

SYMMETRIC TENSORS OF THE SECOND ORDER WHOSE FIRST COVARIANT DERIVATIVES ARE ZERO*

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1. Consider a Riemann space of the n th order, whose fundamental quadratic form, assumed to be positive definite, is written

$$(1) \quad ds^2 = g_{rs} dx^r dx^s \quad (g_{rs} = g_{sr}),$$

where r and s are summed from 1 to n in accordance with the usual convention which will be followed throughout this paper. It is well known that the first covariant derivatives $g_{rs/t}$ are zero, where

$$(2) \quad g_{rs/t} = \frac{\partial g_{rs}}{\partial x^t} - g_{ra} \Gamma_s^a - g_{as} \Gamma_r^a$$

and

$$(3) \quad \Gamma_{st}^a = \frac{1}{2} g^{ap} \left(\frac{\partial g_{sp}}{\partial x^t} + \frac{\partial g_{tp}}{\partial x^s} - \frac{\partial g_{st}}{\partial x^p} \right),$$

the function g^{ap} being the cofactor of g_{ap} in the determinant

$$(4) \quad g = |g_{rs}|$$

divided by g . It is the purpose of this paper to determine the necessary and sufficient conditions that there exist a symmetric covariant tensor α_{rs} such that the first covariant derivatives $\alpha_{rs/t}$ are zero, or more than one such tensor.

2. Let α_{rs} denote the covariant components of any symmetric tensor of the second order. If e_h is a root of the equation

$$(5) \quad |\alpha_{rs} - e_h g_{rs}| = 0,$$

the functions λ_h^r ($r = 1, \dots, n$) defined by

$$(6) \quad (\alpha_{rs} - e_h g_{rs}) \lambda_h^r = 0 \quad (s = 1, \dots, n)$$

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are the contravariant components of a vector. It is well known that the roots of (5) are real, and that if they are simple, the n corresponding vectors at a point are mutually orthogonal.* Moreover, if a root is of order m , equations (6) admit m sets of independent solutions, and any linear combination of them is also a solution. It is possible to choose m solutions so that the corresponding vectors at a point are mutually orthogonal, and thus from (6) obtain n sets of solutions so that the corresponding vectors at a point are orthogonal; that is,

$$(7) \quad g_{rs} \lambda_h^r \lambda_k^s = 0 \quad (h, k = 1, \dots, n; h \neq k).$$

Moreover, the components may be chosen so that

$$(8) \quad g_{rs} \lambda_h^r \lambda_h^s = 1 \quad (h = 1, \dots, n),$$

that is, the vectors are unit vectors.

The curves in space whose direction at each point is defined by λ_h^r form a congruence of curves C_h . Thus equations (6) define an n -uple of congruences of curves, such that the curves of the n -uple through a point are mutually orthogonal.

The covariant components $\lambda_{h,r}$ of the vector h are given by

$$(9) \quad \lambda_{h,r} = g_{rs} \lambda_h^s, \quad \lambda_h^s = g^{rs} \lambda_{h,r},$$

and hence (7) and (8) are equivalent to

$$(10) \quad \lambda_{h,r} \lambda_k^r = \delta_{hk},$$

where

$$(11) \quad \delta_{hk} = 1 \text{ for } h = k; = 0 \text{ for } h \neq k.$$

The functions γ_{hij} defined by

$$(12) \quad \gamma_{hij} = \lambda_{h,r/s} \lambda_i^r \lambda_j^s,$$

where $\lambda_{h,r/s}$ is the covariant derivative of $\lambda_{h,r}$ with respect to x^s , are invariants; they are called *rotations* by Ricci and Levi-Civita.† They have shown that

$$(13) \quad \gamma_{hij} + \gamma_{ihj} = 0, \quad \gamma_{hhi} = 0 \quad (h, i, j = 1, \dots, n).$$

* Cf. these Transactions, vol. 25 (1923), p. 259.

† Mathematische Annalen, vol. 54 (1901), p. 148; also, Wright, *Invariants of Quadratic Differential Forms*, Cambridge Tract, No. 9, p. 68.

From (12) we have

$$(14) \quad \lambda_{h,r/s} = \sum_{i,j}^{1\dots n} \gamma_{hij} \lambda_{i,r} \lambda_{j,s},$$

and since $g_{rs/t} = 0$, it follows from (9) that

$$(15) \quad \lambda_{h/s}^p = \sum_{i,j}^{1\dots n} \gamma_{hij} \lambda_i^p \lambda_{j,s}.$$

3. If all the roots of (5) are equal, we must have $\alpha_{rs} = \rho g_{rs}$. Differentiating covariantly with respect to x^t , and making use of the fact that $g_{rs/t} = 0$ and the assumption that $\alpha_{rs/t} = 0$, we have that ρ is constant. Consequently α_{rs} is essentially the same as g_{rs} . We exclude this case from further consideration.

Since (7) is satisfied whether the functions λ_h^r and λ_k^s correspond to different simple roots of (5), or to the same multiple root when such exists, we have from (6)

$$(16) \quad \alpha_{rs} \lambda_h^r \lambda_k^s = 0 \quad (h, k = 1, \dots, n; h \neq k).$$

Also from (6) we have

$$(17) \quad \alpha_{rs} \lambda_h^r \lambda_h^s = \rho_h.$$

From (17) we have by differentiating covariantly with respect to x^t and making use of (15), (16), and (17)

$$(18) \quad \alpha_{rs/t} \lambda_h^r \lambda_h^s = \frac{\partial \rho_h}{\partial x^t}.$$

Also from (16) we have, because of (13), (14), (16) and (17),

$$\alpha_{rs/t} \lambda_h^r \lambda_k^s + \sum_j^{1\dots n} (\rho_k - \rho_h) \gamma_{hkj} \lambda_{j,t} = 0.$$

Multiplying by λ_l^t and summing for t , we have

$$(19) \quad \alpha_{rs/t} \lambda_h^r \lambda_k^s \lambda_l^t + (\rho_k - \rho_h) \gamma_{hkl} = 0 \quad (h \neq k).$$

From (18) it follows that if $\alpha_{rs/t} = 0$ the roots ϱ are constant. And from (19) we have for two different roots

$$(20) \quad \gamma_{hkl} = 0 \quad (h \neq k).$$

Let ϱ_1 be a root of (5) which we assume to be a multiple root of order m , and denote by λ_h^r ($h = 1, \dots, m$) the components of the m mutually orthogonal vectors corresponding to it, and by λ_k^r ($k = m+1, \dots, n$) the components of the directions corresponding to the other roots of (5). From (20) we have

$$(21) \quad \gamma_{hkl} = 0 \quad (h = 1, \dots, m; k = m+1, \dots, n; l = 1, \dots, n).$$

Consider the system of equations

$$(22) \quad X_k(f) \equiv \lambda_k^r \frac{\partial f}{\partial x^r} = 0 \quad (k = m+1, \dots, n).$$

If we introduce the notation

$$\frac{\partial f}{\partial s^k} = \lambda_k^r \frac{\partial f}{\partial x^r},$$

then, as Ricci and Levi-Civita have shown*, the relation

$$(23) \quad \frac{\partial}{\partial s_j} \frac{\partial f}{\partial s_k} - \frac{\partial}{\partial s_k} \frac{\partial f}{\partial s_j} = \sum_i^{1 \dots n} (\gamma_{ijk} - \gamma_{ikj}) \frac{\partial f}{\partial s_i}$$

is satisfied for any function f .

Applying this formula to equations (22) we have in consequence of (21)

$$X_j X_k(f) - X_k X_j(f) = \sum_i^{m+1 \dots n} (\gamma_{ijk} - \gamma_{ikj}) X_i(f) \quad (j, k = m+1, \dots, n).$$

Hence the system (22) is complete and admits m independent solutions, say f_h ($h = 1, \dots, m$).

* Loc. cit., p. 150; Wright, p. 69.

Let q_2 be another root of (5), of order p , and denote by λ_j^r ($j = m + 1, \dots, m + p$) the components of the corresponding vectors. In like manner we show that the equations

$$\lambda_l^r \frac{\partial f}{\partial x^r} = 0 \quad (l = 1, \dots, m, m + p + 1, \dots, n)$$

form a complete system and admit p independent solutions f_j ($j = m + 1, \dots, m + p$).

From (22) and the equations

$$\lambda_k^r \lambda_{h,r} = 0 \quad (h = 1, \dots, m; k = m + 1, \dots, n)$$

it follows that there exist functions a_h^σ such that

$$\frac{\partial f_h}{\partial x^r} = \sum_{\sigma} a_h^\sigma \lambda_{\sigma,r} \quad (h, \sigma = 1, \dots, m).$$

In like manner, we have

$$\frac{\partial f_j}{\partial x^r} = \sum_{\tau} b_j^\tau \lambda_{\tau,r} \quad (j, \tau = m + 1, \dots, m + p).$$

Consequently we have

$$g^{rs} \frac{\partial f_h}{\partial x^r} \frac{\partial f_j}{\partial x^s} = \sum_{\sigma, \tau} a_h^\sigma b_j^\tau g^{rs} \lambda_{\sigma,r} \lambda_{\tau,s} = 0,$$

that is, any hypersurface $f_h = \text{const.}$ is orthogonal to each of the hypersurfaces $f_j = \text{const.}$

Proceeding in this manner with the other roots of (5) we obtain a group of hypersurfaces corresponding to each distinct root of (5), the number of hypersurfaces in a group being equal to the order of the root. Any two hypersurfaces of two different groups are orthogonal to one another. If we take these n families of hypersurfaces for the parametric surfaces $x^r = \text{const.}$ ($r = 1, \dots, n$), it follows that the functions g_{rs} are zero, for the case where $x^r = \text{const.}$ and $x^s = \text{const.}$ are hypersurfaces of different groups; in this sense we say that r and s refer to different groups, or different roots of (5).

From the equations (22) for this choice of the variables x , it follows that $\lambda_k^r = 0$, for r and k referring to different roots of (5). From (9) it follows also that $\lambda_{k,r} = 0$ for k and r referring to different roots.

Equations (6) may be replaced by*

$$(24) \quad \alpha_{rs} = \sum_h^{1 \dots n} \varrho_h \lambda_{h,r} \lambda_{h,s}$$

whether the roots of (5) are simple, or some are multiple. From (24) and the preceding observations it follows

$$(25) \quad \begin{aligned} \alpha_{rs'} &= g_{rs'} = 0, \\ \alpha_{rs} &= \varrho_h g_{rs}, \end{aligned}$$

where r and s' refer to any two different roots and r and s refer to the root ϱ_h .†

4. From (25) we have $\alpha_{rs'} = 0$, hence if $\alpha_{rs't} = 0$, we must have (cf. (2))

$$\alpha_{rl} \Gamma_{s't}^l + \alpha_{s'q} \Gamma_{rt}^q = 0 \quad (l, q = 1, \dots, n),$$

that is

$$\alpha_{rl} g^{l\mu} \left[\frac{\partial g_{s'\mu}}{\partial x^t} + \frac{\partial g_{t\mu}}{\partial x^{s'}} - \frac{\partial g_{s't}}{\partial x^\mu} \right] + \alpha_{s'q} g^{q\mu} \left[\frac{\partial g_{r\mu}}{\partial x^t} + \frac{\partial g_{t\mu}}{\partial x^r} - \frac{\partial g_{rt}}{\partial x^\mu} \right] = 0.$$

If r refers to the root ϱ_1 of (5), say $r = 1, \dots, m$ and s' to the root ϱ_2 , say $s' = m+1, \dots, m+p$, we have from (25)

$$\begin{aligned} \alpha_{rl} &= \varrho_1 g_{rl} & (l = 1, \dots, m); \\ \alpha_{rl} &= 0 & (l = m+1, \dots, n); \\ \alpha_{s'q} &= \varrho_2 g_{s'q} & (q = m+1, \dots, m+p); \\ \alpha_{s'q} &= 0 & (q = 1, \dots, m, m+p+1, \dots, n). \end{aligned}$$

Hence the above equation reduces to

$$\varrho_1 \left(\frac{\partial g_{s'r}}{\partial x^t} + \frac{\partial g_{tr}}{\partial x^{s'}} - \frac{\partial g_{s't}}{\partial x^r} \right) + \varrho_2 \left(\frac{\partial g_{rs'}}{\partial x^t} + \frac{\partial g_{ts'}}{\partial x^r} - \frac{\partial g_{rt}}{\partial x^{s'}} \right) = 0.$$

* Cf. Ricci and Levi-Civita, loc. cit., p. 159.

† Cf. Levi-Civita, *Annali di Matematica*, ser. 2, vol. 24 (1896), p. 298.

If now t and r refer to the same root, this equation reduces to

$$(\varrho_1 - \varrho_2) \frac{\partial g_{tr}}{\partial x'^s} = 0,$$

and if t and s' refer to the same root, we have

$$(\varrho_1 - \varrho_2) \frac{\partial g_{s't}}{\partial x^r} = 0.$$

If r , s' and t refer to three different roots, the equation vanishes identically.

Since ϱ_1 and ϱ_2 are not equal by hypothesis, we have that each function g_{rs} depends only on the coördinates referring to the same root as r and s .

Consider again

$$\alpha_{rs} = \varrho_1 g_{rs} \quad (r, s = 1, \dots, m).$$

Now

$$\alpha_{rs;t} = \varrho_1 \frac{\partial g_{rs}}{\partial x^t} - \alpha_{rl} \Gamma_{st}^l - \alpha_{sl} \Gamma_{rt}^l \quad (l = 1, \dots, n),$$

which by (25) is reducible to

$$\alpha_{rs;t} = \varrho_1 \left(\frac{\partial g_{rs}}{\partial x^t} - g_{rl} \Gamma_{st}^l - g_{sl} \Gamma_{rt}^l \right) = \varrho_1 g_{rs;t} = 0.$$

Hence we have the following theorem:

A necessary and sufficient condition that a Riemann space admit a symmetric covariant tensor of the second order α_{rs} other than, with a positive definite fundamental form (1), g_{rs} , such that its first covariant derivative is zero, is that (1) be reducible to a sum of forms

$$(26) \quad \varphi^{(i)} = g_{r_i s_i}^{(i)} dx^{r_i} dx^{s_i},$$

where $g_{r_i s_i}^{(i)}$ are functions at most of the x 's of that form; then

$$(27) \quad \alpha_{rs} dx^r dx^s = \sum_i \varrho_i \varphi^{(i)},$$

where the ϱ 's are arbitrary constants.

Since g_{rs} satisfies (28) the systems (29) and (30) are satisfied by g_{rs} and consequently are algebraically consistent. From this it follows either that the functions g_{rs} are the only solution of (29) and (30), or that (29) and the first l (≥ 0) sets of (30) admit a complete system of solutions g_{rs} and $\alpha_{rs}^{(1)}, \dots, \alpha_{rs}^{(p)}$ which satisfy also the $(l+1)$ th set of equations (30). In the latter case the general solution is of the form

$$(31) \quad \alpha_{rs} = \varphi^{(0)} g_{rs} + \varphi^{(1)} \alpha_{rs}^{(1)} + \dots + \varphi^{(p)} \alpha_{rs}^{(p)}.$$

If any one of the functions $\alpha_{rs}^{(\sigma)}$ ($\sigma = 1, \dots, p$) is substituted in (29) and the first l sets of (30), and these equations are differentiated covariantly, we have, in consequence of the above requirement, that the functions $\alpha_{rs/m}^{(\sigma)}$ ($\sigma = 1, \dots, p; m = 1, \dots, n$) satisfy (29) and the first l sets of (30). Consequently we have

$$(32) \quad \alpha_{rs/m}^{(\sigma)} = \lambda_m^{(\sigma)} g_{rs} + \lambda_m^{(\sigma 1)} \alpha_{rs}^{(1)} + \dots + \lambda_m^{(\sigma p)} \alpha_{rs}^{(p)},$$

where the $p(p+1)$ vectors $\lambda_m^{(\sigma\beta)}$ ($\sigma = 1, \dots, p; \beta = 0, 1, \dots, p$) must be such that the functions (32) shall satisfy (28). Substituting in these equations we find that the functions λ must satisfy the system

$$(33) \quad \frac{\partial \lambda_p^{(\sigma\tau)}}{\partial x^q} - \frac{\partial \lambda_q^{(\sigma\tau)}}{\partial x^p} + \sum_{\omega} (\lambda_p^{(\sigma\omega)} \lambda_q^{(\omega\tau)} - \lambda_q^{(\sigma\omega)} \lambda_p^{(\omega\tau)}) = 0 \quad \left(\begin{array}{l} \sigma, \omega = 1, \dots, p \\ \tau = 0, 1, \dots, p \end{array} \right).$$

In order that α_{rs} given by (31) shall satisfy $\alpha_{rs/t} = 0$, it is necessary and sufficient that the functions $\varphi^{(i)}$ satisfy

$$(34) \quad \frac{\partial \varphi^{(0)}}{\partial x^t} + \sum_{\sigma} \varphi^{(\sigma)} \lambda_t^{(\sigma 0)} = 0 \quad (\sigma = 1, \dots, p),$$

and

$$(35) \quad \frac{\partial \varphi^{(\tau)}}{\partial x^t} + \sum_{\sigma} \varphi^{(\sigma)} \lambda_t^{(\sigma\tau)} = 0 \quad (\sigma, \tau = 1, \dots, p).$$

In consequence of (33) equations (35) are completely integrable and therefore admit solutions involving p arbitrary constants. Because of (33) the conditions of integrability of (34) are satisfied; hence $\varphi^{(0)}$ involves these p arbitrary constants and an additive arbitrary constant which may be neglected.*

* If α_{rs} is a tensor whose first covariant derivative is zero, so also is $\alpha_{rs} + \lambda g_{rs}$, where λ is an arbitrary constant.

In view of the above results we have the theorem:

If equations (29) and the first $l (\geq 0)$ sets of equations (30) admit a complete system of solutions g_{rs} and $\alpha_{rs}^{(\sigma)}$ ($\sigma = 1, \dots, p$) which are also solutions of the $(l+1)$ th set of equations (30), there exists a symmetric tensor of the second order, involving p arbitrary constants, whose first covariant derivative is zero.

6. Suppose that the fundamental form is the sum of j forms (26). By definition

$$(36) \quad B_{p's}^a = g^{a'q} B_{pqrs},$$

where B_{pqrs} is the covariant Riemann tensor of the fourth order, that is,

$$(37) \quad B_{pqrs} = \frac{1}{2} \left(\frac{\partial^2 g_{ps}}{\partial x^q \partial x^r} + \frac{\partial^2 g_{qr}}{\partial x^p \partial x^s} - \frac{\partial^2 g_{pr}}{\partial x^q \partial x^s} - \frac{\partial^2 g_{qs}}{\partial x^p \partial x^r} \right) + g^{lm} (\Gamma_{ps,m} \Gamma_{qr,l} - \Gamma_{pr,m} \Gamma_{qs,l}),$$

where

$$(38) \quad \Gamma_{ps,m} = \frac{1}{2} \left(\frac{\partial g_{pm}}{\partial x^s} + \frac{\partial g_{sm}}{\partial x^p} - \frac{\partial g_{ps}}{\partial x^m} \right).$$

For the case under consideration, namely (26), it is readily shown that the components B_{pqrs} are zero, unless p, q, r, s refer to the same root of (5); likewise $B_{p's}^a$, and its first covariant derivatives $B_{p's;t}^a$. Consequently equations (29) and the first set of (30) admit, in addition to g_{rs} , the j sets of solutions of the form (25). If it is understood that each of the forms (26) is not further reducible to sums of such forms, we have a complete set of solutions of (29). Hence when the space is referred to the coördinates giving (25) the number l in the preceding theorem is zero.

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