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THE TORSION OF A HOLLOW SQUARE*

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Summary. SEAC‡ is used to give an approximate solution to the torsion problem for a hollow square, with accurate determination of lower and upper bounds for torsional rigidity.

1. The torsion problem for a multiply connected cross section. To solve the torsion problem for a beam of multiply connected cross section, we seek a function $\psi(x, y)$ which is harmonic in the domain A occupied by the material, and such that

$$\psi = \frac{1}{2}r^2 \text{ on the outer boundary } B_0, \quad (1.1)$$

$$\psi = \frac{1}{2}r^2 + C_\lambda \text{ on the inner boundaries } B_\lambda,$$

the constants C_λ being chosen so that for each inner boundary we have

$$\int_{B_\lambda} \frac{\partial \psi}{\partial n} dB_\lambda = 0. \quad (1.2)$$

Here $r^2 = x^2 + y^2$, where x, y are rectangular Cartesian coordinates in the plane of the cross section.

The components of shearing stress are

$$\mu\alpha \frac{\partial}{\partial y} (\psi - \frac{1}{2}r^2), \quad -\mu\alpha \frac{\partial}{\partial x} (\psi - \frac{1}{2}r^2), \quad (1.3)$$

where μ is the rigidity and α the twist per unit length. The lines of stress are given by the equation

$$\psi - \frac{1}{2}r^2 = \text{const.}, \quad (1.4)$$

this family of curves including, of course, the curves B_0, B_λ .

The warping of the section is given by $\phi(x, y)$, which is the harmonic function conjugate to ψ .

If we denote the torque by $\mu\alpha\Gamma$, then

$$\Gamma = I - \int \left[\left(\frac{\partial \psi}{\partial x} \right)^2 + \left(\frac{\partial \psi}{\partial y} \right)^2 \right] dA, \quad (1.5)$$

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when I is the polar moment of inertia of the cross section,

$$I = \int (x^2 + y^2) dA. \tag{1.6}$$

2. The torsion of a hollow square. The method used below for solving approximately the torsion problem for a hollow square cross section is essentially the hypercircle method, originally developed by Prager and Synge¹ for more general problems in elasticity.

Details of the method will be found in a forthcoming book,² together with numerical results obtained by a desk calculator. The present paper is concerned with the application of SEAC to these calculations, and only essential formulas will be given to make the computations intelligible.

The method is applicable in principle to any cross section, and is particularly suited to a cross section which is a hollow rectangle or a hollow square. The only case treated here in detail is the case of a hollow square bounded externally by a square B_0 of side s and internally by a square B_1 of side $\frac{1}{2}s$, as shown in Fig. 1.

The square is triangulated as shown, a good approximation demanding a fine triangulation. We speak of approximation of order n when the outer side is divided into n equal parts. On account of symmetry, only an octant is needed in the calculations; Fig. 1 shows the triangulated octant MNZY for $n = 16$.

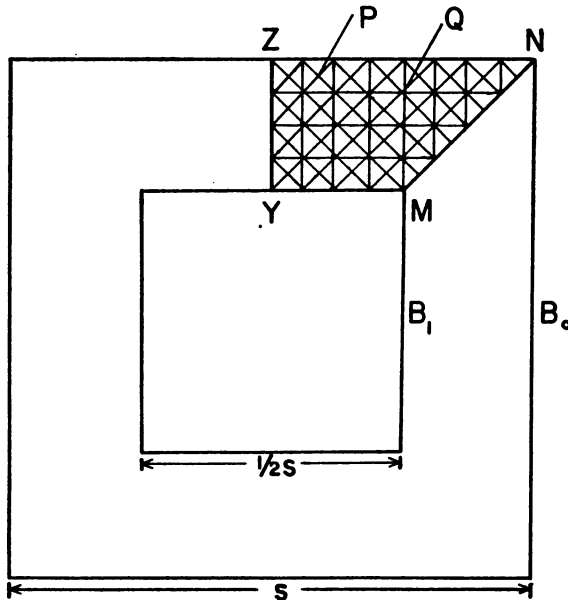


FIG. 1. Triangulation for the approximation $n = 16$.

Each junction in the triangulation is a "station." There are two types of station, type P at the centers of the small squares and type Q at the corners of these small squares.

¹W. Prager and J. L. Synge, *Quart. Appl. Math.* 5 (1947), 241-269.

²J. L. Synge, *The hypercircle in mathematical physics*, Cambridge University Press.

To each station we attach a "weight" w . These weights uniquely determine a function $f(x, y)$ in the domain A of the cross section, by the rule that $f(x, y) = w$ at each station and $f(x, y)$ is a linear function of x and y in each triangle.

The general plan of approximation is to find two sets of weights, say w' and w'' , such that if $f'(x, y)$ and $f''(x, y)$ are the corresponding functions, defined as above, then the following approximations hold:

$$\begin{aligned} f'(x, y) &\sim \psi - \frac{1}{2}r^2, \\ f''(x, y) &\sim \phi. \end{aligned} \tag{2.1}$$

This plan is slightly modified to permit dimensionless calculations, "reduced weights" b' , b'' being introduced.

3. Approximation for lines of stress, and lower bound for torsional rigidity. To approximate $\psi - \frac{1}{2}r^2$ we have to solve the following difference equations:

$$\begin{aligned} b'(P) &= \frac{1}{4} \sum b'(Q) - d(P) b'(R) + 1, \\ b'(Q) &= \frac{1}{4} \sum b'(P) - d(Q) b'(R) + 2, \\ b'(R) &= -\frac{4}{3n^2} \sum_{MN} [b'(P) + b'(Q)] + \frac{7n}{12}, \\ b'(Q) &= 0 \text{ for } Q \text{ on } B_0 \text{ or } B_1. \end{aligned} \tag{3.1}$$

Here $b'(P)$, $b'(Q)$ are reduced weights at stations P , Q . The interpretation of the first line of (3.1) is as follows: The \sum is a sum over the four stations Q which are neighbors of P . $d(P) = 1$ if P is on MN , and otherwise $d(P) = 0$. $b'(R)$ is an additional reduced weight, introduced to allow for multiple-connectivity. The interpretation of the second line of (3.1) is similar. Note that if Q is on B_0 or B_1 it lacks some of its four neighbors; in that case fictitious neighbors are supplied with zero weights. In the third line of (3.1) \sum_{MN} is summation along the diagonal MN of Fig. 1.

The weights $b'(P)$, $b'(Q)$ are symmetric with respect to the lines of symmetry of the hollow square.

The approximation to $\psi - \frac{1}{2}r^2$ is given by

$$\psi - \frac{1}{2}r^2 \sim \frac{1}{6} \frac{s^2}{n^2} F'(x, y) + \frac{1}{3} \frac{s^2}{n} b'(R) G(x, y), \tag{3.2}$$

where $F'(x, y)$ is a function which is linear in each triangle and takes, at the stations P , Q , the values $b'(P)$, $b'(Q)$, while $G(x, y)$ is a function which is linear in each of the four triangles in which the outer square is divided by its diagonals, with $G = 1$ at the center of the squares, and $G = 0$ on B_0 .

If we denote the torque by $\mu\alpha\Gamma$, then a lower bound for torsional rigidity is given by

$$\frac{\Gamma}{s^4} \geq \frac{1}{9n^4} \left[\sum b'(P) + 2 \sum b'(Q) \right] + \frac{7}{36n} b'(R), \tag{3.3}$$

these summations extending over the whole domain A , and not merely the octant $MNZY$.

4. Approximation for warping function, and upper bound for torsional rigidity. To approximate ϕ we have to solve

$$\begin{aligned}
 b''(P) &= \frac{1}{4} \sum b''(Q), \\
 b''(Q) &= \frac{1}{4} \sum b''(P) + m(Q).
 \end{aligned}
 \tag{4.1}$$

Here each summation is over four neighbors. If neighbors are lacking, i.e. when Q is on B_0 or B_1 , fictitious neighbors are to be added by reflection in B_0 or B_1 , the images having the same weights as the actual neighbors. The number $m(Q)$ is given by

$$\begin{aligned}
 m(Q) &= 0 \text{ if } Q \text{ is inside the domain } A, \\
 m(Q) &= 2x/s \text{ if } Q \text{ is on } B_0 \text{ (the outer boundary),} \\
 m(Q) &= -2x/s \text{ if } Q \text{ is on } B_1 \text{ (the inner boundary).}
 \end{aligned}
 \tag{4.2}$$

Here x is the abscissa of Q , the origin of coordinates being at the center of the squares. In this case the weights are skew-symmetric; therefore

$$b''(P) = 0, \quad b''(Q) = 0,
 \tag{4.3}$$

if P or Q is on a line of symmetry of the section.

The approximation to the warping function ϕ is given by

$$\phi \sim \frac{s^2}{4n} F''(x, y),
 \tag{4.4}$$

where $F''(x, y)$ is linear in each triangle and has the values $b''(P), b''(Q)$ at the stations P, Q .

An upper bound for the torsional rigidity is given by

$$\frac{\Gamma}{s^4} \leq \frac{1}{n^2} \left[\frac{5n^2}{32} - \sum_{ZN} m(Q)b''(Q) - \sum_{YM} m(Q)b''(Q) \right],
 \tag{4.5}$$

the summations being along ZN and YM in Fig. 1.

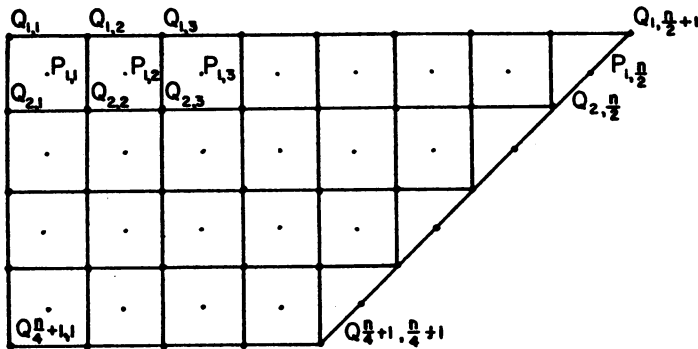


FIG. 2. Enumeration of stations for the approximation n (a multiple of 4)

5. Plan for SEAC calculations. For the approximation of order n , the stations were numbered as indicated in Fig. 2.¹ Then, using the letters P, Q, R for the reduced

¹The procedure may be applied with little additional complication, to the case where the ratio of the sides s, s' of the outer and inner squares is not 2:1. If it is possible to triangulate with n squares along s and n' squares along s' , then we make the following notational changes in Fig. 2:

$$\begin{aligned}
 Q_{(n/4)+1, 1} &\rightarrow Q_{(n-n')/2+1, 1} \\
 Q_{(n/4)+1, (n/4)+1} &\rightarrow Q_{(n-n')/2+1, (n'/2)+1}
 \end{aligned}$$

weights b' , we have, as in §3,

$$Q(x, y) = Q(y, x) = Q(-x, y) = Q(x, -y) = Q(-x, -y), \quad (5.1)$$

$$P(x, y) = P(y, x) = P(-x, y) = P(x, -y) = P(-x, -y), \quad (5.2)$$

$$R = -\frac{4}{3n^2} \sum_{MN} (P + Q) + \frac{7n}{12}, \quad (5.3)$$

$$P_{ij} = \frac{1}{4}(Q_{ij} + Q_{i,i+1} + Q_{i+1,i} + Q_{i+1,i+1}) + 1 - d(P_{ij})R, \quad (5.4)$$

$$Q_{ij} = \frac{1}{4}(P_{i-1,i-1} + P_{i-1,i} + P_{i,i-1} + P_{ij}) + 2 - d(Q_{ij})R, \quad (5.5)$$

$$d(X_{ij}) = \begin{cases} 1 & \text{if } X_{ij} \text{ sits on diagonal,} \\ 0 & \text{otherwise} \end{cases} \quad (5.6)$$

$$Q_{1j} = Q_{(n/4)+1,i} = 0. \quad (5.7)$$

The lower bound for Γ is given by

$$\left(\frac{\Gamma}{s^4}\right)_{LB} = \frac{1}{9n^4} \left\{ \sum_{ALL} (P + 2Q) + \frac{7}{36n} R \right\}. \quad (5.8)$$

Using P, Q for the reduced weights b'' , we have as in §4,

$$Q(x, y) = -Q(-x, y) = -Q(x, -y) = Q(-x, -y) = -Q(y, x), \quad (5.9)$$

$$P(x, y) = -P(-x, y) = -P(x, -y) = P(-x, -y) = -P(y, x). \quad (5.10)$$

For interior points,

$$P_{ij} = \frac{1}{4}(Q_{ij} + Q_{i,i+1} + Q_{i+1,i} + Q_{i+1,i+1}), \quad (5.11)$$

$$Q_{ij} = \frac{1}{4}(P_{i-1,i-1} + P_{i-1,i} + P_{i,i-1} + P_{ij}); \quad (5.12)$$

on the diagonal

$$P_{ii} = Q_{ij} = 0; \quad (5.13)$$

on the outer boundary B_0 ,

$$Q_{1j} = \frac{1}{2}(P_{1,i-1} + P_{1,i}) + \frac{2(j-1)}{n}, \quad (5.14)$$

$$Q_{11} = Q_{1,(n/2)+1} = 0;$$

on the inner boundary B_1 ,

$$Q_{(n/4)+1,i} = \frac{1}{2}(P_{(n/4),i-1} + P_{(n/4),i}) - \frac{2(j-1)}{n}, \quad (5.15)$$

$$Q_{(n/4)+1,1} = Q_{(n/4)+1,(n/4)+1} = 0;$$

on the vertical axis,

$$Q_{i1} = 0. \quad (5.16)$$

0	63	126	188	249	309	367	422	475	523	567	606	638	662	677	683	677	658	626	577	510	423	313	174	0
	30	88	147	204	261	316	368	418	465	507	544	575	600	616	622	618	602	573	528	467	387	285	158	0
0	55	110	164	217	268	318	366	410	451	487	517	541	558	566	563	550	524	484	428	354	260	143	0	
	26	76	127	176	225	272	317	359	398	433	463	487	504	512	512	501	478	442	391	324	238	131	0	
0	47	94	140	185	229	272	312	349	382	412	435	453	463	464	455	436	403	357	296	217	119	0		
	22	65	103	150	191	230	268	303	335	364	387	405	416	419	412	396	367	326	270	198	109	0		
0	39	79	117	155	192	228	261	291	319	342	360	372	376	372	358	334	297	246	181	100	0			
	18	54	89	124	158	190	222	250	277	299	317	330	336	334	323	302	269	224	165	91	0			
0	32	64	96	126	157	185	212	237	259	277	290	298	298	290	272	244	204	150	83	0				
	14	43	71	99	126	152	177	200	221	239	253	262	264	258	244	220	184	136	75	0				
0	25	50	74	98	122	145	166	186	203	217	227	231	228	217	197	166	123	68	0					
	11	32	53	74	95	115	135	153	169	183	194	200	199	191	175	148	111	62	0					
0	18	36	53	71	88	105	122	137	151	162	169	171	167	154	132	99	56	0						
	7	22	36	50	65	79	93	107	120	131	139	144	142	133	116	88	50	0						
0	11	22	33	44	55	67	78	90	101	110	116	118	113	100	77	44	0							
	4	11	18	26	34	43	52	62	71	81	89	94	93	84	67	39	0							
0	4	8	12	16	22	28	35	43	52	61	68	72	68	56	33	0								
	0	0	1	2	3	6	10	16	24	32	42	49	51	45	28	0								
0	-4	-7	-10	-12	-12	-12	-9	-4	3	13	24	32	32	22	0									
	-4	-11	-18	-24	-28	-32	-33	-31	-26	-17	-4	10	18	15	0									
0	-11	-22	-32	-41	-48	-54	-56	-55	-48	-35	-17	0	8	0										
	-7	-22	-36	-50	-62	-72	-80	-82	-80	-70	-51	-24	-3	0										
0	-19	-37	-55	-72	-86	-98	-107	-111	-107	-91	-59	-20	0											
	-11	-34	-56	-78	-97	-115	-129	-138	-141	-134	-110	-51	0											
0	-27	-54	-79	-104	-127	-147	-163	-173	-175	-164	-127	0												

TABLE III. Computation of upper bound in approximation $n = 48$. The numbers are solutions of Eq.(4.1), or equivalently (5.9) — (5.16), multiplied by 100 and rounded off, they represent approximate values of $100 \times [(4 \times 48)/s^2] \phi$.

The bounds on torsional rigidity, and the number of iterations required to give solutions to nine significant figures (starting from zero values) in the several approximations, are shown in Table IV.

TABLE IV
Lower and upper bounds for Γ/s^4

n	Lower Bound		Upper Bound		(U.B.)—(L.B.)		Number of Iterations	
	L.B.	U.B.	L.B.	U.B.	L.B.	U.B.	L.B.	U.B.
8	.1263	0626	.1320	1773	.0057	1147	50	60
16	.1282	4044	.1300	3396	.0017	9352	180	270
32	.1288	4044	.1294	2496	.0005	8452	680	1070
48	.1289	7704	.1292	8697	.0003	0993	1400	2200

In the approximation n , the number of simultaneous equations to be solved is $3n^2/16$ in the case of the lower bound, and one less in the case of the upper bound. Thus, for $n = 48$, there were 432 and 431 equations respectively.