

INVARIANT POLYNOMIALS OF ORE EXTENSIONS BY q -SKEW DERIVATIONS

CHEN-LIAN CHUANG, TSIU-KWEN LEE, AND CHENG-KAI LIU

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ABSTRACT. Let R be a prime ring with the symmetric Martindale quotient ring Q . Suppose that δ is a quasi-algebraic q -skew σ -derivation of R . For a minimal monic semi-invariant polynomial $\pi(t)$ of $Q[t; \sigma, \delta]$, we show that $\pi(t)$ is also invariant if $\text{char } R = 0$ and that either $\pi(t) - c$ for some $c \in Q$ or $\pi(t)^p$ is a minimal monic invariant polynomial if $\text{char } R = p \geq 2$. As an application, we prove that any R -disjoint prime ideal of $R[t; \sigma, \delta]$ is the principal ideal $\langle p(t) \rangle$ for an irreducible monic invariant polynomial $p(t)$ unless σ or δ is X-inner.

1. INTRODUCTION

It will be assumed throughout that R is an associative prime ring in the sense that for any $a, b \in R$, $aRb = 0$ implies $a = 0$ or $b = 0$. Let σ be an automorphism of R . By a σ -derivation of R , we mean a map $\delta: R \rightarrow R$ satisfying

$$\delta(x + y) = \delta(x) + \delta(y) \quad \text{and} \quad \delta(xy) = \delta(x)y + \sigma(x)\delta(y)$$

for all $x, y \in R$. Given $b \in R$, the map $\text{ad}_{b,\sigma}: x \in R \mapsto bx - \sigma(x)b$ defines a σ -derivation of R , called the inner σ -derivation defined by b . Analogously, for a unit $u \in R$, the map $I_u: x \in R \mapsto uxu^{-1}$ defines an automorphism of R , called the inner automorphism defined by the unit element u .

Let Q be the symmetric Martindale quotient ring of R . The center of Q , denoted by C , is called the extended centroid of R . (See [1, Chapter 2] for details.) The σ -derivation δ of R , together with its automorphism σ , can be uniquely extended to a σ -derivation of Q [15, Lemma 1]. A σ -derivation of R is called X-inner if its extension to Q is equal to $\text{ad}_{b,\sigma}$ for some $b \in Q$. An automorphism of R is called X-inner if its extension to Q is equal to I_u for some unit $u \in Q$. Following [14], define for each integer j the C -space

$$\Phi(j) \stackrel{\text{def.}}{=} \{u \in Q \mid ur = \sigma^j(r)u \text{ for all } r \in Q\}.$$

By [22, Chapter 3, Lemma 12.1], any $0 \neq u \in \Phi(j)$ is a unit such that $\sigma^j = I_u$. We recall a very useful property due to Kharchenko and Popov [15].

Lemma 1.1. *If δ is an X-outer σ -derivation, then $\sigma(\alpha) = \alpha$ and either $\delta(\alpha) = 0$ or $\sigma = I_{\delta(\alpha)}$ for each $\alpha \in C$.*

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The first two authors are members of the Mathematics Division, NCTS (Taipei Office).

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Proof. Given $\alpha \in C$ and $x \in R$, $\delta(\alpha x) = \delta(\alpha)x + \sigma(\alpha)\delta(x)$ and $\delta(x\alpha) = \delta(x)\alpha + \sigma(x)\delta(\alpha)$ yield $(\sigma(\alpha) - \alpha)\delta(x) = \sigma(x)\delta(\alpha) - \delta(\alpha)x$. So $\sigma(\alpha) = \alpha$ and $\sigma(x)\delta(\alpha) - \delta(\alpha)x = 0$ by the outerness of δ . Since $x \in R$ is arbitrary, $\delta(\alpha) \neq 0$ implies $\sigma = I_{\delta(\alpha)}$ by [22, Chapter 3, Lemma 12.1]. \square

We shall need the following generalization of Lemma 1.1.

Lemma 1.2. *Let δ be an X-outer σ -derivation. For a unit $u \in Q$, if $\delta I_u = \gamma I_u \delta$, where $\gamma \in C$, then $\sigma(u) = \gamma u$ and either $\delta(u) = 0$ or $\sigma = I_{u^{-1}\delta(u)}$.*

Proof. Expand $0 = \delta(1) = \delta(uu^{-1}) = \delta(u)u^{-1} + \sigma(u)\delta(u^{-1})$. We see that $\delta(u^{-1}) = -\sigma(u)^{-1}\delta(u)u^{-1}$. With this, we compute for $x \in R$

$$\begin{aligned} \delta I_u(x) &= \delta(uxu^{-1}) = \delta(u)xu^{-1} + \sigma(u)\delta(x)u^{-1} + \sigma(u)\sigma(x)\delta(u^{-1}) \\ &= \delta(u)xu^{-1} + \sigma(u)\delta(x)u^{-1} - \sigma(u)\sigma(x)\sigma(u)^{-1}\delta(u)u^{-1}. \end{aligned}$$

The assumption $\delta I_u(x) = \gamma I_u \delta(x) = \gamma u \delta(x) u^{-1}$ gives the identity

$$\delta(u)xu^{-1} + (\sigma(u) - \gamma u)\delta(x)u^{-1} - \sigma(u)\sigma(x)\sigma(u)^{-1}\delta(u)u^{-1} = 0.$$

But δ is X-outer. By [15, Theorem 1], $\sigma(u) = \gamma u$ and for $x \in R$,

$$\begin{aligned} 0 &= \delta(u)xu^{-1} - \sigma(u)\sigma(x)\sigma(u)^{-1}\delta(u)u^{-1} \\ &= \delta(u)xu^{-1} - (\gamma u)\sigma(x)(\gamma u)^{-1}\delta(u)u^{-1} \\ &= \delta(u)xu^{-1} - u\sigma(x)u^{-1}\delta(u)u^{-1} = u(u^{-1}\delta(u)x - \sigma(x)u^{-1}\delta(u))u^{-1}. \end{aligned}$$

So $u^{-1}\delta(u) \in I_\sigma$. If $\delta(u) \neq 0$, then $\sigma = I_{u^{-1}\delta(u)}$, as asserted. \square

The Ore extension of R by a σ -derivation δ , denoted by $R[t; \sigma, \delta]$, is the set of polynomial expressions $a_0 + a_1t + \cdots + a_nt^n$, where $a_0, \dots, a_n \in R$, with componentwise addition and multiplication subjected to the rule $tr = \sigma(r)t + \delta(r)$ for all $r \in R$. We form $Q[t; \sigma, \delta]$ analogously. Ore extensions have been extensively investigated in various directions. In the study of $R[t; \sigma, \delta]$, two crucially important notions are the notion of a right invariant polynomial and that of a semi-invariant polynomial. We omit “right” here for brevity and recall the definition below.

Definition 1 ([16, 17, 18, 20]). We call $f(t) \in Q[t; \sigma, \delta]$ a cv-polynomial if it is associated to an automorphism τ of Q such that $f(t)r - \tau(r)f(t) \in Q$ for any $r \in R$. A cv-polynomial $f(t)$ is called *semi-invariant* if $f(t)r - \tau(r)f(t) = 0$ for all $r \in R$. A semi-invariant polynomial $f(t)$ is called *invariant* if additionally $f(t)t = (at + b)f(t)$ for some $a, b \in Q$. A (semi-)invariant polynomial is called *minimal* if it is nonconstant and its degree is minimal among all nonconstant (semi-)invariant polynomials.

The importance of these polynomials is based on the following: cv-polynomials determine R -stable homomorphisms from other Ore extensions of R into $R[t; \sigma, \delta]$ ([18] or [8, Theorem 12]). Semi-invariant polynomials determine the algebraic dependency of δ ([5]). Invariant polynomials determine the ideal structure of $R[t; \sigma, \delta]$ ([17, 20]). In particular, $R[t; \sigma, \delta]$ has nontrivial R -disjoint ideals iff $R[t; \sigma, \delta]$ has nonconstant (semi-)invariant polynomials ([20, Theorem 2.6]). For a simple ring R , $R[t; \sigma, \delta]$ is simple iff $R[t; \sigma, \delta]$ has no nonconstant (semi-)invariant polynomials. (Semi-)invariant polynomials for X-inner skew derivations can be found easily as follows.

Lemma 1.3. *If $\delta = ad_{b,\sigma}$, where $b \in Q$, then $\pi(t) \stackrel{\text{def.}}{=} t - b$ is the minimal invariant polynomial.*

Proof. Clearly, $\pi(t)r = \sigma(r)\pi(t)$ for $r \in R$. Also,

$$\begin{aligned} (t - b)t &= (t - b)(t - b + b) = (t - b)^2 + (t - b)b \\ &= (t - b)^2 + \sigma(b)(t - b) = (t - b + \sigma(b))(t - b). \end{aligned}$$

So $t - b$ is invariant. □

Let $\pi(t)$ be a minimal monic semi-invariant polynomial of $R[t; \sigma, \delta]$. It is shown in [20] that a factor of $\pi(t)^{\deg \pi(t)}$ forms a minimal monic invariant polynomial. But for an ordinary derivation δ (namely for δ with $\sigma = 1$), $\pi(t)$ is also invariant when $\text{char } R = 0$ and either $\pi(t) - c$ for some $c \in Q$ or $\pi(t)^p$ is a minimal invariant polynomial when $\text{char } R = p \geq 2$. Our aim here is to show that this is also true if δ is q -skew in a sense we now make clear. For any subset S of Q , define

$$S^{(\sigma)} \stackrel{\text{def.}}{=} \{r \in S \mid \sigma(r) = r\}, \quad S^{(\delta)} \stackrel{\text{def.}}{=} \{r \in S \mid \delta(r) = 0\} \text{ and } S^{(\sigma,\delta)} \stackrel{\text{def.}}{=} S^{(\sigma)} \cap S^{(\delta)}.$$

Definition. A σ -derivation δ is called q -skew, where $0 \neq q \in C^{(\sigma,\delta)}$, if $\sigma^{-1}\delta\sigma = q\delta$.

2. RESULTS

Throughout the sequel, let δ be a q -skew σ -derivation and let $\pi(t)$ be a minimal monic semi-invariant polynomial. In order for $\pi(t)$ to exist, we assume that δ is quasi-algebraic [20, p. 147]. We aim to describe the minimal monic invariant polynomial in terms of $\pi(t)$. By Lemma 1.3, we may consider X-outer δ . For X-outer δ , $\pi(t)$ is given as follows.

Theorem 2.1 ([4, Theorem 1] and [9, Theorem 15]). *Let δ be an X-outer quasi-algebraic q -skew σ -derivation of R . Then there exists the least integer $\nu \geq 1$ such that $q^\nu = 1$ and any minimal monic semi-invariant polynomial $\pi(t) \in Q[t; \sigma, \delta]$ is given by*

$$\pi(t) = \begin{cases} t^\nu + b & \text{if char } R = 0, \\ t^{\nu p^s} + \sum_{j=0}^{s-1} b_j t^{\nu p^j} + b & \text{if char } R = p \geq 2, \end{cases}$$

where $b \in Q$ and $b_j \in \Phi(\nu(p^s - p^j))$ for $0 \leq j \leq s - 1$.

We shall retain the notation above throughout. For brevity, we treat all characteristics simultaneously. If $\text{char } R = 0$, then all b_j are interpreted as 0. For any $u \in \Phi(\deg \pi(t))$, $\pi(t) + u$ is also semi-invariant. Clearly, all minimal monic semi-invariant polynomials of $Q[t; \sigma, \delta]$ are so obtained. Moreover, if $\sigma^{\deg \pi(t)}$ is X-outer, viz. $\Phi(\deg \pi(t)) = 0$, then $\pi(t)$ is the unique minimal monic semi-invariant polynomial of $Q[t; \sigma, \delta]$. The following is important.

Lemma 2.2. *If $0 \neq u \in \Phi(i)$, then $\nu \mid i^2$ and $\sigma(u) = q^i u$.*

Proof. Since $0 \neq u \in \Phi(i)$, we have $\sigma^i = I_u$. Since δ is q -skew,

$$\delta I_u = \delta \sigma^i = q^i \sigma^i \delta = q^i I_u \delta.$$

By Lemma 1.2, $\sigma(u) = q^i u$. Inductively, $\sigma^\ell(u) = q^{\ell i} u$ for any $\ell \geq 0$. Setting $\ell = i$, $q^{i^2} u = \sigma^i(u) = I_u(u) = u$. So $q^{i^2} = 1$ and hence $\nu \mid i^2$ by the minimality of ν . □

As a direct application, if σ is X-inner, then $q = 1$. For if $\sigma = I_v$, then $\sigma(v) = qv$ by Lemma 2.2, implying $q = 1$ since $\sigma(v) = I_v(v) = v$. To find minimal monic invariant polynomials, we need more information on $\sigma(b_j), \delta(b_j), \sigma(b)$ and $\delta(b)$.

Lemma 2.3. *For $1 \leq j < s, b_j \in Q^{(\sigma, \delta)}$. If $\nu > 1$, then $b, b_0 \in Q^{(\sigma, \delta)}$ also. If $\nu = 1$, then $\text{char } R = p \geq 2, b_0 \in Q^{(\sigma)}, \delta(b_0) = b - \sigma(b) \in \Phi(p^s)$ and $\delta(b) \in \Phi(p^s + 1)$.*

Proof. Set $n \stackrel{\text{def.}}{=} \deg \pi(t)$ for simplicity. So $n = \nu$ if $\text{char } R = 0$ and $n = \nu p^s$ if $\text{char } R = p \geq 2$. For $0 \leq j < s$, since $b_j \in \Phi(\nu(p^s - p^j))$, we have $b_j \in Q^{(\sigma)}$ by Lemma 2.2. Since the coefficient of t^{n-1} of $\pi(t)$ is zero, $[t, \pi(t)]$ is also semi-invariant by [17, Proposition 2.4] or [20, Lemma 2.5, (2)]. By the monicity of $\pi(t)$ and with $b_j \in Q^{(\sigma)}$ for $0 \leq j < s$,

$$[t, \pi(t)] = \sum_{j=0}^{s-1} \delta(b_j)t^{\nu p^j} + (\sigma(b) - b)t + \delta(b).$$

Since $\deg[t, \pi(t)] < \deg \pi(t)$, we have $[t, \pi(t)] \in \Phi(n + 1)$ by the minimality of $\pi(t)$. If $\nu > 1$, then $\delta(b_j) = 0$ for $0 \leq j < s, \sigma(b) = b$ and $\delta(b) \in \Phi(n + 1)$. Since $\nu | n, \nu \nmid (n + 1)^2$. So $\delta(b) = 0$ by Lemma 2.2. If $\nu = 1$, then $\text{char } R = p \geq 2$ and $n = p^s$ by the outeress of δ . So

$$[t, \pi(t)] = \sum_{j=1}^{s-1} \delta(b_j)t^{p^j} + (\delta(b_0) + \sigma(b) - b)t + \delta(b) \in \Phi(p^s + 1).$$

Comparing coefficients of this yields $\delta(b_j) = 0$ for $1 \leq j < s, \delta(b_0) = b - \sigma(b)$ and $\delta(b) \in \Phi(p^s + 1)$. Extend σ to an automorphism of $Q[t; \sigma, \delta]$ by setting $\sigma(t) \stackrel{\text{def.}}{=} \frac{t}{q}$. Then $\sigma(\pi(t))$ is also semi-invariant. Since $\sigma(\pi(t))$ is also monic and has degree n , the difference $\pi(t) - \sigma(\pi(t))$ is also semi-invariant. We have seen $b_j \in Q^{(\sigma)}$ for $0 \leq j < s$ by Lemma 2.2. So $\pi(t) - \sigma(\pi(t)) = b - \sigma(b) \in \Phi(p^s)$. \square

Lemma 2.4. $[t, \pi(t)^k] = k\delta(b)\pi(t)^{k-1}$ for $k \geq 1$ and $[\pi(t), \delta(b)] = 0$.

Proof. By the Leibniz rule, $[t, \pi(t)^k] = \sum_{i=0}^{k-1} \pi(t)^i [t, \pi(t)] \pi(t)^{k-i-1}$. By Lemma 2.3 (or its proof), $[t, \pi(t)] = \delta(b)$. It suffices to show $[\delta(b), \pi(t)] = 0$. If $\nu > 1$, then $\delta(b) = 0$ by Lemma 2.3 and there is nothing to prove. So assume $\nu = 1$ and $\text{char } R = p \geq 2$. By Lemma 2.3, $u \stackrel{\text{def.}}{=} b - \sigma(b) = \delta(b_0) \in \Phi(p^s)$. So $\sigma(u) = q^{p^s}u = u$ by Lemma 2.2. With this, we obtain inductively $\sigma^k(b) = b - ku$ for $k \geq 0$. In particular, $\sigma^{p^s}(b) = b - p^s u = b$. So $\delta(b) = \delta\sigma^{p^s}(b) = \sigma^{p^s}\delta(b)$. By the semi-invariance of $\pi(t)$, we have $\pi(t)\delta(b) = \sigma^{p^s}(\delta(b))\pi(t) = \delta(b)\pi(t)$, as wanted. \square

Corollary 2.5. *In the notation of Theorem 2.1, the following are equivalent: (1) $\pi(t)$ is invariant; (2) $\pi(t)t = t\pi(t)$; (3) $\delta(b) = 0$.*

Proof. (2) \Rightarrow (1) is trivial. For (1) \Rightarrow (3), let $\pi(t)$ be invariant. So $\pi(t)t = (t-c)\pi(t)$ for some $c \in Q$. Then $c\pi(t) = t\pi(t) - \pi(t)t = \delta(b)$ by Lemma 2.4. Comparing degrees gives $c = 0$ and $\delta(b) = 0$. (3) \Rightarrow (2) holds since $[t, \pi(t)] = \delta(b)$ by Lemma 2.4. \square

We are ready for our main result.

Theorem 2.6. *Let δ be X-outer. (1) If $\text{char } R = 0$ or $q \neq 1$, then $\pi(t)$ is also invariant. (2) Suppose that $\text{char } R = p \geq 2$ and $q = 1$. If $\delta(b) = \delta(c)$ for some $c \in \Phi(p^s)$, then $\pi(t) - c$ is invariant. Otherwise, $\pi(t)^p$ is a minimal monic invariant polynomial.*

Proof. If $\text{char } R = 0$ or $q \neq 1$, then $\nu > 1$ and so $\delta(b) = 0$ by Lemma 2.3. By Corollary 2.5, $\pi(t)$ is invariant. So suppose that $\text{char } R = p \geq 2$ and $q = 1$. Then $\nu = 1$ and $\deg \pi(t) = p^s$. For any $c \in \Phi(p^s)$, $\pi(t) - c$ is also monic and semi-invariant. If $\delta(b - c) = 0$, then $\pi(t) - c$ is invariant by Corollary 2.5. So we suppose that $\delta(b - c) \neq 0$ for any $c \in \Phi(p^s)$. By Lemma 2.4, $t\pi(t)^p - \pi(t)^p t = [t, \pi(t)^p] = p\delta(b)\pi(t)^{p-1} = 0$. So $\pi(t)^p$ is invariant. We show its minimality as an invariant polynomial. Let $f(t) \in Q[t; \sigma, \delta]$ be a monic invariant polynomial. Then $f(t)t = (t-c)f(t)$ for some $c \in Q$. So $cf(t) = tf(t) - f(t)t = [t, f(t)]$, implying $c = 0$, since $\deg [t, f(t)] < \deg f(t)$ by the monicity of $f(t)$. So $[t, f(t)] = 0$. By (1) of [20, Proposition 2.8], write $f(t) = \sum_{i=0}^{\ell} u_i \pi(t)^{\ell-i}$, where $u_0 \stackrel{\text{def.}}{=} 1$ and $u_i \in \Phi(ip^s)$. Since $q = 1$, $\sigma(u_i) = q^{ip^s} u_i = u_i$ by Lemma 2.2. So $[t, u_i] = \sigma(u_i)t + \delta(u_i) - u_i t = \delta(u_i)$. With this and Lemma 2.4, we compute

$$\begin{aligned} 0 &= [t, f(t)] = [t, \sum_{i=0}^{\ell} u_i \pi(t)^{\ell-i}] = \sum_{i=0}^{\ell} [t, u_i] \pi(t)^{\ell-i} + \sum_{i=0}^{\ell} u_i [t, \pi(t)^{\ell-i}] \\ &= \sum_{i=1}^{\ell} \delta(u_i) \pi(t)^{\ell-i} + \sum_{i=0}^{\ell-1} (\ell-i) u_i \delta(b) \pi(t)^{\ell-i-1} \\ &= \sum_{i=0}^{\ell-1} \delta(u_{i+1}) \pi(t)^{\ell-i-1} + \sum_{i=0}^{\ell-1} (\ell-i) u_i \delta(b) \pi(t)^{\ell-i-1} \\ &= \sum_{i=0}^{\ell-1} \left((\ell-i) u_i \delta(b) + \delta(u_{i+1}) \right) \pi(t)^{\ell-i-1}. \end{aligned}$$

In the last expression above, the term of degree $\geq (\ell - 1)p^s$ is contributed by

$$\left(\ell u_0 \delta(b) + \delta(u_1) \right) \pi(t)^{\ell-1} = \left(\ell \delta(b) + \delta(u_1) \right) \pi(t)^{\ell-1}.$$

The coefficient of $t^{p^s(\ell-1)}$ in $[t, f(t)]$ yields the equality $\ell \delta(b) + \delta(u_1) = 0$. If $p \nmid \ell$, then ℓ is a unit and $\delta(b + \frac{u_1}{\ell}) = 0$, contradicting our assumption that $\delta(b - c) \neq 0$ for any $c \in \Phi(p^s)$. So $p \mid \ell$. Then $\ell \geq p$ and $\deg f(t) = \deg \pi(t)^\ell \geq \deg \pi(t)^p$. Since $f(t)$ is arbitrary, the minimality of $\pi(t)^p$ as a monic invariant polynomial is proved. \square

The second assertion of Theorem 2.6 can be simplified if σ is also X-outer.

Theorem 2.7. *Assume that δ, σ are X-outer, $\text{char } R = p \geq 2$ and $q = 1$. Then $\pi(t)$ or $\pi(t)^p$ is a minimal monic invariant polynomial according as $\delta(b) = 0$ or $\delta(b) \neq 0$ respectively. In the former case, $\pi(t) = t^{p^s} + \sum_{j=0}^{s-1} b_j t^{p^j} + b \in Q^{(\sigma, \delta)}[t; \sigma, \delta]$. In the latter case, $\pi(t)^p = t^{p^{s+1}} + \sum_{j=0}^{s-1} b_j^p t^{p^{j+1}} + b^p \in Q^{(\sigma, \delta)}[t; \sigma, \delta]$.*

Proof. Since $q = 1$, $\delta\sigma = \sigma\delta$. So $\delta\sigma^s = \sigma^s\delta$ for any s . Given $0 \neq u \in \Phi(s)$, $I_u = \sigma^s$ and so $\delta I_u = I_u \delta$, implying $\delta(u) = 0$ by Lemma 1.2, since σ is X-outer. So $\delta(\Phi(s)) = 0$. Now, if $\delta(b) = 0$, then $\pi(t)$ is also invariant by Corollary 2.5. If

$\delta(b) \neq 0$, then $\delta(b - c) = \delta(b) \neq 0$ for any $c \in \Phi(p^s)$, since $\delta(\Phi(p^s)) = 0$. By Theorem 2.6, $\pi(t)^p$ is a minimal monic invariant polynomial.

For the rest, since σ is X-outer, we have $\delta(u) = 0$ for any $u \in \Phi(j)$ by Lemma 1.2. By Theorem 2.1, $b_0 \in \Phi(p^s - 1)$, implying $\delta(b_0) = 0$. So $b - \sigma(b) = \delta(b_0) = 0$ by Lemma 2.3. Together with Lemma 2.3, we have thus shown

$$(*) \quad b \in Q^{(\sigma)} \quad \text{and} \quad b_j \in Q^{(\sigma, \delta)} \quad \text{for } 0 \leq j < s.$$

If $\delta(b) = 0$, then $\pi(t) \in Q^{(\sigma, \delta)}[t; \sigma, \delta]$, as asserted. So suppose $\delta(b) \neq 0$. Write $\pi(t) = g(t) + b$, where $g(t) \stackrel{\text{def.}}{=} t^{p^s} + b_{s-1}t^{p^s-1} + \dots + b_0t$. By the semi-invariance of $\pi(t)$, $\pi(t)b = \sigma^{p^s}(b)\pi(t) = b\pi(t)$. So $[g(t), b] = [g(t) + b, b] = [\pi(t), b] = 0$. With this, $\pi(t)^p = (g(t) + b)^p = g(t)^p + b^p$. We show $g(t)^p = t^{p^{s+1}} + b_{s-1}^p t^{p^s} + \dots + b_0^p t^p$. It suffices to observe that all b_j commute with t and with each other. The former holds by (*). For the latter, if all positive powers of σ are X-outer, then all $b_j \in \Phi(\nu(p^s - p^j)) = 0$ and there is nothing to prove. So assume that ℓ is the least positive integer such that $\sigma^\ell = I_u$ for a unit $u \in Q$. Then for nonzero b_j , ℓ divides $\nu(p^s - p^j)$ and $b_j = \beta_j u^{\frac{\nu(p^s - p^j)}{\ell}}$ for some $\beta_j \in C$. So all b_j commute. We have thus shown

$$\pi(t)^p = t^{p^{s+1}} + b_{s-1}^p t^{p^s} + \dots + b_0^p t^p + b^p.$$

Since $\sigma(b) = b$ by (*), $[b, \Phi(j)] = 0$ for any j . By Lemma 2.3, $\delta(b) \in \Phi(p^s + 1)$. So $[b, \delta(b)] = 0$. With this, $\delta(b^p) = pb^{p-1}\delta(b) = 0$. So $\pi(t)^p \in Q^{(\sigma, \delta)}[t; \sigma, \delta]$. \square

The case that σ is X-inner can be reduced to ordinary derivations as follows. Let $u \in Q$ be a unit such that $\sigma = I_u$. The map $d: x \in R \mapsto u^{-1}\delta(x)$ defines a derivation of Q . Form the Ore extension $Q[\tilde{t}; d]$. The map $t \in Q[t; \sigma, \delta] \mapsto u^{-1}\tilde{t} \in Q[\tilde{t}; d]$ induces a ring isomorphism $Q[t; \sigma, \delta] \cong Q[\tilde{t}; d]$ fixing all $r \in R$. Under this automorphism, (semi-)invariant polynomials of $Q[t; \sigma, \delta]$ and of $Q[\tilde{t}; d]$ correspond bijectively. So it suffices to consider the case when δ is an ordinary derivation. This is a special instance of Theorem 2.6. We quote it below for easy reference.

Theorem 2.8 ([21, 6]). *Assume that $\text{char } R = p \geq 2$ and δ is an ordinary derivation. If $\delta(b) = \delta(\gamma)$ for some $\gamma \in C$, then $\pi(t) - \gamma$ is a minimal monic invariant polynomial. Otherwise, $\pi(t)^p$ is a minimal monic invariant polynomial.*

If R is a finite-dimensional central division algebra, Jacobson ([13, Lemma 1.5.3]) proved that there must exist $\gamma \in C$ such that $\pi(t) - \gamma$ is the minimal invariant polynomial. This was generalized to prime GPI-rings in [7, Lemma 2.5].

3. AN APPLICATION

For an invariant polynomial $f(t) \in Q[t; \sigma, \delta]$, $Q[t; \sigma, \delta]f(t) = f(t)Q[t; \sigma, \delta]$ ([20, Proposition 2.1]). We recall

Lemma 3.1 ([20, Proposition 2.1]). *For any ideal $\mathcal{I} \neq 0$ of $R[t; \sigma, \delta]$, there exists a unique monic invariant polynomial $f(t)$, called the invariant generator of \mathcal{I} , such that $If(t) \subseteq \mathcal{I} \subseteq R[t; \sigma, \delta] \cap Q[t; \sigma, \delta]f(t)$ for some ideal $I \neq 0$ of R .*

Definition ([12]). An ideal \mathcal{I} of $R[t; \sigma, \delta]$ is called R -disjoint if $\mathcal{I} \cap R = 0$. Given a monic invariant polynomial $f(t) \in Q[t; \sigma, \delta]$, define $\langle f(t) \rangle \stackrel{\text{def.}}{=} R[t; \sigma, \delta] \cap Q[t; \sigma, \delta]f(t)$, called the principal ideal generated by $f(t)$. We call an invariant polynomial $f(t)$ *irreducible* if it is nonconstant and it is *not* a product of two nonconstant invariant polynomials.

An ideal of $R[t; \sigma, \delta]$ is R -disjoint if and only if its invariant generator is not 1. By definition, $\langle f(t) \rangle$ is maximal among ideals with the invariant generator $f(t)$. We are interested in R -disjoint prime ideals of $R[t; \sigma, \delta]$. It is not hard to see that $\langle p(t) \rangle$ is prime for any irreducible invariant $p(t)$. Our aim here is the following converse.

Theorem 3.2. *Let δ be an X -outer σ -derivation. Unless $\text{char } R = p \geq 2$ and σ is X -inner (necessarily $q = 1$), any R -disjoint prime ideal of $R[t; \sigma, \delta]$ is of the form $\langle p(t) \rangle$ for an irreducible monic invariant polynomial $p(t)$.*

The above says that R -disjoint prime ideals of $R[t; \sigma, \delta]$ are maximal. This problem has been considered for Ore extensions of derivation type in [2, 11, 23] and of automorphism type in [3, 10]. Leroy and Matczuk [19] proved the same result under the assumption $\sigma\delta = \delta\sigma$ plus some mild conditions. We need the following generalization of [19, Lemma 1.8].

Theorem 3.3. *Assume that δ is X -outer. Unless $\text{char } R = p \geq 2$ and σ is X -inner (necessarily $q = 1$), monic invariant polynomials have all their coefficients in $Q^{(\sigma, \delta)}$ and hence commute with t .*

Proof. Let

$$M(t) \stackrel{\text{def.}}{=} \begin{cases} \pi(t) & \text{if } \text{char } R = 0 \text{ or } q \neq 1; \\ \pi(t) & \text{if } \text{char } R = p \geq 2, q = 1 \text{ and } \sigma \text{ is } X\text{-outer with } \delta(b) = 0; \\ \pi(t)^p & \text{if } \text{char } R = p \geq 2, q = 1 \text{ and } \sigma \text{ is } X\text{-outer with } \delta(b) \neq 0. \end{cases}$$

By Theorems 2.6 and 2.7, $M(t)$ is a minimal monic invariant polynomial. If $\text{char } R = 0$ or $q \neq 1$, then $M(t) = \pi(t) \in Q^{(\sigma, \delta)}[t; \sigma, \delta]$ by Lemma 2.3. If $\text{char } R = p \geq 2$, $q = 1$ and σ is X -outer, then $M(t) \in Q^{(\sigma, \delta)}[t; \sigma, \delta]$ by Theorem 2.7. So $M(t) \in Q^{(\sigma, \delta)}[t; \sigma, \delta]$ always. By [20, Proposition 3.4], any monic invariant polynomial can be written in the form $u\omega(t)M(t)^l$, where $l \geq 0$ is an integer, $u \in Q$ is a unit and $\omega(t)$ is a nonzero central polynomial. By (iii) of [20, Theorem 3.7], there exist an integer $\ell > 0$ and a unit $v \in Q$ such that $\zeta \stackrel{\text{def.}}{=} vM(t)^\ell$ is a nonzero central polynomial of minimal degree and the central polynomial $\omega(t)$ can be written in the form

$$\omega(t) = \alpha_n \zeta^n + \alpha_{n-1} \zeta^{n-1} + \dots$$

with $\alpha_i \in C^{(\sigma, \delta)}$. Since $[M(t), t] = 0$, we have $0 = [\zeta, t] = [v, t]M(t)^\ell$, implying $0 = [v, t] = (v - \sigma(v))t - \delta(v)$. So $\sigma(v) = v$ and $\delta(v) = 0$, that is, $v \in Q^{(\sigma, \delta)}$. So $\zeta \in Q^{(\sigma, \delta)}[t; \sigma, \delta]$ and $\omega(t) \in Q^{(\sigma, \delta)}[t; \sigma, \delta]$. Since $u\omega(t)M(t)^l$ and $M(t)^l$ are monic, so is $u\omega(t)$. Hence u is the inverse of the leading coefficient of $\omega(t)$, implying $u \in Q^{(\sigma, \delta)}$. Whence $u\omega(t)M(t)^l \in Q^{(\sigma, \delta)}[t; \sigma, \delta]$, as asserted. \square

We are now ready for

Proof of Theorem 3.2. Let \mathfrak{S} be the set of ideals I of R such that $\sigma(I) \subseteq I$ and $\delta(I) \subseteq I$. For $I \in \mathfrak{S}$, $R[t; \sigma, \delta]I \subseteq I[t; \sigma, \delta]$, where $I[t; \sigma, \delta]$ is the set of polynomials $\sum_i a_i t^i$ with $a_i \in I$. If $I, J \in \mathfrak{S}$, then $IJ \in \mathfrak{S}$. Define

$$Q_0 \stackrel{\text{def.}}{=} \{a \in Q \mid aI \subseteq R \text{ for some } 0 \neq I \in \mathfrak{S}\}.$$

Then Q_0 forms a subring of Q . Given $a \in Q^{(\sigma, \delta)}$ arbitrarily, let $I \neq 0$ be an ideal of R such that $aI \subseteq R$. Set $J \stackrel{\text{def.}}{=} I + \sum_{\theta} \theta(I)$, where the summation ranges over all products θ of σ and δ . Clearly, $0 \neq J \in \mathfrak{S}$ and $aJ \subseteq R$, implying $a \in Q_0$. So

$Q_0 \supseteq Q^{(\sigma, \delta)}$. Clearly, $Q_0 \supseteq R$. Given an R -disjoint prime ideal \mathcal{P} of $R[t; \sigma, \delta]$, let $p(t)$ be its monic invariant generator. Given $f(t) \in \langle p(t) \rangle$, write $f(t) = g(t)p(t)$, where $g(t) \in Q[t; \sigma, \delta]$. By Theorem 3.3, $p(t) \in Q^{(\sigma, \delta)}[t; \sigma, \delta] \subseteq Q_0[t; \sigma, \delta]$. With the left division algorithm in $Q_0[t; \sigma, \delta]$, we see $g(t) \in Q_0[t; \sigma, \delta]$. Let $0 \neq I \in \mathfrak{S}$ be such that $g(t)I \subseteq R[t; \sigma, \delta]$. Let J be a nonzero ideal of R such that $p(t)J \subseteq \mathcal{P}$. Since $[p(t), t] = 0$, $p(t)R[t; \sigma, \delta] = R[t; \sigma, \delta]p(t)$. With this, we compute

$$\begin{aligned} f(t)R[t; \sigma, \delta]IJ &= g(t)p(t)R[t; \sigma, \delta]IJ \\ &= g(t)R[t; \sigma, \delta]p(t)IJ = g(t)R[t; \sigma, \delta]\sigma^{\deg p}(I)p(t)J \\ &\subseteq g(t)R[t; \sigma, \delta]IP \subseteq g(t)I[t; \sigma, \delta]\mathcal{P} \subseteq R[t; \sigma, \delta]\mathcal{P} \subseteq \mathcal{P}. \end{aligned}$$

Since \mathcal{P} is R -disjoint, we have $IJ \not\subseteq \mathcal{P}$. The primeness of \mathcal{P} implies $f(t) \in \mathcal{P}$. But $f(t) \in \langle p(t) \rangle$ is arbitrary. This proves $\mathcal{P} = \langle p(t) \rangle$. For the irreducibility of $p(t)$, suppose that $p(t) = g(t)h(t)$, where $g(t)$ and $h(t)$ are monic invariant. Pick a nonzero ideal I of R such that $Ig(t) \cup Ih(t) \subseteq R[t; \sigma, \delta]$. Then $Ig(t)R[t; \sigma, \delta]Ih(t) = IR[t; \sigma, \delta]I^{\deg g(t)}g(t)h(t) \subseteq \langle p(t) \rangle$, implying $Ig(t) \subseteq \langle p(t) \rangle$ or $Ih(t) \subseteq \langle p(t) \rangle$. That is, $g(t) = 1$ or $h(t) = 1$. So $p(t)$ is irreducible. \square

In the case $\text{char } R = p \geq 2$, our δ and σ above are both X-outer. The problem remains open if one of δ, σ is X-inner, as was raised in [19].

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DEPARTMENT OF MATHEMATICS, NATIONAL TAIWAN UNIVERSITY, TAIPEI 106, TAIWAN
E-mail address: `chuang@math.ntu.edu.tw`

DEPARTMENT OF MATHEMATICS, NATIONAL TAIWAN UNIVERSITY, TAIPEI 106, TAIWAN
E-mail address: `tklee@math.ntu.edu.tw`

DEPARTMENT OF MATHEMATICS, NATIONAL CHANGHUA UNIVERSITY OF EDUCATION, CHANGHUA
500, TAIWAN
E-mail address: `ckliu@cc.ncue.edu.tw`