

## INTEGRAL REPRESENTATION OF SKOROKHOD REFLECTION

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ABSTRACT. We show that a certain integral representation of the one-sided Skorokhod reflection of a continuous bounded variation function characterizes the reflection in that it possesses a unique maximal solution which solves the Skorokhod reflection problem.

### 1. INTRODUCTION

The Skorokhod reflection problem has a long history. Skorokhod [10] introduced it as a method for representing a diffusion process with a reflecting boundary at zero. Given a continuous function  $X : [0, \infty) \rightarrow \mathbb{R}$ , the standard Skorokhod reflection problem seeks to find  $(Q(t), t \geq 0)$  and a continuous, nondecreasing function  $Y : [0, \infty) \rightarrow \mathbb{R}_+$  with  $Y(0) = 0$ , such that  $Q(t) := X(t) + Y(t) \geq 0$  for all  $t$ , and  $\int_0^\infty Q(s) dY(s) = 0$ . Intuitively, the latter expresses the idea that  $Y$  can increase only at points  $t$  such that  $X(t) + Y(t) = 0$ . Skorokhod [10] showed that there is only one such  $Y$ , namely,  $Y(t) = -\inf_{0 \leq s \leq t} (X(s) \wedge 0)$ , and thus

$$Q(t) = X(t) \vee \sup_{0 \leq s \leq t} (X(t) - X(s)).$$

We use the standard notation  $a \vee b := \max(a, b)$ ,  $a \wedge b := \min(a, b)$ . The mapping  $X \mapsto Q$  is referred to as the (one-sided) Skorokhod reflection mapping and has now become a standard tool in probability theory and other areas. As an example, we recall that if  $X$  is the path of a Brownian motion, then  $Q$  is a reflecting Brownian motion and  $Q(t)$  has the same distribution as  $|X(t)|$  for all  $t \geq 0$  [3, 9]. Several extensions of the Skorokhod reflection mapping exist generalizing the range of  $X$  (see, e.g., [11]) or its domain (see, e.g., [1]).

The question resolved in this paper was motivated by an application of the Skorokhod reflection in stochastic fluid queues [7, 6]. Suppose that  $A, C$  are two jointly stationary and ergodic random measures defined on a common probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ , with intensities  $a, c$ , respectively, such that  $a < c$ . Then there exists a unique stationary and ergodic stochastic process  $(Q(t), t \in \mathbb{R})$  defined on

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$(\Omega, \mathcal{F}, \mathbb{P})$  such that, for all  $t_0 \in \mathbb{R}$ ,  $(Q(t_0 + t), t \geq 0)$  is the Skorokhod reflection of  $(Q(t_0) + A(t_0, t_0 + t] - C(t_0, t_0 + t], t \geq 0)$ . In addition, if the random measures  $A, C$  have no atoms, then

$$(1.1) \quad Q(t) = \int_{-\infty}^t \mathbf{1}(Q(s) > C(s, t]) \, dA(s),$$

for all  $t \in \mathbb{R}$ ,  $\mathbb{P}$ -almost surely. The latter equation was called an “integral representation” of Skorokhod reflection and extensions of it were formulated and proved in [6]. The integral representation was found to be useful in several applications, e.g. (i) in deriving the so-called Little’s law for stochastic fluid queues [2], stating that  $\mathbb{E}[Q(0)] = (a/c)\mathbb{E}_A[Q(0)]$ , where  $\mathbb{E}_A$  is expectation with respect to the Palm measure [4] of  $\mathbb{P}$  with respect to  $A$ , and (ii) in deriving the form of the stationary distribution of a stochastic process derived from the local time of a Lévy process [5].

In an open problems session of the workshop on “New Topics at the Interface Between Probability and Communications” [8], the second author asked whether and in what sense (1.1) characterizes Skorokhod reflection. The question will be made precise in Section 2 below, where the main theorem, Theorem 2.1, which answers the question, is stated. In Section 3 the integral representation is explicitly proved, along with some auxiliary results, which are proved in order to make the paper self-contained. Finally, in Section 4 a proof of Theorem 2.1 is given. This requires a number of lemmas, all proved in the same section.

## 2. THE PROBLEM

Consider a locally finite signed measure  $X$  on the Borel sets of  $\mathbb{R}$ . Assume that  $X$  has no atoms, i.e. that  $X(\{t\}) = 0$  for all  $t \in \mathbb{R}$ . Define

$$(2.1) \quad Q^*(t) := \sup_{0 \leq s \leq t} X(s, t], \quad t \geq 0,$$

where  $X(s, t] = X((s, t])$  is the value of  $X$  at the interval  $(s, t]$ .<sup>1</sup> In particular,

$$Q^*(0) = 0.$$

Let  $X(t) := X(0, t]$  and write (2.1) as

$$Q^*(t) = X(t) - \inf_{0 \leq s \leq t} X(s).$$

The standard terminology [3, 12] is that  $Q^*$  solves the Skorokhod reflection problem for the function  $t \mapsto X(t)$ .

Decompose  $X$  as the difference of two locally finite nonnegative measures  $A, C$ , without atoms; i.e. write

$$(2.2) \quad X = A - C.$$

We stress that  $A, C$  are not necessarily the positive and negative parts of  $X$ . In other words, the decomposition is not unique. For instance, we can add an arbitrary locally finite nonnegative measure without atoms to both  $A$  and  $C$ .

<sup>1</sup>Since  $X, A, C$  are assumed to have no atoms, we may as well write  $X[s, t]$  or  $X(s, t)$  instead of  $X(s, t]$ , and likewise for  $A$  and  $C$ , but we have chosen the notation to be consistent with possible generalizations.

In [6] it was proved that (2.1) also satisfies the fixed point equation referred to as the “integral representation” of the reflected process:

$$(2.3) \quad Q(t) = \int_0^t \mathbf{1}(Q(s) > C(s, t)) \, dA(s), \quad t \geq 0.$$

A simpler version of this appeared earlier in [7]; this version was concerned with the case where  $C$  is a multiple of the Lebesgue measure. In an open problems session of the workshop on “New Topics at the Interface between Probability and Communications” [8], the second author asked whether and in what sense (2.3) implies (2.1); the question was actually asked for the special case where  $C$  is a multiple of the Lebesgue measure.

In this note we answer this question by proving the following:

**Theorem 2.1.** *Let  $A, C$  be locally finite Borel measures on  $\mathbb{R}_+ = [0, \infty)$  without atoms and consider the integral equation (2.3). This integral equation admits a unique maximal solution, i.e. a solution which pointwise dominates any other solution. Further, this maximal solution is precisely the function  $Q^*$  defined by (2.1).*

We proceed as follows. First, we present some auxiliary results and also give a proof of (2.1)  $\Rightarrow$  (2.3) which is different from the one found in [6]. Then we prove Theorem 2.1 by a successive approximation scheme and by proving a number of lemmas.

### 3. PROOF OF THE INTEGRAL REPRESENTATION AND AUXILIARY RESULTS

We first exhibit some properties of  $Q^*$ , defined by (2.1), and also show that  $Q^*$  satisfies the integral equation (2.3). The proof of the latter in the special case where  $C$  is a multiple of the Lebesgue measure can be found in [7, Lemma 1] and in [2, §3.5.3]. A more general case is dealt with in [6, Theorem 1]. We give a different proof in Proposition 3.4 below. The lemmas below are straightforward and well-known, but we give proofs for completeness. As before,  $X$  is a locally finite Borel measure without atoms and  $X = A - C$  is a decomposition as the difference of two nonnegative locally finite Borel measures without atoms. We set

$$A(t) := A(0, t], \quad C(t) := C(0, t].$$

**Lemma 3.1.** *If  $0 \leq s \leq s' \leq t$  and if  $Q^*(s) > C(s, t]$ , then  $Q^*(s') > C(s', t]$ .*

*Proof.* Assume that  $C(s, t] < Q^*(s) = \sup_{0 \leq u \leq s} X(u, s]$ . This is equivalent to

$$\begin{aligned} C(t) - C(s) &< \sup_{0 \leq u \leq s} \{A(s) - A(u) - (C(s) - C(u))\} \\ &= A(s) + \sup_{0 \leq u \leq s} \{-A(u) + C(u)\} - C(s), \end{aligned}$$

$$\text{that is, } C(t) < A(s) + \sup_{0 \leq u \leq s} \{-A(u) + C(u)\}.$$

The right-hand side of the latter is increasing in  $s$  and so replacing  $s$  by a larger  $s'$  we obtain

$$C(t) < A(s') + \sup_{0 \leq u \leq s'} \{-A(u) + C(u)\},$$

which is equivalent to  $Q^*(s') > C(s', t]$ . □

**Lemma 3.2.**  $Q^*$  satisfies

$$(3.1) \quad Q^*(t) = \sup_{s \leq u \leq t} X(u, t] \vee (Q^*(s) + X(s, t]), \quad 0 \leq s \leq t.$$

*Proof.* We show that the right-hand side of (3.1) equals the left-hand side:

$$\begin{aligned} \sup_{s \leq u \leq t} X(u, t] \vee (Q^*(s) + X(s, t]) &= \sup_{s \leq u \leq t} X(u, t] \vee \left\{ \left( \sup_{0 \leq u \leq s} X(u, s] \right) + X(s, t] \right\} \\ &= \sup_{s \leq u \leq t} X(u, t] \vee \sup_{0 \leq u \leq s} \{X(u, s] + X(s, t]\} \\ &= \sup_{s \leq u \leq t} X(u, t] \vee \sup_{0 \leq u \leq s} X(u, t] \\ &= \sup_{0 \leq u \leq t} X(u, t] = Q^*(t). \quad \square \end{aligned}$$

**Lemma 3.3.** If  $0 \leq s \leq t$  and if  $Q^*(s) \geq C(s, t]$ , then  $Q^*(t) = Q^*(s) + X(s, t]$ .

*Proof.* We use equation (3.1), rewritten as follows:

$$(3.2) \quad Q^*(t) = \sup_{s \leq u \leq t} \{X(u, t] \vee (Q^*(s) + X(s, t])\}.$$

Suppose  $0 \leq s \leq u \leq t$  and that  $Q^*(s) \geq C(s, t]$ . Then  $Q^*(s) \geq C(s, u]$  and so

$$\begin{aligned} Q^*(s) + X(s, t] &\geq C(s, u] + X(s, t] \\ &= C(s, u] + A(s, t] - C(s, t] \\ &= A(s, t] - C(u, t] \\ &\geq A(u, t] - C(u, t] = X(u, t], \end{aligned}$$

and this inequality implies that the term  $X(u, t]$  inside the bracket of the right-hand side of (3.2) is not needed. Hence  $Q^*(t) = Q^*(s) + X(s, t]$ , which is what we wanted to prove.  $\square$

Define next

$$(3.3) \quad \sigma^*(t) := \sup\{0 \leq s \leq t : Q^*(s) \leq C(s, t]\}.$$

By Lemma 3.1,

$$(3.4a) \quad Q^*(s) \leq C(s, t], \quad \text{if } 0 \leq s \leq \sigma^*(t),$$

$$(3.4b) \quad Q^*(s) > C(s, t], \quad \text{if } \sigma^*(t) < s \leq t,$$

provided that the last inequality is nonvacuous. Since the function  $Q^*$  is nonnegative and continuous, we also have

$$Q^*(\sigma^*(t)) = C(\sigma^*(t), t].$$

**Theorem 3.4.** If  $X$  is a locally finite signed Borel measure on  $[0, \infty)$  without atoms and if  $X = A - C$  is any decomposition of  $X$  as the difference of two nonnegative locally finite Borel measures without atoms, then the function  $Q^*$  defined by (2.1) satisfies (2.3).

*Proof.* By Lemma 3.3, and the last display,

$$\begin{aligned} Q^*(t) &= Q^*(\sigma^*(t)) + A(\sigma^*(t), t] - C(\sigma^*(t), t] \\ &= A(\sigma^*(t), t] \\ &= \int_{\sigma^*(t)}^t dA(s) \\ &= \int_0^t \mathbf{1}(Q^*(s) > C(s, t]) dA(s), \end{aligned}$$

which is the integral representation formula (2.3). Note that, to obtain the last equality in the last display, we used (3.4a)-(3.4b).  $\square$

4. PROOF OF THEOREM 2.1

*A priori*, it is not clear that (2.3) admits a maximal solution and, even if it does, whether it satisfies (2.1). We shall show the validity of these claims in the sequel.

We fix two locally finite measures  $A$  and  $C$  and define the map  $\Theta$  on the set of nonnegative measurable functions by

$$(4.1) \quad \Theta(Q)(t) := \int_0^t \mathbf{1}(Q(s) > C(s, t]) dA(s), \quad t \geq 0.$$

The integral equation (2.3) then reads

$$Q = \Theta(Q).$$

We observe that  $\Theta$  is increasing:

$$(4.2) \quad \text{If } Q \leq \tilde{Q}, \text{ then } \Theta(Q) \leq \Theta(\tilde{Q}).$$

Here, and in the sequel, given two functions  $f, g : [0, \infty) \rightarrow \mathbb{R}$ , we write  $f \leq g$  to mean that  $f(t) \leq g(t)$  for all  $t \geq 0$ . To see that (4.2) holds, simply observe that  $Q \leq \tilde{Q}$  implies  $\mathbf{1}(Q(s) > C(s, t]) \leq \mathbf{1}(\tilde{Q}(s) > C(s, t])$  for all  $0 \leq s \leq t$ .

Define next a sequence of functions  $(Q_k, k = 0, 1, 2, \dots)$  by first letting

$$Q_0 := \infty,$$

and then, recursively,

$$Q_{k+1} := \Theta(Q_k), \quad k \geq 0.$$

Clearly,  $Q_1(t) = \int_0^t dA(s) = A(t)$ . So  $Q_0 \geq Q_1$ . Since  $\Theta$  is an increasing map, we see that

$$Q_k \geq Q_{k+1} \geq 0, \quad k \geq 0.$$

We can then define

$$Q_\infty(t) := \lim_{k \rightarrow \infty} Q_k(t).$$

**Lemma 4.1.** *If  $Q = \Theta(Q)$ , then  $Q \leq Q_\infty$ . Furthermore,*

$$Q^* \leq Q_\infty.$$

*Proof.* Suppose that  $Q$  satisfies  $Q = \Theta(Q)$ . Since the integrand in the right-hand side of (4.1) is  $\leq 1$ , we have  $Q(t) \leq A(t)$  for all  $t \geq 0$ . Letting  $\Theta^{(k)}$  be the  $k$ -fold composition of  $\Theta$  with itself, we have

$$Q = \Theta^{(k)}(Q) \leq \Theta^{(k)}(A) = Q_k,$$

and so  $Q \leq Q_\infty$ . In particular, Proposition 3.4 states that  $Q^* = \Theta(Q^*)$ . Hence  $Q^* \leq Q_\infty$ .  $\square$

However, it is not yet clear at this point that  $Q_\infty$  is a fixed point of  $\Theta$ . We can only show that

$$Q_\infty \geq \Theta(Q_\infty).$$

Indeed,  $Q_\infty \leq Q_k$  for all  $k$ , and so  $\mathbf{1}(Q_\infty(s) > C(s, t]) \leq \mathbf{1}(Q_k(s) > C(s, t])$ , for all  $0 \leq s \leq t$ , implying that  $\Theta(Q_\infty) \leq \Theta(Q_k) = Q_{k+1}$ , and, by taking limits, that  $\Theta(Q_\infty) \leq Q_\infty$ .

**Definition 4.2** (Regulating functions). Consider functions  $B : [0, \infty) \rightarrow [0, \infty)$  which are continuous, nondecreasing, with  $B(0) = 0$ , such that  $X(0, t) + B(t) \geq 0$  for all  $t \geq 0$ . Call these functions *regulating functions of  $X$* . The set of regulating functions is denoted by  $\mathcal{R}$ .

We define a mapping

$$(4.3) \quad \Phi : \mathcal{R} \rightarrow \mathcal{R}$$

in two steps as follows.

**Step 1.** Given  $B \in \mathcal{R}$ , first define

$$\sigma_B(t) := \sup\{0 \leq s \leq t : A(s) + B(s) - C(t) \leq 0\}, \quad t \geq 0.$$

To motivate this definition, note that if  $B$  is chosen according to the formula  $B(t) = -\inf_{0 \leq s \leq t} \{A(s) - C(s)\}$ , then  $\sigma_B(t) = \sigma^*(t)$  for all  $t$ , where  $\sigma^*$  was defined in (3.3).

**Step 2.** Then let

$$\Phi(B)(t) := B(\sigma_B(t)), \quad t \geq 0.$$

We actually need to show that what is claimed in (4.3) holds, namely:

**Lemma 4.3.** *If  $B \in \mathcal{R}$ , then  $\Phi(B) \in \mathcal{R}$ .*

*Proof.* Clearly,  $\sigma_B(\cdot)$  is nondecreasing. Since  $B$  is nondecreasing, it follows that  $\Phi(B) = B \circ \sigma_B$  is nondecreasing. Also,  $\Phi(B)(0) = B(\sigma_B(0)) = B(0) = 0$ . From the continuity of  $A$ ,  $B$  and the definition of  $\sigma_B$ , we have

$$(4.4) \quad A(\sigma_B(t)) + B(\sigma_B(t)) = C(t), \quad t \geq 0.$$

We also have

$$\begin{aligned} A(t) + \Phi(B)(t) - C(t) &= A(t) + B(\sigma_B(t)) - C(t) \\ &= [A(t) - A(\sigma_B(t))] + [A(\sigma_B(t)) + B(\sigma_B(t)) - C(t)] \\ &= A(t) - A(\sigma_B(t)) \geq 0, \end{aligned}$$

where we used (4.4) in the third step. It remains to show that  $\Phi(B)(\cdot)$  is continuous. Note that  $\sigma_B(\cdot)$  need not be continuous. However,  $C(\cdot)$  is a continuous function and so, by (4.4),  $t \mapsto A(\sigma_B(t)) + B(\sigma_B(t))$  is continuous. Hence

$$[A(\sigma_B(t+)) - A(\sigma_B(t-))] + [B(\sigma_B(t+)) - B(\sigma_B(t-))] = 0, \quad \text{for all } t.$$

Since  $A(\sigma_B(\cdot))$  and  $B(\sigma_B(\cdot))$  are both nondecreasing, it follows that  $A(\sigma_B(t+)) - A(\sigma_B(t-)) \geq 0$  and  $B(\sigma_B(t+)) - B(\sigma_B(t-)) \geq 0$  and, since their sum is zero, they are both zero, implying that  $A(\sigma_B(\cdot))$  and  $B(\sigma_B(\cdot))$  are continuous.  $\square$

An immediate property of  $\Phi$  is that

$$(4.5) \quad \Phi(B) \leq B \quad \text{for all } B \in \mathcal{R}.$$

Indeed, for all  $t \geq 0$ ,  $\sigma_B(t) \leq t$  and so  $B(\sigma_B(t)) \leq B(t)$ .

Starting with the function

$$(4.6) \quad B_1(t) := C(t), \quad t \geq 0,$$

we recursively define

$$(4.7) \quad B_{k+1} := \Phi(B_k), \quad k \geq 1.$$

Therefore

$$(4.8) \quad B_1 \geq B_2 \geq \dots \geq B_k \downarrow B_\infty, \quad \text{as } k \rightarrow \infty,$$

where the inequalities and the limit are pointwise.

**Lemma 4.4.** *The function  $B_\infty$ , defined via (4.6), (4.7) and (4.8), is a member of the class  $\mathcal{R}$ .*

*Proof.*  $B_\infty$  is nondecreasing since all the  $B_k$  are nondecreasing. Also,  $B_\infty(0) = 0$ . Since for all  $k$ ,  $A + B_k - C \geq 0$ , we have  $A + B_\infty - C \geq 0$ . We proceed to show that  $B_\infty$  is a continuous function. We observe that, for  $0 \leq t \leq t'$ ,

$$\begin{aligned} |\Phi(B)(t') - \Phi(B)(t)| &= |B(\sigma_B(t')) - B(\sigma_B(t))| \\ &= B(\sigma_B(t')) - B(\sigma_B(t)) \\ &\leq A(\sigma_B(t')) - A(\sigma_B(t)) + B(\sigma_B(t')) - B(\sigma_B(t)) \\ &= [A(\sigma_B(t')) + B(\sigma_B(t'))] - [A(\sigma_B(t)) + B(\sigma_B(t))] \\ &= C(t') - C(t), \end{aligned}$$

where we again used (4.4). It follows that the family of functions  $\{\Phi(B), B \in \mathcal{R}\}$  is uniformly bounded and equicontinuous on each compact interval of the real line. By the Arzelà-Ascoli theorem, the family is compact and therefore  $B_\infty$  is continuous. We have established that  $B_\infty \in \mathcal{R}$ .  $\square$

We now claim that  $B_\infty$  is a fixed point of  $\Phi$ .

**Lemma 4.5.**  $\Phi(B_\infty) = B_\infty$ .

*Proof.* By definition,

$$\Phi(B_\infty)(t) = B_\infty(\sigma_{B_\infty}(t)),$$

where

$$\sigma_{B_\infty}(t) = \sup\{0 \leq s \leq t : A(s) + B_\infty(s) \leq C(t)\}.$$

Now, since  $B_k \geq B_{k+1}$  for all  $k \geq 1$ , it follows that  $\sigma_{B_k} \leq \sigma_{B_{k+1}}$  for all  $k \geq 1$ , and so

$$\sigma_L(t) := \lim_{k \rightarrow \infty} \sigma_{B_k}(t)$$

is well-defined. Since  $B_k \geq B_\infty$  for all  $k \geq 1$ , we have  $\sigma_{B_k} \leq \sigma_{B_\infty}$ . Taking limits, we find

$$\sigma_L \leq \sigma_{B_\infty}.$$

Using the last two displays and the fact that  $B_k$  and  $B_\infty$  are nondecreasing, we have

$$\begin{aligned} \Phi(B_\infty)(t) &= B_\infty(\sigma_{B_\infty}(t)) \geq B_\infty(\sigma_L(t)) \\ &= \lim_{k \rightarrow \infty} B_k(\sigma_L(t)) \\ &\geq \lim_{k \rightarrow \infty} B_k(\sigma_{B_k}(t)) \\ &= \lim_{k \rightarrow \infty} B_{k+1}(t) = B_\infty(t). \end{aligned}$$

By inequality (4.5),  $\Phi(B) \leq B$  for all  $B \in \mathcal{R}$  and since, by Lemma 4.4,  $B_\infty \in \mathcal{R}$ , it follows that we also have  $B_\infty \leq \Phi(B_\infty)$ . Therefore  $B_\infty = \Phi(B_\infty)$ , as claimed.  $\square$

**Lemma 4.6.** *Consider the function  $Q^*$  defined by (2.1) and define a function  $B^*$  by*

$$B^*(t) := Q^*(t) - X(0, t], \quad t \geq 0.$$

Then

- (i)  $B^* \in \mathcal{R}$ ;
- (ii)  $B^* = \Phi(B^*)$ .

*Proof.* (i) We have  $X(0, t] + B^*(t) = Q^*(t) \geq 0$  for all  $t$ . Using (2.1) and (2.2) we see that

$$(4.9) \quad B^*(t) = \sup_{0 \leq s \leq t} \{-A(s) + C(s)\}.$$

Therefore,  $B^*(0) = 0$ , and  $B^*$  is continuous and nondecreasing. We conclude that  $B^* \in \mathcal{R}$ . To prove (ii), recall that  $\Phi(B^*) = B^* \circ \sigma_{B^*}$ , where

$$\sigma_{B^*}(t) = \sup\{0 \leq s \leq t : A(s) + B^*(s) \leq C(t)\}.$$

Splitting the supremum in (4.9) into two parts, we obtain

$$\begin{aligned} B^*(t) &= \sup_{0 \leq s \leq \sigma_{B^*}(t)} \{-A(s) + C(s)\} \vee \sup_{\sigma_{B^*}(t) \leq s \leq t} \{-A(s) + C(s)\}. \\ &= B^*(\sigma_{B^*}(t)) \vee \sup_{\sigma_{B^*}(t) \leq s \leq t} \{-A(s) + C(s)\}. \end{aligned}$$

For  $s \geq \sigma_{B^*}(t)$ , we have  $A(s) + B^*(s) \geq C(t)$ , i.e.  $-A(s) + C(s) \leq B^*(s) - C(s, t]$ . Therefore

$$\begin{aligned} B^*(t) &\leq B^*(\sigma_{B^*}(t)) \vee \sup_{\sigma_{B^*}(t) \leq s \leq t} \{B^*(s) - C(s, t]\} \\ &= B^*(\sigma_{B^*}(t)) = \Phi(B^*)(t). \end{aligned}$$

Thus,  $B^* \leq \Phi(B^*)$ . On the other hand, since  $B^* \in \mathcal{R}$ , we have  $\Phi(B^*) \leq B^*$ , by (4.5).  $\square$

**Lemma 4.7.** *Let  $B \in \mathcal{R}$  be any fixed point of  $\Phi$ . Then  $B \leq B^*$ .*

*Proof.* Since  $B = \Phi(B) = B \circ \sigma_B$  we have

$$B = B \circ \sigma_B^{(k)},$$

where  $\sigma_B^{(k)} := \underbrace{\sigma_B \circ \dots \circ \sigma_B}_{k \text{ times}}$ . Since

$$t \geq \sigma_B(t) \geq \sigma_B \circ \sigma_B(t) \geq \dots \geq \sigma_B^{(k)}(t),$$



we may define

$$\sigma_B^{(\infty)}(t) := \lim_{k \rightarrow \infty} \sigma_B^{(k)}(t).$$

By the continuity of  $B$ ,

$$(4.10) \quad B = B \circ \sigma_B^{(\infty)}.$$

On the other hand, (4.4) gives

$$A \circ \sigma_B^{(k+1)} + B \circ \sigma_B^{(k+1)} = C \circ \sigma_B^{(k)}, \quad k \geq 1.$$

Taking the limit as  $k \rightarrow \infty$ , and using the continuity of  $A$ ,  $B$  and  $C$ , we have

$$A \circ \sigma_B^{(\infty)} + B \circ \sigma_B^{(\infty)} = C \circ \sigma_B^{(\infty)}.$$

Since  $A(t) + B^*(t) \geq C(t)$  for all  $t$ , we have

$$A \circ \sigma_B^{(\infty)} + B^* \circ \sigma_B^{(\infty)} \geq C \circ \sigma_B^{(\infty)},$$

and from the last two displays we conclude that

$$B^* \circ \sigma_B^{(\infty)} \geq B \circ \sigma_B^{(\infty)}.$$

Since  $B^*$  is nondecreasing and since (4.10) holds, we have

$$B^* \geq B^* \circ \sigma_B^{(\infty)} \geq B \circ \sigma_B^{(\infty)} = B,$$

as claimed. □

We are now ready to prove Theorem 2.1. We already know from Lemma 4.1 that  $Q^* \leq Q_\infty$ . So we only have to prove the opposite inequality. Recall that  $Q_1 = A$  and  $B_1 = C$ . Trivially then

$$Q_1(t) + C(t) = A(t) + B_1(t), \quad t \geq 0.$$

Thus, for  $0 \leq s \leq t$  we have

$$\begin{aligned} Q_1(s) > C(s, t] &\iff Q_1(s) + C(s) > C(t) \\ &\iff A(s) + B_1(s) > C(t) \\ &\iff s > \sigma_{B_1}(t). \end{aligned}$$

From this we get

$$\begin{aligned} Q_2(t) &= \int_0^t \mathbf{1}(Q_1(s) > C(s, t]) \, dA(s) \\ &= \int_0^t \mathbf{1}(s > \sigma_{B_1}(t)) \, dA(s) \\ &= A(t) - A(\sigma_{B_1}(t)). \end{aligned}$$

But (4.4) gives

$$A(\sigma_{B_1}(t)) + B_1(\sigma_{B_1}(t)) = C(t),$$

and so

$$Q_2(t) + C(t) = A(t) + B_1(\sigma_{B_1}(t)) = A(t) + B_2(t), \quad t \geq 0.$$

We now claim that

$$Q_k(t) + C(t) = A(t) + B_k(t), \quad t \geq 0, \quad k \geq 1.$$

This can be proved by induction along the same lines as above. Taking limits as  $k \rightarrow \infty$ , we conclude

$$Q_\infty(t) + C(t) = A(t) + B_\infty(t), \quad t \geq 0.$$

Lemma 4.5 tells us that  $B_\infty$  is a fixed point of  $\Phi$ , and so, by Lemma 4.7,

$$B_\infty \leq B^*.$$

Hence

$$\begin{aligned} Q_\infty(t) + C(t) &= A(t) + B_\infty(t) \\ &\leq A(t) + B^*(t) \\ &= Q^*(t) + C(t), \quad t \geq 0, \end{aligned}$$

and this gives

$$Q_\infty \leq Q^*,$$

as needed.

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