

GENERATING THE MÖBIUS GROUP WITH INVOLUTION CONJUGACY CLASSES

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ABSTRACT. A k -involution is an involution with a fixed point set of codimension k . The conjugacy class of such an involution, denoted S_k , generates $\text{Möb}(n)$ (the group of isometries of hyperbolic n -space) if k is odd and its orientation-preserving subgroup if k is even. In this paper, we supply effective lower and upper bounds for the S_k word length of $\text{Möb}(n)$ if k is odd and the S_k word length of $\text{Möb}^+(n)$ if k is even. As a consequence, for a fixed codimension k , the length of $\text{Möb}^+(n)$ with respect to S_k , k even, grows linearly with n , with the same statement holding for $\text{Möb}(n)$ in the odd case. Moreover, the percentage of involution conjugacy classes for which $\text{Möb}^+(n)$ has length two approaches zero as n approaches infinity.

1. INTRODUCTION AND RESULTS

Let G be a group and S a set of symmetric generators for a supergroup of G ; S is not necessarily a subset of G , but every element can be written as a product of elements from S . For $g \in G$, the *length* of g with respect to S (or S -length) is the minimal number of elements of S needed to express g as their product. The supremum over all group element lengths is called the *length of G with respect to S* (or simply the S -length of G), and is denoted by $|G|$.

We are interested in the set $S_k \subset \text{Möb}(n)$ of involutions with a codimension k fixed point set acting on hyperbolic space, \mathbb{H}^n .

Theorem 1.1. *Let $n \geq 2$ and $k = 1, 2, \dots, n - 1$.*

- *If k is even, S_k generates $\text{Möb}^+(n)$ and satisfies*

$$(1) \quad \frac{n(n+1)}{2k(n-k+1)} \leq |\text{Möb}^+(n)|_k \leq 2n+4.$$

- *If k is odd, S_k generates $\text{Möb}(n)$ and satisfies*

$$(2) \quad \frac{n(n+1)}{2k(n-k+1)} \leq |\text{Möb}(n)|_k \leq 2n+2+k,$$

where $|\cdot|_k$ denotes S_k -length.

In particular, we have

Corollary 1.2 (Linear growth). *For a fixed codimension k :*

- *If k is even, $|\text{Möb}^+(n)|_k \asymp n$.*
- *If k is odd, $|\text{Möb}(n)|_k \asymp n$.*

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Our main tool in achieving both lower bounds in Theorem 1.1 is a dimension count which yields the fact that the set of elements of the form $\alpha_1 \dots \alpha_m$, where α_i is a k -involution and $m < \frac{n(n+1)}{2k(n-k+1)}$, has measure zero in $\text{Möb}(n)$ (see Theorem 4.1 and Corollary 2.2). The upper bounds follow from elementary considerations (see Corollary 2.2).

We next consider the percentage of involution conjugacy classes for which $|\text{Möb}^+(n)| = 2$. More precisely, define

$$(3) \quad \Phi(n) = \frac{|\{k : \text{the } S_k\text{-length of } \text{Möb}^+(n) \text{ is } 2\}|}{|\{\text{involution conjugacy classes in dimension } n\}|}.$$

Recall that the conjugacy class of an involution is determined by the dimension of its (totally geodesic) fixed point set. Thus a k -involution determines a conjugacy class, and the denominator above is n . Setting $|\text{Möb}^+(n)| = 2$ and using the lower bound in inequality (1), after a straightforward computation to find bounds on k in terms of n we have

Corollary 1.3. $\Phi(n) = O(n^{-\frac{1}{2}})$.

Remark 1.4. In the paper [1] the authors show that in each dimension n there exists an involution conjugacy class S_k for which $|\text{Möb}^+(n)| = 2$. When n is even, k may be taken to be $\frac{n}{2}$, and when n is odd, k can be taken to be $\frac{n+1}{2}$. The results of our paper show that away from the middle codimensions (relative to n) one cannot expect the length of $\text{Möb}^+(n)$ to be small. Factoring of isometries from a geometric viewpoint in hyperbolic 4-space is also studied in [3].

Hyperbolic n -space is denoted by \mathbb{H}^n . The group of orientation-preserving isometries of \mathbb{H}^n (the Möbius group) is $\text{Möb}^+(n)$, and the full group is $\text{Möb}(n)$. An involution is an order-two isometry of \mathbb{H}^n and a k -involution is an isometry with a fixed point set of codimension k . A *reflection* is an involution with a codimension one fixed point set, and a *half-turn* is an involution with a codimension two fixed point set. The involution is orientation-reversing if and only if the codimension of the fixed point set is odd. For $k = 1, 2, 3, \dots, n$, let S_k be the set (conjugacy class) of k -involutions. For the basics on hyperbolic space and its isometry group we refer to Maskit or Ratcliffe ([2], [4]). For standard material on differential topology and Lie groups the reader is referred to [5] and [6].

We will use the well-known facts that the dimension of $O(n)$, as well as $SO(n)$, is $\frac{n(n-1)}{2}$ and the dimension of $\text{Möb}^+(n)$, as well as $\text{Möb}(n)$, is $\frac{n(n+1)}{2}$.

The paper is organized as follows. Section 2 contains the proofs that conjugacy classes of involutions generate the Möbius group as well as upper bounds on word length. In section 3, we show that the space of k -involutions is a submanifold of $\text{Möb}(n)$ having dimension $k(n-k+1)$. Finally, we prove Theorem 1.1 in section 4.

2. k -INVOLUTIONS IN THE ORTHOGONAL AND MÖBIUS GROUPS

Throughout this section, we fix an integer $n \geq 2$ and an integer $k = 1, 2, \dots, n-1$. The case $k = n$ is excluded since $S_n \cap O(n)$ has only one element and hence does not generate the orthogonal group.

This section is devoted to proving

Theorem 2.1. $S_k \cap O(n)$ generates $O(n)$ if k is odd and generates $SO(n)$ when k is even. Furthermore for $g \in O(n)$,

$$(4) \quad |g| \leq \begin{cases} 2n, & \text{if } g \text{ is orientation-preserving} \\ 2n - 2 + k, & \text{if } g \text{ is orientation-reversing} \end{cases},$$

where $|g|$ is the $S_k \cap O(n)$ -length of g .

Corollary 2.2. S_k generates $Möb(n)$ if k is odd and generates $Möb^+(n)$ when k is even. Furthermore for $g \in Möb(n)$,

$$(5) \quad |g| \leq \begin{cases} 2n + 4, & \text{if } g \text{ is orientation-preserving} \\ 2n + 2 + k, & \text{if } g \text{ is orientation-reversing} \end{cases},$$

where $|g|$ is the S_k -length of g .

Remark 2.3. In both Theorem 2.1 and Corollary 2.2, we note that k is necessarily odd when g is orientation-reversing.

The stabilizer of any point in \mathbb{H}^n has a natural identification with $O(n)$. We fix such a copy of $O(n) \subset Möb(n)$.

Denote the $n \times n$ diagonal matrices with k entries being -1 and with $n - k$ entries being 1 by $\mathcal{D}(n, k)$. Since an involution in $O(n)$ is $O(n)$ -conjugate to a diagonal matrix, it is immediate that a k -involution in $O(n)$ is conjugate to a diagonal matrix in $\mathcal{D}(n, k)$. There are $\binom{n}{k}$ such matrices.

Lemma 2.4. Assume $n \geq 2$ and $k = 1, \dots, n - 1$.

- (1) If k is odd, then any element of $\mathcal{D}(n, 1)$ can be written as the product of k elements of $\mathcal{D}(n, k)$.
- (2) Any element of $\mathcal{D}(n, 2)$ can be written as the product of two elements of $\mathcal{D}(n, k)$.

Proof. For ease of notation, we identify the diagonal matrices of size n having ± 1 entries with the group \mathbb{Z}_2^n . That is, $\bigcup_{k=0}^n \mathcal{D}(n, k) = \mathbb{Z}_2^n$. We write an element of \mathbb{Z}_2^n as a vector with the obvious component-wise multiplication in \mathbb{Z}_2 .

To prove item (1), consider $A = [-1, 1, 1, \dots, 1] \in \mathcal{D}(n, 1)$. It suffices to show that A can be written as the desired product. For $i = 1, \dots, k$, let $C_i \in \mathcal{D}(n, k)$ with j -th component being

$$(6) \quad C_i^j = \begin{cases} 1, & \text{if } j = i + 1 \text{ or } k + 2 \leq j \leq n \\ -1, & \text{if } 1 \leq j \leq k + 1 \text{ and } j \neq i + 1 \end{cases}.$$

Then $A = \prod_{i=1}^k C_i$ and we have the desired decomposition of A .

To prove item (2), consider $A = [-1, -1, 1, \dots, 1] \in \mathcal{D}(n, 2)$. It suffices to show that A can be written as the desired product. Let $R \in \mathcal{D}(n, k)$ be such that its j -th component is

$$(7) \quad R^j = \begin{cases} 1, & \text{if } j = 1 \text{ or } k + 2 \leq j \leq n \\ -1, & \text{if } 2 \leq j \leq k + 1 \end{cases}$$

and let $S \in \mathcal{D}(n, k)$ have j -th entry

$$(8) \quad S^j = \begin{cases} 1, & \text{if } j = 2 \text{ or } k + 2 \leq j \leq n \\ -1, & \text{otherwise} \end{cases}.$$

Then $RS = A$ and we are finished with the proof of item (2). □

Lemma 2.5. *Let a and b be reflections in hyperplanes α and β in $\mathbb{H}^n (n \geq 3)$ and let $g = ab$. Then there exist half-turns h and k such that $g = hk$.*

Proof. Consider the upper half-space model of \mathbb{H}^n . Let $\alpha \cap \hat{\mathbb{R}}^{n-1} = \tilde{\alpha}$ and $\beta \cap \hat{\mathbb{R}}^{n-1} = \tilde{\beta}$. Then $\tilde{\alpha}$ and $\tilde{\beta}$ are $(n - 2)$ -spheres in $\hat{\mathbb{R}}^{n-1}$. We may assume that neither $\tilde{\alpha}$ nor $\tilde{\beta}$ contains the point at infinity (∞) . Consider the unique circle ρ through ∞ and each of the centers of $\tilde{\alpha}$ and $\tilde{\beta}$. It is clear that any $(n - 2)$ -sphere containing ρ is orthogonal to each of $\tilde{\alpha}$ and $\tilde{\beta}$. Let $\tilde{\gamma}$ be one such $(n - 2)$ -sphere.

Then, $\tilde{\gamma} = \gamma \cap \hat{\mathbb{R}}^{n-1}$, where γ is a hyperplane in \mathbb{H}^n which is orthogonal to each of α and β . Let c denote reflection in γ . Then $h = ac$ and $k = cb$ are half-turns in \mathbb{H}^n such that $hk = (ac)(cb) = accb = ab = g$. □

Proof of Theorem 2.1. Fix $k = 1, \dots, n - 1$. Using the block diagonal form for an element in $g \in SO(n)$, it is easy to see that an element $g \in SO(n)$ can be written as a product $\rho_1 \dots \rho_m$, where $\rho_i \in S_1 \cap O(n)$, m is even, and m is at most n . Now, using Lemma 2.5, we write g as a product of m half-turns. Of course, the half-turns are $O(n)$ -conjugate to a diagonal matrix in $\mathcal{D}(n, 2)$ and hence using item (2) of Lemma 2.4, we can write g as the product of at most $2n$ elements in $S_k \cap O(n)$.

If $g \in O(n) - SO(n)$, then $g = \rho_1 \dots \rho_m$, where m is odd and at most n . Note that it must be that k is odd. As above we write $\rho_1 \dots \rho_{m-1}$ as the product of at most $2n - 2$ elements in $S_k \cap O(n)$. The reflection ρ_m , using item (1) of Lemma 2.4, can be written as the product of k elements in $S_k \cap O(n)$. Thus for such an element g , $|g| \leq 2n - 2 + k$. □

Proof of Corollary 2.2. For $g \in \text{Möb}(n)$, it is well known that $g = \Phi\tau\sigma$, where σ and τ are reflections, and Φ is an element of $O(n)$. Moreover g is orientation-preserving if and only if $\Phi \in SO(n)$. Using Lemma 2.5, we can replace $\tau\sigma$ by the product of two half-turns which by Lemma 2.4 can be written as the product of 4 elements in S_k . The corollary now follows from Theorem 2.1. □

3. INVOLUTIONS AND THE SPACE OF TOTALLY GEODESIC SUBSPACES OF \mathbb{H}^n

Throughout this section, we fix an integer $n \geq 2$ and an integer $k = 1, 2, \dots, n - 1$.

Lemma 3.1. *$S_k \subset \text{Möb}(n)$ is a (connected) differentiable submanifold of dimension $k(n - k + 1)$.*

Proof. Set $G = \text{Möb}(n)$. Fix $\alpha \in S_k \subset \text{Möb}(n)$ and denote its fixed point set by π , an $(n - k)$ -dimensional plane. Consider the smooth conjugation action of the Lie group G on itself, namely, $g \cdot f = gf g^{-1}$. Since an orbit of a Lie group action is a submanifold, we have that the G -orbit of α , that is S_k , is a submanifold of $\text{Möb}(n)$. Furthermore, the map from G to G , given by $g \mapsto g\alpha g^{-1}$, induces a one-to-one smooth map from G/K onto S_k , where $K = \text{Stab}_G(\alpha)$. (Note that K is a closed subgroup of G .) Next observe that $\text{Stab}_G(\alpha) = \text{Stab}_G(\pi)$ and consider the map

$$(9) \quad \Phi : \text{Stab}_G(\pi) \rightarrow \text{Möb}(n - k),$$

given by $g \mapsto g|_\pi$. This is a surjective map with kernel being isomorphic to $O(k) \leq \text{Stab}_G(\pi)$. Hence, $\text{Stab}_G(\pi)/O(k)$ is isomorphic to $\text{Möb}(n - k)$, and thus

$$(10) \quad \dim(K) = \dim(\text{Stab}_G(\alpha)) = \dim(\text{Möb}(n - k)) + \dim(O(k)).$$

Thus we have

$$(11) \quad \dim(S_k) = \dim(G) - \dim(K) = \dim(G) - \dim(\text{Möb}(n - k)) - \dim(O(k)).$$

Now plugging in the various quantities and simplifying yield the dimension of S_k to be $k(n - k + 1)$. \square

For $k = 1, \dots, n - 1$, let \mathcal{G}_k denote the space of k -planes (that is, k -dimensional totally geodesic subspaces) in \mathbb{H}^n . The boundary (at infinity) of a k -plane is a round $(k - 1)$ -sphere. The space of $(k - 1)$ -spheres with the Gromov-Hausdorff topology induces a natural topology on \mathcal{G}_k .

Corollary 3.2. \mathcal{G}_k is a differentiable manifold of dimension $(n - k)(k + 1)$.

Proof. Consider the map $\mathcal{G}_k \rightarrow \mathcal{S}_{n-k}$ given by taking the k -plane π to the $(n - k)$ -involution with fixed point set π . As can be checked by the reader, this map is a homeomorphism. Pulling back the differentiable structure from \mathcal{S}_{n-k} , \mathcal{G}_k becomes a differentiable manifold whose dimension by Lemma 3.1 is $(n - k)(k + 1)$. \square

4. BOUNDS FOR THE S_k -LENGTH OF THE MÖBIUS GROUP

Given a subset $J \subseteq \{1, \dots, n - 1\}$, let S be the generating set $S = \bigcup_{k \in J} S_k$, and set $M = M(S) = \max_{c \in J} \{\dim(S_k)\} = \max_{k \in J} \{k(n - k + 1)\}$.

Theorem 4.1. Except for a set of measure zero, no element of $\text{Möb}(n)$ can be written as a product $\alpha_1 \dots \alpha_m$, where $\alpha_i \in S$, and $m < \frac{n(n+1)}{2M}$.

Proof. Consider the manifold which is the m -fold product of the Möbius group. Given a sequence $\{k_1, \dots, k_m\}$ of m -elements from J (repetition is allowed), consider the mapping $\Psi : S_{k_1} \times \dots \times S_{k_m} \rightarrow \text{Möb}(n)$ which assigns the m -tuple of ordered k_i -involutions $(\alpha_1, \dots, \alpha_m)$ to the product $\alpha_1 \dots \alpha_m$. This is a smooth mapping between manifolds. The dimension of $S_{k_1} \times \dots \times S_{k_m}$ is bounded from above by mM , which is by assumption less than the dimension of $\text{Möb}(n) = \frac{n(n+1)}{2}$. Hence Ψ is a smooth mapping from a manifold of lower dimension to one of higher dimension. It is a standard fact that the image of a smooth map from a manifold of lower dimension to one of higher dimension has measure zero.

Finally, there are a finite number of (namely, $\sum_{i=1}^{\lfloor \frac{n(n+1)}{2M} \rfloor} |J|^i$) sequences from J of length less than or equal to $\frac{n(n+1)}{2M}$, and hence a finite number of maps Ψ above. Thus the set of elements in $\text{Möb}(n)$ that are in the images of such maps Ψ is the finite union of sets of measure zero, hence has measure zero. This precisely says that the set of elements of $\text{Möb}(n)$ that can be written as a product of at most m elements from S has measure zero. \square

Theorem 1.1. Let $n \geq 2$ and $k = 1, 2, \dots, n - 1$.

- If k is even, S_k generates $\text{Möb}^+(n)$ and satisfies

$$(12) \quad \frac{n(n+1)}{2k(n-k+1)} \leq |\text{Möb}^+(n)|_k \leq 2n+4.$$

- If k is odd, S_k generates $\text{Möb}(n)$ and satisfies

$$(13) \quad \frac{n(n+1)}{2k(n-k+1)} \leq |\text{Möb}(n)|_k \leq 2n+2+k.$$

Proof. The upper bound in either the even or odd case follows from Corollary 2.2. For the lower bound, if all $k_i = k$, then $M = k(n - k + 1)$. Now if $|g| < \frac{n(n+1)}{2k(n-k+1)}$, for all $g \in \text{Möb}(n)$, then Theorem 4.1 is contradicted. \square

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