

## MAXIMIZATION OF THE SECOND CONFORMAL EIGENVALUE OF SPHERES

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ABSTRACT. In this paper we establish an upper bound on the second eigenvalue of  $n$ -dimensional spheres in the conformal class of the round sphere. This upper bound holds in all dimensions and is asymptotically sharp as the dimension increases.

Given  $(M, g)$  a smooth compact Riemannian manifold (without boundary), the spectrum of the Laplacian  $\Delta_g = -\operatorname{div}_g(\nabla)$  is a discrete sequence of eigenvalues

$$0 = \lambda_0(M, g) < \lambda_1(M, g) \leq \lambda_2(M, g) \leq \cdots \leq \lambda_k(M, g) \leq \cdots$$

which goes to  $+\infty$  as  $k \rightarrow +\infty$ . The eigenfunctions associated to the simple eigenvalue  $\lambda_0 = 0$  are the constant functions. A natural, and often addressed, question is how to get estimates on the eigenvalues thanks to some geometric assumptions. In this paper, we discuss the maximization of eigenvalues for metrics in a given conformal class with fixed volume. We focus on the case of the standard sphere.

We let  $\mathbf{S}^n$  be the unit sphere of  $\mathbf{R}^{n+1}$  for  $n \geq 2$ . If  $g$  is a metric on  $\mathbf{S}^n$ , we are interested in the scale invariant quantity

$$\Lambda_{n,k}(g) = \lambda_k(\mathbf{S}^n, g) \operatorname{Vol}_g(\mathbf{S}^n)^{\frac{2}{n}}.$$

In dimension 2, we can maximize  $\Lambda_{2,k}$  on regular metrics. An inequality has been proved for  $k = 1$  by Hersch [6]:

$$\Lambda_{2,1}(g) \leq 8\pi,$$

with equality iff  $g$  is the round metric. He followed the proof of the maximization by Szegő [9] of the first non-zero Neumann eigenvalue for planar domains, attained by discs. Nadirashvili found an optimal maximization for  $k = 2$ . He proved in [8] that

$$\Lambda_{2,2}(g) < 16\pi,$$

where the supremum is attained in the degenerate case of the union of two identical spheres. His idea was used later in [5] to show that among simply connected planar domains, the second non-zero Neumann eigenvalue is maximal in the degenerate case of two discs of the same area.

If we look for an analogous inequality in dimension  $n \geq 3$ , we have to restrict our attention to some classes of metrics since  $\Lambda_{n,k}$  is not bounded on the set of regular metrics (see [2]). It is natural, as suggested in [4] and [3], to consider the set of

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metrics in some conformal class. Indeed, in any given conformal class,  $\Lambda_{n,k}(g)$  admits some upper bound (see [7]). Thus we define the conformal spectrum of  $(\mathbf{S}^n, [g_0])$ , where  $[g_0]$  is the class of metrics conformal to the round metric  $g_0$ , by

$$\lambda_k^c(\mathbf{S}^n, [g_0]) = \sup_{g \in [g_0]} \Lambda_{n,k}(g).$$

The theorem of Hersch was generalized in this framework in [4]. We have that

$$\lambda_1^c(\mathbf{S}^n, [g_0]) = n\sigma_n^{\frac{2}{n}},$$

where  $\sigma_n$  is the volume of the unit  $n$ -dimensional sphere. We know almost nothing about  $\lambda_k^c(\mathbf{S}^n, [g_0])$  for  $k \geq 2$ . A lower bound was obtained by a method of conformal surgery in [3]. For all  $k$ , we have that

$$\lambda_k^c(\mathbf{S}^n, [g_0]) \geq n(k\sigma_n)^{\frac{2}{n}}.$$

Nadirashvili, Girouard and Polterovich conjectured in [5] that this inequality is an equality in all dimensions for  $k = 2$ , where the supremum is attained for the union of two identical spheres:

**Conjecture** ([5]). *For any metric  $g \in [g_0]$ ,*

$$\lambda_2(\mathbf{S}^n, g) \text{Vol}_g(\mathbf{S}^n)^{\frac{2}{n}} < n(2\sigma_n)^{\frac{2}{n}}.$$

Towards this conjecture, the following theorem gives an “asymptotically sharp” upper bound:

**Theorem.** *Let  $n \geq 2$  and  $g \in [g_0]$  be a metric on  $S^n$  conformal to the round metric. Then*

$$\lambda_2(\mathbf{S}^n, g) \text{Vol}_g(\mathbf{S}^n)^{\frac{2}{n}} < K_n n(2\sigma_n)^{\frac{2}{n}},$$

where  $K_n$  is a constant independant of  $g \in [g_0]$  given by

$$K_n = \frac{n+1}{n} \left( \frac{\Gamma(n)\Gamma(\frac{n+1}{2})}{\Gamma(n+\frac{1}{2})\Gamma(\frac{n}{2})} \right)^{\frac{2}{n}}.$$

Note that  $K_2 = 1$ , that  $1 < K_n \leq 1.04$  for all  $n \geq 3$  and that  $\lim_{n \rightarrow \infty} K_n = 1$ . The Theorem is sharp in dimension 2 and was in fact already proved by Nadirashvili in [8]. In [5], Girouard, Nadirashvili and Polterovich established this inequality in odd dimensions.

In this paper we prove this theorem in all dimensions, unifying the previous proofs in dimension  $n = 2$  and in odd dimensions and along the way extending it. The starting point of the proof is a construction, described in section 1 below, initiated by Nadirashvili [8] and used by Girouard, Nadirashvili and Polterovich [5] in odd dimension. However, our use of this construction differs from that of these two papers: we use the min-max characterization of the second eigenvalue up to the end of the proof (see section 3), capitalizing on a new topological fact proved in section 2.

## 1. CONSTRUCTION OF TEST FUNCTIONS

In this section, we describe the construction of Nadirashvili [8] (see also [5]), which is at the basis of our theorem as well as of the previous results. Let  $g$  be a metric on  $\mathbf{S}^n$  conformal to  $g_0$  of volume 1. We denote by  $dv_g$  the measure

associated to  $g$ . In this paper we shall use the min-max characterization of the second eigenvalue of the Laplacian, which tells us in particular that

$$(1) \quad \lambda_2(\mathbf{S}^n, g) \leq \sup_{u \in E \setminus \{0\}} \frac{\int_{\mathbf{S}^n} |\nabla_g u|_g^2 dv_g}{\int_{\mathbf{S}^n} u^2 dv_g}$$

for all 2-dimensional subspaces  $E$  of functions in  $H^1(\mathbf{S}^n)$  with mean value 0. The aim is to find a suitable space  $E$  of test functions such that (1) gives the estimate of the Theorem.

On  $(\mathbf{S}^n, g_0)$ , the eigenspace associated to  $\lambda_1(\mathbf{S}^n, g_0)$  has dimension  $n+1$ : it is the set of linear forms of  $\mathbf{R}^{n+1}$  written  $X_s = (s, \cdot)$  for  $s \in \mathbf{R}^{n+1}$ . We will build  $E$  with these functions, and as Hersch did for  $\lambda_1(\mathbf{S}^n, g)$ , we proceed to a renormalization of measures in order to keep the orthogonality to constants. For  $\xi \in \mathbf{B}^{n+1}$ , we let  $d_\xi : \overline{\mathbf{B}^{n+1}} \rightarrow \overline{\mathbf{B}^{n+1}}$  be defined by

$$d_\xi(x) = \frac{(1 - |\xi|^2)x + (1 + 2\xi \cdot x + |x|^2)\xi}{1 + 2\xi \cdot x + |x|^2 |\xi|^2},$$

which is a conformal transformation when restricted to the unit sphere.

We say that  $d_\xi$  renormalizes a finite measure  $d\nu$  on the  $n$ -sphere if

$$\forall s \in \mathbf{S}^n, \quad \int_{\mathbf{S}^n} X_s \circ d_\xi d\nu = 0.$$

The Hersch lemma says that for all finite measures  $d\nu$ , such a  $\xi$  exists. Moreover, it is unique and depends continuously on  $d\nu$  (the set of finite measures is considered as the topological dual of the continuous bounded functions) as proved in [5], Proposition 4.1.5. We call  $\xi$  the renormalization point of  $d\nu$ .

We also define families of measures parametrized by the set of caps of  $\mathbf{S}^n$ , denoted by  $\mathcal{C}$ :

$$a_{0,p} = \{x \in \mathbf{S}^n; x \cdot p > 0\}, \quad a_{r,p} = d_{rp}(a_{0,p}), \quad (r, p) \in (-1, 1) \times \mathbf{S}^n.$$

We denote by  $d\mu_a$  the ‘‘lift’’ of the measure  $dv_g$  by the cap  $a \in \mathcal{C}$ :

$$d\mu_a = \begin{cases} dv_g + (\tau_a)^* dv_g & \text{on } a, \\ 0 & \text{on } a^*, \end{cases}$$

where  $a^* = \mathbf{S}^n \setminus \bar{a}$  and  $\tau_a$  is the conformal reflection with respect to the boundary circle of  $a$ . That is,

$$\tau_{a_{r,p}} = d_{rp} \circ R_p \circ d_{-rp},$$

where

$$R_p(x) = x - 2(p, x)p$$

is the reflection of  $\mathbf{R}^{n+1}$  with respect to the hyperplane orthogonal to  $p$ . Let  $\xi(a)$  be the renormalization point of  $d\mu_a$ . We set  $d\nu_a = (d_{\xi(a)})_* d\mu_a$ . Thanks to this family of measures, we can define a new family of test functions orthogonal to the constants:

$$u_a^s = \begin{cases} X_s \circ d_{\xi(a)} & \text{on } a, \\ X_s \circ d_{\xi(a)} \circ \tau_a & \text{on } a^*. \end{cases}$$

By a Hölder inequality, the numerator of the Rayleigh quotient is less than a conformal invariant:

$$\begin{aligned}
 \int_{\mathbf{S}^n} |\nabla_g u_a^s|_g^2 dv_g &< \left( \int_{\mathbf{S}^n} |\nabla_g u_a^s|_g^n dv_g \right)^{\frac{2}{n}} \\
 (2) \qquad \qquad \qquad &= \left( 2 \int_{d_{\xi(a)}(a)} |\nabla_g X_s|_g^n dv_g \right)^{\frac{2}{n}} \\
 &< \left( 2 \int_{\mathbf{S}^n} |\nabla_{g_0} X_s|_{g_0}^n dv_{g_0} \right)^{\frac{2}{n}}.
 \end{aligned}$$

Let us define the multiplicity of a finite measure:

**Definition.** The multiplicity of a finite measure  $d\nu$  on  $\mathbf{S}^n$  is the dimension of the eigenspace  $W$  associated to the maximal eigenvalue of the quadratic form:

$$Q(s) = \int_{\mathbf{S}^n} X_s^2 d\nu.$$

We say that  $d\nu$  is multiple if its multiplicity is greater than or equal to 2. Otherwise, we say that  $d\nu$  is simple.

As was noticed in [5], we know that if  $dv_g$  is multiple, then we can choose  $E = \{X_s; s \in W\}$  in (1) to get that  $\lambda_2(\mathbf{S}^n, g) \leq n(2\sigma_n)^{\frac{2}{n}}$ . We also know that if there is a cap  $a \in \mathcal{C}$  such that  $dv_a$  is multiple, then  $\lambda_2(\mathbf{S}^n, g) < K_n n(2\sigma_n)^{\frac{2}{n}}$  using the space of test functions  $E = \{u_a^s; s \in W\}$  in (1). In this case, the Theorem would be proved. In [5], it was proved that there necessarily exists such a multiple measure in odd dimensions (see below).

Let us now assume that all measures  $dv_g$  and  $dv_a$ , for  $a \in \mathcal{C}$ , are simple. Up to a renormalization and a rotation, we may assume that

$$\forall t \in \mathbf{S}^n, \int_{\mathbf{S}^n} X_t dv_g = 0$$

and that

$$\forall t \in \mathbf{S}^n \setminus [e_1], \int_{\mathbf{S}^n} X_t^2 dv_g < \int_{\mathbf{S}^n} X_{e_1}^2 dv_g.$$

We denote by  $[s(a)]$  the unique direction of maximization of the quadratic form associated to  $dv_a$ . With the parametrization  $(r, p) \in (-1, 1) \times \mathbf{S}^n$  of  $\mathcal{C}$ , the maps  $\xi : \mathcal{C} \rightarrow \mathbf{B}^{n+1}$  and  $[s] : \mathcal{C} \rightarrow \mathbf{R}P^n$  are continuous. Moreover, one may prove that if  $r \rightarrow -1$ , that is,  $a \rightarrow \mathbf{S}^n$ , we have:

$$(3) \qquad \lim_{a \rightarrow \mathbf{S}^n} \xi(a) = 0, \qquad \lim_{a \rightarrow \mathbf{S}^n} [s(a)] = [e_1].$$

2. PROPERTIES OF THE LIFT OF THE MAXIMAL DIRECTION

Let us study the maps  $\xi$  and  $[s]$  in light of the links between a cap  $a \in \mathcal{C}$  and its symmetrical cap  $a^* = \mathbf{S}^n \setminus \bar{a}$ . With the parameter  $(r, p) \in (-1, 1) \times \mathbf{S}^n$ , notice that  $a_{r,p}^* = a_{-r,-p}$ .

*Claim 1.* For  $a \in \mathcal{C}$ , we write  $\xi^* = \xi(a^*)$ ,  $[s^*] = [s(a^*)]$ . Then

$$-\xi^* = \tau_a(-\xi) \qquad \text{and} \qquad [s^*] = R_a[s],$$

where  $R_a = d_{\xi^*(a)} \circ \tau_a \circ d_{-\xi(a)}$  is an orthogonal map.

*Proof.* We set  $\eta = -\tau_a(-\xi)$ . Let  $t \in \mathbf{S}^n$ ; then

$$\int_{\mathbf{S}^n} X_t \circ d_\eta d\mu_{a^*} = \int_{\mathbf{S}^n} X_t \circ d_\eta \circ \tau_a d\mu_a.$$

One can check that  $d\mu_{a^*} = (\tau_a)^* d\mu_a$ . The map  $R_a = d_\eta \circ \tau_a \circ d_{-\xi(a)}$  is orthogonal because it is a Möbius transformation of the unit ball preserving the origin ([1], Theorem 3.4.1). Thus we have that

$$\int_{\mathbf{S}^n} X_t \circ d_\eta d\mu_{a^*} = \int_{\mathbf{S}^n} X_t \circ R_a \circ d_\xi d\mu_a = \int_{\mathbf{S}^n} X_{R_a^{-1}(t)} \circ d_\xi d\mu_a = 0.$$

This is true for all  $t \in \mathbf{S}^n$ , and uniqueness of the renormalization point ensures that  $\xi^* = \eta$ .

The same argument with the function  $(X_t \circ d_{\xi^*})^2$  leads to

$$\forall t \in \mathbf{S}^n, \int_{\mathbf{S}^n} (X_t \circ d_{\xi^*})^2 d\mu_{a^*} = \int_{\mathbf{S}^n} (X_{R_a^{-1}(t)} \circ d_\xi)^2 d\mu_a,$$

and once again we can conclude by uniqueness of the maximal direction that  $[s^*] = R_a[s]$ . □

*Remark.* Thanks to Claim 1, we can prove the Theorem in odd dimensions. Indeed, when  $r \rightarrow 1$ , that is,  $a \rightarrow \{p\}$ , we use (3) in order to obtain:

$$\lim_{a \rightarrow \{p\}} R_a = R_p.$$

Then,  $[s(a)] = R_a^{-1}[s^*(a)] \rightarrow R_p[e_1]$  when  $a \rightarrow \{p\}$  by (3). Therefore, following [5] in odd dimensions, the map  $[s] : [-1, 1] \times \mathbf{S}^n \rightarrow \mathbf{R}P^n$  defines a homotopy between the constant map  $[e_1]$  of degree 0 and  $\phi(p) = R_p[e_1]$  of degree 4. Thus, there is a contradiction and there exists a multiple measure among  $dv_g$  and  $dv_a$  for  $a \in \mathcal{C}$ .

We do not prove that the assumption that all measures are simple leads to a contradiction. Indeed, it is not clear that in even dimensions such a configuration cannot happen. Instead, we look for suitable test functions as in Nadirashvili’s proof in dimension 2 [8]. However, inspired by the method of [5], we use a topological argument to get symmetric properties of the lifts of the maximal directions.

The continuous map  $[s] : [-1, 1] \times \mathbf{S}^n \rightarrow \mathbf{R}P^n$  has exactly two continuous lifts because the set  $[-1, 1] \times \mathbf{S}^n$  is simply connected. We denote by  $s$  the continuous lift such that  $s(-1, \cdot) = -e_1$ ; the other continuous lift is  $-s$ . Thanks to Claim 1,

$$s(-r, -p) = \epsilon(r, p)R_{a_{r,p}}s(r, p),$$

where  $\epsilon : [-1, 1] \times \mathbf{S}^n \rightarrow \{\pm 1\}$  is a continuous map. Since  $s \neq 0$  and  $[-1, 1] \times \mathbf{S}^n$  is connected,  $\epsilon$  is a constant map.

*Claim 2.* We have that  $\epsilon = -1$ . In other words,

$$s(a^*) = -R_a s(a)$$

for all caps  $a$ .

*Proof.* We assume by contradiction that  $\epsilon = 1$ . We set  $f(p) = s(0, p)$  for  $p \in \mathbf{S}^n$ . This function  $f$  is continuous on the sphere and satisfies

$$(4) \quad \forall p \in \mathbf{S}^n, f(-p) = R_p f(p).$$

Indeed,  $R_{a_0,p} = R_p$  because  $\tau_{a_0,p} = R_p$ . Using Claim 3 below, we know that such a map  $f$  cannot have degree 0. However, the map  $s : [-1, 0] \times \mathbf{S}^n \rightarrow \mathbf{S}^n$  defines a homotopy between  $s_0 = f$  and  $s_{-1} = -e_1$  of degree zero. Thus, there is a contradiction.  $\square$

We use the following topology result:

*Claim 3.* Let  $f : \mathbf{S}^n \rightarrow \mathbf{S}^n$  be a continuous map which satisfies (4). Then, if  $n$  is odd,  $\deg(f) = 1$ , and if  $n$  is even,  $\deg(f) \in 2\mathbf{Z} + 1$ .

*Proof.* We first prove the claim for smooth functions which have a property of transversality (Step 1) and we show that this case is generic (Step 2).

*Step 1.* Let  $f : \mathbf{S}^n \rightarrow \mathbf{S}^n$  be a smooth function which satisfies (4). Let us assume that for all fix points  $x \in \mathbf{S}^n$  of  $f$ ,  $T_x f - I : T_x \mathbf{S}^n \rightarrow T_x \mathbf{S}^n$  is an isomorphism. Then, if  $n$  is odd,  $\deg(f) = 1$ , and if  $n$  is even,  $\deg(f) \in 2\mathbf{Z} + 1$ .

*Proof of Step 1.* Let  $F$  be defined by

$$F : \mathbf{S}^n \times [-1, 1] \longrightarrow \mathbf{R}^{n+1},$$

$$(x, t) \longmapsto \frac{1}{2}(f(x) - x + t(f(x) + x)).$$

We notice that if  $F$  never vanishes,  $\frac{F}{|F|}$  defines a homotopy between  $f$  and  $\sigma$ , the antipodal map and  $\deg(f) = \deg(\sigma) = (-1)^{n+1}$ .

Now,  $F(x, t) = 0$  if and only if  $t = 0$  and  $x$  is a fix point of  $f$ , and then

$$\forall (v, t) \in T_x \mathbf{S}^n \times \mathbf{R}, DF(x, 0)(v, t) = \frac{1}{2}(T_x f - I)v + xt.$$

Thus,  $DF(x, 0)$  is an isomorphism, and 0 is a regular value. We write  $(x_1, 0), \dots, (x_r, 0)$  as the regular points of  $F^{-1}(0)$ . Let's approximate  $F$  by its differential in the neighborhood of its zeros. Let  $\alpha > 0$ , and set for  $1 \leq i \leq r$ ,  $\phi_i : B_{x_i}(\alpha) \rightarrow B_0(\alpha) \subset T_{x_i} \mathbf{S}^n$  the exponential chart at  $x_i$ . We obtain for  $(x, t) \in B_{x_i}(\alpha) \times (-\alpha, \alpha)$ :

$$F(x, t) = DF(x_i, 0)(\phi_i(x), t) + R_i(\phi_i(x), t),$$

where  $\frac{R_i(v,t)}{|(v,t)|} \rightarrow 0$  when  $(v, t) \rightarrow 0$ . We write for  $x \in \mathbf{S}^n$  that

$$F_t(x) = F(x, t), \quad L_t(x) = \begin{cases} DF(x_i, 0)(\phi_i(x), t) & \text{if } (x, t) \in B_{x_i}(\alpha) \times (-\alpha, \alpha), \\ 0 & \text{otherwise.} \end{cases}$$

We define a cut-off function  $0 \leq \psi \leq 1$  such that  $\psi = 1$  on  $K_1 = \bigcup_{i=1}^r \overline{B_{x_i}(\frac{\alpha}{2})}$  and  $\psi = 0$  on  $K_2 = \mathbf{S}^n \setminus \bigcup_{i=1}^r B_{x_i}(\alpha)$ . We set for  $s \in [0, 1]$ ,

$$G_s^t = \frac{s\psi L_t + (1 - s\psi)F_t}{|s\psi L_t + (1 - s\psi)F_t|}.$$

One may choose  $\alpha > 0$  small enough so that  $G_s^t$  is well defined for all  $t \in (-\alpha, \alpha) \setminus \{0\}$ . Then, for  $0 < t < \alpha$ ,  $G_1^t$  is homotopic to  $G_0^t = \frac{F_t}{|F_t|}$ , and so to  $f$ , and  $G_1^{-t}$  is homotopic to  $\sigma$ . We now write, for  $t \in (-\alpha, \alpha)$ ,  $g_t = G_1^t$ .

Let us look at the behaviour of  $g_t = \frac{L_t}{|L_t|}$  in the balls  $\overline{B_{x_i}(\frac{\alpha}{2})}$  when  $t \rightarrow 0$ . We recall that

$$L_t(x) = \frac{1}{2}(T_{x_i} f - I)\phi_i(x) + x_i t.$$

Therefore, the image  $I_{x_i}^t = g_t(\overline{B_{x_i}(\frac{\alpha}{2})})$  blows up to the half-sphere  $D_{x_i} = \{x \in \mathbf{S}^n; \langle x, x_i \rangle > 0\}$  when  $t \rightarrow 0$ .

Thanks to (4),  $x$  is a fix point of  $f$  if and only if  $-x$  is a fix point also. Moreover, by differentiating (4) at a fix point  $x$ , we obtain  $T_{-x}f - I = -(T_x f - I)$ .

Let's renumber the fixed points  $x_1, \dots, x_k, -x_1, \dots, -x_k$  (with  $r = 2k$ ), so that  $x_1, \dots, x_k$  are in a same half-sphere  $D_p = \{(x, p) > 0\}$ . We choose  $\epsilon < \alpha$  small enough so that  $\bigcap_{i=1}^k I_{x_i}^\epsilon$  has a non-empty interior  $I$ . Then, for  $z \in I$ , there is a unique point in  $g_t^{-1}(z) \cap B_{x_i}(\frac{\alpha}{2})$  for all  $0 < t < \epsilon$ . Since  $g_\epsilon(x) = g_{-\epsilon}(-x)$ , if  $z \in I$ , then  $z \in I_{-x_i}^{-\epsilon}$  and  $z \notin I_{-x_i}^\epsilon \cup I_{x_i}^{-\epsilon}$ .

For  $1 \leq i \leq k$ , let  $\{a_i\} = B_{x_i}(\frac{\alpha}{2}) \cap g_\epsilon^{-1}(z)$ . Then by the definition of degree and homotopy,

$$\deg(f) - \deg(\sigma) = \deg(g_\epsilon) - \deg(g_{-\epsilon}) = \sum_{i=1}^k \text{ind}_{a_i}(g_\epsilon) - \text{ind}_{-a_i}(g_{-\epsilon}) = \sum_{i=1}^k (1 - (-1)^{n+1})\nu_i,$$

where  $\nu_i = \text{ind}_{a_i}(g_\epsilon) \in \pm 1$ . In odd dimensions,  $\deg(f) = \deg(\sigma) = 1$ , and in even dimensions,  $\deg(f) \in 2\mathbf{Z} + 1$ . This ends the proof of Step 1.

*Step 2.* Let  $f : \mathbf{S}^n \rightarrow \mathbf{S}^n$  be a continuous map which satisfies (4). Then there exists a map, homotopic to  $f$ , which satisfies the assumptions of Step 1.

*Proof of Step 2.* Denote by  $(e_0, e_1, \dots, e_n)$  the canonical basis of  $\mathbf{R}^{n+1}$  and  $B_k^\alpha \subset D_{e_k} = \{(x, e_k) > 0\}$  the ball centered at  $e_k$  such that  $d(B_k^\alpha, D_{-e_k}) = \alpha > 0$ . Choose  $\alpha$  small enough so that

$$\bigcup_{i=0}^n B_i^{2\alpha} \cup (-B_i^{2\alpha}) = \mathbf{S}^n.$$

Let  $\epsilon > 0$ . We build by induction maps  $g_k : \mathbf{S}^n \rightarrow \mathbf{S}^n$  such that  $g_0 = f$  and, for  $0 \leq k \leq n$ ,

- $g_{k+1} = g_k$  on  $\mathbf{S}^n \setminus (B_k^\alpha \cup (-B_k^\alpha))$ ,
- $g_{k+1}$  is smooth on  $\bigcup_{i=0}^k B_i^{2\alpha} \cup (-B_i^{2\alpha})$ ,
- $\|g_{k+1} - g_k\|_{C^0} < \epsilon$ ,
- $g_{k+1}$  satisfies (4).

By density of smooth maps  $\mathbf{S}^n \rightarrow \mathbf{R}^{n+1}$ , choose  $h_k$  such that  $\|h_k - g_k\|_{C^0} < \epsilon$ . Let  $0 \leq \phi \leq 1$  be a smooth cut-off function such that  $\phi = 1$  on  $B_i^{2\alpha}$  and  $\phi = 0$  on  $\mathbf{S}^n \setminus B_i^\alpha$ . We let  $g_{k+1}$  be defined, provided  $\epsilon$  is small enough, by

$$g_{k+1}(x) = \frac{\phi h_k + (1 - \phi)g_k}{|\phi h_k + (1 - \phi)g_k|} \text{ and } g_{k+1}(-x) = R_x \circ g_{k+1}(x)$$

for  $x \in \overline{D_{e_k}}$ . Therefore  $g = g_{n+1}$  is smooth, satisfies (4) and  $\|g - f\|_{C^0} < C\epsilon$ . If  $\epsilon$  is small enough,  $g$  is homotopic to  $f$ .

Let's now tackle the transversality condition. We write  $g$  in the following way:

$$g(x) = X(x) + \lambda(x)x,$$

where  $X$  is a tangent vector field of the sphere and  $|X|^2 + \lambda^2 = 1$ . Then,  $g$  satisfies (4) if and only if  $X$  and  $\lambda$  are even maps. By differentiating these equalities at a fixed point  $x$  (with  $\lambda(x) = 1$  and  $X(x) = 0$ ), one may find  $T_x g - I = T_x X$ . Then,  $T_x g - I$  is an isomorphism for all fixed points  $x$  if and only if  $X$  is transverse to the zero vector field. Then, one may build by induction, with Sard's theorem in

$n$ -dimensional charts on  $D_{e_k}$ , smooth tangent vector fields  $X_k$  such that  $X_0 = X$  and for  $0 \leq k \leq n$ :

- $X_{k+1} = X_k$  on  $\mathbf{S}^n \setminus (B_k^\alpha \cup (-B_k^\alpha))$ ,
- $X_{k+1}$  is transverse to 0 on  $\bigcup_{i=0}^k B_i^{2\alpha} \cup (-B_i^{2\alpha})$ ,
- $\|X_{k+1} - X_k\|_{C^0} < \epsilon$ ,
- $X_{k+1}$  is an even map.

Set

$$\bar{f}(x) = \frac{X_{n+1}(x) + \lambda(x)x}{|X_{n+1}(x)|^2 + \lambda(x)^2}.$$

If  $\epsilon$  is small enough, then  $\bar{f}$  is well defined, satisfies the assumptions of Step 1 and is homotopic to  $f$ . This ends the proof of Step 2.

These two steps clearly end the proof of the claim. □

### 3. CHOICE OF TEST FUNCTIONS

Thanks to Claim 2, one may easily deduce that

$$(5) \quad \forall a \in \mathcal{C}, u_{a^*} = -u_a,$$

where we have set, for this section,  $u_a = u_a^{s(a)}$ . Let  $r \in (-1, 1)$ . We look at the space  $E$  generated by

$$\phi = X_{e_1} \text{ and } \psi_r = u_{a_{r,e_1}}.$$

One may deduce from the continuity of  $\xi$  and  $s$ , (3) and (5) that

*Claim 4.* The map  $r \in (-1, 1) \mapsto \psi_r \in (L^2(\mathbf{S}^n, g), \|\cdot\|_{L^2})$  is continuous and

$$\lim_{r \rightarrow -1} \psi_r = -\phi, \quad \lim_{r \rightarrow 1} \psi_r = \phi.$$

For  $(x, y) \in \mathbf{R}^2 \setminus \{0\}$ , we set  $f_r = x\phi + y\psi_r \in E$ . Conformal invariance gives that

$$\begin{aligned} \frac{\int_{\mathbf{S}^n} |\nabla_g f_r|_g^2 dv_g}{\int_{\mathbf{S}^2} f_r^2 dv_g} &= \frac{\left(\int_{\mathbf{S}^n} |\nabla_g \phi|_g^n dv_g\right)^{\frac{2}{n}}}{\frac{1}{n+1}} \frac{\sigma x^2 + \tau_r y^2 + 2\alpha_r xy}{Ix^2 + J_r y^2 + 2\beta_r xy} \\ &:= (n+1) \left(\int_{\mathbf{S}^n} |\nabla_g \phi|_g^n dv_g\right)^{\frac{2}{n}} q(x, y), \end{aligned}$$

where we set for  $r \in (-1, 1)$

$$\sigma = \frac{\int_{\mathbf{S}^n} |\nabla_g \phi|_g^2 dv_g}{\left(\int_{\mathbf{S}^n} |\nabla_g \phi|_g^n dv_g\right)^{\frac{2}{n}}} < 1, \quad \tau_r = \frac{\int_{\mathbf{S}^n} |\nabla_g \psi_r|_g^2 dv_g}{\left(\int_{\mathbf{S}^n} |\nabla_g \phi|_g^n dv_g\right)^{\frac{2}{n}}} < 2^{\frac{2}{n}},$$

$$\alpha_r = \frac{\int_{\mathbf{S}^n} g(\nabla_g \psi_r, \nabla_g \phi) dv_g}{\left(\int_{\mathbf{S}^n} |\nabla_g \phi|_g^n dv_g\right)^{\frac{2}{n}}}, \quad \beta_r = (n+1) \int_{\mathbf{S}^n} \phi \psi_r dv_g,$$

$$I = (n+1) \int_{\mathbf{S}^n} \phi^2 dv_g > 1, \quad J_r = (n+1) \int_{\mathbf{S}^n} \psi_r^2 dv_g > 1.$$

By (2),  $\tau_r < 2^{\frac{2}{n}}$ , and by maximality of  $\phi$  and  $\psi_r$ ,  $I > 1$  and  $J_r > 1$ .



The value  $(n+1)2^{\frac{2}{n}} \left( \int_{\mathbf{S}^n} |\nabla_g \phi|_g^n dv_g \right)^{\frac{2}{n}}$ , which also appears in (2), is independent of the metric  $g \in [g_0]$  thanks to conformal invariance. The quotient  $K_n$  given in the theorem compares this value with the constant of the conjecture  $n(2\sigma_n)^{\frac{2}{n}}$ :

$$\begin{aligned}
 (6) \quad K_n &:= \frac{(n+1)2^{\frac{2}{n}} \left( \int_{\mathbf{S}^n} |\nabla_{g_0} \phi|_{g_0}^n dv_{g_0} \right)^{\frac{2}{n}}}{n(2\sigma_n)^{\frac{2}{n}}} \\
 &= \frac{n+1}{n} \left( \frac{1}{\sigma_n} \int_{\mathbf{S}^n} (1 - X_{e_1}^2) dv_{g_0} \right)^{\frac{2}{n}} \\
 &= \frac{n+1}{n} \left( \frac{\sigma_{n-1}}{\sigma_n} \int_0^\pi (\sin \theta)^{2n-1} d\theta \right)^{\frac{2}{n}}.
 \end{aligned}$$

The computation of the explicit value of  $K_n$  is classical (see for instance [5]). Thus, in order to get the estimate of the Theorem and using the min-max principle (1), we look for  $r \in (-1, 1)$  such that for all  $(x, y) \in \mathbf{R}^2 \setminus \{0\}$ ,

$$q(x, y) < 2^{\frac{2}{n}}.$$

Since  $I > 1$  and  $J_r > 1$ , we look for  $r \in (-1, 1)$  such that

$$(\sigma - 2^{\frac{2}{n}})x^2 + 2(\alpha_r - 2^{\frac{2}{n}}\beta_r)yx + (\tau_r - 2^{\frac{2}{n}})y^2 < 0.$$

Moreover, since  $\sigma < 1$  and  $\tau_r - 2^{\frac{2}{n}} < 0$ , it is sufficient to find  $r \in (-1, 1)$  such that

$$\alpha_r - 2^{\frac{2}{n}}\beta_r = 0.$$

By Claim 4, we know that

$$\alpha_r = \frac{- \int_{\mathbf{S}^n} \psi_r (\Delta_g \phi) dv_g}{\left( \int_{\mathbf{S}^n} |\nabla_g \phi|_g^n dv_g \right)^{\frac{2}{n}}} \xrightarrow{r \rightarrow 1} \frac{- \int_{\mathbf{S}^n} \phi (\Delta_g \phi) dv_g}{\left( \int_{\mathbf{S}^n} |\nabla_g \phi|_g^n dv_g \right)^{\frac{2}{n}}} = \sigma$$

and that

$$\beta_r = (n+1) \int_{\mathbf{S}^n} \phi \psi_r dv_g \xrightarrow{r \rightarrow 1} (n+1) \int_{\mathbf{S}^n} \phi^2 dv_g = I.$$

Thus, when  $r \rightarrow 1$  and, in an analogous way, when  $r \rightarrow -1$  (see Claim 4),

$$\alpha_r - 2^{\frac{2}{n}}\beta_r \xrightarrow{r \rightarrow 1} \sigma - 2^{\frac{2}{n}}I < 0$$

and

$$\alpha_r - 2^{\frac{2}{n}}\beta_r \xrightarrow{r \rightarrow -1} 2^{\frac{2}{n}}I - \sigma > 0.$$

By continuity (Claim 4), there exists  $r \in (-1, 1)$  such that  $\alpha_r - 2^{\frac{2}{n}}\beta_r = 0$ . As has already been said, this completes the proof of the Theorem.

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