

SPATIAL DISCRETIZATION OF THE DUSTY GAS EQUATIONS

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Abstract. In this article we consider a semi-discretization of the dusty gas equations corresponding to a spatial discretization by finite differences or pseudo-spectral methods and discuss the stability and well-posedness of the corresponding system of ordinary equations.

We will present elsewhere the study of the fully discretized equations (discretization in space and time) as well as some elements of the mathematical theory of the equations (existence and uniqueness of solutions).

1. Introduction. The dusty gas equations are used to describe infiltration processes needed for the manufacturing of a variety of materials. In those techniques a fluid phase (i.e., a gas or a liquid) is transported into a porous structure, where it then reacts to form a solid product. These methods are particularly important for producing composite materials, where the initial porous form is composed of the reinforcement phase (i.e., fibers, whiskers, or particles) and infiltration produces the matrix (see, e.g., [2] and the references therein).

For the mathematical modelling we consider the domain Ω filled by the mixtures, and denote by C_1, \dots, C_s the concentrations of these mixtures that are functions of space and time, $C_i = C_i(x, t)$. These concentrations are governed by the equations (2.2)–(2.5). Instead of introducing the thermohydraulics equations, we assume for the sake of simplicity that the pressure p and the temperature T are known (see (2.1)). The equations for the C_i are supplemented by boundary conditions, and, for more generality, we consider here three different boundary conditions on $\partial\Omega$, namely the Dirichlet, Neumann, and space-periodicity boundary conditions.

Equations (2.2)–(2.5) are classical equations of chemical dynamics and they appear in other areas of sciences, e.g., in combustion [9]. These equations are highly nonlinear and,

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to the best of our knowledge, much remains to be done for their mathematical theory, on questions of existence and uniqueness of solutions.¹ Because of the practical importance of these equations, we nevertheless tackle some issues concerning their discretization and numerical analysis here. Namely, we consider the space discretizations of these equations by either finite differences or spectral methods (Fourier or Legendre, depending on the type of boundary conditions used). We describe very precisely the corresponding discretizations of the equations leading to systems of ordinary differential equations. We then establish estimates on the solutions of these equations which, on one hand, prove existence for all time and, on the other hand, prove the stability of the discretization procedures (stability in the sense of numerical analysis). To the best of our knowledge, this is the first time that such a study is conducted for such highly nonlinear equations.

In a following subsequent article [3], we will study the one-dimensional case in more detail. We also hope to address subsequently the question of space and time discretizations which should hinge on further new tools.

2. Presentation of the problem. We consider S different chemical species contained in a region $\Omega \subset \mathbb{R}^d$, $d = 2$ or 3 . We denote by M_i the molecular mass of species i and by C_i its molecular concentration. The total number of molecules of species i per unit spatial volume at (x, t) is denoted by $\nu_i = \nu_i(x, t)$ and $C_i = \nu_i \mathcal{A}$, where \mathcal{A} is the Avogadro number; the density ρ_i of species i (mass per unit volume) is $\rho_i = M_i \nu_i = M_i C_i \mathcal{A}$ and $\rho = \sum_{i=1}^S \rho_i$ is the density of the mixture.

We denote by $p = p(x, t)$ and $T = T(x, t)$ the pressure and temperature of the mixture which are assumed to be given and satisfy

$$\begin{aligned} 0 \leq \underline{p} \leq p(x, t) \leq \bar{p}, \\ 0 \leq \underline{T} \leq T(x, t) \leq \bar{T}, \quad \forall x \in \Omega, \quad \forall t > 0. \end{aligned} \tag{2.1}$$

Let N_i denote the flux vector of species i , so that N_i/C_i is its relative velocity (velocity relative to the mixture). We then obtain the equation governing the motion of the species, directly related to the conservation of mass equation of the species (see, e.g., [1], [8]):

$$\frac{\partial C_i}{\partial t} + \nabla N_i = \omega_i. \tag{2.2}$$

Here ω_i is the rate of production of the i th species given by the Arrhenius law; it depends on the temperature and is a polynomial function of the C_i . Conservation of mass requires that

$$\sum_{i=1}^S \frac{\omega_i}{M_i} = 0. \tag{2.3}$$

We will also assume that

$$|\omega_i(T, C_1, \dots, C_s)| \leq \kappa_1 + \kappa_2(C_1 + \dots + C_s), \tag{2.4}$$

although this simplifying assumption is not essential.

¹See, however, many relevant results in [4].

Finally the N_i are related to the C_j and ∇C_j by the following relations, sometimes called the Stefan-Maxwell equations:

$$\begin{aligned}
 d_i N_i + \frac{\mathcal{R}T}{p} \sum_{\substack{j=1 \\ j \neq i}}^S d_{ij} (C_j N_i - C_i N_j) \\
 = -\nabla C_i - d_i C_i g \nabla p, \quad i = 1, \dots, S.
 \end{aligned}
 \tag{2.5}$$

Here d_i, d_{ij} are positive coefficients, \mathcal{R} is the perfect gas constant, and g is a given constant.

The system (2.5) will be analyzed when considered as a linear system for the N_i (giving the N_i in terms of the ∇C_j , the C_j , and the other functions, p, T).

We supplement these equations with one of the following boundary conditions:

Space periodicity: Ω is the 2 or 3D rectangle
 $(0, L_1) \times (0, L_2)$ or $(0, L_1) \times (0, L_2) \times (0, L_3)$,
 and each C_i $i = 1, \dots, S$ is periodic (with period L_j
 in the direction x_j , $j = 1, 2, 3$).

$$\tag{2.6a}$$

No flux boundary condition

$$\frac{\partial C_i}{\partial \mathbf{n}} = 0 \text{ on } \Gamma = \partial\Omega, \quad i = 1, \dots, S,$$

$$\tag{2.6b}$$

where \mathbf{n} is the unit outward normal on Γ .

Dirichlet boundary condition,

$$C_i = C_{ib} \text{ on } \partial\Omega, \quad i = 1, \dots, S,$$

$$\tag{2.6c}$$

where each C_{ib} is a regular function prescribed and > 0 on $\partial\Omega$, and arbitrarily extended inside Ω as a regular positive function.

Our aim in this article is to discuss the spatial discretization of the initial and boundary value problem consisting of (2.2), (2.5), (2.6) and the initial conditions

$$C_i(x, 0) = C_{ib}(x), \quad x \in \Omega, \quad i = 1, \dots, S.$$

$$\tag{2.7}$$

3. Formal a priori estimates. Assuming that all C_i 's are positive everywhere and that all functions C_i, N_i are sufficiently regular, we derive some a priori estimates for the solution C_i of (2.2)–(2.6). In Sections 3 and 4, discretized versions of these estimates will be used to establish the stability of the discretized equations. We treat the three boundary conditions (2.6 a,b,c), which necessitate some slight changes in the proofs. Finally at the end of this section we show how to guarantee the positivity of the C_i .

3.1. *The linear system (2.5).* Equations (2.5) are to be considered as an algebraic linear system (S equations, S unknowns), which determine at each point x, t the fluxes $N_i = N_i(x, t)$ in terms of the other quantities in (2.5).

We rewrite (2.5) in the form

$$\begin{aligned} d_i C_i \frac{N_i}{C_i} + \frac{\mathcal{R}T}{p} \sum_{\substack{j=1 \\ j \neq i}}^S d_{ij} C_i C_j \left(\frac{N_i}{C_i} - \frac{N_j}{C_j} \right) \\ = -\nabla C_i - d_i C_i g \nabla p, \end{aligned} \quad (3.1)$$

equivalent to the linear system

$$\tilde{\mathcal{B}} \tilde{\mathcal{N}} = \mathcal{G}, \quad (3.2)$$

where $\tilde{\mathcal{N}} = (\tilde{N}_1, \dots, \tilde{N}_S)$, $\tilde{N}_i = N_i/C_i$, $\mathcal{G} = (G_1, \dots, G_S)$, $G_i = -\nabla C_i - d_i C_i g \nabla p$, and the matrix $\tilde{\mathcal{B}}$ reads

$$\begin{aligned} \tilde{\mathcal{B}}_{ij} &= -\frac{\mathcal{R}T}{p} d_{ij} C_i C_j, \text{ for } i \neq j, \\ \tilde{\mathcal{B}}_{ii} &= d_i C_i + \frac{\mathcal{R}T}{p} \sum_{\substack{j=1 \\ j \neq i}}^S d_{ij} C_i C_j. \end{aligned}$$

The matrix $\tilde{\mathcal{B}}$ is symmetric positive definite; the positivity follows immediately from the Gershgorin theorem. Hence, solving (3.1), we obtain

$$\begin{aligned} \text{The } N_i \text{ are linear functions of } \nabla p \text{ and the} \\ \nabla C_j, \text{ the coefficients being rational functions of} \\ p, T, \text{ and all the } C_k \text{ (and the coefficients } d_i, R, d_{ij}). \end{aligned} \quad (3.3)$$

Let us make further comments depending on the boundary conditions:

- In the periodic case (2.6a), we naturally assume that

$$p, T \text{ are periodic functions (with period } L_j \text{ in direction } x_j). \quad (3.4)$$

Then, since C_j and ∇C_j are assumed to be periodic by (2.6a), the resolution of the system (2.5) or (3.1) shows that

$$\begin{aligned} \text{The } N_i \text{ are periodic with period } L_j \text{ in direction } x_j, \quad j = 1, 2, 3, \\ i = 1, \dots, S. \end{aligned} \quad (3.5)$$

- In the case of the no-flux (Neumann) boundary condition (2.6b), we naturally assume that

$$\frac{\partial p}{\partial \mathbf{n}} = 0 \text{ on } \Gamma. \quad (3.6)$$

Then multiplying equations (3.1) by \mathbf{n} , for $x \in \Gamma$, we find that

$$G_i \cdot \mathbf{n} = -\frac{\partial C_i}{\partial \mathbf{n}} - d_i g C_i \frac{\partial p}{\partial \mathbf{n}} = 0,$$

so that

$$N_i \cdot \mathbf{n} = 0 \text{ on } \Gamma, \quad i = 1, \dots, S. \quad (3.7)$$

We have no particular remark concerning this system in the case (2.6c) (Dirichlet boundary condition).

3.2. *A priori estimates.* Assuming that the C_i are everywhere positive and smooth, a priori estimates are obtained by multiplying Eq. (2.2) by $\log C_i$, integrating over Ω , and adding these equations for $i = 1, \dots, S$. We observe that

$$\log C_i \frac{\partial C_i}{\partial t} = \frac{\partial}{\partial t} (C_i \log C_i - C_i + 2);$$

the constant 2 has been chosen so that the expression between parentheses is bounded from below by a positive number (namely 1). Also

$$\int_{\Omega} \nabla N_i \log C_i dx = \int_{\partial\Omega} N_i \cdot \mathbf{n} \log C_i dx - \int_{\Omega} N_i \frac{\nabla C_i}{C_i} dx.$$

The integral over $\partial\Omega$ vanishes for both boundary conditions (2.6a) and (2.6b): for (2.6a) by periodicity, for (2.6b) because of (3.7); the Dirichlet boundary conditions (2.6c) will be examined later. There remains, after using (3.1) and summing in i :

$$\begin{aligned} & \sum_{i=1}^S \int_{\Omega} d_i \frac{N_i^2}{C_i} dx + \sum_{\substack{i,j=1 \\ i \neq j}}^S \int_{\Omega} \frac{\mathcal{R}T}{p} d_{ij} C_j C_j \left(\frac{N_i}{C_i} - \frac{N_j}{C_j} \right) \frac{N_i}{C_i} dx \\ & + \sum_{i=1}^S \int_{\Omega} d_i N_i g \nabla p dx \\ & = \sum_{i=1}^S \int_{\Omega} d_i \frac{N_i^2}{C_i} dx + \sum_{\substack{i,j=1 \\ i \neq j}}^S \int_{\Omega} \frac{\mathcal{R}T}{2p} d_{ij} C_i C_j \left(\frac{N_i}{C_i} - \frac{N_j}{C_j} \right)^2 dx \\ & + \sum_{i=1}^S \int_{\Omega} d_i N_i g \nabla p dx \\ & \geq \frac{1}{2} \sum_{i=1}^S \int_{\Omega} d_i \frac{N_i^2}{C_i} dx + \sum_{\substack{i,j=1 \\ i \neq j}}^S \int_{\Omega} \frac{\mathcal{R}T}{2p} d_{ij} C_i C_j \left(\frac{N_i}{C_i} - \frac{N_j}{C_j} \right)^2 dx \\ & - \frac{1}{2} \sum_{i=1}^S \int_{\Omega} C_i d_i |g \nabla p|^2 dx. \end{aligned} \tag{3.8}$$

Finally

$$\begin{aligned} & \frac{d}{dt} \sum_{i=1}^S \int_{\Omega} (C_i \log C_i - C_i + 2) \\ & + \frac{1}{2} \sum_{i=1}^S \int_{\Omega} d_i \frac{N_i^2}{C_i} dx \\ & + \frac{1}{2} \sum_{\substack{i,j=1 \\ i \neq j}}^S \int_{\Omega} \frac{\mathcal{R}T}{2p} d_{ij} C_i C_j \left(\frac{N_i}{C_i} - \frac{N_j}{C_j} \right)^2 dx \\ & \leq \frac{1}{2} \sum_{i=1}^S \int_{\Omega} C_i d_i |g \nabla p|^2 dx + \sum_{i=1}^S \int_{\Omega} \omega_i \log C_i dx. \end{aligned} \tag{3.9}$$

Upon using (2.1) and (2.4), we see that

$$\frac{d}{dt} \Phi \leq \kappa_3 \Phi, \tag{3.10}$$

for some suitable constant κ_3 , where

$$\Phi = \Phi(C_1, \dots, C_s) = \sum_{i=1}^S \int_{\Omega} (C_i \log C_i - C_i + 2) dx. \tag{3.11}$$

From (3.11) follows the a priori estimate

$$\Phi(t) \leq \Phi(0)e^{\kappa_3 T}, \tag{3.12}$$

valid for $0 \leq t \leq T$. Further estimates can be derived from (3.9), but they will not be used here.

3.3. *Dirichlet boundary condition.* A similar result is valid in the case of the Dirichlet boundary condition, but the proof must be slightly modified. Instead of multiplying (2.2) by $\log C_i$, we multiply this equation by $\log(C_i/C_{ib})$. The first term gives

$$\begin{aligned} & \int_{\Omega} \frac{\partial C_i}{\partial t} (\log C_i - \log C_{ib}) \\ &= \frac{d}{dt} \int_{\Omega} (C_i \log C_i - C_i + P - C_i \log C_{ib}) dx \\ &+ \int_{\Omega} \frac{C_i}{C_{ib}} \frac{\partial C_{ib}}{\partial t} dx. \end{aligned} \tag{3.13}$$

Denoting by \bar{C}_{ib} the maximum of C_{ib} ($x \in \Omega, t \in [0, T]$), we now choose the constant P so that

$$C \log C - C + P - C \log \bar{C}_{ib} \geq 0, \quad \forall C \geq 0. \tag{3.14}$$

The term ∇N_i now yields:

$$\begin{aligned} & \int_{\Omega} \nabla N_i \log \frac{C_i}{C_{ib}} dx \\ &= \int_{\partial\Omega} N_i \cdot \mathbf{n} \log \frac{C_i}{C_{ib}} dx - \int_{\Omega} N_i \left(\frac{\nabla C_i}{C_i} - \frac{\nabla C_{ib}}{C_{ib}} \right) dx. \end{aligned} \tag{3.15}$$

The term on $\partial\Omega$ vanishes. We then proceed as before and we obtain

$$\begin{aligned} & \sum_{i=1}^S \int_{\Omega} d_i \frac{N_i^2}{C_i} dx + \sum_{\substack{i,j=1 \\ i \neq j}}^S \int_{\Omega} \frac{\mathcal{R}T}{\rho} d_{ij} C_i C_j \left(\frac{N_i}{C_i} - \frac{N_j}{C_j} \right) \frac{N_i}{C_i} dx \\ &+ \sum_{i=1}^S \int_{\Omega} N_i \left(d_i g \nabla p + \frac{\nabla C_{ib}}{C_{ib}} \right) dx \\ &\geq \frac{1}{2} \sum_{i=1}^S \int_{\Omega} d_i \frac{N_i^2}{C_i} dx + \sum_{\substack{i,j=1 \\ i \neq j}}^S \int_{\Omega} \frac{\mathcal{R}T}{p} d_{ij} C_i C_j \left(\frac{N_i}{C_i} - \frac{N_j}{C_j} \right)^2 dx \\ &- \frac{1}{2} \sum_{i=1}^S \int_{\Omega} C_i d_i \left(g \nabla p + \frac{\nabla C_{ib}}{C_{ib}} \right)^2 dx. \end{aligned}$$

We then conclude essentially as in (3.11)–(3.12), the term $g\nabla p$ being replaced by $g\nabla p + \nabla C_{ib}/d_i C_{ib}$.

3.4. *Positivity of the C_i .* In order to guarantee the positivity of the C_i , we will replace C_i by $K_i = \log C_i$, so that $C_i = e^{K_i} > 0$. Whereas this would have very significant implications to the mathematical theory of these equations (existence, uniqueness issues), we will see that, at the level of the space discretized equations, this produces few changes and we automatically obtain the positivity of the C_i .

Equations (2.2) and (2.5) become

$$\frac{\partial K_i}{\partial t} + e^{-K_i} \nabla N_i = e^{-K_i} \omega_i, \quad i = 1, \dots, S, \tag{3.16}$$

$$\begin{aligned} d_i N_i + \frac{\mathcal{R}T}{p} \sum_{\substack{j=1 \\ j \neq i}}^S d_{ij} e^{K_i + K_j} (e^{-K_i} N_i - e^{-K_j} N_j) \\ = -e^{K_i} \nabla K_i - d_i e^{K_i} g \nabla p, \quad i = 1, \dots, S. \end{aligned} \tag{3.17}$$

The boundary and initial conditions (2.6)–(2.7) are easily transferred to the K_i .

To obtain the desired a priori estimates, we mimic what we did in Sections 3.2 and 3.3. For the periodic case and the Neumann boundary conditions, we multiply (3.17) by $e^{K_i} K_i$, integrate over Ω , and add for $i = 1, \dots, S$. With very similar calculations we arrive at (3.9)–(3.12) where, e.g., Φ is expressed in terms of the K_j :

$$\Phi = \sum_{i=1}^S \int_{\Omega} (K_i e^{K_i} - e^{K_i} + 2) dx. \tag{3.18}$$

Hence, as in (3.12),

$$\Phi(t) \leq \Phi(0) e^{\kappa_3 T}, \quad 0 \leq t \leq T. \tag{3.19}$$

In the case of the Dirichlet boundary condition, we multiply (3.17) by $e^{K_i} (K_i - K_{ib})$, $K_{ib} = \log C_{ib}$. The calculations are the same and we obtain again (3.16); as in Sec. 3.3, the term $g\nabla p$ is replaced at the end by $g\nabla p + \nabla C_{ib}/d_i C_{ib} = g\nabla p + d_i^{-1} \nabla K_{ib}$.

4. Spatial discretization by finite differences. We now discuss the spatial discretization of the above equations using finite differences (Sec. 4) or pseudo-spectral methods (Sec. 5). The three boundary conditions (2.6 a,b,c) will be successively considered but, for the sake of simplicity, we will assume in all cases that Ω is a 2D or 3D rectangle, $\Omega = (0, L_1) \times (0, L_2)$ or $\Omega = (0, L_1) \times (0, L_2) \times (0, L_3)$. The one-dimensional case, $\Omega = (0, L_1)$, can be considered as well.

4.1. *Space periodic case.* In the case of finite differences with meshes $h_i = \Delta x_i = L_i/R_i$, $i = 1, 2, 3$, we consider the nodal points $rh = (r_1 h_1, r_2 h_2, r_3 h_3)$, $h = (h_1, h_2, h_3)$, $r = (r_1, r_2, r_3)$, $-1 \leq r_i \leq R_i + 1$. We discretize, for instance, (2.2) with a forward discretization scheme corresponding to ∇_h with, e.g.,

$$\nabla_{1h} \varphi(x) = \frac{\varphi(x_1 + h_1, x_2, x_3) - \varphi(x_1, x_2, x_3)}{h_1}.$$

Hence

$$\frac{dC_{ih}}{dt} + \nabla_h N_{ih} = \omega_i, \tag{4.1}$$

equations (4.1) being understood for all times, and at points $rh, 0 \leq r_i \leq R_i$, forming the mesh Ω_R . Space periodicity is enforced by imposing that

$$C_{ih}|_{x_j=0} = C_{ih}|_{x_j=R_j, h_j=L_j}, \quad j = 1, 2, 3, \quad i = 1, \dots, S. \tag{4.2}$$

Also, we extend the value of C_i at points $-h_j$ and $(R_j + 1)h_j$, by periodicity:

$$C_{ih}|_{x_j=-h_j} = C_{ih}|_{x_j=(R_j-1)h_j}, \quad C_{ih}|_{x_j=(R_j+1)h_j} = C_{ih}|_{x_j=h_j}. \tag{4.3}$$

We then define the backward finite difference operator $\bar{\nabla}_h = (\bar{\nabla}_{1h}, \bar{\nabla}_{2h}, \bar{\nabla}_{3h})$ with, e.g.,

$$\bar{\nabla}_{1h}\varphi(x) = \frac{\varphi(x_1, x_2, x_3) - \varphi(x_1 - h_1, x_2, x_3)}{h_1}.$$

Before discretizing Eq. (2.5), we rewrite it in the following equivalent form:

$$\begin{aligned} d_i \frac{N_i}{C_i} + \frac{\mathcal{R}T}{p} \sum_{\substack{j=1 \\ j \neq i}}^S d_{ij} C_j \left(\frac{N_i}{C_i} - \frac{N_j}{C_j} \right) \\ = -\frac{\nabla C_i}{C_i} - d_i g \nabla p, \quad i = 1, \dots, n. \end{aligned} \tag{4.4}$$

The discretized form of (2.5)–(4.4) then reads

$$\begin{aligned} d_i \frac{N_{ih}}{C_{ih}} + \frac{\mathcal{R}T}{p} \sum_{\substack{j=1 \\ j \neq i}}^S C_{jh} \left(\frac{N_{ih}}{C_{ih}} - \frac{N_{jh}}{C_{jh}} \right) \\ = -\bar{\nabla}_h \log C_{ih} - d_i g \nabla p, \quad i = 1, \dots, n, \end{aligned} \tag{4.5}$$

these equations being written at all points of Ω_h (using (4.2) and (4.3)).

Note that the equations (4.1) and (4.5) written at the points of Ω_h are not all independent. Because of periodicity they are valid at all these points, but the independent equations are obtained, e.g., at the points of Ω_h^- consisting of the points $rh, 0 \leq r_j \leq R_j - 1, i = 1, 2, 3$.

To avoid the difficulties with the sign of C_{ih} , we introduce as in Sec. 3.4 the functions $K_{ih} = \log C_{ih}$ and express (4.1) and (4.5) in terms of the K_{ih} . The discrete analogues of (3.12) provide a priori estimates that promptly imply the existence of the K_{ih} for all time and that guarantee stability of the schemes.

The discrete analogue of Φ is now

$$\Phi_h = \Phi_h(t) = \sum_{x \in \Omega_h^-} \sum_{i=1}^S (K_i(x, t) e^{K_i(x, t)} - e^{K_i(x, t)} + 2).$$

We multiply (4.1) written at $x \in \Omega_h^-$, by $K_{ih}(x, t)$, and add the equations for $x \in \Omega_h^-, i = 1, \dots, S$. We proceed as in the continuous case, using the discrete integration by parts relation

$$\sum_{x \in \Omega_h^-} \nabla_h N_{ih}(x) K_{ih}(x) = - \sum_{x \in \Omega_h^-} N_{ih}(x) \cdot \bar{\nabla}_h K_{ih}(x), \tag{4.6}$$

which is valid here because the functions N_{ih} and K_{ib} are periodic in the sense of (4.2) and (4.3). To check (4.6) we fix $i, 1 \leq i \leq S, j, 1 \leq j \leq 3$ (say $j = 1$), $x_2 = r_2 h_2$, and

$x_3 = r_3 h_3$, $1 \leq r_2 \leq R_2 - 1$, $1 \leq r_3 \leq R_3 - 1$. We then call V_s the value of N_{ih} at sh_1 , and w_s the value of K_{ih} at the same point. After multiplication by h_1 , the corresponding contributions to the left- and right-hand sides of (4.6) are respectively

$$\begin{aligned} & (V_1 - V_0)W_0 + \dots + (V_{R_1} - V_{R_1-1})W_{R_1-1} \\ & = -V_0W_0 - V_1(W_1 - W_0) - \dots - V_{R_1-1}(W_{R_1-1} - W_{R_1-2}) + V_{R_1}W_{R_1-1}, \end{aligned} \tag{4.7}$$

and

$$-V_0(W_0 - W_{-1}) - V_1(W_1 - W_0) - \dots - V_{R_1-1}(W_{R_1-1} - W_{R_1-2});$$

these two sums are the same since $V_0 = V_{R_1}$ and $W_{-1} = W_{R_1-1}$. Hence (4.6).

4.2. *No-flux (Neumann) boundary condition.* For the no-flux (Neumann) boundary condition the mesh Ω_h is the same as before, corresponding to the points $rh = (r_1h_1, r_2h_2, r_3h_3)$, $0 \leq r_j \leq R_j$, $h_j = L_j/R_j$, $j = 1, 2, 3$. The interior mesh Ω_h^- consists now of the points rh , for $1 \leq r_j \leq R_j - 1$, $j = 1, 2, 3$. The independent (unknown) values of the C_{ih} or $K_{ih} = \log(C_{ih})$, are the values of the C_{ih} at the points of Ω_h^- . The boundary condition (2.6b) is enforced by setting

$$\begin{aligned} C_{ih}|_{x_j=0} = C_{ih}|_{x_j=h_j}, \quad C_{ih}|_{x_j=(R_j-1)h_j} = C_{ih}|_{x_j=R_jh_j=L_j}, \\ j = 1, 2, 3, \quad i = 1, \dots, S; \end{aligned} \tag{4.8}$$

we thus extend the definition of the C_{ih} to all the points of Ω_h^- . For consistency, and in view of (3.7), we discretize p by setting $p_h(x) = p(x)$, for $x \in \Omega_h^-$ and we set, as in (4.8),

$$p_h|_{x_j=0} = p_h|_{x_j=h_j}, \quad p_h|_{x_j=(R_j-1)h_j} = p_h|_{x_j=R_jh_j=L_j}, \tag{4.9}$$

thus introducing an $0(h)$ error in the discretization of p .

The discretized equations (4.5) are written at all points $x \in \Omega_h^+$ of the form $rh = (r_1h_1, r_2h_2, r_3h_3)$, $1 \leq r_j \leq R_j$, $j = 1, 2, 3$. Thus the N_{ih} are defined at all points $x \in \Omega_h^+$. In view of (4.8), (4.9), and the discussion before (3.8),

$$\begin{aligned} & \text{The } j^{\text{th}} \text{ component of } N_{ih} \text{ vanishes at } x_j = h_j \\ & \text{and } x_j = R_jh_j = L_j, \quad j = 1, 2, 3, \quad i = 1, \dots, S. \end{aligned} \tag{4.10}$$

Setting $C_{ih} = \log K_{ih}$, we write the equation (4.1) for the K_{ih} at all points $x \in \Omega_h$. The resolution on some interval of time $(0, t_h)$ of the system (4.1) supplemented by (4.5) and the initial conditions (2.7) for the $C_{ih}(K_{ih})$ at $x \in \Omega_h^-$ is standard. The discrete analog of the estimate (3.17) is valid; it guarantees that the K_{ih} are defined on the whole interval $[0, T]$, and thus the $C_{ih} = \exp(K_{ih})$ are defined and positive on the whole interval $[0, T]$. Furthermore, the discrete analog of (3.17) provides the stability of the space discretized equations. In the course of proving this estimate, we make use of (4.6), which is still valid. With the same notation as for (4.7), the proof of (4.6) ends up in showing that the following sums are the same:

$$\begin{aligned} & (V_2 - V_1)W_1 + \dots + (V_{R_1} - V_{R_1-1})W_{R_1-1} \\ & = -V_1W_1 - V_2(W_2 - W_1) \dots - V_{R_1-1}(W_{R_1-1} - W_{R_1-2}) \\ & \quad + V_{R_1}W_{R_1-1}, \end{aligned} \tag{4.11}$$

and

$$-V_1(W_1 - W_0) \dots - V_{R_1-1}(W_{R_1-1} - W_{R_1-2}).$$

These sums are indeed the same since by (4.10) (and the notation in (4.7)), $V_1 = V_{R_1} = 0$.

The proof is now complete for the Neumann boundary condition case.

4.3. *Dirichlet boundary condition.* In this case the notation for the meshes is as in Sec. 4.2: Ω_h is the set of points rh , $0 \leq r_j \leq R_j$, $j = 1, 2, 3$, and Ω_h^- is the set of points rh , $1 \leq r_j \leq R_j - 1$, $j = 1, 2, 3$. The independent (unknown) values of the C_{ih} (or $K_{ih} = \log C_{ih}$) are the values at the points of Ω_h^- . The boundary condition (2.6c) is enforced by setting

$$\begin{aligned} C_{ih} &= C_{ib} \text{ at } x_j = 0 \text{ or } R_j, \\ j &= 1, 2, 3, \quad i = 1, \dots, S; \end{aligned} \tag{4.12}$$

we thus extend the definition of the C_{ih} (or K_{ih}) at all points of Ω_h .

Similarly, K_{ibh} (or C_{ibh}) is defined at all points of Ω_h by just setting

$$K_{ibh}(x) = K_{ib}(x), \quad x \in \Omega_h. \tag{4.13}$$

The discretized equations (4.5) are written at all points $x \in \Omega_h^+$ of the form $rh = (r_1h_1, r_2h_2, r_3h_3)$, $1 \leq r_j \leq R_j$, $j = 1, 2, 3$. Thus the N_{ih} are defined at all points $x \in \Omega_h^+$.

Setting $C_{ih} = \log K_{ih}$, we write the equations (4.1) for the K_{ih} at all points $x \in \Omega_h^-$. The resolution on some interval $(0, t_h)$ of this system, supplemented by equations (4.5) and the initial conditions (2.7) for the $C_{ih}(K_{ih})$ at $x \in \Omega_h^-$, is standard.

We now proceed with the discrete analog of the estimate (3.17) to show that $t_h = T$, and to establish the stability.

At each $x \in \Omega_h^-$, Eq. (4.1) is multiplied by $(K_{ih} - K_{ibh})(x)$; we then sum for $x \in \Omega_h^-$ and $i = 1, \dots, S$. The main difficulty is in establishing the discrete integration by parts formula (4.6) which is now replaced by

$$\begin{aligned} &\sum_{x \in \Omega_h^-} \nabla_h N_{ih}(x)(K_{ih} - K_{ibh})(x) \\ &= - \sum_{x \in \Omega_h^+} N_{ih}(x) \bar{\nabla}_h (K_{ih} - K_{ibh})(x). \end{aligned} \tag{4.14}$$

To prove (4.14) we proceed as in (4.7) with a similar notation: V_j is still the value of (say) the first component of $N_{ih}(x_1, x_2, x_3)$ at $x_1 = jh_1$, and W_j is the value at the same point of $(K_{ih} - K_{ibh})(x_1, x_2, x_3)$, $x_1 = jh_1$. The sums to be compared are now

$$\begin{aligned} &(V_2 - V_1)W_1 + (V_3 - V_2)W_2 + \dots + (V_{R_1} - V_{R_1-1})W_{R_1-1}, \\ &\text{and} \\ &-V_1(W_1 - W_0) \dots - V_{R_1}(W_{R_1} - W_{R_1-1}). \end{aligned} \tag{4.15}$$

We add $(V_{R_1+1} - V_{R_1})W_{R_1}$ to the first sum, this term vanishing ($W_{R_1} = 0$; V_{R_1+1} arbitrary). Remembering that W_0 vanishes like W_{R_1} , we conclude that the two sums are the same, and (4.14) follows.

The stability is proven in the Dirichlet case as well.

5. Spatial discretization by pseudo-spectral methods. In this section we discuss the spatial discretization of the boundary value problem (2.2)–(2.7) using pseudo-spectral methods. We will use trigonometric polynomials based on equidistant points in the space-periodic case and Legendre polynomials based on the Gauss-Lobato points for the Neumann and Dirichlet boundary conditions. The domain Ω is a 2D rectangle, $\Omega = (0, L_1) \times (0, L_2)$, or a 3D parallelepiped, $\Omega = (0, L_1) \times (0, L_2) \times (0, L_3)$. The (simpler) one-dimensional case, $\Omega = (0, L_1)$, can be treated in the same manner.

5.1. *Space periodic case.* In each direction Ox_k , $k = 1, 2, 3$, we consider the equidistant points

$$x_k^i = \frac{iL_k}{R_k}, \quad i = 0, \dots, 2R_k - 1. \tag{5.1}$$

We denote by Ω_R the set of points $Y = (x_1^{i_1}, x_2^{i_2}, x_3^{i_3})$, $0 \leq i_1 \leq 2R_1 - 1$, $0 \leq i_2 \leq 2R_2 - 1$, $0 \leq i_3 \leq 2R_3 - 1$, and by Ω_R^- the set of points $x = (x_1^{i_1}, x_2^{i_2}, x_3^{i_3})$, $0 \leq i_1 \leq 2R_1 - 1$, $0 \leq i_2 \leq 2R_2 - 1$, $0 \leq i_3 \leq 2R_3 - 1$.

Each function is determined by its values at the points of Ω_R^- ; the nodal values at the points of $\Omega_R \setminus \Omega_R^-$ are determined by *periodicity*, thus enforcing the boundary condition (2.6a). The function is then extended to all of Ω (and to the whole space \mathbb{R}^3 or \mathbb{R}^2) by trigonometric polynomial interpolation in each direction. For instance, the interpolation in the direction Ox_1 of a function f reads

$$I_{R_1} f(x_1, x_2, x_3) = \sum_{j=0}^{2R_1-1} f(x_1^j, x_2, x_3) g_j(x_1), \tag{5.2}$$

where x_2 and x_3 are fixed (of the form (5.1)). The Lagrange polynomials g_j belong to the space $\tilde{\mathcal{P}}_{R_1}$ (this is the space spanned by the polynomials $\cos(m\pi x_1)$, $0 \leq m \leq R_1$, and $\sin(m\pi x_1)$, $1 \leq m \leq R_1 - 1$) and satisfy

$$g_j(x_1^k) = \delta_{jk}, \quad 0 \leq j, k \leq 2R_1 - 1. \tag{5.3}$$

Before we continue, let us recall also that the (exact) derivative of $I_{R_1} f$ in the direction Ox_1 belongs also to $\tilde{\mathcal{P}}_{R_1}^1$ and it is characterized by its nodal values:

$$\frac{\partial}{\partial x_1} I_{R_1} f(x_1^k, x_2, x_3) = \sum_{j=0}^{2R_1-1} f(x_1^j, x_2, x_3) \frac{dg_j}{dx_1}(x_1^k), \quad k = 0, \dots, 2R_1 - 1. \tag{5.4}$$

$\{ \frac{dg_j}{dx_1}(x_1^k) \}_{0 \leq k \leq 2R_1-1}$ is determined from the vector $\{ g_j(x_1^k) \}_{0 \leq k \leq 2R_1-1}$ by a linear transformation (matrix-vector product), and the differentiation matrix can be built by Fast Fourier Transform or other suitable fast methods.

The Fourier method involves seeking a trigonometrical polynomial (in all three space directions) $K_i(x_1, x_2, x_3, t)$ such that equation (4.4),

$$\begin{aligned} d_i \frac{N_i}{C_i} + \frac{\mathcal{R}T}{p} \sum_{\substack{j=1 \\ j \neq i}}^S d_{ij} C_j \left(\frac{N_i}{C_i} - \frac{N_j}{C_j} \right) \\ = - \frac{\nabla C_i}{C_i} - d_i g \nabla p, \quad i = 1, \dots, n, \end{aligned} \tag{5.5}$$

is valid in Ω , and

$$\begin{aligned} \frac{\partial K_i(x, t)}{\partial t} + e^{-K_i(x, t)} \nabla I_R N_i(x, t) \\ = e^{-K_i(x, t)} \omega_i(x, t), \quad i = 1, \dots, S, \quad 0 < t < T_*. \end{aligned} \tag{5.6}$$

In the following we will establish the stability of the Fourier discretization of (3.1). We comment here that we use the notation K_i for the Fourier approximation instead of the more correct one K_i^N ; this is done for simplicity.

We multiply (5.5) by $e^{K_i(x, t)} K_i(x, t) \varpi$, $\varpi = \prod_{k=1}^3 (\frac{L_k}{2R_k})$, and sum for $x \in \Omega_R^-$. We obtain a discrete integration formula which is exact for the functions interpolated by I_R , because the product $(I_R K_i)(\nabla I_R N_i)$ belongs to $\mathcal{P}_{2R_k-1}^k$ in each direction k , \mathcal{P}_{2R-1} being the space of trigonometric polynomials of degree $\leq 2R - 1$ (in one direction). It is then legitimate to integrate by parts, i.e., using periodicity:

$$\int_{\Omega} (K_i)(\nabla I_R N_i)(x, t) dx = - \int_{\Omega} (\nabla K_i)(I_R N_i)(x, t) dx. \tag{5.7}$$

For the same reason as before, the integral in the right-hand side of (5.6) is exactly equal to the (opposite of the) sum of the $(\nabla K_i(x, t)) N_i(x, t) \varpi$ for the x in Ω_R^- . As explained before, ∇K_i at the points $x \in \Omega_R^-$ is given by the discrete version of equations (4.4). The analysis continues without any further change until we obtain the discrete analog of (3.18) and (3.19) for

$$\Phi_R = \Phi_R(t) = \sum_{x \in \Omega_R^-} (K_i(x, t) e^{K_i(x, t)} - e^{K_i(x, t)} + 2) \varpi.$$

5.2. *No-flux (Neumann) boundary condition.* For the no-flux (Neumann) boundary condition (2.6b), the mesh Ω_R consists of the Gauss-Lobato points in each direction $0x_k$, i.e., $x = (x_1^{i_1}, x_2^{i_2}, x_3^{i_3})$, $0 \leq i_1 \leq R_1$, $0 \leq i_2 \leq R_2$, $0 \leq i_3 \leq R_3$, and for $k = 1, 2, 3$.

$$\begin{aligned} \text{The } x_k^i \text{ are the roots of } Q(s) = (1 - s^2) P_{R_k}'(s), \\ P_{R_k} \text{ being the Legendre polynomial of degree } R_k, \quad 0 \leq i \leq R_k. \end{aligned} \tag{5.8}$$

In, say, the direction $0x_1$, the interpolation $I_{R_1} f$ of a function f is

$$I_{R_1} f(x_1, x_2, x_3) = \sum_{j=0}^{R_1} f(x_1^j, x_2, x_3) g_j(x_1), \tag{5.9}$$

and

$$g_j(s) = \frac{Q(s)}{Q'(x_1^j)(s - x_1^j)},$$

x_2, x_3 being fixed.

We recall that the g_j satisfy:

$$g_j(x_1^k) = \delta_{jk}, \quad 0 \leq j, k \leq R_1,$$

and that they form a basis of the space $\mathcal{P}_{R_1} = \mathcal{P}_{R_1}(s)$ of algebraic polynomials of degree $\leq R_1$ in the (one-dimensional) variable s . The space \mathcal{P}_R is the space of polynomials in x_1, x_2, x_3 , spanned by the polynomials in $\mathcal{P}_{R_1}(x_1) \cdot \mathcal{P}_{R_2}(x_2) \cdot \mathcal{P}_{R_3}(x_3)$.

We recall also that (in dimension 1) the discrete integration formula

$$\int_0^{L_1} f(s)ds \simeq \sum_{j=0}^{R_1} f(x_1^j) \varpi_1^j(x_1^j) \tag{5.10}$$

is exact for all polynomials f of degrees $\leq 2R_j - 1$, where the ϖ_1^j are the weights of the Legendre-Lobato formula. We write also, for $x = (x_1^{i_1}, x_2^{i_2}, x_3^{i_3}) \in \Omega_R$,

$$\varpi(x) = \varpi_1^{i_1}(x_1^{i_1}) \varpi_2^{i_2}(x_2^{i_2}) \varpi_3^{i_3}(x_3^{i_3}). \tag{5.11}$$

Hence, for a function f defined on Ω , the quadrature formula

$$\int_{\Omega} f(x)dx \simeq \sum_{x \in \Omega_R} f(x) \varpi(x) \tag{5.12}$$

is exact for a polynomial f of degree $\leq 2R_j - 1$ in each variable x_j , $j = 1, 2, 3$.

The exact derivative of $I_{R_1} f$ in direction x_1 belongs, of course, to $\mathcal{P}_{R_1}(x_1)(\mathcal{P}_{R_1-1}(x_1)$ in fact), and it is thus fully characterized by its nodal values:

$$\frac{\partial}{\partial x_1} I_{R_1} f(x_1^k, x_2, x_3) = \sum_{j=0}^{R_1} f(x_1^j, x_2, x_3) \frac{dg_j}{dx_1}(x_1^k), \quad k = 0, \dots, R_1. \tag{5.13}$$

The differentiation matrix $\{\frac{dg_j(x_1^k)}{dx_1}\}_{0 \leq j, k \leq R_1}$ can be written explicitly or evaluated by fast transforms.

Let us now proceed with the resolution of our system. We call Ω_R^0 the set of points $x = (x_1^{i_1}, x_2^{i_2}, x_3^{i_3})$, the x_k^j as in (5.7) and with $1 \leq i_k \leq R_k - 1$, $k = 1, 2, 3$.

For two functions f and g , we have of course the (exact) integration by parts formula

$$\begin{aligned} & \int_0^{L_1} \frac{\partial}{\partial x_1} I_R[f(x_1)] \cdot I_R[g(x_1)] dx_1 \\ &= I_R[f(L_1)] I_R[g(L_1)] - I_R[f(0)] I_R[g(0)] \\ & \quad - \int_0^{L_1} I_R[f(x_1)] \cdot \frac{\partial}{\partial x_1} I_R[g(x_1)] dx_1, \end{aligned} \tag{5.14}$$

equivalent to

$$\begin{aligned} & \sum_{j=0}^{R_1} \frac{\partial}{\partial x_j} I_R[f(x_1^j)] g(x_1^j) \varpi_1^j \\ &= f(x_1^{R_1}) g(x_1^{R_1}) - f(x_1^0) g(x_1^0) \\ & \quad - \sum_{j=0}^{R_1} f(x_1^j) \frac{\partial}{\partial x_1} I_R[g(x_1^j)] \varpi_1^j. \end{aligned} \tag{5.15}$$

In the case, useful below, where $f(0) = f(L_1) = 0$, these formulas become

$$\begin{aligned} & \int_0^{L_1} \frac{\partial}{\partial x_1} I_R[f(x_1)] \cdot I_R[g(x_1)] dx_1 \\ &= - \int_0^{L_1} I_R[f(x_1)] \cdot \frac{\partial}{\partial x_1} I_R[g(x_1)] dx_1, \end{aligned} \tag{5.16}$$

$$\begin{aligned} & \sum_{j=0}^{R_1} \frac{\partial}{\partial x_1} I_R[f(x_1^j)] f(x_1^j) \varpi_1^j(x_1^j) \\ &= - \sum_{j=0}^{R_1} f(x_1^j) \frac{\partial}{\partial x_1} I_R[g(x_1^j)] \varpi_1^j(x_1^j). \end{aligned} \tag{5.17}$$

Before we proceed with the resolution of our system, we need to comment here on the discrete implementation of the boundary condition (2.6b) which will be done by weak (variational) formulation, as is done, in a standard way, with, e.g., finite elements. We start with the continuous (nondiscrete) case and we first make the remark converse to (3.6)–(3.7); namely, if the conditions (3.6) and (3.7) hold, then (3.1) shows that $\mathbf{n} \cdot \nabla C_i = \partial C_i / \partial \mathbf{n} = 0$ on Γ , for $i = 1, \dots, S$. Consequently when p satisfies (3.6), the conditions (2.6b) and (3.7) are equivalent. Hence we will implement (2.6b) by imposing the conditions (3.7). More precisely, multiplying (2.2) by a test function Φ and integrating over Ω gives, with (3.7):

$$\begin{aligned} & \int_{\Omega} \frac{\partial C_i}{\partial t} \Phi dx + \int_{\Omega} \nabla N_i \Phi dx = \int_{\Omega} \omega_i \Phi dx \\ & \int_{\Omega} \nabla N_i \Phi dx = \int_{\Gamma} N_i \mathbf{n} \Phi d\Gamma - \int_{\Omega} N_i \cdot \nabla \Phi dx \\ &= - \int_{\Omega} N_i \cdot \nabla \Phi dx. \end{aligned}$$

Thus

$$\int_{\Omega} \frac{\partial C_i}{\partial t} \Phi dx - \int_{\Omega} N_i \cdot \nabla \Phi dx = \int_{\Omega} \omega_i \Phi dx, \tag{5.18}$$

or equivalently with $C_i = e^{K_i}$,

$$\int_{\Omega} \frac{\partial}{\partial t} e^{K_i} \Phi dx - \int_{\Omega} N_i \cdot \nabla \Phi dx = \int_{\Omega} \omega_i \Phi dx. \tag{5.19}$$

Also (this is a standard exercise in variational formulations) if (5.17) is valid for all smooth test functions Φ , then necessarily (2.2) holds and $N_i \cdot \mathbf{n} = 0$ on Γ . Thus we intend now to approximate (2.2), (2.6b) by implementing a discrete pseudo-spectral form of (5.17)².

We call K_{iR} an approximation of K_i defined at the nodal points of Ω_R and $C_{iR} = e^{K_{iR}}$, and we introduce the interpolation $I_R K_{iR}$ as before. We now approximate (5.18) in the

²We could have done the same for finite differences, but the discretization of the boundary condition was then simpler than in the present case.

following form:

$$\frac{\partial}{\partial t} \sum_{x \in \Omega_R} e^{K_{iR}}(x, t) \Phi(x) - \int_{\Omega} I_R(N_{iR}) \nabla \Phi dx = \int I_R(\omega_i) \Phi dx, \tag{5.20}$$

$$\forall \Phi \in \mathcal{P}_R, \quad i = 1, \dots, S.$$

Here the N_{iR} are defined on Ω_R by the resolution of equations (3.1) written in the form (4.4) at $x \in \Omega_R$; $x \in \Omega_R$ is of the form $x = (x_1^{i_1}, x_2^{i_2}, x_3^{i_3})$, $0 \leq i_1 \leq R_1$, $0 \leq i_2 \leq R_2$, $0 \leq i_3 \leq R_3$. Furthermore, $\nabla C_i/C_i$ is replaced by the value of $\nabla I_R K_{iR}$ and ∇p is replaced by $\nabla I_R p_R$, where $p_R = p$ at the points x of Ω_R . As indicated in (5.19), we impose (5.19) to be valid for every $\Phi \in \mathcal{P}_R$, for $i = 1, \dots, S$.

For each i , (5.19) is an ordinary differential system which we solve in classical ways by advancing in time.

The existence of the K_{iR} on a finite interval of time $(0, T_*)$, $0 < T_* \leq T$ is standard and the a priori estimate similar to (3.18) shows that actually $T_* = T$. To derive this a priori estimate, we replace Φ by $I_R K_{iR}$ in (5.19). We use the integration formulas derived from (5.9), taking advantage of the fact that these integration formulas are exact for $I_R N_{iR} \nabla K_{iR}$. Using then equations (4.4) at the points $x \in \Omega_R$, we conclude, as in the continuous case, that

$$- \int_{\Omega} I_R N_{iR} \nabla K_{iR} dx \geq 0.$$

There remains

$$\int_{\Omega} \frac{\partial}{\partial t} I_R(e^{K_{iR}}) K_{iR} dx \leq \int_{\Omega} (I_R \omega_i) K_{iR} dx,$$

and we derive the analogue of (3.18) as in the continuous case.

REMARK 5.1. We should be able to improve the approximation of (3.8) and thus to improve the approximation by choosing p_R in such a way that

$$\frac{\partial p_{iR}}{\partial \mathbf{n}} = 0 \text{ on } \Gamma. \tag{5.21}$$

To this end we choose $p_R(x) = p(x)$ at all points x of Ω_R^0 , the set of points $x = (x_1^{i_1}, x_2^{i_2}, x_3^{i_3})$, the x_k^j as in (5.7) and with $1 \leq i_k \leq R_k - 1$, $k = 1, 2, 3$. Then we define p_R on $\Omega_R \setminus \Omega_R^0$ so that the relations (5.20) hold. For instance, in direction $0x_1$, and for x_2, x_3 fixed, we would define $p_R|_{x_1^0}$ and $p_R|_{x_1^{R_1}}$ by imposing the following conditions (see (5.8) and (5.12)):

$$\frac{\partial}{\partial x_1} p_R(x_1^k, x_2, x_3) = \sum_{j=0}^{R_1} p_R(x_1^k, x_2, x_3) \frac{dg_j}{dx_1}(x_1^k) = 0, \tag{5.22}$$

for $k = 0$ and R_1 .

The unknowns in (5.21) are $p_R(x_1^0, x_2, x_3)$ and $p_R(x_1^{R_1}, x_2, x_3)$; the unique solvability of (5.21) is classical [7].

5.3. *Dirichlet boundary condition.* The framework is the same as for the Neumann pseudo-spectral case. The unknowns are the values of the K_{iR} on Ω_R ; of course, on $\Omega_R \setminus \Omega_R^0$, we impose

$$K_{iR} = K_{ib} \text{ at } x_j = 0 \text{ or } L_j, \\ j = 1, 2, 3, i = 1, \dots, S.$$

The N_{iR} are defined at all points of Ω_R using the formulas (4.4) written as in the Neumann case. We then solve equations (5.5) at the points $x \in \Omega_R^0$, calling K_{iR} the corresponding approximations (and $C_{iR}(x) = e^{K_{iR}(x)}, \forall x \in \Omega_R$). The existence of a solution K_{iR} on an interval of time $(0, T_*)$, $0 < T_* \leq T$ is known; the a priori estimate guarantees that $T_* = T$. The a priori estimate is obtained as follows: we write the sum

$$\sum_{i=1}^S \sum_{k=1}^3 \sum_{x \in \Omega_R} \frac{\partial N_{iR}^{(k)}}{\partial x_k}(x)(K_{iR}(x) - K_{ib}(x))(\varpi_1^{i_1} \varpi_2^{i_2} \varpi_3^{i_3})(x), \tag{5.23}$$

where $N_{iR}^{(k)}$ is the k^{th} component of N_{iR} , and $x \in \Omega_R$ is of the form $x = (x_1^{i_2}, x_2^{i_2}, x_3^{i_3})$, $0 \leq i_1 \leq R_1, 0 \leq i_2 \leq R_2, 0 \leq i_3 \leq R_3$. We observe that $K_{iR} - K_{ib} = 0$ at x_k^0 and $x_k^{R_k}$ in each direction; hence the above sum is in fact reduced to the points $x \in \Omega_R^0$. We will use the sum for $x \in \Omega_R^0$ in one case and the sum for $x \in \Omega_R$ in the second case.

First we use Eq. (5.5) at the points $x \in \Omega_R^0$ and replace this sum by

$$\sum_{i=1}^S \sum_{x \in \Omega_R^0} \left(e^{K_{iR}} \frac{\partial K_{iR}}{\partial t} - \omega_i \right) (K_{iR} - K_{ib})(x, t) \\ = \frac{\partial}{\partial t} \Phi_R(C_{1R}, \dots, C_{SR}) - \sum_{i=1}^S \sum_{x \in \Omega_R^0} \left(\frac{C_{iR}}{C_{ib}} \frac{\partial C_{ib}}{\partial t} \right) (x). \tag{5.24}$$

Here $C_{iR}(x, t) = e^{K_{iR}(x,t)}, \forall x \in \Omega_R$, and

$$\Phi(C_{1R}, \dots, C_{SR}) \\ = \sum_{i=1}^S \sum_{x \in \Omega_R^0} (C_{iR} \log C_{iR} - C_{iR} + P + C_{iR} \log C_{ib}(x)). \tag{5.25}$$

As in Sec. 3, the constant P is chosen, such that

$$r \log r - r + P + r \log C_{ib}(x) \geq 0, \\ \forall x \in \Omega, i = 1, \dots, S, \forall r \in \mathbb{R}.$$

Now we see the sum (5.22) differently with $x \in \Omega_R$: since $\partial N_{iR} / \partial x_k$ is a polynomial of degree $\leq R_k - 1$ in x_k , and $K_{iR} - K_{ib}$ is a polynomial of degree $\leq R_k$ in x_k , the product is of degree $2R_k - 1$ at most in x_k . Hence the quadrature formula is exact in $x_k, k = 1, 2, 3$, and the sum (5.22) is exactly equal to the integral

$$\sum_{i=1}^S \int_{\Omega} \nabla(N_{iR})(K_{iR} - I_R K_{ib}) dx. \tag{5.26}$$

We integrate by parts, and we find, observing that $K_{iR} - K_{ib} = 0$ on $\partial\Omega$,

$$\sum_{i=1}^S \int_{\Omega} N_{iR} \cdot \nabla(K_{iR} - I_R K_{ib}) dx.$$

Observing that the integral is a polynomial of degree $\leq 2R_k - 1$ in each variable x_k , $k = 1, 2, 3$, we can replace again the last quantity by the following sum corresponding to an exact quadrature formula:

$$\begin{aligned} & \sum_{i=1}^S \sum_{x \in \Omega_R} [N_{iR} - \nabla(K_{iR} - I_R K_{ib})\varpi](x) \\ &= (\text{by equations (4.4) at the } x \in \Omega_R) \\ &= \sum_{i=1}^S \sum_{x \in \Omega_R} (N_{iR} I_R(K_{ib})\varpi)(x) \\ &\quad - \sum_{i=1}^S \sum_{x \in \Omega_R} \left\{ \left[\begin{aligned} & d_i e^{-K_{iR}} N_{iR} \\ & + \frac{\mathcal{R}T}{p} \sum_{\substack{j=1 \\ j \neq i}}^S d_{ij} e^{K_j} (e^{-K_i} N_{iR} - e^{-K_j} N_{jR}) + d_i g \nabla p \end{aligned} \right] N_{iR} \varpi \right\} (x) \\ &= \sum_{i=1}^S \sum_{x \in \Omega_R} [(I_R(K_{ib}) + d_i g \nabla p) N_{iR} \varpi](x) \\ &\quad - \sum_{i=1}^S \sum_{x \in \Omega_R} (d_i e^{-K_{iR}} N_{iR}^2 \varpi)(x) \\ &\quad - \frac{1}{2} \sum_{i=1}^2 \sum_{x \in \Omega_R} \frac{\mathcal{R}T}{p} \sum_{\substack{j=1 \\ j \neq i}}^S [d_{ij} e^{K_i + K_j} (e^{-K_i} N_{iR} - e^{-K_j} N_{jR})^2 \varpi](x) \\ &\leq \sum_{i=1}^S \sum_{x \in \Omega_R} [(I_R(K_{ib}) + d_i g \nabla p) N_{iR} \varpi](x) \\ &\quad - \sum_{i=1}^S \sum_{x \in \Omega_R} (d_i e^{-K_{iR}} N_{iR}^2 \varpi)(x) \\ &\leq -\frac{1}{2} \sum_{i=1}^S \sum_{x \in \Omega_R} (d_i e^{-K_{iR}} N_{iR}^2 \varpi)(x) \\ &\quad + \frac{1}{2} \sum_{i=1}^S \sum_{x \in \Omega_R} [d_i^{-1} e^{K_{iR}} (I_R(K_{ib}) + d_i g \nabla p)^2 \varpi](x). \end{aligned}$$

Hence

$$\begin{aligned} & \sum_{i=1}^S \sum_{x \in \Omega_R} [N_{iR} - \nabla(K_{iR} - I_R K_{ib})\varpi](x) \\ & \leq \kappa'_1 + \kappa'_2 \sum_{i=1}^S \sum_{x \in \Omega_R^0} C_{iR}(x), \end{aligned}$$

where κ'_1, κ'_2 are independent of x and t (and R), and $C_{iR}(x) = e^{K_{iR}(x)}$, $x \in \Omega_R$. Note that the last sum is for $x \in \Omega_R^0$, the terms $x \in \Omega_R \setminus \Omega_R^0$ being absorbed by κ'_1 .

Comparing with (5.23)–(5.24), we find:

$$\begin{aligned} & \frac{\partial \Phi_R}{\partial t}(C_{1R}, \dots, C_{SR}) \\ & \leq \kappa'_1 + \kappa'_2 \sum_{i=1}^S \sum_{x \in \Omega_R^0} C_{iR}(x) + \sum_{i=1}^S \sum_{x \in \Omega_R^0} \left(\frac{C_{iR}}{C_{ib}} \frac{\partial C_{ib}}{\partial t} \right) (x) \\ & \leq \kappa'_1 + \kappa'_3 \sum_{i=1}^S \sum_{x \in \Omega_R^0} C_{iR}(x). \end{aligned} \tag{5.27}$$

Increasing P if needed, we observe that there exists a constant $\lambda > 0$ such that

$$\begin{aligned} r & \leq \lambda(r \log r - r + P + r \log C_{ib}(x)), \\ \forall x \in \Omega, \quad i & = 1, \dots, S, \quad \forall r \in R. \end{aligned}$$

Then (5.25) yields

$$\frac{\partial \Phi_R}{\partial t}(C_{1R}, \dots, C'_{SR}) \leq \kappa'_1 + \kappa'_3 \Phi_R(C_{1R}, \dots, C_{SR}). \tag{5.28}$$

From (5.26) we deduce that the solution to the approximate system is defined for $0 \leq t \leq T$, and that it is bounded on this interval as follows:

$$\begin{aligned} \sum_{i=1}^S \sum_{x \in \Omega_R^0} C_{iR}(x, t) & \leq \lambda^{-1} \Phi(C_{1R}, \dots, C_{SR})(t) \\ & \leq \lambda^{-1} \left[\Phi(C_{1R}, \dots, C_{SR})(0) + \frac{\kappa'_1}{\kappa'_3} \right] e^{\kappa_3 T}. \end{aligned}$$

The stability of the scheme is established in this case as well (namely semi-discretization in space by pseudo-spectral method in the case of the nonhomogeneous-Dirichlet boundary condition).

REMARK 5.2. Numerical simulations and a more detailed analysis in the one-dimensional case will appear in a subsequent paper [3].

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