

ASYMPTOTIC NORMALITY OF L_p -ESTIMATORS IN NONLINEAR REGRESSION MODELS WITH WEAK DEPENDENCE

UDC 519.21

O. V. IVANOV AND I. V. ORLOVSKIĬ

ABSTRACT. A theorem on asymptotic normality is proved, and the limit distribution is found for L_p -estimators of a vector parameter in a nonlinear regression model with continuous time and weakly dependent random noise.

INTRODUCTION

We obtain conditions of asymptotic normality for L_p -estimators of an unknown parameter of nonlinear regression model with random noise satisfying a weak dependence condition.

L_p -estimators belong to the class of the so-called M -estimators. The number of papers related to M -estimators is rather large. Applications of M -estimators in linear regression models with independent observation errors are considered in the pioneering papers by Huber [22, 13]. Several asymptotic results for M -estimators of parameters of linear and nonlinear regression models with independent observation errors are proved by Hampel et al. [21], Chen and Wu [16], Jurečková [29], Liese and Vajda [38, 39, 40, 41, 42], Müller [43], Liese [37], Arcones [15], Wu and Zen [47], van de Geer [17], Orlovskiĭ [12], Ivanov and Orlovskiĭ [10, 27], and by many other authors.

Asymptotic properties of M -estimators of parameters of linear and nonlinear regression models with random noise satisfying a strong dependence condition are studied by Koul [30, 31], Koul and Mukherjee [33], Giraitis et al. [19], Koul and Surgailis [34, 35, 36], Giraitis and Koul [18], Koul et al. [32] in the case of discrete time, and by Ivanov and Leonenko [25] and Ivanov and Orlovskiĭ [11] in the case of continuous time.

Orlovskiĭ [44] and Ivanov and Orlovskiĭ [11] consider asymptotic properties of M -estimators of parameters of nonlinear regression models with continuous time and a weakly dependent random noise.

The most studied in the class of L_p -estimators are the least squares estimator (the case of $p = 2$) and least modules estimator (the case of $p = 1$). Asymptotic properties of least squares estimators and least modules estimators of parameters of nonlinear regression models are studied by many authors. We only mention the monographs by Ivanov and Leonenko [9] and Ivanov [23], where a rather complete bibliography concerning this question can be found.

Asymptotic properties of L_p -estimators of parameters of linear and nonlinear regression models with independent observation errors are considered by Huber [13], Ronner [46], Ivanov [8], Bardadym and Ivanov [1, 2]; those for nonlinear models with random

2000 *Mathematics Subject Classification.* Primary 62J02; Secondary 62J99.

Key words and phrases. L_p -estimators, asymptotic normality, nonlinear regression models, weak dependence.

noise satisfying a condition of either strong or weak dependence are considered in the papers by Ivanov and Orlovskiĭ [26] and Ivanov [24].

We deal with the L_p -estimators, $1 < p < 2$, in this paper.

1. CONDITIONS FOR AND STATEMENT OF THE MAIN RESULT

Consider the following regression model:

$$(1) \quad X(t) = g(t, \theta) + \varepsilon(t), \quad t \in [0, T],$$

where $g(t, \theta): [0; \infty) \times \Theta^c \rightarrow \mathbf{R}^1$ is a real continuous function, Θ^c a closure in \mathbf{R}^q of a bounded open set $\Theta \subset \mathbf{R}^q$, and $\varepsilon(t)$, $t \in \mathbf{R}^1$, a stochastic process satisfying the following condition:

Condition A1. Let $\varepsilon(t)$, $t \in \mathbf{R}^1$, be a real mean square continuous measurable stationary Gaussian process with zero mean and the covariance function $B(t) = \mathbf{E} \varepsilon(0)\varepsilon(t)$, $B(0) = 1$.

Definition 1. Any random vector $\hat{\theta}_T = \hat{\theta}_T(X(t), t \in [0, T]) \in \Theta^c$, such that

$$Q_{p,T}(\hat{\theta}_T) = \inf_{\tau \in \Theta^c} Q_{p,T}(\tau), \quad Q_{p,T}(\tau) = \int_0^T |X(t) - g(t, \tau)|^p dt$$

is called an L_p -estimator of the unknown parameter $\theta \in \Theta$ constructed from observations $X(t)$, $t \in [0, T]$, described by the model (1).

Note that the estimator $\hat{\theta}_T$ exists for $p > 0$ under the conditions introduced above (see, for example, [28, 45, 14]). The case of $p \in [1, 2]$ is the most interesting one.

Let $\rho(x) = |x|^p$, $p \in (1, 2)$. Then $\rho'(x) = \psi(x) = p|x|^{p-1} \operatorname{sgn} x$, $\psi'(x) = p(p-1)|x|^{p-2}$, and $\psi''(x) = p(p-1)(p-2)|x|^{p-3} \operatorname{sgn} x$ for $x \neq 0$. We also assume that $\psi'(0) = \infty$ and $|\psi''(0)| = \infty$.

The most technically complicated part in the proof of the asymptotic (as $T \rightarrow \infty$) properties of L_p -estimators for $p \in (1, 2)$ is related to the observation that the derivatives ψ' and ψ'' are not bounded in a neighborhood of the origin if $\rho(x) = |x|^p$ (this differs from the case of a number of standard M -estimators obtained when minimizing the functionals $\int_0^T \rho(X(t) - g(t, \tau)) dt$).

Assume that $g(t, \tau)$ is a twice continuously differentiable function with respect to $\tau \in \Theta^c$. Put

$$g_i(t, \tau) = \frac{\partial}{\partial \tau_i} g(t, \tau), \quad g_{il}(t, \tau) = \frac{\partial^2}{\partial \tau_i \partial \tau_l} g(t, \tau), \quad i, l = 1, \dots, q,$$

$$d_T^2(\theta) = \operatorname{diag} (d_{iT}(\theta))_{i=1}^q,$$

where

$$d_{iT}^2(\theta) = \int_0^T g_i^2(t, \theta) dt, \quad \underline{\lim} T^{-1} d_{iT}^2(\theta) > 0, \quad T \rightarrow \infty, \quad i = 1, \dots, q.$$

Our approach works even in the case where the latter limits are infinite. Also let

$$d_{il,T}^2(\tau) = \int_0^T g_{il}^2(t, \tau) dt, \quad \tau \in \Theta^c, \quad i, l = 1, \dots, q.$$

By the symbol k with various indices, we denote positive constants. Assume that, for all sufficiently large T ($T > T_0$), the following condition holds.

Condition B1.

$$(2) \quad \sup_{t \in [0, T]} \sup_{\tau \in \Theta^c} \frac{|g_i(t, \tau)|}{d_{iT}(\theta)} \leq k^i T^{-1/2}, \quad i = 1, \dots, q,$$

$$(3) \quad \sup_{t \in [0, T]} \sup_{\tau \in \Theta^c} \frac{|g_{il}(t, \tau)|}{d_{il,T}(\theta)} \leq k^{il} T^{-1/2}, \quad i, l = 1, \dots, q,$$

$$(4) \quad \sup_{\tau \in \Theta^c} \frac{d_{il,T}(\tau)}{d_{iT}(\theta) d_{lT}(\theta)} \leq \tilde{k}^{il} T^{-1/2}, \quad i, l = 1, \dots, q.$$

Put

$$J_T(\theta) = (J_{il,T}(\theta))_{i,l=1}^q, \quad J_{il,T}(\theta) = d_{iT}^{-1}(\theta) d_{lT}^{-1}(\theta) \int_0^T g_i(t, \theta) g_l(t, \theta) dt,$$

$$\Lambda_T(\theta) = (\Lambda_T^{il}(\theta))_{i,l=1}^q = J_T^{-1}(\theta).$$

By $\lambda_{\min}(A)$ ($\lambda_{\max}(A)$) we denote the minimal (maximal) eigenvalue of a positive definite matrix A .

Condition B2. For some $\lambda_* > 0$ and $T > T_0$,

$$\lambda_{\min}(J_T(\theta)) \geq \lambda_*.$$

We have

$$\mathbf{E} \psi(\varepsilon(0)) = p \int_{-\infty}^{\infty} |x|^{p-1} \operatorname{sgn} x \varphi(x) dx = 0,$$

where $\varphi(x) = (2\pi)^{-1/2} \exp\{-x^2/2\}$. On the other hand, we get for $p \in (1, 2)$ that

$$\mathbf{E} \psi^2(\varepsilon(0)) = \frac{p^2 2^{p-1}}{\sqrt{\pi}} \Gamma\left(p - \frac{1}{2}\right), \quad \mathbf{E} \psi'(\varepsilon(0)) = \frac{p 2^{p/2}}{\sqrt{\pi}} \Gamma\left(\frac{p+1}{2}\right) > 0.$$

Moreover

$$\mathbf{E}(\psi'(\varepsilon(0)))^2 = \frac{p^2(p-1)^2 2^{p-2}}{\sqrt{\pi}} \Gamma\left(p - \frac{3}{2}\right) < \infty$$

if $p > 3/2$.

Therefore $\mathbf{E} \psi^2(\varepsilon(0)) < \infty$ and $\mathbf{E}(\psi'(\varepsilon(0)))^2 < \infty$ for $p \in (3/2, 2)$. In this case, the functions $\psi(\varepsilon(t))$ and $\psi'(\varepsilon(t))$, $t \in \mathbf{R}^1$, can be expanded in the series in the Hilbert space $L_2(\mathbf{R}^1, \varphi(x) dx)$, namely

$$(5) \quad \begin{aligned} \psi(x) &= \sum_{k=0}^{\infty} \frac{C_k(\psi)}{k!} H_k(x), & C_k(\psi) &= \int_{-\infty}^{\infty} \psi(x) H_k(x) \varphi(x) dx, \\ \psi'(x) &= \sum_{k=0}^{\infty} \frac{C_k(\psi')}{k!} H_k(x), & C_k(\psi') &= \int_{-\infty}^{\infty} \psi'(x) H_k(x) \varphi(x) dx, \end{aligned}$$

where H_k are the Hermite–Chebyshev polynomials

$$H_k(u) = (-1)^k e^{u^2/2} \frac{d^k}{du^k} e^{-u^2/2}, \quad k \geq 0.$$

Consider the following condition of weak dependence.

Condition A2. Let $\varepsilon(t)$, $t \in \mathbf{R}^1$, be a stochastic process such that

$$\alpha(r) = \sup_{A \in \sigma(-\infty, s], B \in \sigma[s+r, \infty)} |\mathbf{P}(AB) - \mathbf{P}(A)\mathbf{P}(B)| = O(r^{-1-\varepsilon}), \quad r \rightarrow \infty,$$

for some $\varepsilon > 0$, where $\sigma(I)$ denotes the σ -algebra generated by the random variables $\{\varepsilon(t), t \in I\}$.

Condition **A2** implies that $B(\cdot) \in L_1(\mathbf{R}^1)$ and that the process $\varepsilon(t)$ has a bounded continuous spectral density $f(\lambda)$, $\lambda \in \mathbf{R}^1$.

It is easy to see that if $\varepsilon(t)$ satisfies the weak dependence condition, then $\psi(\varepsilon(t))$ also satisfies this condition. For all Borel sets G ,

$$\{\psi(\varepsilon(t)) \in G\} = \{\varepsilon(t) \in \psi^{-1}(G)\},$$

and $\psi^{-1}(G)$ is also a Borel set, whence

$$\alpha_\psi(r) = \sup_{A \in \sigma_\psi(-\infty, t], B \in \sigma_\psi[t+r, \infty)} |\mathbf{P}(AB) - \mathbf{P}(A)\mathbf{P}(B)| \leq \alpha(r),$$

where $\sigma_\psi(I)$ is the σ -algebra generated by the random variables $\{\psi(\varepsilon(t)), t \in I\}$.

Since the stochastic process $\psi(\varepsilon(t))$, $t \in \mathbf{R}^1$, can be expanded in the series (5) with respect to the Hermite–Chebyshev polynomials,

$$\mathbf{E} H_m(\varepsilon(t)) H_k(\varepsilon(s)) = \delta_m^k m! B^m(t-s),$$

and $\mathbf{E} \psi(\varepsilon(0)) = 0$, we get

$$\text{cov}(\psi(\varepsilon(t)), \psi(\varepsilon(s))) = \sum_{k=1}^{\infty} \frac{C_k^2(\psi)}{k!} B^k(t-s).$$

In view of $|B(t)| \leq 1$, $t \in \mathbf{R}^1$, we obtain

$$(6) \quad |\text{cov}(\psi(\varepsilon(t)), \psi(\varepsilon(s)))| \leq \sum_{k=1}^{\infty} \frac{C_k^2(\psi)}{k!} |B(t-s)| = \mathbf{E} \psi^2(\varepsilon(0)) |B(t-s)|.$$

Therefore the stationary stochastic process $\psi(\varepsilon(t))$, $t \in \mathbf{R}^1$, also has a bounded and continuous spectral density $f_\psi(x)$.

Consider the matrix measure $\mu_T(dx; \theta)$ on $(\mathbf{R}^1, \mathcal{B}^1)$ with the following matrix density:

$$\begin{aligned} & (\mu_T^{jl}(x; \theta))_{j,l=1}^q, \\ \mu_T^{jl}(x; \theta) &= g_T^j(x, \theta) \overline{g_T^l(x, \theta)} \left(\int_{\mathbf{R}^1} |g_T^j(x, \theta)|^2 dx \int_{\mathbf{R}^1} |g_T^l(x, \theta)|^2 dx \right)^{-1/2}, \\ g_T^j(x, \theta) &= \int_0^T e^{ixt} g_j(t, \theta) dt, \quad j, l = 1, \dots, q. \end{aligned}$$

Note that $d_{jT}^2(\theta) = (2\pi)^{-1} \int_{\mathbf{R}^1} |g_T^j(x, \theta)|^2 dx$.

Condition B3. The family of measures $\mu_T(\cdot; \theta)$ weakly converges to the measure $\mu(\cdot; \theta)$ as $T \rightarrow \infty$ and

$$\int_{\mathbf{R}^1} f_\psi(x) \mu(dx; \theta)$$

is a positive definite matrix.

Definition 2. The matrix measure $\mu(\cdot; \theta)$ is called the spectral measure of the regression function $g(t, \theta)$ [9, 6, 20].

Conditions **B2** and **B3** imply that

$$\int_{\mathbf{R}^1} \mu(dx; \theta) = \left(\int_{\mathbf{R}^1} \mu^{jl}(dx; \theta) \right)_{j,l=1}^q$$

is a nonsingular matrix.

Let

$$(7) \quad \sigma(\theta) = 2\pi\gamma^2 \left(\int_{\mathbf{R}^1} \mu(dx; \theta) \right)^{-1} \left(\int_{\mathbf{R}^1} f_\psi(x) \mu(dx; \theta) \right) \left(\int_{\mathbf{R}^1} \mu(dx; \theta) \right)^{-1},$$

where

$$(8) \quad \gamma = \frac{1}{\mathbf{E} \psi'(\varepsilon(0))}.$$

Consider the following condition for the asymptotic uniqueness of a solution of the system of “normal” equations defining the L_p -estimator.

Condition C. For all $\varepsilon > 0$ and $R > 0$, the probability that the system of equations (10) with $T > T_0$ has a unique solution in the ball $v^c(R)$ is not less than $1 - \varepsilon$.

Sufficient conditions for Condition **C** can be found in [24].

Now we state the main result of the paper.

Theorem. *Let Conditions **A1**, **A2**, **B1–B3**, and **C** hold. If $p \in (\frac{3}{2}, 2)$, then the distribution of the normalized L_p -estimator*

$$(9) \quad \widehat{u}_T = \widehat{u}_T(\theta) = d_T(\theta)(\widehat{\theta}_T - \theta)$$

converges as $T \rightarrow \infty$ to the Gaussian $N(0, \sigma(\theta))$ distribution.

2. AUXILIARY RESULTS

Consider the change of variables $u = d_T(\theta)(\tau - \theta)$ corresponding to the normalization (9). Applying this change to the regression function and its derivatives, we get

$$\begin{aligned} g(t, \tau) &= g(t, \theta + d_T^{-1}(\theta)u) = h(t, u), \\ g_i(t, \tau) &= g_i(t, \theta + d_T^{-1}(\theta)u) = h_i(t, u), \quad i = 1, \dots, q, \\ g_{il}(t, \tau) &= g_{il}(t, \theta + d_T^{-1}(\theta)u) = h_{il}(t, u), \quad i, l = 1, \dots, q. \end{aligned}$$

We also use the notation

$$\begin{aligned} H(t; u_1, u_2) &= h(t, u_1) - h(t, u_2), \\ H_i(t; u_1, u_2) &= h_i(t, u_1) - h_i(t, u_2), \quad i = 1, \dots, q. \end{aligned}$$

Consider the vectors

$$M_T(u) = (M_T^i(u))_{i=1}^q = \left(\gamma \int_0^T \psi(X(t) - h(t, u)) \frac{h_i(t, u)}{d_{iT}(\theta)} dt \right)_{i=1}^q$$

and

$$\Psi_T(u) = (\Psi_T^i(u))_{i=1}^q = \left(\gamma \int_0^T \psi(\varepsilon(t)) \frac{h_i(t, u)}{d_{iT}(\theta)} dt + \int_0^T H(t; 0, u) \frac{h_i(t, u)}{d_{iT}(\theta)} dt \right)_{i=1}^q,$$

where γ is defined by (8). The vectors $M_T(u)$ and $\Psi_T(u)$ are defined for $u \in U_T^c(\theta)$,

$$U_T(\theta) = d_T(\theta)(\Theta - \theta).$$

Our assumptions mean that the sets $U_T(\theta)$ are extending to \mathbf{R}^q as $T \rightarrow \infty$. Then, for all $R > 0$,

$$v^c(R) = \{u \in \mathbf{R}^q: \|u\| \leq R\} \subset U_T(\theta)$$

for $T > T_0(R)$.

The statistical meaning of the vectors $M_T(u)$ and $\Psi_T(u)$ is clear. Consider the functional $\gamma Q_T(\theta + d_T^{-1}(\theta)u)$. Then the normalized L_p -estimator \widehat{u}_T satisfies the following system of equations:

$$(10) \quad M_T(u) = 0.$$

Let

$$(11) \quad \eta(t) = \gamma \psi(\varepsilon(t)), \quad t \in \mathbf{R}^1,$$

and let the observations be of the following form:

$$(12) \quad Y(t) = g(t, \theta) + \eta(t), \quad t \in [0, T].$$

Then $\Psi_T(u) = 0$ is the system of normal equations determining the least squares estimator

$$\tilde{u}_T = \tilde{u}_T(\theta) = d_T(\theta)(\tilde{\theta}_T - \theta)$$

of the unknown parameter θ of the auxiliary nonlinear regression model (12).

Lemma 1. *Let Conditions A1, A2, and B1 hold. Then, for arbitrary $R > 0$ and $r > 0$,*

$$(13) \quad \mathbb{P} \left\{ \sup_{u \in v^c(R)} \|M_T(u) - \Psi_T(u)\| > r \right\} \xrightarrow{T \rightarrow \infty} 0.$$

Proof. For a fixed i , consider the difference

$$(14) \quad \begin{aligned} & M_T^i(u) - \Psi_T^i(u) \\ &= \gamma \int_0^T \frac{h_i(t, u)}{d_{iT}(\theta)} [\psi(\varepsilon(t) + H(t; 0, u)) - \psi(\varepsilon(t)) - \psi'(\varepsilon(t))H(t; 0, u)] dt \\ & \quad + \gamma \int_0^T H(t; 0, u) \frac{h_i(t, u)}{d_{iT}(\theta)} \zeta(t) dt \\ &= I_1(u) + I_2(u), \\ & \quad \zeta(t) = \psi'(\varepsilon(t)) - \mathbb{E} \psi'(\varepsilon(t)), \quad t \in \mathbf{R}^1. \end{aligned}$$

One needs to prove that $I_1(u)$ and $I_2(u)$ converge to zero in probability uniformly with respect to $u \in v^c(R)$. Let $u \in v^c(R)$ be fixed. Then

$$(15) \quad \mathbb{E} I_2^2(u) = \gamma^2 \int_0^T \int_0^T H(t; 0, u) H(s; 0, u) \frac{h_i(t, u)}{d_{iT}(\theta)} \frac{h_i(s, u)}{d_{iT}(\theta)} \text{cov}(\zeta(t), \zeta(s)) dt ds.$$

We have

$$\sup_{t \in [0, T]} |H(t; 0, u)| = \sup_{t \in [0, T]} \left| \sum_{i=1}^q \frac{h_i(t, u_t^*)}{d_{iT}(\theta)} u_i \right| \leq \|u\| \sup_{t \in [0, T]} \left(\sum_{i=1}^q \left[\frac{h_i(t, u_t^*)}{d_{iT}(\theta)} \right]^2 \right)^{1/2},$$

where $\|u_t^*\| \leq \|u\|$. Using (2), we obtain

$$(16) \quad \sup_{t \in [0, T]} |H(t; 0, u)| \leq T^{-1/2} \|k\| \cdot \|u\|,$$

where $k = (k^1, \dots, k^q)$ are the constants involved in inequality (2). Applying once more inequalities (16) and (2) to integral (15), we get

$$\mathbb{E} I_2^2(u) \leq \gamma^2 \|k\|^2 (k^i)^2 R^2 \frac{1}{T^2} \int_0^T \int_0^T |\text{cov}(\zeta(t), \zeta(s))| dt ds.$$

We show that

$$(17) \quad \frac{1}{T^2} \int_0^T \int_0^T |\text{cov}(\zeta(t), \zeta(s))| dt ds \rightarrow 0$$

as $T \rightarrow \infty$. Similarly to (6),

$$|\text{cov}(\psi'(\varepsilon(t)), \psi'(\varepsilon(s)))| \leq \text{Var} \psi'(\varepsilon(0)) |B(t - s)|$$

and

$$\begin{aligned} \frac{1}{T^2} \int_0^T \int_0^T |\text{cov}(\zeta(t), \zeta(s))| dt ds &\leq \frac{\text{Var} \psi'(\varepsilon(0))}{T^2} \int_0^T \int_0^T |B(t-s)| dt ds \\ &\leq \frac{2 \text{Var} \psi'(\varepsilon(0))}{T} \int_0^T |B(u)| du \rightarrow 0. \end{aligned}$$

This implies that $I_2(u) \xrightarrow{P} 0$ pointwise for $u \in v^c(R)$.

For $u_1, u_2 \in v^c(R)$, consider the difference

$$\begin{aligned} I_2(u_1) - I_2(u_2) &= \gamma \int_0^T H(t; 0, u_1) \frac{H_i(t; u_1, u_2)}{d_{iT}(\theta)} \zeta(t) dt - \gamma \int_0^T H(t; u_1, u_2) \frac{h_i(t, u_2)}{d_{iT}(\theta)} \zeta(t) dt \\ &= I_3(u_1, u_2) + I_4(u_1, u_2). \end{aligned}$$

For all $h > 0$ and $r > 0$, we write

$$(18) \quad \begin{aligned} \mathbb{P} \left\{ \sup_{\|u_1 - u_2\| \leq h} |I_3(u_1, u_2)| > r \right\} &\leq r^{-1} \mathbb{E} \sup_{\|u_1 - u_2\| \leq h} |I_3(u_1, u_2)| \\ &\leq 2r^{-1} T \sup_{\substack{t \in [0, T] \\ u \in v^c(R)}} |H(t; 0, u)| \sup_{\|u_1 - u_2\| \leq h} \sup_{t \in [0, T]} \frac{|H_i(t; u_1, u_2)|}{d_{iT}(\theta)}, \end{aligned}$$

$$(19) \quad \begin{aligned} \sup_{\|u_1 - u_2\| \leq h} \sup_{t \in [0, T]} \frac{|H_i(t; u_1, u_2)|}{d_{iT}(\theta)} &\leq h \sup_{t \in [0, T]} \left[\sum_{l=1}^q \left(\sup_{u \in v^c(R)} \frac{|h_{il}(t, u)|}{d_{il,T}(\theta)} \right) \frac{d_{il,T}(\theta)}{d_{iT}(\theta) d_{lT}(\theta)} \right] \\ &\leq \sum_{l=1}^q k^{il} \tilde{k}^{il} h T^{-1} \end{aligned}$$

by using conditions (3) and (4). Applying (16) and (19) in (18), we get

$$(20) \quad \mathbb{P} \left\{ \sup_{\|u_1 - u_2\| \leq h} |I_3(u_1, u_2)| > r \right\} \leq k_1 r^{-1} T^{-1/2} h,$$

where $k_1 = 2R \|k\| (\sum_{l=1}^q k^{il} \tilde{k}^{il})$. Similarly, we use inequality (2) and obtain

$$(21) \quad \begin{aligned} \mathbb{P} \left\{ \sup_{\|u_1 - u_2\| \leq h} |I_4(u_1, u_2)| > r \right\} &\leq r^{-1} \mathbb{E} \sup_{\|u_1 - u_2\| \leq h} |I_4(u_1, u_2)| \\ &\leq 2r^{-1} T \sup_{\substack{t \in [0, T] \\ u \in v^c(R)}} \frac{|h_i(t, u)|}{d_{iT}(\theta)} \sup_{\|u_1 - u_2\| \leq h} \sup_{t \in [0, T]} |H(t; u_1, u_2)| \leq k_2 r^{-1} h, \end{aligned}$$

where $k_2 = 2k^i \|k\|$. It follows from bounds (20) and (21) that

$$(22) \quad \mathbb{P} \left\{ \sup_{\|u_1 - u_2\| \leq h} |I_2(u_1) - I_2(u_2)| > r \right\} \leq 2r^{-1} h (k_1 T^{-1/2} + k_2) \leq k_3 r^{-1} h.$$

Denote by N_h a finite h -net of the ball $v^c(R)$. Then

$$(23) \quad \sup_{u \in v^c(R)} |I_2(u)| \leq \sup_{\|u_1 - u_2\| \leq h} |I_2(u_1) - I_2(u_2)| + \max_{u \in N_h} |I_2(u)|.$$

From (22) and (23) we obtain for all $r > 0$ that

$$\mathbb{P} \left\{ \sup_{u \in v^c(R)} |I_2(u)| > r \right\} \leq 2k_3 r^{-1} h + \mathbb{P} \left\{ \max_{u \in N_h} |I_2(u)| > \frac{r}{2} \right\}.$$

Let $\varepsilon > 0$ and $h = \varepsilon r / (4k_3)$. In view of the pointwise convergence in probability of $I_2(u)$ to zero we prove that

$$\mathbf{P} \left\{ \max_{u \in N_{\varepsilon r / (4k_3)}} |I_2(u)| > r/2 \right\} \leq \frac{\varepsilon}{2}$$

for $T > T_0$, whence

$$\mathbf{P} \left\{ \sup_{u \in v^c(R)} |I_2(u)| > r \right\} \leq \varepsilon.$$

On the other hand, if $u_T^* \in v^c(R)$ is a random variable, then

$$(24) \quad \begin{aligned} & \sup_{u \in v^c(R)} |I_1(u)| \\ & \leq \gamma \int_0^T \left| \frac{h_i(t, u_T^*)}{d_{iT}(\theta)} \right| |(\psi(\varepsilon(t) + H(t; 0, u_T^*)) - \psi(\varepsilon(t)) - \psi'(\varepsilon(t))H(t; 0, u_T^*))| dt. \end{aligned}$$

Let $\chi_T(t)$ be the indicator of the random event $\{|\varepsilon(t)| \leq 2\|k\|RT^{-1/2}\}$ and let

$$\bar{\chi}_T(t) = 1 - \chi_T(t).$$

Using inequality (2) again, we continue the estimation in (24) as follows:

$$\begin{aligned} & \sup_{u \in v^c(R)} |I_1(u)| \\ & \leq \gamma k^i T^{-1/2} \int_0^T |\psi(\varepsilon(t) + H(t; 0, u_T^*)) - \psi(\varepsilon(t)) - \psi'(\varepsilon(t))H(t; 0, u_T^*)| \chi_T(t) dt \\ & \quad + \gamma k^i T^{-1/2} \int_0^T |\psi(\varepsilon(t) + H(t; 0, u_T^*)) - \psi(\varepsilon(t)) - \psi'(\varepsilon(t))H(t; 0, u_T^*)| \bar{\chi}_T(t) dt \\ & = \Delta_1(T) + \Delta_2(T). \end{aligned}$$

Bound (16) implies that

$$\begin{aligned} \mathbf{E} \Delta_1(T) & \leq \gamma k^i p (3^{p-1} + 2^{p-1}) (\|k\|R)^{p-1} T^{-p/2} \int_0^T \left(\int_{\{|x| \leq 2\|k\|RT^{-1/2}\}} \varphi(x) dx \right) dt \\ & \quad + \gamma k^i p(p-1) \|k\| R \frac{1}{T} \int_0^T \left(\int_{\{|x| \leq 2\|k\|RT^{-1/2}\}} |x|^{p-2} \varphi(x) dx \right) dt \\ & \leq k_4 T^{(1-p)/2}, \end{aligned}$$

where $k_4 = 4\gamma k^i (2\pi)^{-1/2} p (\|k\|R)^p (3^{p-1} + 2^{p-1} + 2^{p-2})$. Therefore $\mathbf{E} \Delta_1(T) \rightarrow 0$ as $T \rightarrow \infty$.

Now we estimate $\mathbf{E} \Delta_2(T)$. Note that

$$(25) \quad \begin{aligned} & |\psi(\varepsilon(t) + H(t; 0, u_T^*)) - \psi(\varepsilon(t)) - \psi'(\varepsilon(t))H(t; 0, u_T^*)| \\ & = \frac{1}{2} |\psi''(\varepsilon(t) + \delta_t H(t; 0, u_T^*))| H^2(t; 0, u_T^*) \\ & \leq \frac{1}{2} p(p-1)(2-p) \frac{1}{|\varepsilon(t) + \delta_t H(t; 0, u_T^*)|^{3-p}} \|k\|^2 R^2 T^{-1} \end{aligned}$$

for some $\delta_i \in (0, 1)$. Let $k_5 = \frac{1}{2}\gamma k^i p(p-1)(2-p)\|k\|^2 R^2$. Taking into account (25), we obtain

$$(26) \quad \begin{aligned} \mathbb{E} \Delta_2(T) &\leq k_5 T^{-3/2} \int_0^T \left(\int_{\{|x| \geq 2\|k\|RT^{-1/2}\}} \frac{\varphi(x) dx}{(|x| - \|k\|RT^{-1/2})^{3-p}} \right) dt \\ &\leq \frac{2k_5}{\sqrt{2\pi}} T^{-1/2} \int_{2\|k\|RT^{-1/2}}^\infty \frac{dx}{(x - \|k\|RT^{-1/2})^{3-p}} = k_6 T^{(1-p)/2}, \end{aligned}$$

where $k_6 = \gamma k^i (2\pi)^{-1/2} p(p-1)\|k\|^p R^p$, that is, $\mathbb{E} \Delta_2(T) \rightarrow 0$.

Bounds (25) and (26) yield

$$\sup_{u \in v^c(R)} |I_1(u)| \xrightarrow{P} 0 \quad \text{as } T \rightarrow \infty.$$

Lemma 1 is proved. \square

Consider the random vector

$$(27) \quad L_T(u) = (L_T^i(u))_{i=1}^q = \left(\int_0^T \left(\eta(t) - \sum_{l=1}^q \frac{g_l(t, \theta)}{d_{lT}(\theta)} u_l \right) \frac{g_i(t, \theta)}{d_{iT}(\theta)} dt \right)_{i=1}^q$$

corresponding to the auxiliary linear regression model

$$Z(t) = \sum_{i=1}^q g_i(t, \theta) \beta_i + \eta(t), \quad t \in [0, T],$$

where $\eta(t)$ is defined by equality (11).

The system of normal equations

$$(28) \quad L_T(u) = 0$$

determines a normalized linear least squares estimator $\tilde{\beta}_T$ of the parameter $\beta \in \mathbf{R}^q$; namely,

$$(29) \quad \tilde{u}_T = \tilde{u}_T(\theta) = d_T(\theta)(\tilde{\beta}_T - \beta).$$

Lemma 2. *If Conditions A1, A2, and B1 hold, then*

$$(30) \quad \mathbb{P} \left\{ \sup_{u \in v^c(R)} \|\Psi_T(u) - L_T(u)\| > r \right\} \rightarrow 0 \quad \text{as } T \rightarrow \infty$$

for all $R > 0$ and $r > 0$.

Proof. For an arbitrary $i \in \{1, \dots, q\}$,

$$\begin{aligned} \Psi_T^i(u) - L_T^i(u) &= \int_0^T \eta(t) \frac{h_i(t, u)}{d_{iT}(\theta)} dt + \int_0^T H(t; 0, u) \frac{h_i(t, u)}{d_{iT}(\theta)} dt - \int_0^T \eta(t) \frac{g_i(t, \theta)}{d_{iT}(\theta)} dt \\ &\quad + \int_0^T \frac{g_i(t, \theta)}{d_{iT}(\theta)} \sum_{l=1}^q \frac{g_l(t, \theta)}{d_{lT}(\theta)} u_l dt \\ &= \int_0^T \eta(t) \frac{H_i(t; u, 0)}{d_{iT}(\theta)} dt + \int_0^T H(t; 0, u) \frac{H_i(t; u, 0)}{d_{iT}(\theta)} dt \\ &\quad + \int_0^T \frac{g_i(t, \theta)}{d_{iT}(\theta)} \left[H(t; 0, u) + \sum_{l=1}^q \frac{g_l(t, \theta)}{d_{lT}(\theta)} u_l \right] dt \\ &= I_5(u) + I_6(u) + I_7(u). \end{aligned}$$

Let $u \in v^c(R)$ be fixed. Using inequalities (6) and (19), we obtain

$$\begin{aligned} \mathbb{E} I_5^2(u) &= \int_0^T \int_0^T \text{cov}(\eta(t), \eta(s)) \frac{H_i(t; u, 0)}{d_{iT}(\theta)} \frac{H_i(s; u, 0)}{d_{iT}(\theta)} dt ds \\ &\leq \left(\sum_{l=1}^q k^{il} \tilde{k}^{il} \right)^2 R^2 \frac{1}{T^2} \int_0^T \int_0^T |\text{cov}(\eta(t), \eta(s))| dt ds \rightarrow 0 \quad \text{as } T \rightarrow \infty; \end{aligned}$$

that is, $I_5(u) \xrightarrow{\mathbb{P}} 0$ as $T \rightarrow \infty$ pointwise for $u \in v^c(R)$. On the other hand,

$$\mathbb{E} \sup_{\|u_1 - u_2\| \leq h} |I_5(u_1) - I_5(u_2)| \leq |\gamma| \mathbb{E} |\psi(\varepsilon(0))| \left(\sum_{l=1}^q k^{il} \tilde{k}^{il} \right) h$$

in view of (19). Similarly to the proof of the convergence of $I_2(u)$ in Lemma 1, one can show that $I_5(u)$ converges uniformly to zero in probability with respect to $u \in v^c(R)$.

Taking into account inequalities (16) and (19) we get

$$\sup_{u \in v^c(R)} |I_6(u)| \leq \|k\| \left(\sum_{l=1}^q k^{il} \tilde{k}^{il} \right) R^2 T^{-1/2} \rightarrow 0 \quad \text{as } T \rightarrow \infty.$$

The term $I_7(u)$ can be represented as follows:

$$I_7(u) = -\frac{1}{2} \sum_{j,l=1}^q \left(\int_0^T \frac{h_{jl}(t, u_T^*)}{d_{jT}(\theta) d_{lT}(\theta)} \frac{g_i(t, \theta)}{d_{iT}(\theta)} dt \right) u_j u_l$$

for some $u_T^* \in v(R)$. Under Condition **B1** we have

$$|I_7(u)| \leq \frac{k^i}{2} \sum_{j,l=1}^q (k^{jl} \tilde{k}^{jl} |u_j| |u_l|) T^{-1/2} \leq \frac{qk^i}{2} \max_{j,l=1,\dots,q} [k^{jl} \tilde{k}^{jl}] \|u\|^2 T^{-1/2},$$

whence $\sup_{u \in v^c(R)} |I_7(u)| \rightarrow 0$. Lemma 2 is proved. \square

Relations (13) and (30) imply the following corollary.

Corollary. *Let Conditions **A1**, **A2**, and **B1** hold. Then*

$$(31) \quad \mathbb{P} \left\{ \sup_{u \in v^c(R)} \|M_T(u) - L_T(u)\| > r \right\} \rightarrow 0 \quad \text{as } T \rightarrow \infty$$

for all $R > 0$ and $r > 0$.

Using (27) and (28) one can evaluate \tilde{u}_T in an explicit form (see (29)) if Condition **B2** holds; namely,

$$(32) \quad \tilde{u}_T = \Lambda_T(\theta) \int_0^T \eta(t) d_T^{-1}(\theta) \nabla g(t, \theta) dt,$$

where $\Lambda_T(\theta) = J_T^{-1}(\theta)$ and $\nabla g(t, \theta)$ is the gradient of the function $g(t, \theta)$:

$$\nabla g(t, \theta) = \begin{bmatrix} g_1(t, \theta) \\ \vdots \\ g_q(t, \theta) \end{bmatrix}.$$

Note that the covariance matrix of the vector \tilde{u}_T is given by

$$\sigma_T(\theta) = 2\pi\gamma^2 \left(\int_{\mathbf{R}^1} \mu_T(dx; \theta) \right)^{-1} \left(\int_{\mathbf{R}^1} f_\psi(x) \mu_T(dx; \theta) \right) \left(\int_{\mathbf{R}^1} \mu_T(dx; \theta) \right)^{-1}.$$

Consider the random event

$$(33) \quad A_T = \{\tilde{u}_T \in v^c(R-r)\}.$$

Lemma 3. *Let Conditions **B2** and (2) hold. Then, for arbitrary $\varepsilon > 0$ and $r > 0$, there exists $R > r$ such that $\mathbf{P}\{\bar{A}_T\} \leq \varepsilon$ for $T > T_0$.*

Proof. Fix $\varepsilon > 0$. Analogously to the proof of convergence (17) we derive that

$$\begin{aligned} \mathbf{P}\{\bar{A}_T\} &= \mathbf{P}\{\|\tilde{u}_T\| > R-r\} \leq \frac{\mathbf{E}\|\tilde{u}_T\|^2}{(R-r)^2} \\ &\leq \frac{1}{\lambda_*^2(R-r)^2} \sum_{i=1}^q \int_0^T \int_0^T \left| \text{cov}(\eta(t), \eta(s)) \frac{g_i(t, \theta)}{d_{iT}(\theta)} \frac{g_i(s, \theta)}{d_{iT}(\theta)} \right| dt ds \\ &\leq \frac{\|k\|^2}{T\lambda_*^2(R-r)^2} \int_0^T \int_0^T |\text{cov}(\eta(t), \eta(s))| dt ds \leq \frac{k_6}{(R-r)^2}, \end{aligned}$$

where $k_6 = 2(\lambda_*)^{-2}\gamma^2\|k\|^2 \mathbf{E}(\psi(\varepsilon(0)))^2 \int_0^\infty |B(u)| du$.

Setting $R = r + \sqrt{k_6/\varepsilon}$ we get the desired result. \square

We need the following results for the proof of the theorem.

Proposition 1. *Let $F: v^c(R) \rightarrow v^c(R)$ be a continuous mapping. Then there exists $x_0 \in v^c(R)$ such that $F(x_0) = x_0$.*

This proposition is a special case of the Brouwer fixed point theorem (see, for example, [4]).

Proposition 2. *Let Conditions **A1**, **A2**, **B2**, and **B3** hold. Then the random vector \tilde{u}_T defined by (32) is asymptotically normal with parameters 0 and $\sigma(\theta)$, where the covariance function $\sigma(\theta)$ is defined by (7).*

The latter result is a multivariate central limit theorem for the integral of a weighted stationary stochastic process satisfying the weak dependence condition. A more general result of this kind as well as its proof can be found in [9] (Theorem 1.7.5).

Let \mathcal{B}^q be the σ -algebra of Borel sets of \mathbf{R}^q . For $C \in \mathcal{B}^q$ and $\varepsilon > 0$, let

$$C_\varepsilon = \{x: x \in \mathbf{R}^q, d(x, C) < \varepsilon\},$$

where $d(x, C) = \inf_{y \in C} \|x - y\|$ and $C_{-\varepsilon} = \mathbf{R}^q \setminus (\mathbf{R}^q \setminus C)_\varepsilon$.

Proposition 3. *Let $\nu \geq 0$ be a differentiable function defined on $[0, \infty)$ and such that*

$$b = \int_0^\infty |\nu'(\lambda)|\lambda^{q-1} d\lambda < \infty, \quad \lim_{\lambda \rightarrow \infty} \nu(\lambda) = 0.$$

Then

$$\int_{C_\varepsilon \setminus C_{-\delta}} \nu(\|x\|) dx \leq b \left(\frac{2\pi^{q/2}}{\Gamma(q/2)} \right) (\varepsilon + \delta)$$

for an arbitrary convex set $C \in \mathcal{B}^q$ and for all $\varepsilon, \delta > 0$.

The proof of the latter result can be found in §3 of the book [3].

3. PROOF OF THE THEOREM

One needs to prove that the distribution function $G_T(y, \theta)$ of the random vector \hat{u}_T defined by (9) converges as $T \rightarrow \infty$ to the Gaussian distribution function $\Phi_{0, \sigma(\theta)}(y)$. Note that $\sigma(\theta)$ is a positive definite matrix (7) in view of Conditions **B2** and **B3**.

We show that

$$(34) \quad \Delta_T(r) = \mathbb{P}\{\|\hat{u}_T - \tilde{u}_T\| > r\} \rightarrow 0, \quad T \rightarrow \infty,$$

for all $r > 0$.

Let A_T be the random event defined by equality (33) and let R be such that $\mathbb{P}\{\bar{A}_T\} \leq \frac{\varepsilon}{3}$ (this inequality holds by Lemma 3), where $\varepsilon > 0$ is a fixed but small number.

We also consider the following random events:

$$B_T = \left\{ \sup_{u \in v^c(R)} \|\Lambda_T(\theta)(M_T(u) - L_T(u))\| \leq r \right\},$$

$$C_T = \{\text{system of equations (10) has a unique solution in the ball } v^c(R)\}.$$

Conditions **B2** and **C** together with the corollary to Lemmas 1 and 2 imply for $T > T_0$ that

$$\mathbb{P}\{\bar{B}_T\} \leq \mathbb{P}\left\{ \sup_{u \in v^c(R)} \|M_T(u) - L_T(u)\| > \lambda_* r \right\} \leq \frac{\varepsilon}{3},$$

$$\mathbb{P}\{\bar{C}_T\} \leq \frac{\varepsilon}{3},$$

whence

$$(35) \quad \mathbb{P}\{A_T \cap B_T \cap C_T\} > 1 - \varepsilon$$

for $T > T_0$.

Taking into account relations (27) and (32) we get $\Lambda_T(\theta)L_T(u) = \tilde{u}_T - u$. If the event $A_T \cap B_T \cap C_T$ occurs, then

$$\|u + \Lambda_T(\theta)M_T(u)\| \leq \|\Lambda_T(\theta)(M_T(u) - L_T(u))\| + \|\tilde{u}_T\| \leq r + (R - r) = R$$

for $u \in v^c(R)$; that is, $F_T(u) = u + \Lambda_T(\theta)M_T(u)$ is a continuous mapping of $v^c(R)$ to $v^c(R)$. To prove (34) we apply the Brouwer fixed point theorem (see Proposition 1).

Applying this theorem to $F_T(u)$, we prove that there exists a point $u_T^0 \in v^c(R)$ such that $F_T(u_T^0) = u_T^0$. Since $\Lambda_T(\theta)$ is nonsingular, we also have $M_T(u_T^0) = 0$. According to Condition **C**, the normalized L_p -estimator \hat{u}_T is a unique solution of the system of equations $M_T(u) = 0$. Therefore $A_T \cap B_T \cap C_T \subset \{\hat{u}_T \in v^c(R)\}$ and hence

$$\mathbb{P}\{\hat{u}_T \in v^c(R)\} > 1 - \varepsilon.$$

Note also that inequality (35) yields

$$(36) \quad 1 - \varepsilon < \mathbb{P}\{\{\hat{u}_T \in v^c(R)\} \cap B_T\}$$

$$\leq \mathbb{P}\{\|\Lambda_T(\theta)(M_T(\hat{u}_T) - L_T(\hat{u}_T))\| \leq r\} = \mathbb{P}\{\|\hat{u}_T - \tilde{u}_T\| \leq r\}.$$

Relation (36) for all $\varepsilon > 0$ is equivalent to (34).

Put $\Pi(-\infty, y \pm \bar{\varepsilon}) = (-\infty, y_1 \pm \varepsilon) \times \cdots \times (-\infty, y_q \pm \varepsilon)$, $\varepsilon \geq 0$. Considering relation (34), we prove for the distribution function $G_T(y, \theta) = \mathbb{P}\{\hat{u}_T \in \Pi(-\infty, y)\}$ that

$$-\Delta_T(\varepsilon) + \mathbb{P}\{\tilde{u}_T \in \Pi(-\infty, y - \bar{\varepsilon})\} \leq G_T(y, \theta) \leq \mathbb{P}\{\tilde{u}_T \in \Pi(-\infty, y + \bar{\varepsilon})\} + \Delta_T(\varepsilon).$$

Proposition 2 implies that

$$(37) \quad |\mathbb{P}\{\tilde{u}_T \in \Pi(-\infty, y \pm \bar{\varepsilon})\} - \Phi_{0, \sigma(\theta)}(y \pm \bar{\varepsilon})| \rightarrow 0$$

as $T \rightarrow \infty$.

Let $\varphi(y, \theta)$ be the Gaussian density corresponding to the distribution function

$$\Phi_{0, \sigma(\theta)}(y).$$

Since $\lambda_{\min}(\sigma(\theta)) = \underline{\lambda} > 0$ and $\lambda_{\max}(\sigma(\theta)) = \bar{\lambda} < \infty$, we get

$$\varphi(y, \theta) \leq (2\pi\underline{\lambda})^{-q/2} \exp\{-\|y\|^2/2\bar{\lambda}\} = \nu(\|y\|).$$

If $A = \Pi(-\infty, y)$, then $A_{-\varepsilon} = \Pi(-\infty, y - \vec{\varepsilon})$ and $(\Pi(-\infty, y + \vec{\varepsilon}))_{-\varepsilon} = \Pi(-\infty, y) = A^c$. Applying Proposition 3 to the function $\nu(\|y\|)$ we conclude that

$$(38) \quad \begin{aligned} |\Phi_{0, \sigma(\theta)}(y) - \Phi_{0, \sigma(\theta)}(y + \vec{\phi})| &= \int_{\Pi} \varphi(y, \theta) dy \leq b \left(\frac{2\pi^{q/2}}{\Gamma(q/2)} \right) |\phi|, \\ \Pi &= \begin{cases} \Pi(-\infty, y + \vec{\phi}) \setminus A^c & \text{if } \phi > 0, \\ A \setminus A_{\phi} & \text{if } \phi < 0, \end{cases} \end{aligned}$$

for all $\phi \neq 0$.

Further

$$(39) \quad \begin{aligned} G_T(y, \theta) - \Phi_{0, \sigma(\theta)}(y) &\leq \Delta_T(\varepsilon) + |\mathbb{P}\{\tilde{u}_T \in \Pi(-\infty, y + \vec{\varepsilon})\} - \Phi_{0, \sigma(\theta)}(y + \vec{\varepsilon})| \\ &\quad + |\Phi_{0, \sigma(\theta)}(y + \vec{\varepsilon}) - \Phi_{0, \sigma(\theta)}(y)|, \end{aligned}$$

$$(40) \quad \begin{aligned} \Phi_{0, \sigma(\theta)}(y) - G_T(y, \theta) &\leq |\Phi_{0, \sigma(\theta)}(y) - \Phi_{0, \sigma(\theta)}(y - \vec{\varepsilon})| \\ &\quad + |\Phi_{0, \sigma(\theta)}(y - \vec{\varepsilon}) - \mathbb{P}\{\tilde{u}_T \in \Pi(-\infty, y - \vec{\varepsilon})\}| + \Delta_T(\varepsilon) \end{aligned}$$

for all $y \in \mathbf{R}^q$ and $\varepsilon > 0$. Applying (37) and (38) to (39), (40) we obtain the desired result.

4. EXAMPLE

Consider the regression model

$$(41) \quad X(t) = A_0 \cos \omega_0 t + B_0 \sin \omega_0 t + \varepsilon(t), \quad t \in (0, \infty),$$

where $\varepsilon(t)$, $t \in \mathbf{R}^1$, is a stochastic process satisfying Conditions **A1** and **A2** and having the covariance function $B(t) = e^{-\lambda|t|}$. The vector of parameters

$$\theta = (\theta_1, \theta_2, \theta_3) = (A_0, B_0, \omega_0)$$

belongs to an open bounded set and moreover $A_0^2 + B_0^2 > 0$ and $0 < \underline{\omega} < \omega_0 < \bar{\omega} < \infty$.

Consider the loss function $\rho(x) = |x|^p$, $p \in (\frac{3}{2}; 2)$.

It is easy to check that

$$\begin{aligned} d_{1T}^2(\theta) &= \frac{T}{2} + \frac{1}{4\omega} \sin 2\omega t, & d_{2T}^2(\theta) &= \frac{T}{2} - \frac{1}{4\omega} \sin 2\omega t, \\ d_{3T}^2(\theta) &= \frac{A^2 + B^2}{6} T^3 + O(T^2), & d_{11,T}^2(\theta) &= d_{12,T}^2(\theta) = d_{21,T}^2(\theta) = d_{22,T}^2(\theta) = 0, \\ d_{13,T}^2(\theta) &= d_{31,T}^2(\theta) = \frac{T^3}{6} + O(T^2), & d_{23,T}^2(\theta) &= d_{32,T}^2(\theta) = \frac{T^3}{6} + O(T^2), \\ d_{33,T}^2(\theta) &= \frac{A^2 + B^2}{10} T^5 + O(T^4). \end{aligned}$$

Condition **B1** is easy to check, too. Further

$$\lim_{T \rightarrow \infty} J_T(\theta) = J(\theta) = \begin{pmatrix} 1 & 0 & \frac{B_0}{\sqrt{4(A_0^2 + B_0^2)/3}} \\ 0 & 1 & -\frac{A_0}{\sqrt{4(A_0^2 + B_0^2)/3}} \\ \frac{B_0}{\sqrt{4(A_0^2 + B_0^2)/3}} & -\frac{A_0}{\sqrt{4(A_0^2 + B_0^2)/3}} & 1 \end{pmatrix}.$$

The above matrix $J(\theta)$ is positive definite; that is, Condition **B2** holds.

It is known that the spectral measure for the regression function of the model (41) is given by

$$\mu(dx, \theta) = \begin{pmatrix} \delta_{\omega_0}(dx) & i\rho_{\omega_0}(dx) & \frac{B_0\delta_{\omega_0}(dx) - iA_0\rho_{\omega_0}(dx)}{\sqrt{\frac{4}{3}(A_0^2 + B_0^2)}} \\ -i\rho_{\omega_0}(dx) & \delta_{\omega_0}(dx) & \frac{-A_0\delta_{\omega_0}(dx) - iB_0\rho_{\omega_0}(dx)}{\sqrt{\frac{4}{3}(A_0^2 + B_0^2)}} \\ \frac{B_0\delta_{\omega_0}(dx) + iA_0\rho_{\omega_0}(dx)}{\sqrt{\frac{4}{3}(A_0^2 + B_0^2)}} & \frac{-A_0\delta_{\omega_0}(dx) + iB_0\rho_{\omega_0}(dx)}{\sqrt{\frac{4}{3}(A_0^2 + B_0^2)}} & \delta_{\omega_0}(dx) \end{pmatrix}$$

(see, for example, [7]) where the measure δ_{ω_0} and the charge ρ_{ω_0} are concentrated at the points $\pm\omega_0$ and

$$\delta_{\omega_0}(\{\pm\omega_0\}) = \frac{1}{2}, \quad \rho_{\omega_0}(\{\pm\omega_0\}) = \pm\frac{1}{2}.$$

This means that

$$\int_{\mathbf{R}} f_{\psi}(x) \mu(dx) = f_{\psi}(\omega_0) J(\theta).$$

If $f_{\psi}(\omega_0) \neq 0$, then $\int_{\mathbf{R}} f_{\psi}(x) \mu(dx)$ is a positive definite matrix and Condition **B3** holds.

It remains to note that the assumptions of the paper [24] are satisfied for model (41) and that they imply Condition **C**. Now one can apply our theorem. Using the above evaluation of $d_T(\theta)$, one can adjust the representation of the normalized L_p -estimator as follows:

$$(42) \quad \hat{u}_T = \begin{pmatrix} \sqrt{\frac{T}{2}}(\hat{A} - A_0) \\ \sqrt{\frac{T}{2}}(\hat{B} - B_0) \\ \sqrt{\frac{A_0^2 + B_0^2}{2}} T^{3/2}(\hat{\omega} - \omega_0) \end{pmatrix}$$

(see [7] for more details). According to this normalization, the covariance function of the asymptotic normal distribution becomes of the following form:

$$(43) \quad \sigma(\theta) = \frac{4\pi\gamma^2 f_{\psi}(\omega_0)}{A_0^2 + B_0^2} \begin{pmatrix} A_0^2 + 4B_0^2 & -3A_0B_0 & -6B_0 \\ -3A_0B_0 & 4A_0^2 + B_0^2 & 6A_0 \\ -6B_0 & 6A_0 & 12 \end{pmatrix},$$

where γ is defined by (8).

Considering the expansion of the function $\psi(\varepsilon(t))$ in the series (5) with respect to the Hermite–Chebyshev polynomials, we obtain the following representation of the spectral density:

$$(44) \quad f_{\psi}(\lambda) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-i\lambda t} B_{\psi}(t) dt = \sum_{n=1}^{\infty} \frac{C_n^2(\psi)}{n!} f_n(\lambda),$$

where $f_n(\lambda) = (2\pi)^{-1} \int_{-\infty}^{\infty} e^{-i\lambda t} B^n(t) dt$. By assumption,

$$f_n(\lambda) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-i\lambda t} e^{-n\kappa|t|} dt = \frac{n\kappa}{\pi(n^2\kappa^2 + \lambda^2)}.$$

Since ψ is an odd function, $C_{2k}(\psi) = 0$; that is,

$$\sigma(\theta) = \frac{4\kappa\gamma^2}{A_0^2 + B_0^2} \left(\sum_{k=0}^{\infty} \frac{C_{2k+1}^2(\psi)}{(2k)! ((2k+1)^2\kappa^2 + \omega_0^2)} \right) \begin{pmatrix} A_0^2 + 4B_0^2 & -3A_0B_0 & -6B_0 \\ -3A_0B_0 & 4A_0^2 + B_0^2 & 6A_0 \\ -6B_0 & 6A_0 & 12 \end{pmatrix}.$$

The coefficients $C_{2k+1}(\psi)$ are the values of known integrals (see, for example, relation 7.376.3 in the book [5]).

BIBLIOGRAPHY

1. T. A. Bardadym and A. V. Ivanov, *Asymptotic normality of l_α -estimators of parameters of a nonlinear regression model*, Dokl. Akad. Nauk Ukrain. SSR Ser. A (1988), no. 8, 68–70, 88. (Russian) MR966270 (90h:62208)
2. T. A. Bardadym and A. V. Ivanov, *On the asymptotic normality of l_α -estimators of a parameter of a nonlinear regression model*, Teor. Imovir. Mat. Stat. **60** (1999), 1–10; English transl. in Theory Probab. Math. Statist. **60** (2000), 1–11. MR1826135
3. R. N. Bhattacharya and R. Ranga Rao, *Normal Approximation and Asymptotic Expansions*, John Wiley & Sons, New York–London–Sydney, 1976. MR0436272 (55:9219)
4. Yu. V. Goncharenko and S. I. Lyashko, *Brouwer's Theorem*, Kii, Kiev, 2000. (Russian)
5. I. S. Gradshteyn and I. M. Ryzhik, *Table of Integrals, Series, and Products*, GIFML, Moscow, 1963; English transl., Academic Press, New York–London, 1965. MR0197789 (33:5952)
6. I. A. Ibragimov and Yu. A. Rozanov, *Gaussian Random Processes*, Nauka, Moscow, 1970; English transl., Springer-Verlag, New York–Berlin, 1978. MR543837 (80f:60038)
7. A. V. Ivanov, *A solution of the problem of detecting hidden periodicities*, Teor. Veroyatnost. i Mat. Statist. **20** (1979), 44–59; English transl. in Theory Probab. Math. Statist. **20** (1980), 51–68. MR529259 (80c:62107)
8. A. V. Ivanov, *On the consistency of l_α -estimators for the parameters of a regression function*, Teor. Veroyatnost. i Mat. Statist. **42** (1990), 42–48; English transl. in Theory Probab. Math. Statist. **42** (1991), 47–53. MR1069312 (92a:62043)
9. A. V. Ivanov and N. N. Leonenko, *Statistical Analysis of Random Fields*, Vyscha Shkola, Kiev, 1986; English transl., Kluwer Academic Publishers Group, Dordrecht, 1989. MR917486 (89e:62125)
10. A. V. Ivanov and I. V. Orlovskii, *Asymptotic normality of Koenker–Bassett estimators in nonlinear regression models*, Teor. Veroyatnost. i Mat. Statist. **72** (2005), 30–41; English transl. in Theory Probab. Math. Statist. **72** (2006), 33–45. MR2168134 (2007b:62029)
11. A. V. Ivanov and I. V. Orlovskii, *The consistency of M -estimators in nonlinear regression models with continuous time*, Naukovi visti NTUU KPI (2005), no. 4 (42), 140–147. (Ukrainian)
12. I. V. Orlovskii, *The consistency of Koenker–Bassett estimators in nonlinear regression models*, Naukovi visti NTUU KPI (2004), no. 3 (35), 144–150.
13. P. Huber, *Robust statistics*, John Wiley & Sons, Inc., New York, 1981. MR606374 (82i:62057)
14. L. Schmetterer, *Introduction to Mathematical Statistics*, Springer-Verlag, Berlin–New York, 1974; Translated from the second German edition. MR0359100 (50:11555)
15. M. A. Arcones, *Asymptotic theory of M -estimators over a convex kernel*, Econometric Theory **14** (1998), no. 4, 387–422. MR1650029 (99m:62029)
16. X. R. Chen and Y. H. Wu, *Strong consistency of M -estimates in linear models*, J. Multivariate Anal. **27** (1988), 116–130. MR971177 (90k:62140)
17. S. A. van de Geer, *Empirical Processes in M -Estimation*, Cambridge University Press, 2000.
18. L. Giraitis and H. L. Koul, *Estimation of the dependence parameter in linear regression with long-range-dependent errors*, Stochastic Process. Appl. **71** (1997), no. 2, 207–224. MR1484160 (99b:62145)
19. L. Giraitis, H. L. Koul, and D. Surgailis, *Asymptotic normality of regression estimators with long memory errors*, Stat. Probab. Letters **29** (1996), 317–335. MR1409327 (97h:62055)
20. U. Grenander and M. Rosenblatt, *Statistical Analysis of Stationary Time Series*, Almqvist and Wiksell, Stockholm, 1956. MR0084975 (18:959b)
21. F. R. Hampel, E. M. Ronchetti, P. J. Rousseeuw, and W. A. Stahel, *Robust Statistics. The Approach Based on Influence Functions*, Wiley, New York, 1986. MR829458 (87k:62054)
22. P. J. Huber, *Robust regression: asymptotics, conjectures and Monte-Carlo*, Ann. Statist. **1** (1973), no. 5, 799–821. MR0356373 (50:8843)
23. A. V. Ivanov, *Asymptotic Theory of Nonlinear Regression*, Kluwer, Dordrecht, 1997. MR1472234 (99h:62086)
24. A. V. Ivanov, *Asymptotic properties of L_p -estimators*, Theor. Stoch. Process. **14** (30) (2008), no. 1, 60–68. MR2479706
25. A. V. Ivanov and N. N. Leonenko, *Asymptotic behavior of M -estimators in continuous-time non-linear regression with long-range dependent errors*, Random Oper. Stoch. Equ. **10** (2002), no. 3, 201–222. MR1923424 (2003k:62080)
26. A. V. Ivanov and I. V. Orlovsky, *L_p -estimates in nonlinear regression with long-range dependence*, Theor. Stoch. Process. **7** (23) (2002), no. 3–4, 38–49.
27. A. V. Ivanov and I. V. Orlovsky, *Parameter estimators of nonlinear quantile regression*, Theor. Stoch. Process. **11** (27) (2005), no. 3–4, 82–91. MR2330004 (2008j:62068)

28. R. I. Jennrich, *Asymptotic properties of non-linear least squares estimators*, Ann. Math. Statist. **40** (1969), 633–643. MR0238419 (38:6695)
29. J. Jurečková, *Consistency of M -estimators in a linear model, generated by nonmonotone and discontinuous ψ -functions*, Probab. Math. Statist. **10** (1989), 1–10. MR990395 (90g:62155)
30. H. L. Koul, *M -estimators in linear models with long range dependent errors*, Stat. Probab. Letters **14** (1992), 153–164. MR1173413 (93f:62124)
31. H. L. Koul, *Asymptotics of M -estimations in non-linear regression with long-range dependence errors*, Proc. Athens Conf. Appl. Probab. and Time Ser. Analysis (P. M. Robinson and M. Rosenblatt, eds.), Lecture Notes in Statistics, vol. II, Springer-Verlag, 1996, pp. 272–291. MR1466752 (98g:62124)
32. H. L. Koul, R. T. Baillie, and D. Surgailis, *Regression model fitting with a long memory covariance process*, Economic Theory **20** (2004), 485–512. MR2061725 (2005e:62124)
33. H. L. Koul and K. Mukherjee, *Regression quantiles and related processes under long range dependent errors*, J. Multivariate Anal. **51** (1994), 318–337. MR1321301 (96e:62153)
34. H. L. Koul and D. Surgailis, *Asymptotic expansion of M -estimators with long memory errors*, Ann. Statist. **25** (1997), 818–850. MR1439325 (98c:62172)
35. H. L. Koul and D. Surgailis, *Second order behavior of M -estimators in linear regression with long-memory errors*, J. Statist. Plann. Inference **91** (2000), 399–412. MR1814792 (2001m:62101)
36. H. L. Koul and D. Surgailis, *Robust estimators in regression models with long memory errors*, Theory and Application of Long-Range Dependence (P. Doukhan, G. Oppenheim, and M. S. Taqqu, eds.), Birkhäuser, Boston, 2003, pp. 339–353. MR1957498
37. F. Liese, *Necessary and sufficient conditions for consistency of approximate M -estimators in nonlinear models*, Proc. Prague Stochastics, 1998, pp. 357–360.
38. F. Liese and I. Vajda, *Asymptotic Normality of M -Estimators in Nonlinear Regression*, Research Report No. 1714, UTIA, Prague, 1991.
39. F. Liese and I. Vajda, *Consistency of M -Estimators in Nonlinear Regression*, Research Report No. 1713, UTIA, Prague, 1991.
40. F. Liese and I. Vajda, *Consistency of M -estimates in general regression models*, J. Multivariate Anal. **50** (1994), no. 1, 93–114. MR1292610 (95g:62133)
41. F. Liese and I. Vajda, *Necessary and sufficient conditions for consistency of generalized M -estimates*, Metrika **42** (1995), 291–324. MR1380211 (97b:62039)
42. F. Liese and I. Vajda, *A General Asymptotic Theory of M -Estimators*, Research Report No. 1951, UTIA, Prague, 1999.
43. Ch. H. Müller, *Robust Planning and Analysis of Experiments*, Lecture Notes in Statistics, Springer, New York, 1997. MR1454843 (98g:62140)
44. I. V. Orlovsky, *M -estimates in nonlinear regression with weak dependence*, Theor. Stoch. Process. **9(25)** (2003), no. 1–2, 108–122. MR2080017 (2005i:62099)
45. J. Pfanzagl, *On the measurability and consistency of minimum contrast estimates*, Metrika **14** (1969), 249–272.
46. A. E. Ronner, *Asymptotic normality of p -norm estimators in multiple regression*, Z. Wahrsch. verw. Gebiete. **66** (1984), 613–620. MR753816 (86a:62042)
47. Y. Wu and M. M. Zen, *A strongly consistent information criterion for linear model selection based on M -estimation*, Probab. Theory Related Fields **113** (1999), 599–625. MR1717532 (2000g:62167)

DEPARTMENT OF MATHEMATICAL ANALYSIS AND PROBABILITY THEORY, NATIONAL TECHNICAL UNIVERSITY OF UKRAINE, KYIV POLYTECHNICAL INSTITUTE, PEREMOGY AVENUE 37, KYIV-56, 03056, UKRAINE

E-mail address: ivanov@paligora.kiev.ua

DEPARTMENT OF MATHEMATICAL ANALYSIS AND PROBABILITY THEORY, NATIONAL TECHNICAL UNIVERSITY OF UKRAINE, KYIV POLYTECHNICAL INSTITUTE, PEREMOGY AVENUE 37, KYIV-56, 03056, UKRAINE

E-mail address: avalon@ukrpost.ua

Received 11/SEP/2008

Translated by OLEG KLESOV