ASYMPTOTIC BEHAVIOR OF THE DISTRIBUTION
OF THE MAXIMUM OF A CHENTSOV FIELD
ON POLYGONAL LINES

UDC 519.21

N. V. KRUGLOVA

Abstract. Let \( X(s, t) \) be a two-parameter Chentsov field. The asymptotic behavior of the tail of the distribution of the maximum of the field \( X(s, t) \) on a polygonal line with several linear sections is found in the paper.

1. Introduction

We consider a two-parameter Chentsov field \( X(s, t) \) (also known as the Brownian sheet). The definition of such a field was given in 1955 by Chentsov [1] in terms of densities of the distribution of the field \( X(s, t) \). We use an equivalent definition due to Yeh [9]. Let \( D = [0, 1] \times [0, 1] \).

Definition 1.1. A real separable Gaussian random field \{ \( X(s, t) \): \( (s, t) \in D \) \} is called a Chentsov field if

1) \( X(0, t) = X(s, 0) = 0 \) for all \( s, t \in [0, 1] \);
2) \( E[X(s, t)] = 0 \) for all \( (s, t) \in D \);
3) \( E[X(s, t)X(s_1, t_1)] = \min\{s, s_1\} \min\{t, t_1\} \) for all \( (s, t) \in D \) and \( (s_1, t_1) \in D \).

The closed form of the distribution of functionals such as max\( (s, t) \in D \) \( X(s, t) \) is still unknown for Chentsov fields. The distribution of the supremum of \( X(s, t) \) on the boundary of the unit square is found by Paranjape and Park [7]. Klesov [4] found an explicit form of the probability

\[
P(L, g) = P\left( \sup_{(s, t) \in L} X(s, t) - g(s, t) < 0 \right),
\]

where \( X \) is a Chentsov field on \( D \), \( L \) is a polygonal line with two linear sections, and \( g \) is a linear function.

The probabilities

\[
P(L, \lambda) = P\left( \sup_{(s, t) \in L} X(s, t) > \lambda \right)
\]

are considered in [5] and [6], where \( L \) is a polygonal line with several linear sections. In [5] and [6], the probability (2) is expressed in terms of the standard Gaussian distribution function in a rather complicated form; thus estimates for (2) are also of a considerable interest.

2010 Mathematics Subject Classification. Primary 60G15, 60G60.
Key words and phrases. Chentsov field, distribution of the maximum, Gaussian processes.

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Nice lower estimates for the distribution of the maximum of the Chentsov field on a square are obtained in [3]. Estimates of the distribution of the maximum of the Chentsov field on a unit square are considered in [2] in a neighborhood of the origin. Estimates in [2] imply that there is no clear-cut notion of a two-parameter reflection principle.

The main aim of this paper is to find the exact asymptotic behavior of probabilities (2) as \( \lambda \to \infty \).

2. Auxiliary results

2.1. The probability of reaching a level by the Chentsov field. Let \( L \) be the polygonal line depicted in Figure 1. It has two linear sections with a unique common point \((x_1, y_1)\), \(0 < x_1 < 1\), \(0 < y_1 < 1\). The line \( L \) can be conveniently treated as the set of points in \( D \) such that

\[
L = \{(s, t): sa^{-1} + t = 1, s \leq k; \ s + tb^{-1} = 1, s > k, (s, t) \in D\},
\]

where \( a = x_1/(1 - y_1) \), \( b = y_1/(1 - x_1) \), and \( k = a(b - 1)/(ab - 1) \) for \( a, b > 1 \).

![Figure 1. Polygonal line with two linear sections](image)

In what follows we use the notation

\[
\Phi(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{x} e^{-t^2/2} dt, \quad \Psi(x) = 1 - \Phi(x).
\]

Let \( \Gamma(z) = \int_{0}^{\infty} t^{z-1} e^{-t} dt, \ Re \, z > 0 \), be the gamma function.

**Theorem 2.1** (Paranjape and Park [7]). Let \( L \) be the polygonal line defined by (3). Let \( X(s, t), (s, t) \in D \), be a Chentsov field. Then

\[
P\left\{ \sup_{(s, t) \in L} X(s, t) \leq \lambda \right\} = \Phi \left( \frac{\lambda(a + c)}{a\sqrt{c}} \right) - \exp \left\{ \frac{-2\lambda^2}{a} \right\} \Phi \left( \frac{\lambda(c - a)}{a\sqrt{c}} \right)
\]

\[
- \exp \left\{ \frac{-2\lambda^2}{b} \right\} \Phi \left( \frac{\lambda(1 - bc)}{b\sqrt{c}} \right) + \exp \left\{ \frac{-2\lambda^2}{b} \left( \frac{1}{a} + \frac{1}{b} - 2 \right) \right\} \Phi \left( \frac{\lambda(1 - bc - 2b)}{b\sqrt{c}} \right),
\]

where \( c = a(b - 1)/(b(a - 1)) \).
2.2. The distribution of the maximum of the Chentsov field on polygonal lines with several linear sections. We need some results obtained in the paper [6].

Fix $n \geq 1$. Let

$$x_0 = 0, \quad x_{n+1} = 1, \quad y_0 = 1, \quad y_{n+1} = 0.$$ 

Suppose a polygonal line $L$ changes its direction at each of $n$ points $Q_1, \ldots, Q_n$ with coordinates $(x_1, y_1), \ldots, (x_n, y_n)$, respectively. The line $L$ can be considered as a set of points in $D$, namely

$$L = \left\{ (s, t): t = I_{[0]}(s) + \sum_{i=1}^{n+1} (-sk_i + b_i) I_{[x_{i-1}; x_i]}(s), s \in [0, 1] \right\},$$

where $I_A$ is the indicator of the set $A$.

Let $\Delta_0 = 0$ and $\Delta_i = x_i/y_i$, $i = 1, \ldots, n$.

**Theorem 2.2** (Kruglova [6]). Let $\{X(s, t): (s, t) \in D\}$ be the Chentsov field defined on the unit square. Suppose the polygonal line $L$ changes its direction $n$ times at the points $Q_1, \ldots, Q_n$ with coordinates $(x_1, y_1), \ldots, (x_n, y_n)$, respectively, and let $L$ be defined by equality [5]. Suppose the coordinates of these points satisfy

$$0 < x_1 < \cdots < x_n < 1, \quad 1 > y_1 > \cdots > y_n > 0.$$

Then

$$P_n(\lambda) \overset{\text{def}}{=} \mathbb{P} \left\{ \sup_{(s, t) \in L} X(s, t) < \lambda \right\}$$

$$= \int_{-\infty}^{\lambda_1} \cdots \int_{-\infty}^{\lambda_n} \left( 1 - \exp \left\{ -2\lambda \left( \frac{\lambda}{y_n} - u_n \right) \right\} \right)$$

$$\times \prod_{i=1}^{n} \left( 1 - \exp \left\{ -2\frac{\lambda_{i-1}\lambda_i}{(\Delta_i - \Delta_{i-1})} \right\} \right) \varphi_{0, \Delta_i, \Delta_{i-1}}(u_i - u_{i-1}) \, du_1 \cdots \, du_n$$

for all $\lambda > 0$, where $\lambda_i = \lambda/y_i - u_i$, $0 \leq i \leq n$, $u_0 = 0$, and

$$\varphi_{0, \Delta}(u) = \exp \{-u^2/(2\Delta)\}/\sqrt{2\pi\Delta}$$

is the density of the Gaussian distribution with parameters 0 and $\Delta$.

**Remark 2.1.** If $n = 1$, then Theorem 2.2 implies that

$$P_1(\lambda) = I_1(\lambda) - I_2(\lambda) - I_3(\lambda) + I_4(\lambda),$$

where

$$I_1(\lambda) = \int_{-\infty}^{\lambda} \varphi_{0, \Delta_1}(u_1) \, du_1 = \Phi \left( \frac{\lambda}{\sqrt{x_1 y_1}} \right),$$

$$I_2(\lambda) = \int_{-\infty}^{\lambda} \frac{2\lambda (\lambda y_1 - u_1)}{\Delta_1} \varphi_{0, \Delta_1}(u_1) \, du_1$$

$$= \exp \left\{ -2\frac{\lambda^2}{x_1} (1 - y_1) \right\} \Phi \left( \frac{\lambda (1 - 2y_1)}{\sqrt{x_1 y_1}} \right),$$

$$I_3(\lambda) = \int_{-\infty}^{\lambda} \frac{2\lambda}{x_1} (1 - y_1) \varphi_{0, \Delta_1}(u_1) \, du_1$$

$$= \exp \left\{ -2\frac{\lambda^2}{x_1} (1 - y_1) \right\} \Phi \left( \frac{\lambda (1 - 2y_1)}{\sqrt{x_1 y_1}} \right),$$

$$I_4(\lambda) = \int_{-\infty}^{\lambda} \frac{2\lambda}{x_1} (1 - y_1) \varphi_{0, \Delta_1}(u_1) \, du_1.$$
and
\[ I_3(\lambda) = \int_{-\infty}^{\pi} \exp \left\{ -2\lambda \left( \frac{\lambda}{y_1} - u_1 \right) \right\} \varphi_{0, \Delta_1}(u_1) du_1 \]
\[ = \exp \left\{ -\frac{2\lambda^2}{y_1} (1 - x_1) \right\} \Phi \left( \frac{\lambda(1 - 2x_1)}{\sqrt{x_1y_1}} \right), \]
\[ I_4(\lambda) = \int_{-\infty}^{\pi} \exp \left\{ -2\lambda \left( \frac{\lambda}{y_1} - u_1 \right) \right\} \exp \left\{ \frac{2\lambda (\Delta_2 - u_1)}{\Delta_1} \right\} \varphi_{0, \Delta_1}(u_1) du_1 \]
\[ = \exp \left\{ \frac{2\lambda^2}{x_1y_1} (x_1 + y_1)(x_1 + y_1 - 1) \right\} \Phi \left( \frac{\lambda(1 - 2x_1 - 2y_1)}{\sqrt{x_1y_1}} \right). \]

The right hand sides of (4) and (6) coincide, since
\[ \sigma \in (0, 1) \]
\[ \alpha > 0, \]
\[ \max_{t \in [0, 1]} \sigma_t \leq \sigma_M, \]
\[ \chi(t) = x_t, \quad x_t = \left\{ \begin{array}{ll} 1 & \text{if } t < 0, \\ 0 & \text{if } t = 0, \\ -1 & \text{if } t > 0. \end{array} \right. \]

on the right hand side of (4). This means that Theorem 2.1 is a special case of Theorem 2.2 for \( n = 1 \).

2.3. Asymptotic behavior of the distributions of Gaussian processes. Let \( Y(t), t \in [0, 1], \) be a zero mean Gaussian process with continuous trajectories. Suppose the variance \( \sigma^2(t) = E(Y^2(t)) \) attains its maximum at a unique point \( t_0 \) of the interval \( [0, 1] \).

Denote by \( \rho(s, t) \) the covariance function of the process \( Y(t) \). Consider the following conditions introduced in [S].

**E1:** There are constants \( \beta > 0 \) and \( A \geq 0 \) such that
\[ \sigma(t) = \sigma(t_0) - A|t - t_0|^\beta(1 + o(1)), \quad t \to t_0. \]

**E2:** There are constants \( \alpha > 0 \) and \( C > 0 \) such that
\[ \rho(t, s) = 1 - C|t - s|^{\alpha}(1 + o(1)), \quad t \to t_0, \quad s \to t_0. \]

**E3:** For some \( \gamma > 0 \) and \( G \) and for all \( t, s, \)
\[ E \left[ (Y(t) - Y(s))^2 \right] \leq G|t - s|^{\gamma}. \]

For \( 0 < \alpha \leq 2 \), denote by \( \chi(t), t \in (0, \infty), \) a Gaussian process such that
1) \( E[\chi(t)] = -|t|^{\alpha} \) for all \( t \in (0, \infty); \)
2) \( \text{cov}[\chi(s), \chi(t)] = |t|^{\alpha} + |s|^{\alpha} - |t - s|^{\alpha} \) for all \( s, t \in (0, \infty). \)

For all \( b > 0, M < B, \) and \( 0 < \alpha < 2 \) let
\[ H_0(\alpha, M, B) = E \left[ \exp \left\{ \frac{1}{1 + b|1+b|^{2/\alpha}M, (1+b)^{2/\alpha}B} \chi(t) \right\} \right], \]
\[ H_0(\alpha, 0, B) = \lim_{B \to \infty} H_0(\alpha, 0, B) < \infty, \]
\[ 0 < H_0^{K, 1}(\alpha, -B, B) < \infty, \quad K > 0, \]
\[ 0 < H_0^{K, 2}(\alpha, 0, B) < \infty. \]

Piterbarg [S] proved that these limits are finite.

The following result is also proved in [S].

**Theorem 2.3** (Piterbarg [S]). Let \( Y(t), t \in [0, 1], \) be a zero mean Gaussian process with continuous trajectories. Suppose its variance \( \sigma^2(t) = E(Y^2(t)) \) attains the maximal value \( \max_{t \in T} \sigma^2(t) = \sigma_M^2 \) at a unique point \( t_0 \in [0, 1] \). Assume that conditions E1–E3 hold for \( \alpha > 0 \).
1) If $\alpha < \beta$, then
\[
P\left\{ \max_{t \in [0,1]} Y(t) > u \right\} = \begin{cases} 2N \left( \frac{u}{\sigma_M} \right)^{\frac{\alpha}{2} - \frac{\beta}{2}} \Psi \left( \frac{w}{\sigma_M} \right) (1 + o(1)), & t_0 \in (0,1), \\
N \left( \frac{u}{\sigma_M} \right)^{\frac{\alpha}{2} - \frac{\beta}{2}} \Psi \left( \frac{w}{\sigma_M} \right) (1 + o(1)), & t_0 = 0 \text{ or } t_0 = 1, \end{cases}
\] as $u \to \infty$, where
\[
N = \frac{H_a \Gamma(\frac{1}{\beta}) C_{\alpha}^{\frac{1}{2}} \sigma_M^{\frac{1}{2}}}{\beta A^2}
\]
and the constants $\beta$ and $A$ are defined in condition E1, while the constants $\alpha$ and $C$ are defined in condition E2;

2) if $\alpha = \beta$, then
\[
P\left\{ \max_{t \in [0,1]} Y(t) > u \right\} = \begin{cases} H_{\alpha}^{K,1} \Psi \left( \frac{u}{\sigma_M} \right) (1 + o(1)), & t_0 \in (0,1), \\
H_{\alpha}^{K,2} \Psi \left( \frac{w}{\sigma_M} \right) (1 + o(1)), & t_0 = 1 \text{ or } t_0 = 0, \end{cases}
\] as $u \to \infty$, where $K = A/(C\sigma_M)$;

3) if $\alpha > \beta$, then
\[
P\left\{ \max_{t \in [0,1]} X(t) > u \right\} = \Psi \left( \frac{u}{\sigma_M} \right) (1 + o(1))
\] as $u \to \infty$.

3. THE MAIN RESULT

Consider the restriction of the Chentsov field on the polygonal line with one change of direction. Let $(x_1, y_1)$ be the coordinates of the change point. Put
\[
P_1(\lambda) = P\left\{ \sup_{(s,t) \in L} X(s, t) < \lambda \right\},
\]
where $L$ is the polygonal line depicted in Figure 1 and where $\lambda > 0$ is a certain constant.

The following theorem contains estimates for the distribution of the maximum of the Chentsov field on a polygonal line with one change point. The estimates depend on the position of the change point.

![Figure 2. Domains where the estimates are of the same order](image-url)
Theorem 3.1. Let $X(s,t)$ be the Chentsov field defined on a unit square. Suppose a polygonal line $L$ such as depicted in Figure 1 has a unique change point $Q$ with coordinates $(x_1, y_1)$. Let

$$D_1 = \{(x,y): 0 \leq x \leq 1/2, 1/2 < y \leq 1, x+y > 1\},$$
$$D_2 = \{(x,y): 1/2 < x \leq 1, 1/2 < y \leq 1\},$$
$$D_3 = \{(x,y): 0 \leq y \leq 1/2, 1/2 < x \leq 1, x+y > 1\},$$
$$D_4 = \{(x,y): 0 \leq x \leq 1, 0 \leq y \leq 1, x+y = 1\},$$

be the domains shown in Figure 2.

1) If $Q \in D_1$, then

$$\alpha e^{-c_1\lambda^2} + e^{-c_2\lambda^2} \left( \frac{B_1}{\lambda} + \frac{B_2}{\lambda^3} \right) < 1 - P_1(\lambda) < e^{-c_1\lambda^2} + e^{-c_2\lambda^2} \left( \frac{B_1}{\lambda} + \frac{B_3}{\lambda^3} \right),$$

where

$$\alpha = \begin{cases} \frac{1}{2}, & x_1 = \frac{1}{2}, \\ 1, & \text{otherwise}, \end{cases} \quad c_1 = \frac{2(1-x_1)}{y_1}, \quad c_2 = \frac{1}{2x_1y_1},$$

and

$$B_1 = \left\{ \frac{\sqrt{x_1y_1}}{\sqrt{2\pi}} \left( 1 + \frac{1}{2x_1-1} + \frac{1}{2y_1-1} - \frac{1}{2x_1+2y_1-1} \right), \quad y_1 \neq 1/2, \ x_1 \neq 1/2, \right. \quad \left. y_1 = 1/2, \ x_1 \neq 1/2, \right. \quad \left. y_1 = 1/2, \ x_1 \neq 1/2; \right.$$\[
B_2 = -\left( \frac{x_1y_1}{\sqrt{2\pi}} \right)^{3/2} \left( 1 + \frac{1}{(2y_1-1)^3} \right); \]

$$B_3 = \left\{ \frac{x_1y_1}{\sqrt{2\pi}} \left( \frac{1}{(1-2x_1)^3} + \frac{1}{(2x_1+2y_1-1)^3} \right), \quad x_1 \neq 1/2, \quad x_1 = 1/2. \right.$$\[]

2) If $Q \in D_2$, then

$$e^{-c_2\lambda^2} \left( \frac{B_1}{\lambda} + \frac{B_4}{\lambda^3} \right) < 1 - P_1(\lambda) < e^{-c_2\lambda^2} \left( \frac{B_1}{\lambda} + \frac{B_5}{\lambda^3} \right),$$

where

$$B_4 = -\frac{(x_1y_1)^{3/2}}{\sqrt{2\pi}} \left( 1 + \frac{1}{(2y_1-1)^3} + \frac{1}{(2x_1-1)^3} \right);$$

$$B_5 = -\frac{x_1y_1^{3/2}}{\sqrt{2\pi}} \frac{1}{(2x_1+2y_1-1)^3};$$

3) If $Q \in D_3$, then

$$\beta e^{-c_3\lambda^2} + e^{-c_2\lambda^2} \left( \frac{B_1}{\lambda} + \frac{B_6}{\lambda^3} \right) < 1 - P_1(\lambda) < e^{-c_3\lambda^2} + e^{-c_2\lambda^2} \left( \frac{B_1}{\lambda} + \frac{B_7}{\lambda^3} \right),$$

where

$$\beta = \begin{cases} \frac{1}{2}, & y_1 = \frac{1}{2}, \\ 1, & \text{otherwise}, \end{cases}$$
We reduce

\[ B_0 = \frac{(x_1 y_1)^{3/2}}{\sqrt{2\pi}} \left( 1 + \frac{1}{(2x_1 - 1)^3} \right); \]
\[ B_7 = \begin{cases} 
\frac{(x_1 y_1)^{3/2}}{\sqrt{2\pi}} \left( \frac{1}{(2y_1 - 1)^2} + \frac{1}{(2x_1 + 2y_1 - 1)^2} \right), & y_1 \neq 1/2, \\
\frac{1}{32\sqrt{\pi x_1^2}}, & y_1 = 1/2; 
\end{cases} \]

and \( c_3 = 2(1 - y_1)/x_1. \)

4) If \( Q \in D_4, \) then
\[ 1 - P_1(\lambda) = e^{-2\lambda^2}. \]

**Remark 3.1.** All coefficients \( c_1, c_2, c_3, \) and \( B_1, \ldots, B_7 \) depend on the coordinates of the point \( Q. \)

**Proof.** First we consider the case of \( Q \in D_4. \) Substituting \( x_1 = 1 - y_1 \) in (5), we obtain
\[ P_1(\lambda) = \Phi \left( \frac{\lambda}{\sqrt{(1 - y_1)y_1}} \right) - e^{-2\lambda^2} \Phi \left( \frac{\lambda(1 - 2y_1)}{\sqrt{(1 - y_1)y_1}} \right) - e^{-2\lambda^2} \Phi \left( \frac{\lambda(2y_1 - 1)}{\sqrt{(1 - y_1)y_1}} \right) + \Phi \left( -\frac{\lambda}{\sqrt{(1 - y_1)y_1}} \right) = 1 - e^{-2\lambda^2}. \]

In what follows we apply the inequalities
\[ e^{-x^2/2} \left( \frac{1}{x} - \frac{1}{x^3} \right) < 1 - \Phi(x) < \frac{e^{-x^2/2}}{x\sqrt{2\pi}}, \quad x > 0. \]

Since \( 1 - \Phi(x) = \Phi(-x), \) \( x > 0, \) an analogous inequality holds for \( \Phi(-x), \) \( x > 0, \) as well. For the first term in (6), we have
\[ \frac{\exp\{-\lambda^2/(2x_1y_1)\}}{\lambda\sqrt{2\pi}} \left( 1 - \frac{x_1y_1}{\lambda^2} \right) < 1 - I_1(\lambda) < \frac{\exp\{-\lambda^2/(2x_1y_1)\}}{\lambda\sqrt{2\pi}} \left( 1 - \frac{x_1y_1}{\lambda^2} \right). \]

Now we represent \( I_2(\lambda) \) as follows:
\[ I_2(\lambda) = \exp \left\{ -\frac{2\lambda^2}{x_1} (1 - y_1) \right\} - \exp \left\{ -\frac{2\lambda^2}{x_1} (1 - y_1) \right\} \left( 1 - \Phi \left( \frac{\lambda(1 - 2y_1)}{\sqrt{x_1y_1}} \right) \right). \]

If \( y_1 < 1/2, \) then
\[ I_2(\lambda) > \exp \left\{ -\frac{2\lambda^2}{x_1} (1 - y_1) \right\} - \frac{\exp\{-\lambda^2/(2x_1y_1)\}}{\lambda\sqrt{2\pi}(1 - 2y_1)} \left( 1 - \frac{x_1y_1}{\lambda^2} \right), \]
\[ I_2(\lambda) < \exp \left\{ -\frac{2\lambda^2}{x_1} (1 - y_1) \right\} - \frac{\exp\{-\lambda^2/(2x_1y_1)\}}{\lambda\sqrt{2\pi}(1 - 2y_1)} \left( 1 - \frac{x_1y_1}{(1 - 2y_1)^2\lambda^2} \right). \]

If \( y_1 > 1/2, \) then
\[ \frac{\exp\{-\lambda^2/(2x_1y_1)\}}{\lambda\sqrt{2\pi}(2y_1 - 1)} \left( 1 - \frac{x_1y_1}{(2y_1 - 1)^2\lambda^2} \right) < I_2(\lambda) < \frac{\exp\{-\lambda^2/(2x_1y_1)\}}{\lambda\sqrt{2\pi}(2y_1 - 1)}, \]
and if \( y_1 = 1/2, \) then
\[ I_2(\lambda) = \frac{1}{2} e^{-\lambda^2/x_1}. \]

We reduce \( I_3(\lambda) \) to the following form:
\[ I_3(\lambda) = \exp \left\{ -\frac{2\lambda^2}{y_1} (1 - x_1) \right\} - \exp \left\{ -\frac{2\lambda^2}{y_1} (1 - x_1) \right\} \left( 1 - \Phi \left( \frac{\lambda(1 - 2x_1)}{\sqrt{x_1y_1}} \right) \right). \]
If $x_1 < 1/2$, then
\[ I_3(\lambda) > \exp \left\{ -\frac{2\lambda^2}{y_1} (1 - x_1) \right\} - \frac{\exp\left\{ -\frac{\lambda^2}{(2x_1y_1)} \sqrt{x_1y_1} \right\}}{\lambda \sqrt{2\pi(1 - 2x_1)}}, \]
\[ I_3(\lambda) < \exp \left\{ -\frac{2\lambda^2}{y_1} (1 - x_1) \right\} - \frac{\exp\left\{ -\frac{\lambda^2}{(2x_1y_1)} \sqrt{x_1y_1} \right\}}{\lambda \sqrt{2\pi(1 - 2x_1)}} \left( 1 - \frac{x_1y_1}{(1 - 2x_1)^2 \lambda^2} \right). \]

If $x_1 > 1/2$, then
\[ \frac{\exp\left\{ -\frac{\lambda^2}{(2x_1y_1)} \sqrt{x_1y_1} \right\}}{\lambda \sqrt{2\pi(2x_1 - 1)}} \left( 1 - \frac{x_1y_1}{(2x_1 - 1)^2 \lambda^2} \right) < I_3(\lambda) < \frac{\exp\left\{ -\frac{\lambda^2}{(2x_1y_1)} \sqrt{x_1y_1} \right\}}{\lambda \sqrt{2\pi(2x_1 - 1)}}, \]
and if $x_1 = 1/2$, then
\[ I_3(\lambda) = \frac{1}{2} e^{-\lambda^2/y_1}. \]

Finally
\[ I_4(\lambda) < \exp\left\{ -\frac{\lambda^2}{(2x_1y_1)} \sqrt{x_1y_1} \right\}, \]
\[ I_4 > \frac{\exp\left\{ -\frac{\lambda^2}{(2x_1y_1)} \sqrt{x_1y_1} \right\}}{\lambda \sqrt{2\pi(2x_1 + 2y_1 - 1)}} \left( 1 - \frac{x_1y_1}{(2x_1 + 2y_1 - 1)^2 \lambda^2} \right). \]

Combining the inequalities obtained above and using representation (6), we complete the proof of the theorem. \[ \square \]

The following corollary explains the dependence of the asymptotic behavior of the maximum of the Chentsov field on a polygonal line with a unique change point on the position of this point.

**Corollary 3.1.**
1. If $Q \in D_1$, then
   \[ 1 - P_1(\lambda) = e^{-c_1 \lambda^2} + \frac{B_1 e^{-c_2 \lambda^2}}{\lambda} + o \left( \frac{e^{-c_2 \lambda^2}}{\lambda} \right) \quad \text{as } \lambda \to \infty. \]
2. If $Q \in D_2$, then
   \[ 1 - P_1(\lambda) = \frac{B_1 e^{-c_2 \lambda^2}}{\lambda} + o \left( \frac{e^{-c_2 \lambda^2}}{\lambda} \right) \quad \text{as } \lambda \to \infty. \]
3. If $Q \in D_3$, then
   \[ 1 - P_1(\lambda) = e^{-c_3 \lambda^2} + \frac{B_1 e^{-c_2 \lambda^2}}{\lambda} + o \left( \frac{e^{-c_2 \lambda^2}}{\lambda} \right) \quad \text{as } \lambda \to \infty. \]
4. If $Q \in D_4$, then
   \[ 1 - P_1(\lambda) = e^{-2\lambda^2}, \]
where the constants $B_1$, $c_1$, $c_2$, and $c_3$ are defined in Theorem 3.1.

**Remark 3.2.** To separate the main term in the asymptotic formula, we find the relations between the coefficients in the estimates for the tail of the distribution of the maximum of the Chentsov field defined on a polygonal line. Namely,
1) if $Q \in D_1$, then $c_1 \leq c_2$; moreover, $c_1 = c_2$ only if $x_1 = \frac{1}{2}$;
2) if $Q \in D_3$, then $c_3 \leq c_2$; moreover, $c_3 = c_2$ only if $y_1 = \frac{1}{2}$.

Therefore, the main term of the asymptotics in (8) and (9) is determined by the first summand.
Corollary 3.2. \[ \begin{align*}
1) & \text{ Let } Q \in D_1. \text{ If } x_1 \neq \frac{1}{2}, \text{ then } \\
& \lim_{\lambda \to \infty} \lambda e^{c_2 \lambda^2} \left( 1 - P_1(\lambda) - e^{-c_1 \lambda^2} \right) = B_1, \\
& \text{while if } x_1 = \frac{1}{2}, \text{ then } \\
& \lim_{\lambda \to \infty} e^{c_2 \lambda^2} (1 - P_1(\lambda)) = \frac{1}{2}.
\end{align*} \]

2) Let \( Q \in D_2 \). Then

\[ \lim_{\lambda \to \infty} \lambda e^{c_2 \lambda^2} (1 - P_1(\lambda)) = B_1. \]

3) Let \( Q \in D_3 \). If \( y_1 \neq \frac{1}{2} \), then

\[ \lim_{\lambda \to \infty} \lambda e^{c_2 \lambda^2} \left( 1 - P_1(\lambda) - e^{-c_3 \lambda^2} \right) = B_1, \]

while if \( y_1 = \frac{1}{2} \), then

\[ \lim_{\lambda \to \infty} \lambda e^{c_2 \lambda^2} (1 - P_1(\lambda)) = \frac{1}{2}. \]

Remark 3.3. We want to determine the “maximal” and “minimal” asymptotics. First we define these notions.

Let \( D \) be a set of parameters, \( f_Q(\cdot) \) a family of functions, \( Q \in D \), and \( g(\cdot) \) a fixed function. We write

\[ \max_{Q \in D} f_Q(\lambda) = g(\lambda) \]

if, for all \( Q \in D \), either \( f_Q(\lambda) = g(\lambda) \) or \( \lim_{\lambda \to \infty} f_Q(\lambda)/g(\lambda) = 0. \)

Similarly we write

\[ \min_{Q \in D} f_Q(\lambda) = g(\lambda) \]

if, for all \( Q \in D \), either \( f_Q(\lambda) = g(\lambda) \) or \( \lim_{\lambda \to \infty} g(\lambda)/f_Q(\lambda) = 0. \)

We show how the order of the asymptotic formulas for \( 1 - P_1(\lambda) \) changes in different domains, namely

- **D\(_1\)**: \( \min_{D_1} (1 - P_1(\lambda)) = e^{-2 \lambda^2} \); \( \max_{D_1} (1 - P_1(\lambda)) = e^{-\lambda^2} \).
- **D\(_2\)**: \( \min_{D_2} (1 - P_1(\lambda)) = e^{-2 \lambda^2} \); \( \max_{D_2} (1 - P_1(\lambda)) = e^{-\lambda^2} \).

The maximal asymptotics for the whole square \( D \) is

\[ \max_{D} (1 - P_1(\lambda)) = \frac{2^{5/2}}{3 \sqrt{\pi}} \lambda^{-1} e^{-\lambda^2/2}. \]

This result can be used to obtain a lower estimate of the tail of the distribution of the maximum of the Chentsov field on the unit square:

\[ \mathbb{P} \left\{ \max_{(s,t) \in D} X(s,t) > \lambda \right\} > \frac{2^{5/2}}{3 \sqrt{\pi}} \lambda^{-1} e^{-\lambda^2/2}. \]

The following result is a generalization of Theorem 3.1

**Theorem 3.2.** Let \( X(s,t) \) be the Chentsov field defined on the unit square. Suppose a polygonal line \( L \) has \( n \) change points \( Q_1, \ldots, Q_n \) whose coordinates \((x_1,y_1), \ldots, (x_n,y_n)\)
satisfy the assumptions of Theorem 2.2. Put \( x_i = a_i x_1 \) and \( y_i = b_i y_1, \ i = 2, \ldots, n. \)
Consider the following domains in \( \mathbb{R}^{2n}: \)

\[
D_1 = \left\{ y_1 > 1/2, \ a_i b_i < 1, \ \frac{a_i b_i - a_{i-1} b_i}{2(b_{i-1} - b_i)} > a_i \right\},
\]

or \( a_{i-1} > \frac{a_i b_{i-1} - a_{i-1} b_i}{2(b_{i-1} - b_i)}, \ \ a_{x_i} + b_i y_1 \geq 1, \ i = 2, \ldots, n, \ a_n x_1 \geq 1/2,\) \( j = 2, \ldots, n, \)

\[
D_j = \left\{ y_1 > 1/2, \ a_j b_j > 1, \ a_i b_i < 1, \ \frac{a_i b_i - a_{i-1} b_i}{2(b_{i-1} - b_i)} > a_i \right\},
\]

or \( a_{i-1} > \frac{a_i b_{i-1} - a_{i-1} b_i}{2(b_{i-1} - b_i)}, \ \ a_{x_i} + b_i y_1 \geq 1, \ i = 2, \ldots, n, \ i \neq j, \ a_n x_1 \geq 1/2, \)

\[
D_{n+j} = \left\{ y_1 > 1/2, \ a_{j-1} < \frac{a_{j-1} b_{j-1} - a_{j-1} b_j}{2(b_{j-1} - b_j)} < a_j, \ j \neq i, \ a_{i-1} > \frac{a_i b_{i-1} - a_{i-1} b_i}{2(b_{i-1} - b_i)}, \ a_{x_i} + b_i y_1 \geq 1, \ i = 2, \ldots, n, \ a_n x_1 \geq 1/2 \right\},
\]

\[
D_{n+1} = \left\{ y_1 \leq 1/2, \ a_i b_i < 1, \ \frac{a_i b_i - a_{i-1} b_i}{2(b_{i-1} - b_i)} > a_i \right\},
\]

or \( a_{i-1} > \frac{a_i b_{i-1} - a_{i-1} b_i}{2(b_{i-1} - b_i)}, \ \ a_{x_i} + b_i y_1 \geq 1, \ i = 2, \ldots, n, \ a_n x_1 \geq 1/2 \)

\[
D_{2n+1} = \{ a_n x_1 < 1/2, \ a_i x_i + b_i y_1 \geq 1, \ i = 2, \ldots, n \}.
\]

Let

\[
K_1 = 2y_1 - 1, \quad K_j = \frac{2(x_j - 1)y_j + x_j y_{j-1} - 2x_j y_j}{(x_j y_{j-1} - x_j - 1 y_j)}, \quad j = 2, \ldots, n.
\]

Set \((\bar{x}, \bar{y}) = (x_1, \ldots, x_n, y_1, \ldots, y_n).\) Then

\[
1 - P_n(\lambda) = \begin{cases} \omega_n(\lambda) & (\bar{x}, \bar{y}) \in D_j, \ j = 1, \ldots, n, \\ \exp \left\{ -\frac{2(1-y_1)\lambda^2}{x_1} \right\} (1 + o(1)), & (\bar{x}, \bar{y}) \in D_{n+}, j = 2, \ldots, n, \\ \exp \left\{ -\frac{2(b_{j-1} - b_j)(a_j - a_{j-1})\lambda^2}{b_j y_j} \right\} (1 + o(1)), & (\bar{x}, \bar{y}) \in D_{2n+1} \end{cases}
\]

as \( \lambda \to \infty. \)

**Proof.** Let the polygonal line \( L \) be given by (3). Then the covariance function of the restriction of the Chentsov field to this polygonal line is equal to

\[
r(s, t) = s \sum_{i=2}^{n} \left( -\frac{(y_{i-1} - y_i) t}{x_i - x_{i-1}} + \frac{x_i y_{i-1} - x_{i-1} y_i}{x_i - x_{i-1}} \right) I_{[x_{i-1}, x_i]}(t)
\]

\[
+ \left( -\frac{(1 - y_i) t}{x_1} + 1 \right) I_{[0, x_1]}(t) + \left( -\frac{y_n t}{1 - x_n} + \frac{y_n}{1 - x_n} \right) I_{[x_n, 1]}(t), \quad s \leq t.
\]
Thus the variance \( \sigma^2 \) of this process is given by
\[
g(t) = \sigma^2(t) = \sum_{i=2}^{n} \left( -\frac{(y_{i-1} - y_i)t}{x_i - x_{i-1}} + \frac{x_i y_{i-1} - x_{i-1}y_i}{x_i - x_{i-1}} \right) I(x_{i-1}, x_i)(t) + \left( 1 - \frac{(1 - y_1)t}{x_1} \right) I(0, x_1)(t) + \left( -\frac{y_1 t}{1 - x_n} + \frac{y_n}{1 - x_n} \right) I(x_n, 1)(t).
\]

Now we find the maximum of the variance between the change points.

**Case 1.** If \( t \in [0, x_1] \), then
\[
g(t) = t - \frac{(1 - y_1)t^2}{x_1} = (1 - y_1)\left(t - \frac{x_1}{2(1 - y_1)}\right)^2 + \frac{x_1}{4(1 - y_1)}.
\]
If \( x_1/(2(1 - y_1)) < x_1 \), then
\[
\max_{t \in [0, x_1]} g(t) = \frac{x_1}{4(1 - y_1)}.
\]
Otherwise, the function \( g \) increases in the interval \([0, x_1]\), and one needs to evaluate the function \( g \) at the point \( x_1 \):
\[
g(x_1) = x_1y_1.
\]
Thus
\[
\max_{t \in [0, x_1]} g(t) = \begin{cases} 
\frac{x_1}{4(1 - y_1)}, & y_1 \leq 1/2, \\
x_1 y_1, & y_1 > 1/2.
\end{cases}
\]

**Case 2.** If \( t \in (x_{i-1}, x_i), \ i = 2, \ldots, n, \) then
\[
g(t) = -\frac{(y_{i-1} - y_i)t^2}{x_i - x_{i-1}} + \frac{(x_i y_{i-1} - x_{i-1}y_i)t}{x_i - x_{i-1}}
\]
\[
= -\frac{(y_{i-1} - y_i)}{x_i - x_{i-1}} \left( t - \frac{x_i y_{i-1} - x_{i-1}y_i}{2(y_i - y_{i-1})} \right)^2 + \frac{(x_i y_{i-1} - x_{i-1}y_i)^2}{4(x_i - x_{i-1})(y_i - y_{i-1})}.
\]
If \( (x_i y_{i-1} - x_{i-1}y_i) \) \( \in (x_{i-1}, x_i) \), then
\[
\max_{t \in (x_{i-1}, x_i)} g(t) = \frac{(x_i y_{i-1} - x_{i-1}y_i)^2}{4(x_i - x_{i-1})(y_i - y_{i-1})}.
\]
Otherwise, one needs to find the values at the endpoints of the interval:
\[
g(x_{i-1}) = x_{i-1} y_{i-1}, \quad g(x_i) = x_i y_i.
\]
Comparing these values, we conclude that
\[
\max_{t \in (x_{i-1}, x_i)} g(t) = \begin{cases} 
\frac{a_i b_{i-1} x_1 y_1}{4(a_i - a_{i-1})(b_{i-1} - b_i)}, & a_i b_{i-1} x_1 y_1 < 1, \ A_i > a_i \text{ or } a_{i-1} > A_i, \\
\frac{x_i y_i (a_i b_{i-1} - a_{i-1} b_i)^2}{4(a_i - a_{i-1})(b_{i-1} - b_i)}, & a_{i-1} < A_i < a_i, \\
\frac{a_i b_i x_1 y_1}{2(b_{i-1} - b_i)}, & a_i b_i > A_i > a_i \text{ or } a_{i-1} > A_i,
\end{cases}
\]
where \( A_i = \frac{a_i b_{i-1} - a_{i-1} b_i}{2(b_{i-1} - b_i)}. \)
Case 3. If \( t \in (x_n, 1] \), then
\[
g(t) = -\frac{y_n t}{1-x_n} (1-t) = -\frac{y_n}{1-x_n} \left( t - \frac{1}{2} \right)^2 + \frac{y_n}{4(1-x_n)}.
\]

If \( \frac{1}{2} \in (x_n, 1] \), then
\[
\max_{t \in (x_n, 1]} g(t) = \frac{y_n}{4(1-x_n)}.
\]

Otherwise the function \( g \) decreases in the interval \((x_n, 1]\), and one needs to evaluate the function \( g \) at the point \( x_n \):
\[
g(x_n) = x_n y_n = a_n b_n x_1 y_1.
\]

Now one can determine the maximum of the variance:
\[
\max_{t \in (x_n, 1]} g(t) = \begin{cases} \frac{b_n y_1}{4(1-a_n x_1)}, & a_n x_1 < 1/2, \\ a_n b_n x_1 y_1, & a_n x_1 \geq 1/2, \end{cases}
\]

The case of \((x_1, \ldots, x_n, y_1, \ldots, y_n) \in D_1\). In this case,
\[
\sigma(t) = \sqrt{t \left( 1 - \frac{(1-y_1)t}{x_1} \right)},
\]
and the maximum of the function \( g \) is attained at the point \( x_1 \), that is,
\[
\max_{t \in [0,1]} g(t) = g(x_1) = x_1 y_1.
\]

Thus
\[
\sigma_M = \sqrt{x_1 y_1},
\]
whence
\[
\sigma(t) = \sqrt{x_1 y_1} \left( 1 - \frac{(2y_1-1)(t-x_1)}{2x_1 y_1} \right) (o(1) + 1), \quad t \to x_1.
\]

The covariance function is of the form
\[
\rho(s, t) = \sqrt{s \left( 1 - \frac{(1-y_1)s}{x_1} \right) \overline{t} \left( 1 - \frac{(1-y_1)t}{x_1} \right)}.
\]

Moreover,
\[
\rho(s, t) = 1 - \frac{1}{2x_1 y_1} (t-s)(1+o(1)), \quad s, t \to x_1.
\]

Using conditions E1 and E2 and representations (10) and (11), we find that
\[
\alpha = \beta = 1, \quad A = \frac{(2y_1 - 1)}{2\sqrt{x_1 y_1}}, \quad C = \frac{1}{2x_1 y_1}, \quad \sigma_M = \sqrt{x_1 y_1}, \quad K_1 = 2y_1 - 1.
\]

Applying Theorem 2.3 (case 2), we obtain
\[
P \left\{ \max_{t \in L} X(s, t) > u \right\} = H_{1.1}^{K_1} \Psi \left( \frac{u}{\sqrt{x_1 y_1}} \right) (1 + o(1)).
\]

The case of \((x_1, \ldots, x_n, y_1, \ldots, y_n) \in D_{n+1}\). In this case,
\[
\sigma(t) = \sqrt{t \left( 1 - \frac{(1-y_1)t}{x_1} \right)}
\]
and the maximum of the function \( g \) is attained at the point \( x_1/(2(1-y_1)) \), that is,
\[
\max_{t \in [0,1]} g(t) = g \left( \frac{x_1}{2(1-y_1)} \right) = \frac{x_1}{4(1-y_1)}.
\]
Therefore
\[ \sigma_M = \sqrt{\frac{x_1}{4(1 - y_1)}}. \]
whence
\[ \sigma(t) = \left( \sqrt{\frac{x_1}{4(1 - y_1)}} - \left( \frac{1 - y_1}{x_1} \right)^{3/2} \left( t - \frac{x_1}{2(1 - y_1)} \right)^2 \right)(o(1) + 1). \]

The covariance function can be written as follows:
\[ \rho(s, t) = \left( 1 - \frac{2(1 - y_1)}{x_1}(t - s) \right)(1 + o(1)), \quad s, t \to \frac{x_1}{2(1 - y_1)}. \]

Now we obtain from \[(12)\] and \[(13)\] that
\[ \alpha = 1, \quad \beta = 2, \quad A = \left( \frac{1 - y_1}{x_1} \right)^{3/2}, \quad C = \frac{2(1 - y_1)}{x_1}. \]

Applying Theorem 2.3, 1), we get
\[ \mathbb{P} \left\{ \max_{(s, t) \in \mathcal{L}} X(s, t) > u \right\} = \exp \left\{ -\frac{2(1 - y_1)u^2}{x_1} \right\}(1 + o(1)). \]

The case of \((x_1, \ldots, x_n, y_1, \ldots, y_n) \in D_{n+1}, j = 2, \ldots, n.\) In this case,
\[ \sigma(t) = \sqrt{t} \left( -\frac{(y_j - y_j s)}{x_j - x_{j-1}} + \frac{x_j y_j - x_{j-1} y_j}{x_j - x_{j-1}} \right). \]

The maximum of the function \(g\) is attained at the point
\[ \frac{(a_j b_{j-1} - a_{j-1} b_j)x_1}{2(b_{j-1} - b_j)}, \]
that is,
\[ \max_{t \in [0, 1]} g(t) = g \left( \frac{(a_j b_{j-1} - a_{j-1} b_j)x_1}{2(b_{j-1} - b_j)} \right) = \frac{x_1 y_1 (a_j b_{j-1} - a_{j-1} b_j)^2}{4(a_j - a_{j-1})(b_{j-1} - b_j)}. \]

Hence
\[ \sigma_M = \sqrt{\frac{x_1 y_1 (a_j b_{j-1} - a_{j-1} b_j)^2}{4(a_j - a_{j-1})(b_{j-1} - b_j)}}. \]
\[ \sigma(t) = \left( \sqrt{\frac{x_1 y_1 (a_j b_{j-1} - a_{j-1} b_j)^2}{4(a_j - a_{j-1})(b_{j-1} - b_j)}} - \frac{(b_{j-1} - b_j) y_1 \sqrt{(a_j - a_{j-1}) (b_{j-1} - b_j)}}{x_1 (a_j - a_{j-1}) (a_j b_{j-1} - a_{j-1} b_j) \sqrt{x_1 y_1}} \right) \times \left( t - \frac{(a_j b_{j-1} - a_{j-1} b_j)x_1}{2(b_{j-1} - b_j)} \right)^2(o(1) + 1). \]

The covariance function can be written as follows:
\[ \rho(s, t) = \left( 1 - \frac{2(b_{j-1} - b_j)}{x_1 (a_j b_{j-1} - a_{j-1} b_j)}(t - s) \right)(1 + o(1)). \]

Then we obtain from \[(14)\] and \|(15)\] that \(\alpha = 1, \beta = 2,\) and
\[ A = \frac{(b_{j-1} - b_j) y_1 \sqrt{(a_j - a_{j-1}) (b_{j-1} - b_j)}}{x_1 (a_j - a_{j-1}) (a_j b_{j-1} - a_{j-1} b_j) \sqrt{x_1 y_1}}, \quad C = \frac{2(b_{j-1} - b_j)}{x_1 (a_j b_{j-1} - a_{j-1} b_j)}. \]
Applying Theorem 2.3, we get

\[ P \left\{ \max_{t \in \mathbb{L}} X(s, t) > u \right\} = \exp \left\{ -\frac{2(a_j - a_{j-1})(b_j - b_j)u^2}{x_1y_1(a_jb_j - a_{j-1}b_{j-1})^2} \right\} (1 + o(1)). \]

The case of \((x_1, \ldots, x_n, y_1, \ldots, y_n) \in \mathbb{D}_j, j = 2, \ldots, n\). In this case,

\[ \max_{t \in [0,1]} g(t) = g(x_j) = x_jy_j = a_jb_jx_1y_1. \]

Since

\[ \sigma(t) = \left( \sqrt{x_jy_j} - \frac{(x_{j-1}y_{j-1} + x_jy_j - 2x_jy_j)}{x_j - x_{j-1}}(t - x_j) \right) (1 + o(|t - x_j|)), \]

\[ \rho(s, t) = \left( 1 - \frac{(x_{j-1}y_{j-1} - 2x_jy_j)}{2(x_j - x_{j-1})x_jy_j} (t - s) \right) (1 + o(|t - s|)), \]

we obtain \( \alpha = 1, \beta = 1 \), and

\[ A = \frac{(x_{j-1}y_j + x_jy_j - 2x_jy_j)}{(x_j - x_{j-1})x_jy_j} , \quad C = \frac{(x_{j-1}y_{j-1} - 2x_jy_j)}{2(x_j - x_{j-1})x_jy_j} , \]

\[ K_j = 2 \frac{(x_{j-1}y_j + x_jy_j - 2x_jy_j)}{(x_jy_j - x_{j-1}y_{j-1})}. \]

Therefore

\[ P \left\{ \max_{(s, t) \in \mathbb{L}} X(s, t) > u \right\} = H_1^{(K_j, \Psi)} \left( \frac{u}{\sqrt{x_jy_j}} \right) (1 + o(1)), \quad j = 2, \ldots, n. \]

The case of \((x_1, \ldots, x_n, y_1, \ldots, y_n) \in \mathbb{D}_{2n+1}\). We have

\[ \max_{t \in [0,1]} g(t) = g(1/2) = \frac{b_ny_1}{4(1 - a_nx_1)} \]

and

\[ P \left\{ \max_{(s, t) \in \mathbb{L}} X(s, t) > u \right\} = \exp \left\{ -\frac{2(1 - a_nx_1)u^2}{b_ny_1} \right\} (1 + o(1)). \]

4. Concluding remarks

In this paper, we have obtained estimates for the tail of the distribution of the maximum of the Chentsov field on a polygonal line with a unique change point. We showed how the estimates depend on the position of the change point. We have also found the behavior of the tail of the distribution of the maximum of the field \( X(s, t) \) on polygonal lines with several change points.

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Department of Mathematical Analysis and Probability Theory, Faculty for Physics and Mathematics, National Technical University of Ukraine (KPI), Peremogy Avenue 37, Kyiv 03056, Ukraine

E-mail address: natahak@ukr.net

Received 22/SEP/2009

Translated by S. KVASKO