## ON THE ENVELOPE OF THE AXES OF A SYSTEM OF CONICS

## PASSING THROUGH THREE FIXED POINTS\*

BY

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In a recent number of the Annals of Mathematics † I have shown that the envelope of the asymptotes of a system of conics passing through three fixed points consists of two three-cusped hypocycloids, touching the three straight lines that join the three fixed points in pairs. I propose now to show that the envelope of the axes of the same system of conics consists of two three-cusped hypocycloids touching three concurrent straight lines.

The foci of a conic may be regarded as four of the vertices of a complete four-side circumscribing the conic, the other two vertices being the circular points at infinity; then the straight line at infinity is one diagonal line of this four-side, and the axes are the other two diagonal lines.

The coördinates of the circular points at infinity are  $(1, -e^{Ci}, -e^{-Bi})$  and  $(1, -e^{-Ci}, -e^{Bi})$ ; let us denote these points for the present by  $(x_1, y_1, z_1)$  and  $(x_2, y_2, z_2)$ .

Let the equation of the conic be

$$U \equiv \lambda_1 yz + \lambda_2 zx + \lambda_3 xy = 0,$$

the three fixed points through which the conic is to pass being the vertices of the triangle of reference; and put

$$U_{1} \equiv \lambda_{1} y_{1} z_{1} + \lambda_{2} z_{1} x_{1} + \lambda_{3} x_{1} y_{1}; \quad U_{2} = \lambda_{1} y_{2} z_{2} + \lambda_{2} z_{2} x_{2} + \lambda_{3} x_{2} y_{2};$$

$$U_{1}^{'} \equiv x_{1} \frac{\partial U}{\partial x} + y_{1} \frac{\partial U}{\partial y} + z_{1} \frac{\partial U}{\partial z}; \quad U_{2}^{'} = x_{2} \frac{\partial U}{\partial x} + y_{2} \frac{\partial U}{\partial y} + z_{2} \frac{\partial U}{\partial z}.$$

<sup>\*</sup>Presented to the Society (Chicago) January 2, 1903. Received for publication August 2, 1902.

<sup>†</sup> On some curves connected with a system of similar conics, Annals of Mathematics, 2d series, vol. 3 (1902), p. 154.

The equations of the tangents from the circular points at infinity are

$$U_1^{'^2} = 4 U U_1$$

and

$$U_2^{\prime 2} = 4 U U_2;$$

and the foci are the intersections of these two pairs of straight lines.

The equation  $U_2 U_1^{\prime 2} = U_1 U_2^{\prime 2}$  evidently represents a third pair of straight lines passing through the foci, and must therefore represent the axes.

Now the condition for similarity may be expressed in the form \*

$$\sum (\lambda_1^2 \sin^2 A - 2\lambda_2 \lambda_3 \sin B \sin C) = t^2 (\lambda_1 \cos A + \lambda_2 \cos B + \lambda_3 \cos C)^2,$$

where t is the tangent of the angle between the asymptotes; or,

that is, 
$$\sum (\lambda_1^2-2\,\lambda_2\lambda_3\cos\,A\,)=s^2(\,\lambda_1\cos\,A\,+\,\lambda_2\cos\,B\,+\,\lambda_3\cos\,C\,)^2\,,$$
 
$$U_1U_2=s^2P^2\,,$$

where s is the secant of the angle between the asymptotes, and

$$P = \lambda_1 \cos A + \lambda_2 \cos B + \lambda_3 \cos C$$
.

Hence the equations of the axes may be expressed in the form

and

$$U_1 U_2' = sPU_1',$$
 or  $U_2 U_1' = sPU_2';$   $U_1 U_2' = -sPU_1',$  or  $U_2 U_1' = -sPU_2'.$ 

Using the first of these equations, we may write the tangential coordinates of the corresponding axis in the form

$$\begin{split} u &= U_1(\lambda_2 z_2 + \lambda_3 y_2) - sP(\lambda_2 z_1 + \lambda_3 y_1), \\ v &= U_1(\lambda_3 x_2 + \lambda_1 z_2) - sP(\lambda_3 x_1 + \lambda_1 z_1), \\ w &= U_1(\lambda_1 y_2 + \lambda_2 x_2) - sP(\lambda_1 y_1 + \lambda_2 x_1). \end{split}$$

Noticing that

$$\lambda_1(y_1z_2 + y_2z_1) + \lambda_2(z_1x_2 + z_2x_1) + \lambda_3(x_1y_2 + x_2y_1) = -2P,$$

we have, on multiplying these equations first by  $x_1$ ,  $y_1$ ,  $z_1$  and adding, and then by  $x_2$ ,  $y_2$ ,  $z_2$ , and adding,

$$V \equiv x_1 u + y_1 v + z_1 w = -2P U_1 - 2sP U_1,$$
  
 $W = x_2 u + y_2 v + z_2 w = 2 U_1 U_2 + 2sP^2.$ 

<sup>\*</sup>See the paper entitled, On some curves, etc., referred to above.

Hence, taking account of the relation  $U_1U_2=s^2P^2$ , we find,

$$P = \frac{\sqrt{W}}{\sqrt{2s(s+1)}}, \qquad U_{\rm l} = -\frac{V\sqrt{s}}{\sqrt{2(s+1)\ W}}.$$

Now writing the coördinates in the form

$$\begin{split} u &= (z_2 U_1 - z_1 s P) \lambda_2 + (y_2 U_1 - y_1 s P) \lambda_3, \\ v &= (z_2 U_1 - z_1 s P) \lambda_1 + (x_2 U_1 - x_1 s P) \lambda_3, \\ w &= (y_2 U_1 - y_1 s P) \lambda_1 + (x_2 U_1 - x_1 s P) \lambda_2, \end{split}$$

and using the equation

$$P = \lambda_1 \cos A + \lambda_2 \cos B + \lambda_3 \cos C,$$

we have, on eliminating  $\lambda_1$ ,  $\lambda_2$ ,  $\lambda_3$  the relation

$$\begin{vmatrix} u & 0 & z_2U_1 - z_1sP & y_2U_1 - y_1sP \\ v & z_2U_1 - z_1sP & 0 & x_2U_1 - x_1sP \\ w & y_2U_1 - y_1sP & x_2U_1 - x_1sP & 0 \\ P & \cos A & \cos B & \cos C \end{vmatrix} = 0.$$

On substituting the values of P and  $U_1$  found above, and reducing by means of the relations

$$x_{\!\scriptscriptstyle 2} \, V + x_{\!\scriptscriptstyle 1} \, W = 2 \, (\, u - v \, \cos \, C - w \, \cos \, B \,) \,, \, \text{etc.,} \label{eq:constraint}$$

we finally obtain the equation of the envelope in the form

$$\begin{vmatrix} u & 0 & u\cos B + v\cos A - w & w\cos A + u\cos C - v \\ v & u\cos B + v\cos A - w & 0 & v\cos C + w\cos B - u \\ w & w\cos A + u\cos C - v & v\cos C + w\cos B - u & 0 \\ 1/(s+1) & \cos A & \cos B & \cos C \end{vmatrix} = 0,$$

 $\mathbf{or}$ 

$$\sum \left[ u(v\cos C + w\cos B - u) \left\{ u\cos (B - C) - v\cos B - w\cos C \right\} \right] \\ - \frac{2}{s+1} (v\cos C + w\cos B - u)(w\cos A + u\cos C - v)(u\cos B + v\cos A - w) = 0.$$

It may be shown that this curve has the straight line at infinity for a double tangent, the circular points at infinity being the points of contact.

It must therefore be of the fourth order and have three cusps; and hence for all values of s (except s = -1) it is a three-cusped hypocycloid.

It may easily be shown that it always touches the perpendicular bisectors of the sides of the triangle of reference; in the special case, s=-1, the curve degenerates into the points at infinity on these three lines.

The two axes envelope the same curve only in the case of the equilateral hyperbola, for which  $s = \infty$ .

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