

## ON THE BREAKING OF WATER WAVES ON A SLOPING BEACH OF ARBITRARY SHAPE\*

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**Summary.** Greenspan [1] considered water waves of finite amplitude on a beach of *constant* slope. He proved that: ( $G_1$ ) A wave of elevation with nonzero slope at the front propagating shoreward into quiescent water always breaks before the shore.<sup>†</sup> ( $G_2$ ) Under the same conditions a wave of depression never breaks.

In this note we do not assume that the beach has constant slope, but rather we allow the depth to be an *arbitrary* smooth function of position. We show that the appropriate generalizations of Greenspan's results are: ( $G_1'$ ) In the above circumstances a wave of elevation always breaks; in particular, it breaks at the shore when the amplitude is sufficiently small, otherwise it breaks before the shore. ( $G_2'$ ) A wave of depression breaks if and only if a certain integral (involving only the depth function) is finite, and it never breaks away from shore.

**Analysis.** The conservation equations for mass and momentum in the (nonlinear) theory of shallow water are (see Stoker [3]):

$$\eta_t + \{v(\eta + h)\}_x = 0, \quad v_t + vv_x + g\eta_x = 0, \quad (1)$$

where  $h(x) + \eta(x, t)$  is the depth of the water,  $h(x)$  is the undisturbed depth ahead of the wave,  $v(x, t)$  is the (particle) velocity, and  $g$  is the gravitational acceleration. We assume, in what follows, that  $h(x)$  is continuously differentiable.

We now consider a wave front which at time  $t = 0$  occupies the position  $x = 0$  and which is propagating in the direction of increasing  $x$ . We assume that across the front:

(a)  $v$  and  $\eta$  are continuous;

(b) the first and second derivatives of  $v$  and  $\eta$  suffer (at most) jump discontinuities.

We assume further that the region ahead of the wave is quiescent, so that

(c)  $v(x, t) = \eta(x, t) = 0$  for  $0 \leq t \leq \hat{t}(x)$ ,

where  $\hat{t}(x)$  is the time at which the wave passes the point  $x$ . Note that conditions (a) and (b) assert that the front is an acceleration wave.

Given a function  $f(x, t)$ , we write

$$f^-(x) = \lim_{t \downarrow \hat{t}(x)} f(x, t) \quad (2)$$

for the value of  $f$  immediately behind the wave. Then (a) and (c) imply that

$$v^- = \eta^- = 0, \quad (3)$$

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<sup>†</sup> Cf. Carrier and Greenspan [2], who established the existence of waves of elevation with zero slope at the front which do *not* break.

while (a)–(c) and Maxwell's Theorem (see, e.g., Truesdell and Toupin [4], Sec. 175) yield the compatibility relations

$$c(v_x)^- = -(v_t)^-, \quad c(\eta_x)^- = -(\eta_t)^-, \quad (4)$$

where

$$c = \left( \frac{dt}{dx} \right)^{-1} \quad (5)$$

is the *velocity* of the front. If we evaluate (1) just behind the wave, we conclude, with the aid of (3), that

$$(\eta_t)^- = -h(v_x)^-, \quad (v_t)^- = -g(\eta_x)^-. \quad (6)$$

If we assume that  $(\eta_x)^- \neq 0$ , then (4) and (6) yield the following well-known formula for the velocity  $c$ :

$$c = (gh)^{1/2}. \quad (7)$$

Our next step will be to establish an explicit expression for the *amplitude*

$$a = a(x) = (\eta_x)^-. \quad (8)$$

By (4), (6), and (8),

$$(v_t)^- = -ga, \quad (v_x)^- = ga/c. \quad (9)$$

If we differentiate (1)<sub>1</sub> with respect to  $x$  and (1)<sub>2</sub> with respect to  $t$ , and evaluate the resulting relations immediately behind the wave, we find, using (3) and (7)–(9), that

$$c^2(v_{xx})^- - (v_{tt})^- + \frac{2g^2h_x}{c}a + \frac{3g^2}{c}a^2 = 0. \quad (10)$$

Next, by (2) and (5),

$$\frac{d}{dx}(v_x)^- = (v_{xx})^- + \frac{1}{c}(v_{xt})^-, \quad \frac{d}{dx}(v_t)^- = (v_{tx})^- + \frac{1}{c}(v_{tt})^-,$$

so that

$$c^2 \frac{d}{dx}(v_x)^- - c \frac{d}{dx}(v_t)^- = c^2(v_{xx})^- - (v_{tt})^-. \quad (11)$$

Eqs. (7) and (9)–(11) yield the following differential equation for  $a$ :

$$\frac{da}{dx} + \frac{3h_x}{4h}a + \frac{3}{2h}a^2 = 0. \quad (12)$$

To solve this equation one notes that the substitution  $a = b^{-1}$  yields a linear differential equation for  $b$ . This equation is easily solved; the solution in terms of the amplitude  $a$  is

$$a(x) = \frac{\left( \frac{h_0}{h(x)} \right)^{3/4}}{\frac{1}{a_0} + I(x)}, \quad (13)$$

where  $a_0 = a(0)$  and  $h_0 = h(0)$  are the initial amplitude and the initial depth, and

$$I(x) = \frac{3h_0^{3/4}}{2} \int_0^x h^{-7/4}. \quad (14)$$

**Results.** We now assume that the front is propagating up a sloping beach with shore at  $x = l$ , so that  $h(x) > 0$  for  $0 \leq x < l$  and

$$h(l) = 0. \quad (15)$$

We use the following terminology: the front corresponds to a wave of *elevation* (respectively, *depression*) if  $a_0 < 0$  (respectively,  $a_0 > 0$ ); the wave *breaks* if  $a(x)$  becomes infinite at some point  $x$ . It is clear from (14) and the assumption containing (15) that  $I(l) = \infty$  is a distinct possibility; when this is the case we define  $1/I(l) = 0$ . We are now in a position to state our main result; in the statement of this theorem conditions (a)–(c) are tacitly assumed to hold.

*A wave of elevation always breaks. In particular, the wave breaks before the shore when  $|a_0| > 1/I(l)$ , at the shore when  $|a_0| \leq 1/I(l)$ .*

*A wave of depression propagating up a beach for which  $I(l) < \infty$  always breaks, but at the shore. On the other hand, when  $I(l) = \infty$  a wave of depression never breaks.*

This theorem is an immediate consequence of (13) and (14). Indeed, by the assumption containing (15) the numerator in (13) is strictly positive on  $[0, l)$  and tends to infinity as  $x \rightarrow l$ . The results for waves of elevation are consequences of this remark and the following facts: the denominator is strictly negative at  $x = 0$  and increases monotonically as  $x$  increases; the denominator vanishes for  $x < l$  if and only if  $|a_0| > 1/I(l)$ . On the other hand, for a wave of depression the denominator is strictly positive at  $x = 0$ , increases as  $x$  increases, and is finite on  $[0, l)$ . Thus  $a(x)$  is finite for  $0 \leq x < l$ . If  $I(l) < \infty$ , then  $a(x) \rightarrow \infty$  as  $x \rightarrow l$  and the wave breaks at the shore. If  $I(l) = \infty$  both the numerator and the denominator tend to infinity as  $x \rightarrow l$ , but an application of L'Hospital's rule shows that

$$a(x) \rightarrow -\frac{1}{2}h_x(l) \quad \text{as } x \rightarrow l,$$

and the wave does not break. This completes the proof.

Assume now that near the shore  $h$  behaves like  $h_0(1 - x/l)^p$ ; i.e.,

$$\lim_{x \rightarrow l} \frac{h(x)}{h_0 \left(1 - \frac{x}{l}\right)^p} = 1 \quad (\text{for some } p > 0).$$

Then the integral  $I$ , defined in (14), is convergent or divergent according as  $p < \frac{4}{7}$  or  $p \geq \frac{4}{7}$ . Thus in the present circumstances the second portion of the theorem can be restated as follows: a wave of depression breaks if and only if the beach is sufficiently deep near shore.

In view of the above remarks,  $I(l) = \infty$  when the beach has constant slope; thus as a corollary of our theorem we have Greenspan's [2] result: for a linear beach a wave of elevation always breaks before the shore, a wave of depression never breaks.

#### REFERENCES

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