

SPIN MATRIX EXPONENTIALS AND TRANSMISSION MATRICES*

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Abstract. The three Pauli spin matrices σ_i ($i = 1, 2, 3$) occur in the mechanical, especially quantum mechanical, theory of rotation in three-dimensional space. The three spin matrix exponentials are here defined as $\exp(\sigma_i x)$, where x is the independent variable. Transmission matrices can be expressed in terms of spin matrix exponentials, thereby permitting a more systematic treatment of transmission line circuits.

Introduction. In the design of quarter-wave transformers, it has hitherto always been assumed that the guide wavelength is independent of *position* along the line. This is so, for instance, for *TEM* modes; or for *TE_{0n}* modes in rectangular waveguide where the wide or 'a' dimension is kept constant. Such transformers, having guide wavelength independent of position, are called homogeneous transformers [1]. The first exact design formulas for ideal homogeneous quarter-wave transformers were given by Collin [2], who considered up to four sections. (The junction of two transmission lines when junction discontinuities are neglected, is called an "ideal transformer". This is analogous to two perfectly coupled coils of turns ratio $(Z_2/Z_1)^{1/2}$ and having infinite inductance.) The first complete synthesis procedure was given by Riblet [3]. The author later computed extensive numerical tables [4], which have been checked out experimentally on numerous occasions.

Riblet's synthesis procedure [3] is based on Richards' transformation [5] and Richards' theorem [6], and thereby depends on the commensurability of all transmission line sections in the circuit. The homogeneous quarter-wave transformer has also been used as a prototype circuit in the design of direct-coupled-cavity filters [7].

It has been shown that the performance of single-section quarter-wave transformers can always be improved by going from a homogeneous to an inhomogeneous design [8]. The analysis of inhomogeneous transformers of more than one section has only recently been undertaken [9], and the purpose of this paper is to present the mathematical tools which were developed for this purpose. A separate paper will deal with the design considerations and numerical results for multi-section inhomogeneous quarter-wave transformers [21].

Spin matrix exponentials. With line-lengths no longer commensurable, a more general formulation than is possible by Richards' transformation is required. For a systematic and compact treatment of transmission matrices, we shall employ the three Pauli spin matrices [10], which may be represented as follows:

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$$\left. \begin{aligned} \sigma_1 &= \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \\ \sigma_2 &= j \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \\ \sigma_3 &= \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \end{aligned} \right\}. \quad (1)$$

They anti-commute among themselves, and their squares are equal to unity:

$$\left. \begin{aligned} \sigma_1\sigma_2 &= -\sigma_2\sigma_1 = j\sigma_3 \\ \sigma_2\sigma_3 &= -\sigma_3\sigma_2 = j\sigma_1 \\ \sigma_3\sigma_1 &= -\sigma_1\sigma_3 = j\sigma_2 \\ \sigma_1^2 &= \sigma_2^2 = \sigma_3^2 = I, \end{aligned} \right\} \quad (2)$$

where I is the unit matrix (idemfactor). We define the "spin matrix exponentials" by

$$E_i(x) = \exp(x\sigma_i) = I \cosh x + \sigma_i \sinh x \quad (i = 1, 2, 3) \quad (4)$$

and their derivatives by

$$\left. \begin{aligned} E'_i(x) &= \frac{d}{dx} E_i(x) = \sigma_i \exp(x\sigma_i) \\ &= \sigma_i E_i(x) = I \sinh x + \sigma_i \cosh x \quad (i = 1, 2, 3) \end{aligned} \right\}. \quad (5)$$

They do not commute among themselves unless i is the same, and then they commute and behave like ordinary exponentials:

$$E_i(x)E_i(y) = E_i(x + y). \quad (6)$$

Also,

$$E_i(x)\sigma_i = \sigma_i E_i(x) \quad (7)$$

but

$$E_i(x)\sigma_j = \sigma_j E_i(-x), \quad i \neq j. \quad (8)$$

Similarly,

$$E'_i(x)E'_i(y) = E'_i(x + y), \quad (9)$$

$$E'_i(x)\sigma_i = \sigma_i E'_i(x), \quad (10)$$

$$E'_i(x)\sigma_j = -\sigma_j E'_i(-x), \quad i \neq j. \quad (11)$$

Spin matrix exponentials occur in the mechanical (especially quantum mechanical) theory of rotation in three-dimensional space [11, 12]. The matrix product

$$Q = E_3\left(\frac{j\psi}{2}\right)E_1\left(\frac{j\theta}{2}\right)E_3\left(\frac{j\phi}{2}\right), \quad (12)$$

where θ , ϕ , ψ are the three Eulerian angles, yields a matrix whose four elements are the Cayley-Klein parameters [11]. At this point, we anticipate in order to complete the analogy: it will be seen later that Eq. (12) is like the transfer matrix of a single-section ideal transformer. This is not altogether surprising, since geometrical analogies have

been developed before [13, 14, 15], and projective charts have been used for the numerical solution of transmission line problems. The spinor theory of two-ports and its geometrical interpretation has also been discussed in general terms by Payne [16].

The Pauli spin matrices, together with the unit matrix, can be used to express any matrix [17] in the form of a quaternion, but the resulting more general form does not have the simplicity of the spin matrix exponentials which are well-suited for the analytic description and solution of inhomogeneous transformers.

The transfer matrix. There is no uniform terminology for the transformation matrices [18-20] which are used to analyze two-ports. The matrix defined by

$$\begin{bmatrix} a_1 \\ b_1 \end{bmatrix} = \mathbf{T} \begin{bmatrix} a_2 \\ b_2 \end{bmatrix}, \tag{13}$$

where a_1, b_1 are the incident and reflected wave amplitudes at the input, and a_2, b_2 those at the output (Fig. 1), will be referred to as the transfer matrix. As only lossless two-ports are here considered, wave amplitudes may be defined in terms of power by

$$\left. \begin{aligned} |a|^2 &= \text{power flow in the forward direction} \\ &\quad (\text{i.e. towards the load}) \\ |b|^2 &= \text{power flow in the backward direction} \\ &\quad (\text{i.e. towards the generator}) \end{aligned} \right\} \tag{14}$$

The transmission coefficient, T , between two reference planes is the same (in both phase and amplitude) when going from left to right as when going from right to left. The transfer matrix can then be written [18]

$$\mathbf{T} = \begin{bmatrix} \frac{1}{T} & -\frac{\Gamma_2}{T} \\ \frac{\Gamma_1}{T} & T - \frac{\Gamma_1 \Gamma_2}{T} \end{bmatrix}, \tag{15}$$

where T is the (unique) transmission coefficient, Γ_1 is the reflection coefficient seen at the input (on the left) when a matched load is placed at the output (on the right), and Γ_2 is similarly defined for the output side.

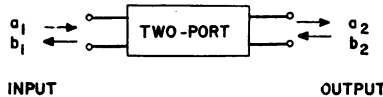
We may, by appropriate choice of reference planes, let

$$\Gamma_1 = -\Gamma_2 = \Gamma \quad (\text{say}). \tag{16}$$

From energy considerations:

1. Let $b_2 = 0$ in Fig. 1. Then

$$|\Gamma|^2 + |T|^2 = 1. \tag{17}$$



$$\begin{pmatrix} a_1 \\ b_1 \end{pmatrix} = \mathbf{T} \begin{pmatrix} a_2 \\ b_2 \end{pmatrix}$$

FIG. 1. Defining the transfer matrix.

2. Let $a_2 = 0$ in Fig. 1. Then

$$|T^2 + \Gamma^2| = 1. \quad (18)$$

Comparing Eqs. (17) and (18), we infer that, under the condition (16), the transmission coefficient vector is parallel to the reflection coefficient vector [22]:

$$T \text{ parallel to } \Gamma. \quad (19)$$

Now further choose the reference planes so that

$$\Gamma = \text{real}. \quad (20)$$

The transfer matrix then reduces to:

$$\mathbf{T} = \frac{1}{T} \begin{pmatrix} 1 & \Gamma \\ \Gamma & 1 \end{pmatrix}. \quad (21)$$

The diagonal and anti-diagonal parts of \mathbf{T} . From Eq. (15) it follows that for a reflectionless two-port, \mathbf{T} must be a diagonal matrix. Let

$$\mathbf{T} = \begin{pmatrix} T_{11} & T_{12} \\ T_{21} & T_{22} \end{pmatrix}. \quad (22)$$

Two useful concepts are

$$Di(\mathbf{T}) = \begin{pmatrix} T_{11} & 0 \\ 0 & T_{22} \end{pmatrix} \quad (23)$$

= diagonal part of \mathbf{T}

$$Ag(\mathbf{T}) = \begin{pmatrix} 0 & T_{12} \\ T_{21} & 0 \end{pmatrix} \quad (24)$$

= anti-diagonal part of \mathbf{T} .

For zero reflection,

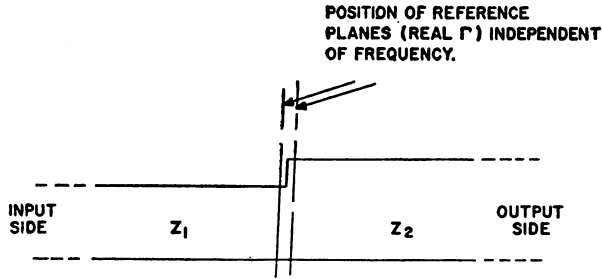
$$Ag(\mathbf{T}) = 0. \quad (25)$$

The ideal transformer. The magnitude of the reflection coefficient at an ideal transformer (Fig. 2) is

$$|\Gamma| = \left| \frac{Z_2 - Z_1}{Z_2 + Z_1} \right|. \quad (26)$$

Select both reference planes to be coincident in the plane of the junction itself, and choose Γ to be real. This satisfies Eqs. (16) and (20) and therefore leads to the form (21) for the transfer matrix. Γ is now determined except for sign. In agreement with Ref. [4], we (arbitrarily) pick the positive sign and let

$$\Gamma = \frac{Z_2 - Z_1}{Z_2 + Z_1}. \quad (27)$$



Z_1, Z_2 : CHARACTERISTIC IMPEDANCES.

FIG. 2. Ideal transformer.

Defining the “junction *VSWR*” by

$$V = \frac{Z_2}{Z_1} \tag{28}$$

and the “log ratio” by

$$\alpha = \frac{1}{2} \ln V \tag{29}$$

the transfer matrix (21) of the ideal transformer reduces to

$$\mathbf{T} = E_1(\alpha) \tag{30}$$

which is the first spin matrix exponential as a function of the log ratio, α , of the junction.

$$\text{Also } \Gamma = \tanh \alpha, \tag{31}$$

and since Γ is real,

$$T = (1 - \Gamma^2)^{1/2} = \text{sech } \alpha. \tag{32}$$

Length of transmission line. A section of transmission line of electrical length θ radians (Fig. 3) has a transfer matrix

$$\mathbf{T} = E_3(j\theta) \tag{33}$$

which is the third spin matrix exponential of imaginary argument $j\theta$.

The ABCD matrix. The ABCD matrix of an ideal transformer is

$$\mathbf{A} = E_3(\alpha) \tag{34}$$

and that of a length of transmission line is

$$\mathbf{A} = E_1(j\theta). \tag{35}$$

The transition between transfer and *ABCD* matrices has thus been effected merely by interchanging suffixes of the first and third spin matrix exponentials.

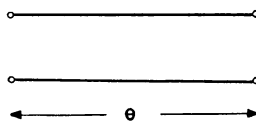


FIG. 3. Section of transmission line.

Conclusion. The spin matrix exponentials $\exp(\sigma_i x)$, where x is either $j\theta$ ($\theta =$ electrical line length) or the log ratio of a transformer, represent the transformation matrices of line sections and transformer steps. They are useful in the treatment of transmission line transformers, particularly inhomogeneous transformers, where the line lengths are incommensurable and Richards' transformation then does not apply [21].

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