AN ALGEBRAIC CONSTRUCTION OF A SOLUTION TO THE MEAN FIELD EQUATIONS ON HYPERELLIPTIC CURVES AND ITS ADIABATIC LIMIT

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ABSTRACT. In this paper, we give an algebraic construction of the solution to the following mean field equation:

$$\Delta \psi + e^{\psi} = 4\pi \sum_{i=1}^{2g+2} \delta_{P_i}$$

on a genus $g \ge 2$ hyperelliptic curve (X, ds^2) , where ds^2 is a canonical metric on X and $\{P_1, \cdots, P_{2g+2}\}$ is the set of Weierstrass points on X.

1. INTRODUCTION

Let f(x) be a complex polynomial in x with 2g + 2 distinct complex roots $\{e_1, \cdots, e_{2g+2}\}$. The affine plane curve $C_0 = \{(x, y) \in \mathbb{C}^2 : y^2 = f(x)\}$ defines a noncompact Riemann surface with respect to the complex analytic topology on \mathbb{C}^2 . To compactify C_0 in the category of Riemann surfaces, we introduce another smooth affine plane curve C'_0 . Let g(z) be the complex polynomial $g(z) = \prod_{i=1}^{2g+2} (1-e_i z)$ and C'_0 be the smooth affine plane curve defined by $w^2 = g(z)$, i.e., $C'_0 = \{(z, w) \in \mathbb{C}^2 : w^2 = g(z)\}$. Let U_0 be the open subset of C_0 consisting of points (x, y) so that $x \neq 0$ and U'_0 be the open subset of C'_0 consisting of points (z, w) such that $z \neq 0$. The map $\varphi : U_0 \to U'_0$ defined by $\varphi(x, y) = (1/x, y/x^{g+1})$ is an isomorphism of Riemann surfaces. It is well known that the gluing $C_0 \cup_{\varphi} C'_0$ of C_0 and C'_0 along φ is a connected compact Riemann surface of genus g; see [3] or [4]. The compact Riemann surface $C_0 \cup_{\varphi} C'_0$ is called the hyperelliptic curve of genus g defined by $y^2 = f(x)$ and is denoted by X in this paper. The holomorphic map $\pi : X \to \mathbb{P}^1$ defined by

$$\pi(P) = \begin{cases} (x(P):1) & \text{if } P \in C_0, \\ (1:z(P)) & \text{if } P \in C'_0, \end{cases}$$

is a degree two ramified covering map of \mathbb{P}^1 , where $(z_0 : z_1)$ is the homogeneous coordinate on \mathbb{P}^1 . The Weierstrass points of X are the 2g + 2 ramification points $\{P_1, \dots, P_{2g+2}\}$ of π such that $(x(P_k), y(P_k)) = (e_k, 0)$ for $1 \le k \le 2g + 2$.

The space $H^0(X, \Omega^1_X)$ of holomorphic one forms on X has a simple basis of the form $\{x^{i-1}dx/y: 1 \leq i \leq g\}$ and the integral homology group $H_1(X)$ of X has a (symplectic) \mathbb{Z} -basis $\{a_i, b_j: 1 \leq i, j \leq g\}$ such that $\int_{a_j} \omega_i = \delta_{ij}$ for $1 \leq i, j \leq g$. Denote $\tau_{ij} = \int_{b_j} \omega_i$ for $1 \leq i, j \leq g$ and let τ be the complex $g \times g$ matrix $[\tau_{ij}]_{i,j=1}^g$.

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Then τ is a symmetric matrix with a positive definite imaginary part. Let Λ_{τ} be the lattice in \mathbb{C}^g generated by the column vectors of the $g \times 2g$ matrix $\Omega = [I_g, \tau]$. Let Ω_i be the *i*-th column vector of Ω and let $\{dx_1, \dots, dx_{2g}\}$ be the real basis dual to $\{\Omega_i : 1 \leq i \leq 2g\}$. The complex torus $\operatorname{Jac}(X) = \mathbb{C}^g / \Lambda_{\tau}$ together with the class $[\omega]$, where $\omega = \sum_{i=1}^g dx_i \wedge dx_{g+i}$ is a principally polarized abelian variety called the Jacobian variety of X. Fixing a point P_0 on X, we define a holomorphic map

$$\mu: X \to \operatorname{Jac}(X), \quad \mu(P) = \left(\int_{P_0}^P \frac{dx}{y}, \cdots, \int_{P_0}^P \frac{x^{g-1}dx}{y}\right) \mod \Lambda.$$

Let (z_1, \dots, z_g) be the standard holomorphic coordinate on $\operatorname{Jac}(X)$ and let $d\tilde{s}_H^2$ be the flat hermitian metric $\sum_{i,j=1}^g h_{ij} dz^i \otimes d\overline{z}^j$ on $\operatorname{Jac}(X)$, where $H = [h_{ij}]$ is a $g \times g$ positive definite hermitian matrix. The canonical metric ds_H^2 on X is defined by $ds_H^2 = \mu^* d\tilde{s}_H^2$ and has the form

$$ds_{H}^{2} = \frac{1}{|y^{2}|} \sum_{i,j=1}^{g} h_{ij} x^{i-1} \overline{x}^{j-1}$$

Let Δ_H be the Laplace operator associated with the metric ds_H^2 . In this paper, we study the following mean field equation:

(1.1)
$$\Delta_H \psi + e^{\psi} = 4\pi \sum_{i=1}^{2g+2} \delta_{P_i},$$

where $\{P_1, \dots, P_{2g+2}\}$ is the set of all Weierstrass points on X and $\delta_P : C^{\infty}(X) \to \mathbb{C}$ is the Dirac measure centered at P for $P \in X$.

In [2], we discovered that when X has genus two, the Gaussian curvature function K of a canonical metric determines a solution ψ to (1.1). This paper is a continuation of [2]; we give an algebraic construction of a solution to (1.1) involving the study of solutions to the formal nonlinear ordinary differential equation

(1.2)
$$(tQ''(t) + Q'(t))Q(t) - t(Q'(t))^2 = S(t)Q(t),$$

and the study of solutions to the formal nonlinear partial differential equation

(1.3)
$$u\frac{\partial^2 u}{\partial x \partial y} - \frac{\partial u}{\partial x}\frac{\partial u}{\partial y} = \sigma u.$$

Here S(t) is a complex formal power series and σ is a complex polynomial in x, y. We call S the data for (1.2) and σ the data for (1.3), respectively. In Section 2, we define a sequence of polynomials to solve (1.2) and give a necessary and sufficient condition for (1.2) possesing a polynomial solution. In Section 3, we show that the existence of solutions to (1.3) is equivalent to the nonemptiness of a certain (ind) affine algebraic set. Solutions to (1.2) would allow us to construct solutions to (1.3) for a certain type of polynomials σ . In Section 4, using the method developed in Section 2 and Section 3, we give a construction of a solution to (1.1) and the closed form of a solution to (1.1) when H is a diagonal matrix with positive diagonals. In Section 5, we introduce a real positive parameter γ into (1.1) and generalize the solutions constructed in previous sections. The parameter arises from a rescaling of a canonical metric by γ and we discuss the adiabatic limit of solutions as $\gamma \to 0$.

2. A FORMAL NONLINEAR ORDINARY DIFFERENTIAL EQUATION

Let $\{\lambda_i : i \geq 0\}$ be an infinite sequence of variables and $\mathbb{K}[\Lambda]$ be the ring of polynomials in $\{\lambda_i : i \geq 0\}$ over a field \mathbb{K} . We define a sequence of polynomials $\{f_{\lambda}^i : i \geq 1\}$ in $\mathbb{Q}[\Lambda][t]$ by $f_{\lambda}^1(t) = \lambda_0$ and (2.1)

$$f_{\lambda}^{k+1}(t) = \frac{\lambda_k}{(k+1)^2} + \frac{t}{(k+1)^2} \sum_{i=0}^{k-1} (\lambda_i - (i+1)(2i+1-k)f_{\lambda}^{i+1}(t))f_{\lambda}^{k-i}(t), \quad k \ge 2.$$

By definition,

$$f_{\lambda}^{2}(t) = \frac{\lambda_{0}^{2}t + \lambda_{1}}{4}, \quad f_{\lambda}^{3}(t) = \frac{\lambda_{0}\lambda_{1}t + \lambda_{2}}{9}, \quad f_{\lambda}^{4}(t) = -\lambda_{0}^{2}\lambda_{1}t^{2} + (3\lambda_{1}^{2} + 8\lambda_{0}\lambda_{2})t + \frac{\lambda_{3}}{16}.$$

By induction, the degree of $f_{\lambda}^{i}(t)$ in t is i-2 for $i \geq 3$ and the t^{0} term of $f_{\lambda}^{i}(t)$ is $\lambda_{i-1}/(i-1)^{2}$ for $i \geq 2$. Let us denote f_{λ}^{i} by

$$f^i_{\lambda}(t) = \sum_{j=0}^{i-2} \beta_{ij}(\lambda) t^j, \quad \beta_{ij}(\lambda) \in \mathbb{Q}[\Lambda].$$

If $S(t) = \sum_{i=0}^{\infty} s_i t^i$ is a complex formal power series, we set $f_S^1(t) = s_0$ and

$$f_{S}^{i}(t) = \sum_{j=0}^{i-2} \beta_{ij}(s_{0}, s_{1}, \cdots) t^{j}$$

Notice that when S(t) is a polynomial of degree at most n, then $f_S^i(t)$ is divisible by t for all $i \ge n+2$.

Lemma 2.1. Let f(t) and g(t) be complex power series such that $g(0) \neq 0$ and f(t)g(t) is divisible by t^m for some $m \geq 1$. Then f(t) is divisible by t^m .

Proof. We assume that $f(t)g(t) = t^m h(t)$ for some $h(t) \in \mathbb{C}[[t]]$. Then f(0) = 0. Taking the (formal) derivatives of the equation $f(t)g(t) = t^m h(t)$ with respect to t and using the fact that $g(0) \neq 0$, we prove by induction that $f^{(i)}(0) = 0$ for $1 \leq i \leq m-1$. This implies that $f(t) = t^m f_1(t)$ with $f_1 \in \mathbb{C}[[t]]$. \Box

Assume that Q(t) is a solution to (1.2) and Q(t) is divisible by t^m but not by t^{m+1} . Define $Q_1(t) \in \mathbb{C}[[t]]$ such that $Q(t) = t^m Q_1(t)$. $(Q_1(t)$ is defined since $\mathbb{C}[[t]]$ is a unique factorization domain.) Then $Q_1(0) \neq 0$. By an elementary computation,

$$t^{m}\left((tQ_{1}''(t)+Q_{1}'(t)Q_{1}(t))-t(Q_{1}'(t))^{2}\right)=S(t)Q_{1}(t).$$

By Lemma 2.1, S(t) is divisible by t^m . Define $S_1(t)$ by $S(t) = t^m S_1(t)$. Then

$$(tQ_1''(t) + Q_1'(t)Q_1(t)) - t(Q_1'(t))^2 = S_1(t)Q_1(t).$$

This shows that $Q_1(t)$ is a solution to (1.2) with the data $S_1(t)$ and with the initial condition $Q_1(0) \neq 0$. Owing to this observation, it suffices to consider the solutions Q(t) to (1.2) for a given data S(t) under the assumption $Q(0) \neq 0$.

Proposition 2.2. Let $S(t) = \sum_{i=0}^{\infty} s_i t^i$ be a complex formal power series and let a be a nonzero complex number. A formal power series $Q(t) = \sum_{i=1}^{\infty} q_i t^i$ with Q(0) = 1/a solves (1.2) for the data S(t) if and only if $q_i = f_S^i(a)$ for $i \ge 1$. Proof. After some basic computation, we know

$$(tQ''(t) + Q'(t))Q(t) - t(Q'(t))^2 = \sum_{k=0}^{\infty} \left(\sum_{i=0}^k (i+1)(2i+1-k)q_{i+1}q_{k-i} \right) t^k,$$
$$S(t)Q(t) = \sum_{k=0}^{\infty} \left(\sum_{i=0}^k s_i q_{k-i} \right) t^k.$$

If Q(t) is a solution to (1.2), then

(2.2)
$$\sum_{i=0}^{k} (i+1)(2i+1-k)q_{i+1}q_{k-i} = \sum_{i=0}^{k} s_i q_{k-i}, \quad k \ge 0.$$

Hence $q_0q_1 = q_0s_0$. Since $q_0 \neq 0$, $q_1 = s_0$. Then $q_1 = f_S^1(a)$ holds. Furthermore, (2.2) can be rewritten as:

(2.3)
$$(k+1)^2 q_{k+1} q_0 = s_k q_0 + \sum_{i=0}^{k-1} (s_i - (i+1)(2i+1-k)q_{i+1})q_{k-i}, \quad k \ge 1,$$

which implies that (by $q_0 = 1/a$)

$$q_{k+1} = \frac{s_k}{(k+1)^2} + \frac{a}{(k+1)^2} \sum_{i=0}^{k-1} (s_i - (i+1)(2i+1-k)q_{i+1})q_{k-i}, \quad k \ge 1.$$

By (2.1) and induction, $q_{k+1} = f_S^{k+1}(a)$ for $k \ge 1$. For the converse, since $q_i = f_S^i(a)$, (q_i) satisfies (2.2). Define $Q(t) = \sum_{i=0}^{\infty} q_i t^i$. By (2.2), Q(t) satisfies (1.2). We complete the proof of our assertion.

This proposition implies that the solution to (1.2) is uniquely determined by the initial condition Q(0) = a with $a \neq 0$ and the solution can be constructed by the numbers $f_S^i(a)$ for $i \geq 1$.

When S(t) is a polynomial of degree m, we would like to find the necessary and the sufficient condition for (1.2) possessing polynomial solutions.

Lemma 2.3. Let S(t) be a polynomial of degree m. If the solution Q(t) to (1.2) for the data S(t) is a polynomial of degree n in t, then $n \ge m + 2$.

Proof. The polynomial $(tQ''(t) + Q'(t))Q(t) - t(Q'(t))^2$ has degree at most 2n - 2 while the degree of S(t)Q(t) is n + m. Hence $n + m \le 2n - 2$ implies that $n \ge m + 2$.

Proposition 2.4. Let S(t) be a polynomial of degree m. The solution Q(t) to (1.2) for the data S(t) constructed in Proposition 2.2 is a polynomial in t if and only if there exists $N \in \mathbb{N}$ with $N \ge m + 2$ such that q_0^{-1} is the common root of the polynomials $\{f_S^i : N + 1 \le i \le 2N - 1\}$. Here $q_0 = Q(0)$.

Proof. Suppose that $Q(t) = \sum_{i=0}^{\infty} q_i t^i$ is a polynomial of degree n. Then $q_i = 0$ for all $i \ge n+1$. We choose N = n. By Lemma 2.3, $N \ge m+2$. Since $q_i = f_S^i(q_0^{-1})$, q_0^{-1} is a root of f_S^i for all $i \ge N+1$ and hence $f_S^i(q_0^{-1}) = 0$ for all $i \ge N+1$. Therefore, q_0^{-1} is a root of $f_S^i(t)$ for $i \ge N+1$ and thus for $N+1 \le i \le 2N-1$.

Let us prove the converse. Assume that q_0^{-1} is a common root of $f_S^i(t)$ for $N+1 \le i \le 2N-1$. Let us prove the statement $q_{2N-1+j} = 0$ for $j \ge 1$ by induction

on j. For j = 1,

$$q_{2N} = \frac{1}{(2N)^2 q_0} \sum_{i=0}^{2N-2} (s_i - (i+1)(2N - 2i + 2)q_{i+1})q_{2N-1-i}.$$

For $0 \leq i \leq N-2$, $N+1 \leq 2N-1-i \leq 2N-1$. Hence $q_{2N-1-i} = 0$ for $0 \leq i \leq N-2$. For $i \geq N-1$, $i \geq m+1$ and hence $s_i = 0$ for $i \geq N-1$. For $N \leq i \leq 2N-2$, $N+1 \leq i+1 \leq 2N-1$. Hence $q_{i+1} = 0$ for $N \leq i \leq 2N-2$ by assumption. Notice that when i = N-1, 2i-2N+2 = 0. We conclude that $q_{2N} = 0$. This proves that the statement holds for j = 1. We assume that the statement is true for $0 \leq j \leq l$. If j = l+1, $2N-1+j \geq N \geq m+2$ and hence $s_{2N-1+j} = 0$ which implies that

$$q_{2N+l} = \frac{1}{(2N+l)^2 q_0} \sum_{i=0}^{2N+l-2} (s_i - (i+1)(2i+1-k)q_{i+1})q_{2N+l-1-i}.$$

For $0 \leq i \leq N-1$, $N+1 \leq N+l < 2N-1+l-i \leq 2N-1+l-i \leq 2N-1+l$. By induction hypothesis and the assumption, we obtain that $q_{2N-1+l-i} = 0$ for $0 \leq i \leq N-1$. For $N \leq i \leq 2N+l-2$, $N+1 \leq i+1 \leq 2N-1+l$ and hence $s_i = q_{i+1} = 0$. We conclude that $q_{2N+l} = 0$. We prove that $q_{2N-1+j} = 0$ holds for j = l+1. By mathematical induction, $q_{2N-1+j} = 0$ for all $j \geq 1$. Combining with the assumption, one has $q_i = 0$ for all $i \geq N+1$. Therefore, Q(t) is a polynomial. \Box

In fact, we can prove that:

Lemma 2.5. Let x_0, \dots, x_m be a set of formal variables for $m \ge 1$. For each *i*, define a polynomial over \mathbb{Q} in x_0, \dots, x_m, t by

(2.4)
$$F^{i}(x_{0}, \cdots, x_{m}, t) = f^{i}_{x_{0}+x_{1}t+\cdots+x_{m}t^{m}}(t),$$

where f_S^i is the polynomial defined in (2.1). Let N be a natural number so that $N \ge m+2$. The set of polynomials $\{F^i : N+1 \le i \le 2N-1\}$ is divisible by $G(x_0, \dots, x_{g-1}, t) \in \mathbb{Q}[x_0, \dots, x_{g-1}, t]$ if and only if $\{F^i : i \ge N+1\}$ is divisible by G.

Proof. The proof follows from the recursive relation

$$F^{k+1} = \frac{t}{(k+1)^2} \sum_{i=0}^{k-1} (x_i - (i+1)(2i+1-k)F^{i+1})F^{k-i}, \quad k \ge m+1,$$

and is similar to that given in Proposition 2.4. We leave it to the readers.

Corollary 2.6. Let S(t) be a complex polynomial of degree m and let Q(t) be a solution to (1.2) for the data S(t) such that $Q(0)^{-1}$ is a common zero of $\{f_S^i : m+3 \le i \le 2m+3\}$. Then Q(t) is a polynomial of degree m+2.

Proof. By assumption and Proposition 2.4, $q_i = 0$ for $i \ge m+3$. Then Q(t) is a polynomial of degree at most m+2. By Lemma 2.3, the degree of Q(t) is at least m+2. We conclude that Q(t) is a polynomial of degree m+2.

Lemma 2.7. For any $i \ge 1$, and any $S(t) \in \mathbb{C}[[t]]$,

$$f_{\lambda S}^{i}(t) = \lambda f_{S}^{i}(\lambda t)$$

for any $\lambda \in \mathbb{C}$.

Proof. When i = 1, the statement is obvious. One can also verify that the statement is true for i = 2 and 3. Assume that the statement is true for i = k. For i = k + 1, we use the recursive relation:

$$\begin{split} f_{\lambda S}^{k+1}(t) &= \frac{\lambda s_k}{(k+1)^2} + \frac{t}{(k+1)^2} \sum_{i=0}^{k-1} (\lambda s_i - (i+1)(2i+1-k)f_{\lambda S}^{i+1}(t))f_{\lambda S}^{k-i}(t) \\ &= \frac{\lambda s_k}{(k+1)^2} + \frac{t}{(k+1)^2} \sum_{i=0}^{k-1} (\lambda s_i - (i+1)(2i+1-k)\lambda f_S^{i+1}(\lambda t))\lambda f_{\lambda S}^{k-i}(\lambda t) \\ &= \lambda \left(\frac{s_k}{(k+1)^2} + \frac{\lambda t}{(k+1)^2} \sum_{i=0}^{k-1} (s_i - (i+1)(2i+1-k)f_S^{i+1}(\lambda t))f_S^{k-i}(\lambda t) \right) \\ &= \lambda f_S^i(\lambda t). \end{split}$$

This lemma implies that:

Corollary 2.8. Let S(t) be a complex polynomial of degree m. Then (1.2) has a polynomial solution for data S(t) if and only if (1.2) has polynomial solution for data $\lambda S(t)$ for $\lambda \in \mathbb{C}^*$.

Given any complex polynomial $B(t) = \sum_{i=0}^{n} b_i t^i$, we define a new polynomial $\widetilde{B}(t)$ by

$$\widetilde{B}(t) = t^{\deg B} B(t^{-1})$$

and write $\widetilde{B}(t) = \sum_{i=0}^{n} \widetilde{b}_i t^i$, where $n = \deg B(t)$. Then $\widetilde{b}_i = b_{n-i}$ for $0 \le i \le n$.

Proposition 2.9. Let S(t) be a complex polynomial of degree m. Suppose that (1.2) has a polynomial solution Q(t) of degree n for the data S(t). Then $\tilde{Q}(t)$ solves (1.2) for the data $t^{n-m-2}\tilde{S}(t)$.

Proof. One uses the chain rules to prove the statement while the calculation is elementary. $\hfill \Box$

This proposition implies that

Corollary 2.10. Let S(t) be a complex polynomial of degree m. Suppose that (1.2) has a polynomial solution Q(t) of degree m + 2 for the data S(t). Then $\tilde{Q}(t)$ solves (1.2) for the data $\tilde{S}(t)$.

3. A FORMAL NONLINEAR PARTIAL DIFFERENTIAL EQUATION

Let $M_n(\mathbb{C})$ be the algebra of $n \times n$ complex matrices. For each $n \ge 1$, we consider the algebra monomorphism $\psi_{n,n+1} : M_n(\mathbb{C}) \to M_{n+1}(\mathbb{C})$ defined by

$$\psi_{n,n+1}(A) = \left[\begin{array}{cc} A & 0\\ 0 & 0 \end{array} \right].$$

The direct limit of the directed system $\{(M_n(\mathbb{C}), \psi_{n,m})\}$ is denoted by $M_{\infty}(\mathbb{C})$, where the algebra monomorphism $\psi_{n,m} : M_n(\mathbb{C}) \to M_m(\mathbb{C})$ for n < m is defined by

$$\psi_{n,m} = \psi_{m,m-1} \circ \cdots \circ \psi_{n+1,n}.$$

Denote the canonical map $M_n(\mathbb{C}) \to M_\infty(\mathbb{C})$ by ψ_n and identify $M_n(\mathbb{C})$ with its image in $M_\infty(\mathbb{C})$. Then $M_\infty(\mathbb{C})$ can be realized as a union $\bigcup_{n=1}^{\infty} M_n(\mathbb{C})$; $M_\infty(\mathbb{C})$ is an ind-variety over \mathbb{C} .

By an ind-variety over a field k, we mean that a set X together with a filtration $X_0 \subset X_1 \subset X_2 \subset \cdots$ such that $\bigcup_{n\geq 0} X_n = X$ and each X_n is a finite dimensional variety over k such that the inclusion $X_n \to X_{n+1}$ is a closed embedding. An ind-variety has a natural topology defined as follows. A subset U of X is said to be open if and only if $U \cap X_n$ is open in X_n for each $n \geq 0$. The ring of regular functions on X denoted by k[X] is defined to be $k[X] = \lim_{n \to \infty} k[X_n]$. An ind-variety is said to be projective, resp., affine, if each X_n is projective, resp., affine. For more details about ind-varieties, see [5].

For each $A \in M_{\infty}(\mathbb{C})$, we may write $A = (a_{ij})_{i,j=1}^{\infty}$ with $a_{ij} = 0$ for all but finitely many i, j. We associate to A a complex polynomial $\mathfrak{p}(A)(x, y)$ in x, y by

$$\mathfrak{p}(A)(x,y) = \sum_{i,j=0}^{\infty} a_{i+1,j+1} x^i y^j.$$

We obtain a linear monomorphism $\mathfrak{p} : M_{\infty}(\mathbb{C}) \to \mathbb{C}[x, y]$. The image of \mathfrak{p} is denoted by $\mathfrak{P}_{\infty}[x, y]$. Given $\sigma \in \mathfrak{P}_{\infty}[x, y]$, we would like to solve for the formal nonlinear differential equation (1.3) in $\mathfrak{P}_{\infty}[x, y]$. To solve for (1.3) in $\mathfrak{P}_{\infty}[x, y]$, let us assume that

$$u(x,y) = \sum_{\alpha,\beta=0}^{\infty} a_{\alpha+1,\beta+1} x^{\alpha} y^{\beta} \quad \text{and} \quad \sigma(x,y) = \sum_{i,j=0}^{\infty} c_{i+1,j+1} x^i y^j.$$

By simple computation,

$$uu_{xy} - u_x u_y = \sum_{\alpha,\beta=0}^{\infty} \left(\sum_{i=0}^{\alpha+1} \sum_{j=0}^{\beta+1} i(2j-\beta-1)a_{i+1,j+1}a_{\alpha-i+2,\beta-j+2} \right) x^{\alpha} y^{\beta},$$
$$\sigma u = \sum_{\alpha,\beta=0}^{\infty} \left(\sum_{i=0}^{\alpha} \sum_{j=0}^{\beta} a_{i+1,j+1}c_{\alpha-i+1,\beta-j+1} \right) x^{\alpha} y^{\beta}.$$

Then u solves (1.3) if and only if

$$\sum_{i=0}^{\alpha+1} \sum_{j=0}^{\beta+1} i(2j-\beta-1)a_{i+1,j+1}a_{\alpha-i+2,\beta-j+2} = \sum_{i=0}^{\alpha} \sum_{j=0}^{\beta} a_{i+1,j+1}c_{\alpha-i+1,\beta-j+1}a_{\alpha-i+2,\beta-j+2} = \sum_{i=0}^{\alpha} \sum_{j=0}^{\beta} a_{i+1,j+1}c_{\alpha-i+1,\beta-j+1}a_{\alpha-i+1,\beta-i+1}a_{\alpha-i+1,\beta-i+1}a_{\alpha-i+1,\beta-i+1}a_{\alpha-i+1,\beta-i+1}a_{\alpha-i+1,\beta-i+1}a_{\alpha-i+1,\beta-i+1}a_{\alpha-i+1,\beta-i+1}a_{\alpha-i+1,\beta-i+1}a_{\alpha-i+1,\beta-i+1}a_{\alpha-i+1,\beta-i+1}a_{\alpha-i+1,\beta-i+1}a_{\alpha-i+1,\beta-i+1}a_{\alpha-i+1,\beta-i+1}a_{\alpha-i+1,\beta-i+1}a_{\alpha-i+1,\beta-i+1}a_{\alpha-i+1,\beta-i+1}a_{\alpha-i+$$

for any $\alpha, \beta \geq 0$. For each α, β , we define

$$\varphi_{\sigma}^{\alpha,\beta}(A) = \sum_{i=0}^{\alpha+1} \sum_{j=0}^{\beta+1} i(2j-\beta-1)a_{i+1,j+1}a_{\alpha-i+2,\beta-j+2} - \sum_{i=0}^{\alpha} \sum_{j=0}^{\beta} a_{i+1,j+1}c_{\alpha-i+1,\beta-j+1}.$$

Then $u = \mathfrak{p}(A)$ for some $A \in M_{\infty}(\mathbb{C})$ solves (1.3) for data σ if and only if $\varphi_{\sigma}^{\alpha,\beta}(A) = 0$ for all α, β , i.e., A satisfies a family of quadratic polynomials. The subset

$$V_{\sigma} = \{ A \in M_{\infty}(\mathbb{C}) : \varphi_{\sigma}^{\alpha,\beta}(A) = 0 \}$$

of $M_{\infty}(\mathbb{C})$ is called the ind-affine algebraic variety associated with σ . The equation (1.3) has a solution for σ if and only if V_{σ} is nonempty.

For each $u \in \mathfrak{P}_{\infty}[x, y]$, we define $M_{xy}u$ by

$$(M_{xy}u)(x,y) = (xy)u(x,y)$$

Then M_{xy} defines a linear endomorphism on $\mathfrak{P}_{\infty}[x, y]$.

Lemma 3.1. Suppose that $u \in \mathfrak{P}_{\infty}[x, y]$ is a solution to (1.3) for data σ . Then $M_{xy}u$ is a solution to (1.3) for data $M_{xy}\sigma$.

Proof. Let $v = M_{xy}u$. Then v(x, y) = (xy)u(x, y). Hence $v_x = yu + (xy)u_x$, and $v_y = xu + (xy)u_y$, and $v_{xy} = u + yu_y + xu_x + (xy)u_{xy}$. We discover that

$$vv_{xy} - v_x v_y = (xy)^2 (uu_{xy} - u_x u_y) = (xy)^2 \sigma u = (M_{xy}\sigma)v.$$

This proves our assertion.

By making use of the fact that $\mathbb{C}[x, y]$ is a unique factorization domain, we prove the following fact:

Proposition 3.2. Let $v \in \mathfrak{P}_{\infty}[x, y]$ be a solution to (1.3) for a data $\sigma \in \mathfrak{P}_{\infty}[x, y]$. Assume that there exists $m \in \mathbb{N}$ such that v is divisible by $(xy)^m$ but not by $x^{m+1}y^m$ and not by $x^m y^{m+1}$. Then σ is divisible by $(xy)^m$. Furthermore, if $u \in \mathfrak{P}_{\infty}[x, y]$ and $\gamma \in \mathfrak{P}_{\infty}[x, y]$ are polynomials so that $v = M_{xy}^m u$ and $\sigma = M_{xy}^m \gamma$, then u is a solution to (1.3) for the data γ .

Proof. Since v is divisible by $(xy)^m$, we write $v = M_{xy}^m u$ for some $u \in \mathfrak{P}_{\infty}[x, y]$. We can show that

$$vv_{xy} - v_x v_y = (xy)^{2m} (uu_{xy} - u_x u_y).$$

Since $vv_{xy} - v_x v_y = \sigma v = (xy)^m \sigma u$, we find

$$\sigma u = (xy)^m (uu_{xy} - u_x u_y).$$

Since v is not divisible by $x^{m+1}y^m$ and not by $x^m y^{m+1}$, u is not divisible by x and y. We see that σ is divisible by $(xy)^m$. Let $\sigma = M_{xy}^m \gamma$ for $\gamma \in \mathfrak{P}_{\infty}[x, y]$. Then

$$uu_{xy} - u_x u_y = \gamma u$$

This proves our assertion.

Definition 3.3. A solution $u \in \mathfrak{P}_{\infty}[x, y]$ to (1.3) for a given data is called a prime solution to (1.3) if u is not divisible by xy.

Let us denote the image of $M_n(\mathbb{C})$ in $\mathbb{C}[x, y]$ via \mathfrak{p} by $\mathfrak{P}_n[x, y]$. Then $\mathfrak{P}_{\infty}[x, y] = \bigcup_{n>1} \mathfrak{P}_n[x, y]$.

Lemma 3.4. Let $\sigma \in \mathfrak{P}_m[x, y]$ with deg $\sigma = 2m - 2$. If $u \in \mathfrak{P}_{\infty}[x, y]$ is a solution to (1.3) for the data σ of degree 2n - 2, then $n \ge m + 2$.

Proof. We observe that the coefficients of $x^{2n-3}y^{2n-3}$ and of $x^{2n-3}y^{2n-4}$ and of $x^{2n-4}y^{2n-3}$ in $uu_{xy} - u_x u_y$ all vanish. Then $uu_{xy} - u_x u_y$ is a polynomial of degree at most 4n - 8. On the other hand, the degree of σu is 2n + 2m - 4. We conclude that $n \ge m + 2$.

Let us write a remark that V_{σ} is an ind-affine variety. Given $\sigma \in \mathfrak{P}_m[x, y]$ with degree 2m-2, the intersection $V_{\sigma}^n = V_{\sigma} \cap M_n(\mathbb{C})$ is an affine algebraic subvariety of $M_n(\mathbb{C}) \cong \mathbb{A}^{n^2}(\mathbb{C})$ for $n \ge m+2$ and $V_{\sigma} = \bigcup_{n \ge m+2} V_{\sigma}^n$.

Let $q \in \mathfrak{P}_n[x, y]$. Formally, we define

$$\tilde{q}(x,y) = (xy)^n q(x^{-1}, y^{-1}).$$

Lemma 3.5. Let $\sigma \in \mathfrak{P}_m[x, y]$ be given with deg $\sigma = 2m - 2$. If $u \in \mathfrak{P}_n[x, y]$ is a solution to (1.3) for data σ , then \widetilde{u} is a solution to (1.3) with data $M_{xy}^{n-m-2}\widetilde{\sigma}$.

Proof. Let
$$v = \tilde{u}$$
. Then $v(x, y) = (xy)^n u(x^{-1}, y^{-1})$. Then
 $v_x = nx^{n-1}y^n u(x^{-1}, y^{-1}) - x^{n-2}y^n u_x(x^{-1}, y^{-1}),$
 $v_y = nx^n y^{n-1} u(x^{-1}, y^{-1}) - x^n y^{n-2} u_y(x^{-1}, y^{-1}),$
 $v_{xy} = n^2 x^{n-1} y^{n-1} u(x^{-1}, y^{-1}) - nx^{n-1} y^{n-2} u_y(x^{-1}, y^{-1})$
 $- nx^{n-2} y^{n-1} u_x(x^{-1}, y^{-1}) + x^{n-2} y^{n-2} u_{xy}(x^{-1}, y^{-1}).$

This implies that

$$\begin{aligned} vv_{xy} - v_x v_y &= (xy)^{2n-2} (u(x^{-1}, y^{-1}) u_{xy}(x^{-1}, y^{-1}) - u_x(x^{-1}, y^{-1}) u_y(x^{-1}, y^{-1})) \\ &= (xy)^{2n-2} \sigma(x^{-1}, y^{-1}) u(x^{-1}, y^{-1}) \\ &= (xy)^{n-m-2} (xy)^m \sigma(x^{-1}, y^{-1}) \cdot (xy)^n u(x^{-1}, y^{-1}) \\ &= M_{xy}^{n-m-2} \widetilde{\sigma}(x, y) v(x, y). \end{aligned}$$

This proves our assertion.

This lemma leads to:

Corollary 3.6. Let $\sigma \in \mathfrak{P}_m[x, y]$ be given with deg $\sigma = 2m - 2$. If $u \in \mathfrak{P}_{m+2}[x, y]$ is a solution to (1.3) for data σ , then \widetilde{u} is a solution to (1.3) with data $\widetilde{\sigma}$.

Apparently, it is not simple to determine whether the set V_{σ} is empty or not. For the main purpose of this paper, we give only a partial solution to this question.

A polynomial u in $\mathfrak{P}_{\infty}[x, y]$ is called diagonal if $u = \mathfrak{p}(A)$ for some diagonal matrix $A \in M_{\infty}(\mathbb{C})$. If a polynomial u is diagonal, we can find a polynomial $Q(t) \in \mathbb{C}[t]$ such that u(x, y) = Q(xy). Here comes a natural question: given a diagonal polynomial σ as a data of (1.3), can we find a solution u to (1.3) such that u is also diagonal? From now on, we only consider prime solutions to (1.3).

Theorem 3.7. Let $\sigma \in \mathfrak{P}_m[x, y]$ be a diagonal polynomial of degree 2m - 2 with $\sigma(x, y) = S(xy)$ for some $S(t) \in \mathbb{C}[t]$. Then (1.3) has a solution u that is also diagonal if and only if there exists $N \in \mathbb{N}$ with $N \ge m + 2$ such that the family of polynomial $\{f_S^i : N + 1 \le i \le 2N - 1\}$ has a nonzero common root. Furthermore, if N = m + 2, then $u \in \mathfrak{P}_{m+2}[x, y]$ with $\deg u = 2m + 2$.

Proof. Assume that v(x, y) = q(xy) for some $q \in \mathbb{C}[t]$. Then

(3.1)
$$vv_{xy} - v_x v_y - \sigma v = (xy)q''(xy)q(xy) + q'(xy)q(xy) - (xy)(q'(xy))^2 - S(xy)q(xy).$$

If u(x, y) is a diagonal polynomial that solves (1.3) for data σ , and if we write u(x, y) = Q(xy) for some $Q(t) \in \mathbb{C}[t]$, then by (3.1), Q(t) solves (1.2) for data S(t) with t = xy. Since Q(t) is a polynomial solution to (1.2) with data S(t), Proposition 2.4 implies the result.

Let us prove the converse. Let a be a nonzero common root of $\{f_S^i : N+1 \le i \le 2N-1\}$. Define q_i by $q_0 = 1/a$ and $q_i = f_S^i(a)$ for $i \ge 1$. By Proposition 2.4, the polynomial $Q(t) = \sum_{i=0}^{\infty} q_i t^i$ solves (1.2) with data S(t). Define u(x,y) = Q(xy). Then u(x,y) is a polynomial. By (3.1), u solves (1.3) for data σ . The rest follows from Corollary 2.6.

This theorem enables us to find a class of polynomials σ in $\mathfrak{P}_{\infty}[x, y]$ such that V_{σ} is nonempty. It would be interesting to find criterions to know when V_{σ} is nonempty for any $\sigma \in \mathfrak{P}_{\infty}[x, y]$.

4. An explicit construction of a solution to the mean field equation for hyperelliptic curves

Let $H = (h_{ij})_{i,j=1}^g$ be a $g \times g$ positive definite hermitian matrix and consider the corresponding canonical metric ds_H^2 on the hyperelliptic curve X of genus g defined in the introduction. If we let $\sigma_H(x, y)$ be the complex polynomial $\sigma_H(x, y) = \sum_{i,j=1}^g h_{ij} x^{i-1} y^{j-1}$, then the canonical metric ds_H^2 on X has the local expression

$$ds_{H}^{2} = \begin{cases} \frac{\sigma_{H}(x,\overline{x})}{|y^{2}|} dx \otimes d\overline{x} & \text{ on } C_{0}, \\ \frac{\widetilde{\sigma}_{H}(z,\overline{z})}{|w^{2}|} dz \otimes d\overline{z} & \text{ on } C'_{0}. \end{cases}$$

Theorem 4.1. Suppose (1.3) has a solution $u = \mathfrak{p}(A) \in P_{g+1}[x, y]$ for the data σ_H with $A \in M_{g+1}(\mathbb{C})$ being positive definite. Then the function

$$\varphi = \begin{cases} \frac{4|f(x)|}{u(x,\overline{x})} & \text{on } C_0, \\ \frac{4|g(z)|}{\widetilde{u}(z,\overline{z})} & \text{on } C'_0, \end{cases}$$

is a globally defined nonnegative smooth function whose zero set coincides with the set of Weierstrass points of X and $\psi = \log \varphi$ defines smooth function on $X \setminus \{P_1, \dots, P_{2g+2}\}$ satisfying (1.1)

Proof. The proof is the same as that given in our previous paper; we give a sketch of the proof. For more details, see [2]. Let us verify that $\Delta \psi + e^{\psi} = 0$ on $U = X \setminus \{P_1, \dots, P_{2g+2}\}$. We will prove this equation on $U \cap C_0$. Since u satisfies (1.3), on $U \cap C_0$,

$$\frac{\partial^2}{\partial x \partial \overline{x}} \log \varphi = -\frac{u_{x\overline{x}}u - u_x u_{\overline{x}}}{u^2} = -\frac{\sigma u}{u^2} = -\frac{\sigma}{u}.$$

As a consequence,

$$\Delta_H \psi = 4 \frac{|f(x)|}{\sigma(x,\overline{x})} \frac{\partial^2}{\partial x \partial \overline{x}} \log \varphi = -4 \frac{|f(x)|}{u(x,\overline{x})} = -\varphi = -e^{\psi}.$$

Similarly, the equation holds on $U \cap C'_0$.

Let $P = P_k$ be a Weierstrass point of X. In a coordinate neighborhood (U_P, ζ) of $P = P_k$, where $\zeta = \sqrt{x - e_k}$, the function ψ has a local expression $\psi = 2 \log |\zeta| + \alpha$, where α is a nonzero smooth function on U_P . By classical analysis, the action of the Laplace operator Δ on ψ creates a Dirac delta measure $4\pi\delta_{P_k}$. We complete the proof of our assertion.

Since *H* is a $g \times g$ positive definite hermitian matrix, there exists a $g \times g$ unitary matrix *U* such that U^*HU is a diagonal matrix Λ with positive diagonals. We assume that $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_g)$ with $\lambda_i > 0$ for $1 \leq i \leq g$. Let us denote $S_{\Lambda}(t) = \sum_{i=0}^{g-1} \lambda_{i+1} t^i$; then the polynomial $\sigma_{\Lambda}(x, y) = S_{\Lambda}(xy)$ is diagonal. In other words, we consider the canonical metric on *X* of the form

$$ds_{\Lambda}^{2} = \begin{cases} \frac{\sum_{i=1}^{g} \lambda_{i}(x\overline{x})^{i-1}}{|y^{2}|} dx \otimes d\overline{x} & \text{ on } C_{0}, \\ \frac{\sum_{i=1}^{g} \lambda_{i}(z\overline{z})^{g-i}}{|w^{2}|} dz \otimes d\overline{z} & \text{ on } C_{0}'. \end{cases}$$

One can use Theorem 3.7 to determine diagonal solutions to (1.3) for σ_H in this case and to obtain "positive definite" solutions to (1.3) for σ_H . We need further analysis, i.e., solutions $u = \mathfrak{p}(A)$ so that A is a $g \times g$ positive definite hermitian matrix. For $g \geq 2$, let $\{F^i(x_0, \dots, x_{g-1}, t) : i \geq 1\}$ be the sequence of polynomials defined in (2.4). Let V be the affine algebraic subset of \mathbb{C}^{g+1} defined by the zero set of the polynomials $\{F^{g+2}, \dots, F^{2g-1}\}$ and let D_+^{g+1} be the set of all n-tuples of real numbers (a_1, \dots, a_{g+1}) such that $a_i > 0$ for all $1 \leq i \leq g+1$ and let Q_+^{g+1} be the subset of all D_+^{g+1} consisting of points (a_0, \dots, a_{g+1}) so that $F^i(a_0, \dots, a_{g+1}) > 0$ for $1 \leq i \leq g+1$. If there exists a positive real number a such that $(\Lambda, a) \in V \cap Q_+^{g+1}$, then the polynomial

(4.1)
$$u_{(\Lambda,a)}(x,y) = \frac{1}{a} + \sum_{i=1}^{g+1} F^i(\Lambda,a)(xy)^i$$

solves for (1.3) and equals $\mathfrak{p}(A)$ for $A = \operatorname{diag}(1/a, F^1(\Lambda, a), \cdots, F^{g+1}(\Lambda, a))$ and hence determines a solution to (1.1) by

(4.2)
$$\psi_{(\Lambda,a)} = \begin{cases} \log \frac{|f(x)|}{u_{(\Lambda,a)}(x,\overline{x})} & \text{on } C_0, \\ \log \frac{|g(z)|}{\widetilde{u}_{(\Lambda,a)}(z,\overline{z})} & \text{on } C'_0, \end{cases}$$

for $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_g)$. Let us take a look at the case when X is of genus two and of genus three.

Example 4.2. Let X be the hyperelliptic curve defined by the equation $y^2 = f(x)$ with metric ds^2 , where f(x) is a degree six polynomial with six distinct roots and

$$ds^2 = \frac{1+|x|^2}{|y^2|} dx \otimes d\overline{x}$$

In this case, S(t) = 1 + t. Then $f_S^1(t) = 1$ and $f_S^2(t) = (t+1)/4$ and $f_S^3(t) = t/9$ and

$$f_S^4(t) = -\frac{1}{192}t^2 + \frac{1}{64}t,$$

$$f_S^5(t) = \frac{1}{1800}t^3 - \frac{1}{600}t^2.$$

One sees that 3 is the common root of the polynomials $f_S^4(t)$ and $f_S^5(t)$. Then $h_0 = 1/3$ and $h_1 = f_S^1(3) = 1$ and $h_2 = f_S^2(3) = 1$ and $h_3 = f_S^3(3) = 1/3$. We obtain a polynomial u(x, y) by

$$u(x,y) = \frac{1}{3} + xy + (xy)^2 + \frac{1}{3}(xy)^3$$

which solves (1.3) for data $\sigma(x, y) = 1 + xy$. This gives us a solution ψ to (1.1) by the construction of Theorem 4.1 for the genus two hyperelliptic curve:

$$\psi = \begin{cases} \log \frac{12|f(x)|}{(1+|x|^2)^3} & \text{on } C_0, \\ \log \frac{12|g(z)|}{(1+|z|^2)^3} & \text{on } C'_0, \end{cases}$$

The result coincides with that obtained in our previous paper.

Example 4.3. Let X be the hyperelliptic curve defined by the equation $y^2 = f(x)$ with the metric ds^2 , where f(x) is a polynomial with eight distinct roots and

$$ds^2 = \frac{1+|x|^2+|x|^4}{|y^2|}dx \otimes d\overline{x}.$$

In this case, $S(t) = 1 + t + t^2$. Then $f_S^1(t) = 1$ and $f_S^2(t) = (t+1)/4$ and $f_S^3(t) = (t+1)/9$ and $f_S^4(t) = (-t^2 + 11t)/192$ and

$$\begin{split} f_S^5(t) &= \frac{1}{1800} t^3 - \frac{11}{1800} t^2 + \frac{1}{75} t, \\ f_S^6(t) &= -\frac{1}{11520} t^4 + \frac{11}{11520} t^3 - \frac{1}{405} t^2 + \frac{1}{324} t, \\ f_S^7(t) &= \frac{1}{58800} t^5 - \frac{401}{2116800} t^4 + \frac{373}{705600} t^3 - \frac{43}{52920} t^2 \end{split}$$

One sees that 8 is the common root of the polynomials $f_S^5(t)$ and $f_S^6(t)$ and $f_S^7(t)$. We see that $h_0 = 1/8$ and $h_1 = f_S^1(8) = 1$ and $h_2 = f_S^2(8) = 9/4$ and $h_3 = f_S^3(8) = 1$ and $h_4 = f_S^4(8) = 1/8$. We obtain a polynomial

$$u(x,y) = \frac{1}{8} + xy + \frac{9}{4}(xy)^2 + (xy)^3 + \frac{1}{8}(xy)^4$$

that solves (1.3) for the data $\sigma(x, y) = 1 + xy + (xy)^2$. This gives us a solution ψ to (1.1) by Theorem 4.1 for the genus three hyperelliptic curve:

$$\psi = \begin{cases} \log \frac{12|f(x)|}{\left(\frac{1}{8} + |x|^2 + \frac{9}{4}|x|^4 + |x|^6 + \frac{1}{8}|x|^8\right)} & \text{on } C_0, \\ \log \frac{12|g(z)|}{\left(\frac{1}{8} + |z|^2 + \frac{9}{4}|z|^4 + |z|^6 + \frac{1}{8}|z|^8\right)} & \text{on } C'_0, \end{cases}$$

5. Adiabatic limit of solutions to mean field equations

We propose a possible direction following the results above. Rescale the canonical metric by $\gamma \in \mathbb{R}^+$, i.e., we consider the rescaling of the canonical metric $ds_{\Lambda,\gamma}^2 = \gamma ds_{\Lambda}^2$. With respect to this metric, the mean field equation is equivalent to

(5.1)
$$\Delta \psi_{\gamma} + \gamma e^{\psi_{\gamma}} = 4\pi \gamma \sum_{i=1}^{2g+2} \delta_{P_i}$$

with respect to $ds_{\Lambda}^{2,1}$ Following from the analysis in [1], we study the existence of a solution to this equation for small γ , as well as the limit of the solutions $\{\psi_{\gamma}\}$ as $\gamma \to 0$. Directly observing (5.1), we naturally expect $\Delta \psi_{\gamma} \to 0$ as $\gamma \to 0$, or that ψ_{γ} approaches to a constant function since X is a connected closed manifold. Classical analysis from [1] confirms both expectations. We normalize the metrics so that the area of X is 1. Let $W^{k,p}(X)$ be the completion of $C^{\infty}(X)$ with respect to the (k, p)-norm:

$$||u||_{W^{k,p}(X)} = \sum_{j=0}^{k} \left(\int_{X} |\nabla^{j}u|^{p} d\nu \right)^{1/p},$$

¹For convenience, we use Δ instead of Δ_{Λ} in this section.

where $\nabla^{j} u$ is the *j*-th covariant derivative of *u*. We call $W^{k,p}(X)$ the Sobolev (k, p)-space on X^{2} . A technical analytic statement is needed to conclude the asymptotic behaviors:

Proposition 5.1. If $u_j \to u$ weakly in $W^{1,2}(X)$, then $e^{u_j} \to e^u$ strongly in $L^2(X)$.

Proof. For the proof, see (3.7) in [1].

Theorem 5.2 (Adiabatic limit). A solution to (5.1) exists for all γ small enough and approaches a constant in $W^{2,2}(X)$ as $\gamma \to 0$.

Proof. We only sketch the existence part of the proof since it is a replica of the proof from Theorem 7.2 in [1]. Let

(5.2)
$$\psi_{\gamma} := v_{\gamma} + 4\pi\gamma \sum_{i=1}^{2g+2} G_i,$$

where G_i is the Green's function satisfying $\Delta G_i = -\delta_{P_i} + 1$. Solving (5.1) is then equivalent to solving the following equation:

(5.3)
$$\Delta v_{\gamma} + \gamma h e^{v_{\gamma}} = 8\pi \gamma (g+1),$$

where the function $h = \exp\left(4\pi \sum_{i=1}^{2g+2} G_i\right) \in C^{\infty}(X)$ is nonnegative with zero set precisely the Weierstrass points. This is a Kazdan-Warner equation of the type discussed in section 7 from [1], which is solved by a variational method. One notes that (5.3) is the minimizing equation to the functional

(5.4)
$$J(u) = \int_X \left(\frac{1}{2}|\nabla u|^2 + 8\pi\gamma(g+1)u\right)d\nu$$

on the subset $B \subset W^{1,2}(X)$ satisfying the constraint equation

(5.5)
$$\int_X he^u d\nu = 8\pi (g+1).$$

Following identical reasoning, we have the following estimate for J:

(5.6)
$$J(u) \ge \frac{1}{4\beta} (2\beta - 8\pi\gamma(g+1)) \|\nabla u\|_{L^2(X)}^2 + \delta,$$

where δ is a constant and β is a Trudinger constant for X both independent of γ . More precisely, β is a positive constant so that

$$\int_X e^{\beta v^2} d\nu$$

are uniformly bounded for all $v \in W^{1,2}(X)$ with $\overline{v} = 0$ and $\|\nabla v\|_{L^2(X)} \leq 1$. Such a constant always exists for surfaces (cf. (3.4) in [1]). Therefore, for γ small enough so that $2\beta - 8\pi\gamma(g+1) > 0$, J is bounded below and positive.

For each γ , (5.6) and Sobolev embedding shows that the minimizing sequence $\{v_{\gamma}^i\}$ of J is contained in a fixed ball of radius R_{γ} in $W^{1,2}(X)$, which is weakly compact. Passing to a subsequence, let v_{γ} be the weak limit. Arguments in the proof of Theorem 5.3 in [1] show that v_{γ} minimizes J in B and, therefore, is a strong limit and solution to (5.3). The proof there also provides a regularity argument,

²In some context, people use $H^{k,p}(X)$ for Sobolev (k,p) spaces.

which is applicable to our case here, to show that v_{γ} is actually smooth. The existence of a smooth solution for each γ is established.

Furthermore, one notices that the radii R_{γ} are uniformly controlled over γ (in fact proportional to $(2\beta - 8\pi\gamma(g+1))^{-1}$) and therefore $\{v_{\gamma}\}$ are uniformly bounded in $W^{1,2}(X)$. Following identical arguments, let v be the limit of v_{γ} in $W^{1,2}(X)$. Proposition 5.1 then implies that $e^{v_{\gamma}}$ converge to e^{v} in $L^{2}(X)$ and, therefore, are uniformly bounded in $L^{2}(X)$. It then follows from elliptic regularity of Δ in (5.3):

(5.7)
$$\|v_{\gamma}\|_{W^{2,2}(X)} \le c(\gamma \|8\pi(g+1) - he^{v_{\gamma}}\|_{L^{2}(X)} + \|v_{\gamma}\|_{L^{2}(X)})$$

that v_{γ} are uniformly bounded in $W^{2,2}(X)$. The estimate, together with some Schauder estimates, also imply that $v \in C^{\infty}(X)$. After taking a subsequence, we conclude that $v_{\gamma} \to v$ in $W^{2,2}(X)$. Taking the limit $\gamma \to 0$ in (5.3), it then follows that

(5.8)
$$\Delta v = \lim_{\gamma \to 0} \Delta v_{\gamma} = 0$$

and, therefore, v is a constant function since X is closed.

It is of great interest, as stated in [1], to study the upper bound of γ :

$$\gamma_0 = \frac{\beta}{4\pi(g+1)}$$

for (5.3) to be solvable, a quantity related to the geometry of X. It is not immediately clear whether $\gamma_0 \geq 1$, despite the explicit solution to (5.3) with $\gamma = 1$ in Section 4. One may attempt to construct a variation of (4.2) depending on γ , and its corresponding mean field equation so that the limiting solution at $\gamma = 0$ coincides with that of Theorem 5.2. Such a conjecture provides significant geometric insight. In the case of Example 4.2 where solutions are precisely the logarithm of Gaussian curvatures, the limiting solution suggests that the manifold deforms into \mathbb{S}^2 , a sign of topological jumps, or bubbling.

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3706

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