v^\beta} + \beta \frac{v_i^2 v_j^2}{v^{\beta+1}},
 \end{aligned}$$

$$\begin{aligned}
 w_j &= \frac{2v_i v_{ij}}{v^\beta} - \beta \frac{v_i^2 v_j}{v^{\beta+1}}, \\
 (2.2) \quad v_{jj} &= \frac{2v_{ij}^2}{v^\beta} + \frac{2v_i v_{ijj}}{v^\beta} - 4\beta \frac{v_i v_{ij} v_j}{v^{\beta+1}} - \beta \frac{v_i^2 v_{jj}}{v^{\beta+1}} + \beta(\beta+1) \frac{v_i^2 v_j^2}{v^{\beta+2}}.
 \end{aligned}$$

By (2.1) and (2.2),

$$\begin{aligned}
 &(1-\alpha)v\Delta w - w_t \\
 &= 2(1-\alpha) \frac{v_{ij}^2}{v^{\beta-1}} + 2(1-\alpha) \frac{v_i v_{ijj}}{v^{\beta-1}} - 4\beta(1-\alpha) \frac{v_i v_{ij} v_j}{v^\beta} \\
 &\quad - \beta(1-\alpha) \frac{v_i^2 v_{jj}}{v^\beta} + \beta(\beta+1)(1-\alpha) \frac{v_i^2 v_j^2}{v^{\beta+1}} \\
 &\quad - 2(1-\alpha) \frac{v_i^2 v_{jj}}{v^\beta} - 2(1-\alpha) \frac{v_i v_{jji}}{v^{\beta-1}} + 4 \frac{v_i v_{ij} v_j}{v^\beta} \\
 &\quad + \beta(1-\alpha) \frac{v_i^2 v_{jj}}{v^\beta} - \beta \frac{v_i^2 v_j^2}{v^{\beta+1}} \\
 &= 2(1-\alpha) \frac{v_{ij}^2}{v^{\beta-1}} - 2(1-\alpha) \frac{v_i^2 v_{jj}}{v^\beta} + 2(1-\alpha) \frac{R_{ij} v_i v_j}{v^{\beta-1}} \\
 &\quad + 4(1-\beta(1-\alpha)) \frac{v_i v_{ij} v_j}{v^\beta} + (\beta(\beta+1)(1-\alpha) - \beta) \frac{v_i^2 v_j^2}{v^{\beta+1}}.
 \end{aligned}$$

Here, in the second equality, we use the Ricci formula:  $v_{ijj} - v_{jji} = R_{ij} v_j$ .

Notice that

$$(2.3) \quad \nabla w \cdot \nabla v = w_j v_j = \frac{2v_i v_{ij} v_j}{v^\beta} - \beta \frac{v_i^2 v_j^2}{v^{\beta+1}}.$$

Using (2.3), we obtain

$$\begin{aligned}
 & (1 - \alpha)v\Delta w - w_t \\
 &= 2(1 - \alpha)\frac{v_{ij}^2}{v^{\beta-1}} - 2(1 - \alpha)\frac{v_i^2 v_{jj}}{v^\beta} + 2(1 - \alpha)\frac{R_{ij} v_i v_j}{v^{\beta-1}} \\
 &\quad + 4(1 - \beta(1 - \alpha))\frac{v_i v_{ij} v_j}{v^\beta} + (\beta(\beta + 1)(1 - \alpha) - \beta)\frac{v_i^2 v_j^2}{v^{\beta+1}} \\
 &\geq -\frac{n(1 - \alpha)}{2}\frac{|\nabla v|^4}{v^{\beta+1}} - 2(1 - \alpha)k\frac{|\nabla v|^2}{v^{\beta-1}} + 2(1 - \beta(1 - \alpha))\nabla w \cdot \nabla v \\
 &\quad + 2\beta(1 - \beta(1 - \alpha))\frac{v_i^2 v_j^2}{v^{\beta+1}} + (\beta(\beta + 1)(1 - \alpha) - \beta)\frac{v_i^2 v_j^2}{v^{\beta+1}} \\
 &= 2(1 - \beta(1 - \alpha))\nabla w \cdot \nabla v - 2(1 - \alpha)k\frac{|\nabla v|^2}{v^{\beta-1}} \\
 &\quad + (\beta(\beta + 1)(1 - \alpha) - \beta - \frac{n(1 - \alpha)}{2} + 2\beta(1 - \beta(1 - \alpha)))\frac{|\nabla v|^4}{v^{\beta+1}}.
 \end{aligned}$$

For the purpose of obtaining the gradient estimates as in [14], we need to have the coefficient of  $w^2$  be positive. Fortunately, we can do this by choosing a suitable  $\beta$ . In fact,

$$\begin{aligned}
 & \beta(\beta + 1)(1 - \alpha) - \beta - \frac{n(1 - \alpha)}{2} + 2\beta(1 - \beta(1 - \alpha)) \\
 &= -(1 - \alpha)\left(\beta^2 - \frac{2 - \alpha}{1 - \alpha}\beta + \frac{n}{2}\right).
 \end{aligned}$$

It is easily found that the discriminant is  $(-\frac{2-\alpha}{1-\alpha})^2 - 2n$ , which is positive when  $\alpha \in (1 - \frac{2}{n}, 1)$ . So we can choose a suitable  $\beta$  to make sure the term will be positive.

Rearranging, we have

$$\begin{aligned}
 & (1 - \alpha)v\Delta w - w_t \\
 &= 2(1 - \beta(1 - \alpha))\nabla w \cdot \nabla v - 2(1 - \alpha)kvw - (1 - \alpha)\left(\beta^2 - \frac{2 - \alpha}{1 - \alpha}\beta + \frac{n}{2}\right)v^{\beta-1}w^2.
 \end{aligned}$$

From here, we will use the well-known cutoff function of Li and Yau to derive the desired bounds. We caution the reader that the calculation is not the same as that in [12] due to the difference of the first order.

Let  $\psi = \psi(x, t)$  be a smooth cutoff function supported in  $Q_{R,T}$ , satisfying the following properties:

- (1)  $\psi = \psi(d(x, x_0), t) \equiv \psi(r, t)$ ;  $\psi(r, t) = 1$  in  $Q_{R/2, T/2}$ ,  $0 \leq \psi \leq 1$ .
- (2)  $\psi$  is decreasing as a radial function in the spatial variables.
- (3)  $|\partial_r \psi|/\psi^a \leq C_a/R$ ,  $|\partial_r^2 \psi|/\psi^a \leq C_a/R^2$  when  $0 < a < 1$ .
- (4)  $|\partial_t \psi|/\psi^{1/2} \leq C/T$ .

By straightforward calculation, one has

$$\begin{aligned}
 & (1 - \alpha)v\Delta(\psi w) + b \cdot \nabla(\psi w) - 2(1 - \alpha)v\frac{\nabla \psi}{\psi} \cdot \nabla(\psi w) - (\psi w)_t \\
 &\geq -(1 - \alpha)\left(\beta^2 - \frac{2 - \alpha}{1 - \alpha}\beta + \frac{n}{2}\right)v^{\beta-1}\psi w^2 + (b \cdot \nabla \psi)w \\
 &\quad - 2(1 - \alpha)v\frac{|\nabla \psi|^2}{\psi}w + (1 - \alpha)v(\Delta \psi)w - \psi_t w - 2(1 - \alpha)kvw,
 \end{aligned}$$

where  $b = -2(1 - \beta(1 - \alpha))\nabla v$ .

Suppose that the maximum of  $\psi w$  is reached at  $(x_1, t_1)$ . By [12], we can assume, without loss of generality, that  $x_1$  is not on the cut-locus of  $\mathbf{M}$ . Then at  $(x_1, t_1)$ , one has  $\Delta(\psi w) \leq 0$ ,  $(\psi w)_t \geq 0$  and  $\nabla(\psi w) = 0$ . Therefore,

$$\begin{aligned}
 & - (1 - \alpha)\left(\beta^2 - \frac{2 - \alpha}{1 - \alpha}\beta + \frac{n}{2}\right)v^{\beta-1}\psi w^2(x_1, t_1) \\
 & \leq - [(b \cdot \nabla\psi)w - 2(1 - \alpha)v\frac{|\nabla\psi|^2}{\psi}w \\
 (2.4) \quad & + (1 - \alpha)v(\Delta\psi)w - \psi_t w - 2(1 - \alpha)kv\psi w](x_1, t_1).
 \end{aligned}$$

Denote  $-(1 - \alpha)\left(\beta^2 - \frac{2 - \alpha}{1 - \alpha}\beta + \frac{n}{2}\right) = \frac{2}{\gamma}$ . Then  $\gamma > 0$  only depends on  $\alpha, \beta$ .

Rearranging, we have

$$\begin{aligned}
 & 2\psi w^2(x_1, t_1) \\
 & \leq [-\gamma(b \cdot \nabla\psi)v^{1-\beta}w + 2(1 - \alpha)\gamma v^{2-\beta}\frac{|\nabla\psi|^2}{\psi}w \\
 (2.5) \quad & - (1 - \alpha)\gamma v^{2-\beta}(\Delta\psi)w + \gamma v^{1-\beta}\psi_t w + 2(1 - \alpha)\gamma kv^{2-\beta}\psi w](x_1, t_1).
 \end{aligned}$$

We need to find an upper bound for each term on the right-hand side of (2.5). For the first term,

$$\begin{aligned}
 -\gamma(b \cdot \nabla\psi)v^{1-\beta}w & \leq \gamma(b \cdot \nabla\psi)v^{1-\beta}w \\
 & = C|\nabla v||\nabla\psi|v^{1-\beta}w \\
 & \leq CM^{1-\beta/2}w^{3/2}|\nabla\psi| \\
 & \leq \frac{1}{4}\psi w^2 + C\left(\frac{M^{1-\beta/2}|\nabla\psi|}{\psi^{3/4}}\right)^4 \\
 (2.6) \quad & \leq \frac{1}{4}\psi w^2 + CM^{4-2\beta}\frac{1}{R^4}.
 \end{aligned}$$

Here we used the fact that  $0 < v \leq M$ .

For the second term on the right-hand side of (2.5), we proceed as follows:

$$\begin{aligned}
 2(1 - \alpha)\gamma v^{2-\beta}\frac{|\nabla\psi|^2}{\psi}w & \leq CM^{2-\beta}\frac{|\nabla\psi|^2}{\psi^{\frac{3}{2}}}\psi^{\frac{1}{2}}w \\
 & \leq \frac{1}{4}\psi w^2 + CM^{4-2\beta}\left(\frac{|\nabla\psi|^2}{\psi^{\frac{3}{2}}}\right)^2 \\
 (2.7) \quad & \leq \frac{1}{4}\psi w^2 + CM^{4-2\beta}\frac{1}{R^4}.
 \end{aligned}$$

Furthermore, by the properties of  $\psi$  and the assumption on the Ricci curvature, one has

$$\begin{aligned}
 & - (1 - \alpha)\gamma v^{2-\beta}(\Delta\psi)w \\
 &= -(1 - \alpha)\gamma(\partial_r^2\psi + (n - 1)\frac{\partial_r\psi}{r} + \partial_r\psi\partial_r \log \sqrt{g})v^{2-\beta}w \\
 &\leq CM^{2-\beta}(|\partial_r^2\psi| + (n - 1)\frac{|\partial_r\psi|}{r} + \sqrt{k}|\partial_r\psi|)w \\
 &\leq CM^{2-\beta}\left(\frac{|\partial_r^2\psi|}{\psi^{\frac{1}{2}}} + 2(n - 1)\frac{|\partial_r\psi|}{R\psi^{\frac{1}{2}}} + \sqrt{k}\frac{|\partial_r\psi|}{\psi^{\frac{1}{2}}}\right)\psi^{\frac{1}{2}}w \\
 &\leq \frac{1}{4}\psi w^2 + CM^{4-2\beta}\left(\left(\frac{|\partial_r^2\psi|}{\psi^{\frac{1}{2}}}\right)^2 + \left(\frac{|\partial_r\psi|}{R\psi^{\frac{1}{2}}}\right)^2 + (\sqrt{k}\frac{|\partial_r\psi|}{\psi^{\frac{1}{2}}})^2\right) \\
 (2.8) \quad &\leq \frac{1}{4}\psi w^2 + CM^{4-2\beta}\left(\frac{1}{R^4} + k\frac{1}{R^2}\right).
 \end{aligned}$$

Now we estimate  $\gamma v^{1-\beta}\psi_t w$  as

$$\begin{aligned}
 \gamma v^{1-\beta}\psi_t w &\leq \gamma v^{1-\beta}|\psi_t|w \\
 &\leq \gamma\frac{|\psi_t|}{\psi^{1/2}}\psi^{1/2}wM^{1-\beta} \\
 (2.9) \quad &\leq \frac{1}{4}\psi w^2 + CM^{2-2\beta}\frac{1}{T^2}.
 \end{aligned}$$

Here we suppose  $\beta \leq 1$ .

Finally, for the last term, we have

$$\begin{aligned}
 2(1 - \alpha)\gamma k v^{2-\beta}\psi w &\leq C\psi^{1/2}w k M^{2-\beta} \\
 (2.10) \quad &\leq \frac{1}{4}\psi w^2 + CM^{4-2\beta}k^2.
 \end{aligned}$$

Substituting (2.6)–(2.10) into the right-hand side of (2.5), we deduce that

$$2\psi w^2(x_1, t_1) \leq \frac{5}{4}\psi w^2(x_1, t_1) + CM^{4-2\beta}\left(\frac{1}{R^4} + \frac{1}{T^2} + k^2\right).$$

Therefore,

$$\psi w^2(x_1, t_1) \leq CM^{4-2\beta}\left(\frac{1}{R^4} + \frac{1}{T^2} + k^2\right).$$

What we get shows, for all  $(x, t) \in Q_{R,T}$ , that

$$\begin{aligned}
 \psi^2(x, t)w^2(x, t) &\leq \psi^2(x_1, t_1)w^2(x_1, t_1) \\
 &\leq \psi(x_1, t_1)w^2(x_1, t_1) \\
 &\leq CM^{4-2\beta}\left(\frac{1}{R^4} + \frac{1}{T^2} + k^2\right).
 \end{aligned}$$

Notice that  $\psi(x, t) = 1$  in  $Q_{R/2, T/2}$ ,  $w = \frac{|\nabla v|^2}{v^\beta}$ . We have

$$\frac{|\nabla v(x, t)|}{v^{\beta/2}(x, t)} \leq CM^{1-\beta/2} \left( \frac{1}{R} + \frac{1}{\sqrt{T}} + \sqrt{k} \right),$$

where  $C = C(\alpha, \beta, \mathbf{M})$ .

Then we choose  $\beta = 1$ . This ends the proof of Theorem 1.

### 3. SIMPLE PROOF OF COROLLARY 1.1

From Theorem 1, we know that, when  $v$  is a positive ancient solution to the equation (1.2) such that  $v(x, t) = o([d(x, x_0) + \sqrt{|t|}]^2)$ , then  $v$  is a constant.

Notice that  $v = \frac{\alpha}{1-\alpha} u^{\alpha-1} = \frac{\alpha}{1-\alpha} (\frac{1}{u})^{1-\alpha}$ , so when  $u$  is a positive ancient solution to the equation (1.1) such that  $\frac{1}{u(x, t)} = o([d(x, x_0) + \sqrt{|t|}]^{\frac{2}{1-\alpha}})$ , then  $u$  is a constant. This ends the proof of Corollary 1.1.

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