

CONFORMAL DIFFERENTIAL GEOMETRY OF A SUBSPACE

BY

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INTRODUCTION

Scope. Conformal differential geometry (as developed in this paper) concerns itself with certain spaces, point transformations, and configurations. The particular spaces which are considered here are the m -dimensional Riemann spaces V_m . These spaces are generalizations of and include euclidean m -space R_m . The basic point transformations of this paper are the conformal transformations. A conformal transformation defined on a Riemann space V_m is a mapping of V_m on itself or another Riemann space \bar{V}_m so that corresponding angles in V_m and \bar{V}_m are equal in magnitude. We do not study the conformal transformations of the Riemannian spaces as a whole upon each other (that is, the intrinsic conformal theory of the space) but the conformal geometry of configurations in these spaces. The configuration in V_m which we study is a subspace V_n . The dimensionality n of this subspace may be any integer between 1 (curve) and $m-1$ (hypersurface) inclusive. Accordingly, conformal differential geometry, as defined above, investigates those properties of a curve, hypersurface or other subspace which remain unchanged when the enveloping Riemann space V_m undergoes any conformal mapping, not necessarily on itself. As an important special case, this geometry includes the inversive geometry of a euclidean space R_m .

Method. Euclidean geometry may be defined as the invariant theory of the euclidean metric or congruence group. Not only do the congruence transformations define the geometry; they were a fundamental method in the development of the early (Greek) geometry of the plane. The picture is quite different in the classical differential geometry of two and three-dimensional euclidean space. Here, since the time of Gauss, the fundamental method in the geometry (as distinguished from its definition) has been based upon quadratic differential forms. These quadratic differential forms control the metric of the space and the metrics and curvatures of configurations (curves, surfaces) in the space. What was a powerful tool for the geometric exploration of space in the hands of Gauss became the defining structure of the space in the epoch making generalization of Riemann. The geometry of Riemann spaces and the corresponding tensor calculus have since been developed by Christoffel, Ricci, Levi-Civita and others into a beautiful and elegant theory. The power of the methods of Riemannian geometry rests primarily upon

(1) the existence of a fundamental metric tensor (whose components are the coefficients of the fundamental quadratic differential form), (2) the process of covariant differentiation, (3) the tensor character of the important geometric objects in the space, and of the operations performed upon these objects.

In our development of conformal differential geometry, we have largely ignored the conformal transformations which define the geometry and have attempted to take maximum advantage of the methods of Riemannian geometry. A first necessary step in the realization of this aim is the discovery of a symmetric second order tensor in V_m (corresponding to the Riemann metric tensor) which remains unchanged by conformal transformations of V_m . In the intrinsic conformal theory of V_m , there does not exist at present any method for attaining this desirable objective.

But a subspace V_n introduces new elements of structure into the enveloping Riemann space V_m at points of V_n . By means of these new structural properties, we discover a relative conformal scalar⁽¹⁾ Λ which exists at points of the subspace. The existence of Λ makes it an easy matter to define two new symmetric second order tensors which do not change when V_m undergoes any conformal transformation. These tensors, called the "conformal measure tensors," introduce a new "conformal metric" into the space. The first tensor is used to measure "conformal distance" in the subspace V_n and the second to measure "conformal distance" in the enveloping space V_m at points of V_n . By making use of Λ , it is also possible to invent a new type of covariant differentiation (with respect to the subspace V_n) which plays a role analogous to ordinary covariant differentiation in Riemannian geometry. This "conformal covariant differentiation" process or "conformal derivative" enjoys all the usual properties of covariant differentiation as well as a number of others which give it its distinctive conformal character.

The tensors for the measurement of conformal distance and the conformal differentiation process constitute the methodological foundation for our development of conformal differential geometry. By means of the conformal measure tensors and conformal differentiation, it is possible to apply all the usual operations to conformal tensors⁽²⁾ without altering either their conformal or tensor character. Consequently our development of conformal differential geometry proceeds by a full utilization of the technical apparatus of tensor calculus and Riemannian geometry. Its formal, technical aspects are scarcely more involved than those of the ordinary (metric) theory of Riemann spaces. The same methods may be used to investigate the conformal differential geometry of configurations⁽³⁾ in V_m other than those which are considered here.

(1) This term is defined in §3 and Λ is defined in §6.

(2) This term is defined in §3.

(3) Examples of such configurations are: congruences of curves, families of subspaces, m -beins.

The formal calculations themselves may be shortened considerably by making use of the "replacement principle." This principle states that certain tensors which appear frequently in the sequel may be replaced by zeros in the expressions where they occur. It depends upon a change in gauge, but in its effect is somewhat analogous to the choice of special coordinate systems frequently made in classical and Riemannian geometry.

Results. In the preceding paragraphs we have discussed, in general terms, the scope of our subject and the methods employed. What are the actual questions which are considered and what answers are obtained? The conclusions of this paper may be summarized under the following topics:

(1) *Conformal geometric objects.* A number of new conformal geometric objects are invented and their definition obtained in tensor form. Among these geometric objects are conformal analogues of the metric tensor, the Christoffel symbols, and the Riemann tensor, all of which are defined both for the subspace V_n and for the enveloping space V_m at points of V_n . We also construct various new tensors from the Weyl conformal curvature tensor. The existence of conformal analogues of the geodesic and normal coordinates of Riemannian geometry is proved. By successive conformal differentiation of the tangent vector space of V_n , we obtain a sequence of conformal vector spaces analogous to the osculating and normal vector spaces of V_n in Riemannian geometry. The measurement of the conformal length of vectors lying in these "conformal normal vector spaces" introduces various tensors analogous to the coefficients of the second fundamental form of a hypersurface. We call these tensors the "conformal normal measure tensors" of V_n . We also define still another symmetric second order tensor in connection with the variation of the relative conformal curvature Λ . This tensor which we call the "deviation tensor" has no analogue in Riemannian geometry. Symmetric tensors constructed from the various conformal measure tensors and the deviation tensor are the "conformal fundamental tensors" of V_n . Their components serve as coefficients of the various "conformal fundamental forms" of V_n .

(2) *Conformal relations.* Various relations among these conformal geometric objects (principally in the form of conformal tensor equations) are derived. For example, both the Weyl tensors and the "conformal Riemann tensors" have symmetry properties like those of the ordinary Riemann tensor and satisfy identities similar to the Bianchi identities of Riemannian geometry. Conformal differentiation of the various conformal tangent and normal vector spaces leads to a system of tensor equations analogous to the Frenet equations. The integrability conditions of these "conformal Frenet equations" are another system of equations involving various conformal tensors. The simplest of these latter equations are analogues of the Gauss equations and the Codazzi equations which occur both in classical and Riemannian geometry. In addition to the above conditions, the integrability conditions of still another set of partial differential equations which have no analogue in classi-

cal or Riemannian geometry are of equal importance. However, if $n > 2$ some of these last conditions, and if $n > 3$ all of these last conditions, are consequences of the integrability conditions of the conformal Frenet equations. The various integrability conditions enumerated above as well as a number of other important algebraic and differential equations are termed the "fundamental equations" of V_n . All of the quantities which occur in the fundamental equations are conformal tensors defined on V_n .

(3) *The basic theorems.* Since the process of construction of the conformal fundamental forms of V_n consisted entirely of conformal elements, it follows that if $V_m \rightleftharpoons \bar{V}_m$, $V_n \rightleftharpoons \bar{V}_n$ by a conformal map, then the corresponding fundamental forms of V_n and \bar{V}_n are equal. The converse holds in spaces which are conformal to a euclidean space. In this case, we have the fundamental conformal equivalence theorem: *If V_m and \bar{V}_m are conformal to a euclidean space and the corresponding conformal fundamental forms of V_n and \bar{V}_n are equal, then a conformal transformation exists so that $V_m \rightleftharpoons \bar{V}_m$ and $V_n \rightleftharpoons \bar{V}_n$.* This is the conformal analogue of the congruence theorem of classical and Riemannian geometry which holds in a euclidean space and in a space of constant curvature. We also prove the existence theorem: *A subspace V_n exists in any conformally euclidean space with preassigned conformal fundamental forms whose coefficients satisfy the fundamental equations. The V_n is determined uniquely by a set of initial conditions which is found explicitly.* The basic question concerning the conformal differential forms of any subspace V_n is answered (at least when the enveloping space is conformally euclidean) by the theorem: *The coefficients of any conformal differential form of a V_n in a conformally euclidean space are tensor functions of the conformal fundamental tensors and the conformal Riemann tensor of V_n and their conformal derivatives, and conversely.*

(4) *Exceptional cases.* If the relative conformal curvature Λ vanishes identically in V_n , all the results outlined above become meaningless. There are two categories of exceptional cases for which $\Lambda \equiv 0$:

(i) $n > 1$. In this case, the conformal distance measured between any two points on V_n is identically zero and V_n is a "conformal null subspace." These subspaces retain this characteristic under conformal transformations of V_m . They are the conformal images of totally geodesic subspaces, and conversely. In euclidean space, they are the n -dimensional planes and spheres.

(ii) $n = 1$. The conformal theory outlined in this introduction does not apply to one-dimensional subspaces since Λ is identically zero on every curve. The conformal geometry of curves was developed by the author in a separate paper [8]⁽⁴⁾. Results analogous to those stated above were proved subject to the restriction that the dimensionality⁽⁵⁾ m of the enveloping space ex-

(4) The numbers in brackets refer to the bibliography at the end of the paper.

(5) This is a natural restriction since every analytic curve in a V_2 is conformally equivalent to a straight line in the plane and hence cannot have conformal properties.

ceed 2. If $m=2$, the results still apply if the conformal transformations are restricted to mappings which are similar to and include the inversive transformations of the plane. In the last section of this paper, we show how these results of our previous paper on conformal curve theory may be obtained by a slight modification of the methods used here for a general subspace.

Previous literature⁽⁶⁾. The literature on conformal differential geometry may be divided into two main categories. One approach to the subject is the intrinsic conformal theory; that is, the investigation of conformal transformations of Riemann spaces as a whole upon each other. The discovery of the conformal curvature tensor by Weyl and the characterization of conformally euclidean spaces by Schouten mark the modern beginning of this subject. The central problem of the intrinsic theory is the question of the conformal equivalence of Riemann spaces. A number of investigations by T. Y. Thomas, Veblen, Cartan, Schouten, Haantjes and others have appeared which deal with this topic.

The other approach (which is followed in this paper) is the study of configurations in an enveloping Riemann space V_m and their behavior when the enveloping manifold undergoes any conformal mapping. An early result of this kind is the theorem of Schouten and Struik which states that the lines of curvature of a hypersurface of V_m remain invariant under conformal transformations of V_m . Several other results of a similar character exist, some of which are not purely conformal theorems since they depend upon metric properties of the configuration and upon the particular transformation to which the V_m is subjected. Recently a number of papers by Sasaki and Yano have appeared which investigate the conformal geometry of subspaces using the formal methods which have been developed in connection with the intrinsic theory.

In addition to the above work, a considerable number of papers have appeared dealing with the inversive geometry of plane curves and of curves and surfaces in euclidean three-dimensional space. These studies make no use of tensors or of Riemannian geometry; their methods depend, in most cases, upon the Schwarzian derivative or tetracyclic and pentaspherical coordinates. These investigations of inversive geometry are the only papers on conformal geometry which in any way overlap the work of the present paper. In particular, the books of Thomsen and Blaschke [2] and of Takasu [14] constitute an inversive theory of curves and surfaces in the plane and in euclidean 3-space which is complete in its essential parts and anticipates many of our results for this important but special case. However, their methods depend upon the systematic use of tetracyclic and pentaspherical coordinates and therefore differ completely from the methods which are employed here.

(6) References to and more detailed remarks about the various papers mentioned in this section appear in our paper on curve theory [8, pp. 436-438, 441, 495]. Also see the book of Schouten and Struik [13, pp. 199-215] for a general discussion of the conformal differential geometry of Riemann spaces.

I. PRELIMINARY MATTERS

1. **Notation.** In this section, various conventions concerning notation and terminology which are used in the sequel are summarized. Except where the contrary is stated explicitly, it is understood that these conventions are used throughout the paper. Precise definitions of the various terms used in this section appear in later portions of the paper.

Terminology. (i) In this paper, two different metrics occur: the usual Riemann metric of Riemannian geometry and the new metric of conformal geometry. The Riemannian metric of a space is frequently referred to simply as the "metric" of the space and geometric objects which are constructed relative to the Riemannian metric are referred to as "metric geometric objects."

(ii) However, when no ambiguity is possible, the adjective "conformal" used in referring to various geometric objects is omitted. For example, the "conformal measure tensors" are usually called the "measure tensors."

(iii) The words "space" and "surface" are used to distinguish geometric objects defined relative to an enveloping Riemann space or to a subspace imbedded in it. When there is no danger of ambiguity, these words are omitted. For example, the "surface conformal Riemann tensor" may be referred to as the "conformal Riemann tensor."

General conventions. (i) The usual conventions of tensor notation are assumed. For example, a tensor equation in which an index is not summed is valid for each value of the index within its range. When the same letter appears in any term as a subscript and superscript, it is understood that this letter is summed for all values within its range. Sometimes summation is also denoted by \sum .

(ii) The same kernel letter(?) is used to indicate the contravariant and covariant components of the same vector. For example, π^α and π_α refer to the same vector. A similar assumption is made for any tensor.

(iii) Space and surface components of the same tensor are also indicated by the same kernel letter. For example, the space vector λ^α and the space tensor $\pi^{\alpha k}_{\beta l}$ have the surface components λ^i and π^{ik}_{jl} respectively.

(iv) The properties of a general tensor are usually illustrated by means of the tensor π^α_β or π^i_j or $\pi^{\alpha i}_{\beta j}$. Here α and i (β and j) represent any contravariant (covariant) space and surface indices respectively.

(v) As a general rule, lower case Roman and Greek kernel letters represent Riemannian metric geometric objects, capital Greek kernel letters represent relative conformal geometric objects and capital Roman kernel letters represent conformal geometric objects.

(vi) References, indicated by brackets, refer to the bibliography at the end of the paper.

(?) We call π the "kernel letter" of the vector π^α or π_α and use similar terminology for any tensor.

Indices. The set of indices $\alpha, \beta, \gamma, \delta, \epsilon, \zeta; g, h, i, j, k, l; \tau, \omega$ have the ranges $1, 2, \dots, m; 1, 2, \dots, n; n+1, n+2, \dots, m$ respectively. The powers and subscripts u, v, w, a, b have arbitrary ranges. Indices such as α_w and i_v have the same range as α and i respectively. The symbol (i_w) means $i_1 i_2 \dots i_w$. The letters m, n, p and q, r, s represent dimension numbers and class numbers respectively. They are not indices.

Spaces. The symbols V_m, R_m, S_m are used to represent an m -dimensional Riemann space, euclidean space, and space of constant curvature respectively. The symbol $V^{(p)}$ refers to a p -dimensional vector space. However $I_1, I_2, \dots, I_{12} \dots M$ and I_2, I_3, \dots, I_M refer to the conformal osculating vector spaces and conformal normal vector spaces of V_n .

Conformal correspondence. A Riemann space conformal to V_m is denoted by \bar{V}_m . Thus \bar{R}_m signifies a conformally euclidean space. A geometric object in \bar{V}_m corresponding to the geometric object \mathcal{F} in V_m is denoted by $\bar{\mathcal{F}}$.

Operations. (i) The projection of a vector π^α in a vector space $V^{(p)}$ is denoted by $^*\pi^\alpha$. The precise space $V^{(p)}$ into which π^α is projected is indicated in the context.

(ii) Covariant differentiation with respect to $a_{\alpha\beta}, g_{ij}$ and $\bar{a}_{\alpha\beta}, \bar{g}_{ij}$ are denoted by a comma (,) and semicolon (;) respectively. The symbol for conformal covariant differentiation is the colon (:). The conformal derivative (along a curve) with respect to S is denoted by $\vartheta/\vartheta S$.

(iii) A cyclic sum of tensors is indicated by a plus sign (+) and an alternating sum by a minus sign (-). For example,

$$\begin{aligned} \rho^\alpha_{\beta\gamma\delta} + \rho^\alpha_{\delta\gamma\beta} &\equiv \rho^{\alpha\beta+\gamma\delta+}, & B_{ij}F_k - B_{ik}F_j &\equiv B_{ij-}F_k- \equiv B_{i(j}F_{k)-}, \\ \rho^\alpha_{\beta\gamma\delta} + \rho^\alpha_{\gamma\delta\beta} + \rho^\alpha_{\delta\beta\gamma} &\equiv \rho^{\alpha\beta+\gamma+\delta+} \equiv \rho^{\alpha\beta+(\gamma\delta)+} \equiv \rho^{\alpha(\beta\gamma\delta)+}, \\ \rho^\alpha_{\beta\gamma\delta,\epsilon} + \rho^\alpha_{\beta\delta\epsilon,\gamma} + \rho^\alpha_{\beta\epsilon\gamma,\delta} &\equiv \rho^{\alpha\beta\gamma+\delta+,\epsilon+} \equiv \rho^{\alpha\beta(\gamma\delta)+,\epsilon+} \equiv \rho^{\alpha\beta(\gamma\delta,\epsilon)+}, \\ G^{\alpha_{ijk}} - G^{\alpha_{ikj}} &\equiv G^{\alpha_{ij-k-}} \equiv G^{\alpha_{i(jk)-}}, \\ E_{ij:k} - E_{ik:j} &\equiv E_{ij-:k-} \equiv E_{i(j:k)-}. \end{aligned}$$

(iv) The replacement operation is denoted by a small zero (⁰). For example, ⁰ $\kappa_{ij},$ ⁰ $a_{\alpha\beta}$.

(v) The Weyl operation is symbolized by a vertical arrow (\uparrow). For example, $\uparrow \rho^\alpha_{\beta\gamma\delta}$.

2. Riemann spaces conformal to V_m . Let V_m be a real Riemann space whose coordinate manifold is of class⁽⁸⁾ C^q and whose real metric tensor, defined over the manifold, is positive definite⁽⁹⁾ and of class C^{q-1} with $q \geq 1$.

(⁸) The definitions of the class of a coordinate manifold and of a Riemann space are based upon the discussion which appears in [16, pp. 98-99, 104]. In particular, if the coordinate manifold is of class C^q , then the admissible coordinate systems are related to each other by transformations of class C^q .

(⁹) The greater part of the following discussion and of the results of the paper will hold even if the metric tensor is indefinite provided that it is not singular. The only real novelty arises when a vector is a null vector. We shall not consider the indefinite case.

Briefly, we say that V_m is a Riemann space of class C^q . Suppose $\{y^\alpha\}$ are admissible real local coordinates in a coordinate neighborhood of any point of V_m . In each coordinate neighborhood, we write the first fundamental form of V_m as

$$(2.1) \quad ds^2 = a_{\alpha\beta} dy^\alpha dy^\beta.$$

Let \bar{V}_m be a real Riemann space of class C^q whose first fundamental form may be written as

$$(2.2) \quad d\bar{s}^2 = \bar{a}_{\alpha\beta} d\bar{y}^\alpha d\bar{y}^\beta$$

where $\{\bar{y}^\alpha\}$ are allowable local coordinates. Then \bar{V}_m is conformal to V_m by means of a transformation of class C^q (briefly: \bar{V}_m is conformal to V_m) if a one-to-one point transformation \mathcal{T} exists between the points \mathcal{P} of V_m and the points $\bar{\mathcal{P}}$ of \bar{V}_m which may be written (locally) as

$$(2.3) \quad \bar{y}^\alpha = \bar{y}^\alpha(y^1, y^2, \dots, y^m), \quad y^\alpha = y^\alpha(\bar{y}^1, \bar{y}^2, \dots, \bar{y}^m)$$

so that the real functions

$$\bar{y}^\alpha(y^1, y^2, \dots, y^m), \quad y^\alpha(\bar{y}^1, \bar{y}^2, \dots, \bar{y}^m)$$

are of class C^q and⁽¹⁰⁾

$$(2.4) \quad d\bar{s} = e^\sigma ds$$

at corresponding points. It follows that $\sigma(y^\alpha)$ is a real function of class C^{q-1} and that the form (2.2) is positive definite. We refer to $\sigma(y^\alpha)$ as the *conformal mapping function* of V_m on \bar{V}_m , or briefly, as the *mapping function*. Whenever we say that \bar{V}_m is conformal to V_m it is to be understood that the conformal transformation is of class C^q .

The transformation \mathcal{T} may be written in the simple form

$$(2.5) \quad \bar{y}^\alpha = y^\alpha$$

after a suitable change of coordinates. For if we transform the coordinate neighborhoods of V_m according to (2.3) considered as an admissible coordinate transformation, points in \bar{V}_m and V_m with the same coordinates correspond and the conformal transformation becomes (2.5). Throughout this paper, unless a contrary assumption is explicitly made, we shall always assume that coordinate systems have been chosen so that (2.5) holds. In these coordinate systems,

$$(2.6) \quad \bar{a}_{\alpha\beta} = e^{2\sigma} a_{\alpha\beta}, \quad \bar{a}^{\alpha\beta} = \bar{e}^{2\sigma} a^{\alpha\beta},$$

where $a^{\alpha\beta}$ and $\bar{a}^{\alpha\beta}$ are the contravariant components of the metric tensors.

⁽¹⁰⁾ The condition (2.4) is readily seen to be equivalent to either of the geometric statements: (1) The magnitudes of corresponding angles of V_m and \bar{V}_m are equal. (2) The ratio of the length of any vector at any point \mathcal{P} of V_m to the length of the corresponding vector in \bar{V}_m is the same for all vectors at \mathcal{P} ; that is, the transformation is a local similitude.

The contravariant metric tensor $a^{\alpha\beta}$ is determined by the equations

$$a_{\beta\gamma}a^{\alpha\gamma} = \delta^{\alpha}_{\beta}$$

where δ^{α}_{β} are the Kronecker deltas and $\bar{a}^{\alpha\beta}$ is determined by similar equations. Conversely, if (2.5) is a point transformation of the points of V_m and \bar{V}_m and (2.6) holds at corresponding points where the mapping function $\sigma(y^{\alpha})$ is a real function of class C^{q-1} , it follows that \bar{V}_m is conformal to V_m .

Let

$$(2.7) \quad \{e^{2\sigma}a_{\alpha\beta}\}$$

denote the set of all second order, symmetric, positive definite tensors of class C^{q-1} , any two of which are equal except for a positive multiplicative scalar factor of class C^{q-1} . Let

$$(2.8) \quad \{\bar{V}_m\}$$

denote the set of all conformally equivalent Riemann spaces of class C^q whose metric tensors (in some allowable coordinate system) belong to (2.7). Throughout this paper, whenever we refer to the conformally equivalent Riemann spaces V_m, \bar{V}_m , it will be understood that these spaces are any two spaces of the set of conformally equivalent Riemann spaces (2.8).

3. Conformal tensors. Let $T^{\alpha_1 \dots \alpha_w}_{\beta_1 \dots \beta_v}$ be components of a tensor at a point \mathcal{P} of V_m whose values depend upon geometric objects of V_m and of its subspaces⁽¹¹⁾. Let \bar{V}_m be any Riemann space conformal to V_m and let $\bar{T}^{\alpha_1 \dots \alpha_w}_{\beta_1 \dots \beta_v}$ be the components of the tensor at $\bar{\mathcal{P}}$ whose values depend in the same way upon the corresponding geometric objects of \bar{V}_m and its corresponding subspaces. Then if (2.6) holds and

$$(3.1) \quad \bar{T}^{\alpha_1 \dots \alpha_w}_{\beta_1 \dots \beta_v} = (e^{\sigma})^u T^{\alpha_1 \dots \alpha_w}_{\beta_1 \dots \beta_v}$$

we call $T^{\alpha_1 \dots \alpha_w}_{\beta_1 \dots \beta_v}$ a *relative conformal tensor of weight u* . The law of transformation of $T^{\alpha_1 \dots \alpha_w}_{\beta_1 \dots \beta_v}$ between any two \bar{V}_m as well as between any two coordinate systems is consistent. If $u = 0$, the tensor has the same components in V_m and \bar{V}_m . In this case, we call $T^{\alpha_1 \dots \alpha_w}_{\beta_1 \dots \beta_v}$ a *conformal tensor*.

As a consequence of our definitions it follows that if the components of a relative conformal tensor are zero in V_m , they are zero in any \bar{V}_m . This fact permits us to write conformal tensor equations which retain their meaning under conformal transformations. The sum or difference of relative conformal tensors of the same weight and valence is a relative conformal tensor of that weight and valence. The inner or outer product of relative conformal tensors is a relative conformal tensor. In particular, the sum, difference, inner or outer product of conformal tensors is a conformal tensor.

⁽¹¹⁾ Examples of such geometric objects which will be used in this paper are: the metric tensor $a_{\alpha\beta}$, the Christoffel symbols of the second kind, the coefficients of the first and second fundamental forms of a subspace.

As examples, we note that the metric tensors $a_{\alpha\beta}$ and $a^{\alpha\beta}$ are relative conformal tensors of weight 2 and -2 respectively as follows from (2.6). The Weyl conformal curvature tensor $C^{\alpha\beta\gamma\delta}$ is a conformal tensor.

4. Algebraic and metric properties. In §§4, 5, we summarize some of the results of the metric theory of a subspace of a Riemann space. These well known results are useful for the development of the conformal theory. We suppose that V_m is any Riemann space belonging to (2.8) and let \mathcal{R} be a subset of V_m with the following properties:

- (a) \mathcal{R} is a real n -dimensional topological space with $n < m$.
- (b) The coordinate manifold of \mathcal{R} is of class C^r where r is a fixed integer subject to the inequalities

$$(4.1) \quad g \geq r$$

and⁽¹²⁾

$$(4.2) \quad r \geq 1.$$

We denote any system of admissible local coordinates in a coordinate neighborhood of \mathcal{R} by $\{x^i\}$. Following Mayer [3, p. 53], we refer to the coordinates x^i of a point of \mathcal{R} as *parameters* to differentiate them from the *coordinates* y^α of the same point considered as a point of⁽¹³⁾ V_m .

(c) In each parameter neighborhood of \mathcal{R} , lying in a coordinate neighborhood of V_m , the correspondence between the coordinates y^α and the parameters x^i at points of \mathcal{R} determines the y^α as functions of class C^r in the x^i ; that is, the functions

$$(4.3) \quad y^\alpha = y^\alpha(x^1, x^2, \dots, x^n)$$

are of class C^r . Equations (4.3) are the parametric equations of \mathcal{R} . It follows from (b) that condition (c) is true in every allowable coordinate and parameter system. Hence if a tensor, defined on a space neighborhood containing a surface neighborhood, is of class C^s ($s \leq r$) in the y^α it is also of class C^s in the x^i .

(d) The rank of the matrix $\|\partial y^\alpha / \partial x^i\|$ at a given fixed point \mathcal{P} of \mathcal{R} is n . Since, according to (4.2), the functions $\partial y^\alpha / \partial x^i$ are continuous, it follows that the rank of $\|\partial y^\alpha / \partial x^i\|$ must be n at each point \mathcal{P}' of a sufficiently small neigh-

⁽¹²⁾ It is assumed that conditions (a) to (d) hold throughout this paper except that (4.2) is frequently replaced by a stronger inequality.

⁽¹³⁾ Similarly, we shall distinguish quantities and geometric objects defined relative to V_m and to \mathcal{R} from each other by means of the words "space" and "surface" respectively. For example, a *space tensor* (*surface tensor*) exhibits its tensor character with respect to transformations of the coordinates y^α (parameters x^i) and remains unchanged under parameter (coordinate) transformations. Space components of a tensor are denoted by indices having the range $1, 2, \dots, m$ (*space indices*); surface components by indices having the range $1, 2, \dots, n$ (*surface indices*). A tensor defined at a point of \mathcal{R} which has both space and surface indices may be represented uniquely in terms of two beins—an m -bein spanning V_m and an n -bein spanning \mathcal{R} .

neighborhood $\mathcal{U}(\mathcal{P})$ of the point \mathcal{P} . If $\{y'^\alpha\}$, $\{x'^i\}$ are allowable coordinate and parameter systems,

$$(4.4) \quad \frac{\partial y'^\alpha}{\partial x'^i} = \frac{\partial y'^\alpha}{\partial y^\beta} \cdot \frac{\partial y^\beta}{\partial x^i} \cdot \frac{\partial x^i}{\partial x'^i}, \quad \frac{\partial y^\alpha}{\partial x^i} = \frac{\partial y^\alpha}{\partial y'^\beta} \cdot \frac{\partial y'^\beta}{\partial x'^i} \cdot \frac{\partial x'^i}{\partial x^i}.$$

Hence it is clear that (d) holds independently of any allowable choice of coordinates and parameters. It also follows from (4.4) that $\partial y^\alpha / \partial x^i$ is a contravariant vector with respect to coordinate changes (*space transformations*) and a covariant vector with respect to parameter changes (*surface transformations*). We frequently write y_i^α for $\partial y^\alpha / \partial x^i$.

According to (4.4),

$$\partial y^\alpha / \partial x^1, \partial y^\alpha / \partial x^2, \dots, \partial y^\alpha / \partial x^n,$$

defined at each point $\mathcal{P}' \subset \mathcal{U}(\mathcal{P})$, represent n linearly independent contravariant vectors with respect to changes of the coordinates y^α . These vectors span the *tangent vector space* of \mathcal{R} at \mathcal{P}' . If λ^α and λ^i are space and surface components of any vector in the tangent vector space of \mathcal{R} at \mathcal{P}' ,

$$\lambda^\alpha = y^\alpha_i \lambda^i.$$

The totality of vectors ζ^α which obey the equations

$$y^\alpha_i \zeta^\alpha = 0$$

form a covariant linear vector space of dimension $m - n$ which is called the *normal vector space* of \mathcal{R} at \mathcal{P}' . Each vector in the normal vector space is called a *normal vector*.

The equations

$$(4.5) \quad g_{ij} = a_{\alpha\beta} y^\alpha_i y^\beta_j$$

define a covariant symmetric positive definite tensor of the second order with respect to parameter transformations. If λ^α , ξ^α are the space components of two contravariant tangent vectors and λ^i , ξ^i are the corresponding surface components of these vectors, then

$$(4.6) \quad a_{\alpha\beta} \lambda^\alpha \xi^\beta = g_{ij} \lambda^i \xi^j.$$

Since g_{ij} is not singular, the contravariant components g^{ij} are uniquely defined by means of the tensor equations

$$g_{ij} g^{jk} = \delta^k_i$$

where the δ 's are the Kronecker deltas. If λ_α , λ_i are the covariant components of λ^α , λ^i defined by $\lambda_\alpha = a_{\alpha\beta} \lambda^\beta$, $\lambda_i = g_{ij} \lambda^j$ then

$$(4.7) \quad \lambda_i = \lambda_\alpha y^\alpha_i.$$

As a consequence of (4.6), the lengths of and angles between contravariant

tangent vectors may be measured by means of their surface components and the tensor g_{ij} . Consequently the metric (2.1) of V_m induces a Riemannian metric, by means of the *surface metric tensor* g_{ij} , at all points of the region $\mathcal{U}(\mathcal{P})$. As follows from (b), (c) and (4.5), g_{ij} is of class C^{r-1} in the x^i . Hence the region $\mathcal{U}(\mathcal{P})$ is an n -dimensional Riemann space V_n of class C^r .

Since the results of this paper are local theorems which hold for a sufficiently small neighborhood of a point, we shall restrict ourselves to a portion of V_n which is a surface neighborhood $\mathcal{U}_1(\mathcal{P})$ of the point \mathcal{P} coverable by a single parameter system $\{x^i\}$. Furthermore, we choose $\mathcal{U}_1(\mathcal{P})$ so that it lies in a space neighborhood $\mathcal{U}_2(\mathcal{P})$ coverable by a single coordinate system $\{y^\alpha\}$. We shall refer to $\mathcal{U}_1(\mathcal{P})$ and $\mathcal{U}_2(\mathcal{P})$ as the Riemann spaces V_n and V_m respectively and use similar language in connection with the other Riemann spaces which appear in the paper.

Let π^α, π_α be the contravariant and covariant components of any space vector at a point of V_m , and $V^{(p)}$ a p -dimensional vector space at this point. Then ${}^*\pi^\alpha, {}^*\pi_\alpha$ is called the *projection of π^α, π_α in $V^{(p)}$* if (1) ${}^*\pi^\alpha, {}^*\pi_\alpha$ lies in $V^{(p)}$, (2) $\pi^\alpha - {}^*\pi^\alpha, \pi_\alpha - {}^*\pi_\alpha$ is orthogonal⁽¹⁴⁾ to the vector space $V^{(p)}$. A unique symmetric tensor $s^{\alpha\beta}$ always exists so that the projection ${}^*\pi^\alpha$ of any π_α in the fixed $V^{(p)}$ is given by

$${}^*\pi^\alpha = s^{\alpha\beta}\pi_\beta.$$

The tensor $s^{\alpha\beta}$ as well as the covariant tensor $s_{\alpha\beta} (= a_{\alpha\gamma}a_{\beta\delta}s^{\gamma\delta})$ and the mixed tensor $s^\alpha_\beta (= a_{\beta\delta}s^{\alpha\delta})$ is called the *projection tensor of the vector space $V^{(p)}$* . The vector π^α may be decomposed into its projection ${}^*\pi^\alpha$ in $V^{(p)}$ and another vector ζ^α orthogonal to $V^{(p)}$ so that

$$(4.8) \quad \pi^\alpha = {}^*\pi^\alpha + \zeta^\alpha.$$

A canonical representation of $s^{\alpha\beta}$ exists by means of a normalized p -bein (that is, a set of p mutually orthogonal unit vectors) which spans $V^{(p)}$. If $(1)\lambda^\alpha, (2)\lambda^\alpha, \dots, (p)\lambda^\alpha$ is this p -bein then

$$s^{\alpha\beta} = (1)\lambda^\alpha(1)\lambda^\beta + (2)\lambda^\alpha(2)\lambda^\beta + \dots + (p)\lambda^\alpha(p)\lambda^\beta.$$

In particular, if $(1)\lambda^\alpha, (2)\lambda^\alpha, \dots, (n)\lambda^\alpha$ is a normalized n -bein which spans the tangent vector space of V_n at a point and if $(1)\zeta^\alpha, (2)\zeta^\alpha, \dots, (m-n)\zeta^\alpha$ is a normalized $(m-n)$ -bein spanning the normal vector space of V_n at this point, then

$$(4.9) \quad \begin{aligned} a^{\alpha\beta} &= (1)\lambda^\alpha(1)\lambda^\beta + (2)\lambda^\alpha(2)\lambda^\beta + \dots + (n)\lambda^\alpha(n)\lambda^\beta + (1)\zeta^\alpha(1)\zeta^\beta + (2)\zeta^\alpha(2)\zeta^\beta \\ &\quad + \dots + (m-n)\zeta^\alpha(m-n)\zeta^\beta, \\ g^{ij} &= (1)\lambda^i(1)\lambda^j + (2)\lambda^i(2)\lambda^j + \dots + (n)\lambda^i(n)\lambda^j, \\ h^{\alpha\beta} &= (1)\zeta^\alpha(1)\zeta^\beta + (2)\zeta^\alpha(2)\zeta^\beta + \dots + (m-n)\zeta^\alpha(m-n)\zeta^\beta, \end{aligned}$$

⁽¹⁴⁾ A vector space $V^{(p_1)}$ is orthogonal to a vector space $V^{(p_2)}$ if each vector in $V^{(p_1)}$ is orthogonal to every vector in $V^{(p_2)}$.

where $h^{\alpha\beta}$ is the projection tensor of the normal vector space of V_n . The expression for the projection tensor $g^{\alpha\beta}$ of the tangent vector space at a point of V_n is

$$(4.10) \quad g^{\alpha\beta} = g^{ij}y^\alpha_i y^\beta_j.$$

We write

$$g^{\alpha\beta} = a_{\beta\delta}g^{\alpha\delta}, \quad g_{\alpha\beta} = a_{\alpha\gamma}a_{\beta\delta}g^{\gamma\delta}$$

and note that g^α_i defined as $g^\alpha_\beta y^\beta_i$ may be written as

$$(4.11) \quad g^\alpha_i = y^\alpha_i = \partial y^\alpha / \partial x^i.$$

If $h^{\alpha\beta}, h^\alpha_\beta, h_{\alpha\beta}$ represent the various components of the projection tensor of the normal vector space of V_n ,

$$(4.12) \quad h^{\alpha\beta} = a^{\alpha\beta} - g^{\alpha\beta}, \quad h^\alpha_\beta = \delta^\alpha_\beta - g^\alpha_\beta, \quad h_{\alpha\beta} = a_{\alpha\beta} - g_{\alpha\beta}.$$

If (4.8) represents the decomposition of a space vector π^α relative to the tangent vector space, then we have

$$\pi_\alpha g^\alpha_i = {}^*\pi_\alpha g^\alpha_i = {}^*\pi_i$$

where ${}^*\pi_i$ are the surface components of ${}^*\pi_\alpha$.

The projection of any tensor in the tangent vector space may be defined in a manner analogous to that used for the space vector π^α . We first give some preliminary definitions. A space index α of a tensor⁽¹⁵⁾ π^α, π_α is called a *tangent index* if

$$\pi^\alpha \zeta_\alpha = 0, \quad \pi_\alpha \zeta^\alpha = 0$$

for every normal vector $\zeta^\alpha, \zeta_\alpha$. The name *tangent index* is also applied to every surface index of the tensor. Any tangent space index may be raised or lowered by means of $g^{\alpha\beta}, g_{\alpha\beta}$ instead of $a^{\alpha\beta}, a_{\alpha\beta}$. A *tangent tensor* is a tensor all of whose indices are tangent indices. For example, the projection tensor $g_{\alpha\beta}$ is a tangent tensor. Any tangent tensor may be represented in the usual manner by an n -bein (having both space and surface components) spanning the tangent vector space. The surface components λ^{ki}_{ij} of any tangent tensor $\lambda^{\alpha\beta}_{ij}$ are obtained by a formula like that of equations (4.7) which holds for tangent vectors. The formula is

$$\lambda^{ki}_{ij} = \lambda^{\alpha\beta}_{ij} g^k_\alpha g^\beta_l$$

where g^k_i and g^k_α are defined by (4.11) and (4.14) respectively.

The mixed tensor ${}^*\pi^{\alpha\beta}_{ij}$ is the *projection of $\pi^{\alpha\beta}$ in the tangent vector space of V_n* if (1) ${}^*\pi^{\alpha\beta}_{ij}$ is a tangent tensor, (2) $\pi^{\alpha\beta}_{ij} - {}^*\pi^{\alpha\beta}_{ij}$ is not a tangent tensor unless it is a zero tensor. Then ${}^*\pi^{\alpha\beta}_{ij} = \pi^{\gamma\delta}_{ij} g^\alpha_\gamma g^\beta_\delta$. The surface components⁽¹⁶⁾

⁽¹⁵⁾ We have omitted all tensor indices except the index α to which reference is made.

⁽¹⁶⁾ When there is no danger of ambiguity, we write π^{ki} for ${}^*\pi^{ki}_{ij}$.

$*\pi^{ki}{}_{lj}$ of the projection $*\pi^{\alpha\beta}{}_{ij}$ are obtained by means of the equations

$$(4.13) \quad *\pi^{ki}{}_{lj} = \pi^{\alpha i}{}_{\beta j} g^k{}_{\alpha} g^{\beta l}.$$

We note some algebraic relations which were useful in the above development and are used in the sequel. These equations are either definitions or simple consequences of the definitions of the various tensors.

$$(4.14) \quad \begin{aligned} g^{\alpha i} &= g^{\alpha}{}_j g^{ij}, & g^i{}_{\alpha} &= a_{\alpha\beta} g^{\beta i}, & g_{\alpha i} &= a_{\alpha\beta} g^{\beta}{}_i, \\ a^{\alpha\gamma} a_{\beta\gamma} &= a^{\alpha}{}_{\beta} = \delta^{\alpha}{}_{\beta}, \\ g^{ik} g_{kj} &= g^{\alpha}{}_i g^i{}_{\alpha} = g^{\alpha i} g_{\alpha j} = g^i{}_j = \delta^i{}_j, \\ a^{\alpha\beta} g^{\beta}{}_i &= g^{\alpha}{}_{\beta} g^{\beta}{}_i = g^{\alpha}{}_j g^{ji} = g^{\alpha j} g_{ji} = g^{\alpha\beta} g_{\beta i} = g^{\alpha}{}_i, \\ h^{\alpha} g_{\alpha} &= h_{\alpha} g^{\alpha} = 0. \end{aligned}$$

In the last set of equations, g_{α} indicates any of the tensors $g^{\beta}{}_{\alpha}$, $g^i{}_{\alpha}$, $g_{\alpha\beta}$, $g_{\alpha i}$. There is a similar convention for g^{α} . Similarly h^{α} indicates either of the tensors $h^{\alpha\beta}$, $h^{\alpha}{}_{\beta}$. Finally, we remark that the operations of projection and addition (or subtraction) applied to tensors of the same valence are commutative. Whenever the operations of projection and differentiation are applied to a tensor, it is assumed that differentiation follows projection unless the contrary is explicitly indicated.

5. **Generalized covariant differentiation and the second fundamental form of V_n .** We replace (4.2) by the stronger inequality

$$(5.1) \quad r \geq 2.$$

Then, according to (4.1) and (5.1), the Christoffel symbols of the second kind for V_m and V_n exist and are continuous. These symbols are denoted by

$$\left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\} \quad \text{and} \quad \left\{ \begin{matrix} i \\ jk \end{matrix} \right\}$$

respectively. The *generalized covariant derivative (with respect to $a_{\alpha\beta}$ and g_{ij})* of a tensor of class C^1 defined on a surface neighborhood of V_n is

$$(5.2) \quad \begin{aligned} \pi^{\alpha i}{}_{\beta j, k} &= \frac{\partial \pi^{\alpha i}{}_{\beta j}}{\partial x^k} + \pi^{\delta i}{}_{\beta j} \left\{ \begin{matrix} \alpha \\ \delta\gamma \end{matrix} \right\} g^{\gamma k} - \pi^{\alpha i}{}_{\delta j} \left\{ \begin{matrix} \delta \\ \beta\gamma \end{matrix} \right\} g^{\gamma k} \\ &\quad + \pi^{\alpha l}{}_{\beta j} \left\{ \begin{matrix} i \\ lk \end{matrix} \right\} - \pi^{\alpha i}{}_{\beta l} \left\{ \begin{matrix} l \\ jk \end{matrix} \right\}. \end{aligned}$$

As a consequence of (5.1) and (4.11), the class of $g^{\alpha}{}_i$ is at least 1. Hence its covariant derivative exists and is defined by

$$(5.3) \quad g^{\alpha}{}_{i, j} = \frac{\partial g^{\alpha}{}_i}{\partial x^j} + \left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\} g^{\beta}{}_i g^{\gamma j} - \left\{ \begin{matrix} l \\ ij \end{matrix} \right\} g^{\alpha l}$$

whence $g^{\alpha_{i,j}} = g^{\alpha_{j,i}}$. We write $g^{\alpha_{ij}}$ for $g^{\alpha_{i,j}}$. The $g^{\alpha_{ij}}$, considered as space vectors, all lie in the normal vector space at any point \mathcal{P} of V_n , that is,

$$(5.4) \quad a_{\alpha\beta} g^{\alpha_{ij}} g^{\beta_{kl}} = 0.$$

If $m = n + 1$, the dimension of the normal vectors $g^{\alpha_{ij}}$ does not exceed unity so that $g^{\alpha_{ij}}$ may be written as

$$g^{\alpha_{ij}} = b_{ij} \zeta^{\alpha}$$

where b_{ij} is a second order symmetric surface tensor and ζ^{α} is the unit normal vector. The components of the tensor b_{ij} are the coefficients of the *second fundamental form* of V_n . If $m > n + 1$, the coefficients of the *second fundamental form* of V_n are the components of the tensor $b_{ij|kl}$ defined by

$$(5.5) \quad b_{ij|kl} = a_{\alpha\beta} g^{\alpha_{ij}} g^{\beta_{kl}}.$$

This tensor is equal to $b_{ij} b_{kl}$ if $m = n + 1$.

The *principal curvature vectors or directions* (directions of the lines of curvature) at a point \mathcal{P} of a hypersurface are the principal directions determined by b_{ij} ; that is, they are the unit vectors ${}_{(h)}\lambda^i$ which satisfy

$$(5.6) \quad (b_{ij} - {}_{(h)}b g_{ij}) {}_{(h)}\lambda^i = 0$$

where the scalar ${}_{(h)}b$ is a *principal normal curvature* of V_n at \mathcal{P} , being determined as a root of the determinant equation

$$(5.7) \quad |b_{ij} - {}_{(h)}b g_{ij}| = 0.$$

Since g_{ij} is definite⁽¹⁷⁾, there exists a normalized n -bein of principal curvature directions. According to (5.6), the value of ${}_{(h)}b$ is given by

$$(5.8) \quad {}_{(h)}b = b_{ij} {}_{(h)}\lambda^i {}_{(h)}\lambda^j.$$

In the case of a subspace with $m > n + 1$, there is no unique set of principal curvatures and principal curvature directions. However, there exists an n -bein of *principal curvature vectors* and n *principal normal curvatures* at each point \mathcal{P} corresponding to any direction ζ^{α} in the normal vector space of V_n . These are determined by equations analogous to (5.6), (5.7) and (5.8), with b_{ij} replaced by $g^{\alpha_{ij}} \zeta_{\alpha}$. If every direction at \mathcal{P} is a principal curvature direction, the point \mathcal{P} is called *umbilical*.

The *mean curvature normal* μ^{α} is defined at any point \mathcal{P} of V_n as

$$(5.9) \quad \mu^{\alpha} = n^{-1} g^{\alpha_{ij}} g^{ij}.$$

The length of this vector is called the *mean curvature* μ . Hence, according to (5.5) and (5.9),

$$(5.10) \quad \mu^2 = n^{-2} b_{ij|kl} g^{ij} g^{kl}.$$

⁽¹⁷⁾ See [4, pp. 107–113] for the theory of the principal directions determined by a symmetric covariant tensor of the second order. The present discussion is based upon this theory.

For a hypersurface, (5.9) and (5.10) may be written as

$$(5.11) \quad \mu^\alpha = \mu \zeta^\alpha, \quad \mu = n^{-1} b_{ij} g^{ij}.$$

If we make use of the canonical representation of g_{ij} given by (4.9) and also (5.8) and (5.11), we obtain

$$(5.12) \quad \mu = n^{-1} \sum_h ({}_h) b.$$

An analogous formula for μ obtains for any subspace in terms of the principal normal curvatures of V_n corresponding to the direction of μ^α .

If (5.1) is strengthened still further by the inequality

$$(5.13) \quad r \geq 3,$$

the Riemann curvature tensors $\rho_{\alpha\beta\gamma\delta}$ of V_m and κ_{ijkl} of V_n exist and are of class C^{r-3} and C^{r-3} respectively. The tensors $\rho^\alpha{}_{\beta\gamma\delta}$ and $\kappa^i{}_{jkl}$ are defined by the equations

$$(5.14) \quad \begin{aligned} \rho^\alpha{}_{\beta\gamma\delta} &= \frac{\partial}{\partial y^\gamma} \left\{ \begin{matrix} \alpha \\ \beta\delta \end{matrix} \right\} - \frac{\partial}{\partial y^\delta} \left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\} + \left\{ \begin{matrix} \epsilon \\ \beta\delta \end{matrix} \right\} \left\{ \begin{matrix} \alpha \\ \epsilon\gamma \end{matrix} \right\} - \left\{ \begin{matrix} \epsilon \\ \beta\gamma \end{matrix} \right\} \left\{ \begin{matrix} \alpha \\ \epsilon\delta \end{matrix} \right\}, \\ \kappa^i{}_{jkl} &= \frac{\partial}{\partial x^k} \left\{ \begin{matrix} i \\ jl \end{matrix} \right\} - \frac{\partial}{\partial x^l} \left\{ \begin{matrix} i \\ jk \end{matrix} \right\} + \left\{ \begin{matrix} h \\ jl \end{matrix} \right\} \left\{ \begin{matrix} i \\ hk \end{matrix} \right\} - \left\{ \begin{matrix} h \\ jk \end{matrix} \right\} \left\{ \begin{matrix} i \\ hl \end{matrix} \right\}. \end{aligned}$$

It is an immediate consequence of these definitions that $\rho_{\alpha\beta\gamma\delta}$ satisfies the identities

$$(5.15) \quad \rho_{\alpha\beta\gamma\delta} = -\rho_{\beta\alpha\gamma\delta} = -\rho_{\alpha\beta\delta\gamma} = \rho_{\gamma\delta\alpha\beta}, \quad \rho_{\alpha(\beta\gamma\delta)^+} = 0$$

and that κ_{ijkl} obeys a similar set of equations. In writing these equations we have represented the cyclic operation by a plus sign and (below) the alternation operation by a minus sign. The Ricci tensor $\rho_{\beta\gamma}$ and the invariant curvature ρ of V_m are defined by $\rho_{\beta\gamma} = \rho_{\alpha\beta\gamma\delta} a^{\alpha\delta}$, $\rho = \rho_{\beta\gamma} a^{\beta\gamma}$ with analogous definitions for κ_{jk} and κ . Under these conditions, the Gauss equations

$$(5.16) \quad b_{i(k|l)-j} = \kappa_{ijkl} - \rho_{ijkl}$$

are satisfied where, in accordance with §4, we have written

$$\rho_{\alpha\beta\gamma\delta} g^\alpha{}_i g^\beta{}_j g^\gamma{}_k g^\delta{}_l = \rho_{ijkl}.$$

II. CONFORMAL TENSOR ALGEBRA

6. The relative conformal curvature of V_n . Let \bar{V}_m be any other Riemann space belonging to (2.8) and let $\bar{\mathcal{R}}$ be the subset of \bar{V}_m which correspond to \mathcal{R} under the conformal map (2.4). We suppose that the parameters \bar{x}^i at points of $\bar{\mathcal{R}}$ are related to the parameters x^i at the corresponding points of \mathcal{R} by transformations of class C^r . Then the assumptions of §2 concerning the classes of V_m and \bar{V}_m and of the conformal mapping between them together with the assumptions (a) to (d) of §4 about \mathcal{R} guarantee that these latter conditions

also hold true for $\overline{\mathcal{R}}$. Also, according to the discussion of §2, it is possible to choose allowable parameter systems $\{x^i\}$ and $\{\bar{x}^i\}$ in the parameter neighborhoods of \mathcal{R} and $\overline{\mathcal{R}}$ respectively so that the transformation of \mathcal{R} on $\overline{\mathcal{R}}$ is given by $\bar{x}^i = x^i$. Unless the contrary is stated, we suppose that this is done throughout the remainder of the paper. Then the equations of $\overline{\mathcal{R}}$ corresponding to (4.3) are

$$\bar{y}^\alpha = \bar{y}^\alpha(\bar{x}^1, \bar{x}^2, \dots, \bar{x}^n),$$

where $y^\alpha(x^i)$ and $\bar{y}^\alpha(\bar{x}^i)$ are the same functions of x^i and \bar{x}^i respectively.

According to the discussion of §4, the region of \mathcal{R} which corresponds to V_n is also a Riemann space which we denote by \overline{V}_n . The remarks of the previous paragraph show that

$$(6.1) \quad \bar{g}^\alpha_i = g^\alpha_i$$

where we have written $\bar{g}^\alpha_i = \partial \bar{y}^\alpha / \partial \bar{x}^i$. Consequently the tangent vector space of V_n is conformally invariant. Since orthogonality is a conformal property, the normal vector spaces of V_n and \overline{V}_n at corresponding points are also in conformal correspondence. If the metric tensor of \overline{V}_n is denoted by \bar{g}_{ij} , \bar{g}^{ij} , it follows from equations analogous to (4.5) and from (2.6) and (6.1) that

$$(6.2) \quad \bar{g}_{ij} = e^{2\sigma} g_{ij}, \quad \bar{g}^{ij} = e^{-2\sigma} g^{ij}.$$

Thus the conformal transformation (2.4) induces a conformal mapping on the respective subspaces of V_m and \overline{V}_m .

Under the assumption (5.1), the existence and continuity of the Christoffel symbols of the second kind of \overline{V}_m and \overline{V}_n are assured. We denote these symbols by

$$\left\{ \begin{matrix} \bar{\alpha} \\ \beta\gamma \end{matrix} \right\} \quad \text{and} \quad \left\{ \begin{matrix} \bar{i} \\ jk \end{matrix} \right\}$$

respectively. As a consequence of (2.6) and (6.2), we have

$$(6.3) \quad \left\{ \begin{matrix} \bar{\alpha} \\ \beta\gamma \end{matrix} \right\} = \left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\} + a^{\alpha\beta\sigma,\gamma} + a^{\alpha\gamma\sigma,\beta} - a_{\beta\gamma} a^{\alpha\delta\sigma,\delta},$$

$$\left\{ \begin{matrix} \bar{i} \\ jk \end{matrix} \right\} = \left\{ \begin{matrix} i \\ jk \end{matrix} \right\} + g^i_{j\sigma,k} + g^i_{k\sigma,j} - g_{jk} g^{il\sigma,l}.$$

We denote covariant differentiation with respect to $\bar{a}_{\alpha\beta}$, \bar{g}_{ij} by means of a semicolon. Then

$$(6.4) \quad \bar{g}^\alpha_{i;j} = \frac{\partial}{\partial \bar{x}^j} \bar{g}^\alpha_i + \left\{ \begin{matrix} \bar{\alpha} \\ \beta\gamma \end{matrix} \right\} \bar{g}^\beta_i \bar{g}^\gamma_j - \left\{ \begin{matrix} \bar{l} \\ ij \end{matrix} \right\} \bar{g}^\alpha_l.$$

We write $\bar{g}^\alpha_{i;j}$ as $\bar{g}^\alpha_{i;j}$. Also,

$$(6.5) \quad \sigma_{,i} = \sigma_{,a} g^a_i.$$

If we simplify (6.4) by means of (4.5), (4.14), (5.3), (6.1), (6.3) and (6.5), we obtain

$$\bar{g}^{\alpha}_{ij} = g^{\alpha}_{ij} - g_{ij}(a^{\alpha\beta}\sigma_{,\beta} - g^{kl}\sigma_{,k}g^{\alpha}_l).$$

But according to (4.10), (4.12) and (6.5), these last equations may be written as

$$(6.6) \quad \bar{g}^{\alpha}_{ij} = g^{\alpha}_{ij} - g_{ij}h^{\alpha\beta}\sigma_{,\beta}.$$

We denote the mean curvature normal of \bar{V}_n by $\bar{\mu}^{\alpha}$. Since

$$\bar{\mu}^{\alpha} = n^{-1}\bar{g}^{\alpha}_{ij}\bar{g}^{ij},$$

we find from these equations and (5.9), (6.2) and (6.6) that

$$(6.7) \quad e^{2\sigma}\bar{\mu}^{\alpha} = \mu^{\alpha} - h^{\alpha\beta}\sigma_{,\beta}.$$

From these equations and $\bar{\mu}_{\alpha} = \bar{a}_{\alpha\beta}\bar{\mu}^{\beta}$, $\mu_{\alpha} = a_{\alpha\beta}\mu^{\beta}$, we obtain

$$(6.8) \quad \bar{\mu}_{\alpha} = \mu_{\alpha} - h^{\beta}_{\alpha}\sigma_{,\beta}.$$

As result of (6.2) and (6.7), equations (6.6) become

$$(6.9) \quad \bar{G}^{\alpha}_{ij} = G^{\alpha}_{ij},$$

where we have written

$$(6.10) \quad G^{\alpha}_{ij} = g^{\alpha}_{ij} - g_{ij}\mu^{\alpha}$$

and analogous equations for \bar{G}^{α}_{ij} . Consequently the mixed tensor G^{α}_{ij} of class C^{r-2} is a conformal tensor and the contravariant vector space which it spans remains unchanged by conformal transformations. According to (5.4) and (5.9), this vector space is normal to the tangent vector space of V_n .

If $n = 1$, V_n is a curve. In this case the surface metric tensor has one component which may be written as $g_{11} = \lambda_1\lambda_1$. Then, from (5.9) and (6.10),

$$G^{\alpha}_{11} = g^{\alpha}_{11} - \lambda_1\lambda_1g^{\alpha}_{11}\lambda^1\lambda^1$$

so that $G^{\alpha}_{ij} \equiv 0$ for a curve. If $G^{\alpha}_{ij} = 0$ at a point \mathcal{P} of V_n and n exceeds unity, it follows from (6.10) that

$$(6.11) \quad g^{\alpha}_{ij} = g_{ij}\mu^{\alpha}.$$

In accordance with the analogue of (5.6) for any subspace, every direction at \mathcal{P} is a principal curvature direction so that \mathcal{P} is an umbilical point of V_n . Conversely, if \mathcal{P} is an umbilical point, then (6.11) holds so that $G^{\alpha}_{ij} = 0$ at \mathcal{P} .

The scalar quantity Λ defined, except for a choice of sign, by

$$(6.12) \quad \Lambda^2 = n^{-1}a_{\alpha\beta}g^{il}g^{jk}G^{\alpha}_{ij}G^{\beta}_{kl}$$

is called the *relative conformal curvature* of V_n if $n > 1$. If $n = 1$, Λ is identically zero. As follows from (2.6), (6.2) and (6.9), it is a relative conformal scalar of class C^{r-2} obeying the equation

$$(6.13) \quad \bar{\Lambda} = e^{-\sigma}\Lambda.$$

The reality of Λ is guaranteed by showing that Λ^2 , defined by (6.12), is non-negative. To prove this statement, we choose coordinates y^α and parameters x^i so that $a_{\alpha\beta} = \delta^{\alpha\beta}$, $g_{ij} = \delta^i_j$ at the point \mathcal{P} . Then, from (6.12), we have at \mathcal{P} that

$$\Lambda^2 = n^{-1} \sum_{\alpha} g^{i\ell} g^{jk} G^{\alpha}_{ij} G^{\alpha}_{k\ell} = n^{-1} \sum_{\alpha} \sum_i \sum_j (G^{\alpha}_{ij})^2 \geq 0.$$

The equality sign is valid if and only if $G^{\alpha}_{ij} = 0$. We summarize these results in the following theorem.

THEOREM 6.1. *The relative conformal curvature Λ of a subspace V_n in V_m vanishes at a point of V_n if and only if the conformal tensor G^{α}_{ij} is zero at the point. If $n=1$, G^{α}_{ij} vanishes identically. If $n>1$, G^{α}_{ij} equals zero at a point of V_n if and only if this point is umbilical in V_m .*

Throughout the remainder of the paper, except where the contrary is explicitly stated, we shall assume that ⁽¹⁸⁾ $n>1$ (so that $m>2$) and restrict ourselves to subspaces V_n (more accurately: regions of V_n) which do not contain any umbilical points. Since $\Lambda \neq 0$ in V_n , we suppose that an initial choice of sign for Λ is made so that $\Lambda > 0$ in V_n .

The principal directions determined by the surface tensor $G^{\alpha}_{ij} \zeta_\alpha$ where ζ_α is a vector belonging to the normal vector space of V_n are, from (6.10), the principal directions determined by $g^{\alpha}_{ij} \zeta_\alpha$. Consequently these directions are the principal curvature directions of V_n corresponding to ζ_α . Since both G^{α}_{ij} and the orthogonality of ζ_α to V_n remain unchanged by conformal transformations of V_m , this proves the conformal invariance of the principal curvature vectors. In particular, we note the following theorems of Schouten and Struik [13, pp. 211–212].

THEOREM 6.2. *The lines of curvature of a hypersurface V_n ($n>1$) in V_{n+1} are invariant under conformal transformations of V_{n+1} .*

THEOREM 6.3. *The umbilical points of a subspace V_n ($n>1$) in V_m remain umbilical under conformal transformations of V_m .*

Digression. The remainder of this section is devoted to the derivation of some relations between Λ and various metric geometric objects of V_n . The relative conformal curvature may be expressed in terms of the coefficients of the first and second fundamental forms of V_n . If we make use of equations (4.14), (5.5), (5.9) and (6.10) then (6.12) becomes

$$(6.14) \quad \Lambda^2 = n^{-1} b_{ij|kl} (g^{i\ell} g^{jk} - n^{-1} g^{ij} g^{kl}).$$

If V_n is a hypersurface, a formula for Λ in terms of the principal normal

⁽¹⁸⁾ The case $n=1$ (curve theory) is considered in §34.

curvatures of V_n may be found. In this case, by the use of the canonical representation of g^{ij} given by (4.9) and also (5.8), we find that

$$b_{i|k}g^{ik} = \sum_i (i)b^2.$$

If we take account of this equation as well as of (5.10) and (5.12), equation (6.14) becomes

$$\begin{aligned} \Lambda^2 &= n^{-1} \left[\sum_i (i)b^2 - n^{-1} \left(\sum_i (i)b \right)^2 \right] = n^{-1} \sum_i \left[(i)b^2 - n^{-1} (i)b \sum_j (j)b \right] \\ &= n^{-1} \sum_i (i)b [(i)b - \mu]. \end{aligned}$$

Now from (5.12),

$$\sum_i \mu [(i)b - \mu] = \mu \sum_i [(i)b - \mu] = 0.$$

Hence the above equation remains unchanged if $n^{-1} \sum_i \mu [(i)b - \mu]$ is subtracted from the right member. This gives⁽¹⁹⁾

$$(6.15) \quad \Lambda^2 = n^{-1} \sum_i (i)b - \mu)^2.$$

If $m > n + 1$, a similar result may be obtained for any subspace V_n . Let $(1)\zeta^\alpha, (2)\zeta^\alpha, \dots, (m-n)\zeta^\alpha$ be the normalized $(m-n)$ -bein of (4.9). We denote the n principal normal curvatures of V_n corresponding to $(1)\zeta^\alpha$ by $(1,1)b_1, (1,2)b_2, \dots, (1,n)b_n$ and write $(1)\mu = n^{-1} \sum_i (1,i)b_i$ and use an analogous notation with respect to the other ζ^α . In a manner analogous to that used in the derivation of (6.15), we find that

$$(6.16) \quad \begin{aligned} \Lambda^2 &= n^{-1} \left\{ \sum_i (1,i)b_i - (1)\mu \right\}^2 + \sum_i (2,i)b_i - (2)\mu \right\}^2 + \dots \\ &\quad + \sum_i (m-n,i)b_i - (m-n)\mu \right\}^2 \left. \right\}. \end{aligned}$$

7. The conformal measure tensors. In this section, we define the fundamental conformal geometric objects which have roles in the conformal theory analogous to those of the metric tensors $a_{\alpha\beta}, g_{ij}$ in classical and Riemannian geometry. If (5.1) is obeyed, the relative conformal curvature Λ exists. Since $\Lambda > 0$, we may write it as

$$(7.1) \quad \Lambda = e^\phi.$$

We call ϕ the *gauge function* of V_n . According to (2.6), (6.2), (6.13) and (7.1),

⁽¹⁹⁾ An alternative form of equation (6.15) is $\Lambda^2 = n^{-2} \sum_i \sum_j (i)b - (j)b)^2$. The quantity $(i)b - (j)b$ is a relative conformal scalar having the transformation law $[(i)b - (j)b] = e^{-\sigma} [(i)b - (j)b]$. This fact and the definition of Λ given in this footnote provide another proof of (6.13). Analogous remarks apply to the case of a general subspace V_n and are based upon equation (6.16) instead of (6.15).

the tensors $A_{\alpha\beta}$, G_{ij} defined at points of V_n by

$$(7.2) \quad A_{\alpha\beta} = e^{2\phi} a_{\alpha\beta},$$

$$(7.3) \quad G_{ij} = e^{2\phi} g_{ij}$$

are positive definite tensors of class C^{r-2} and remain unchanged by conformal transformations of V_m , that is,

$$\bar{A}_{\alpha\beta} = A_{\alpha\beta}, \quad \bar{G}_{ij} = G_{ij}.$$

We call $A_{\alpha\beta}$ the *conformal (space)⁽²⁰⁾ measure tensor of V_m* and G_{ij} the *conformal (surface) measure tensor of V_n* . Where there is no ambiguity, we shall refer to each of these tensors as a *measure tensor*.

The contravariant components of these measure tensors are defined by

$$(7.4) \quad A^{\alpha\beta} A_{\beta\gamma} = \delta^\alpha_\gamma, \quad G^{ij} G_{jk} = \delta^i_k.$$

It is clear that these tensors satisfy the equations

$$(7.5) \quad A^{\alpha\beta} = e^{-2\phi} a^{\alpha\beta},$$

$$(7.6) \quad G^{ij} = e^{-2\phi} g^{ij}.$$

If $T^{\alpha\beta}_j$ is a conformal tensor and any of its indices are raised or lowered by means of $A^{\alpha\beta}$, $A_{\alpha\beta}$, G^{ij} , G_{ij} , it is clear that the new tensor retains the conformal character of the original one. Consequently the raising or lowering of the indices of any conformal tensor in the sequel is accomplished by means of these measure tensors unless the contrary is stated. On the other hand, the raising or lowering of the indices of any non-conformal (metric) tensor is done by means of the metric tensors $a^{\alpha\beta}$, $a_{\alpha\beta}$, g^{ij} , g_{ij} unless the contrary is indicated. As a result of (4.5), (7.2) and (7.3), the measure tensors are related by the equations

$$(7.7) \quad G_{ij} = A_{\alpha\beta} G^{\alpha}_i G^{\beta}_j.$$

In these equations, we have written G^{α}_i for $\partial y^\alpha / \partial x^i$ in virtue of the conformal invariance of the latter tensor which is stated in (6.1).

A tensor algebra may be based upon these measure tensors, which is analogous in every respect to the classical algebra developed in §4 which is founded upon $a_{\alpha\beta}$, g_{ij} . With reference to conformal tensors similar to those defined in §4, every equation of §4 has a precise analogue in the new algebra. In particular, the *conformal length T* of any conformal space vector T^α is defined by

$$(7.8) \quad T^2 = A_{\alpha\beta} T^\alpha T^\beta.$$

(20) It should be noted that the space measure tensor $A_{\alpha\beta}$ is defined relative to the sub-space V_n . This is true of almost all the space conformal objects which appear in this paper and the definitions of these objects should be understood as containing the phrase "relative to V_n ."

If $T = 1$, T^α is called a *unit conformal vector*. If T^α is a conformal tangent vector L^α , its space and surface components obey the equations

$$(7.9) \quad L^\alpha = L^i G^\alpha_i, \quad L_i = L_\alpha G^\alpha_i$$

and its conformal length may be measured with equal validity by either $A_{\alpha\beta}$ or G_{ij} . The magnitude of the angle between two vectors is obviously the same, regardless of whether the angle is measured by means of the metric tensors $a_{\alpha\beta}$, g_{ij} or the conformal measure tensors $A_{\alpha\beta}$, G_{ij} . This is a natural phenomenon, since the magnitude of an angle (measured by the Riemannian metric) is unchanged by conformal transformations.

For the tangent vector space of V_n , the projection tensor $G^{\alpha\beta}$ relative to the conformal length measure stated in (7.8) is defined by

$$(7.10) \quad G^{\alpha\beta} = G^{ij} G^\alpha_i G^\beta_j.$$

The various equations of §4 are true if conformal unit vectors are substituted for the metric unit vectors and if the replacements $a \rightarrow A$, $g \rightarrow G$, $\pi \rightarrow T$, $h \rightarrow H$ are made in these equations. In the remainder of the paper, we frequently use the conformal analogue of (4.14) and refer to it simply as equations (4.14). Finally, we note that the important algebraic identities

$$(7.11) \quad G^\alpha_i G^{ij} = 0,$$

$$(7.12) \quad A_{\alpha\beta} G^\alpha_i G^\beta_k G^{ik} G^{jl} = n$$

are an easy consequence of (5.9), (6.10), (6.12), (7.1), (7.2), (7.4) and (7.6).

III. CONFORMAL TENSOR ANALYSIS

8. Conformal differentiation. In order to define a covariant differentiation process in conformal geometry, we first replace (5.1) by (5.13). This guarantees the existence of the Christoffel symbols. It is natural to require this differentiation process to satisfy the following conditions:

(a) If $T^{\alpha i}_{\beta j}$ is a tensor of class C^1 defined on a surface neighborhood of V_n , then $T^{\alpha i}_{\beta j;k}$ may be written as⁽²¹⁾

$$(8.1) \quad T^{\alpha i}_{\beta j;k} = \frac{\partial}{\partial x^k} T^{\alpha i}_{\beta j} + T^{\delta i}_{\beta j} \Gamma^{\alpha}_{\delta\gamma} G^\gamma_k - T^{\alpha i}_{\delta j} \Gamma^{\delta}_{\beta\gamma} G^\gamma_k + T^{\alpha i}_{\beta j} \Gamma^i_{ik} - T^{\alpha i}_{\beta l} \Gamma^l_{jk}.$$

(b) The coefficients $\Gamma^{\alpha}_{\beta\gamma}$ and Γ^i_{jk} , defined⁽²²⁾ on V_n , are symmetric in the two lower indices.

⁽²¹⁾ The form of equations (8.1) is suggested by (5.2). They need not be assumed for a general tensor $T^{\alpha i}_{\beta j}$ but may be developed axiomatically from the assumed laws for a scalar and a contravariant vector. (If T is a scalar, then (8.1) becomes $T_{;k} = \partial T / \partial x^k$.) The details of this development are analogous to those of a similar proof in our paper on the conformal theory of curves [8, pp. 447-449].

⁽²²⁾ The definition of $\Gamma^{\alpha}_{\beta\gamma}$ and Γ^i_{jk} is implicit in conditions (a) to (e). The explicit definition of these coefficients appears in equations (8.5) and (8.11).

(c) $T^{\alpha^i_{\beta j; k}}$ is a tensor.

(d) If $T^{\alpha^i_{\beta j}}$ is a conformal tensor, $T^{\alpha^i_{\beta j; k}}$ is also a conformal tensor; that is, $\bar{T}^{\alpha^i_{\beta j}} = T^{\alpha^i_{\beta j}}$ implies $\bar{T}^{\alpha^i_{\beta j; k}} = T^{\alpha^i_{\beta j; k}}$.

(e) The measure tensors behave like constants with reference to the differentiation process; that is,

$$(8.2) \quad A_{\alpha\beta; k} = A^{\alpha\beta; k} = A^\alpha_{\beta; k} = 0,$$

$$(8.3) \quad G_{ij; k} = G^{ij; k} = G^i_{j; k} = 0.$$

The quantities $\Gamma^{\alpha_{\beta\gamma}}$ and Γ^i_{jk} are the conformal analogues of the Christoffel symbols of the second kind

$$\left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\} \quad \text{and} \quad \left\{ \begin{matrix} i \\ jk \end{matrix} \right\}$$

respectively. It follows directly from (a) and (c) that $\Gamma^{\alpha_{\beta\gamma}}$ and Γ^i_{jk} are coefficients of connection⁽²³⁾ and consequently differ from the Christoffel symbols

$$\left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\} \quad \text{and} \quad \left\{ \begin{matrix} i \\ jk \end{matrix} \right\}$$

respectively by quantities which are tensors. The converse is also true. As a result of (a) and (d), it is readily seen that $\Gamma^{\alpha_{\beta\gamma}}$ and Γ^i_{jk} must be conformal geometric objects which remain unchanged under conformal transformations of V_m ; that is,

$$(8.4) \quad \bar{\Gamma}^{\alpha_{\beta\gamma}} = \Gamma^{\alpha_{\beta\gamma}}, \quad \bar{\Gamma}^i_{jk} = \Gamma^i_{jk}.$$

Condition (b) as applied to Γ^i_{jk} plus the first of equations (8.3) readily determines Γ^i_{jk} as the Christoffel symbols of the second kind formed from G_{ij} . The conformal invariance of these Christoffel symbols may now be proved independently of the above discussion since G_{ij} is a conformal tensor. According to (7.3) and equations similar to (6.3),

$$(8.5) \quad \Gamma^i_{jk} = \left\{ \begin{matrix} i \\ jk \end{matrix} \right\} + g^i_j \phi_{,k} + g^i_k \phi_{,j} - g_{jk} g^{il} \phi_{,l}.$$

The $\Gamma^{\alpha_{\beta\gamma}}$ cannot be similarly determined as the Christoffel symbols formed from $A_{\alpha\beta}$ since $A_{\alpha\beta}$ is only defined at points of V_n and consequently $\partial A_{\alpha\beta} / \partial y^\gamma$ does not exist. Condition (b) for $\Gamma^{\alpha_{\beta\gamma}}$ and the first of equations (8.2) do not determine $\Gamma^{\alpha_{\beta\gamma}}$ uniquely. If $\Gamma^{\alpha_{\beta\gamma}}$ is chosen in the form

$$(8.6) \quad \Gamma^{\alpha_{\beta\gamma}} = \left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\} + a^\alpha_{\beta\pi} \pi_\gamma + a^\alpha_{\gamma\pi} \pi_\beta - a_{\beta\gamma} a^{\alpha\delta} \pi_\delta$$

then these conditions are satisfied if $\pi_\gamma g^\gamma_i = \phi_{,i}$.

⁽²³⁾ For the definition and properties of coefficients of connection, see [5, pp. 3-6].

We digress somewhat in order to find a value for π_α in this formula which makes (8.6) a conformal geometric object. Equations (6.13) and (7.1) are equivalent to

$$(8.7) \quad \sigma = \phi - \bar{\phi}.$$

From this equation, we obtain $\sigma_{,i} = \bar{\phi}_{,i} - \phi_{,i}$. Since $\sigma_\beta g^\beta_\alpha = \sigma_\beta g^\beta_i g^i_\alpha = \sigma_i g^i_\alpha$, the above equation leads to

$$\sigma_\beta g^\beta_\alpha = \bar{\phi}_\alpha - \phi_\alpha,$$

where $\phi_\alpha, \bar{\phi}_\alpha$ are the space components of $\phi_{,i}, \bar{\phi}_{,i}$ so that

$$(8.8) \quad \phi_\alpha = \phi_{,i} g^i_\alpha.$$

Now

$$\sigma_{,\alpha} = \sigma_{,\beta} a^\beta_\alpha = \sigma_{,\beta} g^\beta_\alpha + \sigma_{,\beta} h^\beta_\alpha.$$

The above results and (6.8) permit us to write these last equations in the form

$$(8.9) \quad \sigma_{,\alpha} = \eta_\alpha - \bar{\eta}_\alpha$$

where η_α is the *gauge vector* defined by

$$(8.10) \quad \eta_\alpha = \phi_\alpha + \mu_\alpha.$$

Use of (8.8), (8.9) and (8.10) shows that (6.3) may be written in the invarientive form

$$\left\{ \begin{matrix} \bar{\alpha} \\ \beta\gamma \end{matrix} \right\} + \bar{a}^\alpha_\beta \bar{\eta}_{,\gamma} + \bar{a}^\alpha_\gamma \bar{\eta}_{,\beta} - \bar{a}_{\beta\gamma} \bar{a}^{\alpha\delta} \bar{\eta}_{,\delta} = \left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\} + a^\alpha_\beta \eta_{,\gamma} + a^\alpha_\gamma \eta_{,\beta} - a_{\beta\gamma} a^{\alpha\delta} \eta_{,\delta},$$

$$\left\{ \begin{matrix} \bar{i} \\ jk \end{matrix} \right\} + \bar{g}^i_j \bar{\phi}_{,k} + \bar{g}^i_k \bar{\phi}_{,j} - \bar{g}_{jk} \bar{g}^{il} \bar{\phi}_{,l} = \left\{ \begin{matrix} i \\ jk \end{matrix} \right\} + g^i_j \phi_{,k} + g^i_k \phi_{,j} - g_{jk} g^{il} \phi_{,l}.$$

The second of these equations establishes the conformal invariance of the Γ^i_{jk} defined by (8.5) in a new way. The first equations suggest that π_α in (8.6) be defined as η_α so that $\Gamma^\alpha_{\beta\gamma}$ is defined by the equations

$$(8.11) \quad \Gamma^\alpha_{\beta\gamma} = \left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\} + a^\alpha_\beta \eta_{,\gamma} + a^\alpha_\gamma \eta_{,\beta} - a_{\beta\gamma} a^{\alpha\delta} \eta_{,\delta}.$$

The definitions (8.5) and (8.11) show that Γ^i_{jk} and $\Gamma^\alpha_{\beta\gamma}$ are of class C^{r-3} in the x^i .

The quantities Γ^i_{jk} defined by (8.5) are called the *conformal (surface) coefficients of connection* and the quantities $\Gamma^\alpha_{\beta\gamma}$ defined by (8.11) are called the *conformal (space) coefficients of connection*. The derivative defined by (8.1) is called the *conformal (surface) derivative of $T^{\alpha\beta}_j$* . It is clear that *all the properties (a) through (e) as well as (8.4) are satisfied and that conformal differentiation of the sum, difference, inner and outer product of tensors obeys the same rules as*

ordinary differentiation. However, we note that both Γ^i_{jk} and $\Gamma^\alpha_{\beta\gamma}$ are defined at points of V_n only and consequently the conformal derivative does not have a meaning throughout the imbedding space V_m but only on the subspace V_n . We also observe that the conformal coefficients of connection are defined relative to V_n . This means that the conformal differentiation process is dependent not only on the metric of V_m but also on the subspace V_n (or, more precisely, on the third order differential element of V_n). This definition of differentiation with respect to a subspace is somewhat analogous to the similar definition of parallel displacement of vectors in a general Riemann space with respect to a curve.

If T^α_β is a conformal tensor of class C^1 defined on a space neighborhood of V_m which includes a surface neighborhood of V_n then $T^\alpha_{\beta;\gamma}$ may be defined at points of the surface neighborhood as

$$(8.12) \quad T^\alpha_{\beta;\gamma} = \frac{\partial}{\partial y^\gamma} T^\alpha_\beta + T^\delta_\beta \Gamma^\alpha_{\delta\gamma} - T^\alpha_\delta \Gamma^\delta_{\beta\gamma}.$$

It is immediate that this *conformal (space) derivative* $T^\alpha_{\beta;\gamma}$ of T^α_β enjoys all the properties of the conformal surface derivative $T^\alpha_{\beta;k}$. It is a simple consequence of (8.1) and (8.12) that these derivatives are related by means of the equations

$$(8.13) \quad T^\alpha_{\beta;k} = T^\alpha_{\beta;\gamma} G^\gamma_k.$$

According to (8.1),

$$G^\alpha_{;i} = \frac{\partial^2 y^\alpha}{\partial x^i \partial x^j} + \Gamma^\alpha_{\beta\gamma} g^\beta_{;i} g^\gamma_{;j} - \Gamma^h_{ij} g^\alpha_{;h}$$

since $G^\alpha_{;i} = g^\alpha_{;i}$. If these equations are simplified by means of (4.5), (4.14), (5.3), (8.5) and (8.11), we obtain

$$(8.14) \quad G^\alpha_{;i} = g^\alpha_{;i} + g^\alpha_{;i}(\eta_\gamma g^\gamma_{;j} - \phi_{,i}) + g^\alpha_{;i}(\eta_\beta g^\beta_{;i} - \phi_{,i}) - g_{ij}(a^{\alpha\delta} \eta_\delta - g^{\alpha l} \phi_{,l}).$$

Since μ_α is orthogonal to $g^\alpha_{;i}$, it follows from (4.14), (8.8) and (8.10) that

$$\eta_\beta g^\beta_{;i} - \phi_{,i} = 0, \quad a^{\alpha\delta} \eta_\delta - g^{\alpha l} \phi_{,l} = \mu^\alpha.$$

Hence, in virtue of (6.10) and these last equations, (8.14) may be written as

$$(8.15) \quad G^\alpha_{;i} = G^\alpha_{;i}.$$

In particular, we note as an immediate consequence of (8.15) that

$$G^\alpha_{;i} = G^\alpha_{;i}.$$

While the Γ^i_{jk} are uniquely determined by conditions (a) through (e), this is not true for the $\Gamma^\alpha_{\beta\gamma}$. Let $\Gamma'^\alpha_{\beta\gamma}$ be any space coefficients of connection for which conditions (a) to (e) are true, other than the $\Gamma^\alpha_{\beta\gamma}$ defined by (8.11). Then

$$(8.16) \quad \Gamma'^{\alpha}_{\beta\gamma} - \Gamma^{\alpha}_{\beta\gamma} = T^{\alpha}_{\beta\gamma},$$

where $T^{\alpha}_{\beta\gamma}$ is a tensor. It is easy to show, using conditions (a) to (e), that $T^{\alpha}_{\beta\gamma}$ must be a conformal tensor which satisfies the relations

$$(8.17) \quad T_{\alpha\beta\gamma} = T_{\alpha\gamma\beta}, \quad [T_{\alpha\beta\gamma} + T_{\beta\alpha\gamma}]G^{\gamma}_k = 0,$$

where $T_{\alpha\beta\gamma} = A_{\alpha\delta}T^{\delta}_{\beta\gamma}$, and conversely. It follows from (8.17) that we may write

$$(8.18) \quad T_{\alpha\beta\gamma} + T_{\beta\alpha\gamma} = S_{\alpha\beta\gamma},$$

where $S_{\alpha\beta\gamma}$ is any conformal tensor which obeys the equations

$$(8.19) \quad S_{\alpha\beta\gamma} = S_{\beta\alpha\gamma}, \quad S_{\alpha\beta\gamma}G^{\gamma}_k = 0.$$

From equations (8.18) and the symmetry properties of $T_{\alpha\beta\gamma}$, we easily find that

$$(8.20) \quad T_{\alpha\beta\gamma} = [S_{\alpha\beta\gamma} + S_{\alpha\gamma\beta} - S_{\beta\gamma\alpha}]/2.$$

Conversely, if $S_{\alpha\beta\gamma}$ is any conformal tensor which obeys (8.19) then $T_{\alpha\beta\gamma}$, defined by (8.20), obeys (8.17). It follows from (8.16) that the most general $\Gamma'^{\alpha}_{\beta\gamma}$ are given by

$$(8.21) \quad \Gamma'^{\alpha}_{\beta\gamma} = \Gamma^{\alpha}_{\beta\gamma} + A^{\alpha\delta}[S_{\delta\beta\gamma} + S_{\delta\gamma\beta} - S_{\beta\gamma\delta}]/2$$

where $S_{\alpha\beta\gamma}$ is any conformal tensor which has the properties stated in (8.19).

Finally we note that Γ^i_{jk} and $\Gamma^{\alpha}_{\beta\gamma}$ exist if $r \geq 3$. However we may show that if Γ^i_{jk} exists on a V_n of class C^r with $r \geq 2$ then $\Gamma^{\alpha}_{\beta\gamma}$ as well as the quantities $\bar{\Gamma}^i_{jk}$, $\bar{\Gamma}^{\alpha}_{\beta\gamma}$ defined on any \bar{V}_n also exists. For the proof, we note that (8.5) may be solved for $\phi_{,i}$ in terms of Γ^i_{jk} and

$$\left\{ \begin{matrix} i \\ jk \end{matrix} \right\}.$$

Since $r \geq 2$, $\bar{\phi}$ exists and (8.7) is true. The existence of $\phi_{,i}$ plus the validity of (8.7) permits us to deduce the existence of $\bar{\phi}_{,i}$. Hence $\bar{\Gamma}^i_{jk}$ exists. Also (8.10) and analogous equations in \bar{V}_n show that η_{α} and $\bar{\eta}_{\alpha}$ exist. It follows from (8.6) that both $\Gamma^{\alpha}_{\beta\gamma}$ and $\bar{\Gamma}^{\alpha}_{\beta\gamma}$ exist. Incidentally, the proof also shows that if $\phi_{,i}$ exists and $r \geq 2$, then $\bar{\phi}_{,i}$ also exists.

9. The replacement principle. Many of the equations of this paper contain a mixture of some quantities which are unchanged by conformal transformations of V_m as well as of others which vary under conformal changes of the metric of V_m . In this section, we show, by means of a change of gauge, that certain of these latter non-conformal geometric objects may be treated as independent variables in expressions where they occur and, in particular, may be replaced by zeros. This replacement principle results in a very considerable curtailment of many of the formal calculations which are made in the paper. In this respect, it is analogous to the choice of special coordinate systems (for

example, normal coordinates or coordinates where the coordinate directions have special initial positions) frequently made in classical and Riemannian geometry.

THEOREM 9.1. *Let V_n be a subspace of class C^r ($r \geq 2$) in a V_m of class C^q ($q \geq r$) and suppose that the gauge function ϕ , its derivative $\phi_{,i}$, and the mean curvature normal μ_α exist⁽²⁴⁾ in V_n . Then an allowable conformal transformation of a region of V_m containing V_n exists so that $V_m \rightleftharpoons \bar{V}_m$, $V_n \rightleftharpoons \bar{V}_n$ and the values at any fixed point of \bar{V}_n of the geometric quantities $\bar{\phi}$, $\bar{\phi}_{,i}$, $\bar{\mu}_\alpha$ defined on \bar{V}_n are arbitrary preassigned numbers.*

The proof is simple. For the existence of $\bar{\phi}$, $\bar{\phi}_{,i}$, and $\bar{\mu}_\alpha$ in \bar{V}_n follows from the assumed existence of the corresponding quantities in V_n and the concluding paragraph of §8. Now the values of $\bar{\phi}$, $\bar{\phi}_{,i}$, $\bar{\mu}_\alpha$ at a point \bar{P} of \bar{V}_n are pre-assigned numbers and the values of ϕ , $\phi_{,i}$, μ_α at the corresponding point P of V_n (having the same coordinates) are known. Hence the corresponding values of η_α , $\bar{\eta}_\alpha$ at P , \bar{P} respectively may be computed by equations like (8.10) evaluated at these points. Then (8.7) and (8.9) determine the value of the mapping function σ and of its first space derivative $\sigma_{,\alpha}$ at P . It is clear that an infinite number of functions $\sigma(y^\alpha)$ of class C^{q-1} exist having the determined values of σ , $\sigma_{,\alpha}$ at P . Any one of these functions may serve as the conformal mapping function and satisfy the conditions of the theorem. This completes the proof.

Now consider any conformal tensor $T^{\alpha_i \beta_j}$ defined on V_n and depending upon geometric objects of V_m and V_n . If $V_m \rightleftharpoons \bar{V}_m$, $V_n \rightleftharpoons \bar{V}_n$ under an allowable conformal map, we assume that the corresponding tensor $\bar{T}^{\alpha_i \beta_j}$ obeys

$$(9.1) \quad \bar{T}^{\alpha_i \beta_j} = T^{\alpha_i \beta_j}.$$

It is understood that $T^{\alpha_i \beta_j}$ and $\bar{T}^{\alpha_i \beta_j}$ are the same formal functions of the corresponding geometric objects of V_n , V_m and of \bar{V}_n , \bar{V}_m respectively. However, despite the conformal character of $T^{\alpha_i \beta_j}$ stated in (9.1), the formal expression for $T^{\alpha_i \beta_j}$ may frequently be given as a complicated mixture of conformal quantities and non-conformal quantities. In what follows, we explain how the conformal nature of $T^{\alpha_i \beta_j}$ may be formally exhibited in an explicit manner.

If $T^{\alpha_i \beta_j}$ depends formally upon some of the quantities ϕ , $\phi_{,i}$, μ_α , we denote by ${}^0T^{\alpha_i \beta_j}$ its formal value when ϕ , $\phi_{,i}$, μ_α are each replaced⁽²⁵⁾ by zero. If $T^{\alpha_i \beta_j}$ is formally independent of these quantities, then we write ${}^0T^{\alpha_i \beta_j} = T^{\alpha_i \beta_j}$. We use a similar symbolism for any (not necessarily conformal) geometric object in V_n . Whenever we speak of *replacements* for a geometric object in V_n , we mean the substitutions described in this paragraph.

(24) If $r \geq 3$, all of these last conditions are fulfilled.

(25) Since zero is a tensor, these replacements leave the tensor character of $T^{\alpha_i \beta_j}$ undisturbed.

Let \mathcal{P} be a point of V_n . According to Theorem 9.1, a conformal map $V_m \leftrightarrow \bar{V}_m, V_n \leftrightarrow \bar{V}_n, \mathcal{P} \leftrightarrow \bar{\mathcal{P}}$ exists so that $\bar{\phi} = \phi, \bar{\mu}_\alpha = 0$ at $\bar{\mathcal{P}}$. In virtue of these equations, the value of $\bar{T}^{\alpha_i \beta_j}$ at $\bar{\mathcal{P}}$ may be written as

$$(9.2) \quad \bar{T}^{\alpha_i \beta_j} = {}^0(\bar{T}^{\alpha_i \beta_j}).$$

Now if it is possible to write the formal expression for ${}^0(T^{\alpha_i \beta_j})$ so that it involves only conformal geometric objects, it remains unchanged (both formally and in its value) under conformal transformations so that

$$(9.3) \quad {}^0T^{\alpha_i \beta_j} = {}^0(\bar{T}^{\alpha_i \beta_j}),$$

where ${}^0T^{\alpha_i \beta_j}$ is evaluated at \mathcal{P} . Of course, this condition is equivalent to the assumption that ${}^0T^{\alpha_i \beta_j}$ is a formal function of conformal geometric objects only. A comparison of (9.1), (9.2) and (9.3) leads to

$$(9.4) \quad T^{\alpha_i \beta_j} = {}^0T^{\alpha_i \beta_j},$$

which is valid at \mathcal{P} . The considerations which lead up to equations (9.1) and (9.2) may be applied at each fixed point of V_n . If (9.3) obtains throughout V_n , then equations (9.4) are valid at each point of V_n ; that is, (9.4) is true throughout V_n .

The above ideas may also be applied to certain tensor equations. A tensor equation in V_n may be written as

$$(9.5) \quad \pi^{\alpha_i \beta_j} = 0,$$

where $\pi^{\alpha_i \beta_j}$ is defined in terms of geometric objects of V_n and V_m . Suppose that $\bar{\pi}^{\alpha_i \beta_j}$ is the corresponding tensor in any \bar{V}_n defined in terms of the corresponding geometric objects of \bar{V}_n, \bar{V}_m and that the equation

$$(9.6) \quad \bar{\pi}^{\alpha_i \beta_j} = 0$$

is obeyed in \bar{V}_n . Then it follows from (9.5) and (9.6) that $\pi^{\alpha_i \beta_j}$ is a conformal tensor $T^{\alpha_i \beta_j}$ so that (9.5) is a conformal equation. (Of course, $T^{\alpha_i \beta_j}$ is equivalent to the zero tensor.) Under these circumstances, the above discussion shows that if $T^{\alpha_i \beta_j}$ obeys (9.3), then (9.5) is equivalent to ${}^0T^{\alpha_i \beta_j} = 0$. We summarize these results in the *replacement principle*.

THEOREM 9.2. *Let $T^{\alpha_i \beta_j}$ ($T^{\alpha_i \beta_j} = 0$) be a conformal tensor (conformal equation) in a V_n of class C^r ($r \geq 2$). Then, if the formal expression for ${}^0T^{\alpha_i \beta_j}$ involves only conformal geometric objects, $T^{\alpha_i \beta_j} = {}^0T^{\alpha_i \beta_j}$ (${}^0T^{\alpha_i \beta_j} = 0$ is equivalent to $T^{\alpha_i \beta_j} = 0$) throughout V_n .*

Finally, we note that the argument used to establish this theorem says in essence: under conformal transformations, $\phi, \phi_{,i}, \mu_\alpha$ have the role of independent variables while $T^{\alpha_i \beta_j}$ remains constant. Hence $T^{\alpha_i \beta_j}$ is independent of the values assigned to $\phi, \phi_{,i}, \mu_\alpha$ so that $T^{\alpha_i \beta_j} = {}^0T^{\alpha_i \beta_j}$.

It is clear that the operation of replacement is commutative with the oper-

ations of addition, subtraction, inner and outer multiplication and projection of tensors. Whenever the operations of replacement and differentiation are both applied to a tensor, it is assumed that the replacement operation is applied last unless the contrary is indicated. For later use, we append the following equations which are immediate consequences of the definitions:

$$(9.7) \quad {}^0\phi = {}^0\phi_{,i} = {}^0\mu_\alpha = {}^0\eta_\alpha = 0,$$

$$(9.8) \quad \begin{aligned} {}^0g_{ij} &= G_{ij}, & {}^0g^{ij} &= G^{ij}, \\ {}^0a_{\alpha\beta} &= A_{\alpha\beta}, & {}^0a^{\alpha\beta} &= A^{\alpha\beta}, \end{aligned}$$

$${}^0g_{\alpha\beta} = G_{\alpha\beta}, \quad {}^0g^{\alpha\beta} = G^{\alpha\beta},$$

$$(9.9) \quad \begin{aligned} {}^0\left\{ \begin{matrix} i \\ jk \end{matrix} \right\} &= \Gamma^i_{jk}, & {}^0\left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\} &= \Gamma^\alpha_{\beta\gamma}, \end{aligned}$$

$$(9.10) \quad {}^0\pi^{\alpha i}_{\beta j,k} = \pi^{\alpha i}_{\beta j,k}, \quad {}^0\pi^{\alpha}_{\beta,\gamma} = \pi^{\alpha}_{\beta,\gamma}.$$

Digression. The result stated in Theorem 9.1 suffices for many aspects of our work but we note that it is possible to obtain a much stronger theorem. Indeed $\bar{\phi}$ and $\bar{\mu}_\alpha$ may be assigned as almost arbitrary functions defined not only at $\bar{\mathcal{P}}$ but throughout \bar{V}_n if V_n is of class C^r ($r \geq 2$) and ϕ is of class C^1 in V_n . To prove this, we first rearrange equations (4.3) so that the Jacobian of the first n of these equations does not vanish. We denote the y^α in these equations by y^i and the remaining y^α by y^ω ($\omega = n+1, n+2, \dots, m$). Then equations (4.3) may be written as

$$y^i = y^i(x^j), \quad y^\omega = y^\omega(x^j).$$

The parameter transformation

$$x'^i = y^i(x^j)$$

is an allowable change of parameters and, in these x'^i , the equations of V_n and \bar{V}_n assume the form

$$(9.11) \quad y^i = x'^i, \quad y^\omega = f^\omega(x'^j).$$

We suppose that $q=r$. Then the coordinate transformation

$$y'^i = y^i, \quad y'^\omega = y^\omega - f^\omega(x'^j)$$

is an allowable coordinate change. Equations (9.11) become

$$(9.12) \quad y^i = x^i, \quad y^\omega = 0$$

where, for simplicity, we have omitted the primes both for the y'^α and the x'^i . From (9.12), we have

$$(9.13) \quad g^{\alpha i} = \delta^{\alpha i}.$$

According to our hypothesis, $r \geq 2$. Hence ϕ and μ_α exist. Since we also as-

sume the existence of $\phi_{,i}$, the vector η_α defined by (8.10) exists. Also, in accordance with the concluding paragraph of §8, the geometric objects $\bar{\phi}$, $\bar{\phi}_{,i}$, $\bar{\mu}_\alpha$ and $\bar{\eta}_\alpha$, defined on any \bar{V}_n obtained from V_n by an allowable conformal map must exist. Furthermore, since σ is of class C^{q-1} and $\sigma_{, \alpha}$ is of class C^{q-2} , it follows from (8.7) and (8.9) that $\phi - \bar{\phi}$ must be of class C^{q-1} and $\eta_\alpha - \bar{\eta}_\alpha$ must be of class C^{q-2} . According to (9.13) and the definition for $\bar{\eta}_\alpha$, it follows that $\mu_\alpha - \bar{\mu}_\alpha$ must be of class C^{q-2} .

Conversely, let $\bar{\phi}(x^i)$ be any scalar function and $\bar{\mu}_\alpha(x^i)$ any vector functions which satisfy the conditions:

$$(9.14) \quad \begin{aligned} \phi(x^i) - \bar{\phi}(x^i) & \text{ is of class } C^{q-1} & (q = r \geq 2), \\ \mu_\alpha(x^i) - \bar{\mu}_\alpha(x^i) & \text{ are of class } C^{q-2}, \end{aligned}$$

$$(9.15) \quad \bar{\mu}_\alpha g^\alpha_i = 0.$$

We shall show that an allowable conformal transformation $V_m \leftrightarrow \bar{V}_m$, $V_n \leftrightarrow \bar{V}_n$ exists so that $\bar{\phi}$ and $\bar{\mu}_\alpha$ are the gauge function and the mean curvature normal of \bar{V}_n .

If we define $\bar{\eta}_\alpha$ by the equations

$$\bar{\eta}_\alpha = \bar{\mu}_\alpha + \phi_{,i} g^i_\alpha$$

it follows that

$$\eta_\alpha - \bar{\eta}_\alpha = (\mu_\alpha - \bar{\mu}_\alpha) + (\phi_{,i} - \bar{\phi}_{,i}) g^i_\alpha$$

and, from (9.14), $\eta_\alpha - \bar{\eta}_\alpha$ is of class C^{q-2} . As a result of (8.8), (8.10), (9.13) and (9.15), the first n components η_i and $\bar{\eta}_i$ of η_α and $\bar{\eta}_\alpha$ respectively are given by

$$(9.16) \quad \eta_i = \eta_\alpha g^\alpha_i = \phi_{,i}, \quad \bar{\eta}_i = \bar{\eta}_\alpha g^\alpha_i = \bar{\phi}_{,i}.$$

Now, according to a theorem due to Whitney [18, p. 65, Theorem 1], functions $f_\omega(y^i, y^r)$ ($r = n+1, n+2, \dots, m$) exist so that

$$(9.17) \quad \begin{aligned} f_\omega(y^i, y^r) & \text{ is of class } C^{q-2} \text{ in } V_m, \\ f_\omega(x^i, 0) & = \eta_\omega(x^i) - \bar{\eta}_\omega(x^i), \\ f_\omega(x^i, y^r) & \text{ is analytic at points of } V_m \text{ which are not in } V_n. \end{aligned}$$

Consider the function $\sigma(y^\alpha)$ defined by

$$(9.18) \quad \sigma(y^\alpha) = \sum_\omega y^\omega f_\omega(y^i, y^r) + [\phi(y^i) - \bar{\phi}(y^i)].$$

From (9.17), it follows that

$$\sum_\omega y^\omega f_\omega(y^i, y^r)$$

is analytic at points where at least one of the y^ω differs from zero and is of

class C^{q-2} at points where all the y^ω vanish, that is, in V_n . If⁽²⁶⁾ $q > 2$, any $(q-2)$ th partial derivative of this expression may be written in the form

$$h(y^\alpha) = \sum_{\omega} \dot{y}^\omega g_\omega(y^i, y^r) + g(y^i, y^r).$$

Here g_ω is a $(q-2)$ th derivative of f_ω and is therefore of class C^0 in V_n . Also, the highest order of derivative of the f_ω which occurs in g is $q-3$ so that g is of class C^1 in V_n .

We show that $h(y^\alpha)$ is of class C^1 in V_m . There are two cases: (1) If any y^ω is not zero, $h(y^\alpha)$ is analytic. (2) If all the y^ω vanish, then

$$\partial h / \partial y^j = \partial g(y^i, 0) / \partial y^j$$

and, by definition of the derivative,

$$\frac{\partial h}{\partial y^r} = \lim_{\Delta y^r \rightarrow 0} \frac{1}{\Delta y^r} [\Delta y^r g_r(y^i, \Delta y^r)] + \frac{\partial g(y^i, 0)}{\partial y^r}.$$

This last expression becomes

$$\partial h / \partial y^r = g_r(y^i, 0) + \partial g(y^i, 0) / \partial y^r.$$

Hence $h(y^\alpha)$ is of class C^1 in V_m .

Now, from (9.14), $\phi(y^i) - \bar{\phi}(y^i)$ is of class C^{q-1} in V_m . Hence σ , defined by (9.18), is of class C^{q-1} in V_m . Furthermore,

$$(9.19) \quad \begin{aligned} \frac{\partial \sigma}{\partial y^i} &= \sum_{\omega} \frac{\partial f_{\omega}}{\partial y^i} \cdot y^{\omega} + \left(\frac{\partial \phi}{\partial y^i} - \frac{\partial \bar{\phi}}{\partial y^i} \right), \\ \frac{\partial \sigma}{\partial y^r} &= \sum_{\omega} \left(\frac{\partial f_{\omega}}{\partial y^r} y^{\omega} \right) + f_r. \end{aligned}$$

By means of (9.12), (9.16) and (9.17), we see that, at points of V_n , (9.18) becomes

$$(9.20) \quad \begin{aligned} \sigma &= \phi(x^j) - \bar{\phi}(x^j), \\ \partial \sigma / \partial y^i &= \eta_i(x^j) - \bar{\eta}_i(x^j), \\ \partial \sigma / \partial y^r &= \eta_r(x^j) - \bar{\eta}_r(x^j). \end{aligned}$$

Since $\sigma(y^\alpha)$ is of class C^{q-1} , it defines a conformal transformation $V_m \rightleftharpoons \bar{V}_m$, $V_n \rightleftharpoons \bar{V}_n$ so that points with the same coordinates and parameters correspond. Then a comparison of (9.20) with (8.7) and (8.9) shows that $\bar{\phi}$ is the gauge function of \bar{V}_n and that $\bar{\mu}_\alpha$ is the mean curvature normal of \bar{V}_n . This completes the proof of the above italicized statement.

As a special case of this result, we note that we may choose $\bar{\phi} = \phi$, $\bar{\mu}_\alpha = 0$. Since μ_α is of class C^{r-2} , conditions (9.14) and (9.15) are satisfied. Hence a \bar{V}_n

⁽²⁶⁾ If $q=2$, then $h(y^\alpha) = \sum_{\omega} y^\omega f_\omega(y^i, y^r)$ in the following argument.

exists for which $\bar{\mu}_\alpha = 0$. Hence any V_n of class C^q is conformal to a minimal subspace. However this proof requires that n exceed 1. Actually, the conclusion may be extended to apply to the case $n=1$. We state this result in the theorem.

THEOREM 9.3. *A subspace V_n of class C^q in a V_m of class C^q ($q \geq 2$) is conformally equivalent to a subspace of zero mean curvature (minimal subspace if $n > 1$, geodesic curve if $n = 1$).*

For the proof, we simply note that the theorem of Whitney used above may be employed to show the existence of functions $f(y^i, y^r)$ with the properties enumerated in (9.17) except that the second set of equations is replaced by

$$f_\omega(y^i, 0) = \mu_\omega.$$

Then, as above, the function $\sigma(y^\alpha)$ defined by

$$\sigma(y^\alpha) = \sum_\omega y^\omega f_\omega(y^i, y^r)$$

is of class C^{q-1} in V_m . Also, at points of V_n ,

$$\partial\sigma/\partial y^i = 0, \quad \partial\sigma/\partial y^r = \mu_r.$$

Now, μ_α is orthogonal to g^α_i . Hence, from (9.13), the first n components μ_i of μ_α , defined by $\mu_i = \mu_\alpha \delta^\alpha_i$, must be zero. Therefore the above equations become

$$\partial\sigma/\partial y^\alpha = \mu_\alpha$$

at points of V_n . If $\sigma(y^\alpha)$ is used as a conformal mapping function, it follows from (6.8) that $\bar{\mu}_\alpha$ vanishes identically. This completes the proof. Theorem 9.3, with n equal to 1, was used in a previous paper [8, §10].

10. Conformal geodesic and conformal normal coordinates and parameters.

When the coordinates y^α (parameters x^i) are subjected to an allowable transformation (that is, with $r \geq 3$), the $\Gamma^\alpha_{\beta\gamma}$ (Γ^i_{jk}) change according to the law of transformation of coefficients of connection. If primes are used to denote the new coordinate (parameter) system and the components of the $\Gamma^\alpha_{\beta\gamma}$, Γ^i_{jk} in this system, then this law of transformation is

$$(10.1) \quad \begin{aligned} \Gamma'^{\delta}_{\beta\gamma} \frac{\partial y^\alpha}{\partial y'^\delta} &= \Gamma^{\alpha}_{\delta\epsilon} \frac{\partial y^\delta}{\partial y'^\beta} \frac{\partial y^\epsilon}{\partial y'^\gamma} + \frac{\partial^2 y^\alpha}{\partial y'^\beta \partial y'^\gamma}, \\ \Gamma'^h_{jk} \frac{\partial x^i}{\partial x'^h} &= \Gamma^i_{hl} \frac{\partial x^h}{\partial x'^j} \frac{\partial x^l}{\partial x'^k} + \frac{\partial^2 x^i}{\partial x'^j \partial x'^k}. \end{aligned}$$

It is clear from these equations that allowable transformations of y^α , x^i exist⁽²⁷⁾ so that

⁽²⁷⁾ For example, the equations $y'^\alpha = (y^\alpha)_0 + y'^\alpha - (\Gamma^\alpha_{\beta\gamma})_0 y'^\beta y'^\gamma / 2$, where $(y^\alpha)_0, (\Gamma^\alpha_{\beta\gamma})_0$ are the values of $y^\alpha, \Gamma^\alpha_{\beta\gamma}$ at \mathcal{P} , define a coordinate transformation for which (10.2) is true.

$$(10.2) \quad (\Gamma'^{\alpha}_{\beta\gamma})_0 = 0,$$

$$(10.3) \quad (\Gamma'^i_{jk})_0 = 0$$

at any preassigned point \mathcal{P} of V . The new coordinate system $\{y'^{\alpha}\}$ [parameter system $\{x'^i\}$] in which (10.2) [(10.3)] is true is called a coordinate [parameter] system which is *conformal geodesic at \mathcal{P}* . These coordinates are analogous to the geodesic coordinates of Riemannian geometry.

It is also possible to define parameters⁽²⁸⁾ which are *conformal normal at \mathcal{P}* . These are similar to the normal coordinates of Riemannian geometry. Parameters x'^i which are conformal normal at \mathcal{P} are parameters so that the equations of those "geodesics" based upon the tensor G_{ij} which pass through \mathcal{P} are $x'^i = L^i S$ where the L^i are constants and S is the conformal length based upon the tensor G_{ij} . Of course, conformal normal parameters are also conformal geodesic at \mathcal{P} . It is sometimes useful to choose the parametric directions at the center \mathcal{P} of the conformal normal parameters so that they coincide with n mutually orthogonal curvature directions of V_n at \mathcal{P} .

The existence of conformal normal parameters is established by exactly the same proof as that used in Riemannian geometry. For this existence proof, it is sufficient that G_{ij} be of class C^2 in the x^i , or otherwise, that $r \geq 4$. The parameter transformation to conformal normal parameters is, in general, of class C^{r-2} and therefore not an allowable transformation unless $r = \infty$ or unless V_n is considered as a space of class C^{r-2} .

11. The Weyl tensors. The assumption

$$(11.1) \quad q \geq 3$$

guarantees the existence of the Riemann curvature tensors $\rho_{\alpha\beta\gamma\delta}$ and $\bar{\rho}_{\alpha\beta\gamma\delta}$ of V_m and \bar{V}_m respectively. A straightforward calculation based on the definition (5.14) and the first equations of (6.3) gives⁽²⁹⁾

$$(11.2) \quad e^{-2\sigma} \bar{\rho}_{\alpha\beta\gamma\delta} = \rho_{\alpha\beta\gamma\delta} + a_{\alpha(\delta\sigma\gamma)-\beta} + a_{\beta(\gamma\sigma\delta)-\alpha} + a_{\alpha(\delta a_{\gamma})-\beta} \cdot \Delta_1 \sigma.$$

From these equations, we readily obtain

$$\bar{\rho}_{\beta\gamma} = \rho_{\beta\gamma} + (m - 2)\sigma_{\beta\gamma} + a_{\beta\gamma} [a^{\alpha\delta}\sigma_{,\alpha\delta} + (m - 2)\Delta_1 \sigma]$$

and

$$(11.3) \quad (m - 1)(m - 2)\sigma_{\alpha\beta} = (m - 1)[\bar{\rho}_{\alpha\beta} - \rho_{\alpha\beta}] - [\bar{\rho}\bar{a}_{\alpha\beta} - \rho a_{\alpha\beta}]/2 - (m - 1)(m - 2)\Delta_1 \sigma \cdot a_{\alpha\beta}/2.$$

In these equations, $\Delta_1 \sigma$ is the differential parameter of the first order defined by $\Delta_1 \sigma = a^{\alpha\beta}\sigma_{,\alpha}\sigma_{,\beta}$ and $\sigma_{\alpha\beta}$ is defined by the equations

$$(11.4) \quad \sigma_{\alpha\beta} = \sigma_{,\alpha\beta} - \sigma_{,\alpha}\sigma_{,\beta}.$$

⁽²⁸⁾ Since the $\Gamma^{\alpha}_{\beta\gamma}$ are only defined at points of V_n , there are obvious difficulties in defining "conformal normal coordinates."

⁽²⁹⁾ For a derivation of (11.2) along these lines, see [4, pp. 89-90].

If $m > 2$, (11.3) may be solved for $\sigma_{\alpha\beta}$. If the resulting value for $\sigma_{\alpha\beta}$ is substituted in (11.2) and account is taken of (2.6), we find that

$$\bar{C}^{\alpha\beta\gamma\delta} = C^{\alpha\beta\gamma\delta}$$

where $C^{\alpha\beta\gamma\delta}$ is the conformal (space) Weyl tensor of V_m ($m > 2$) defined by

$$(11.5) \quad C^{\alpha\beta\gamma\delta} = \rho^{\alpha\beta\gamma\delta} + \frac{1}{(m-2)} [a^{\alpha(\gamma\rho\delta)-\beta} + a_{\beta(\delta\rho^{\alpha}\gamma)-}] + \frac{\rho}{(m-1)(m-2)} \cdot a^{\alpha(\delta a_{\gamma})-\beta}.$$

If $m = 3$, it may be shown that $C^{\alpha\beta\gamma\delta}$ is a zero tensor. It was proved by Weyl [17, p. 404] and Schouten [12, p. 80] that, if $m > 3$, the equation $C^{\alpha\beta\gamma\delta} = 0$ is the necessary and sufficient condition that V_m be a conformally euclidean space \bar{R}_m .

Unlike the Riemann tensor, contraction of indices in the Weyl tensor does not lead to any new tensors. For, from (11.5),

$$(11.6) \quad C^{\alpha\beta\gamma\alpha} = C^{\alpha\beta\alpha\delta} = C^{\alpha\alpha\gamma\delta} = C^{\alpha\beta\gamma\delta} a^{\beta\gamma} = C^{\alpha\beta\gamma\delta} a^{\beta\delta} = C^{\alpha\beta\gamma\delta} a^{\gamma\delta} = 0.$$

However, new conformal tensors may be constructed from $C^{\alpha\beta\gamma\delta}$ at points of V_n by means of the conformal projection tensor $G^{\alpha\beta}$ and the indices of these various tensors may be raised or lowered by means of $A^{\alpha\beta}$, $A_{\alpha\beta}$ if (5.1) holds. We define the following conformal tensors:

$$(11.7) \quad C_{\alpha\beta\gamma\delta} = A_{\alpha\epsilon} C^{\epsilon\beta\gamma\delta},$$

$$(11.8) \quad C_{\beta\gamma} = C_{\alpha\beta\gamma\delta} G^{\alpha\delta},$$

$$(11.9) \quad C = C_{\beta\gamma} G^{\beta\gamma},$$

$$(11.10) \quad C_{\alpha\beta\gamma k} = C_{\alpha\beta\gamma\delta} G^{\delta k}, \quad C_{\alpha\beta i k} = C_{\alpha\beta\gamma k} G^{\gamma i},$$

$$(11.11) \quad C_{\alpha i j k} = C_{\alpha\beta j k} G^{\beta i}, \quad C_{h i j k} = C_{\alpha i j k} G^{\alpha h},$$

$$(11.11) \quad C_{\beta j} = C_{\beta\gamma} G^{\gamma j}, \quad C_{i j} = C_{\beta j} G^{\beta i}.$$

It follows easily that

$$(11.12) \quad C_{i j} = C_{h i j k} G^{h k}, \quad C = C_{i j} G^{i j}.$$

According to (11.6), (11.7) and (11.8),

$$(11.13) \quad C_{\alpha\beta\gamma\delta} A^{\alpha\beta} = C_{\alpha\beta\gamma\delta} A^{\alpha\gamma} = C_{\alpha\beta\gamma\delta} A^{\alpha\delta} = C_{\alpha\beta\gamma\delta} A^{\beta\gamma} = C_{\alpha\beta\gamma\delta} A^{\beta\delta} = C_{\alpha\beta\gamma\delta} A^{\gamma\delta} = 0, \\ C_{\alpha\beta} A^{\alpha\beta} = 0.$$

As an easy consequence of (5.15), (11.5) and (11.7), we have the identities

$$(11.14) \quad C_{\alpha\beta\gamma\delta} = C_{\gamma\delta\alpha\beta} = -C_{\beta\alpha\gamma\delta} = -C_{\alpha\beta\delta\gamma}, \quad C_{\alpha(\beta\gamma\delta)+} = 0.$$

Similar identities also hold for $C_{h i j k}$. From these last equations, we also obtain

$$(11.15) \quad C_{\alpha\beta\gamma\delta}G^{\alpha\beta} = C_{\alpha\beta\gamma\delta}G^{\gamma\delta} = 0,$$

$$(11.16) \quad C_{\beta\gamma} = C_{\beta\alpha\delta\gamma}G^{\alpha\delta},$$

$$(11.17) \quad C_{\beta\gamma} = C_{\gamma\beta}.$$

The conformal tensors $D^{\alpha}_{\beta jk}$ and D^{α}_{ijk} which appear in later sections of the paper are defined by the equations

$$(11.18) \quad D^{\alpha}_{\beta jk} = \left\{ C^{\alpha}_{\beta\gamma\delta} + \frac{1}{(n-1)} [A^{\alpha}_{(\gamma}C_{\delta)\epsilon}H^{\epsilon}_{\beta} + A_{\beta(\delta}C^{\epsilon}_{\gamma)}H^{\alpha}_{\epsilon}] \right\} G^{\gamma}_j G^{\delta}_k,$$

$$D_{\alpha\beta jk} = A_{\alpha\gamma}D^{\gamma}_{\beta jk},$$

$$(11.19) \quad D^{\alpha}_{ijk} = C^{\alpha}_{ijk} + \frac{1}{(n-1)} H^{\alpha}_{\epsilon} C^{\epsilon}_{\gamma} G_{i(k} G^{\gamma}_{j)\epsilon},$$

$$D_{\alpha ijk} = A_{\alpha\gamma}D^{\gamma}_{ijk},$$

where the raising of indices in $C_{\alpha\beta}$ is naturally accomplished by means of $A^{\alpha\beta}$. It is clear that

$$D^{\alpha}_{ijk} = D^{\alpha}_{\beta jk} G^{\beta}_i, \quad D_{\alpha ijk} = D_{\alpha\beta jk} G^{\beta}_i.$$

If $m = n + 1$, so that V_n is a hypersurface, the measure tensor $A^{\alpha\beta}$ may be written as

$$(11.20) \quad A^{\alpha\beta} = G^{\alpha\beta} + Z^{\alpha}Z^{\beta},$$

where Z^{α} is the unit conformal normal to V_n (determined except for algebraic sign) so that

$$(11.21) \quad A_{\alpha\beta}Z^{\alpha}G^{\beta}_j = 0, \quad A_{\alpha\beta}Z^{\alpha}Z^{\beta} = 1.$$

It follows from (11.8), (11.13) and (11.20) that

$$(11.22) \quad C_{\beta\gamma} = -C_{\alpha\beta\gamma\delta}Z^{\alpha}Z^{\delta}.$$

As a consequence of (11.9), (11.13), (11.14), (11.20) and (11.22), the following identities also hold for a hypersurface

$$(11.23) \quad C = C_{\alpha\beta\gamma\delta}Z^{\alpha}Z^{\beta}Z^{\gamma}Z^{\delta} = 0, \quad C_{\beta\gamma}Z^{\beta} = 0.$$

The last set of equations shows that $C_{\beta\gamma}$ is a tangent conformal tensor. Finally we note that, for a hypersurface, the conformal tensors $D^{\alpha}_{\beta jk}$ and D^{α}_{ijk} , defined by (11.18) and (11.19), become

$$(11.24) \quad D^{\alpha}_{\beta jk} = C^{\alpha}_{\beta jk}, \quad D^{\alpha}_{ijk} = C^{\alpha}_{ijk}.$$

If (11.1) is replaced by (5.13), the Riemann curvature tensors κ_{ijkl} and $\bar{\kappa}_{ijkl}$ of V_n and \bar{V}_n respectively exist. As in the beginning of this section, we may construct the conformal (surface) Weyl tensors of V_n and \bar{V}_n from the Riemann tensors if $n > 2$. The Weyl tensor W^i_{jkl} of V_n ($n > 2$) is defined by

$$(11.25) \quad W^i{}_{jkl} = \kappa^i{}_{jkl} + \frac{1}{(n-2)} [g^{i(k\kappa l)-j} + g_{j(l\kappa^i k)-}] + \frac{\kappa}{(n-1)(n-2)} g^i{}_{(l g k)-j}.$$

If $n=3$, $W^i{}_{jkl}$ is a zero tensor. If n exceeds 3, the vanishing of $W^i{}_{jkl}$ is the necessary and sufficient condition that V_n be a conformally euclidean space. The indices of $W^i{}_{jkl}$ may be raised or lowered by means of G^{ij} , G_{ij} without changing its conformal character. For example,

$$(11.26) \quad W_{ijkl} = G_{ih}W^h{}_{jkl}.$$

Since equations like (11.13) hold when W_{ijkl} , G^{ij} replace $C_{\alpha\beta\gamma\delta}$, $A^{\alpha\beta}$ there are no analogues to $C_{\alpha\beta}$, C . It is easy to verify that the usual identities hold for W_{ijkl} , that is,

$$(11.27) \quad W_{ijkl} = W_{klij} = -W_{jikl} = -W_{ijlk}, \quad W_{i(jkl)+} = 0.$$

We now define the *Weyl operation* \uparrow which when applied to $\rho^{\alpha\beta\gamma\delta}$, $\kappa^i{}_{jkl}$ yields the Weyl tensors $C^{\alpha\beta\gamma\delta}$, $W^i{}_{jkl}$. This operation is used later in the paper. Let $n > 2$ and f_{ij} be any symmetric positive definite surface tensor and let d_{ijkl} ($d^i{}_{jkl}$) be any surface tensor. Then the *Weyl \uparrow operation with respect to f_{ij}* applied to the tensor d_{ijkl} ($d^i{}_{jkl}$) yields the tensor $\uparrow d_{ijkl}$ ($\uparrow d^i{}_{jkl}$) defined by the equations

$$(11.28) \quad \begin{aligned} \uparrow d_{ijkl} &= d_{ijkl} + \frac{1}{(n-2)} [f_{i(kd l)-j} + f_{j(l d k)-i}] \\ &\quad + \frac{d}{(n-1)(n-2)} f_{i(l f k)-j}, \\ \uparrow d^i{}_{jkl} &= d^i{}_{jkl} + \frac{1}{(n-2)} [\delta^i{}_{(k d l)-j} + f_{j(l d^i k)-}] \\ &\quad + \frac{d}{(n-1)(n-2)} \delta^i{}_{(l f k)-j}, \end{aligned}$$

where f^{ih} are the contravariant components of f_{ih} and $d_{il} = d_{ijk l} f^{jk}$, $d^i{}_l = d^i{}_{jkl} f^{jk}$, $d = d_{il} f^{il} = d^i{}_i$. A similar definition is made for space tensors. Then it is immediate that

$$(11.29) \quad C^{\alpha\beta\gamma\delta} = \uparrow \rho^{\alpha\beta\gamma\delta}, \quad W^i{}_{jkl} = \uparrow \kappa^i{}_{jkl}$$

where the \uparrow operations in these equations are with respect to $a_{\alpha\beta}$ and g_{ij} respectively. The following rules are direct consequences of the above definitions:

$$(11.30) \quad \uparrow (d_{ijkl} + e_{ijkl}) = \uparrow d_{ijkl} + \uparrow e_{ijkl},$$

$$(11.31) \quad \begin{aligned} \uparrow (f_{i(k\ell l)-j} + f_{j(i\ell k)-i}) &= 0, \\ f^{jk} \uparrow d_{ijkl} &= 0. \end{aligned}$$

As a consequence of the last equations,

$$\uparrow \uparrow d_{ijkl} = \uparrow d_{ijkl}.$$

12. The Bianchi identities for the Weyl tensors. If (10.1) is replaced by the stronger inequality

$$(12.1) \quad g \geq 4,$$

the covariant derivative of the space Riemann tensor $\rho^{\alpha\beta\gamma\delta}$ exists. If we choose geodesic coordinates at a point \mathcal{P} of V_m , differentiation of (5.14) and evaluation at \mathcal{P} yields

$$\rho^{\alpha\beta\gamma\delta,\epsilon} = \frac{\partial^2}{\partial y^\epsilon \partial y^\gamma} \left\{ \begin{matrix} \alpha \\ \beta\delta \end{matrix} \right\} - \frac{\partial^2}{\partial y^\epsilon \partial y^\delta} \left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\}.$$

From this result and similar equations, we obtain [4, p. 82]

$$(12.2) \quad \rho^{\alpha\beta(\gamma\delta,\epsilon)+} = 0$$

at \mathcal{P} . Since the terms in these equations are the components of a tensor, the equations hold in all coordinate systems and at all points of V_m . The equations are the well known *Bianchi identities*. If (12.2) is contracted for α and δ and also multiplied by $a^{\beta\epsilon}$ and summed for β, ϵ , we obtain

$$(12.3) \quad a^{\beta\epsilon} \rho_{\beta\gamma,\epsilon} = \rho_{,\gamma/2}$$

after using (5.15) and the definitions for $\rho_{\beta\gamma}$ and ρ .

If $m > 2$ and $C^{\alpha\beta\gamma\delta,\epsilon}$ is calculated from (11.5), we obtain, after using (12.2),

$$(12.4) \quad C^{\alpha\beta(\gamma\delta,\epsilon)+} = \frac{1}{(m-2)} [a^{\alpha\gamma+\rho\beta(\delta\epsilon)+} + a_{\beta\delta+\rho^{\alpha(\gamma\epsilon)+}]$$

where we have written

$$(12.5) \quad \rho_{\beta\gamma\delta} = \rho_{\beta(\gamma,\delta)-} + \frac{1}{2(m-1)} \rho_{,(\gamma a\delta)-\beta}, \quad \rho^{\alpha\gamma\delta} = a^{\alpha\beta} \rho_{\beta\gamma\delta}.$$

It follows from (12.3) and (12.5) that

$$(12.6) \quad \rho^{\alpha\alpha\delta} = 0.$$

Contraction of (12.4) for α and δ leads to

$$(12.7) \quad C^{\alpha\beta\epsilon\gamma,\alpha} = (m-3)\rho_{\beta\epsilon\gamma}/(m-2)$$

after simplification by means of (11.6) and (12.6).

Since $C^{\alpha\beta\gamma\delta}$ is of class C^1 throughout V_m , $C^{\alpha\beta\gamma\delta,\epsilon}$ exists at points of V_n if condition (5.13) is adjoined to (12.1). From (8.11), (8.12), (11.6) and (11.14), we obtain

$$(12.8) \quad C^{\alpha\beta\gamma\delta;\epsilon} = C^{\alpha\beta\gamma\delta,\epsilon} + (m - 3)C^{\alpha\beta\gamma\delta}\eta_{\alpha}.$$

This equation is true on V_n . It follows from (12.7) and (12.8) that, at points of V_n ,

$$(12.9) \quad C^{\alpha\beta\gamma\delta;\alpha} = (m - 3) \left[\frac{1}{(m - 2)} \rho_{\beta\gamma\delta} + C^{\alpha\beta\gamma\delta}\eta_{\alpha} \right].$$

According to (9.10),

$$(12.10) \quad {}^0C^{\alpha\beta\gamma\delta,\epsilon} = C^{\alpha\beta\gamma\delta;\epsilon}.$$

If $m > 3$, (9.7) and (12.9) show that

$$(12.11) \quad {}^0\rho_{\beta\gamma\delta} = (m - 2)C^{\alpha\beta\gamma\delta;\alpha}/(m - 3).$$

Now equations analogous to (12.4) are true in every \bar{V}_m so that (12.4) are conformal equations. If replacements are made for the various tensors in these equations by means of (9.8), (12.10) and (12.11), we obtain

$$(12.12) \quad C^{\alpha\beta(\gamma\delta;\epsilon)+} = \frac{1}{(m - 3)} [A^{\alpha\gamma} + C^{\gamma\beta(\delta\epsilon)+;\zeta} + A_{\beta\delta} + C^{\zeta\alpha(\gamma\epsilon)+;\zeta}]$$

where $C^{\zeta\alpha\gamma\epsilon} = C^{\zeta\beta\gamma\epsilon}A^{\alpha\beta}$. Since the terms in (12.12) are components of conformal tensors, the replacement principle enables us to conclude that (12.12) is equivalent to (12.4) at points of V_n . Consequently equations (12.12) are valid throughout V_n if $m > 3$. They are the *Bianchi identities for the space Weyl tensor* $C^{\alpha\beta\gamma\delta}$.

If $m \leq 3$, no corresponding Bianchi identities for $C^{\alpha\beta\gamma\delta}$ hold since $C^{\alpha\beta\gamma\delta}$ does not exist if $m = 2$ and is a zero tensor if $m = 3$. If $m = 2$, $\rho_{\alpha\beta} = \rho \cdot a_{\alpha\beta}/2$ so that $\rho_{\alpha\beta\gamma}$ defined by (12.5) is a zero tensor. If $m > 2$, covariant differentiation of (11.3) and use of (2.6) and (6.3) gives

$$(12.13) \quad \begin{aligned} (m - 2)[\sigma_{,\alpha\beta\gamma} - \sigma_{,\alpha\gamma\sigma,\beta} - \sigma_{,\alpha\sigma,\beta\gamma}] &= \bar{\rho}_{\alpha\beta;\gamma} + 2\bar{\rho}_{\alpha\beta}\sigma_{,\gamma} \\ &+ \bar{\rho}_{\gamma\beta}\sigma_{,\alpha} + \bar{\rho}_{\alpha\gamma}\sigma_{,\beta} - \bar{\rho}_{\epsilon\beta}a^{\epsilon\delta}\sigma_{,\delta}a_{\alpha\gamma} - \bar{\rho}_{\epsilon\alpha}a^{\epsilon\delta}\sigma_{,\delta}a_{\beta\gamma} \\ &- \rho_{\alpha\beta,\gamma} - (1/2(m - 1))[\bar{\rho}_{;\gamma}\bar{a}_{\alpha\beta} + 2\bar{\rho}\bar{a}_{\alpha\beta}\sigma_{,\gamma} - \rho_{,\gamma}a_{\alpha\beta}] \\ &- (m - 2)a_{\alpha\beta}a^{\epsilon\delta}\sigma_{,\epsilon\gamma\sigma,\delta}. \end{aligned}$$

According to the Ricci identities⁽⁸⁰⁾ for this type of differentiation, $\sigma_{,\alpha(\beta\gamma)-} = \sigma_{,\epsilon\rho^{\epsilon}\alpha\beta\gamma}$ which, if $m > 2$, become

$$(12.14) \quad \begin{aligned} \sigma_{,\alpha(\beta\gamma)-} &= \sigma_{,\epsilon}C^{\epsilon\alpha\beta\gamma} + (1/(m - 2))[\sigma_{,(\gamma\rho\beta)-\alpha} + a_{\alpha(\beta\rho\gamma)-\epsilon}a^{\epsilon\delta}\sigma_{,\delta}] \\ &+ (\rho/(m - 1)(m - 2))\sigma_{,(\beta a_{\gamma})-\alpha} \end{aligned}$$

upon application of (11.5).

⁽⁸⁰⁾ These identities are derived for general covariant differentiation in §17.

If the indices β, γ in (12.13) are interchanged and the new equations subtracted from (12.13), the resulting equations may be simplified by means of (11.3), (11.4), (12.5) and (12.14). In this manner, we obtain

$$(12.15) \quad (m - 2)\sigma_{\epsilon} C^{\epsilon}_{\alpha\beta\gamma} = \bar{\rho}_{\alpha\beta\gamma} - \rho_{\alpha\beta\gamma}.$$

According to (8.9), (12.15) is equivalent to

$$(12.16) \quad \rho_{\alpha\beta\gamma} + (m - 2)\eta_{\epsilon} C^{\epsilon}_{\alpha\beta\gamma} = \bar{\rho}_{\alpha\beta\gamma} + (m - 2)\bar{\eta}_{\epsilon} \bar{C}^{\epsilon}_{\alpha\beta\gamma}.$$

If $m = 3$ or if V_m is a conformally euclidean space \bar{R}_m of any dimensionality, $C^{\epsilon}_{\alpha\beta\gamma} \equiv 0$. Consequently, from (12.15), $\rho_{\alpha\beta\gamma}$ is a conformal tensor in an R_m ($m \geq 3$) and in any V_3 . Schouten [12, p. 80] proved that $\rho_{\alpha\beta\gamma}$ is a zero tensor in a V_3 if and only if V_3 is an \bar{R}_3 . According to (12.9) and (12.16), if $m > 2$, the tensor $\rho_{\alpha\beta\gamma} + (m - 2)\eta_{\epsilon} C^{\epsilon}_{\alpha\beta\gamma}$ is a conformal tensor at all points of a V_n in V_m . It is equal to $(m - 2)C^{\epsilon}_{\alpha\beta\gamma} / (m - 3)$ if $m > 3$.

According to (4.13), the surface components $C_{hi;jk}$ of the projection of $C_{\alpha\beta\gamma\delta}$ in the tangent vector space of V_n are given by (11.10). Conformal differentiation of these equations with respect to x^l gives

$$C_{hi;jk;l} = C_{\alpha\beta\gamma\delta} G^{\alpha}_h G^{\beta}_i G^{\gamma}_j G^{\delta}_k G^{\epsilon}_l + C_{\alpha\beta\gamma\delta} [G^{\alpha}_h G^{\beta}_i G^{\gamma}_j G^{\delta}_k + G^{\alpha}_h G^{\beta}_{;i} G^{\gamma}_j G^{\delta}_k + G^{\alpha}_h G^{\beta}_i G^{\gamma}_{;j} G^{\delta}_k + G^{\alpha}_h G^{\beta}_i G^{\gamma}_j G^{\delta}_{;k} + G^{\alpha}_h G^{\beta}_i G^{\gamma}_j G^{\delta}_{;kl}]$$

after account is taken of (8.13) and (8.15). If these equations and similar equations are added and the result is simplified by means of (11.14) and (12.12), we obtain

$$(12.17) \quad C_{hi(jk;l)+} = \frac{1}{(m - 3)} [G_{hj} C^{\alpha}_{i(kl)+;\alpha} + G_{ik} C^{\alpha}_{h(jl)+;\alpha}] + C_{\alpha\beta\gamma\delta} [G^{\alpha}_{hj} G^{\beta}_{;i} G^{\gamma}_{k+} G^{\delta}_{l+} + G^{\alpha}_{hj} G^{\beta}_{;i+j} G^{\gamma}_{k+} G^{\delta}_{l+}]$$

where⁽³¹⁾ $C^{\alpha}_{ijk;\alpha}$ are the surface components of the projection of $C^{\alpha}_{\beta\gamma\delta;\alpha}$ in the tangent vector space of V_n , that is,

$$(12.18) \quad C^{\alpha}_{ijk;\alpha} = C^{\alpha}_{\beta\gamma\delta;\alpha} G^{\beta}_i G^{\gamma}_j G^{\delta}_k.$$

We multiply (12.17) by G^{hl} and sum on repeated indices and simplify the result by means of (7.4), (7.10), (7.11), (11.8), (11.11) and (11.14). In this way we obtain

$$(12.19) \quad C_{hi(jk;l)+} G^{hl} = (1/(m - 3)) [(n - 3)C^{\alpha}_{ijk;\alpha} + G_{ij} C^{\alpha}_{hkl-;\alpha} G^{hl}] + C_{\alpha\beta\gamma\delta} G^{hl} [G^{\alpha}_{hj} G^{\beta}_{;i} G^{\gamma}_{k-} G^{\delta}_{l-} + G^{\alpha}_{hj} G^{\beta}_{;i} G^{\gamma}_j G^{\delta}_k] + C_{\beta(k} G^{\beta}_{j)-i}.$$

In a similar manner, conformal differentiation of $C_{\beta j}$ defined by (11.11)

(31) In accordance with the convention of §4, we omit the projection symbol * since $C^{\alpha}_{ijk;\alpha}$ can only mean $(C^{\alpha}_{\beta\gamma\delta;\alpha}) G^{\beta}_i G^{\gamma}_j G^{\delta}_k$. For the other interpretation, namely $(C^{\alpha}_{ijk})_{;\alpha}$, is meaningless since the space conformal derivative of C^{α}_{ijk} does not exist. These remarks also apply to similar tensors defined in this section.

with respect to x^k gives

$$C_{\alpha j; k} = C_{\alpha\beta\gamma\delta} G^{\beta\gamma} G^{\delta}{}_{j} G^{\epsilon}{}_{k} + C_{\alpha\delta} G^{\delta}{}_{jk} + C_{\alpha\beta\gamma\delta} G^{\delta}{}_{j} G^{hl} [G^{\beta}{}_{hk} G^{\gamma}{}_{l} + G^{\beta}{}_{h} G^{\gamma}{}_{lk}]$$

after use of (8.15) and (11.8). From these equations and (12.12) we find that

$$(12.20) \quad \begin{aligned} C_{\alpha(j; k)-} &= -C_{\alpha\beta jk} G^{\beta\epsilon} + (1/(m-3)) [C^{\epsilon}{}_{\beta jk} G^{\beta}{}_{\alpha} \\ &+ G_{\alpha k} C^{\epsilon}{}_{\beta\gamma j-} G^{\beta\gamma} + (2-n) C^{\epsilon}{}_{\alpha jk} G^{\beta}{}_{\gamma} \\ &+ C_{\alpha\beta\gamma\delta} G^{\delta}{}_{j-} G^{hl} [G^{\beta}{}_{hk} G^{\gamma}{}_{l} + G^{\beta}{}_{h} G^{\gamma}{}_{lk-}] \end{aligned}$$

where, as in (12.18),

$$(12.21) \quad \begin{aligned} C_{\alpha\beta jk; \epsilon} &= C_{\alpha\beta\gamma\delta} G^{\gamma}{}_{j} G^{\delta}{}_{k}, \\ C^{\epsilon}{}_{\beta jk; \zeta} &= C^{\epsilon}{}_{\beta\gamma\delta} G^{\gamma}{}_{j} G^{\delta}{}_{k}, \\ C^{\epsilon}{}_{\beta\gamma k; \zeta} &= C^{\epsilon}{}_{\beta\gamma\delta} G^{\delta}{}_{k}. \end{aligned}$$

Now, according to (11.11),

$$C_{i(j; k)-} = [C_{\alpha j-} G^{\alpha}{}_{i}]_{; k-}$$

so that

$$(12.22) \quad C_{i(j; k)-} = C_{\alpha(j; k)-} + C_{\alpha(j} G^{\alpha}{}_{k)-i}.$$

The results of these last two paragraphs are used in the sequel.

If (12.1) is replaced by

$$(12.23) \quad r \geq 4$$

the Bianchi identities for the surface Riemann tensor $\kappa^h{}_{ijk}$ may be derived in the same manner as (12.2). They are

$$(12.24) \quad \kappa^h{}_{i(jk, l)+} = 0$$

and are valid at all points of V_n . In a similar way, equations like (12.4) to (12.7) hold for the surface objects which are analogous to the corresponding space objects of these equations if $n > 2$. We also obtain the following analogues of equations (12.8) and (12.9) respectively:

$$(12.25) \quad W^h{}_{ijk; h} = W^h{}_{ijk, h} + (n-3)W^h{}_{ijk}\phi_{, h},$$

$$(12.26) \quad W^h{}_{ijk; h} = (n-3) \left[\frac{1}{(n-2)} \kappa_{ijk} + W^h{}_{ijk}\phi_{, h} \right],$$

where κ_{ijk} is defined by

$$(12.27) \quad \kappa_{ijk} = \kappa_{i(j, k)-} + \frac{1}{2(n-1)} \kappa_{(jgk)-i}.$$

The method followed in the derivation of (12.12) is valid if $n > 3$. In this case, we find the *Bianchi identities for the surface Weyl tensor* $W^h{}_{ik}$:

$$(12.28) \quad W^{h_{i(jk:l)+}} = \frac{1}{(n-3)} [G^{h_{j+}} W^{\sigma_{i(kl)+; \sigma}} + G_{i j+} W^{\sigma^h_{(lk)+; \sigma}}]$$

where $W^{\sigma^h_{ji}} = W^{\sigma_{ij}} G^{hi}$.

13. **The deviation tensor.** In Riemannian geometry, the fundamental forms of a subspace V_n are defined in connection with the Frenet equations which describe the variation of the tangent and normal vector spaces of V_n . In later sections, components of conformal tensors which are analogous to the coefficients of these (metric) fundamental forms are discovered. However, the tensors thus defined are not sufficient for a complete conformal characterization of V_n and this fact gives rise to several decisive differences between Riemannian and conformal differential geometry. It is also necessary to investigate the variation of the relative conformal curvature Λ and of the mean curvature normal μ^α . The first of these two problems is considered in the present section and its solution depends upon the discovery of a new conformal tensor which has no analogue in the metric theory of V_n . Naturally there are important qualitative differences between the geometric properties of this tensor, defined in connection with the variation of Λ , and the geometric properties of the other tensors, defined in connection with the Frenet equations.

Suppose (12.23) is satisfied. Then the second partial derivatives of Λ (or of ϕ) exist and are continuous. At points of V_n , covariant differentiation of (8.7) leads to the equations

$$(13.1) \quad \sigma_{,i} = \phi_{,i} - \bar{\phi}_{;i}$$

$$(13.2) \quad \sigma_{,ij} = \phi_{,ij} - \bar{\phi}_{;ij} - \bar{\phi}_{;i}\sigma_{,j} - \bar{\phi}_{;j}\sigma_{,i} + g_{ij}g^{hk}\sigma_{,k}\bar{\phi}_{;h}$$

since, from (6.3),

$$\bar{\phi}_{,ij} = \bar{\phi}_{;ij} + \bar{\phi}_{;i}\sigma_{,j} + \bar{\phi}_{;j}\sigma_{,i} - g_{ij}g^{hk}\sigma_{,k}\bar{\phi}_{;h}.$$

We make the definitions

$$(13.3) \quad \sigma_{ij} = \sigma_{,ij} - \sigma_{,i}\sigma_{,j}$$

$$(13.4) \quad \phi_{ij} = \phi_{,ij} - \phi_{,i}\phi_{,j}$$

$$\bar{\phi}_{ij} = \bar{\phi}_{;ij} - \bar{\phi}_{;i}\bar{\phi}_{;j}$$

As a consequence of these equations and (13.1) and (13.2),

$$(13.5) \quad \sigma_{ij} = \phi_{ij} - \bar{\phi}_{ij} + g_{ij}g^{hk}\sigma_{,k}\bar{\phi}_{;h}.$$

Now

$$(13.6) \quad \sigma_{,i} = \sigma_{,\alpha}g^\alpha_{i}$$

$$\sigma_{,ij} = \sigma_{,\alpha\beta}g^\alpha_{i}g^\beta_{j} + \sigma_{,\alpha}g^\alpha_{ij}$$

where g^α_{ij} is defined by (5.3). It follows from (11.4), (13.3) and the last two sets of equations that

$$(13.7) \quad \sigma_{ij} = \sigma_{\alpha\beta} g^{\alpha}{}_{i} g^{\beta}{}_{j} + \sigma_{,\alpha} g^{\alpha}{}_{ij}$$

If account is taken of (4.5), (6.10), (11.3), (13.5) and (13.7), we obtain

$$(13.8) \quad \left[\frac{\rho}{2(m-1)(m-2)} \cdot g_{ij} - \frac{1}{(m-2)} \cdot \rho_{\alpha\beta} g^{\alpha}{}_{i} g^{\beta}{}_{j} - \phi_{ij} \right] \\ - \left[\frac{\bar{\rho}}{2(m-1)(m-2)} \cdot \bar{g}_{ij} - \frac{1}{(m-2)} \cdot \bar{\rho}_{\alpha\beta} \bar{g}^{\alpha}{}_{i} \bar{g}^{\beta}{}_{j} - \bar{\phi}_{ij} \right] \\ = \sigma_{,\alpha} G^{\alpha}{}_{ij} + [\sigma_{,\alpha} \mu^{\alpha} - a^{\alpha\beta} \sigma_{,\alpha} \sigma_{,\beta} / 2 - g^{hk} \sigma_{,k} \bar{\phi}_{;h}] g_{ij}$$

Since μ^{α} and $G^{\alpha}{}_{ij}$ are orthogonal to $\phi_{,\alpha}$, it follows from (4.14), (8.8), (8.9) and (8.10) that the expression which appears in the right member of (13.8) is equal to

$$[\mu_{\alpha} G^{\alpha}{}_{ij} + (\mu^2 - \Delta_1 \phi) g_{ij} / 2] - [\bar{\mu}_{\alpha} \bar{G}^{\alpha}{}_{ij} + (\bar{\mu}^2 - \bar{\Delta}_1 \bar{\phi}) \bar{g}_{ij} / 2]$$

Therefore (13.8) may be written as

$$E_{ij} = \bar{E}_{ij}$$

where

$$(13.9) \quad E_{ij} = \mu_{\alpha} G^{\alpha}{}_{ij} - \phi_{ij} - \frac{1}{(m-2)} \rho_{\alpha\beta} g^{\alpha}{}_{i} g^{\beta}{}_{j} \\ + \frac{1}{2} [\mu^2 - \Delta_1 \phi + \rho / (m-1)(m-2)] g_{ij}$$

and \bar{E}_{ij} is the tensor formed from the corresponding geometric objects of \bar{V}_n . We call the conformal tensor E_{ij} the *deviation tensor*⁽⁸²⁾ of V_n . It is immediate that $E_{ij} = E_{ji}$.

The above proof is valid even if $r \geq 3$ provided ϕ is of class C^2 . For, under these assumptions, $\bar{\phi}_{;i}$ exists and (13.1) holds. Since $\phi_{,i}$ and $\sigma_{,i}$ are of class C^1 , (13.1) shows that the second partial derivatives of $\bar{\phi}$ exist. Hence $\bar{\phi}$ is of class C^2 . From this point the previous proof may be continued unchanged. Now (13.9) shows that the existence of E_{ij} with $r \geq 3$ implies the existence of $\phi_{,ij}$ so that, in this case, ϕ is of class C^2 . Hence we may conclude that *if E_{ij} exists in a V_n with $r \geq 3$, \bar{E}_{ij} exists in any corresponding \bar{V}_n obtained from V_n by an allowable conformal map.*

It is convenient to derive another expression for E_{ij} which involves conformal differentiation instead of the usual (metric) differentiation. To attain this end, we write

$$(13.10) \quad \psi = -\phi.$$

It follows from (8.1), (8.5), (13.4) and (13.10) that

⁽⁸²⁾ A justification for this name depends upon a pictorial interpretation of E_{ij} which will appear elsewhere.

$$(13.11) \quad \psi_{;i} = -\phi_{;i}$$

$$(13.12) \quad \psi_{ij} = -\phi_{ij} - G^{hk}\psi_{;h}\psi_{;k}G_{ij},$$

where

$$(13.13) \quad \psi_{ij} = \psi_{;ij} - \psi_{;i}\psi_{;j}.$$

According to (7.3), (13.9), (13.10), (13.11) and (13.12), E_{ij} may be written as

$$(13.14) \quad E_{ij} = \psi_{ij} + \mu_{\alpha}G^{\alpha}_{ij} - \frac{1}{(m-2)}\rho_{\alpha\beta}G^{\alpha}_{i}G^{\beta}_{j} \\ + \frac{1}{2}[e^{2\psi}\mu^2 + G^{hk}\psi_{;h}\psi_{;k} + e^{2\psi}\rho/(m-1)(m-2)]G_{ij}.$$

From these equations and (9.7), we obtain

$$(13.15) \quad \psi_{ij} = E_{ij} + \frac{1}{(m-2)}{}^0\rho_{\alpha\beta}G^{\alpha}_{i}G^{\beta}_{j} - \frac{{}^0\rho}{2(m-1)(m-2)}G_{ij}.$$

Digression. The proof of the conformal character of E_{ij} which appears above does not depend upon the definition of ϕ given by equations (6.12) and (7.1). The only property of ϕ which is actually used is that stated in (8.7). Hence if χ is any other scalar which transforms so that $\sigma = \chi - \bar{\chi}$, a conformal tensor similar to E_{ij} may be constructed by replacing ϕ by χ in (13.9). However, this tensor is closely related to E_{ij} as we now show.

It follows from the transformation laws for ϕ and χ that

$$(13.16) \quad \chi = \phi + T$$

where T is a conformal scalar. Conversely, if T is any conformal scalar, χ may be defined by (13.16). We denote the conformal tensor obtained by replacing ϕ by χ in (13.9) by $E_{ij}(T)$. An easy calculation based upon (13.16) and the definitions of $E_{ij}(T)$ and E_{ij} leads to the equations

$$E_{ij}(T) = E_{ij} - T_{;ij} + T_{;i}T_{;j} + T_{;i}\phi_{;j} + T_{;j}\phi_{;i} \\ - g^{hk}T_{;h}[T_{;k} + 2\phi_{;k}]g_{ij}/2.$$

According to (8.1) and (8.5) (or by making replacements), these equations may be written as

$$(13.17) \quad E_{ij}(T) = E_{ij} - T_{;ij} + T_{;i}T_{;j} - G^{hk}T_{;h}T_{;k}G_{ij}/2.$$

Hence $E_{ij}(T)$ is the sum of E_{ij} and a tensor obtained by the classical method of covariant differentiation. We note that $E_{ij}(0) = E_{ij}$.

14. The conformal Riemann tensor of V_n . A conformal geometric object which plays the role of the Riemann curvature tensor relative to the surface measure tensor G_{ij} may be constructed if the Γ^i_{jk} are of class C^1 . This is true if (12.23) holds. It is defined at all points of V_n by the equations

$$(14.1) \quad K^i{}_{jkl} = \frac{\partial}{\partial x^k} \Gamma^i{}_{jl} - \frac{\partial}{\partial x^l} \Gamma^i{}_{jk} + \Gamma^h{}_{jl} \Gamma^i{}_{hk} - \Gamma^h{}_{jk} \Gamma^i{}_{hl}$$

and is called the *conformal Riemann tensor of V_n* or the *surface conformal Riemann tensor*. Since the $\Gamma^i{}_{jk}$ are Christoffel symbols, it follows easily that $K^i{}_{jkl}$ is a tensor with respect to parameter transformations. We also define the *conformal Ricci tensor of V_n* (*surface conformal Ricci tensor*) by the equations

$$(14.2) \quad K_{jk} = K^i{}_{jki}, \quad K^i{}_{\cdot k} = G^{ij} K_{jk}$$

and the *conformal curvature of V_n* (*surface conformal curvature*) by the equation

$$(14.3) \quad K = K_{ij} G^{ij}.$$

Of course, K_{jk} is a symmetric tensor and $K^i{}_{\cdot j}$ may be defined by the equations $K^i{}_{\cdot j} = K^i{}_{klj} G^{kl}$. If we write $K_{ijkl} = G_{hi} K^h{}_{jkl}$, it is a consequence of (14.1) that K_{ijkl} satisfies the identities

$$(14.4) \quad K_{ijkl} = -K_{jikl} = -K_{ijlk} = K_{klij}, \quad K_{i(jkl)+} = 0.$$

We also note that equations like those below (11.2) may be derived which are based upon (5.14), (8.5), (13.10) and (14.1). These equations are

$$\kappa_{ij} = K_{ij} + (n-2)\psi_{ij} + G_{ij} G^{hk} [\psi_{\cdot hk} + (n-2)\psi_{\cdot h\psi_{\cdot k}}]$$

where ψ_{ij} is defined by (13.13). From these equations and (7.10), (7.11) and (13.14), we obtain

$$(14.5) \quad \begin{aligned} \kappa_{ij} = K_{ij} + (n-2) & \left[E_{ij} - \mu_\alpha G^\alpha{}_{ij} + \frac{1}{(m-2)} \rho_{\alpha\beta} G^\alpha{}_{\cdot i} G^\beta{}_{\cdot j} \right] \\ & + G_{ij} \left[E + \frac{1}{(m-2)} \rho_{\alpha\beta} G^{\alpha\beta} - (n-1) e^{2\psi} \left(\mu^2 + \frac{\rho}{(m-1)(m-2)} \right) \right] \end{aligned}$$

where we have written

$$(14.6) \quad E = E_{ij} G^{ij}.$$

It follows from (14.5) that

$$(14.7) \quad \begin{aligned} {}^0\kappa_{ij} = K_{ij} + (n-2) & \left[E_{ij} + \frac{1}{(m-2)} {}^0\rho_{\alpha\beta} G^\alpha{}_{\cdot i} G^\beta{}_{\cdot j} \right] \\ & + G_{ij} \left[E + \frac{1}{(m-2)} {}^0\rho_{\alpha\beta} G^{\alpha\beta} - \frac{(n-1){}^0\rho}{(m-1)(m-2)} \right]. \end{aligned}$$

If we assume that

$$(14.8) \quad r \geq 5$$

the first derivatives of the K^h_{ijk} exist. In this case, by means of conformal geodesic parameters, the *Bianchi identities for the surface conformal Riemann tensor* may be derived following the proof in the metric case. These identities are

$$(14.9) \quad K^h_{i(jk:l)+} = 0.$$

From these equations, other results such as the equations

$$(14.10) \quad G^{ij}K_{il;j} = K_{;l}/2$$

which are analogous to (12.3) may be obtained.

Since, according to (7.3), the correspondence between the tensors G_{ij} and g_{ij} is a conformal one, the Weyl tensors formed with respect to G_{ij} and g_{ij} are each equal to W^h_{ijk} . Consequently, if $n > 2$, the equations analogous to (12.4) and (12.7) are

$$(14.11) \quad W^h_{i(jk:l)+} = \frac{1}{(n-2)} [G^h_{j+}K_{i(kl)+} + G_{ij+}K^h_{(lk)+}]$$

and

$$(14.12) \quad W^h_{ijk;l} = \frac{(n-3)}{(n-2)} K_{ijk}$$

where

$$(14.13) \quad K_{ijk} = K_{i(j:k)-} + \frac{1}{2(n-1)} \cdot K_{;(j}G_{k)-i}, \quad K^h_{jk} = G^h_{i}K_{ijk}.$$

15. Variation of the mean curvature normal. We assume that (5.13) is true. Then generalized covariant differentiation of (6.10) leads to the equations

$$(15.1) \quad G^{\alpha}_{ih;l} = g^{\alpha}_{h,il} - \mu^{\alpha}_{;l}g_{ih}.$$

Now the Ricci identities for this type of differentiation show that

$$g^{\alpha}_{h,(il)-} = g^{\alpha}_{jk^j h i l} - g^{\beta}_{hg^{\gamma}}g^{\delta}_{l\rho^{\alpha}}\rho^{\beta}_{\gamma\delta}.$$

If the value of $g^{\alpha}_{h,il}$ from these equations is substituted in (15.1) and the result is multiplied by g^{hl} and summed, we obtain

$$(15.2) \quad (n-1)\mu^{\alpha}_{;i} = g^{hl}G^{\alpha}_{ih;l} + g^{\alpha}h^k_{;i} + g^{\gamma}g^{\beta\delta}\rho^{\alpha}_{\beta\gamma\delta}$$

after simplification by means of (4.10), (5.6) and (5.14).

Now, according to the definitions which appear in (5.2) and (8.1) as well as (7.11), (8.5), (8.10), (8.11) and (13.10), it follows that

$$g^{hl}G^{\alpha}_{ih;l} = [G^{\alpha}_{ih;l} - (n-1)G^{\alpha}_{ih}\psi_{;l} + \mu_{\beta}G^{\beta}_{ih}g^{\alpha}_{;l}]g^{hl},$$

$$\mu^{\alpha}_{;i} = \mu^{\alpha}_{;i} - \mu^{\alpha}\psi_{;i} + \mu^2g^{\alpha}_{;i}.$$

To obtain these equations, use has also been made of the fact that both G^{α}_{ij} and μ^{α} are orthogonal to g^{α}_i . As a consequence of these equations, (15.2) is equivalent to

$$(15.3) \quad \begin{aligned} (n-1)\mu^{\alpha}_{:i} &= e^{-2\psi}G^{hl}[G^{\alpha}_{ih}{}_{:l} + (n-1)G^{\alpha}_{ih}\psi_{:l} - \mu_{\beta}G^{\beta}_{ih}G^{\alpha}_l] \\ &+ (n-1)\mu^2G^{\alpha}_i - (n-1)\mu^{\alpha}\psi_{:i} + G^{\alpha}_{hk}h_i \\ &+ e^{-2\psi}G^{\gamma}_iG^{\beta\delta}\rho^{\alpha}_{\beta\gamma\delta}. \end{aligned}$$

If assumption (5.13) is replaced by (12.23), we may substitute the value for κ_{ij} given by (14.5) in (15.3). If this is done and we then make use of (11.5) and (11.6), we obtain

$$(15.4) \quad \begin{aligned} (n-1)\mu^{\alpha}_{:i} &= e^{-2\psi}[G^{\alpha}_{ih}{}_{:l}G^{hl} + (n-1)G^{\alpha}_{ih}G^{hl}\psi_{:l} - (n-1)e^{2\psi}\mu^{\alpha}\psi_{:i} \\ &- (n-1)\mu_{\gamma}G^{\gamma}_{ih}G^{\alpha}_iG^{hl} + G^{\alpha}_{hk}K^h_i + (n-2)G^{\alpha}_hE^h_i \\ &+ G^{\alpha}_iE - C^{\alpha}_{\beta}G^{\beta}_i - ((n-1)/(m-2))H^{\alpha\beta}\rho_{\beta\gamma}G^{\gamma}_i]. \end{aligned}$$

These equations, or (15.2), or (15.3) describe the variation of μ^{α} . From (9.8) and (15.3), we find that

$$(15.5) \quad (n-1)^0\mu^{\alpha}_{:i} = G^{\alpha}_{ih}{}_{:l}G^{hl} + G^{\alpha}_{hk}{}^0K^h_i + G^{\gamma}_iG^{\beta\delta}{}^0\rho^{\alpha}_{\beta\gamma\delta}$$

and from (9.8) and (15.4), we obtain

$$(15.6) \quad \begin{aligned} (n-1)^0\mu^{\alpha}_{:i} &= G^{\alpha}_{ih}{}_{:l}G^{hl} + G^{\alpha}_{hk}K^h_i + (n-2)G^{\alpha}_hE^h_i + G^{\alpha}_iE \\ &- C^{\alpha}_{\beta}G^{\beta}_i - ((n-1)/(m-2)) \cdot H^{\alpha\beta}\rho_{\beta\gamma}G^{\gamma}_i. \end{aligned}$$

16. The conformal Riemann tensor of V_m . Since the space measure tensor $A_{\alpha\beta}$ is defined only on V_n , it is not possible to construct a Riemann curvature tensor relative to $A_{\alpha\beta}$ throughout V_m . A complete analogue does not even exist at points of V_n since $\partial\Gamma^{\alpha}_{\beta\gamma}/\partial\gamma^{\delta}$ is not defined. However, if (12.23) holds, the quantities $R^{\alpha}_{\beta jk}$ are defined on V_n by the equations

$$(16.1) \quad R^{\alpha}_{\beta jk} = G^{\delta}_k \frac{\partial}{\partial x^j} \Gamma^{\alpha}_{\beta\delta} - G^{\gamma}_j \frac{\partial}{\partial x^k} \Gamma^{\alpha}_{\beta\gamma} + [\Gamma^{\epsilon}_{\beta\delta}\Gamma^{\alpha}_{\epsilon\gamma} - \Gamma^{\epsilon}_{\beta\gamma}\Gamma^{\alpha}_{\epsilon\delta}]G^{\gamma}_iG^{\delta}_k.$$

Formally, $R^{\alpha}_{\beta jk}$ is equal to $R^{\alpha}_{\beta\gamma\delta}G^{\gamma}_jG^{\delta}_k$ where $R^{\alpha}_{\beta\gamma\delta}$ is the (non-existent) formal Riemann tensor constructed from the symbols $\Gamma^{\alpha}_{\beta\gamma}$. This leads to the conjecture that $R^{\alpha}_{\beta jk}$ is a tensor with respect to coordinate-parameter transformations. The correctness of this guess may be verified by a direct calculation or by other methods. We call $R^{\alpha}_{\beta jk}$ the *conformal Riemann tensor of V_m* or the *space conformal Riemann tensor*. We also define the *conformal Ricci tensor of V_m* (*space conformal Ricci tensor*) by the equations

$$(16.2) \quad R^{\alpha}_k = R^{\alpha}_{\beta jk}G^{\beta j}$$

and the *conformal curvature of V_m* (*space conformal curvature*) by the equation

$$(16.3) \quad R = R^{\alpha}_k G^k_{\alpha}.$$

If we write

$$(16.4) \quad \begin{aligned} R_{\alpha\beta jk} &= A_{\alpha\gamma} R^\gamma_{\beta jk}, & R_{\alpha k} &= A_{\alpha\beta} R^\beta_k, \\ R^{\alpha}_{ijk} &= R^{\alpha}_{\beta jk} G^\beta_i, & R_{jk} &= R_{\alpha k} G^\alpha_j, \\ R_{hijk} &= R_{\alpha\beta jk} G^\alpha_h G^\beta_i; \end{aligned}$$

it follows from (16.1) and (16.4) that

$$(16.5) \quad \begin{aligned} R_{\alpha\beta jk} &= -R_{\beta\alpha jk} = -R_{\alpha\beta kj}, \\ R^{\alpha}_{(ijk)^+} &= 0, \\ R_{hijk} &= -R_{ihjk} = -R_{hikj} = R_{jkhi}, \\ R_{h(ijk)^+} &= 0, \\ R_{ij} &= R_{hijk} G^{hk} = R_{ihkj} G^{hk}, & R_{ij} &= R_{ji}. \end{aligned}$$

These equations may be derived by direct calculation or by making use of the identities satisfied by the formal tensor $R^{\alpha}_{\beta\gamma\delta}$.

Assumption (14.8) guarantees the existence of $R^{\alpha}_{\beta jk:i}$. If we choose conformal geodesic coordinates and parameters at a point \mathcal{P} of V_n , differentiation of (16.1) at \mathcal{P} yields

$$\begin{aligned} R^{\alpha}_{\beta jk:i} &= G^\delta_k \frac{\partial^2}{\partial x^i \partial x^j} \Gamma^{\alpha}_{\beta\delta} - G^\gamma_j \frac{\partial^2}{\partial x^i \partial x^k} \Gamma^{\alpha}_{\beta\gamma} \\ &\quad + G^\delta_{ki} \frac{\partial}{\partial x^j} \Gamma^{\alpha}_{\beta\gamma} - G^\gamma_{ji} \frac{\partial}{\partial x^k} \Gamma^{\alpha}_{\beta\gamma}. \end{aligned}$$

From this result and similar equations, we obtain $R^{\alpha}_{\beta(jk:i)^+} = 0$ at \mathcal{P} . It is clear that these equations hold in all coordinate-parameter systems and at all points of V_n . They are the *Bianchi identities for the conformal Riemann tensor of V_m* .

It is possible to express $R^{\alpha}_{\beta jk}$ in terms of other tensors which have already been defined. To simplify the calculations, we choose conformal geodesic coordinates at a point \mathcal{P} of V_n . Since (16.1) are conformal equations, the replacement principle may also be employed. It follows from (9.9) that the coordinates are geodesic at \mathcal{P} , that is,

$$\left\{ \begin{array}{l} \alpha \\ \beta\gamma \end{array} \right\} = 0$$

at \mathcal{P} . However, the results obtained are true in all coordinate-parameter systems and at all points of V_n . Now (16.1) becomes

$$R^{\alpha}_{\beta jk} = G^\delta_k \left(\frac{\partial}{\partial x^j} \Gamma^{\alpha}_{\beta\delta} \right) - G^\gamma_j \left(\frac{\partial}{\partial x^k} \Gamma^{\alpha}_{\beta\gamma} \right).$$

According to (8.11) and (9.7) this may be written as

$$(16.6) \quad R^{\alpha}_{\beta jk} = G^{\gamma}_j G^{\delta}_k \left[\frac{\partial}{\partial y^{\gamma}} \left\{ \begin{matrix} \alpha \\ \beta \delta \end{matrix} \right\} - \frac{\partial}{\partial y^{\delta}} \left\{ \begin{matrix} \alpha \\ \beta \gamma \end{matrix} \right\} \right] + G^{\alpha}_k {}^0\eta_{\beta: k} \\ - G^{\alpha}_j {}^0\eta_{\beta: k} - G_{\beta k} A^{\alpha\epsilon} {}^0\eta_{\epsilon: j} + G_{\beta j} A^{\alpha\epsilon} {}^0\eta_{\epsilon: k}.$$

To obtain these equations, we have made use of the fact that ${}^0\eta_{\gamma:k} G^{\gamma}_j$ is symmetric in the indices j, k . To prove this we note that conformal differentiation of $\eta_{\gamma} G^{\gamma}_j = -\psi_{:j}$ gives, using (8.15),

$$\eta_{\gamma:k} G^{\gamma}_j + \eta_{\gamma} G^{\gamma}_{jk} = -\psi_{:jk}.$$

Since $\psi_{:jk}$ and G^{γ}_{jk} are symmetric in the lower indices this is also true for $\eta_{\gamma:k} G^{\gamma}_j$ and hence for ${}^0\eta_{\gamma:k} G^{\gamma}_j$.

Now from (8.8), (8.10), (13.10), (9.7) and (9.8), ${}^0\eta_{\beta:j} = {}^0\mu_{\beta:j} - {}^0(\psi_{hk}) G^h_{\beta}$. As a consequence of (13.15), (14.7) and (15.5), the above equations become

$$(16.7) \quad (n-1) {}^0\eta_{\beta:j} = A_{\epsilon\beta} G^{\epsilon}_{jh} G^{hi} + G^{\gamma}_j G^{\delta\epsilon} {}^0\rho_{\beta\epsilon\gamma\delta} \\ + G^h_{\beta} [K_{hj} - E_{hj} + EG_{hj} - (1/(m-2)) {}^0\rho_{\epsilon\gamma} G^{\epsilon}_h G^{\gamma}_j \\ + (1/(m-2)) {}^0\rho_{\epsilon\gamma} G^{\epsilon\gamma} G_{hj} \\ - ((n-1) {}^0\rho/2(m-1)(m-2)) G_{hj}].$$

Since the coordinates are geodesic, (5.14) shows that

$${}^0\rho^{\alpha}_{\beta\gamma\delta} = \frac{\partial}{\partial y^{\gamma}} \left\{ \begin{matrix} \alpha \\ \beta \delta \end{matrix} \right\} - \frac{\partial}{\partial y^{\delta}} \left\{ \begin{matrix} \alpha \\ \beta \gamma \end{matrix} \right\}.$$

If this result and (16.7) are substituted in (16.6), after some simplification we obtain

$$(16.8) \quad R^{\alpha}_{\beta jk} = \left\{ C^{\alpha}_{\beta\gamma\delta} + \frac{1}{(n-1)} [A^{\alpha}_{(\gamma} C_{\delta)-\beta} + C^{\alpha}_{(\gamma} A_{\delta)-\beta}] \right\} G^{\gamma}_j G^{\delta}_k \\ + \frac{1}{(n-1)} \{ E^l_{k-} [G^{\alpha}_j G_{\beta l} - G^{\alpha}_l G_{\beta j-}] + 2EG^{\alpha}_k G_{\beta j-} \} \\ + \frac{1}{(n-1)} \cdot K^l_{j-} [G^{\alpha}_k G_{\beta l} - G^{\alpha}_l G_{\beta k-}] \\ + \frac{G^{\sigma l}}{(n-1)} [A_{\beta\gamma} G^{\alpha}_{(k} G^{\gamma}_{j)-\sigma: l} + G_{\beta(i} G^{\alpha}_{k)-\sigma: l}]$$

where we have written $E^i_j = G^{hi} E_{hj}$ and have also used the definitions stated in (11.5) and (11.8).

It is shown in §22 that (16.8) may be simplified by means of the conformal analogues of the Gauss equations⁽²³⁾ and written as

⁽²³⁾ The "conformal Frenet equations" (20.7) and the "derived condition" (21.9) with $w = 1$ are also used in this derivation.

$$(16.9) \quad R^{\alpha}_{\beta jk} = D^{\alpha}_{\beta jk} + E^l_{\cdot k} [G^{\alpha}_{\cdot j} G_{\beta l} - G^{\alpha}_{\cdot l} G_{\beta j}] \\ \cdot \frac{G^{\sigma l}}{(n-1)} [H^{\alpha}_{\cdot \gamma} G_{\beta(\cdot j} G^{\gamma}_{k)\cdot \sigma} \cdot l + H_{\gamma \beta} G^{\alpha}_{\cdot (k} G^{\gamma}_{j)\cdot \sigma} \cdot l]$$

where $D^{\alpha}_{\beta jk}$ is defined by (11.18). This expression does not involve K_{ij} . From these equations and (16.2), (16.3) and (16.4) as well as (4.12), (11.8), (11.10) and (11.11), we find that

$$(16.10) \quad R^{\alpha}_{ijk} = D^{\alpha}_{ijk} + G^{\alpha}_{\cdot (j} E_{k)\cdot i} + G^{\alpha}_{\cdot l} E^l_{\cdot (j} G_{k)\cdot i} \\ + (1/(n-1)) G^{\sigma l} H^{\alpha}_{\cdot \gamma} G_{i(\cdot j} G^{\gamma}_{k)\cdot \sigma} \cdot l,$$

$$(16.11) \quad R_{hijk} = C_{hijk} + G_{h(\cdot j} E_{k)\cdot i} + G_{i(\cdot k} E_{j)\cdot h},$$

$$(16.12) \quad R^{\alpha}_{\cdot k} = C_{\beta k} G^{\beta \alpha} - (n-2) G^{\alpha}_{\cdot l} E^l_{\cdot k} - EG^{\alpha}_{\cdot k} + G^{\sigma l} H^{\alpha}_{\cdot \gamma} G^{\gamma}_{k\sigma} \cdot l,$$

$$(16.12) \quad R_{jk} = C_{jk} - (n-2) E_{jk} - EG_{jk},$$

$$R = C - 2(n-1)E.$$

If $n > 2$, we may apply the \uparrow operation with respect to G_{ij} to (16.11). From (11.27) and (11.28),

$$(16.13) \quad \uparrow C_{hijk} = \uparrow R_{hijk}$$

where, in accordance with (11.25),

$$(16.14) \quad \uparrow C_{hijk} = C_{hijk} + \frac{1}{(n-2)} [G_{h(\cdot j} C_{k)\cdot i} + G_{i(\cdot k} C_{j)\cdot h}] \\ + \frac{C}{(n-1)(n-2)} G_{h(\cdot k} G_{j)\cdot i},$$

$$(16.15) \quad \uparrow R_{hijk} = R_{hijk} + \frac{1}{(n-2)} [G_{h(\cdot j} R_{k)\cdot i} + G_{i(\cdot k} R_{j)\cdot h}] \\ + \frac{R}{(n-1)(n-2)} G_{h(\cdot k} G_{j)\cdot i}.$$

Each member of these equations is formed in a manner exactly analogous to that used in the construction of the Weyl tensor W_{hijk} .

Finally, we note that $R_{\alpha\beta jk}$ is defined if $\Gamma^{\alpha}_{\beta\gamma}$ is of class C^1 in the x^i . Also, if the Γ^i_{jk} exist and $r \geq 3$,

$$\left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\}, \quad \left\{ \begin{matrix} i \\ jk \end{matrix} \right\}$$

are of class C^1 . It is readily found from (8.5) and (8.11) that $\phi_{\cdot i}$ and η_{α} exist and are of class C^1 . Hence Γ^i_{jk} are also of class C^1 . Since Γ^i_{jk} and $\Gamma^{\alpha}_{\beta\gamma}$ exist, it follows from (8.4) that they are of class C^1 . It is then found that all the work of this section is valid. This shows that if $\Gamma^{\alpha}_{\beta\gamma}$ is of class C^1 and $r \geq 3$ then $R_{\alpha\beta jk}$, $\bar{R}_{\alpha\beta jk}$ exist and (16.9) are valid.

17. The Ricci identities. The equality of the differential operators $\partial^2/\partial x^i \partial x^j$ and $\partial^2/\partial x^j \partial x^i$ may be conveniently expressed in terms of covariant differentiation based upon the coefficients of connection⁽³⁴⁾ $\Gamma^\alpha_{\beta\gamma}$, Γ^i_{jk} . By direct calculation⁽³⁵⁾ using the definitions which appear in (8.1), (14.1) and (16.1), we obtain

$$(17.1) \quad \begin{aligned} \pi^\alpha_{:(jk)^-} &= -\pi^\beta R^\alpha_{\beta jk}, \\ \pi^\alpha_{i:(jk)^-} &= \pi^\alpha_h K^h_{ijk} - \pi^\beta_i R^\alpha_{\beta jk}. \end{aligned}$$

Similar equations for more complicated tensors are also valid. These tensor equations are the *Ricci identities*. They are used frequently in the sequel to express the integrability conditions of the various partial differential equations which occur in our work.

IV. THE CONFORMAL VECTOR SPACES OF V_n

The purpose of this chapter is to define the various osculating and normal conformal vector spaces of V_n . Associated with these vector spaces are certain important tensors analogous to the "mass tensors" of the metric theory. As in the metric case, a system of Frenet equations is obtained which describes the variation of the vector spaces. The entire development is accomplished without any recourse to beins which span the various vector spaces. A similar theory, which utilizes vector beins, may be developed by our methods. The results of this latter theory are undoubtedly useful for the solution of various special problems which depend upon particular vector beins. The motivation behind our present work is to avoid the introduction of any elements (such as bein indices) which are extraneous to the purely geometric questions which are considered here. The comparable development of the metric theory (at least for spaces of constant curvature) has been given by Mayer [10].

18. The conformal osculating and normal vector spaces of V_n . At an arbitrary point \mathcal{P} of V_n , the space vectors

$$(18.1) \quad G^\alpha_i$$

span an n -dimensional vector space in accordance with §4 (d). As previously defined, this space is called the *tangent vector space* of V_n . Since (18.1) is a conformal geometric object, we also name the space the *first conformal osculating vector space* of V_n and denote it by the symbol I_1 .

Suppose

$$(18.2) \quad x'^i = x'^i(x^j), \quad x^i = x^i(x'^j)$$

⁽³⁴⁾ No assumption is made that Γ^i_{jk} , $\Gamma^\alpha_{\beta\gamma}$ have the meaning given them by equations (8.5) and (8.11) respectively. The quantities Γ^i_{jk} , $\Gamma^\alpha_{\beta\gamma}$ may be any surface and space coefficients of connection and K^h_{ijk} , $R^\alpha_{\beta jk}$ are the tensors defined in terms of Γ^i_{jk} , $\Gamma^\alpha_{\beta\gamma}$ by equations (14.1) and (16.1) respectively.

⁽³⁵⁾ These calculations may be simplified by choosing coordinates and parameters which are geodesic with respect to Γ^i_{jk} , $\Gamma^\alpha_{\beta\gamma}$.

is an allowable parameter transformation. The symbols which denote geometric objects in the parameter system $\{x'^i\}$ are written with primes to distinguish them from the corresponding symbols in the parameter system $\{x^i\}$. Then

$$G'^{\alpha_i} = G^{\alpha_j} \partial x^j / \partial x'^i, \quad G^{\alpha_i} = G'^{\alpha_j} \partial x'^j / \partial x^i.$$

Consequently $I_1 \equiv I'_1$ and the tangent vector space does not depend upon the parameterization of V_n .

The *second conformal osculating vector space* I_{12} of V_n at \mathcal{P} is defined as the totality of space vectors at \mathcal{P} which are spanned linearly by the space vectors G^{α_i} , $G^{\alpha_{i;j}}$. It is immediate that this vector space is unchanged by conformal transformations of V_m . It is also invariant under parameter changes as can be seen from the transformation law between $G^{\alpha_{i;j}}$ and $G'^{\alpha_{i;j}}$. This law as well as the one connecting G^{α_i} and G'^{α_i} which appears above are special cases of the general formula

$$(18.3) \quad \begin{aligned} G'^{\alpha_{i_1; i_2 \dots i_w}} &= G^{\alpha_{j_1; j_2 \dots j_w}} \frac{\partial x^{j_1}}{\partial x'^{i_1}} \cdots \frac{\partial x^{j_w}}{\partial x'^{i_w}} + \sum_{v=1}^{w-1} G^{\alpha_{j_1; j_2 \dots j_v}} (\cdots), \\ G^{\alpha_{i_1; i_2 \dots i_w}} &= G'^{\alpha_{j_1; j_2 \dots j_w}} \frac{\partial x'^{j_1}}{\partial x^{i_1}} \cdots \frac{\partial x'^{j_w}}{\partial x^{i_w}} + \sum_{v=1}^{w-1} G'^{\alpha_{j_1; j_2 \dots j_v}} (\cdots). \end{aligned}$$

The *wth conformal osculating vector space* $I_{12 \dots w}$ of V_n at \mathcal{P} is defined as the totality of space vectors at \mathcal{P} which are spanned linearly by the space vectors $G^{\alpha_{i_1}}$, $G^{\alpha_{i_1; i_2}}$, \dots , $G^{\alpha_{i_1; i_2 \dots i_w}}$. The invariance of $I_{12 \dots w}$ with respect to parameter changes is a consequence of (18.3). Of course, $I_{12 \dots w}$ is invariant with respect to coordinate transformations. Its conformal character follows from its definition and the properties of conformal differentiation. The osculating spaces are so defined that $I_{12 \dots w}$ contains $I_{12 \dots w-1}$.

Since orthogonality is a conformal geometric property, the set of space vectors belonging to $I_{12 \dots w}$ which are normal to $I_{12 \dots w-1}$ form a conformal linear vector space I_w . We call I_w the $(w-1)$ th *conformal normal vector space* of V_n at \mathcal{P} . According to this definition, I_w is the vector space which is spanned by the projection of $G^{\alpha_{i_1; i_2 \dots i_w}}$ into the vector space which is orthogonal to $I_{12 \dots w-1}$. We denote this projection⁽⁸⁾ of $G^{\alpha_{i_1; i_2 \dots i_w}}$ by $G^{\alpha_{i_1 i_2 \dots i_w}}$. Of course $G^{\alpha_{i_1 i_2 \dots i_w}}$ is a conformal geometric object. It transforms as a contravariant vector with respect to coordinate transformations. It follows from (18.3) that

$$\begin{aligned} G'^{\alpha_{i_1 i_2 \dots i_w}} &= G^{\alpha_{j_1 j_2 \dots j_w}} \frac{\partial x^{j_1}}{\partial x'^{i_1}} \cdots \frac{\partial x^{j_w}}{\partial x'^{i_w}}, \\ G^{\alpha_{i_1 i_2 \dots i_w}} &= G'^{\alpha_{j_1 j_2 \dots j_w}} \frac{\partial x'^{j_1}}{\partial x^{i_1}} \cdots \frac{\partial x'^{j_w}}{\partial x^{i_w}}. \end{aligned}$$

Consequently $G^{\alpha_{i_1 i_2 \dots i_w}}$ transforms like a covariant surface tensor of the *wth*

(8) The projection tensor of I_w should be defined relative to $A_{\alpha\beta}$ and is a conformal tensor.

order under changes of parameter. Using the notation of §1, we frequently write $G^{\alpha_{i_1 i_2 \dots i_w}}$ as $G^{\alpha_{(i_w)}}$.

The construction of successive osculating vector spaces continues to lead to new spaces until we reach an osculating space $I_{12 \dots M}$ which has the property

$$(18.4) \quad I_{12 \dots M} \neq I_{12 \dots M-1}, \quad I_{12 \dots M+1} = I_{12 \dots M}.$$

It follows from (18.4) that

$$I_{12 \dots M+u} = I_{12 \dots M}$$

if $u \geq 0$. Consequently we call $I_{12 \dots M}$ the *last conformal osculating vector space* of V_n . It is clear from these remarks and the various definitions that

$$(18.5) \quad I_w \neq 0, \quad w \leq M,$$

$$(18.6) \quad I_{M+1} \equiv 0,$$

that is, I_{M+1} is the first empty space. Each succeeding normal vector space also has dimension zero.

We denote the dimension of I_w , which is identical with the rank of the matrix $\|G^{\alpha_{(i_w)}}\|$ by N_w . Then the dimension $N_{12 \dots w}$ of $I_{12 \dots w}$ is equal to

$$(18.7) \quad N_{12 \dots w} = N_1 + N_2 + \dots + N_w.$$

Of course, $N_1 = n$. Equations (18.5) are equivalent to

$$(18.8) \quad N_w > 0, \quad w \leq M$$

and (18.6) to $N_{M+1} = 0$. The existence of an integer M for which (18.6) holds follows from (18.7), (18.8) and the inequalities

$$(18.9) \quad N_{12 \dots w} \leq m.$$

Of course, (18.9) is true because the osculating vector spaces all lie in V_m .

It is clear that (18.6) is equivalent to

$$(18.10) \quad G^{\alpha_{(i_{M+1})}} = 0.$$

The space vectors

$$(18.11) \quad G^{\alpha_{i_1}}, G^{\alpha_{(i_2)}}, \dots, G^{\alpha_{(i_M)}}$$

constitute a *basis* for the conformal osculating spaces and conformal normal spaces of V_n . We note that if $r \geq 3$, each successive *conformal basis* *bein* $G^{\alpha_{(i_w)}}$ exists if the preceding basis *bein* $G^{\alpha_{(i_{w-1})}}$ exists and is of class⁽²⁷⁾ C^1 . A suffi-

(27) In making this statement, we are thinking of an alternative method of development of this section. In this other method, we first define the vector spaces I_1, I_2, \dots, I_w and afterwards define $I_{12 \dots w}$ as the linear vector space spanned by the vectors of I_1, I_2, \dots, I_w . The normal vector space I_w is defined as the linear vector space which is spanned by the space vectors $G_{i_{w-1} i_w}$ which are normal to $I_{12 \dots w-1}$.

cient but not necessary condition that all the beins of the basis (18.11) exist and be of class C^1 is that the inequality

$$(18.12) \quad r \geq M + 1$$

be true. If each bein of (18.11) is of class C^s , we say that (18.11) is a *basis of class C^s* . We also remark that if the basis beins $G^\alpha_{(i_w)}$ exist and are of class C^1 in a V_n with $r \geq 3$, then the corresponding basis beins $\bar{G}^\alpha_{(i_w)}$ in any \bar{V}_n obtained by an allowable conformal transformation of the enveloping V_m exist and are equal to the $G^\alpha_{(i_w)}$.

Simply as a matter of convenient notation and without further significance, we agree to write I_∞ for the vector space which is orthogonal to all the conformal osculating vector spaces of V_n . We write $G^\alpha_{(i_\infty)}$ for any set of space vectors which span I_∞ . Hence

$$(18.13) \quad A_{\alpha\beta} G^\alpha_{(i_w)} G^\beta_{(i_\infty)} = 0, \quad w \leq M.$$

If we write N_∞ for the dimension number of I_∞ , it follows that $N_1 + N_2 + \dots + N_M + N_\infty = m$.

19. The conformal normal measure tensors. Any space vector L^α which lies entirely in the tangent vector space of V_n may be written as

$$(19.1) \quad L^\alpha = G^\alpha_i L^i.$$

The surface vector L^i is the parameter representation of L^α . Similarly, if X^α is any space vector which lies entirely in I_w ($w \leq M$), it has a representation of the form

$$(19.2) \quad X^\alpha = G^\alpha_{(i_w)} X^{(i_w)}.$$

It is clear that the quantities $X^{(i_w)}$ which appear in this parameter representation of X^α behave like the components of a contravariant surface tensor of the w th order with respect to parameter transformations. The conformal basis beins $G^\alpha_{(i_w)}$ enjoy various symmetry properties in the covariant indices i_1, i_2, \dots, i_w which are derived in §27. The components of $X^{(i_w)}$ may be assumed to have these same symmetry properties without loss of generality. We denote the number of different components of $X^{(i_w)}$ by N'_w .

In general, if $w > 1$ the space vectors $G^\alpha_{(i_w)}$ are not linearly independent. Consequently the null vector also has a representation in I_w of the form

$$(19.3) \quad 0 = G^\alpha_{(i_w)} \theta^{(i_w)}$$

where not all the components of $\theta^{(i_w)}$ vanish. We call $\theta^{(i_w)}$ a *null tensor* or a *null solution*. The number of linearly independent solutions of (19.3) is $N'_w - N_w$. In the representation of X^α which appears in (19.2), the tensor $X^{(i_w)}$ is determined up to an additive null solution $\theta^{(i_w)}$ of equations (19.3). We call any of these tensors $X^{(i_w)}$ a *contravariant (parameter) representation* of the vector X^α .

An analogous representation for the covariant vector X_α which corresponds to X^α may be defined by the equations

$$(19.4) \quad X_{(i_w)} = X_\alpha G^\alpha_{(i_w)}.$$

The $X_{(i_w)}$ are the components of a covariant surface tensor of the w th order. We call $X_{(i_w)}$ the *covariant (parameter) representation* of the vector X_α . In contrast to the tensor $X^{(i_w)}$ which, in general, is not uniquely determined by X^α , the covariant representation $X_{(i_w)}$ is completely fixed by X_α . On the other hand, the contravariant representation tensors may be chosen arbitrarily while the covariant $X_{(i_w)}$ are subject to the algebraic condition

$$X_{(i_w)}\theta^{(i_w)} = 0$$

for all null tensors $\theta^{(i_w)}$. This condition is a consequence of (19.4) and is a necessary and sufficient condition that quantities $X_{(i_w)}$ be the components of a covariant representation tensor.

Similar considerations apply to any vector Y^α which lies in $I_{12\dots w}$. Any such vector has a representation of the form

$$Y^\alpha = \sum_{u=1}^w G^\alpha_{(i_u)} Y^{(i_u)}.$$

The $Y^{(i_u)}$ are contravariant surface tensors of order u which are determined except for additive null solutions $\theta^{(i_u)}$ of the equations

$$G^\alpha_{(i_u)}\theta^{(i_u)} = 0, \quad u = 1, 2, \dots, w.$$

Indeed each tensor $Y^{(i_u)}$ is readily seen to be the contravariant representation of the projection of Y^α in I_u . In the same way Y_α which corresponds to Y^α determines the covariant surface tensors $Y_{(i_u)}$ ($u = 1, 2, \dots, w$) by means of the equations

$$Y_{(i_u)} = Y_\alpha G^\alpha_{(i_u)}, \quad u = 1, 2, \dots, w.$$

As in the contravariant case, $Y_{(i_u)}$ is the covariant representation of the projection of Y_α in I_u .

According to (7.8) and (19.2), the conformal length of X^α lying entirely in I_w , is given by

$$(19.5) \quad A_{\alpha\beta}X^\alpha X^\beta = A_{\alpha\beta}G^\alpha_{(i_w)}G^\beta_{(h_w)}X^{(i_w)}X^{(h_w)}.$$

Consequently, if we use the surface representation $X^{(i_w)}$ of X^α , conformal length of vectors in I_w may be measured by the covariant surface tensor of order $2w$ whose components are defined by the equations

$$(19.6) \quad B_{(i_w)|(h_w)} = A_{\alpha\beta}G^\alpha_{(i_w)}G^\beta_{(h_w)}.$$

If $w=1$, $B_{i|h} = G_{ih}$. If $w>1$, we call $B_{(i_w)|(h_w)}$ the $(w-1)$ th conformal normal measure tensor of V_n . It is symmetric in the two blocks of indices (i_w) , (h_w)

taken as units. According to (19.6), *the conformal normal measure tensors remain unchanged by conformal transformations of V_m* . It follows from (19.2), (19.4) and (19.6) that the contravariant and covariant representations of X^α are related by the equations

$$X^{(i_w)} = B_{(i_w)|(h_w)} X^{(h_w)}.$$

Similar results may be obtained for vectors Y^α in $I_{12 \dots w}$.

From (19.3) and (19.6), it follows that if $\theta^{(i_w)}$ is a solution of (19.3) then

$$(19.7) \quad B_{(i_w)|(h_w)} \theta^{(i_w)} = 0$$

so that every null solution of (19.3) is also a null solution of (19.7). Conversely, if $\theta^{(i_w)}$ is a null solution of (19.7), it follows from (19.6) and (19.7) that

$$A_{\alpha\beta} [G^\alpha_{(i_w)} \theta^{(i_w)}] [G^\alpha_{(h_w)} \theta^{(h_w)}] = 0.$$

Since $A_{\alpha\beta}$ is positive definite, (19.3) is true. Hence the solutions of (19.3) and (19.7) coincide. This means that the ranks of the matrices⁽⁸⁸⁾

$$\|G^\alpha_{(i_w)}\| \quad \text{and} \quad \|B_{(i_w)|(h_w)}\|$$

are equal. Consequently, *the dimension N_w of I_w is equal to the "rank" of the normal measure tensor $B_{(i_w)|(h_w)}$* .

We also note that as a consequence of (19.5) and (19.6) and the positive definite character of $A_{\alpha\beta}$,

$$B_{(i_w)|(h_w)} X^{(i_w)} X^{(h_w)} \geq 0,$$

where $X^{(i_w)}$ is any contravariant surface tensor of the w th order. The equality sign holds only if $X^{(i_w)}$ is a null tensor and this is possible only if $w > 1$. This means that the conformal measure tensor G_{ij} is positive definite and that the conformal normal measure tensors are positive semi-definite.

The above discussion shows that the conformal measure tensors

$$(19.8) \quad B_{i_1|h_1} (= G_{i_1 h_1}), B_{(i_2)|(h_2)}, \dots, B_{(i_M)|(h_M)}$$

are a system of surface tensors which are used to measure the conformal length of vectors which lie in the conformal osculating or normal vector spaces of V_n . In a later chapter, we show that *if V_m is a conformally euclidean space \bar{R}_m , these conformal measure tensors (19.8) together with the deviation tensor E_{ih} completely determine the subspace V_n except for a conformal transformation of \bar{R}_m* .

As in the metric theory, we may base the conformal theory of V_n on tensors constructed by symmetrizing the measure tensors. We define the surface tensor $G_{(i_w)|(h_w)}$ ($w = 1, 2, \dots, M$) as the tensor of order $2w$, symmetric in all its $2w$ indices, which obeys the equations

⁽⁸⁸⁾ In the matrix $\|B_{(i_w)|(h_w)}\|$, each row corresponds to a definite sequence of i -indices (i_w) and each column to a definite sequence of h -indices (h_w).

$$(19.9) \quad B_{(i_w)(h_w)} X^{i_1} \cdots X^{i_w} X^{h_1} \cdots X^{h_w} = G_{(i_w)(h_w)} X^{i_1} \cdots X^{i_w} X^{h_1} \cdots X^{h_w}.$$

We call the symmetric covariant surface tensors

$$(19.10) \quad G_{i_1 h_1}, G_{(i_2)(h_2)}, \cdots, G_{(i_M)(h_M)}, E_{i_h}$$

the *first, second, . . . , Mth, (M + 1)th conformal fundamental tensors* of V_n and we name the differential forms

$$(19.11) \quad G_{i_1 h_1} dx^{i_1} dx^{h_1}, \cdots, G_{(i_M)(h_M)} dx^{i_1} \cdots dx^{i_M} dx^{h_1} \cdots dx^{h_M}, E_{i_h} dx^i dx^h$$

the *first, second, . . . , Mth, (M + 1)th conformal fundamental forms* of V_n . A comparison of coefficients in (19.9) shows that

$$(19.12) \quad (2w)! G_{(i_w)(h_w)} = \sum B_{(i_w)(k_w)}$$

where the indices $(j_w), (k_w)$ in the summation assume all possible $(2w)!$ permutations of $(i_w), (h_w)$. According to the concluding remarks of §18 and the definitions of this section, both the measure tensors and fundamental tensors (except E_{i_h}) exist and are of class C^1 if the basis of the conformal osculating vector spaces is of class C^1 in a V_n of class C^r with $r \geq 3$. Under the same hypothesis, if E_{i_h} exists in V_n , then all the measure tensors and fundamental tensors also exist in any conformally equivalent subspace \bar{V}_n . Also, as noted in §13, E_{i_h} exists if (12.23) holds and hence is of class C^1 if (14.8) is true. We summarize some of the results of this section in the following theorem.

THEOREM 19.1. *If the conformal osculating vector spaces of a V_n of class C^r ($r \geq 3$) have a basis of class C^1 and the deviation tensor E_{i_h} is of class C^1 , then the conformal measure tensors of V_n and the conformal fundamental tensors of V_n exist and are of class C^1 . If $V_m \rightleftharpoons \bar{V}_m, V_n \rightleftharpoons \bar{V}_n$ by an allowable conformal map, then the conformal measure tensors and conformal fundamental tensors of \bar{V}_n exist and, at corresponding points of V_n and \bar{V}_n , the corresponding tensors of V_n and \bar{V}_n are equivalent.*

The equivalence of corresponding tensors of V_n and \bar{V}_n means that these tensors are *equal* if the parameters on V_n and \bar{V}_n are chosen so that $x^i = \bar{x}^i$ at corresponding points.

20. The conformal Frenet equations. We suppose that the inequalities (5.13) hold so that conformal differentiation is possible. In order to derive a system of Frenet equations it is also necessary that the space vectors of the basis (18.11) of the conformal osculating spaces of V_n exist and be of class C^1 . As already noted, this last condition is satisfied if (18.12) is true. In what follows, we derive a system of partial differential equations for the quantities

$$(20.1) \quad \gamma^\alpha(x^i), G^\alpha_{i_1}, G^\alpha_{(i_2)}, \cdots, G^\alpha_{(i_M)}, \mu^\alpha, \psi, \psi_i.$$

Here ψ_i is a symbol for $\partial\psi/\partial x^i$. It will be convenient to write these equations so that the left member of each of the equations is a conformal derivative of one of the quantities (20.1).

According to the definition of $G^{\alpha_{i_1}}$ and (8.15), the first two sets of equations may be written as

$$(20.2) \quad \begin{aligned} y^{\alpha_{i_1}} &= G^{\alpha_{i_1}}, \\ G^{\alpha_{i_1}; i_2} &= G^{\alpha_{(i_2)}}. \end{aligned}$$

We now derive the w th set of equations of this system. The definition of $G^{\alpha_{(i_w)}}$ implies that it differs from $G^{\alpha_{i_1; i_2 \dots i_w}}$ by a vector in $I_{12 \dots w-1}$, that is,

$$(20.3) \quad G^{\alpha_{(i_w)}} \equiv G^{\alpha_{i_1; i_2 \dots i_w}} \pmod{I_{12 \dots w-1}}.$$

By conformal differentiation, we obtain $G^{\alpha_{(i_w); i_{w+1}}} \equiv G^{\alpha_{i_1; i_2 \dots i_{w+1}}} \pmod{I_{12 \dots w}}$. The analogue of (20.3) for $G^{\alpha_{(i_{w+1})}}$ permits us to write the last equations as

$$G^{\alpha_{(i_w); i_{w+1}}} \equiv G^{\alpha_{(i_{w+1})}} \pmod{I_{12 \dots w}}.$$

These equations may be written as

$$(20.4) \quad \begin{aligned} G^{\alpha_{(i_w); i_{w+1}}} &= G^{\alpha_{(i_{w+1})}} + U^{(i_w)}_{(i_{w+1})} G^{\alpha_{(j_w)}} \\ &+ U^{(i_{w-1})}_{(i_{w+1})} G^{\alpha_{(j_{w-1})}} + \dots + U^{i_1}_{(i_{w+1})} G^{\alpha_{j_1}}. \end{aligned}$$

Since

$$(20.5) \quad A_{\alpha\beta} G^{\alpha_{(i_w)}} G^{\beta_{(h_v)}} = 0, \quad w \neq v,$$

we find, by conformal differentiation, that

$$(20.6) \quad A_{\alpha\beta} G^{\beta_{(h_v)}} G^{\alpha_{(i_w); i_{w+1}}} = -A_{\alpha\beta} G^{\alpha_{(i_w)}} G^{\beta_{(h_v); i_{w+1}}}.$$

As a consequence of (20.4), $G^{\beta_{(h_v); i_{w+1}}}$ is a vector of $I_{12 \dots v+1}$. Hence if $v = 1, 2, \dots, w-2$, it follows from (20.5) that the left member of (20.6), and therefore the right member of (20.6), vanishes. This fact together with (19.6) and (20.4) leads to

$$U^{(h_v)}_{(i_{w+1})} B_{(h_v) | (k_v)} = 0, \quad v = 1, 2, \dots, w-2,$$

which, according to §19, is equivalent to

$$U^{(h_v)}_{(i_{w+1})} G^{\alpha_{(h_v)}} = 0, \quad v = 1, 2, \dots, w-2.$$

Hence (20.4) becomes

$$(20.7) \quad \begin{aligned} G^{\alpha_{(i_w); i_{w+1}}} &= G^{\alpha_{(i_{w+1})}} + U^{(h_w)}_{(i_{w+1})} G^{\alpha_{(h_w)}} + U^{(h_{w-1})}_{(i_{w+1})} G^{\alpha_{(h_{w-1})}}, \\ &w = 0, 1, 2, \dots, M. \end{aligned}$$

We have included (20.2) and the case $w = M$ in (20.7) by means of the conventions

$$(20.8) \quad \begin{aligned} G^{\alpha_{(i_0)}} &= y^{\alpha}, U^{\dots (i_1)} = U^{\dots (i_2)} = U^{\dots (i_{M+2})} = U^{(i_{M+1})} \dots = 0, \\ G^{\alpha_{(i_{M+1})}} &= 0. \end{aligned}$$

The last set of these equations is simply (18.10). Equations (20.7) are called

the conformal Frenet equations of V_n . It is clear that if these equations exist for V_n in V_m they are also valid for the \bar{V}_n in \bar{V}_m obtained by means of any allowable conformal mapping. The quantities $U_{(i_w+1)}^{(j_w)}$, $U_{(i_w+1)}^{(j_w-1)}$ (determined up to null solutions) are conformal surface tensors since all the other quantities in (20.7) are conformal tensors and the $G^\alpha_{(i_w+1)}$, $G^\alpha_{(i_w)}$, $G^\alpha_{(i_w-1)}$ span mutually orthogonal vector spaces. The symmetry properties of the contravariant and covariant indices of these U 's follow from and are similar to those for the $G^\alpha_{(i_w)}$ which are derived later. We state some of the results of this section and §18 in the following theorem.

THEOREM 20.1. *Let V_n be a subspace of class C^r ($r \geq 3$) in a V_m and let the conformal osculating vector spaces of V_n have a basis of class C^1 . Then there exists a set of continuous conformal surface tensors $U_{(i_w+1)}^{(h_w)}$, $U_{(i_w+1)}^{(h_w-1)}$ ($w=0, 1, 2, \dots, M$) such that the basis beins $G^\alpha_{(i_w)}$ satisfy the conformal Frenet equations (20.7) and so that (20.8) is true. If $V_m \rightleftharpoons \bar{V}_m$, $V_n \rightleftharpoons \bar{V}_n$ by a conformal transformation, then the conformal osculating vector spaces of \bar{V}_n exist and have a basis of class C^1 . The corresponding basis beins $\bar{G}^\alpha_{(i_w)}$ for \bar{V}_n also satisfy the conformal Frenet equations. At corresponding points of V_n and \bar{V}_n , the respective conformal tangent and normal vector spaces I_w and \bar{I}_w correspond and their basis beins $G^\alpha_{(i_w)}$ and $\bar{G}^\alpha_{(i_w)}$ are equivalent tensors.*

The equations (20.7) actually involve all of the quantities (20.1). The quantities μ^α, ψ, ψ_i which do not appear to be present are implicit in the coefficients of connection $\Gamma^i_{jk}, \Gamma^\alpha_{\beta\gamma}$ which are used to define the conformal derivatives of the $G^\alpha_{(i_w)}$. Consequently we adjoin equations involving the derivatives of μ^α, ψ, ψ_i to the conformal Frenet equations. These adjoined equations, which are obtained from (13.14) and (15.4) and are valid if (12.23) is true, are

$$\begin{aligned}
 \psi_{;i} &= \psi_i, \\
 \psi_{i;j} &= \psi_i \psi_j + E_{ij} - \mu_\alpha G^\alpha_{ij} + \frac{1}{(m-2)} \rho_{\alpha\beta} G^\alpha_i G^\beta_j \\
 &\quad - \frac{G_{ij}}{2} \left[e^{2\psi} \mu^2 + G^{hk} \psi_h \psi_k + \frac{e^{2\psi} \rho}{(m-1)(m-2)} \right], \\
 \mu^\alpha_{;i} &= \frac{e^{-2\psi}}{(n-1)} \left[G^\alpha_{ih} : i G^{hl} + (n-1) G^\alpha_{ih} G^{hl} \psi_l - (n-1) e^{2\psi} \mu^\alpha \psi_i \right. \\
 &\quad \left. - (n-1) \mu_\gamma G^\gamma_{ih} G^\alpha_i G^{hl} + G^\alpha_h K^h_i + (n-2) G^\alpha_h E^h_i + G^\alpha_i E \right. \\
 &\quad \left. - C^\alpha_\beta G^\beta_i - \frac{(n-1)}{(m-2)} H^{\alpha\beta} \rho_{\beta\gamma} G^\gamma_i \right].
 \end{aligned}
 \tag{20.9}$$

Despite the fact that these equations involve metric quantities, their formal structure is unaltered by conformal transformations of V_m so that (20.9) are

conformal equations. Equations (20.7) and (20.9) are a system of partial differential equations in the unknowns (20.1) written in normal form. We call these equations the *extended conformal Frenet equations*.

Application to hypersurface theory. If V_r is a hypersurface of V_n , $n = m - 1$ and $M = 2$. Consequently I_2 is one-dimensional and I_3 is empty. Hence we may write G^{α}_{ij} as

$$(20.10) \quad G^{\alpha}_{ij} = B_{ij}Z^{\alpha},$$

where⁽³⁹⁾ B_{ij} is a symmetric covariant surface tensor and Z^{α} is a space vector which obeys (11.21). Both B_{ij} and Z^{α} are unique except for algebraic sign. Of course, B_{ij} is not a zero tensor since G^{α}_{ij} does not vanish on V_n . The conformal normal tensor $B_{(i_2)|(j_2)}$ of V_n is given by

$$(20.11) \quad B_{(i_2)|(j_2)} = B_{i_1i_2} \cdot B_{j_1j_2}.$$

We call B_{ij} the *conformal normal measure tensor* of the hypersurface instead of $B_{(i_2)|(j_2)}$ and also use it as the *second conformal fundamental tensor* of V_n instead of the one constructed from $B_{(i_2)|(j_2)}$.

In place of (20.7), we may write the *conformal Frenet equations* of V_n as⁽⁴⁰⁾

$$(20.12) \quad y^{\alpha}_{:i} = G^{\alpha}_i,$$

$$(20.13) \quad G^{\alpha}_{:j} = B_{ij}Z^{\alpha},$$

$$(20.14) \quad Z^{\alpha}_{:i} = -B_{ij}G^{jk}G^{\alpha}_k.$$

To obtain the last set of these equations we note that

$$(20.15) \quad Z^{\alpha}_{:i} = G^{\alpha}_h U^h_i + Z^{\alpha} U_i.$$

If we obtain the conformal derivatives of (11.21) and simplify by means of (11.21) and (20.13), we find that

$$(20.16) \quad A_{\alpha\beta}Z^{\alpha}Z^{\beta}_{:i} = 0, \quad A_{\alpha\beta}Z^{\alpha}_{:i}G^{\beta}_j = -B_{ij}.$$

It follows from (7.7), (11.21), (20.15) and (20.16) that

$$U_i = 0, \quad G_{hj}U^h_i = -B_{ij}.$$

These equations establish the truth of (20.14). Since Z^{α} is defined algebraically by (11.18), it is of class C^{r-1} . According to (20.10), B_{ij} is of class C^{r-2} . Hence the conformal Frenet equations of V_n , (20.12), (20.13) and (20.14), are valid if $r \geq 2$.

From (20.10), (20.13) and (20.14), we readily find that

$$(20.17) \quad G^{\alpha}_{ij:k} = B_{ij:k}Z^{\alpha} - B_{ij}B_{kh}G^{hl}G^{\alpha}_l$$

if $r \geq 3$. Now, according to (7.12), (20.10) and (20.16),

⁽³⁹⁾ The tensor $B_{i|j}$ ($=G_{ij}$) is distinguished from B_{ij} by the presence of the vertical bar.

⁽⁴⁰⁾ All of these definitions very frequently replace those previously given for any subspace V_n if V_n is a hypersurface.

$$Z^\alpha = n^{-1}G^{g_1h_1}G^{g_2h_2}B_{(g_2)}G^\alpha_{(h_2)}.$$

If this value for Z^α is substituted in (20.17) and the resulting equations compared with (20.7) where $w=2$, we find that

$$(20.18) \quad \begin{aligned} U^{(h_2)}_{(i_2)} &= n^{-1}G^{g_1h_1}G^{g_2h_2}B_{(g_2)}B_{(i_2):i_2}, \\ U^{h_1}_{(i_1)} &= -B_{(i_2)}B_{i_2h_2}G^{(h_2)} \end{aligned}$$

for any hypersurface. The $U^{(h_2)}_{(i_2)}$ are determined except for a null solution of $G^\alpha_{(h_2)}\theta^{(h_2)}=0$. The components of $U^{(h_1)}_{(i_1)}$ are unique.

For a hypersurface, the direction of the unit normal vector ζ^α to V_n , defined in §5, and the direction of the unit conformal normal Z^α to V_n correspond under any conformal transformation of V_m . It follows from (7.2) and (13.10) that

$$(20.19) \quad Z^\alpha = e^\psi \zeta^\alpha.$$

Consequently the mean curvature normal, defined for a hypersurface by (5.11), may be written as

$$(20.20) \quad \mu^\alpha = e^{-\psi} \mu \cdot Z^\alpha.$$

We define Z_α by means of the equations

$$(20.21) \quad Z_\alpha = A_{\alpha\beta} Z^\beta$$

and multiply (15.3) by Z_α and sum for α . It follows from (11.21), (20.10), (20.17), (20.20) and (20.21) that

$$(20.22) \quad (n-1)\mu_{:i} = e^{-\psi} [B_{ih:l}G^{hl} + (n-1)B_{ih}\psi_{:l}G^{hl} + \rho^\alpha_{\beta\gamma\delta}G^{\beta\delta}G^\gamma Z_\alpha].$$

Since $G^{\beta\delta} = A^{\beta\delta} - Z^\beta Z^\delta$ and $\rho^\alpha_{\beta\gamma\delta}Z_\alpha Z^\beta = 0$, (20.22) becomes

$$(20.23) \quad (n-1)\mu_{:i} = e^{-\psi} \{G^{hl} [B_{ih:l} + (n-1)B_{ih}\psi_{:l}] - \rho_{\alpha\beta} Z^\alpha G^\beta_{:i}\}.$$

These equations are valid if $r \geq 3$. For a hypersurface, the unknowns (20.1) may be replaced by

$$(20.24) \quad \gamma^\alpha, G^\alpha_{:i}, Z^\alpha, \mu, \psi, \psi_{:i}$$

and the last set of equations (20.9) may be replaced by (20.23).

V. THE FUNDAMENTAL EQUATIONS

In the metric theory of a hypersurface V_{m-1} in a V_m , the basic partial differential equations which are satisfied by the coefficients of the first and second fundamental forms of V_{m-1} are the Gauss and Codazzi equations. These equations are the integrability conditions of the system of Frenet equations for the V_{m-1} . Much of the geometry of the V_{m-1} is simply a geometric restatement of various analytical consequences of these equations. In the metric theory of any subspace V_n in V_m , a similar but more extensive set of

fundamental equations is obtained by considering the integrability conditions of the Frenet equations for the V_n .

In this chapter, we obtain the fundamental equations of the conformal differential geometry of a subspace. These equations involve the various conformal measure and curvature tensors connected with the V_n in V_m which were defined in earlier sections of the paper. Some of the equations are purely algebraic ones which follow from the definitions and conformal Frenet equations. Others are partial differential equations obtained by a consideration of the integrability conditions of (20.7) and (20.9). Since (20.7) and (20.9) are conformal equations, their integrability conditions are also conformal equations. These latter equations are obtained in a form which explicitly involves only conformal tensors.

These equations include analogues of the classical Gauss-Codazzi equations. However both the algebraic and differential equations which are obtained present several new features. The most important of these differences in the differential equations may be traced to the deviation tensor E_{ij} and equations (20.9) which have no analogue in the metric theory. However, if $n \geq 4$, the fundamental equations which arise in the metric theory and in the conformal theory of a V_n in V_m are quite similar. The cases $n = 3, 2, 1$ exhibit increasing degrees of deviation from the "usual" situation.

21. The boundary, algebraic, reality and derived conditions. The inner orientation of the basis beins $G^\alpha_{(i_w)}$, which determines the various lengths of and angles between these beins, is given by

$$(21.1) \quad A_{\alpha\beta} G^\alpha_{(i_w)} G^\beta_{(l_w)} = 0, \quad w \neq v; w, v = 1, 2, \dots, M,$$

$$(21.2) \quad A_{\alpha\beta} G^\alpha_{(i_w)} G^\beta_{(l_w)} = B_{(i_w)|(l_w)}.$$

These equations are simply equations (20.5) and (19.5) respectively and are exactly analogous to the corresponding equations in the metric theory. In addition to these equations, we have the equations

$$(21.3) \quad A_{\alpha\beta} \mu^\alpha G^\beta_j = 0$$

since the mean curvature normal is orthogonal to the tangent vector space. We think of equations (20.7) and (20.9) as partial differential equations in the unknowns (20.1). Then (21.1), (21.2) and (21.3) are *boundary conditions* for the system of extended Frenet equations which involve the unknowns $G^\alpha_{(i_w)}$ and μ^α . We denote (21.1), (21.2) and (21.3) by $[B 1]$, $[B 2]$ and $[B 3]$ respectively and refer to them as the *B-conditions*.

A new type of algebraic condition not occurring in the metric theory is contained in equations (7.11) and (7.12). According to (21.2), (7.12) may be written as

$$(21.4) \quad B_{(i_2)|(h_2)} G^{i_1 h_1} G^{i_2 h_2} = n.$$

According to §19 and (21.2), equations (7.11) are equivalent to

$$(21.5) \quad B_{(i_2)|(h_2)}G^{(i_2)} = 0.$$

We call equations (21.4) and (21.5) the *algebraic conditions* or *A-conditions*. We denote the algebraic conditions (21.5) and (21.4) by the symbols [A 1] and [A 2] respectively.

Various algebraic conditions may be derived from (21.1) and (21.2). It follows directly from (21.2) and the fact that $A_{\alpha\beta}$ is a symmetric tensor that

$$(21.6) \quad B_{(i_w)|(h_w)} = B_{(h_w)|(i_w)}.$$

Also, as was noted in §19,

$$(21.7) \quad B_{(i_w)|(h_w)} \text{ is } \begin{cases} \text{positive definite if } w = 1, \\ \text{positive semi-definite if } w > 1. \end{cases}$$

Furthermore, according to (18.7), (18.8) and (18.9),

$$(21.8) \quad \sum_{w=1}^M N_w \leq m, \quad N_w > 0,$$

where, as noted in §19, N_w is the rank of the matrix $\|B_{(i_w)|(h_w)}\|$. Conversely, if tensors $B_{(i_w)|(h_w)}$ are defined at a point \mathcal{P} of V_m such that (21.6), (21.7) and (21.8) are true, then these equations are sufficient conditions for the existence of real basis beins $G^{\alpha_{(i_w)}}$ at \mathcal{P} which satisfy (21.1) and (21.2). For this reason, we call (21.6), (21.7) and (21.8) the *reality conditions* or *R-conditions* and denote them by the symbols [R 1], [R 2] and [R 3] respectively.

Other equations may be obtained by differentiation of (21.1), (21.2) and (21.3). This differentiation is possible if the hypothesis of Theorem 20.1 is satisfied. If the conformal derivative with respect to x^j of (21.1) is found and the result is simplified by means of (20.7) and (21.1) we obtain an identity if $|w-v| > 1$. If $v = w + 1$, using (21.1) and (21.2) we obtain

$$(21.9) \quad B_{(i_w)j|(l_{w+1})} + U^{(h_w)_{(l_{w+1})}j}B_{(h_w)|(i_w)} = 0, \quad w = 1, 2, \dots, M - 1.$$

In a similar manner, conformal differentiation of (21.2) leads to the result

$$(21.10) \quad B_{(i_w)|(l_w):j} - U^{(h_w)_{(l_w)j}}B_{(h_w)|(l_w)} - U^{(h_w)_{(l_w)j}}B_{(h_w)|(i_w)} = 0, \\ w = 1, 2, \dots, M.$$

Also, conformal differentiation of (21.3) and use of the last set of equations (20.9) and of (7.7), (20.7) and (21.1) leads to

$$U^k{}_{ih}G_{kj}G^{hl} + K_{ij} + (n - 2)E_{ij} + EG_{ij} - C_{ij} = 0.$$

In virtue of (21.9) with $w=1$, these conditions are identical with equations (22.10) of the next section. Equations (22.10), in turn, are a consequence of the conformal analogues of the Gauss equations (22.13). Hence the above conditions may be omitted if (22.13) are included as is done later. Equations (21.9) and (21.10) are consequences of the *B-conditions* (21.1) and (21.2).

We call these equations the *derived conditions* or simply the *D-conditions*. We denote these equations by the symbols [D 1] and [D 2] respectively.

We now note several other equations which are consequences of some of the above equations. It follows from (21.5) and (21.9) with $w = 2, 3, \dots, M - 1$ successively that

$$(21.11) \quad B_{(i_w)|(l_w)}G^{(i_2)} = 0.$$

Equations (21.10) and (21.6), (21.9) and (21.10) lead to the equations

$$(21.12) \quad \begin{aligned} G^{(i_2)}U^{(h_w)}{}_{(i_{w+1})}B_{(h_w)|(l_w)} &= 0, & w = 2, 3, \dots, M, \\ G^{(i_2)}U^{(h_{w-1})}{}_{(i_{w+1})}B_{(h_{w-1})|(l_{w-1})} &= 0. \end{aligned}$$

Equations similar to (21.11) and (21.12) may also be obtained by conformal differentiation of (21.6).

Application to hypersurface theory. If V_n is a hypersurface, $n = m - 1$ and $M = 2$. In this case, we write the conformal Frenet equations as (20.12), (20.13) and (20.14) and we replace the last set of equations (20.9) by (20.23). We also eliminate the tensor $B_{(i_2)|(j_2)}$ by means of equations (20.11).

It is easy to see that the boundary conditions (21.1) may be replaced by the first set of equations (11.21)

$$A_{\alpha\beta}Z^\alpha G^\beta{}_i = 0$$

and that (21.2) may be written as (7.7) and the second set of equations (11.21)

$$\begin{aligned} A_{\alpha\beta}G^\alpha{}_i G^\beta{}_j &= G_{ij}, \\ A_{\alpha\beta}Z^\alpha Z^\beta &= 1. \end{aligned}$$

We denote these conditions which are equivalent to (21.1) and (21.2) by the symbols [B' 1] and [B' 2] respectively. Since μ^α is replaced by $e^\psi \mu Z^\alpha$, (21.3) is a consequence of [B' 1] and may be omitted for a hypersurface. Equations (21.4) and (21.5) become

$$(21.13) \quad B_{(i_2)}B_{(h_2)}G^{i_1 h_1}G^{i_2 h_2} = n,$$

$$(21.14) \quad B_{(i_2)}G^{(i_2)} = 0.$$

We denote (21.14) and (21.13) by the symbols [A' 1] and [A' 2] respectively.

We also note that (21.6) and (21.7) need only be stated for the case $w = 1$; namely,

$$(21.15) \quad G_{ij} = G_{ji},$$

$$(21.16) \quad G_{ij} \text{ is positive definite.}$$

The remaining case, $w = 2$, follows directly from (20.11). We denote (21.15) and (21.16) by the symbols [R' 1] and [R' 2] respectively. Equation (21.8) is always true since $M = 2$ and $N_1 = n, N_2 = 1$ follows from (21.16) and (20.11)

respectively. Finally, the derived conditions obtained by differentiating $[B' 1]$ and $[B' 2]$ are true identically in virtue of the conformal Frenet equations and B -conditions. Hence there are no conditions corresponding to $[D 1]$ and $[D 2]$ for a hypersurface.

22. The conformal Gauss-Codazzi equations. Each of the various conformal Frenet equations contains a single contravariant space index α . Consequently the integrability conditions of these equations also contain α as the only space index. Therefore if the integrability conditions for the Frenet equations whose left members are $G^{\alpha}_{(i_w) : i_{w+1}}$ ($w=0, 1, 2, \dots, M$) are multiplied by $A_{\alpha\beta}G^{\beta}_{(l_v)}$ ($v=1, 2, \dots, M, \infty$) and summed for α, β the resulting equations only involve surface indices. We denote these equations by the symbol $[w, v]$. It is clear that the integrability conditions of the conformal Frenet equations and the equations $[w, v]$ where $w=0, 1, 2, \dots, M; v=1, 2, \dots, M, \infty$ are equivalent.

The integrability conditions of the first set of the conformal Frenet equations, which describe the variation of $y^{\alpha}(=G^{\alpha}_{(i_0)})$, are $y^{\alpha}_{(j_k)-}=0$. According to the first two sets (20.2) of the conformal Frenet equations, the above equations become $G^{\alpha}_{(j_k)-}=0$ which, in turn, are equivalent to

$$(22.1) \quad A_{\alpha\beta}G^{\alpha}_{(j_k)-}G^{\beta}_{(l_v)} = 0, \quad v = 1, 2, \dots, M, \infty.$$

These are conditions $[0, v]$. As a result of (21.1) and (21.2) all of these equations are identities except for the condition $[0, 2]$ which is

$$(22.2) \quad B_{(j_k)-1(l_2)} = 0.$$

This is equivalent to the symmetry property of G^{α}_{jk} in its covariant indices already noted at the end of §8.

The integrability conditions of the second set of conformal Frenet equations are

$$(22.3) \quad G^{\alpha}_{i : (j_k)-} = G^{\alpha}_{\sigma}K^{\sigma}_{ijk} - G^{\beta}_{i}R^{\alpha}_{\beta jk}$$

according to (17.1). The tensor $R^{\alpha}_{\beta jk}$ is defined by (16.8). Now from (20.7) and (20.8), we obtain $G^{\alpha}_{i : jk} = G^{\alpha}_{i j : k} = G^{\alpha}_{ijk} + U^{(h_2)}_{ijk}G^{\alpha}_{(h_2)} + U^{h_1}_{ijk}G^{\alpha}_{h_1}$. These last equations show that (22.3) is equivalent to

$$(22.4) \quad A_{\alpha\beta}G^{\beta}_{(l_v)}[G^{\alpha}_{i(j_k)-} + U^{(h_2)}_{i(j_k)-}G^{\alpha}_{(h_2)} + U^{h_1}_{i(j_k)-}G^{\alpha}_{h_1}] \\ = A_{\alpha\beta}G^{\alpha}_{\sigma}G^{\beta}_{(l_v)}K^{\sigma}_{ijk} - A_{\alpha\epsilon}G^{\epsilon}_{(l_v)}G^{\beta}_{i}R^{\alpha}_{\beta jk}.$$

These are conditions $[1, v]$. According to (21.1) and (21.2), the first of these conditions, when $v=1$, becomes

$$(22.5) \quad U^{h_1}_{i(j_k)-}G_{h_1 l_1} = K_{l_1 j k} - R_{\alpha\beta j k}G^{\alpha}_{l_1}G^{\beta}_{i}.$$

Now (21.9) with $w=1$ may be written as

$$(22.6) \quad U^{h_1}_{ijk}G_{h_1 l_1} = -B_{ij|l_1 k}.$$

If we write h for l_1 and take account of (22.6), (22.5) may be written as

$$(22.7) \quad B_{i(k|j)^{-h}} = K_{hijk} - R_{\alpha\beta jk} G^\alpha_h G^\beta_i.$$

These are conformal analogues of the Gauss equations which we now proceed to simplify.

From these equations and (7.4), (7.7), (14.2), (14.3), (14.6), (16.8), (16.16), (20.7), (21.4), (21.5) and (22.6), we find by an easy calculation that

$$(22.8) \quad (n-1)B_{ik|h_j} G^{hk} = K_{ij} - C_{ij} + (n-2)E_{ij} + (n-2)B_{ik|h_j} G^{hk} \\ + [C + (3-2n)E - K + n]G_{ij}.$$

If these equations are multiplied by G^{ij} and summed,

$$(22.9) \quad K = n + C + 2(1-n)E.$$

Substitution of this result in (22.8) yields

$$(22.10) \quad K_{ij} = B_{ik|h_j} G^{hk} + C_{ij} + (2-n)E_{ij} - EG_{ij}.$$

We replace K_{ij} in (16.8) by its value given in (22.10) and simplify the resulting equations, making use of the conformal analogue of (4.12) and of

$$(22.11) \quad H^{\alpha\gamma} G^\gamma_{ij:k} = G^{\alpha}_{ijk} + U^{(h_2)}_{ijk} G^\alpha_{(h_2)} = A^{\alpha\gamma} G^\gamma_{ij:k} + G^{h\alpha} B_{ij|kh}$$

which follows from (20.7) and (22.6). Then equations (16.8) become equations (16.9).

If we use this simplified form of $R^\alpha_{\beta jk}$ in (22.7), we find that (22.7) becomes

$$(22.12) \quad B_{i(k|j)^{-h}} = K_{hijk} - R_{hijk}$$

where R_{hijk} is given by (16.11). Conversely, it is easy to see that (22.7) is an identity in virtue of (22.12) and that (16.8) and (16.9) are equivalent if (22.12) holds. Consequently condition [1, 1], originally written as (22.5), may also be written as (22.12). According to (22.12) and (16.11), these equations are

$$(22.13) \quad B_{i(k|j)^{-h}} = K_{hijk} - C_{hijk} + G_{i(j)E_k)^{-h}} + G_{h(k)E_j)^{-i}}.$$

We call (22.13) the *conformal Gauss equations* of the V_n in V_m . If these equations are multiplied by G^{hk} and then by G^{ij} we obtain equations (22.10) and (22.9) respectively after summation on repeated indices.

A comparison of the metric Gauss equations (5.16) and (22.12) exhibits an exact analogy if the analogous pairs of metric and conformal tensors are: $b_{ik|jl}$, $B_{ik|jl}$; κ_{hijk} , K_{hijk} ; ρ_{hijk} , R_{hijk} . However, if this last pair is replaced by ρ_{hijk} , C_{hijk} , (22.13) shows that an additional expression involving E_{ij} is present in the conformal Gauss equations. This additional expression is responsible for many of the new geometric features in the conformal theory of V_n which are absent in the metric theory.

Now K_{hijk} and κ_{hijk} are the Riemann curvature tensors formed with re-

spect to G_{ij} and g_{ij} respectively. Since, from (7.3), the tensors G_{ij} , g_{ij} are in conformal correspondence, it follows from §11 that, if $n > 2$, $\uparrow K^h{}_{ijk} = \uparrow \kappa^h{}_{ijk}$. In these equations, the \uparrow operation for the left member is with respect to G_{ij} while that for the right member is with respect to g_{ij} . As a result of (11.26), (11.28) and (11.29),

$$(22.14) \quad \uparrow K_{hijk} = W_{hijk}.$$

Consequently, if $n > 2$ and the \uparrow operation with respect to G_{ij} is applied to (22.13), we find that

$$(22.15) \quad W_{hijk} = \uparrow \mathcal{B}_{hijk} + \uparrow C_{hijk}$$

after use is made of (11.30) and (11.31). The tensor $\uparrow C_{hijk}$ is defined by (16.14) and $\uparrow \mathcal{B}_{hijk}$, defined by (11.28), is

$$(22.16) \quad \begin{aligned} \uparrow \mathcal{B}_{hijk} = \mathcal{B}_{hijk} + \frac{1}{(n-2)} [G_{h(i}\mathcal{B}_{k)j} + G_{i(k}\mathcal{B}_{j)h}] \\ + \frac{\mathcal{B}}{(n-1)(n-2)} G_{h(k}G_{j)i} \end{aligned}$$

where we have written

$$(22.17) \quad \mathcal{B}_{hijk} = B_{i(k|j)h}, \quad \mathcal{B}_{ij} = \mathcal{B}_{hijk}G^{hk}, \quad \mathcal{B} = \mathcal{B}_{ij}G^{ij}.$$

It follows from (21.6) and (21.7) that

$$(22.18) \quad \mathcal{B}_{ij} = B_{ik|hj}G^{hk}, \quad \mathcal{B} = n.$$

We return to conditions [1, v] or (22.4) and let $v = 2$. If the resulting equations are simplified by means of (16.4), (21.1) and (21.2) they become

$$(22.19) \quad U^{(h_2)}{}_{i(jk)h} B_{(h_2)|l_2} = -A_{\alpha\beta} R^{\alpha}{}_{ijk} G^{\beta}{}_{l_2}.$$

Use of (11.16), (16.10), (21.1), (21.2) and (22.11) transforms (22.19) into the equations

$$(22.20) \quad \begin{aligned} U^{(h_2)}{}_{i(jk)h} B_{(h_2)|l_2} = -D_{\beta ijk} G^{\beta}{}_{l_2} \\ + \frac{1}{(n-1)} G^{(g_2)} G_{i(k} U^{(h_2)}{}_{j)(g_2)} B_{(h_2)|l_2}. \end{aligned}$$

This is condition [1, 2]. Equations (22.20) are called the *conformal Codazzi equations* of the V_n in V_m .

If M exceeds 2, we let v equal 3 in the conditions [1, v] and simplify as was done to obtain (22.19). We obtain

$$(22.21) \quad B_{i(jk)h} B_{l_3} = -A_{\alpha\beta} R^{\alpha}{}_{ijk} G^{\beta}{}_{l_3}.$$

We proceed as in the derivation of (22.20) and find that the above equations are equivalent to

$$(22.22) \quad B_{i(jk)^{-1}(l_2)} = -D_{\beta i j k} G^\beta_{(l_2)} + \frac{1}{(n-1)} G^{(\sigma_2)} G_{i(kB_j)^{-}(\sigma_2) | (l_2)}.$$

This is condition [1, 3]. The cases where $v > 3$ are considered in a similar manner and lead to the following analogues of (22.21) and (22.22):

$$(22.23) \quad A_{\alpha\beta} R^{\alpha}_{i j k} G^\beta_{(l_u)} = 0, \quad u = 4, 5, \dots, M, \infty,$$

$$(22.24) \quad D_{\beta i j k} G^\beta_{(l_u)} = 0, \quad u = 4, 5, \dots, M, \infty.$$

The latter of these is condition [1, u], $u > 3$.

23. Higher integrability conditions. The third set ($w = 2$) of the conformal Frenet equations is

$$(23.1) \quad G^{\alpha}_{(i_2): j} = G^{\alpha}_{(i_2) j} + U^{(h_2)}_{(i_2) j} G^{\alpha}_{(h_2)} + U^{h_1}_{(i_2) j} G^{\alpha}_{h_1}.$$

The integrability conditions of these equations are

$$(23.2) \quad G^{\alpha}_{(i_2): (jk)^{-} = G^{\alpha}_{\sigma i_2} K^{\sigma}_{i_1 j k} + G^{\alpha}_{i_1 \sigma} K^{\sigma}_{i_2 j k} - G^{\beta}_{(i_2)} R^{\alpha}_{\beta j k}.$$

Conformal differentiation of (23.1) and simplification by means of (20.7) and (20.8) gives

$$(23.3) \quad \begin{aligned} G^{\alpha}_{(i_2): j k} &= G^{\alpha}_{(i_2) j k} + [U^{(h_2)}_{(i_2) j k} + U^{(h_2)}_{(i_2) j} G^{h_2}_k] G^{\alpha}_{(h_2)} \\ &+ [U^{(h_2)}_{(i_2) j k} + U^{(h_2)}_{(i_2) j: k} + U^{(\sigma_2)}_{(i_2) j} U^{(h_2)}_{(\sigma_2) k} + U^{h_1}_{(i_2) j} G^{h_2}_k] G^{\alpha}_{(h_2)} \\ &+ [U^{h_1}_{(i_2) j: k} + U^{(\sigma_2)}_{(i_2) j} U^{h_1}_{(\sigma_2) k}] G^{\alpha}_{h_1}. \end{aligned}$$

Also, from (16.9), (20.7), (20.8), (21.1) and (21.2),

$$(23.4) \quad G^{\beta}_{(i_2)} R^{\alpha}_{\beta j k} = D^{\alpha}_{\beta j k} G^{\beta}_{(i_2)} + \frac{1}{(n-1)} G^{(\sigma_2)} G^{\alpha}_{(kU^{(h_2)}) j^{-}(\sigma_2)} B_{(h_2) | (i_2)}.$$

We substitute (23.3) and (23.4) in (23.2) and multiply successively by $A_{\alpha\beta} G^\beta_{(l_v)}$ ($v = 1, 2, \dots, M, \infty$) and simplify using (18.13), (21.1) and (21.2). This gives the various integrability conditions [2, v]:

$$(23.5) \quad \begin{aligned} [U^h_{(i_2)(j:k)^{-} + U^{(\sigma_2)}_{(i_2) j^{-} U^h_{(\sigma_2) k^{-}]} G_{h l} &= -D_{\alpha\beta j k} G^{\alpha}_{i} G^{\beta}_{(i_2)} \\ &+ \frac{1}{(n-1)} G^{(\sigma_2)} G_{l(jU^{(h_2)}) k^{-}(\sigma_2)} B_{(h_2) | (i_2)}, \end{aligned}$$

$$(23.6) \quad \begin{aligned} [U^{(h_2)}_{(i_2)(jk)^{-} + U^{(h_2)}_{(i_2)(j:k)^{-} + U^{(\sigma_2)}_{(i_2) j^{-} U^{(h_2)}_{(\sigma_2) k^{-}]} & \\ &+ U^{h_1}_{(i_2)(jG^{h_2}) k^{-}]} B_{(h_2) | (l_2)} \\ &= B_{\sigma i_2 | (l_2)} K^{\sigma}_{i_1 j k} + B_{i_1 \sigma | (l_2)} K^{\sigma}_{i_2 j k} - D_{\alpha\beta j k} G^{\alpha}_{(l_2)} G^{\beta}_{(i_2)}, \end{aligned}$$

$$(23.7) \quad (U^{(h_2)}_{(i_2)(jk)^{-} + U^{(h_2)}_{(i_2)(jG^{h_2}) k^{-}]} B_{(h_2) | (l_2)} = -D_{\alpha\beta j k} G^{\alpha}_{(l_2)} G^{\beta}_{(i_2)},$$

$$(23.8) \quad B_{(i_2)(jk)^{-1}(l_4)} = -D_{\alpha\beta j k} G^{\alpha}_{(l_4)} G^{\beta}_{(i_2)},$$

$$(23.9) \quad 0 = D_{\alpha\beta j k} G^{\alpha}_{(l_u)} G^{\beta}_{(i_2)}, \quad u = 5, 6, \dots, M, \infty.$$

These are conditions [2, 1], [2, 2], [2, 3], [2, 4] and [2, u], $u > 4$, respec-

tively. In (23.5), we have omitted the subscript 1 from the indices h, l .

We now consider the general $(w+1)$ th set of conformal Frenet equations (20.7). The integrability conditions of this set of equations are

$$(23.10) \quad G^\alpha_{(i_w):(jk)^-} = \sum_{u=1}^w G^\alpha_{(i_{u-1})\sigma^i_{u+1}\dots i_w} K^\sigma_{i_u j k} - G^\beta_{(i_w)} R^\alpha_{\beta j k}.$$

Now conformal differentiation of (20.7) and simplification by means of the conformal Frenet equations leads to

$$(23.11) \quad \begin{aligned} G^\alpha_{(i_w):jk} &= G^\alpha_{(i_w)jk} + [U^{(hw+1)}_{(i_w)jk} + U^{(hw)}_{(i_w)j} G^{hw+1}_k] G^\alpha_{(hw+1)} \\ &\quad + [U^{(hw)}_{(i_w)jk} + U^{(hw)}_{(i_w)j:k} + U^{(\sigma w)}_{(i_w)j} U^{(hw)}_{(\sigma w)k} \\ &\quad \quad \quad + U^{(hw-1)}_{(i_w)j} G^{hw}_k] G^\alpha_{(hw)} \\ &\quad + [U^{(hw-1)}_{(i_w)j:k} + U^{(\sigma w)}_{(i_w)j} U^{(hw-1)}_{(\sigma w)k} \\ &\quad \quad \quad + U^{(\sigma w-1)}_{(i_w)j} U^{(hw-1)}_{(\sigma w-1)k}] G^\alpha_{(hw-1)} \\ &\quad + U^{(\sigma w-1)}_{(i_w)j} U^{(hw-2)}_{(\sigma w-1)k} G^\alpha_{(hw-2)}. \end{aligned}$$

Also, from (16.9), (20.7), (20.8), (21.1) and (21.2), we find that

$$(23.12) \quad \begin{aligned} G^\beta_{(i_u)} R^\alpha_{\beta j k} &= D^\alpha_{\beta j k} G^\beta_{(i_u)} + \frac{1}{(n-1)} G^{(\sigma 2)} G^\alpha_{(k B_j)^-(\sigma 2)|(\iota_2)}, \\ G^\beta_{(i_w)} R^\alpha_{\beta j k} &= D^\alpha_{\beta j k} G^\beta_{(i_w)}, \quad u = 4, 5, \dots, M, \infty. \end{aligned}$$

We substitute (23.11) and (23.12) in (23.10) and multiply successively by $A_{\alpha\beta} G^\beta_{(i_w)}$ ($v=1, 2, \dots, M, \infty$) and then simplify using (18.13), (21.1) and (21.2). In this manner we obtain the integrability conditions $[w, v]$ for $w > 2$. These equations are

$$(23.13) \quad U^{(\sigma 2)}_{(i_u)j} U^{h_{(\sigma 2)k}} G_{hl} = -D_{\alpha\beta j k} G^\alpha_{i_u} G^\beta_{(i_u)} + \frac{1}{(n-1)} G^{(\sigma 2)} G_{l(j B_k)^-(\sigma 2)|(\iota_2)},$$

$$(23.14) \quad U^{(\sigma w-1)}_{(i_w)j} U^{(hw-2)}_{(\sigma w-1)k} B_{(hw-2)|(\iota_{w-2})} = -D_{\alpha\beta j k} G^\alpha_{(\iota_{w-2})} G^\beta_{(i_w)},$$

$$(23.15) \quad [U^{(hw-1)}_{(i_w)(j:k)^-} + U^{(\sigma w)}_{(i_w)j} U^{(hw-1)}_{(\sigma w)k^-} \\ + U^{(\sigma w-1)}_{(i_w)j} U^{(hw-1)}_{(\sigma w-1)k^-}] B_{(hw-1)|(\iota_{w-1})} = -D_{\alpha\beta j k} G^\alpha_{(\iota_{w-1})} G^\beta_{(i_w)},$$

$$(23.16) \quad [U^{(hw)}_{(i_w)(jk)^-} + U^{(hw)}_{(i_w)(j:k)^-} + U^{(\sigma w)}_{(i_w)j} U^{(hw)}_{(\sigma w)k^-} \\ + U^{(hw-1)}_{(i_w)(j G^{hw}_k)^-}] B_{(hw)|(\iota_w)} \\ = -D_{\alpha\beta j k} G^\alpha_{(\iota_w)} G^\beta_{(i_w)} + \sum_{u=1}^w B_{(i_{u-1})\sigma^i_{u+1}\dots i_w|(\iota_w)} K^\sigma_{i_u j k},$$

$$(23.17) \quad [U^{(hw+1)}_{(i_w)(jk)^-} + U^{(hw)}_{(i_w)(j G^{hw+1}_k)^-}] B_{(hw+1)|(\iota_{w+1})} \\ = -D_{\alpha\beta j k} G^\alpha_{(\iota_{w+1})} G^\beta_{(i_w)},$$

$$(23.18) \quad B_{(i_w)(jk)^-|(\iota_{w+2})} = -D_{\alpha\beta j k} G^\alpha_{(\iota_{w+2})} G^\beta_{(i_w)},$$

$$(23.19) \quad 0 = D_{\alpha\beta jk}G^\alpha_{(l_u)}G^\beta_{(i_w)}, \quad u > w + 2 \text{ or } u < w - 2.$$

The above equations are conditions $[3, 1]$, $[w, w - 2]$ with $w > 3$, $[w, w - 1]$, $[w, w]$, $[w, w + 1]$, $[w, w + 2]$ and $[w, u]$ with $u > w + 2$ or $u < w - 2$ respectively. In all of these equations, it is assumed that $w > 2$ and that w does not exceed M while u has the range $1, 2, \dots, M, \infty$. In accordance with (20.8), $U^{(h_{M+1})}$, $U^{(i_{M+2})}$, $B_{(h_{M+1})|(l_{M+1})}$ and $B_{(h_{M+2})|(l_{M+2})}$ are zero tensors and the appropriate substitution should be made for these tensors in the above equations wherever they occur.

In the above paragraphs and in the previous section, we have derived the various integrability conditions $[w, v]$ of the conformal Frenet equations. However, not all of these conditions are distinct. In the sequel, we indicate which of the $[w, v]$ may be omitted because of the duplications which arise.

If neither w nor v exceeds M , a straightforward calculation shows that

$$(23.20) \quad [A_{\alpha\beta}G^\alpha_{(i_w)}G^\beta_{(l_v)}]_{:(jk)-} = A_{\alpha\beta}G^\alpha_{(i_w): (jk)-}G^\beta_{(l_v)} - A_{\alpha\beta}G^\alpha_{(i_w)}G^\beta_{(l_v): (jk)-}.$$

If $w \neq v$, it follows from (21.1) that the left member of these equations is zero. Consequently (23.20) may be written as $A_{\alpha\beta}G^\alpha_{(i_w): (jk)-}G^\beta_{(l_v)} + R_{\alpha\beta jk}G^\alpha_{(i_w)}G^\beta_{(l_v)} = -A_{\alpha\beta}G^\alpha_{(l_v): (jk)-}G^\beta_{(i_w)} - R_{\alpha\beta jk}G^\alpha_{(i_w)}G^\beta_{(l_v)}$, $v \neq w$. According to (23.10), the left member of these equations equated to zero is condition $[w, v]$ and the right member equated to zero is condition $[v, w]$. Hence it follows that conditions $[w, v]$ and $[v, w]$ are identical. This means that *all the integrability conditions of the conformal Frenet equations are conditions $[w, v]$ with $v \geq w$.*

It is easy to see that the differentiation implicit in the integrability conditions $[w, v]$ is possible if V_n is of class C^r with $r \geq 4$ and if the basis beins (18.11) of V_n form a basis of class C^2 . Comparison with (18.12) shows that

$$(23.21) \quad r \geq M + 2$$

is a sufficient but not necessary condition for the satisfaction of these last conditions.

Finally, we note that the extended conformal Frenet equations (20.7) and (20.9) and the B -conditions (21.1) and (21.2) remain unchanged if any tensor $U^{(h_w)}_{(i_{w+1})}$, $U^{(h_{w-1})}_{(i_{w+1})}$ is replaced by another which differs from it by an additive null solution. Consequently any equations derived from (20.7), (20.9), (21.1) and (21.2) such as the D -conditions and the integrability conditions also must remain unchanged if any U is changed by an additive null tensor. This fact may be verified directly by using various relationships which are obeyed by null tensors.

As an illustration, we derive and use some of these relationships. By conformal differentiation of (19.3) with respect to x^j and use of (20.7), we obtain

$$G^\alpha_{(i_w)j}\theta^{(i_w)} + G^\alpha_{(h_w)}[\theta^{(h_w)}]_{:j} + U^{(h_w)}_{(i_w)j}\theta^{(i_w)} + G^\alpha_{(h_{w-1})}U^{(h_{w-1})}_{(i_w)j}\theta^{(i_w)} = 0.$$

It follows from these equations and (21.1) and (21.2) that the relationships

$$\begin{aligned}
 B_{(i_w)j|(l_w+1)}\theta^{(i_w)} &= 0, \\
 B_{(h_w)|l_w}[\theta^{(h_w)}; j + U^{(h_w)}{}_{(i_w)j}\theta^{(i_w)}] &= 0, \\
 B_{(h_w-1)|l_w-1}U^{(h_w-1)}{}_{(i_w)j}\theta^{(i_w)} &= 0
 \end{aligned}$$

are true if $\theta^{(i_w)}$ is a null tensor satisfying (19.3). An example of the application which may be made of these relationships follows. If $U^{(h_w+1)}{}_{(i_w)jk}$ in (23.17) is changed by an additive null tensor $\theta^{(h_w+1)}$, the additional terms $\theta^{(h_w+1)}B_{(h_w+1)|(l_w+1)}$ must vanish by definition of $\theta^{(h_w+1)}$. If $U^{(h_w)}{}_{(i_w)j}$ in (23.17) is changed by a null solution $\theta^{(h_w)}$, the additional terms $\theta^{(h_w)}G^{(h_w+1)}{}_k B_{(h_w+1)|(l_w+1)}$ must vanish according to the first of the above relationships. Hence (23.17) remains unchanged.

Application to hypersurface theory. If V_n is a hypersurface, the integrability conditions $[w, v]$ may be derived more easily from (20.12), (20.13) and (20.14) instead of from (20.7). Of the integrability conditions, $[0, 1]$ is a consequence of (11.21) and $[0, 2]$, $[1, 1]$ and $[1, 2]$ may be written as

(23.22) $B_{(jk)}^- = 0,$

(23.23) $B_{i(k}B_{j)-h} = K_{hijk} - C_{hijk} + G_{i(j}E_{k)-h} + G_{h(k}E_{j)-i},$

(23.24) $B_{i(j:k)}^- = -C_{\beta ijk}Z^\beta + G_{i(k}F_{j)}^-,$

where the conformal vector F_j , of class C^{r-3} , is defined by the equations

(23.25) $F_j = (1/(n - 1))G^{(\sigma_2)}B_{j\sigma_1: \sigma_2}.$

These equations are simply equations (22.2), (22.13) and (22.20) respectively after simplification by means of (11.24), (20.10), (20.11), (20.18) and (21.13). Equations (23.23) and (23.24) are the *conformal Gauss equations* and *conformal Codazzi equations* respectively for the hypersurface V_{m-1} . The vector F_j defined by (23.25) plays an important role in the conformal geometry of V_{m-1} . It is called the *deviation vector*.

The remaining conditions are $[2, 1]$ and $[2, 2]$. The first of these is identical with the conformal Codazzi equations according to the italicized statement of this section. We substitute the values of $U^{(h_2)}{}_{(i_2)}$ and $U^{h_1}{}_{(i_2)}$ given by (20.18) in (23.6) (condition $[2, 2]$). To simplify the resulting equations, we note that, according to (11.24) and (20.10), $D_{\alpha\beta jk}G^\alpha{}_{(l_2)}G^\beta{}_{(i_2)} = C_{\alpha\beta jk}Z^\alpha Z^\beta B_{(l_2)}B_{(i_2)} = 0$ and that, according to §17, $B_{(i_2):(jk)}^- = B_{\sigma i_2}K^\sigma{}_{i_1jk} + B_{i_1\sigma}K^\sigma{}_{i_2jk}$. If use is made of these equations as well as of (8.3), (20.11) and (21.13), it is found that condition $[2, 2]$ is true identically. Therefore conditions $[0, 2]$, $[1, 1]$ and $[1, 2]$ constitute the complete set of integrability conditions of the conformal Frenet equations for a hypersurface. All of the above conditions are valid in any hypersurface of class C^r with $r \geq 4$.

24. The third derivatives of the relative conformal curvature. We assume that (14.8) holds. Then E_{ij} is of class C^1 . The integrability conditions of the

first set of equations of (20.9) are $\psi_{(i;j)^-} = 0$. We denote these equations by the symbol $[\psi]$. In view of the second set of (20.9), these integrability conditions are equivalent to

$$(24.1) \quad E_{(ij)^-} = 0.$$

According to §17, the integrability conditions of the second set of (20.9) may be written as

$$(24.2) \quad \psi_{i:(jk)^-} = \psi_h K^h_{ijk}.$$

We denote these equations by the symbol $[\psi_i]$. Also, from (20.9),

$$(24.3) \quad \begin{aligned} \psi_{i:jk} = & \psi_{:ik}\psi_{:j} + \psi_{:i}\psi_{:jk} + E_{ij:k} - \mu_{\alpha:k}G^{\alpha}_{ij} - \mu_{\alpha}G^{\alpha}_{ij:k} \\ & + (1/(m-2))[\rho_{\alpha\gamma:\gamma}G^{\alpha}_{:i}G^{\beta}_{:j}G^{\gamma}_k + \rho_{\alpha\beta}G^{\alpha}_{:ik}G^{\beta}_{:j} + \rho_{\alpha\beta}G^{\alpha}_{:i}G^{\beta}_{:jk}] \\ & - (G_{ij}/2)[2e^{2\psi}\mu^2\psi_{:k} + 2e^{2\psi}\mu\mu_{:k} + 2G^{hl}\psi_{:h}\psi_{:lk} \\ & + (2e^{2\psi}\rho\psi_{:k} + e^{2\psi}\rho_{:k})/(m-1)(m-2)]. \end{aligned}$$

Now equations corresponding to (24.2) and (24.3) are true in any \bar{V}_n in \bar{V}_m . Consequently the replacement principle stated in Theorem 9.2 may be applied if the resulting equations are conformally invariant. This will be seen to be the case.

The value of $\psi_{i:jk}$ given by (24.3) is substituted in (24.2) and the replacement principle is applied. If account is taken of (7.7), (9.7), (9.8), (9.10), (11.11), (12.5), (15.6) and (21.1) with $w=1, v=2$, we readily obtain

$$(24.4) \quad \begin{aligned} E_{i:(j:k)^-} = & \frac{1}{(n-1)} A_{\alpha\beta}G^{\alpha}_{:i}G^{\beta}_{:(jG^{\gamma}_{:k})^-} :tG^{hl} + \frac{1}{(n-1)} C_{\alpha(j}G^{\alpha}_{:k)^-} :i \\ & - \frac{1}{(m-2)} {}^0\rho_{\alpha\beta\gamma}G^{\alpha}_{:i}G^{\beta}_{:j}G^{\gamma}_k. \end{aligned}$$

These are the integrability conditions of the second set of equations (20.9). According to the conformal Frenet equations and (21.1),

$$(24.5) \quad A_{\alpha\beta}G^{\alpha}_{:i}G^{\beta}_{:kh} :tG^{hl} = G^{(s_2)}U^{(h_2)}_{k(s_2)}B_{(h_2)|ij}.$$

Also, it follows from §12 that if $m > 3$, the conformal value of ${}^0\rho_{\alpha\beta\gamma}G^{\alpha}_{:i}G^{\beta}_{:j}G^{\gamma}_k$ is given by (12.11) and (12.18). If $m=3, n$ must be 2. It follows from §§11, 12 that $C^{\alpha}_{\beta\gamma\delta}$ is a zero tensor and that $\rho_{\alpha\beta\gamma}$ is a conformal tensor so that, in this case, ${}^0\rho_{\alpha\beta\gamma} = \rho_{\alpha\beta\gamma}$. Also, if V_n is a hypersurface (as is true in the present case $m=3$), it follows from (20.11), (20.18), (21.13) and (23.25) that

$$(24.6) \quad (1/(n-1))G^{(s_2)}U^{(h_2)}_{k(s_2)}B_{(h_2)|ij} = B_{ij}F_k.$$

If use is made of (24.5), (24.6) and these statements, the integrability conditions (24.4) may be written as

$$(24.7) \quad E_{i(j:k)^-} = \frac{1}{(n-1)} [G^{(\sigma_2)} U^{(h_2)} k^{-(\sigma_2)} B_{(h_2)|i}{}^- + C_{\alpha(\gamma} G^{\alpha k)^-}{}_{-i}] - \frac{1}{(m-3)} C^{\epsilon_{ijk}}{}_{\epsilon}, \quad m > 3,$$

$$(24.8) \quad E_{i(j:k)^-} = B_{i(j} F_{k)^-} - \rho_{\alpha\beta\gamma} G^{\alpha}{}_{i} G^{\beta}{}_{j} G^{\gamma}{}_{k}, \quad m = 3.$$

Either (24.7) or (24.8), depending upon the value of m , are conditions $[\psi_i]$. Also, according to the above remarks, if V_n is a hypersurface, (24.7) becomes

$$(24.9) \quad E_{i(j:k)^-} = B_{i(j} F_{k)^-} + \frac{1}{(n-1)} C_{\alpha(\gamma} G^{\alpha k)^-}{}_{-i} - \frac{1}{(m-3)} C^{\epsilon_{ijk}}{}_{\epsilon}, \quad m = n + 1, m > 3.$$

We now prove the following theorem.

THEOREM 24.1. *If $n > 3$, the integrability conditions (24.7) are a consequence of the conformal Gauss-Codazzi equations.*

Conformal differentiation of the conformal Gauss equations (22.13) leads to the equations

$$C_{hijk:l} = K_{hijk:l} + B_{i(j|k)^-}{}_{-h:l} + G_{i(j} E_{k)^-}{}_{-h:l} + G_{h(k} E_{j)^-}{}_{-i:l}.$$

To these equations, we add the other two sets obtained by adding cyclic permutations on the indices j, k, l and simplify the result by using (14.9). Now we multiply these last equations by G^{hl} and sum for h, l making use of (21.5). If $m > 3$, the left member of these final equations may be replaced by the right member of (12.19). The resulting equations are

$$(24.10) \quad \frac{(n-3)}{(m-3)} C^{\alpha_{ijk}}{}_{\alpha} + \frac{1}{(m-3)} G_{ij} C^{\alpha_{hkl}}{}_{-i} G^{hl} + C_{\beta(k} G^{\beta}{}_{j)^-}{}_{-i} + C_{\alpha\beta\gamma\delta} G^{\alpha h} [G^{\alpha}{}_{h\gamma} G^{\beta}{}_{i} G^{\gamma}{}_{k} G^{\delta}{}_{l} + G^{\alpha}{}_{h} G^{\beta}{}_{i} G^{\gamma}{}_{j} G^{\delta}{}_{k}] = [B_{i(j|k)^-}{}_{-h:l} + B_{il|h(j:k)^-}] G^{hl} + (n-3) E_{i(k:j)^-} + G_{i(j} E^{h}{}_{k)^-}{}_{-i} + E_{i(j} G_{k)^-}{}_{-i}$$

where we have written

$$(24.11) \quad E^h{}_k = G^{hl} E_{lk}.$$

By means of (11.19) and the conformal Codazzi equations (22.20), the terms involving $C_{\alpha\beta\gamma\delta}$ in (24.10) may be eliminated. Also, the various terms such as $B_{i(j|k)^-}{}_{-h:l}$ in (24.10) may be eliminated by taking account of (21.10). The resulting equations are

$$\begin{aligned}
 & \frac{1}{(m-3)} [(n-3)C^{\alpha_{ijk}: \alpha} + G_{ij}C^{\alpha_{h}lk}: \alpha G^{hl}] \\
 (24.12) \quad & + \frac{1}{(n-1)} [(n-3)C_{\beta(k}G^{\beta}_{j)}{}_{-i} + C_{\beta l}G^{\beta}_{h(j}G_{k)}{}_{-i}G^{hl} \\
 & + (n-3)G^{(\sigma_2)}U^{(h_2)}{}_{j-(\sigma_2)}B_{(h_2)|ik}- \\
 & + G^{(\sigma_2)}G^{(l_2)}U^{(h_2)}{}_{l_1(\sigma_2)}B_{(h_2)|l_2(j}G_{k)}{}_{-i}] = (n-3)E_{i(k: j)}- \\
 & + G_{i(j}E^{h_k)}{}_{-: h} + E_{: (j}G_k)-i.
 \end{aligned}$$

We multiply these equations by G^{ik} and sum for i, k and obtain

$$\begin{aligned}
 (24.13) \quad & 2(n-2) \left[E_{: j} - E^h{}_{j: h} + \frac{1}{(m-3)} C^{\alpha_{h}lj}: \alpha G^{hl} \right. \\
 & \left. + \frac{1}{(n-1)} (G^{(\sigma_2)}G^{(l_2)}U^{(h_2)}{}_{l_1(\sigma_2)}B_{(h_2)|l_2j} - C_{\beta l}G^{\beta}_{hj}G^{hl}) \right] = 0.
 \end{aligned}$$

If $n=2$, these equations are trivial. However, if $n>2$, and the results of (24.13) are substituted in (24.12), equations (24.12) become

$$\begin{aligned}
 (24.14) \quad & (n-3)E_{i(j: k)}- = \frac{(n-3)}{(n-1)} [G^{(\sigma_2)}U^{(h_2)}{}_{k-(\sigma_2)}B_{(h_2)|ij}- + C_{\alpha(j}G^{\alpha}_{k)}{}_{-i}] \\
 & - \frac{(n-3)}{(m-3)} C^{\epsilon_{ijk}: \epsilon}.
 \end{aligned}$$

If $n=3$, these equations are true trivially. However, if $n>3$, (24.14) coincides with (24.7). This completes the proof. Incidentally, we note that if $n=3$, equations (24.13) which may be obtained from (24.7) by multiplying with G^{ik} and summing on i, k are a consequence of the conformal Gauss-Codazzi equations.

Another set of partial differential equations satisfied by the deviation tensor E_{ij} is now derived from the conformal Gauss equations if $n>2$. These equations are not related to the integrability conditions (24.7). As has been noted in §22, (22.9) and (22.10) are consequences of the conformal Gauss equations. From these two sets of equations, we readily obtain

$$(24.15) \quad (n-2)E_{ij} = \mathcal{B}_{ij} + C_{ij} - K_{ij} - \frac{1}{2(n-1)} (\mathcal{B} + C - K)G_{ij}$$

after account is taken of (22.17) and (22.18). Conformal differentiation of (24.15) leads to the differential equations

$$(24.16) \quad (n-2)E_{i(j: k)}- = \mathcal{B}_{ijk} + C_{ijk} - K_{ijk}$$

where K_{ijk} is defined by (14.14) and B_{ijk} and C_{ijk} are defined by the analogous equations

$$(24.17) \quad \mathcal{B}_{ijk} = \mathcal{B}_{i(j:k)^-} + \frac{1}{2(n-1)} \mathcal{B}_{:(jG_k)^-i} = \mathcal{B}_{i(j:k)^-},$$

$$(24.18) \quad C_{ijk} = C_{i(j:k)^-} + \frac{1}{2(n-1)} C_{:(jG_k)^-i}.$$

25. The second derivatives of the mean curvature. Discussion for a hypersurface. In obtaining the integrability conditions of the last set of equations (20.9), we divide our work into two sections. In this section, we consider the simplest case only, that is, the case where V_n is a hypersurface of V_m so that $m = n + 1$. In this instance the calculations are considerably shorter than for a general subspace of V_m . The general case is considered in the following section. For the work of this section, we assume that (12.23) holds.

For a hypersurface, the last set of equations (20.9) may be replaced by (20.23). If account is taken of (23.25), equations (20.23) may be written as

$$(25.1) \quad \mu_{:j} = e^{-\psi} \left[F_j + B_{jh} \psi_{:l} G^{hl} - \frac{1}{(n-1)} \rho_{\alpha\beta} Z^\alpha G^\beta \right].$$

The integrability conditions of these equations are

$$(25.2) \quad \mu_{:(jk)^-} = 0.$$

The replacement principle may be applied to equations (25.1) and (25.2) for reasons like those stated in the beginning of the preceding section. This means that (25.2) is equivalent to

$$(25.3) \quad {}^0\mu_{:(jk)^-} = 0.$$

Conformal differentiation of (25.1) leads to equations in which we make replacements using (9.7), (13.15), (20.13) and (20.14). In this way, we obtain the equations

$$(25.4) \quad \begin{aligned} {}^0\mu_{:jk} &= F_{j:k} + B_{jh} E_{lk} G^{hl} + \frac{1}{(m-2)} {}^0\rho_{\alpha\beta} G^\alpha G^\beta B_{jh} G^{hl} \\ &- \frac{{}^0\rho}{2(m-1)(m-2)} B_{ik} - \frac{1}{(n-1)} {}^0\rho_{\alpha\beta} \gamma Z^\alpha G^\beta G^\gamma \\ &+ \frac{1}{(n-1)} {}^0\rho_{\alpha\beta} [B_{kh} G^{hl} G^\alpha G^\beta - Z^\alpha Z^\beta B_{jk}]. \end{aligned}$$

Now $m = n + 1$ and $\rho_{\alpha\beta}$, B_{jk} are symmetric tensors and ${}^0\rho_{\alpha\beta;\gamma} = {}^0\rho_{\alpha\beta,\gamma}$. Hence substitution of (25.4) in (25.3) leads to the equations

$$(25.5) \quad F_{(j:k)^-} = B_{h(k} E^h_{j)^-} + \frac{1}{(n-1)} {}^0\rho_{\alpha\beta\gamma} Z^\alpha G^\beta G^\gamma$$

where $\rho_{\alpha\beta\gamma}$ is defined by (12.5) and account has been taken of (11.21). These equations are the integrability conditions of (25.1). As in the case of (24.4), the integrability conditions (25.5) may be written as

$$(25.6) \quad F_{(j;k)^-} = B_{h(k}E^h_{j)^-} + \rho_{\alpha\beta\gamma}Z^\alpha G^\beta_j G^\gamma_k, \quad n = 2,$$

$$(25.7) \quad F_{(j;k)^-} = B_{h(k}E^h_{j)^-} + \frac{1}{(n-2)} C^\epsilon_{\alpha jk} \epsilon Z^\alpha, \quad n > 2,$$

where $C^\epsilon_{\alpha jk}$ is defined by (12.21). We denote the integrability conditions (25.6) or (25.7) by the symbol $[\mu]$.

We now prove the following theorem.

THEOREM 25.1. *If $n > 2$, the integrability conditions (25.7) are a consequence of the conformal Gauss-Codazzi equations.*

We first derive some equations which are needed in the proof of this theorem. Conformal differentiation of the conformal Codazzi equations (23.24) leads to

$$(25.8) \quad B_{j(i;k)^-l} = - (C_{\alpha jik}Z^\alpha)_{:l} + G_{j(k}F_{i)^-l}.$$

From the Ricci identities of §17,

$$(25.9) \quad B_{ij:(lk)^-} = B_{hj}K^h_{ilk} + B_{ih}K^h_{jlk}.$$

From (25.8) and (25.9), we obtain

$$(25.10) \quad B_{ji:lk} = B_{jk:il} - (C_{\alpha jik}Z^\alpha)_{:l} + G_{j(k}F_{i)^-:l} + B_{hj}K^h_{ilk} + B_{ih}K^h_{jlk}.$$

We multiply (25.10) by G^{il} and sum for the indices i, l . In the resulting equations, we apply the alternation operation to the indices j, k and simplify, using (11.14), (14.4) and (23.25). In this way, we find that

$$(25.11) \quad (n-2)F_{(j;k)^-} = [C_{\alpha\beta\gamma\delta}Z^\alpha G^\beta_j G^\gamma_k G^\delta_i]_{:i} G^{il} + G^{il} B_{hi} K^h_{ljk} + B_{h(j} K^h_{k)^-}.$$

If use is made of (7.10), (8.13), (20.13) and (20.14), we find that

$$(25.12) \quad [C_{\alpha\beta\gamma\delta}Z^\alpha G^\beta_j G^\gamma_k G^\delta_i]_{:i} G^{il} = C_{\alpha\beta\gamma\delta} : Z^\alpha G^\beta_j G^\gamma_k G^\delta_i + C_{\alpha\beta\gamma\delta} G^{il} Z^\alpha G^\beta_i [B_{kj} Z^\gamma G^\delta_j + B_{ji} G^\gamma_k Z^\delta]$$

since $C_{\alpha\beta\gamma\delta} Z^\alpha Z^\beta = 0$, $C_{\alpha\beta\gamma\delta} G^{il} G^{\sigma h} B_{i\sigma} G^\alpha_h G^\beta_i = 0$. Now $G^{\beta\epsilon} = A^{\beta\epsilon} - Z^\beta Z^\epsilon$, so that $C_{\alpha\beta\gamma\delta} : Z^\alpha G^\beta_j G^\gamma_k G^\delta_i = C^\epsilon_{\alpha\beta\gamma\delta} \epsilon Z^\alpha G^\beta_j G^\gamma_k$. If this is substituted in (25.12) and the result is then substituted in (25.11), we obtain

$$(25.13) \quad (n-2)F_{(j;k)^-} = C^\epsilon_{\alpha jk} \epsilon Z^\alpha + C_{\alpha\beta\gamma\delta} Z^\alpha G^{il} G^\beta_i Z^\gamma G^\delta_{(j} B_{k)^-l} + G^{il} B_{hi} K^h_{ljk} + B_{h(j} K^h_{k)^-}.$$

These equations are consequences of the conformal Codazzi equations.

Also, from the conformal Gauss equations (23.23), we may obtain equa-

tions for the tensors $G^{il}B_{hi}K^h{}_{ljk}$, $B_{jh}K^h{}_k$ and $B_{hk}K^h{}_j$, which occur in (25.13). From these equations we find that

$$(25.14) \quad G^{il}B_{hi}K^h{}_{ljk} + B_{h(j}K^h{}_{k)} = C_{\alpha\delta}G^\alpha{}_iG^\delta{}_{(k}B_{j)}-lG^{il} + (n - 2)B_{h(k}E^h{}_{j)}-$$

after account is taken of (11.16) and of the equations $C_{\alpha\beta\gamma\delta}G^\alpha{}_iG^\beta{}_hG^\gamma{}_jG^\delta{}_kG^{il}G^{h\sigma}B_{\sigma l} = 0$ which are a consequence of (11.14) and (23.22). Now, if use is made of (11.22), we find that (25.14) becomes

$$(25.15) \quad G^{il}B_{hi}K^h{}_{ljk} + B_{h(j}K^h{}_{k)} = C_{\alpha\beta\gamma\delta}G^\alpha{}_iZ^\beta Z^\gamma G^\delta{}_{(j}B_{k)}-lG^{il} + (n - 2)B_{h(k}E^h{}_{j)}-$$

These equations are consequences of the conformal Gauss equations.

If (25.13) is simplified by means of (25.15) and use is made of (11.14), we find that

$$(25.16) \quad (n - 2)F_{(j; k)} = (n - 2)B_{h(k}E^h{}_{j)} + C^\epsilon{}_{\alpha jk} \epsilon Z^\alpha$$

is a consequence of the conformal Gauss-Codazzi equations. If $n > 2$, these equations are equivalent to (25.7). This completes the proof of the theorem.

26. The second derivatives of the mean curvature normal. Discussion for the general case. We return to a consideration of the last set of equations (20.9) in the general case. We assume that (14.8) holds. According to (17.1), the integrability conditions of these equations are $\mu^\alpha{}_{(jk)} = -\mu^\beta R^\alpha{}_{\beta jk}$. As in the two previous sections, the replacement principle may be applied to these equations. After replacements and utilization of (9.7), the integrability conditions become

$$(26.1) \quad {}^0\mu^\alpha{}_{(jk)} = 0.$$

In the calculations that follow, only the main links in the chain of the argument are given explicitly and the intervening links are only stated in outline form. This is done in order to avoid the appearance of several lengthy tensor equations which do not differ essentially from those which actually occur in the following calculations. An expression for ${}^0\mu^\alpha{}_{jk}$ may be obtained by conformal differentiation of the last set of equations (20.9) and employment of the replacement principle. If this expression is substituted in (26.1) and the result simplified by means of (8.15), (9.7), (9.10), (12.5), (13.15), (15.6) and (20.9), we obtain the equivalent integrability conditions

$$(26.2) \quad \begin{aligned} &G^\alpha{}_{j-h}{}_{ik}G^{hl} + (n - 1)G^\alpha{}_{h(j}E^h{}_{k)} - A_{\beta\gamma}G^\beta{}_{h(j}G^\gamma{}_{k)}-g_l{}_{\sigma_2}G^{hl}G^{(\sigma_2)}G^\alpha{}_l \\ &+ C_{\beta\gamma}G^\beta{}_{h(j}G^\gamma{}_{k)}-G^{hl}G^\alpha{}_l + G^\alpha{}_{h(k}K^h{}_{j)} + G^\alpha{}_{h}K^h{}_{(j; k)}- \\ &+ (n - 2)G^\alpha{}_{h(k}E^h{}_{j)} + (n - 2)G^\alpha{}_{h}E^h{}_{(j; k)} + E_{(k}G^\alpha{}_{j)}- \\ &+ C^\epsilon{}_{\beta\gamma\delta}{}^\epsilon G^{\beta\delta}G^\gamma{}_jG^\epsilon{}_k - \frac{(n - 1)}{(m - 2)} {}^0\rho_{\beta\gamma\delta}G^\gamma{}_jG^\delta{}_kH^{\alpha\beta} \\ &+ C^\epsilon{}_{\beta\gamma\delta}G^{hl}G^\gamma{}_j-[G^\beta{}_{hk}G^\delta{}_l + G^\beta{}_{h}G^\delta{}_{lk}] = 0. \end{aligned}$$

The terms involving $K^h{}_j$ and $K^h{}_{j;k}$ are replaced by means of (12.20),

(12.22) and (22.10). The terms involving⁽⁴¹⁾ $C^{\alpha}_{\beta\gamma\delta;\epsilon}$ are replaced by the use of (12.12) and the value of ${}^0\rho_{\beta\gamma\delta}$ is given by (12.11). After these various substitutions and further simplifications by means of the symmetry properties of the Weyl space tensor, (26.2) becomes

$$\begin{aligned}
 &G^{\alpha}_{j^{-}h:lk}G^{hl} + (n-1)G^{\alpha}_{hk^{-}}[\mathcal{B}^{h}_{j^{-}} + C^{h}_{j^{-}} - (n-1)E^{h}_{j^{-}}] \\
 &\quad + G^{\alpha}_{h}[\mathcal{B}^{h}_{(j:k)^{-}} - A_{\beta\gamma}G^{\beta}_{l(jG^{\gamma}_{k})^{-}\sigma_1:\sigma_2}G^{hl}G^{(\sigma_2)}] \\
 (26.3) \quad &+ H^{\alpha\epsilon} \left[(C_{\epsilon\beta\gamma\delta} + C_{\epsilon\delta\gamma\beta})G^{\beta}_{h(kG^{\gamma}_{j})^{-}G^{\delta}_{l}G^{hl}} + C_{\epsilon\beta jk:\gamma}G^{\beta\gamma} \right. \\
 &\quad \left. + \frac{1}{(m-3)} C^{\zeta}_{\epsilon kj:\zeta} \right] = 0.
 \end{aligned}$$

Now, from (20.7), we find that

$$\begin{aligned}
 G^{\alpha}_{jh:lk} &= G^{\alpha}_{jhlk} + [U^{(h_2)}_{jhlk} + U^{(h_2)}_{jh}G^{h_2}_k]G^{\alpha}_{(h_2)} \\
 (26.4) \quad &+ [\bar{U}^{(h_2)}_{jhlk} + U^{(h_2)}_{jhl:k} + U^{(\sigma_2)}_{jhl}U^{(h_2)}_{(\sigma_2)k} + U^{h_1}_{jhl}G^{h_2}_k]G^{\alpha}_{(h_2)} \\
 &+ [U^{(\sigma_2)}_{jhl}U^{h_1}_{(\sigma_2)k} + U^{h_1}_{jhl:k}]G^{\alpha}_{h_1}
 \end{aligned}$$

and that

$$(26.5) \quad A_{\beta\gamma}G^{\beta}_{jl}G^{\gamma}_{k\sigma_1:\sigma_2} = U^{(h_2)}_{k(\sigma_2)}B_{(h_2)jl}.$$

Also, as a consequence of (12.20),

$$\begin{aligned}
 H^{\alpha\epsilon} \left[(C_{\epsilon\beta\gamma\delta} + C_{\epsilon\delta\gamma\beta})G^{\beta}_{h(kG^{\gamma}_{j})^{-}G^{\delta}_{l}G^{hl}} + C_{\epsilon\beta jk:\gamma}G^{\beta\gamma} + \frac{1}{(m-3)} C^{\zeta}_{\epsilon kj:\zeta} \right] \\
 (26.6) \quad &= H^{\alpha\epsilon} \left[C_{\epsilon(k:j)^{-}} + \frac{(n-1)}{(m-3)} C^{\zeta}_{\epsilon kj:\zeta} \right].
 \end{aligned}$$

We substitute these values in (26.3) and multiply successively by $A_{\alpha\beta}G^{\beta}_{(i_1)}$ ($v=1, 2, \dots, M, \infty$) and simplify using (18.13), (21.1) and (21.2). In this way we obtain the following equations which are equivalent⁽⁴²⁾ to the integrability conditions (26.1) if m exceeds 3:

$$\begin{aligned}
 (26.7) \quad &[U^{(h_2)}_{j^{-}h lk^{-}} + U^{(h_2)}_{j^{-}hl:k^{-}} + U^{(\sigma_2)}_{j^{-}hl}U^{(h_2)}_{(\sigma_2)k^{-}} \\
 &+ U^{h_1}_{j^{-}hl}G^{h_2}_k]G^{hl}B_{(h_2)l(i_2)} + [\mathcal{B}^{h}_{j^{-}} + C^{h}_{j^{-}} - (n-1)E^{h}_{j^{-}}]B_{hk^{-}l(i_2)} \\
 &= \left[C_{\epsilon(j:k)^{-}} + \frac{(n-1)}{(m-3)} C^{\zeta}_{\epsilon jk:\zeta} \right] G^{\epsilon}_{(i_2)},
 \end{aligned}$$

$$\begin{aligned}
 (26.8) \quad &[U^{(h_3)}_{j^{-}h lk^{-}} + U^{(h_2)}_{j^{-}hl}G^{h_3}_k]G^{hl}B_{(h_3)l(i_3)} \\
 &= \left[C_{\epsilon(j:k)^{-}} + \frac{(n-1)}{(m-3)} C^{\zeta}_{\epsilon jk:\zeta} \right] G^{\epsilon}_{(i_3)},
 \end{aligned}$$

⁽⁴¹⁾ The assumption $m > 3$ is implicit in these substitutions. In the remaining case, $m = 3$, it follows that $n = 2$. This case is discussed in §25.

⁽⁴²⁾ This equivalence has been established by the use of the following equations of chapter V: $[1, 1]$, $[B 1]$, $[B 2]$, $[D 1]$ with $w = 1$.

$$(26.9) \quad B_{j^{-h}lk^{-1}(i_4)}G^{hl} = \left[C_{\epsilon(j:k)^-} + \frac{(n-1)}{(m-3)} C_{\epsilon jk:\xi}^* \right] G^{\epsilon(i_4)},$$

$$(26.10) \quad \left[C_{\epsilon(j:k)^-} + \frac{(n-1)}{(m-3)} C_{\epsilon jk:\xi}^* \right] G^{\epsilon(i_u)} = 0, \quad u = 5, 6, \dots, M, \infty.$$

We denote the integrability conditions (26.7), (26.8), (26.9) and (26.10) by the symbols $[\mu^\alpha, 2]$, $[\mu^\alpha, 3]$, $[\mu^\alpha, 4]$ and $[\mu^\alpha, u]$, $u > 4$, respectively. In writing these equations, we have omitted the first set ($v=1$) obtained by multiplying (26.3) by $A_{\alpha\beta}G^\beta$. For this first set of equations becomes an identity after application is made of (7.11) [equivalent to (21.5)] and (21.9) with $w=1$.

For a hypersurface, $m=n+1$ and $M=2$. In this case, (26.8) to (26.10) become vacuous so that (26.7) are the only integrability conditions. These equations (26.7) are equivalent to the integrability conditions (25.7) previously obtained for a hypersurface. Consequently the integrability conditions (25.7) for a hypersurface are $[\mu^\alpha, 2]$. The proof of this statement follows. The expression which multiplies $B_{(h_2)(i_2)}$ in (26.7) is equal to $A_{\alpha\beta}G^\alpha_{j^{-h}lk^{-1}}G^{hl}G^\beta_{(i_2)}$. Now for a hypersurface, according to (11.21), (20.10), (20.13) and (20.14),

$$(26.11) \quad A_{\alpha\beta}G^\alpha_{j^{-h}lk^{-1}}G^\beta_{(i_2)}G^{hl} = B_{j^{-h}:lk^{-1}}G^{hl}B_{(i_2)}.$$

Also, from (11.23), (20.10) and (20.14),

$$(26.12) \quad C_{\epsilon j:k}G^\epsilon_{(i_2)} = [(C_{\epsilon j}Z^\epsilon)_{:k} - C_{\epsilon j}Z^\epsilon_{:k}]B_{(i_2)} = C_{hj}B^{hk} \cdot B_{(i_2)}.$$

Also, from (20.11) and (22.18),

$$(26.13) \quad \mathcal{B}^h_{(jB_k)^{-h}(i_2)} = B^h_{\sigma_1}B_{\sigma_2(jB_k)^{-h}(i_2)}G^{(\sigma_2)} = 0.$$

If the results stated in (26.11), (26.12) and (26.13) are substituted in (26.7) and account is taken of (23.25), we obtain (25.7).

We now return to a consideration of the general case and prove the following theorem which is a generalization of Theorem 25.1:

THEOREM 26.1. *If $n > 2$, the integrability conditions (26.7), (26.8), (26.9) and (26.10) are a consequence⁽⁴³⁾ of the equations $[1, v]$ and $[2, v]$, $v = 1, 2, \dots, M, \infty$.*

The first stage of the proof consists in obtaining new tensor equations which may be solved for the expression $G^\alpha_{j^{-h}:lk^{-1}}G^{hl}$ occurring in (26.3). Conditions $[1, v]$ are equivalent to the equations $G^\alpha_{jh:k} = G^\alpha_{jk:h} + G^\alpha_{\sigma}K^\sigma_{jhh} - R^\alpha_{jhh}$.

⁽⁴³⁾ The proofs of the theorems of §§24-26 also depend upon the definitions and identities of chapter III, the extended conformal Frenet equations and the A, D and B conditions. However, if V_m is an \bar{R}_m , the extended conformal Frenet equations and B -conditions (which involve space indices) may be omitted from this list. Some of the above equations are also used in the derivation of the various integrability conditions which appear in §§24-26.

Conformal differentiation of these equations with respect to x^l leads to

$$(26.14) \quad G^{\alpha}_{jh:kl} = G^{\alpha}_{jk:hl} + G^{\alpha}_{gl}K^g_{ihk} + G^{\alpha}_{g}K^g_{ihk:l} - R^{\alpha}_{jhk:l}.$$

Now conditions $[2, v]$ are equivalent to

$$(26.15) \quad G^{\alpha}_{jh:lk} = G^{\alpha}_{jh:kl} + G^{\alpha}_{gh}K^g_{jlk} + G^{\alpha}_{ig}K^g_{hlk} - R^{\alpha}_{\beta lk}G^{\beta}_{jh}.$$

We substitute the value for $G^{\alpha}_{jh:kl}$ given by (26.14) in (26.15). Then we multiply the equations by G^{hl} and perform the alternation operation on the indices j, k . In this manner, we obtain

$$(26.16) \quad G^{\alpha}_{j-h:lk}G^{hl} = 2G^{\alpha}_{gl}K^g_{j-hk}G^{hl} + G^{\alpha}_{h(j}K^h_{k)-} + G^{\alpha}_{g}K^g_{j-hk-} : G^{hl} - R^{\alpha}_{j-hk-} : G^{hl} - R^{\alpha}_{\beta l(k}G^{\beta}_{j)-h}G^{hl}$$

after taking account of (14.2).

We replace the conformal Riemann tensor in these equations by (16.9) and (16.10) and then simplify using (11.14) and (14.4). In this way (26.16) becomes

$$(26.17) \quad \begin{aligned} \frac{(n-2)}{(n-1)} G^{\alpha}_{j-h:lk}G^{hl} &= G^{\alpha}_{h(j}K^h_{k)-} + G^{\alpha}_{g}K^g_{hjk-} : G^{hl} \\ &+ \left[C^{\alpha}_{hjk} + \frac{1}{(n-1)} H^{\alpha\beta}C_{\beta(k}G_{j)-h} \right] : G^{hl} \\ &+ G^{\alpha}_{(k}E^h_{j)-:h} + G^{\alpha}_{h}E^h_{(k:j)-} + C^{\alpha}_{\beta l(j}G^{\beta}_{k)-h}G^{hl} \\ &+ \frac{1}{(n-1)} G^{hl}G^{\beta}_{hk-} [C_{\beta j-}G^{\alpha}_{l} - C_{\beta l}G^{\alpha}_{j-}] \\ &+ \frac{1}{(n-1)} [G^{\alpha}_{h(k}B^h_{j)-} + G^{\alpha}_{h}B^h_{(j:k)-}] \\ &+ \frac{1}{(n-1)} G^{(g_2)}G^{hl}A_{\gamma\beta}G^{\beta}_{hj-} [G^{\gamma}_{k-\sigma_1: \sigma_2}G^{\alpha}_{l} - G^{\gamma}_{l\sigma_1: \sigma_2}G^{\alpha}_{k-}]. \end{aligned}$$

Now if use is made of (12.12), (12.21) and (11.14), we find that

$$(26.18) \quad \begin{aligned} \left[C^{\alpha}_{hjk} + \frac{1}{(n-1)} H^{\alpha\beta}C_{\beta(k}G_{j)-h} \right] : G^{hl} &= C^{\alpha}_{\beta kj} : G^{\beta\epsilon} \\ &+ \frac{1}{(n-1)} H^{\alpha\beta} \left[C_{\gamma\beta kj: \delta}G^{\gamma\delta} - \frac{(n-2)}{(m-3)} C^{\gamma}_{\beta kj: \zeta} \right] + C^{\alpha}_{h\gamma(j}G^{\gamma}_{k)-l}G^{hl} \\ &+ \frac{1}{(n-1)} H^{\alpha\beta} [C_{h\beta k-\delta} + C_{\delta\beta k-h}]G^{\delta}_{lj-}G^{hl} + C_{h(j}G^{\alpha}_{k)-l}G^{hl} \\ &+ C_{\beta(j}G^{\beta}_{k)-l}G^{hl}G^{\alpha}_{h}. \end{aligned}$$

Also, from (22.10), which is a consequence of condition [1, 1], we find that

$$(26.19) \quad G^{\alpha}_{h(j)K^h_{k-}} = G^{\alpha}_{h(j)B^h_{k-}} + G^{\alpha}_{h(j)C^h_{k-}} + (2 - n)G^{\alpha}_{h(j)E^h_{k-}}.$$

From (22.10) and (12.12), we obtain

$$(26.20) \quad \begin{aligned} G^{\alpha}_{\rho}K^{\rho}_{hjk} : G^{hl} &= G^{\alpha}_{\rho}G^{hl}[-K^{\rho}_{hlij:k} - K^{\rho}_{hkl:i}] = G^{\alpha}_{h}K^h_{(k:i)-} \\ &= G^{\alpha}_{h}B^h_{(k:i)-} + (C_{\epsilon\beta k-l} + C_{l\beta k-\epsilon})G^{\epsilon}_{h\gamma}G^{hl}G^{\alpha\beta} \\ &\quad + C_{\gamma\beta k:j} : \delta G^{\gamma\delta}G^{\alpha\beta} + \frac{(n-3)}{(m-3)} C^{\gamma}_{\beta jk} : \zeta G^{\alpha\beta} \\ &\quad + \frac{1}{(m-3)} G^{\alpha}_{\gamma}C^{\gamma}_{\gamma\delta k-} : \zeta G^{\gamma\delta} + C_{\beta(k)G^{\beta}_{j-}h}G^{\alpha}_{\gamma}G^{hl} \\ &\quad + E_{:(k)G^{\alpha}_{j-}} + (n-2)G^{\alpha}_{h}E^h_{(j:k)-}. \end{aligned}$$

If the results given by equations (26.18), (26.19) and (26.20) are substituted in (26.17), and account is taken of the fact that $H^{\alpha\beta} = A^{\alpha\beta} - G^{\alpha\beta}$ and of (11.14), equations (26.17) become

$$(26.21) \quad \begin{aligned} \frac{(n-2)}{(n-1)} G^{\alpha}_{j-h} : ik G^{hl} &= \frac{n^2 - 5n + 5}{(m-3)(n-1)} C^{\gamma}_{\beta jk} : \zeta G^{\alpha\beta} + \frac{(n-2)}{(n-1)} C_{\gamma\beta jk} : \delta G^{\gamma\delta} H^{\alpha\beta} \\ &\quad + \frac{(n-2)}{(m-3)(n-1)} C^{\gamma}_{\alpha jk} : \zeta + \frac{1}{(m-3)} G^{\alpha}_{\gamma}C^{\gamma}_{\gamma\delta k-} : \zeta G^{\gamma\delta} \\ &\quad + \frac{1}{(n-1)} G^{hl}C_{\beta\gamma} [(n-3)G^{\beta}_{h(j)G^{\gamma}_{k-}}G^{\alpha}_{i} \\ &\quad + G^{\beta}_{h(j)G^{\alpha}_{k-}}G^{\gamma}_{i} + (n-2)G^{\beta}_{h}G^{\gamma}_{(k)G^{\alpha}_{j-}i}] \\ &\quad + \frac{(n-2)}{(n-1)} (C_{\beta\gamma l j-} + C_{\beta l \gamma j-})G^{\gamma}_{hk}G^{hl}H^{\alpha\beta} \\ &\quad + \frac{(n-2)}{(n-1)} [G^{\alpha}_{h(j)B^h_{k-}} + G^{\alpha}_{h}B^h_{(k:i)-}] \\ &\quad + (n-2)G^{\alpha}_{h(k)E^h_{j-}} + (n-3)G^{\alpha}_{h}E^h_{(j:k)-} \\ &\quad + E_{:(k)G^{\alpha}_{j-}} + G^{\alpha}_{(k)E^h_{j-}h} \\ &\quad + \frac{1}{(n-1)} G^{(s_2)}G^{hl}A_{\gamma\beta}G^{\beta}_{\gamma-h} [G^{\gamma}_{k-s_1} : s_2 G^{\alpha}_{l} - G^{\gamma}_{l s_1 : s_2} G^{\alpha}_{k-}]. \end{aligned}$$

The derivation of equations (26.21) by the use of conditions [1, v] and [2, v] completes the first stage of the proof.

To complete the proof of the theorem, we now show that the integrability conditions (26.3) [equivalent to (26.7) through (26.10)] become identities when use is made of (26.21). If $n > 2$, we may solve (26.21) for $G^{\alpha}_{j-h} : ik G^{hl}$ and substitute the result in (26.3). When the result is simplified, (26.3) be-

comes, after multiplication by the factor $(n - 2)$,

$$\begin{aligned}
 (26.22) \quad & \frac{(n - 1)}{(m - 3)} [(n - 3)C_{\beta jk}^{\gamma} G^{\alpha\beta} + G^{\alpha j} C_{\gamma\delta k}^{\gamma} G^{\gamma\delta}] + (n - 3)C_{\beta(kG^{\beta}j)^{-}h} G^{\alpha} G^{hl} \\
 & + C_{\beta l} G^{\beta} G^h_{(jG^{\alpha}k)^{-}G^{hl}} + (n - 1)(n - 3)G^{\alpha} G^h_{(j:k)^{-}} \\
 & + (n - 1)E_{:(kG^{\alpha}j)^{-}} + (n - 1)G^{\alpha} G^h_{(kE^h j)^{-}:h} \\
 & + G^{(\sigma_2)} G^h G^{hl} A_{\gamma\beta} G^{\beta} G^h_{k-h} [(n - 3)G^{\gamma} G^{\alpha l}_{\sigma_1: \sigma_2} + G^{\gamma} G^{\alpha l}_{\sigma_1: \sigma_2} G^{\alpha j}] = 0.
 \end{aligned}$$

Since all the indices of (26.22) are tangent indices, equations (26.22) are equivalent to the ones obtained from them by multiplication with $A_{\alpha\epsilon} G^{\epsilon i}$. These new equations are

$$\begin{aligned}
 (26.23) \quad & \frac{(n - 1)}{(m - 3)} [(n - 3)C_{ijk}^{\gamma} G^{\gamma\delta} + G_{ij} C_{\gamma\delta k}^{\gamma} G^{\gamma\delta}] + (n - 3)C_{\beta(kG^{\beta}j)^{-}i} \\
 & + C_{\beta l} G^{hl} G^{\beta} G^h_{(jG^{\alpha}k)^{-}i} + (n - 1)(n - 3)E_{i(j:k)^{-}} + (n - 1)E_{:(kG^{\beta}j)^{-}i} \\
 & + (n - 1)G_{i(kE^h j)^{-}:h} + (n - 3)G^{(\sigma_2)} B_{(h_2) | i (k U^{(h_2)} j)^{-}(\sigma_2)} \\
 & + G^{(\sigma_2)} G^{hl} U^{(h_2)}_{l(\sigma_2)} B_{(h_2) | h (kG^{\beta}j)^{-}i} = 0
 \end{aligned}$$

after use is made of (26.5). If we multiply (26.23) by G^{ik} we obtain

$$\begin{aligned}
 (26.24) \quad & 2(n - 2) \left[\frac{(n - 1)}{(m - 3)} C_{\gamma\delta j}^{\gamma} G^{\gamma\delta} - C_{\beta l} G^{\beta} G^h_{jG^{hl}} + U^{(h_2)}_{l(\sigma_2)} B_{(h_2) | j h} G^{(\sigma_2)} G^{hl} \right. \\
 & \left. + (n - 1)(E_{:j} - E^h_{:j;h}) \right] = 0.
 \end{aligned}$$

Since $n > 2$, we may solve (26.24) for $C_{\gamma\delta j}^{\gamma} G^{\gamma\delta}$ and substitute in (26.23). Then (26.23) becomes

$$\begin{aligned}
 (26.25) \quad & (n - 3) \left[\frac{(n - 1)}{(m - 3)} C_{ijk}^{\gamma} G^{\gamma\delta} + C_{\beta(kG^{\beta}j)^{-}i} + (n - 1)E_{i(j:k)^{-}} \right. \\
 & \left. + G^{(\sigma_2)} B_{(h_2) | i (k U^{(h_2)} j)^{-}(\sigma_2)} \right] = 0.
 \end{aligned}$$

If $n = 3$, (26.25) is true identically so that (26.24) is equivalent to (26.23). According to the italicized statement following (24.14), equations (26.24) [which are identical with (24.13)] are a consequence of conditions [1, 1] and [1, 2]. Consequently this is also true for (26.23). If $n > 3$, (26.25) is equivalent to (26.23) since (26.24) may be obtained from (26.25) by summing with G^{ih} and (26.23) follows from (26.24) and (26.25). According to Theorem 24.1, equations (26.25) [which are identical with (24.7)] are a consequence of conditions [1, 1] and [1, 2]. Therefore this is also true for (26.2²). The preceding discussion of the two cases $n = 3$ and $n > 3$ shows that, after use of [1, 1] and

$[1, 2]$, (26.23) is an identity if $n > 2$. Since (26.23) is equivalent to the integrability conditions (26.3) by means of the conditions $[1, v]$ and $[2, v]$, the above remark completes the proof of Theorem 26.1. More precisely, the proof of this theorem shows that, for a fixed v between 2 and M inclusive, the integrability condition $[\mu^\alpha, v]$ is a consequence of conditions $[1, v-1]$, $[1, v]$, $[1, v+1]$ and $[2, v]$. (Of course, we omit $[1, v+1]$ from this list if $v = M$.)

Summary. The following table lists the important equations which have appeared in this chapter together with sufficient conditions for their validity:

(1) *the B-conditions*: $[B\ 1]$, $[B\ 2]$, $[B\ 3]$ if the basis beins $G^\alpha_{(i_w)}$ are a basis of class C^1 and $r \geq 3$.

(2) *the A-conditions*: $[A\ 1]$, $[A\ 2]$ if $r \geq 2$.

(3) *the R-conditions*: $[R\ 1]$, $[R\ 2]$, $[R\ 3]$ if the basis beins $G^\alpha_{(i_w)}$ are a basis of class C^1 and $r \geq 3$.

(4) *the D-conditions*: $[D\ 1]$, $[D\ 2]$ if the basis beins $G^\alpha_{(i_w)}$ are a basis of class C^1 and $r \geq 3$.

(5) *the integrability conditions of the extended conformal Frenet equations*:

(α) $[0, 2]$, $[w, v]$; $w = 1, 2, \dots, M$, $v = 1, 2, \dots, M$, ∞ , $v \geq w$, if the basis beins $G^\alpha_{(i_w)}$ are a basis of class C^2 and $r \geq 4$.

(β) $[\psi]$, $[\psi_i]$ if $r \geq 5$. If $n > 3$, conditions $[\psi_i]$ are a consequence of $[1, 1]$ and $[1, 2]$.

(γ) $[\mu^\alpha, u]$, $u = 2, 3, \dots, M$, ∞ if $r \geq 5$. If $n > 2$, conditions $[\mu^\alpha, u]$ are a consequence of $[1, v]$ and $[2, v]$.

If any $U^{(h_w)}_{(i_w+1)}$, $U^{(h_w-1)}_{(i_w+1)}$ occurring in any of the above equations is replaced by another which differs from it by an additive null solution, the equation remains unchanged and the additional tensors due to the presence of the null tensor must vanish. All of the sufficient conditions enumerated above are satisfied if r is equal to or greater than the maximum of the integers 5, $M+2$. It also follows from previous sections and the work of this chapter, that if the A , B , D , R and integrability conditions are valid on a V_n of class C^3 in a V_m of class C^4 then they are also valid in any \bar{V}_n in \bar{V}_m obtained from V_n in V_m by an allowable conformal transformation. We call the totality of A -conditions, R -conditions, D -conditions and the integrability conditions the *fundamental equations* of V_n .

If V_n is a hypersurface, the following simpler set of equations is equivalent to the set which appears above for a general subspace:

(1) *the B-conditions*: $[B' 1]$, $[B' 2]$ if $r \geq 1$.

(2) *the A-conditions*: $[A' 1]$, $[A' 2]$ if $r \geq 2$.

(3) *the R-conditions*: $[R' 1]$, $[R' 2]$ if $r \geq 1$.

(4) *the integrability conditions of the extended conformal Frenet equations*:

(α) $[0, 2]$, $[1, 1]$, $[1, 2]$ if $r \geq 4$.

(β) $[\psi]$, $[\psi_i]$ if $r \geq 5$.

(γ) $[\mu]$ if $r \geq 4$.

If V_m is a conformally euclidean space \bar{R}_m , the integrability conditions

$[w, v]$ are true identically if $|w - v| > 2$. In this case, the complete set of integrability conditions $[w, v]$ of the conformal Frenet equations are $[0, 2]$, $[w, v]$ where $w = 1, 2, \dots, M$ and $v = w, w + 1, w + 2$ subject to the inequality $v < M + 1$. The remaining integrability conditions which are not identities are $[\psi]$, $[\psi_i]$, $[\mu^\alpha, u]$ where $u = 2, 3, 4$. We note that all the indices in the fundamental equations of V_n are surface indices if V_m is an \bar{R}_m . Space indices occur only in the extended conformal Frenet equations and the B -conditions.

VI. SUBSPACES IN A CONFORMALLY EUCLIDEAN SPACE \bar{R}_m

The Riemannian geometry of subspaces V_n in an enveloping Riemann space V_m is based upon the various fundamental forms of V_n . But these fundamental forms are the basis for a complete characterization of V_n only in euclidean spaces and in spaces of constant curvature. In these spaces, we have the fundamental theorem of the Riemannian geometry of subspaces—the congruence theorem: *All subspaces V_n in an S_m with equal fundamental forms are congruent; that is, they may be made to coincide by a motion in S_m .* In addition, it is only in these spaces of constant curvature that one may obtain an existence theorem⁽⁴⁴⁾ for subspaces⁽⁴⁵⁾. This theorem affirms the existence of subspaces in S_m whose fundamental forms are any arbitrary preassigned differential forms. The only conditions on these forms are that the coefficients of the forms satisfy certain partial differential equations—the generalization of the Gauss-Codazzi equations.

The analogues of these two theorems in conformal differential geometry hold when the enveloping space is any conformally euclidean⁽⁴⁶⁾ space \bar{R}_m . In this chapter, we derive various minor results which are then used to prove the existence theorem and fundamental (conformal equivalence) theorem of the conformal differential geometry of subspaces.

27. **Symmetry relations.** As a result of (23.11), which is derived from the conformal Frenet equations (20.7) and (20.8), it follows that

$$(27.1) \quad *G^\alpha_{(i_w):(l_v)} = G^\alpha_{(i_w):(l_v)}, \quad w + v = 1, 2, \dots, M,$$

where $*G^\alpha_{(i_w):(l_v)}$ denotes the projection of the space vectors $G^\alpha_{(i_w):(l_v)}$ into I_{w+v} . The integrability conditions (22.1), (22.3) and (23.10) may be written as

$$(27.2) \quad G^\alpha_{:(jk)^-} = 0,$$

$$(27.3) \quad G^\alpha_{i:(jk)^-} \equiv -D^\alpha_{ijk} + \frac{1}{(n-1)} G^{(a2)} G_{i(k} G^\alpha_{j)^-(a2)} \pmod{I_{12}},$$

⁽⁴⁴⁾ For a statement and proof of various forms of this existence theorem, see [3, chapter 9], [10] and [13, §13].

⁽⁴⁵⁾ An exception to this statement occurs if $n = 1$ (curve). In this case, there is an existence theorem for a curve in any enveloping space V_m .

⁽⁴⁶⁾ Since any space which is conformal to S_m is also an \bar{R}_m , the analogy between Riemannian and conformal geometry is complete as regards the enveloping space in which one may obtain an existence theorem and an equivalence theorem.

$$(27.4) \quad G^\alpha_{(i_u):(jk)^-} \equiv -D^\alpha_{\beta jk} G^\beta_{(i_u)} \pmod{I_{12\dots u}}, \quad u = 2, 3, \dots, M - 2,$$

after account is taken of (16.9), (16.10) and (27.1). If the space vectors in (27.2), (27.3) and (27.4) are projected into I_2, I_3 and I_{u+2} respectively, it follows from (27.1) that

$$(27.5) \quad G^\alpha_{(jk)^-} = 0,$$

$$(27.6) \quad G^\alpha_{i(jk)^-} = - *D^\alpha_{ijk} + \frac{1}{(n-1)} G^{(\sigma_2)} G_{i(kG^\alpha_j)^-(\sigma_2)},$$

$$(27.7) \quad G^\alpha_{(i_u)(jk)^-} = - *D^\alpha_{\beta jk} G^\beta_{(i_u)}, \quad u = 2, 3, \dots, M - 2,$$

where $*D^\alpha_{\beta jk} G^\beta_{(i_u)}$ is the projection of $D^\alpha_{\beta jk} G^\beta_{(i_u)}$ in I_{u+2} . It follows from (27.1) and (27.5) that

$$(27.8) \quad G^\alpha_{(jk)^-(l_v)} = 0, \quad v = 0, 1, 2, \dots, M - 2.$$

This means that *the basis beins $G^\alpha_{(i_w)}$ are symmetric in the first two covariant indices i_1, i_2 .*

We now assume that V_m is a conformally euclidean space \bar{R}_m . Then $C^\alpha_{\beta\gamma\delta} \equiv 0$, so that $D^\alpha_{\beta jk} \equiv D^\alpha_{ijk} \equiv 0$. Then, from (27.1) and (27.6), we find that

$$(27.9) \quad G^\alpha_{i(jk)^-(l_v)} = \frac{1}{(n-1)} G^{(\sigma_2)} G_{i(kG^\alpha_j)^-(\sigma_2)(l_v)}, \quad v = 0, 1, 2, \dots, M - 3,$$

since $*D^\alpha_{ijk} = 0$. These equations show that, in general, the basis beins $G^\alpha_{(i_w)}$ are not symmetric in the second and third covariant indices. It is readily seen from (27.9) that *the necessary and sufficient condition that*

$$(27.10) \quad G^\alpha_{i(jk)^-(l_v)} = 0, \quad v = 0, 1, 2, \dots, M - 3,$$

is that, for the same value of v ,

$$(27.11) \quad G^{(\sigma_2)} G^\alpha_{i(\sigma_2)(l_v)} = 0.$$

Since $*D^\alpha_{\beta jk} = 0$, (27.7) shows that

$$(27.12) \quad G^\alpha_{(i_u)(jk)^-} = 0, \quad u = 2, 3, \dots, M - 2,$$

that is, $G^\alpha_{(i_u)jk}$ is symmetric in the indices j, k . In what follows, we prove that

$$(27.13) \quad G^\alpha_{(i_w)} \text{ is symmetric in the last } (w-2) \text{ indices } i_3, i_4, \dots, i_w, \\ w = 4, 5, \dots, M.$$

The proof depends upon mathematical induction. We suppose that $G^\alpha_{(i_v)}$ is symmetric in the last $v-2$ covariant indices, where v is some fixed integer between 4 and $M-1$ inclusive. According to (27.12), this is true if $v=4$. We now establish that $G^\alpha_{(i_{v+1})}$ must be symmetric in the last $(v-1)$ indices. From (27.1), it follows that

$$(27.14) \quad *G^\alpha_{(i_{v-1})j:k} = G^\alpha_{(i_{v-1})jk}.$$

In accordance with the hypothesis of the induction, $G^\alpha_{(i_{v-1})j}$ is symmetric in the indices $i_3, i_4, \dots, i_{v-1}, j$. Hence, from (27.14), this symmetry property is also enjoyed by the tensor $G^\alpha_{(i_{v-1})jk}$. But it has been shown that $G^\alpha_{(i_{v-1})jk}$ is symmetric in the indices j, k . Therefore $G^\alpha_{(i_{v-1})jk}$ is symmetric in the last $(v-1)$ indices or, using another notation, $G^\alpha_{(i_{v+1})}$ is symmetric in the indices i_3, i_4, \dots, i_{v+1} . This completes the proof of the symmetry property stated in (27.13).

Incidentally, the above argument also shows that if $G^\alpha_{(i_v)}$ is symmetric in the indices i_2, i_3 this is also true for the basis bein $G^\alpha_{(i_{v+1})}$. If account is taken of (27.1), (27.8) and (27.13), it follows from this statement that *if $G^\alpha_{(i_v)}$ ($v > 2$) is symmetric in the indices i_2, i_3 , then the basis beins*

$$G^\alpha_{(i_v)}, G^\alpha_{(i_{v+1})}, G^\alpha_{(i_{v+2})}, \dots, G^\alpha_{(i_M)}$$

enjoy symmetry in all their covariant indices and are symmetric covariant tensors. This occurs if and only if $G^{i_2 i_3} G^\alpha_{(i_v)} = 0$. In this case, according to (27.11),

$$(27.15) \quad G^{i_a i_b} G^\alpha_{(i_u)} = 0, \quad u \geq v,$$

where a, b are any integers between 1 and u .

This is similar to the equations

$$(27.16) \quad G^{i_1 i_2} G^\alpha_{(i_w)} = 0, \quad w = 2, 3, \dots, M,$$

which follow from (7.11) [equivalent to (21.5)] and (27.1) and hold for all basis beins $G^\alpha_{(i_w)}$ regardless of whether the $G^\alpha_{(i_w)}$ are symmetric in i_2, i_3 and in any enveloping space V_m , not necessarily an \bar{R}_m .

The symmetry properties of the basis beins $G^\alpha_{(i_w)}$ induce similar properties in the conformal measure tensors $B_{(i_w)|(h_w)}$. It follows directly from (21.2), (27.8), (27.9) and (27.13) that

$$(27.17) \quad B_{(jk)^-(l_v)|(h_{v+2})} = 0, \quad v = 0, 1, 2, \dots, M - 2,$$

$$(27.18) \quad B_{i(jk)^-(l_v)|(h_{v+3})} = \frac{1}{(n-1)} G^{(g_2)} G_{i(kB_j)^-(g_2)(l_v)|(h_{v+3})}, \quad v = 0, 1, 2, \dots, M - 3,$$

$$(27.19) \quad B_{(i_w)|(h_w)} \text{ is symmetric in the last } (w-2) \text{ indices of } (i_w): i_3, i_4, \dots, i_w, \quad w = 4, 5, \dots, M.$$

In addition, as stated in (21.6),

$$B_{(i_w)|(h_w)} = B_{(h_w)|(i_w)}, \quad w = 1, 2, \dots, M.$$

Furthermore, as in equations (27.10) and (27.11) of the discussion for the basis beins, *the necessary and sufficient condition that*

$$(27.20) \quad B_{i(jk)^-(l_v)|(h_{v+2})} = 0, \quad v = 0, 1, 2, \dots, M - 3,$$

is that, for the same value of v ,

$$(27.21) \quad G^{(\sigma^2)} B_{i(\sigma^2)(l_v)|(h_{v+2})} = 0.$$

If $B_{(i_v)|(h_v)}$ ($v > 2$) is symmetric in the indices i_2, i_3 then the normal measure tensors $B_{(i_v)|(h_v)}, B_{(i_{v+1})|(h_{v+1})}, \dots, B_{(i_M)|(h_M)}$ enjoy symmetry in all the i -indices and in all the h -indices; that is, these measure tensors are unaltered by any interchange among the i -indices or any interchange among the h -indices. This occurs if and only if $G^{i_2 i_3} B_{(i_v)|(h_v)} = 0$. In this case, as in (27.15),

$$(27.22) \quad G^a i_b B_{(i_u)|(h_u)} = 0, \quad u \geq v,$$

where a, b are any integers between 1 and u . Even if $B_{(i_w)|(h_w)}$ is not symmetric in the indices $i_2, i_3, G^{i_1 i_2} B_{(i_w)|(h_w)} = 0, w = 2, 3, \dots, M$, is true as is stated in (21.11). This is a special case of (27.22) and is true in any enveloping space V_m .

Finally we note that the symmetry properties of the $G^\alpha_{(i_w)}$ also induce similar relations upon the covariant indices of the tensors $U^{(h_w)}_{(i_{w+1})}, U^{(h_{w-1})}_{(i_{w+1})}$ which occur in the conformal Frenet equations. We state these relations in terms of the tensors $U_{(i_{w+1})|(l_w)}$ and $U_{(i_{w+1})|(l_{w-1})}$ defined by means of the equations

$$(27.23) \quad \begin{aligned} U_{(i_{w+1})|(l_w)} &= U^{(h_w)}_{(i_{w+1})} B_{(h_w)|(l_w)}, \\ U_{(i_{w+1})|(l_{w-1})} &= U^{(h_{w-1})}_{(i_{w+1})} B_{(h_{w-1})|(l_{w-1})}. \end{aligned}$$

It follows readily from (20.7), (21.2) and the symmetry relations for the $G^\alpha_{(i_w)}$ that $U_{(i_{w+1})|(l_w)}$ and $U_{(i_{w+1})|(l_{w-1})}$ are symmetric in the groups of indices $i_1, i_2, i_3, i_4, \dots, i_w; l_1, l_2$; and either l_3, l_4, \dots, l_w or l_3, l_4, \dots, l_{w-1} .

Also, according to (20.7),

$$G^\alpha_{i_{jk}(l_{v-1}): l_v} = G^\alpha_{i_{jk}(l_v)} + U^{(h_{v+2})}_{i_{jk}(l_v)} G^\alpha_{(h_{v+2})} + U^{(h_{v+1})}_{i_{jk}(l_v)} G^\alpha_{(h_{v+1})}$$

and

$$\begin{aligned} &\left[\frac{1}{(n-1)} G^{(\sigma^2)} G_{ik} G^\alpha_{j(\sigma^2)(l_{v-1})} \right] : l_v \\ &= \frac{1}{(n-1)} G^{(\sigma^2)} G_{ik} \left[G^\alpha_{j(\sigma^2)(l_v)} + U^{(h_{v+2})}_{j(\sigma^2)(l_v)} G^\alpha_{(h_{v+2})} + U^{(h_{v+1})}_{j(\sigma^2)(l_v)} G^\alpha_{(h_{v+1})} \right]. \end{aligned}$$

Therefore we find from (21.1), (21.2), (27.9), (27.23) and the above equations that

$$(27.24) \quad U_{i(jk)^-(l_v)|(h_{v+2})} = \frac{1}{(n-1)} G^{(\sigma^2)} G_{i(kU_j)^-(\sigma^2)(l_v)|(h_{v+2})}, \quad v = 0, 1, 2, \dots, M-2,$$

$$(27.25) \quad U_{i(jk)^-(l_v)|(h_{v+1})} = \frac{1}{(n-1)} G^{(\sigma^2)} G_{i(kU_j)^-(\sigma^2)(l_v)|(h_{v+1})}, \quad v = 0, 1, 2, \dots, M-2.$$

We note that if $U_{(i_w+1)|(l_w)}$ and $B_{(h_w)|(l_w)}$ are known then $U^{(h_w)}_{(i_w+1)}$ is determined except for an additive tensor $\theta^{(h_w)}_{(i_w+1)}$ which obeys

$$B_{(h_w)|(l_w)}\theta^{(h_w)}_{(i_w+1)} = 0.$$

Hence, for any fixed values of i_1, i_2, \dots, i_{w+1} , $\theta^{(h_w)}_{(i_w+1)}$ is a null solution and, according to §19, also obeys the equations

$$G^\alpha_{(h_w)}\theta^{(h_w)}_{(i_w+1)} = 0.$$

This means that while the $U^{(h_w)}_{(i_w+1)}$ are only fixed up to an additive null solution by the $U_{(i_w+1)|(l_w)}$ and $B_{(h_w)|(l_w)}$ the tensor $U^{(h_w)}_{(i_w+1)}G^\alpha_{(h_w)}$ which occurs in the conformal Frenet equations is uniquely determined by the $U_{(i_w+1)|(l_w)}$ and $G^\alpha_{(h_w)}$. In a similar way, the $U_{(i_w+1)|(l_w-1)}$ and $B_{(h_w-1)|(l_w-1)}$ determine the $U^{(h_w-1)}_{(i_w+1)}$ except for additive null solutions with respect to $B_{(h_w-1)|(l_w-1)}$ or $G^\alpha_{(h_w-1)}$.

All of the symmetry properties obtained in this section are derived from the conformal Frenet equations, B -conditions and fundamental equations. Consequently the symmetry relations for $B_{(i_w)|(h_w)}$, $U_{(i_w)|(l_w-1)}$ and $U_{(i_w)|(l_w-2)}$ do not represent any new conditions. They may be derived directly from the fundamental equations.

28. Determination of $U^{(h_w-1)}_{(i_w+1)}$, $U^{(h_w)}_{(i_w+1)}$, $B_{(i_w)|(l_w)}$. In previous sections, it was shown that every subspace V_n in V_m which satisfies certain general conditions determines a set of conformal tensors. The tensors include the conformal measure tensors (19.8) and the deviation tensor E_{ij} and are unchanged by conformal transformations of V_m . The components of these tensors satisfy the various algebraic and integrability conditions which were derived in chapter V.

We are now in a position to begin the proof of a converse theorem which is true if the enveloping space V_m is a conformally euclidean space \bar{R}_m . Briefly, this theorem states that *subspaces V_n exist in \bar{R}_m whose conformal measure tensors and deviation tensor are any arbitrary tensors whose components satisfy the fundamental equations and that any such subspace is uniquely determined by a number of initial conditions.* Indeed, we prove an even stronger theorem which may be stated loosely⁽⁴⁷⁾ as follows: *A V_n exists in \bar{R}_m with preassigned conformal fundamental forms (19.11) whose coefficients satisfy certain algebraic and differential equations and this V_n is uniquely determined by a number of initial conditions.*

In its general outline, the derivation of these results is somewhat similar to that used to prove the corresponding existence theorem of Riemannian geometry⁽⁴⁸⁾. However, the details of the present proof involve enormously greater algebraic difficulties. As a result, there is only a very weak analogy between the details of the proofs of the preliminary theorems which lead up

⁽⁴⁷⁾ A precise statement of these theorems appears in Theorem 29.1 and Theorem 29.3.

⁽⁴⁸⁾ For example, compare the work of §§28, 29 of this paper with [10, §4].

to the existence theorems of conformal geometry and the corresponding theorems of Riemannian geometry. Since the enveloping V_m is a conformally euclidean space, it is assumed that $C_{\alpha\beta\gamma\delta} = D_{\alpha\beta jk} = D_{\alpha ijk} = 0$ in all the work of this section.

In this section, we develop a number of results of secondary interest which lead to a proof of the existence theorem. These results show that the tensors $U^{(hw)}_{(i_w+1)}$, $U^{(hw-1)}_{(i_w+1)}$ may be expressed in terms of the conformal measure tensors $B_{(i_w)|(l_w)}$ and of the deviation tensor⁽⁴⁹⁾ E_{ij} by means of the various equations derived in chapter V and finally that the $B_{(i_w)|(l_w)}$ in turn are uniquely determined by the symmetric conformal fundamental tensors $G_{(i_w)(l_w)}$. These results, which constitute the aim of the lengthy calculations of the present section, are stated in Theorem 28.1 and Theorem 28.2.

(1) *Determination of the $U^{(hw-1)}_{(i_w+1)}$.* According to (21.9) and the definition given by (27.23),

$$U_{(i_w+1)|(l_w-1)} = - B_{(l_w-1)i_w+1|(i_w)}, \quad w = 2, 3, \dots, M.$$

[If $w=1$, $U_{(i_2)|(l_1)}=0$ by the convention of (20.8).] From the discussion at the end of §27, this means that $B_{(l_w)|(i_w)}$ and $B_{(l_w-1)|(i_w-1)}$ fix the value of $U^{(hw-1)}_{(i_w+1)}$ except for the necessarily indeterminate additive null solution.

(2) *Determination of the $U^{(hw)}_{(i_w+1)}$.* In the calculations that follow, the following notation is very useful. If a tensor expression T is equal to a single-valued⁽⁵⁰⁾ tensor function of

$$(28.1) \quad \begin{aligned} & B_{i_1|l_1}, \quad \text{if } w = 1, \\ & E_{il}, B_{i_1|l_1}, B_{(i_2)|(l_2)}, \dots, B_{(i_w)|(l_w)}, \quad \text{if } w \geq 2, \end{aligned}$$

we write

$$(28.2) \quad T \overset{w}{\sim} 0$$

to denote this fact. Similarly, if T_1 and T_2 are two tensor expressions and if T_1 differs from T_2 by a combination of the tensors (28.1), we write

$$(28.3) \quad T_1 \overset{w}{\sim} T_2.$$

Hence both (28.2) and (28.3) are equivalent to equations. We call each of them a \sim^w equation.

It is clear that (28.3) is equivalent to $T_1 - T_2 \sim^w 0$. Furthermore $T \sim^{w+1} 0$ and $T_{;i} \sim^w 0$ are both consequences of (28.2). Also, if

$$T_1 \overset{w}{\sim} 0, \quad T_2 \overset{w}{\sim} 0$$

⁽⁴⁹⁾ If $n > 2$, the tensor E_{ij} may be expressed in terms of $B_{i|l}$ and its derivatives and $B_{(i_2)|(l_2)}$ by means of (24.15). Hence, in this case, the U 's may be written as functions of the conformal measure tensors alone.

⁽⁵⁰⁾ If T is equal to $U^{(hw-1)}_{(i_w+1)}$ or $U^{(hw)}_{(i_w+1)}$ and is determined except for an additive null tensor, we also write (28.2). A similar remark applies to (28.35).

then

$$T_1 \pm T_2 \overset{w}{\sim} 0, \quad T_1 T_2 \overset{w}{\sim} 0$$

so that, in some respects, (28.2) and (28.3) behave as though they were the equations $T=0$ and $T_1=T_2$ respectively. We also consider a generalization of the notion of symmetry for a tensor T . Let i, j be two covariant (or contravariant) indices of T and suppose that

$$(28.4) \quad T_{ij} - T_{ji} \overset{w}{\sim} 0.$$

We call the kind of "symmetry" defined by (28.4) by the name \sim^w symmetry and say that T is a \sim^w symmetric tensor in the indices i, j . Of course, ordinary symmetry implies \sim^w symmetry.

The first case in the determination of the $U^{(hw)}_{(i_{w+1})}$ to be considered is $w=2$ since $U^{h_1}_{(i_2)}=0$ by the convention stated in (20.8). We now find $U_{(i_3)|(l_2)}$. If $m=3$, this problem is solved by (20.18). We therefore assume that m exceeds 3.

We introduce an abbreviated notation by means of the equations

$$(28.5) \quad \begin{aligned} \{(i_w) | (l_w) | j\} &= U_{(i_w)j|(l_w)}, & w > 1, \\ \{i_1 | (l_2)\} &= G^{h_1} \{i_1 h_1 | (l_2) | j\}, \\ \{(i_{w-1}) | (l_w)\} &= G^{h_j} \{i_1 h_j i_2 i_3 \cdots i_{w-2} | (l_w) | i_{w-1}\}, & w > 2, \\ [l] &= G^{h_j} \{h | l_j\}, \\ [(i_{w-1})(l_{w-2})] &= G^{h_j} \{(i_{w-1}) | l_1 h_j l_2 l_3 \cdots l_{w-2}\}, & w > 2. \end{aligned}$$

From the symmetry properties of $\{(i_2) | (l_2) | j\}$ stated in §27, it follows that

$$(28.6) \quad \{i | (jk)^-\} = 0.$$

Also, from equations (24.7),

$$(28.7) \quad \{(i | j)^- k\} \overset{2}{\sim} 0.$$

As a consequence of (28.6) and (28.7), it follows that $\{i | jk\}$ is a \sim^2 symmetric tensor in all its indices. We multiply (28.7) by G^{ik} and sum on the repeated indices. Since

$$G^{ik} \{j | ik\} = 0,$$

in accordance with (21.12), the resulting equations may be written as

$$(28.8) \quad [j] \overset{2}{\sim} 0.$$

Now it follows from (21.10) with $w=2$ and (27.23) and (28.5) that

$$(28.9) \quad \{(i_2) | (l_2) | j\} + \{(l_2) | (i_2) | j\} = B_{(i_2)|(l_2):j}.$$

From (28.9), we obtain

$$(28.10) \quad \begin{aligned} & \{i_1 i_2 | l_1 l_2 | j\} + \{l_1 l_2 | i_1 i_2 | j\} - \{l_2 j | i_1 i_2 | l_1\} \\ & - \{i_1 i_2 | l_2 j | l_1\} + \{i_2 l_1 | l_2 j | i_1\} + \{l_2 j | i_2 l_1 | i_1\} \\ & - \{j i_1 | i_2 l_1 | l_2\} - \{i_2 l_1 | j i_1 | l_2\} + \{l_1 l_2 | j i_1 | i_2\} \\ & + \{j i_1 | l_1 l_2 | i_2\} \stackrel{2}{\sim} 0. \end{aligned}$$

Also, from the conformal Codazzi equations (22.20),

$$(28.11) \quad \{j^- | l_1 l_2 | k^-\} = \frac{1}{(n-1)} G_{ik^-} \{j^- | l_1 l_2\}.$$

If (28.11) is substituted in (28.10), we obtain

$$\begin{aligned} & 2\{i_1 i_2 | l_1 l_2 | j\} + \frac{1}{(n-1)} [G_{l_2 j^-} \{l_1^- | i_1 i_2\} + G_{i_2 i_1^-} \{l_1^- | l_2 j\} + G_{j i_1^-} \{l_2^- | i_2 l_1\} \\ & + G_{l_1 i_2^-} \{l_2^- | j i_1\} + G_{i_1 i_2^-} \{j^- | l_1 l_2\}] \stackrel{2}{\sim} 0. \end{aligned}$$

When we make use of the \sim^2 symmetry of $\{j | l_1 l_2\}$ these last equations become

$$(28.12) \quad 2\{i_1 i_2 | l_1 l_2 | j\} + \frac{2}{(n-1)} [G_{i_1 i_2} \{l_1 | l_2 j\} - G_{l_1 l_2} \{i_1 | i_2 j\}] \stackrel{2}{\sim} 0.$$

We multiply (28.12) by $G^{i_1 i_2}$ and sum for i_1, i_2 . If we make use of (21.11) and (28.5), we obtain

$$n \cdot \{l_1 | l_2 j\} - G_{l_1 l_2} [j] \stackrel{2}{\sim} 0.$$

In virtue of (28.8), these equations become $\{l_1 | l_2 j\} \sim^2 0$. If these last results are substituted in (28.12), we find that

$$(28.13) \quad \{i_1 i_2 | l_1 l_2 | j\} \stackrel{2}{\sim} 0.$$

This means that $\{i_1 i_2 | l_1 l_2 | j\}$ or $U_{(i_2)j | (l_2)}$ may be expressed in terms of the tensors E_{il}, G_{il} and $B_{(i_2) | (l_2)}$. Hence $U^{(h_2)}_{(i_2)}$ is determined by these tensors up to an additive null solution.

We now proceed to a consideration of the general case $w > 2$ which we establish by mathematical induction. For the hypothesis of the induction, we assume⁽⁶¹⁾ that the tensors

$$(28.14) \quad U^{h_1}_{(i_3)}, U^{(h_2)}_{(i_4)}, \dots, U^{(h_{w-2})}_{(i_w)}; U^{(h_2)}_{(i_3)}, U^{(h_3)}_{(i_4)}, \dots, U^{(h_{w-1})}_{(i_w)}$$

may be expressed uniquely (except for additive null tensors) in terms of the tensors

$$(28.15) \quad E_{i_l}, G_{i_l}, B_{(i_2) | (l_2)}, \dots, B_{(i_{w-1}) | (l_{w-1})}.$$

⁽⁶¹⁾ This has already been shown for all the tensors of the first set in (28.14) as well as the first tensor $U^{(h_2)}_{(i_3)}$ of the second set.

In the sequel, we shall show that $U^{(h_w)}_{(i_w+1)}$ is determined (except for an additive null solution) by the tensors (28.15) and $B_{(i_w)|(l_w)}$. This is equivalent to proving that

$$(28.16) \quad U_{(i_w+1)|(l_w)} \overset{w}{\sim} 0$$

which is the form in which our result is established. The proof follows.

For the present, we assume that the tensors (28.14) are determined uniquely by the tensors (28.15). Later we consider the effect of changing any tensor of (28.14) by an additive null solution. According to the results of §27, $\{(i_w)|(l_w)|j\}$ is symmetric in the groups of indices $i_1, i_2, i_3, i_4, \dots, i_w$; l_1, l_2 and l_3, l_4, \dots, l_w . It also follows from (23.7), (23.17) and the hypothesis of the induction that

$$(28.17) \quad \{(i_w)|(l_w)|j\} - \{(i_{w-1})j|(l_w)|i_w\} \overset{w}{\sim} 0.$$

Also, from (21.10),

$$(28.18) \quad \{(i_w)|(l_w)|j\} + \{(l_w)|(i_w)|j\} \overset{w}{\sim} 0.$$

It follows from (28.17) and (28.18) that

$$(28.19) \quad \begin{aligned} & \{(i_w)|(l_w)|j\} \overset{w}{\sim} - \{(l_w)|(i_w)|j\} \overset{w}{\sim} - \{(l_{w-1})j|(i_w)|l_w\} \\ & \overset{w}{\sim} \{(i_w)|(l_{w-1})j|l_w\}. \end{aligned}$$

As a consequence of (28.17) and (28.19) and the symmetry properties, $\{(i_w)|(l_w)|j\}$ is $\overset{w}{\sim}$ symmetric in the indices $i_3, i_4, \dots, i_w, l_3, l_4, \dots, l_w, j$.

Now the integrability conditions (26.3) lead to the equations

$$G^{i_2 i_3} G^{\alpha_{i_1 - i_2; i_3 i_4 -}} \equiv 0 \pmod{I_{12}}$$

when V_m is an \bar{R}_m . Conformal differentiation of these equations and simplification by means of the conformal Frenet equations (20.7) yield the equations

$$(28.20) \quad G^{i_1 i_2} G^{\alpha_{i_1 - i_2; i_3 i_4 - \dots i_w j}} \equiv 0 \pmod{I_{12 \dots (w-1)}}.$$

Now according to (20.7) and easy mathematical induction,

$$(28.21) \quad \begin{aligned} G^{\alpha_{i_1 i_2; i_3 \dots i_w j}} & \equiv G^{\alpha_{i_1 \dots i_w j}} \\ & + G^{\alpha_{(h_w)}} [U^{(h_w)}_{i_1 \dots i_w j} + \text{combination of the tensors (28.14)}] \\ & \pmod{I_{12 \dots (w-1)}}. \end{aligned}$$

We substitute (28.21) in (28.20) and multiply by $A_{\alpha\beta} G^\beta_{(l_w)}$ and sum for α, β . If use is made of (21.1), (21.2) as well as the definitions (27.23) and (28.5), we obtain

$$(28.22) \quad G^{i_1 i_2} \{i_1^- i_2 i_3 i_4^- \dots i_w | (l_w) | j\} \overset{w}{\sim} 0.$$

This result can be derived from the fundamental equations alone without using any equations involving space indices. Of course, (28.22) is equivalent to

$$(28.23) \quad \{i_1^- i_4^- \cdots i_w j | l_w\} \overset{w}{\sim} 0$$

where $\{i_1 i_4 \cdots i_w j | l_w\}$ or, in other notation, $\{(i_{w-1}) | l_w\}$ is defined by (28.5). It follows from (28.23) and the $\overset{w}{\sim}$ symmetry properties of $\{(i_w) | l_w | j\}$ stated in the preceding paragraph that $\{(i_{w-1}) | l_w\}$ is $\overset{w}{\sim}$ symmetric in the indices $i_1, i_2, i_3, \dots, i_w, l_3, l_4, \dots, l_w$.

From (28.18), we obtain

$$(28.24) \quad G^{i_2 i_3} \{(i_w) | l_w | j\} + G^{i_2 i_3} \{l_w | (i_w) | j\} \overset{w}{\sim} 0.$$

According to the conclusion of the preceding paragraph, the first tensor in (28.24) is $\overset{w}{\sim}$ symmetric in all indices except l_1, l_2 . Consequently the second tensor $G^{i_2 i_3} \{l_w | (i_w) | j\}$ is also $\overset{w}{\sim}$ symmetric in these indices. Also $G^{l_2 l_3} \{l_w | (i_w) | j\}$ is $\overset{w}{\sim}$ symmetric in all indices except i_1, i_2 . It follows from these remarks that $G^{l_2 l_3} G^{i_2 i_3} \{l_w | (i_w) | j\}$ is $\overset{w}{\sim}$ symmetric in all the remaining indices. In the notation of (28.5), this means that $[(i_{w-1})(l_{w-2})]$ is a $\overset{w}{\sim}$ symmetric tensor. If we multiply (28.24) by $G^{l_2 l_3}$ and sum on the repeated indices and use the fact that $[(i_{w-1})(l_{w-2})]$ is $\overset{w}{\sim}$ symmetric, we obtain

$$(28.25) \quad [(i_{w-1})(l_{w-2})] \overset{w}{\sim} 0$$

after replacing the indices $i_1, i_4, i_5, \dots, i_w, j, l_1, l_4, l_5, \dots, l_w$ by $i_1, i_2, i_3, \dots, i_{w-1}, l_1, l_2, l_3, \dots, l_{w-2}$.

Now (27.24) may be written as

$$(28.26) \quad \{l_1 l_2 l_3^- \cdots l_w | (i_w) | j\} = \frac{1}{(n-1)} G_{l_1 l_3^-} \{l_2^- l_4 \cdots l_w j | (i_w)\}.$$

From (28.18) and (28.26),

$$(28.27) \quad \{(i_w) | l_1 l_2 l_3^- \cdots l_w | j\} \overset{w}{\sim} \frac{1}{(n-1)} G_{l_1 l_3^-} \{l_2^- l_4 \cdots l_w j | (i_w)\}.$$

We multiply (28.27) by $G^{i_2 i_3}$ and sum on repeated indices. This gives

$$\{i_1 i_4 \cdots i_w j | l_1 l_2 l_3^- \cdots l_w\} \overset{w}{\sim} \frac{1}{(n-1)} G_{l_1 l_3^-} [l_2^- l_4 \cdots l_w j i_1 i_4 \cdots i_w]$$

after using the definitions (28.5). According to (28.25) and a change of indices, these last equations become

$$\{(i_{w-1}) | l_1 l_2 l_3^- \cdots l_w\} \overset{w}{\sim} 0$$

so that $\{(i_{w-1}) | l_w\}$ is $\overset{w}{\sim}$ symmetric in the indices l_2, l_3 . Since it has already been shown that $\{(i_{w-1}) | l_w\}$ is $\overset{w}{\sim}$ symmetric in all the indices except l_1, l_2 and is also symmetric in l_1, l_2 , the above remark shows that $\{(i_{w-1}) | l_w\}$ is $\overset{w}{\sim}$ symmetric in all its indices.

We now consider a tensor expression suggested by (28.18). As a result of (28.18),

is a rational function of the tensors (28.1) and their first conformal derivatives.

The above work disregarded the possible effect of changing any of the tensors (28.14) by additive null tensors⁽⁵²⁾. Now as noted in the summary at the conclusion of chapter V, any change of this kind has no effect on any of the equations used in our proof. This means that the value obtained for $U_{(i_w+1)|(l_w)}$ is not dependent upon the particular choice that we make for each U in (28.14).

Consequently the $U^{(h_w)}_{(i_w+1)}$ are uniquely determined by the tensors (28.1) except for necessarily indeterminate additive null solutions. This completes the proof by mathematical induction. The results of this section up to the present point may be summarized by the theorem:

THEOREM 28.1. *The \sim^w equations*

$$(28.33) \quad \begin{aligned} U^{(h_{w-1})}_{(i_w+1)} &\sim^w 0, & w = 1, 2, \dots, M, \\ U^{(h_w)}_{(i_w+1)} &\sim^w 0 \end{aligned}$$

are consequences of the fundamental equations of V_n . The U 's are uniquely determined by these \sim^w equations except for additive null tensors.

(3) *Determination of the $B_{(i_w)|(l_w)}$.* The following conventions regarding notation are very useful for the calculations which appear in the remainder of this section. If a tensor expression T is equal to a single-valued tensor function of

$$(28.34) \quad \begin{aligned} &G_{i_1 l_1} && \text{if } w = 1, \\ E_{i_1}, G_{i_1 l_1}, G_{(i_2)(l_2)}, \dots, G_{(i_w)(l_w)} && \text{if } w \geq 2, \end{aligned}$$

we write

$$(28.35) \quad T \simeq^w 0$$

to denote this fact. Similarly, if T_1 and T_2 are two tensor expressions and if T_1 differs from T_2 by a combination of the tensors (28.34), we write

$$(28.36) \quad T_1 \simeq^w T_2.$$

According to these definitions, both (28.35) and (28.36) are equivalent to equations. We call each of them a \simeq^w equation. The various remarks which appeared earlier in connection with the definitions of \sim equations are also valid here in analogous form. In particular, if i, j are two covariant (or contravariant) indices of T and if $T_{ij} - T_{ji} \simeq^w 0$ we say that T is a \simeq^w symmetric tensor in the indices i, j .

We begin by observing that $B_{i_1|l_1} (=G_{i_1 l_1})$ and E_{i_1} are themselves funda-

⁽⁵²⁾ The corresponding proof in the metric theory [10, §4] should be amended to include remarks analogous to those made here.

mental tensors. We now consider the problem of expressing $B_{(i_2)|(l_2)}$ in terms of the fundamental tensors. As a consequence of (19.12) and the symmetry properties of $B_{(i_2)|(l_2)}$, it follows that

$$(28.37) \quad \begin{aligned} 3G_{(i_2)(l_2)} &= B_{i_1 i_2 | l_1 l_2} + B_{i_1 l_1 | i_2 l_2} + B_{i_1 l_2 | i_2 l_1} \\ &= 3B_{(i_2)|(l_2)} + B_{i_1(l_1|i_2)^{-}l_2} + B_{i_1(l_2|i_2)^{-}l_1}. \end{aligned}$$

According to the conformal Gauss equations (22.13), $B_{i(k|j)^{-}h}$ is a tensor function of G_{ij} and E_{ij} . Hence, using the notation previously introduced,

$$B_{i_1(l_1|i_2)^{-}l_2} \stackrel{2}{\simeq} 0, \quad B_{i_1(l_2|i_2)^{-}l_1} \stackrel{2}{\simeq} 0.$$

It follows from these equations and (28.37) that

$$B_{(i_2)|(l_2)} \stackrel{2}{\simeq} 0.$$

We now proceed to a consideration of the general case $w > 2$ which we establish by mathematical induction. For the hypothesis of the induction, we assume that the tensors

$$E_{il}, B_{i_1|l_1}, B_{(i_2)|(l_2)}, \dots, B_{(i_{w-1})|(l_{w-1})}$$

may be expressed uniquely in terms of the fundamental tensors

$$(28.38) \quad E_{il}, G_{i_1 l_1}, G_{(i_2)(l_2)}, \dots, G_{(i_{w-1})(l_{w-1})}.$$

In the work that follows, we prove that $B_{(i_w)|(l_w)}$ is determined by the tensors (28.38) and $G_{(i_w)|(l_w)}$; that is,

$$(28.39) \quad B_{(i_w)|(l_w)} \stackrel{w}{\simeq} 0.$$

We note that the hypothesis of the induction has been proved to be true if $w = 1$ or $w = 2$. From the hypothesis and Theorem 28.1, it follows that the tensors (28.14) are also determined (except for null solutions⁽⁶⁸⁾) by the fundamental tensors (28.38). Now, as a result of this remark, the hypothesis of the induction and equations (23.6) and (23.16), we find that

$$U^{(h_{w-1})}{}_{(i_{w-1})(j_k)^{-}B_{(h_{w-1})|(l_{w-1})} \stackrel{w}{\simeq} 0.$$

It follows from (21.9) that these equations are equivalent to

$$(28.40) \quad B_{(i_{w-1})k^-(l_{w-1})i^-} \stackrel{w}{\simeq} 0.$$

Now, according to the results of §27, $B_{(i_w)|(l_w)}$ is symmetric in the groups of indices $i_1, i_2; l_1, l_2; i_3, i_4, \dots, i_w$ and l_3, l_4, \dots, l_w . It follows from (28.40) that $B_{(i_w)|(l_w)}$ is \simeq^w symmetric in the indices $i_3, i_4, \dots, i_w, l_3, l_4, \dots, l_w$.

Equations (28.20) and (28.21) may be written in the form

⁽⁶⁸⁾ This lack of a unique determination for the tensors (28.14) may be disregarded in the present work for reasons which are stated in connection with the proof of Theorem 28.1.

$$(28.41) \quad G^{i_2 i_3} G^{\alpha}_{i_1 i_2, i_3 i_4 \dots i_w} \equiv 0 \pmod{I_{12 \dots (w-2)}},$$

$$(28.42) \quad G^{\alpha}_{i_1 i_2, i_3 \dots i_w} \equiv G^{\alpha}_{(i_w)} \pmod{I_{12 \dots (w-1)}}.$$

We substitute (28.42) in (28.41) and multiply the result by $A_{\alpha\beta} G^{\beta}_{(l_w)}$ and sum for α, β . If use is made of (21.1) and (21.2), we obtain

$$(28.43) \quad G^{(g_2)} B_{i_1 i_2 \dots i_{w-2} | (l_w)} = 0$$

after a change of indices. This result may be proved by means of the fundamental equations alone without using any equations involving space indices. It follows from (28.43) and the \simeq^w symmetry properties of $B_{(i_w) | (l_w)}$ stated in the preceding paragraph that $G^{(g_2)} B_{i_1 (g_2) i_2 \dots i_{w-2} | (l_w)}$ is \simeq^w symmetric in the indices $i_1, i_2, \dots, i_{w-2}, l_3, l_4, \dots, l_w$. From (21.6), we obtain

$$G^{(g_2)} B_{i_1 (g_2) i_2 \dots i_{w-2} | (l_w)} = G^{(g_2)} B_{(l_w) | i_1 (g_2) i_2 \dots i_{w-2}}.$$

Hence $G^{(g_2)} B_{(l_w) | i_1 (g_2) i_2 \dots i_{w-2}}$ is \simeq^w symmetric in the indices $i_1, i_2, \dots, i_{w-2}, l_3, l_4, \dots, l_w$. It follows from these remarks that $G^{(g_2)} G^{(h_2)} B_{i_1 (g_2) i_2 \dots i_{w-2} | l_1 (h_2) l_2 \dots l_{w-2}}$ is \simeq^w symmetric in all its indices except l_1 and in all its indices except i_1 and hence is \simeq^w symmetric in all its indices.

We shall use the following notation which is suggested by the \simeq^w symmetry properties derived above:

$$(28.44) \quad \begin{aligned} \{(i_2) | (l_2) | (h_{2w-4})\} &= B_{i_1 i_2 h_1 \dots h_{w-2} | l_1 l_2 h_{w-1} \dots h_{2w-4}}, \\ \{(l_2) | (i_{2w-4})\} &= G^{(g_2)} B_{i_1 (g_2) i_2 \dots i_{w-2} | l_1 l_2 i_{w-1} \dots i_{2w-4}}, \\ [(i_{2w-4})] &= G^{(g_2)} G^{(h_2)} B_{i_1 (g_2) i_2 \dots i_{w-2} | i_{w-1} (h_2) i_w \dots i_{2w-4}}. \end{aligned}$$

It follows that $\{(i_2) | (l_2) | (h_{2w-4})\}$ is \simeq^w symmetric in the groups of indices $i_1, i_2; l_1, l_2; h_1, h_2, \dots, h_{2w-4}$ and that

$$(28.45) \quad \{(i_2) | (l_2) | (h_{2w-4})\} \simeq^w \{(l_2) | (i_2) | (h_{2w-4})\}.$$

Also, $\{(l_2) | (i_{2w-4})\}$ is \simeq^w symmetric in l_1, l_2 and in $i_1, i_2, \dots, i_{2w-4}$ and $[(i_{2w-4})]$ is a \simeq^w symmetric tensor. We shall also write

$$(28.46) \quad \begin{aligned} [(i_{2w-6})] &= G^{(g_2)} [g_1 g_2 (i_{2w-6})], \\ [(i_{2w-8})] &= G^{(g_2)} [g_1 g_2 (i_{2w-8})], \\ &\dots \dots \dots \\ [(i_2)] &= G^{(g_2)} [g_1 g_2 (i_2)]. \end{aligned}$$

It is clear that all the above tensors are \simeq^w symmetric tensors.

We now derive several relationships which are used in the sequel to prove (28.39). According to (27.18) and (28.44),

$$(28.47) \quad \begin{aligned} \{(i_2) | (l_2) | (j_{2w-4})\} &= \{i_1 j_1 | (l_2) | i_2 j_2 \dots j_{2w-4}\} \\ &+ (1/(n-1)) G_{i_1 j_1} \{(l_2) | i_2 j_2 \dots j_{2w-4}\}. \end{aligned}$$

If we multiply (28.47) by $G^{(i_2)}$ and sum on the repeated indices, we obtain

$$(28.48) \quad G^{j_1 i_2} \{ (i_2) \mid (l_2) \mid (j_{2w-4}) \} \simeq^w \frac{n}{(n-1)} \{ (l_2) \mid i_1 i_2 j_3 \cdots j_{2w-4} \} \\ - \frac{1}{(n-1)} G^{j_1 i_2} G_{i_1 i_2} \{ (l_2) \mid (j_{2w-4}) \}$$

after account is taken of the \simeq^w symmetry properties of $[(l_2) \mid (i_{2w-4})]$. Also, from (27.18), (28.44), (28.45) and (28.46), we obtain the equations

$$(28.49) \quad \{ (l_2) \mid (j_{2w-4}) \} \simeq^w \{ l_1 j_1 \mid l_2 j_2 \cdots j_{2w-4} \} \\ + (1/(n-1)) G_{l_1 i_1}^- [l_2^- j_2 \cdots j_{2w-4}].$$

If these last equations are multiplied by $G^{(i_2)}$ and summed for j_1, j_2 , we obtain

$$G^{j_1 i_2} \{ (l_2) \mid (j_{2w-4}) \} \simeq^w \frac{n}{(n-1)} [l_1 l_2 j_3 \cdots j_{2w-4}] \\ - \frac{1}{(n-1)} G_{l_1 l_2} [j_3 \cdots j_{2w-4}]$$

after account is taken of (28.46) and the \simeq^w symmetry of the various tensors. Substitution of this last result in (28.48) leads to the equations

$$(28.50) \quad G^{j_1 i_2} \{ (i_2) \mid (l_2) \mid (j_{2w-4}) \} \simeq^w \frac{n}{(n-1)} \{ (l_2) \mid i_1 i_2 j_3 \cdots i_{2w-4} \} \\ - \frac{n}{(n-1)^2} G_{i_1 i_2} [l_1 l_2 j_3 \cdots j_{2w-4}] \\ + \frac{1}{(n-1)^2} G_{i_1 i_2} G_{l_1 l_2} [j_3 \cdots j_{2w-4}].$$

We also note that if (28.47) is multiplied by $G^{i_2 l_2}$ and summed on repeated indices, we obtain the equations

$$(28.51) \quad G^{i_2 l_2} \{ (i_2) \mid (l_2) \mid (j_{2w-4}) \} \simeq^w \{ i_1 j_1 \mid l_1 j_2 \cdots j_{2w-4} \} \\ + \frac{1}{(n-1)} G_{i_1 i_1} [l_1 j_2 \cdots j_{2w-4}] - \frac{1}{(n-1)} \{ i_1 l_1 \mid j_1 \cdots j_{2w-4} \}.$$

Now, as in (28.49),

$$\{ i_1 l_1 \mid j_1 \cdots j_{2w-4} \} = \{ i_1 j_1 \mid l_1 j_2 \cdots j_{2w-4} \} + \frac{1}{(n-1)} G_{i_1 i_1}^- [l_1^- j_2 \cdots j_{2w-4}].$$

If this result is substituted in (28.51), we find that

$$(28.52) \quad G^{i_2 l_2} \{ (i_2) | (l_2) | (j_{2w-4}) \} \simeq^w \frac{(n-2)}{(n-1)} \{ i_1 j_1 | l_1 j_2 \cdots j_{2w-4} \} \\ + \frac{(n-2)}{(n-1)^2} G_{i_1 j_1} [l_1 j_2 \cdots j_{2w-4}] + \frac{1}{(n-1)^2} G_{i_1 l_1} [j_1 \cdots j_{2w-4}].$$

Finally, if (28.49) is multiplied by $G^{(i_2)}$ and summed on j_1, j_2 , we obtain

$$(28.53) \quad G^{j_1 i_2} \{ (l_2) | (j_{2w-4}) \} \simeq^w \frac{n}{(n-1)} [l_1 l_2 j_3 \cdots j_{2w-4}] \\ - \frac{1}{(n-1)} G_{l_1 l_2} [j_3 \cdots j_{2w-4}].$$

In the notation of the present section, (19.12) may be written as

$$(28.54) \quad \sum \{ (i_2) | (l_2) | (j_{2w-4}) \} \simeq^w 0$$

where the indices $i_1, i_2, l_1, l_2, j_1, \dots, j_{2w-4}$ in the summation assume all possible $(2w)!$ permutations of themselves. We now show, using the equations and \simeq^w symmetry properties established in the preceding paragraphs, that (28.54) may be solved for the $B_{(i_w) | (k_w)}$. The proof is accomplished in a sequence of successive stages.

If account is taken of (28.47) and of the \simeq^w symmetry properties of the tensors of (28.54), each of these tensors may be written as the fixed tensor $\{ (i_2) | (l_2) | (j_{2w-4}) \}$ plus a possible sum of terms like $\pm (1/(n-1)) G_{(i_2)} \{ (l_2) | (j_{2w-4}) \}$. Thus (28.47) defines $\{ i_1 j_1 | (l_2) | i_2 j_2 \cdots j_{2w-4} \}$ in this manner. Similarly,

$$\{ (i_2) | l_1 j_1 | l_2 j_2 \cdots j_{2w-4} \} \simeq^w \{ (i_2) | (l_2) | (j_{2w-4}) \} \\ + \frac{1}{(n-1)} G_{l_1 l_2} \{ (i_2) | j_1 j_2 \cdots j_{2w-4} \}.$$

Repeated application of (28.47) also leads to an analogous expression for $\{ i_1 l_1 | i_2 l_2 | (j_{2w-4}) \}$. It follows from these remarks that (28.54) may be written in the form

$$c_0 \{ (i_2) | (l_2) | (j_{2w-4}) \} \simeq^w \text{sum of terms like } \pm \frac{1}{(n-1)} G_{(i_2)} \{ (l_2) | (j_{2w-4}) \}$$

where $c_0 > 0$, so that the problem of determining $\{ (i_2) | (l_2) | (j_{2w-4}) \}$ is reduced to the similar question for $\{ (l_2) | (j_{2w-4}) \}$. This completes the first stage of the proof.

If (28.54) is multiplied by $G^{(i_2)}$ and summed for i_1, i_2 , we obtain the \simeq^w equations

$$(28.55) \quad \sum_1 \overset{w}{\simeq} 0$$

where \sum_1 is a sum of terms like

$$(28.56) \quad 0, \{(l_2) | (j_{2w-4})\}, G^{i_1 i_2} \{(j_2) | (l_2) | i_1 i_2 j_3 \cdots j_{2w-4}\}, \\ G^{i_1 i_2} \{i_1 l_1 | i_2 l_2 | (j_{2w-4})\}.$$

The first of these is obtained by the use of (21.11). In view of the \simeq^w symmetry properties of $\{(i_2) | (l_2) | (j_{2w-4})\}$, these are the only possible types of terms which may occur in \sum_1 . Now the second and third types listed in (28.56) may be changed by means of (28.50) and (28.52) respectively. Hence \sum_1 may be written as the sum of tensors like

$$(28.57) \quad \{(l_2) | (j_{2w-4})\}, \\ \frac{n}{(n-1)} \{(l_2) | (j_{2w-4})\} - \frac{n}{(n-1)^2} G_{j_1 i_2} [l_1 l_2 j_3 \cdots j_{2w-4}] \\ + \frac{1}{(n-1)^2} G_{i_1 i_2} G_{l_1 l_2} [j_3 \cdots j_{2w-4}], \\ \frac{(n-2)}{(n-1)} \{l_2 j_1 | l_1 j_2 \cdots j_{2w-4}\} + \frac{(n-2)}{(n-1)^2} G_{l_2 j_1} [l_1 j_2 \cdots j_{2w-4}] \\ + \frac{1}{(n-1)^2} G_{l_1 l_2} [j_1 \cdots j_{2w-4}].$$

Since $n \geq 2$, each of the terms (28.57) involves the tensors like $\{(l_2) | (j_{2w-4})\}$, $\{l_2 j_1 | l_1 j_2 \cdots j_{2w-4}\}$ with non-negative coefficients. Also, if account is taken of (28.49) and the \simeq^w symmetry properties of $\{(l_2) | (j_{2w-4})\}$, any tensor constructed from $\{(l_2) | (j_{2w-4})\}$ by a permutation of its indices may be written as the fixed tensor $\{(l_2) | (j_{2w-4})\}$ plus a possible sum of terms like $\pm(1/(n-1))G_{(l_2)} [(j_{2w-4})]$. It follows from these remarks that (28.55) may be written as

$$c_1 \{(l_2) | (j_{2w-4})\} \overset{w}{\simeq} \text{sum of terms like } G_{(l_2)} [(j_{2w-4})] \text{ with numerical coefficients}$$

where $c_1 > 0$, so that the problem of determining $\{(l_2) | (j_{2w-4})\}$ is reduced to the similar question for $[(j_{2w-4})]$. This completes the second stage of the proof.

If (28.55) is multiplied by $G^{(l_2)}$ and summed for l_1, l_2 , we obtain the \simeq^w equations

$$(28.58) \quad \sum_2 \overset{w}{\simeq} 0.$$

Here \sum_2 is a sum of terms like those obtained by multiplying each of the tensors (28.57) by $G^{h_1 h_2}$ where h_1, h_2 are any combination of the indices $l_1, l_2, j_1, j_2, \dots, j_{2w-4}$, and summing for the repeated indices. The first tensor

in (28.57) may lead to terms like

$$(28.59) \quad 0, [(j_{2w-4})], \frac{n}{(n-1)} [(j_{2w-4})] - \frac{1}{(n-1)} G_{i_1 i_2} [j_3 \cdots j_{2w-4}]$$

after multiplication by $G^{l_1 l_2}$, $G^{l_1 i_1}$ and $G^{i_1 i_2}$ respectively, and replacing l -indices by j 's. Also, in the last case, we have made use of (28.53). The second tensor expression in (28.57) may lead to terms like

$$(28.60) \quad \begin{aligned} & 0, \frac{n(n-2)}{(n-1)^2} [(j_{2w-4})] + \frac{1}{(n-1)^2} G_{i_1 i_2} [j_3 \cdots j_{2w-4}], \\ & \frac{n}{(n-1)} [(j_{2w-4})] - \frac{1}{(n-1)} G_{i_1 i_2} [j_3 \cdots j_{2w-4}], \\ & \frac{n^2}{(n-1)^2} [(j_{2w-4})] - \frac{n}{(n-1)^2} (G_{i_3 i_4} [j_1 j_2 j_5 \cdots j_{2w-4}] + G_{i_1 i_2} [j_3 \cdots j_{2w-4}]) \\ & \quad + \frac{1}{(n-1)^2} G_{i_1 i_2} G_{i_3 i_4} [j_5 \cdots j_{2w-4}] \end{aligned}$$

after multiplication by $G^{l_1 l_2}$, $G^{l_1 i_1}$, $G^{l_1 i_3}$ and $G^{i_3 i_4}$ respectively and replacing l 's by j 's. In the last case, use has been made of (28.53). The third tensor expression in (28.57) may lead to terms like

$$(28.61) \quad \begin{aligned} & \frac{n}{(n-1)} [(j_{2w-4})], \quad [(j_{2w-4})], \\ & \frac{n(n-2)}{(n-1)^2} [(j_{2w-4})] + \frac{1}{(n-1)^2} G_{i_1 i_2} [j_3 \cdots j_{2w-4}] \end{aligned}$$

after multiplication by $G^{l_1 l_2}$, $G^{l_1 i_1}$ and $G^{i_1 i_2}$ respectively and replacing the l 's by j 's. Now the tensors in (28.57) are \simeq^w equivalent to those in (28.56). The \simeq^w symmetry properties of the various tensors in (28.56) show that we have considered every possible product of one of these terms by $G^{h_1 h_2}$ in deriving (28.59), (28.60) and (28.61). Hence \sum_2 may be written as a sum of terms like those which appear in (28.59), (28.60) and (28.61).

Since $n \geq 2$, each of these terms involves the tensor $[(j_{2w-4})]$ with non-negative coefficients. Since $[(j_{2w-4})]$ is a \simeq^w symmetric tensor, it follows from the remarks of this and the preceding paragraphs that (28.58) may be written as

$$c_2 [(j_{2w-4})] \simeq^w \text{sum of terms like } G_{i_{2w-5} i_{2w-4}} [(j_{2w-6})] \text{ with numerical coefficients}$$

where $c_2 > 0$, so that the problem of finding $[(j_{2w-4})]$ is reduced to a similar one for $[(j_{2w-6})]$. This completes the third stage of the proof.

We may now multiply (28.58) by $G^{i_{2w-5} i_{2w-4}}$ and sum on repeated indices.

In this way we obtain

$$(28.62) \quad \sum_3 \overset{w}{\simeq} 0.$$

Here \sum_3 is a sum of terms like those obtained by multiplying each of the tensors of (28.59), (28.60) and (28.61) by $G^{h_1 h_2}$ where h_1, h_2 are any combination of the indices $j_1, j_2, \dots, j_{2w-4}$ and summing for repeated indices. All of these terms involve only non-negative coefficients except possibly the terms which arise from

$$(28.63) \quad \begin{aligned} & \frac{n}{(n-1)} [(j_{2w-4})] - \frac{1}{(n-1)} G_{j_1 i_2} [j_3 \cdots j_{2w-4}], \quad \frac{n^2}{(n-1)^2} [(j_{2w-4})] \\ & - \frac{n}{(n-1)^2} (G_{j_3 i_4} [j_1 j_2 j_5 \cdots j_{2w-4}] + G_{j_1 i_2} [j_3 \cdots j_{2w-4}]) \\ & + \frac{1}{(n-1)^2} G_{i_1 i_2} G_{i_3 i_4} [j_5 \cdots j_{2w-4}]. \end{aligned}$$

Now the first of these expressions can only lead to terms like zero or like

$$(28.64) \quad \frac{n}{(n-1)} [(j_{2w-6})] - \frac{1}{(n-1)} G_{j_1 i_2} [j_3 \cdots j_{2w-6}]$$

which we obtain by multiplying by $G^{i_1 i_2}$ and $G^{i_1 i_3}$ respectively and then changing our indices somewhat. The second of the expressions in (28.63) can only lead to terms like zero or like the expressions

$$(28.65) \quad \begin{aligned} & \frac{n(n-2)}{(n-1)^2} [(j_{2w-6})] + \frac{1}{(n-1)^2} G_{j_1 i_2} [j_3 \cdots j_{2w-6}], \\ & \frac{n}{(n-1)} [(j_{2w-6})] - \frac{1}{(n-1)} G_{j_1 i_2} [j_3 \cdots j_{2w-6}], \\ & \frac{n^2}{(n-1)^2} [(j_{2w-6})] - \frac{n}{(n-1)^2} (G_{j_3 i_4} [j_1 j_2 j_5 \cdots j_{2w-6}] + G_{j_1 i_2} [j_3 \cdots j_{2w-6}]) \\ & + \frac{1}{(n-1)^2} G_{j_1 i_2} G_{i_3 i_4} [j_5 \cdots j_{2w-6}] \end{aligned}$$

which we obtain by multiplying by $G^{i_1 i_2}$, $G^{i_1 i_3}$, $G^{i_1 i_5}$ and $G^{i_5 i_6}$ respectively and then changing some of the indices. In all the tensor expressions of (28.64) and (28.65), the coefficients of $[(j_{2w-6})]$ are non-negative.

It is clear from the above remarks that (28.62) may be written⁽⁶⁴⁾ as

$$c_3 [(j_{2w-6})] \overset{w}{\simeq} \text{tensor function of terms like } G_{j_1 i_2}, [(j_{2w-8})] \text{ and } [(j_{2w-10})]$$

⁽⁶⁴⁾ If $w=3$ or $w=4$, simple modifications of the present discussion are necessary.

where $c_3 > 0$. This completes the fourth stage of the proof.

To find $[(j_{2w-8})]$, we multiply (28.62) by $G^{i_2w-7i_2w-6}$ and sum on repeated indices. All the terms of the resulting \simeq^w equations

$$(28.66) \quad \sum_4^w \simeq 0$$

have non-negative coefficients except possibly the terms which arise from the last two expressions of (28.65). But these expressions are exactly analogous to those of (28.63) which were considered in connection with (28.62). The previous discussion shows that the tensors $[(j_{2w-8})]$ which arise from these expressions have non-negative coefficients and consequently (28.66) may be solved for $[(j_{2w-8})]$ in terms of $[(j_{2w-10})]$, and so on. This completes the fifth stage of the proof.

This process may be continued until eventually, at the $(w+1)$ th stage of the proof, we reach a \simeq^w equation which may be written as

$$c_w G^{(i_2)} [(j_2)] \simeq^w 0$$

with $c_w > 0$. It follows from this equation that

$$(28.67) \quad G^{(i_2)} [(j_2)] \simeq^w 0.$$

Since the solution for each of the tensors

$$(28.68) \quad G^{(i_2)} [(j_2)], [(j_2)], [(j_4)], \dots, [(j_{2w-4})], \{ (l_2) | (j_{2w-4}) \}, \\ \{ (i_2) | (l_2) | (j_{2w-4}) \}$$

is dependent only upon the solution for the preceding ones in the chain (28.68), it follows from (28.67) that

$$\{ (i_2) | (l_2) | (j_{2w-4}) \} \simeq^w 0$$

which is equivalent to (28.39). This completes that proof of the mathematical induction. The details of the proof show that $B_{(i_w) | (l_w)}$ is a rational function of the tensors (28.34) and their first conformal derivatives and of K_{hijk} . The present proof as well as that of Theorem 28.1 only involves systems of linear algebraic equations. We may summarize the results of the above discussion and of Theorem 28.1 in the following theorem.

THEOREM 28.2. *The \simeq^w equations*

$$(28.69) \quad B_{(i_w) | (l_w)} \simeq^w 0, \quad w = 1, 2, \dots, M, \\ U^{(h_{w-1}) (i_{w+1})} \simeq^w 0, \quad U^{(h_w) (i_{w+1})} \simeq^w 0$$

are consequences of the fundamental equations of V_n and of equation (19.12). The B 's are uniquely determined by these \simeq^w equations and the U 's are uniquely determined except for additive null solutions.

29. The existence theorem. We now prove the *first form of the existence theorem* :

THEOREM⁽⁶⁵⁾ 29.1. *Let \bar{R}_m be any conformally euclidean space of class C^4 and dimensionality $m > 2$ and let \mathcal{R} be an open region of an n -dimensional number space $\{x^i\}$ of dimensionality $n > 1$. Suppose that*

$$(29.1) \quad B_{i_1 | l_1}, B_{(i_2) | (l_2)}, \dots, B_{(i_M) | (l_M)}, E_{i l}$$

are any functions of x^i defined on \mathcal{R} so that the functions $B_{i_1 | l_1}$ are of class C^2 and the others are of class C^1 . Also, suppose that functions

$$(29.2) \quad U^{h_1}_{(i_1)}, U^{(h_2)}_{(i_2)}, \dots, U^{(h_{M-1})}_{(i_{M-1})}; U^{(h_2)}_{(i_2)}, U^{(h_3)}_{(i_3)}, \dots, U^{(h_M)}_{(i_{M+1})}$$

of class C^1 on \mathcal{R} exist such that the fundamental equations formed with respect to (29.1) and (29.2) are true. Let y^α_0 be the coordinates of any point \mathcal{P} of \bar{R}_m ; x^i_0 any fixed parameters belonging to \mathcal{R} ; ϕ_0, ϕ_{i_0} any $n+1$ real numbers; $G^\alpha_{i_0}, G^\alpha_{(i_2)0}, \dots, G^\alpha_{(i_M)0}, \mu^\alpha_0$ any set of basis beins and any vector at \mathcal{P} which satisfy the boundary conditions when $x^i = x^i_0$. Then there exists an n -dimensional Riemann space V_n of class C^3 defined on some region of \mathcal{R} about x^i_0 which is imbedded in \bar{R}_m by equations of the form

$$(29.3) \quad y^\alpha = y^\alpha(x^i)$$

and which has the respective functions (29.1) as its successive conformal measure tensors and deviation tensor respectively. For $x = x^i_0$, V_n passes through \mathcal{P} so that its moving conformal basis beins and mean curvature normal take the positions $G^\alpha_{i_0}, G^\alpha_{(i_2)0}, \dots, G^\alpha_{(i_M)0}, \mu^\alpha_0$ respectively and the values of the gauge function of V_n and of its derivative with respect to x^i at \mathcal{P} are ϕ_0 and ϕ_{i_0} respectively. Any other subspace with these properties will coincide with the V_n defined by (29.3) in the common region of definition.

For the proof of this theorem, we consider the following system of partial differential equations in the unknown quantities (20.1) :

$$(29.4) \quad \begin{aligned} \frac{\partial y^\alpha}{\partial x^{i_1}} &= G^\alpha_{i_1}, \\ \frac{\partial G^\alpha_{i_1}}{\partial x^{i_2}} &= G^\alpha_{i_1} \Gamma^h_{i_1 i_2} - G^\beta_{i_1} G^\gamma_{i_2} \Gamma^\alpha_{\beta \gamma} + G^\alpha_{(i_2)}, \\ \frac{\partial G^\alpha_{(i_w)}}{\partial x^{i_{w+1}}} &= \sum_{v=1}^w G^\alpha_{i_1 \dots i_{v-1} i_{v+1} \dots i_w} \Gamma^h_{i_v i_{w+1}} - G^\beta_{(i_w)} G^\gamma_{i_{w+1}} \Gamma^\alpha_{\beta \gamma} + G^\alpha_{(i_{w+1})} \\ &\quad + U^{(h_w)}_{(i_{w+1})} G^\alpha_{(h_w)} + U^{(h_{w-1})}_{(i_{w+1})} G^\alpha_{(h_{w-1})}, \quad w = 2, 3, \dots, M, \\ \frac{\partial \psi}{\partial x^i} &= \psi_i, \end{aligned}$$

⁽⁶⁵⁾ Various modifications of this theorem appear in the remarks at the conclusion of the proof.

$$\begin{aligned}
 \frac{\partial \psi_i}{\partial x^j} &= \psi_h \Gamma^h_{ij} + \psi_i \psi_j + E_{ij} - a_{\alpha\beta} \mu^\alpha G^\beta_{ij} + \frac{1}{(m-2)} \rho_{\alpha\beta} G^\alpha_i G^\beta_j \\
 &\quad - \frac{1}{2} \left[e^{2\psi} a_{\alpha\beta} \mu^\alpha \mu^\beta + G^{hk} \psi_h \psi_k + \frac{e^{2\psi} \rho}{(m-1)(m-2)} \right] G_{ij}, \\
 (29.4) \quad \frac{\partial \mu^\alpha}{\partial x^i} &= -\mu^\beta G^\gamma_i \Gamma^\alpha_{\beta\gamma} + \frac{e^{-2\psi}}{(n-1)} \left[G^\alpha_{ih} G^{hl} + U^{(\sigma_2)}_{ih} G^{hl} G^\alpha_{(\sigma_2)} \right. \\
 &\quad + U^\sigma_{ih} G^{hl} G^\alpha_\sigma + (n-1) G^\alpha_{ih} G^{hl} \psi_l - (n-1) l^{2\psi} \mu^\alpha \psi_i \\
 &\quad - (n-1) a_{\beta\gamma} \mu^\beta G^\gamma_{ih} G^\alpha_i G^{hl} + G^\alpha_h K^h_i + (n-2) G^\alpha_h E^h_i \\
 &\quad \left. + G^\alpha_i E - \frac{(n-1)}{(m-2)} (e^{2\psi} a^{\alpha\beta} - G^{hk} G^\alpha_h G^\beta_k) \rho_{\beta\gamma} G^\gamma_i \right].
 \end{aligned}$$

Here Γ^i_{jk} and K_{ij} are the Christoffel symbols of the second kind and the Ricci tensor formed with respect to G_{ij} and $\Gamma^\alpha_{\beta\gamma}$ is given by

$$(29.5) \quad \Gamma^\alpha_{\beta\gamma} = \left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\} + a^{\alpha\beta} \eta_\gamma + a^\alpha_\gamma \eta_\beta - a_{\beta\gamma} a^{\alpha\delta} \eta_\delta$$

where η_γ is defined by

$$\eta_\gamma = a_{\gamma\beta} [\mu^\beta - \psi_h e^{-2\psi} G^{hk} G^\beta_k].$$

The definition of $\Gamma^\alpha_{\beta\gamma}$ in terms of the given tensors and the unknowns (20.1) is suggested by (8.8), (8.10), (8.11) and (13.10). We also define $A_{\alpha\beta}$ by means of the equations

$$(29.6) \quad A_{\alpha\beta} = e^{-2\psi} a_{\alpha\beta}.$$

Of course, equations (29.4) are the extended conformal Frenet equations after account is taken of the definition of the conformal derivative.

To the system of equations (29.4), we adjoin the equations

$$\begin{aligned}
 (29.7) \quad a_{\alpha\beta} G^\alpha_{(i_w)} G^\beta_{(l_v)} &= 0, & w \neq v, w, v = 1, 2, \dots, M, \\
 a_{\alpha\beta} G^\alpha_{(i_w)} G^\beta_{(l_w)} &= e^{2\psi} B_{(i_w)(l_w)}, \\
 a_{\alpha\beta} \mu^\alpha G^\beta_j &= 0.
 \end{aligned}$$

These equations constitute a set of algebraic boundary conditions which must be satisfied by the solutions of (29.4). In virtue of (29.6), it is clear that (29.7) are equivalent to the B -conditions.

The right members of equations (29.4) depend upon the known functions

$$\Gamma^i_{jk}(x), U^{\dots}(x), G_{ij}(x), K_{ij}(x), E_{ij}(x), E(x)$$

and the unknowns (20.1). These latter appear both explicitly and also implicitly in the functions

$$a_{\alpha\beta}(y), \left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\}, \rho_{\alpha\beta}(y), \rho(y).$$

Actually, the U 's are not given functions. The hypothesis of the theorem merely affirms the existence of at least one set of U 's. But according to Theorem 28.1, any other set of U 's differs from the first by null solutions which do not affect equations (29.4). Hence we may think of the U 's as uniquely determined by the given functions (29.1).

According to the hypothesis, $a_{\alpha\beta}(y)$ is of class C^3 , $G_{ij}(x)$ is of class C^2 and $E_{ij}(x)$ is of class C^1 . Since G_{ij} is of class C^2 , Γ^i_{jk} is of class C^1 and K_{hijk} is of class C^0 . However, since the conformal Gauss equations (22.13) (condition [1, 1]) are satisfied, it follows from the hypothesis of the theorem that K_{hijk} are actually of class C^1 in the x^i . Hence each right member of (29.4) is of class C^1 in all the dependent variables (20.1) and in the x^i for any y^α in the coordinate system; any x^i in \mathcal{R} ; any ψ, ψ_i ; any $G^\alpha_i, G^\alpha_{(i_2)}, \dots, G^\alpha_{(i_M)}, \mu^\alpha$. The equations obtained by partial differentiation of (29.7) and utilizing both (29.4) and the boundary conditions are the set of equations which we have called the D -conditions. Now, by hypothesis, both the D -conditions and the integrability conditions of (29.4) are true identically. The remarks of the last two paragraphs show that we may apply the fundamental existence theorem⁽⁶⁶⁾ for such a system of partial differential equations with boundary conditions.

According to this theorem, there exists a set of functions

$$(29.8) \quad y^\alpha(x), G^\alpha_{i_1}(x), \dots, G^\alpha_{(i_M)}(x), \mu^\alpha(x), \psi(x), \psi_i(x)$$

of class C^1 , satisfying the equations (29.4) and the boundary conditions (29.7) throughout the region of definition, which are defined in a sufficiently small region of \mathcal{R} about x^{i_0} and which assume the values $y^{\alpha_0}, G^{\alpha_{i_0}}, \dots, G^{\alpha_{(i_M)0}}, \mu^{\alpha_0}, -\phi_0, -\phi_{i_0}$ for $x = x^{i_0}$. Any two solutions of (29.4) which have the same initial conditions for $x = x^{i_0}$ are identical in their common region of definition.

Since the functions (29.8) are of class C^1 , it follows from the equations of (29.4) which involve $\partial\psi_i/\partial x^j$ that $\partial\psi_i/\partial x^j$ is actually of class C^1 so that ψ is of class C^3 . Also, since μ^α is of class C^1 , $\Gamma^\alpha_{\beta\gamma}$ is also of class C^1 . If we now return to the equations of (29.4) which involve $\partial\mu^\alpha/\partial x^i$, we see that $\partial\mu^\alpha/\partial x^i$ is actually of class C^1 so that μ^α and consequently $\Gamma^\alpha_{\beta\gamma}$ are of class C^2 . These remarks and the conformal Frenet equations of (29.4) show that the various basis beins $G^\alpha_{(i_w)}$ are actually of class C^2 . It follows from the special form of the first set of equations of (29.4) that the $y^\alpha(x)$ are of class C^3 .

The hypothesis of the existence theorem assumes that real basis beins $G^\alpha_{(i_w)}$ exist at \mathcal{P} which satisfy the boundary conditions. Since the $B_{(i_w)|(t_w)}$ all satisfy the R -conditions, the existence of such real basis beins for any x^i

⁽⁶⁶⁾ The existence theorem which we are using is an easy modification (to allow boundary conditions) of one which appears in [11, p. 661].

in \mathcal{R} is guaranteed. Further, since $B_{i_1|l_1}$ is positive definite by condition [R 2], it follows from the second set of boundary conditions (29.7) with $w=1$ that the rank of the matrix $\|G^{\alpha_{i_1}}\|$ is n for x^i in \mathcal{R} . Consequently, according to the definition and discussion contained in §4, the subspace defined by (29.3), where the $y^\alpha(x^i)$ are the unique solutions of (29.4), is an n -dimensional Riemann space V_n of class C^3 .

According to the first set of equations (29.4), G^α_i spans the tangent vector space of V_n . Hence the Riemann metric tensor of V_n is defined by

$$g_{ij} = a_{\alpha\beta} G^\alpha_i G^\beta_j.$$

A comparison of these equations with (29.7) for $w=1$ shows that

$$(29.9) \quad e^{2\psi} G_{ij} = g_{ij}$$

where we have written G_{ij} for $B_{i_1|l_1}$. It follows from these equations that

$$(29.10) \quad \left\{ \begin{matrix} i \\ jk \end{matrix} \right\} = \Gamma^i_{jk} + G^i_j \psi_{,k} + G^i_k \psi_{,j} - G_{jk} G^{il} \psi_{,l}$$

where

$$\left\{ \begin{matrix} i \\ jk \end{matrix} \right\}$$

are the Christoffel symbols of the second kind formed with respect to g_{ij} . Also, (5.3) is true for V_n where $g^\alpha_i(x)$ and $G^\alpha_i(x)$ are identical functions. Hence it follows from (5.3) and the second set of equations (29.4) that

$$G^\alpha_k \left[\Gamma^h_{ij} - \left\{ \begin{matrix} h \\ ij \end{matrix} \right\} \right] - G^\beta_i G^\alpha_j \left[\Gamma^\alpha_{\beta\gamma} - \left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\} \right] = g^\alpha_{ij} - G^\alpha_{ij}.$$

If we simplify these equations, using (29.5), (29.9), (29.10) and the boundary conditions, we find that

$$(29.11) \quad G^\alpha_{ij} = g^\alpha_{ij} - \mu^\alpha g_{ij}.$$

If we multiply these equations by G^{ij} and sum on repeated indices, using the A -condition [A 1] (in the equivalent form of equation (7.11)) and (29.9), we obtain equations (5.9). Consequently the functions $\mu^\alpha(x)$ listed in (29.8) are the components of the mean curvature normal of V_n . It also follows from (29.11) that $G^\alpha_{ij}(x)$ is the basis bein which spans the first conformal normal vector space of V_n . The relative conformal curvature Λ of V_n is defined by (6.12). If use is made of condition [A 2] (in the form of equation (7.12)), (29.6) and (29.9), we find that $\Lambda = e^{-\psi}$ so that $-\psi$ is the guage function.

As a result of the geometric interpretation which we have shown for the functions $\mu^\alpha(x)$, $\psi(x)$, $G^\alpha_i(x)$ and $G^\alpha_{ij}(x)$, it is clear from equations (29.5), (29.6) and (29.9) that $A_{\alpha\beta}(x)$, $G_{ij}(x)$, $\Gamma^\alpha_{\beta\gamma}(x)$ and $\Gamma^i_{jk}(x)$, defined in this section, are the conformal measure tensors and conformal coefficients of connec-

tion of \bar{R}_m and V_n respectively. It is then immediate from the boundary conditions and the remaining equations (29.4) that $G^{\alpha_{i_1}}(x), G^{\alpha_{(i_2)}}(x), \dots, G^{\alpha_{(i_M)}}(x)$ are the conformal basis beins of V_n and that the given functions (29.1) are the successive conformal measure tensors and deviation tensor respectively of V_n .

The choice of initial conditions in the determination of V_n makes it clear that for $x = x^i_0$, V_n passes through \mathcal{P} so that its moving conformal basis beins and mean curvature normal occupy the positions preassigned by the theorem and so that the gauge function of V_n and its derivative with respect to x^i at \mathcal{P} are ϕ and ϕ_{i_0} . This remark completes the proof of the theorem. We note that, in this proof, the theorem applies to a fixed coordinate and parameter system. Nevertheless, under coordinate transformations of class C^4 and parameter changes of class C^3 , the solutions in one coordinate-parameter system will transform into the solutions in any other allowable system since the partial differential equations (29.4) may be written in the invariant form, tensor = tensor. Finally, we remark that all the derivations of the various fundamental equations of V_n are valid under the hypothesis of the existence theorem.

Remark 1. Since the $G^{\alpha_{(i_w)}}$ are all of class C^2 , it follows from (29.7) that the various conformal normal measure tensors $B_{(i_2)|(l_2)}, \dots, B_{(i_M)|(l_M)}$ must be of class C^2 . This means that if the complete hypothesis of Theorem 29.1 is satisfied (including the validity of the fundamental equations), the conformal measure tensors must all be of class C^2 instead of class C^1 .

Remark 2. If $B_{i_1|l_1}$ is assumed to be of class C^3 instead of class C^2 , then the Γ^i_{jk} are of class C^2 . Consequently it is seen from the special form of the first two sets of equations (29.4) that $y^\alpha(x^i)$ are of class C^4 in this case.

Remark 3. Suppose that the enveloping space is a euclidean space R_m or any space of constant curvature S_m and that we limit the conformal transformations to mappings between spaces of this kind only⁽⁶⁷⁾. Then the hypothesis of Theorem 29.1 may be weakened so that R_m or S_m is of class C^3 instead of class C^4 and the remainder of the theorem will hold as stated. For in this case, $\rho_{\alpha\beta\gamma\delta}$ is replaced by $k(a_{\alpha\gamma}a_{\beta\delta} - a_{\alpha\delta}a_{\beta\gamma})$ where k is the constant Riemann curvature of the space so that only the first derivatives of $a_{\alpha\beta}$ occur in equations (29.4).

Remark 4. According to Theorem 26.1, the conditions $[\mu^\alpha, u]$ may be omitted from the fundamental equations if $n > 2$. According to Theorem 24.1, the conditions $[\psi_i]$ may be omitted from the fundamental equations if $n > 3$. If $n > 2$, the tensor E_{il} is defined in terms of $B_{(i_2)|(l_2)}$ and G_{il} by means of (24.15) and therefore is not an independent tensor.

By considering equations (20.12), (20.13), (20.14), (20.23) and the first

⁽⁶⁷⁾ These transformations are a first generalization of the inversive group of transformations of R_m on itself. These transformations may be characterized by the fact that they map each geodesic circle of a space of constant curvature on a geodesic circle in the image space.

two sets of equations (20.9) instead of equations (29.4), a somewhat simpler formulation may be given to the existence theorem for a hypersurface. As the methods parallel those used in the general case (except that Theorem 28.1 plays no role in the proof), we state this theorem without proof.

THEOREM 29.2 *Let \bar{R}_m be any conformally euclidean space of class C^4 and dimensionality $m > 2$ and let \mathcal{R} be an open region of an $(m-1)$ -dimensional number space $\{x^i\}$. Suppose that*

$$(29.12) \quad G_{ij}dx^i dx^j, \quad B_{ij}dx^i dx^j, \quad E_{ij}dx^i dx^j$$

are any symmetric quadratic differential forms defined on \mathcal{R} of which the first is positive definite and so that the coefficients of these forms are of class C^2 , C^2 and C^1 respectively. Also, suppose that the A -conditions $[A' 1]$, $[A' 2]$ and the integrability conditions $[1, 1]$, $[1, 2]$, $[\psi_i]$, $[\mu]$ are satisfied by these coefficients. Let y^α be the coordinates of any point \mathcal{P} of \bar{R}_m ; x^i_0 any fixed parameters belonging to \mathcal{R} ; μ_0, ϕ_0, ϕ_{i0} any $(m+1)$ real numbers; $G^\alpha_{i0}, Z^\alpha_0$ any basis vien and vector at \mathcal{P} which satisfy the boundary conditions $[B' 1]$ and $[B' 2]$ when $x = x^i_0$. Then there exists an $(m-1)$ -dimensional hypersurface V_{m-1} of class C^3 defined on some region of \mathcal{R} about x^i_0 which is imbedded in \bar{R}_m by equations of the form $y^\alpha = y^\alpha(x^i)$ and has the respective forms (29.12) as its successive conformal fundamental forms. For $x = x^i_0$, V_{m-1} passes through \mathcal{P} so that its conformal tangent vector bein and normal vector take the position $G^\alpha_{i0}, Z^\alpha_0$ and the values of its mean curvature, gauge function and of the derivative of the latter with respect to x^i at \mathcal{P} are μ_0, ϕ_0 and ϕ_{i0} respectively. Any other hypersurface with these properties will coincide with the V_{m-1} defined above in the common region of definition.

Finally we note that, in accordance with Theorem 28.2, the conformal fundamental tensors determine the $B_{(i_w)|(l_w)}$ and the U 's. As a corollary of Theorem 28.2 and Theorem 29.1, we have the *second form of the existence theorem* :

THEOREM 29.3 *Suppose that*

$$(29.13) \quad G_{(i_1 l_1)} dx^{i_1} dx^{l_1}, G_{(i_2 l_2)} dx^{i_2} dx^{l_2} dx^{i_1} dx^{l_1} dx^{i_2} dx^{l_2}, \dots, \\ G_{(i_M l_M)} dx^{i_1} \dots dx^{i_M} dx^{l_1} \dots dx^{l_M}, E_{ij} dx^i dx^j$$

are any symmetric differential forms defined on \mathcal{R} whose coefficients satisfy equations (19.12) for suitable functions (29.1). Suppose further that the entire hypothesis of Theorem 29.1 is satisfied with reference to these functions (29.1). Then there exists an n -dimensional Riemann space V_n of class C^3 defined on some region of \mathcal{R} about x^i_0 which is imbedded in the \bar{R}_m of class C^4 by equations of the form (29.3) and which has the respective differential forms (29.13) as its successive conformal fundamental forms. The conclusion of Theorem 29.1 concerning the initial position and unique determination of V_n is also valid here.

30. Groups of conformal transformations in euclidean space R_m and in a conformally euclidean space \bar{R}_m . If an S_m of constant curvature k is mapped on an S'_m of constant curvature k' where S_m and S'_m are spaces of class C^3 and $m > 2$, then one readily finds as a result of (11.3) that $\sigma(y^\alpha)$ satisfies the partial differential equations

$$(30.1) \quad \sigma_{\alpha\beta} = - [e^{2\sigma} k' - k + \Delta_1 \sigma] a_{\alpha\beta} / 2.$$

Conversely, if a transformation whose mapping function $\sigma(y^\alpha)$ is a solution of (30.1) is applied to S_m , the image space must be S'_m .

Now suppose that both S_m and S'_m are euclidean spaces. Then $k = k' = 0$. In this case, (30.1) may be written as

$$(30.2) \quad (e^{-\sigma})_{,\alpha\beta} = (\Delta_1(e^{-\sigma}) / 2(e^{-\sigma})) \cdot a_{\alpha\beta}.$$

If we let y^α be cartesian rectangular coordinates, $a_{\alpha\beta} = \delta_{\alpha\beta}$ and

$$\left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\} = 0.$$

The solution of equations (30.2) in these coordinates is easily found to be

$$(30.3) \quad e^{-\sigma} = a, \quad a > 0,$$

or

$$(30.4) \quad e^{-\sigma} = \sum_{\alpha} b(y^\alpha - d^\alpha)^2, \quad b > 0$$

where a, b, d^α are real constants. The point defined by $y^\alpha = d^\alpha$ is a singular point of any conformal transformation associated with (30.4). We state the above result in the following theorem.

THEOREM 30.1. *Every mapping function $\sigma(y^\alpha)$ that maps R_m ($m > 2$) on itself conformally must satisfy (30.3) or (30.4), and conversely.*

The totality of conformal transformations of R_m on itself forms a group \mathcal{G} . As a consequence of Theorem 30.1, it is easy to establish the theorem of Liouville⁽⁶⁸⁾. This theorem states that *the most general conformal map of R_m ($m > 2$) on itself is the product of an inversion with respect to a hypersphere by a motion⁽⁶⁹⁾ or the product of a magnification of similitude by a motion*. Now every magnification of similitude is the product of two inversions with respect to hyperspheres having the same center. Hence the group \mathcal{G} is the inversive group of transformations of R_m .

⁽⁶⁸⁾ For $m > 3$, this theorem was proved by S. Lie [9, p. 186]. Also see [1, pp. 375-376], [13, pp. 205-210].

⁽⁶⁹⁾ By a motion, we mean any point transformation of R_m which is expressed (in cartesian coordinates) by equations having an orthogonal matrix. The Jacobian of the transformation may be either +1 or -1 so that every motion is the product of a finite number of translations, rotations and reflections with respect to hyperplanes.

It is shown later that the set of geometric objects: y^α , $G^\alpha_{(i_w)}$ ($w=1, 2, \dots, M$), μ_α , ϕ , ϕ_i determine the parameters of \mathcal{G} . For this reason, we call this set of objects the *group parameter set* or *parameter set*. We denote this set by the symbol Ψ . The *order* of Ψ is the integer $N_{12 \dots M}$ which is the dimension number of the largest osculating vector space $I_{12 \dots M}$ of V_n . Of course, as stated in (18.9), the maximum value of the order of Ψ is m . It is possible to define the objects belonging to Ψ independently of V_n and in any V_m . The $G^\alpha_{(i_w)}$ and μ_α are any set of beins spanning vector spaces and a space vector which obey equations (29.7) where the $B_{(i_w)|(l_w)}$ are any surface tensors, $\psi = -\phi$ and $\mu^\alpha = a^{\alpha\beta}\mu_\beta$. The quantity ϕ is any surface scalar and ϕ_i is $\partial\phi/\partial x^i$. Under any conformal transformation of V_m , the respective objects of Ψ transform according to the laws (2.5),

$$(30.5) \quad \bar{G}^\alpha_{(i_w)} = G^\alpha_{(i_w)},$$

(6.8), (8.7) and

$$(30.6) \quad \bar{\phi}_i = \phi_i - \sigma_{,i},$$

respectively.

Since the $G^\alpha_{(i_w)}$ are unchanged by a conformal transformation of V_m , it follows from the laws of change for $a_{\alpha\beta}$ and ϕ and from (29.7) that the $B_{(i_w)|(l_w)}$ are also unchanged. We also define η_α corresponding to Ψ by means of (8.10) where ϕ_α is defined by equations (8.8) written in the form

$$\phi_\alpha = e^{2\phi} G^{ij} G^{\beta}_j a_{\alpha\beta} \phi_i$$

where G^{ij} are the contravariant components of the positive definite tensor $B_{i|j}$. It follows readily from the above laws of change that η_α transforms according to (8.9) under a conformal transformation of V_m . If the geometric objects of a parameter set Ψ have the geometric significance described in Theorem 29.1 for some subspace V_n , then Ψ is said to be *associated* with V_n at the point whose coordinates belong to Ψ . If, for two parameter sets Ψ and $\bar{\Psi}$, the tensors $B_{(i_w)|(l_w)}$ and $\bar{B}_{(i_w)|(l_w)}$ which occur in the conditions (29.7) for the $G^\alpha_{(i_w)}$ are equivalent (equal after suitable changes of the x^i), then we say that Ψ and $\bar{\Psi}$ are *equivalent*. Of course, equivalent parameter sets have the same order. A justification for this definition of equivalent parameter sets lies in the following theorem:

THEOREM 30.2. *A conformal transformation of R_m ($m > 2$) into itself exists which transforms any given parameter set Ψ into any other equivalent parameter set $\bar{\Psi}$.*

The proof of the theorem follows. Let the parameter sets Ψ and $\bar{\Psi}$ be $\{y^\alpha, G^\alpha_{(i_w)}, \mu_\alpha, \phi, \phi_i\}$ and $\{\bar{y}^\alpha, \bar{G}^\alpha_{(i_w)}, \bar{\mu}_\alpha, \bar{\phi}, \bar{\phi}_i\}$ respectively. According to (8.7), if a mapping function σ is applied to Ψ , the quantity ϕ transforms into

ϕ' where $\phi' = \phi - \sigma$. Hence by means of a conformal transformation⁽⁶⁰⁾ \mathcal{T}_1 of R_m , it is possible to transform Ψ into Ψ' : $\{y'^\alpha, G'^\alpha_{(i_w)}, \mu'_\alpha, \bar{\phi}, \bar{\phi}_i\}$ so that the quantities ϕ', ϕ'_i in Ψ' corresponding to ϕ, ϕ_i are $\bar{\phi}, \bar{\phi}_i$. The tensors $B_{(i_w)|(i_w)}$ are unchanged by this transformation. Also, by hypothesis, we may consider $B_{(i_w)|(i_w)}$ and $\bar{B}_{(i_w)|(i_w)}$ as equal after a suitable change in the surface parameters x^i . Then it follows since $\phi' = \bar{\phi}$ that the conditions (29.7) on the $G'^\alpha_{(i_w)}$ and $\bar{G}^\alpha_{(i_w)}$ are identical; that is, the vector spaces $G'^\alpha_{(i_w)}$ and $\bar{G}^\alpha_{(i_w)}$ have the same inner orientation. It follows that a motion \mathcal{T}_2 in R_m exists so that $y'^\alpha = \bar{y}^\alpha, G'^\alpha_{(i_w)} = \bar{G}^\alpha_{(i_w)}$. Under this motion, the parameter set Ψ' becomes the parameter set Ψ'' : $\{\bar{y}^\alpha, \bar{G}^\alpha_{(i_w)}, \mu''_\alpha, \phi'', \phi''_i\}$. We write η''_α and $\bar{\eta}_\alpha$ for the quantities corresponding to Ψ'' and $\bar{\Psi}$ and now consider the following two cases:

(1) Suppose that $\eta''_\alpha = \bar{\eta}_\alpha$. This is equivalent to $\mu''_\alpha = \bar{\mu}_\alpha$ and $\phi''_i = \bar{\phi}_i$. Then a unique positive constant a exists so that $e^{\bar{\phi}} = ae^{\phi''}$. If we subject R_m to the magnification of similitude \mathcal{T}_3 determined by $e^{-\sigma} = a$, it follows from (6.8), (8.7) and (30.6) that $\{\mu''_\alpha, \phi'', \phi''_i\}$ transforms into $\{\bar{\mu}_\alpha, \bar{\phi}, \bar{\phi}_i\}$. According to (2.5) and (30.5), $\bar{y}^\alpha, \bar{G}^\alpha_{(i_w)}$ of Ψ'' remain unchanged. Consequently the conformal transformation $\mathcal{T}_3\mathcal{T}_2\mathcal{T}_1$ changes Ψ into $\bar{\Psi}$.

(2) Suppose at least one of the equations in the hypothesis of case (1) is untrue. We choose cartesian rectangular coordinates in R_m so that the $\bar{y}^\alpha = 0$ (or transform the point whose coordinates belong to Ψ'' and $\bar{\Psi}$ to the origin by a motion). We now determine a mapping function σ satisfying (30.4) which transforms Ψ'' into $\bar{\Psi}$. At the origin, we find from (30.4) that

$$e^{-\sigma} = b \sum_{\beta} d\beta^2, \quad \sigma_{,\alpha} = 2d^\alpha / \sum_{\beta} d\beta^2.$$

If we substitute these values in (8.7) and (8.9), we find that

$$(30.7) \quad e^{\bar{\phi} - \phi''} = b \sum_{\beta} d\beta^2, \quad \eta''_\alpha - \bar{\eta}_\alpha = 2d^\alpha / \sum_{\beta} d\beta^2.$$

Since $\eta''_\alpha \neq \bar{\eta}_\alpha$, at least one d^α differs from zero. Hence, from the second set of equations (30.7),

$$\frac{1}{4} \sum_{\alpha} (\eta''_\alpha - \bar{\eta}_\alpha)^2 = 1 / \sum_{\beta} d\beta^2.$$

Therefore the solution of (30.7) is

$$(30.8) \quad b = \frac{1}{4} e^{\bar{\phi} - \phi''} \cdot \sum_{\beta} (\eta''_\beta - \bar{\eta}_\beta)^2, \\ d^\alpha = 2(\eta''_\alpha - \bar{\eta}_\alpha) / \sum_{\beta} (\eta''_\beta - \bar{\eta}_\beta)^2.$$

It is immediate that b is positive so that values b, d^α given by (30.8) may be

⁽⁶⁰⁾ The existence of conformal transformations of R_m with this property follows from the discussion which appears below.

used to define a mapping function σ in accordance with (30.4). Since not all the d^α are zero, the origin is not a singular point of any transformation associated with (30.4). Any such transformation \mathcal{C}_3 would transform $\{\mu''_\alpha, \phi'', \phi''_i\}$ into $\{\bar{\mu}_\alpha, \bar{\phi}, \bar{\phi}_i\}$. Since $\bar{y}^\alpha, \bar{G}^\alpha_{(i_w)}$ remain unchanged by \mathcal{C}_3 , the conformal transformation $\mathcal{C}_3\mathcal{C}_2\mathcal{C}_1$ changes Ψ into $\bar{\Psi}$. This completes the proof of the theorem.

Now suppose that the geometric objects in $\bar{\Psi}$ are fixed while those which belong to Ψ range over all admissible values. Then the corresponding conformal transformations range over the totality of transformations belonging to the inversive group \mathcal{G} . Hence the geometric objects of Ψ determine the parameters of \mathcal{G} . As noted in a previous paper⁽⁶¹⁾, a count of the independent parameters proves that \mathcal{G} has exactly $(m+1)(m+2)/2$ essential parameters.

Let \bar{R}_m ($m > 2$) be a conformally euclidean space and suppose \mathcal{C}_1 is a conformal transformation which transforms \bar{R}_m into R_m . If \mathcal{C} is any transformation belonging to \mathcal{G} , then the conformal transformation $\mathcal{C}_1^{-1}\mathcal{C}\mathcal{C}_1$ maps \bar{R}_m on itself. The totality of these transformations $\{\bar{\mathcal{C}}\}$ forms the complete group $\bar{\mathcal{G}}$ of conformal transformations of \bar{R}_m upon itself. The group $\bar{\mathcal{G}}$ is the conformal image in \bar{R}_m of the group \mathcal{G} in R_m and is independent of the particular mapping \mathcal{C}_1 . It is clear that Theorem 30.2 may be proved to be valid for parameter sets in \bar{R}_m by means of this correspondence between \mathcal{G} and $\bar{\mathcal{G}}$. Another consequence is that every conformally euclidean space \bar{R}_m ($m > 2$) admits a continuous group of conformal transformations on itself having $(m+1)(m+2)/2$ essential parameters.

31. The conformal equivalence theorem. The fundamental theorem of Riemannian geometry for a subspace in a euclidean space R_m or a space of constant curvature S_m is the congruence theorem. We are now in a position to establish easily the analogue of this theorem for conformal differential geometry.

THEOREM⁽⁶²⁾ 31.1. *Let $(1)\bar{R}_m$ and $(2)\bar{R}_m$ be conformally euclidean spaces of class C^4 and dimensionality $m > 2$ and let $(1)V_n$ and $(2)V_n$ be subspaces of class C^3 in $(1)\bar{R}_m$ and $(2)\bar{R}_m$ respectively of dimensionality $n > 1$. Suppose that the fundamental equations of $(1)V_n$ and $(2)V_n$ are valid and suppose that the corresponding conformal fundamental forms of $(1)V_n$ and $(2)V_n$ are equal. Then a conformal transformation exists so that $(1)\bar{R}_m \rightleftharpoons (2)\bar{R}_m$ and $(1)V_n \rightleftharpoons (2)V_n$.*

In short, this theorem states that n -dimensional subspaces of \bar{R}_m 's whose corresponding conformal fundamental forms are equal are conformally equivalent. To prove the theorem, we note that conformal transformations \mathcal{C}_1 and \mathcal{C}_2 exist which map $(1)\bar{R}_m$ and $(2)\bar{R}_m$ respectively on R_m . For these transformations we also have $(1)V_n \rightarrow (1)\bar{V}_n$ and $(2)V_n \rightarrow (2)\bar{V}_n$ respectively, where $(1)\bar{V}_n$

⁽⁶¹⁾ The details of the present discussion appear in [8, pp. 472-473].

⁽⁶²⁾ Various modifications of this theorem appear in the remarks at the conclusion of the proof.

and $(2)\bar{V}_n$ are subspaces in R_m . Since the conformal fundamental forms exist for $(1)V_n$ and $(2)V_n$, in accordance with Theorem 19.1, they also exist for $(1)\bar{V}_n$ and $(2)\bar{V}_n$ and corresponding forms of $(1)\bar{V}_n$ and $(2)\bar{V}_n$ are equal. Furthermore, as a consequence of the remarks in the summary of chapter V, the fundamental equations of $(1)\bar{V}_n$ and $(2)\bar{V}_n$ are valid.

Let \mathcal{P}_1 and \mathcal{P}_2 be points which belong to $(1)\bar{V}_n$ and $(2)\bar{V}_n$ respectively which have the same parameters x^{i_0} and such that the corresponding conformal fundamental forms, evaluated at \mathcal{P}_1 and \mathcal{P}_2 , are equal. Let Ψ_1 and Ψ_2 be the group parameter sets associated with $(1)\bar{V}_n$ and $(2)\bar{V}_n$ respectively at \mathcal{P}_1 and \mathcal{P}_2 . As a consequence of Theorem 30.2, a conformal transformation \mathcal{C} of R_m into itself exists which transforms Ψ_1 into Ψ_2 . This same transformation transforms $(1)\bar{V}_n$ into some subspace V'_n passing through \mathcal{P}_2 for $x^i = x^{i_0}$ and having the associated parameter set Ψ_2 at \mathcal{P}_2 . For reasons like those given in connection with $(1)\bar{V}_n$ and $(2)\bar{V}_n$, the fundamental forms for V'_n exist and are equal to the corresponding forms of $(2)\bar{V}_n$. Also, the fundamental equations of V'_n are valid. It follows from Theorem 29.3 that V'_n coincides with $(2)\bar{V}_n$ in a sufficiently small neighborhood of \mathcal{P}_2 . Hence the transformation $\mathcal{C}^{-1} \mathcal{C} \mathcal{C}_1$ transforms $(1)\bar{R}_m$ into $(2)\bar{R}_m$ mapping sufficiently small regions of $(1)V_n$ and $(2)V_n$ on each other. This proves Theorem 31.1.

Remark 1. Suppose that the enveloping space is an R_m or an S_m and we limit the conformal transformations to mappings between these spaces of constant curvature only. For reasons like those stated in Remark 3 of §29, the hypothesis of Theorem 31.1 may be weakened so that R_m or S_m is of class C^3 instead of class C^4 and the remainder of the theorem will hold as stated.

Remark 2. An analogous equivalence theorem exists in which the conformal measure tensors and deviation tensor occupy roles similar to those of the coefficients of the conformal fundamental forms in Theorem 31.1. The proof of this theorem is based upon Theorem 29.1 instead of Theorem 29.3.

Remark 3. If $m = n + 1$, it follows from (20.11) that the condition $(1)B_{(i_2)|(l_2)} = (2)B_{(i_2)|(l_2)}$ in the conformal equivalence theorem may be replaced by $(1)B_{ij} = \pm (2)B_{ij}$.

As a result of the existence and equivalence theorems, it is clear that equations which assign arbitrary values to the coefficients of the conformal fundamental forms of V_n (subject, of course, to (19.12) and the fundamental equations) may be regarded as conformal intrinsic equations of V_n in \bar{R}_m . These equations determine the V_n up to a conformal transformation of the space. A detailed conformal differential geometry of subspaces based upon these fundamental forms may be developed.

32. Conformal differential forms. A conformal differential form

$$(32.1) \quad T_{(i_p)} dx^{i_1} dx^{i_2} \cdots dx^{i_p}$$

of a subspace V_n in V_m whose equations are $y^\alpha = y^\alpha(x^i)$ is a differential form whose coefficients $T_{(i_p)}$ are functions of the variables

$$(32.2) \quad y^\alpha(x^i), \partial y^\alpha/\partial x^i, \partial^2 y^\alpha/\partial x^i \partial x^j, \dots, a_{\alpha\beta}[y^\gamma(x^i)], \\ \partial a_{\alpha\beta}/\partial y^\gamma, \partial^2 a_{\alpha\beta}/\partial y^\gamma \partial y^\delta, \dots$$

defined along V_n and which, at any point \mathcal{P} of V_n , has the same value for any admissible change of coordinates y^α or of the parameters x^i and whose value also remains unchanged if V_m is mapped conformally on \bar{V}_m . This last condition, which gives (32.1) its conformal character, is equivalent to the assumption that (32.1) is invariant if the $a_{\alpha\beta}$ and their derivatives are replaced respectively by $e^{2\sigma} a_{\alpha\beta}$ and their derivatives while the other variables in (32.2) are unchanged.

The simplest conformal differential forms of V_n are its conformal fundamental forms. The most important problem concerning conformal forms is the discovery of all such differential forms. It is seen from the definition that this question is equivalent to finding all conformal tensors $T_{(i_w)}$ which depend upon the variables (32.2). In the sequel, we solve this problem when V_n is a subspace of any conformally euclidean space \bar{R}_m . We prove the following theorem of which the converse statement has already been demonstrated.

THEOREM 32.1. *The most general conformal differential form of a subspace V_n ($n > 1$) in an \bar{R}_m is a differential form whose coefficients are tensor functions of the conformal fundamental tensors and conformal Riemann tensor of V_n and of their conformal covariant derivatives. Conversely, every such differential form is a conformal differential form.*

The proof follows. We consider a conformal differential form (32.1) defined at any point of an n -dimensional subspace in an \bar{R}_m . The coefficients $T_{(i_w)}$ are conformal tensors which depend upon the variables (32.2). By means of a conformal mapping of \bar{R}_m on R_m , (32.1) becomes a conformal differential form defined at any point \mathcal{P} of a subspace V_n in R_m . We therefore first discuss conformal forms of V_n in R_m .

By virtue of (29.4), the successive partial derivatives of y^α with respect to the x^i may be written as functions of $U^{(h_w)}_{(i_w+1)}$, $U^{(h_w-1)}_{(i_w+1)}$, G_{ij} , E_{ij} , K_{ij} , Γ^h_{ij} and their derivatives with respect to x^k and of $a_{\alpha\beta}$ and their derivatives with respect to y^γ and of y^α , $G^\alpha_{(i_w)}$, ψ , ψ_i , μ^α . (Here w has the range $1, 2, \dots, M$.) According to Theorem 28.2, $U^{(h_w)}_{(i_w+1)}$, $U^{(h_w-1)}_{(i_w+1)}$ may be replaced by a combination of the conformal fundamental tensors (except for unessential additive null tensors).

Hence $T_{(i_w)}$ is a tensor function which depends upon the variables

$$(32.3) \quad y^\alpha, G^\alpha_{(i_w)}, \psi, \psi_i, \mu^\alpha, a_{\alpha\beta}, \frac{\partial a_{\alpha\beta}}{\partial y^\gamma}, \frac{\partial^2 a_{\alpha\beta}}{\partial y^\gamma \partial y^\delta}, \dots, \dots, \\ G_{ij}, \Gamma^h_{ij}, \frac{\partial}{\partial x^k} \Gamma^h_{ij}, \dots, G_{(i_2)(j_2)}, G_{(i_2)(j_2):k}, G_{(i_2)(j_2):kl}, \dots, \\ G_{(i_M)(j_M)}, G_{(i_M)(j_M):k}, G_{(i_M)(j_M):kl}, \dots, E_{ij}, E_{ij:k}, E_{ij:kl}, \dots$$

Of these variables, only the conformal fundamental tensors and their conformal derivatives, Γ^h_{ij} and its partial derivatives and the $G^\alpha_{(i_w)}$, have a conformal character. When the enveloping R_m is subjected to a conformal transformation, $\bar{y}^\alpha = y^\alpha$, $\bar{x}^i = x^i$, $\bar{T}_{(i_w)}$ is the same function with the variables (32.3) replaced by the variables \bar{y}^α , $G^\alpha_{(i_w)}$, $\bar{\psi}$, $\bar{\psi}_i$, and so on, which correspond to (32.3) under the conformal mapping and $\bar{T}_{(i_w)} = T_{(i_w)}$ at corresponding points.

Of the variables (32.3), it is very plausible that the effective presence (other than in conformal derivatives) of Γ^h_{ij} and its successive derivatives in $T_{(i_w)}$ must be limited to combinations which are functions of the conformal Riemann curvature tensor K^h_{ijk} of V_n and its successive conformal derivatives. To prove this conjecture, we choose a system of conformal normal parameters $\{x^i\}$ whose center is an arbitrary point \mathcal{P} of V_n . Then, in a neighborhood about⁽⁶³⁾ \mathcal{P} ,

$$(32.4) \quad \Gamma^h_{ij} x^i x^j = 0.$$

Differentiation of (32.4) with respect to x^k , followed by multiplication by x^k and simplification by means of (32.4), leads to the equations

$$(32.5) \quad (\partial \Gamma^h_{ij} / \partial x^k) x^i x^j x^k = 0.$$

Analogous equations for the higher derivatives of Γ^h_{ij} may be obtained from (32.5) in a similar way. Successive differentiation of (32.4), (32.5), and so on, and evaluation at \mathcal{P} leads to the following equations which are valid at \mathcal{P} :

$$(32.6) \quad \Gamma^h_{ij} = 0, \quad \sum \partial \Gamma^h_{ij} / \partial x^k = 0, \quad \sum \partial^2 \Gamma^h_{ij} / \partial x^i \partial x^k = 0, \dots$$

In these equations the summation symbol indicates the symmetric sum over all indices except h .

It follows from (14.1) and the first two equations of (32.6) that, at \mathcal{P} ,

$$\partial \Gamma^h_{ij} / \partial x^k = [K^h_{ikj} + K^h_{jki}] / 3.$$

In a similar way, by successive differentiation of (14.1) and use of the equations of (32.6), we may express the values of the higher partial derivatives of Γ^h_{ij} at \mathcal{P} in terms of K^h_{ijk} and its various conformal derivatives. Hence the quantities

$$(32.7) \quad \Gamma^h_{ij}, \partial \Gamma^h_{ij} / \partial x^k, \dots$$

may be replaced by

$$(32.8) \quad 0, [K^h_{ikj} + K^h_{jki}] / 3, \dots$$

at \mathcal{P} when the parameter system $\{x_i\}$ is conformal normal. Now $T_{(i_w)}$ as well as the quantities (32.8) and all the variables of (32.3) except (32.7) are tensors. Therefore if the variables (32.7) in $T_{(i_w)}$ are replaced by (32.8) at \mathcal{P} ,

⁽⁶³⁾ For a proof of this characteristic property of normal coordinates, see [4, p. 54].

$T_{(i_0)}$ becomes a tensor function of tensor variables and hence is valid under all parameter transformations. Since \mathcal{P} is any point of V_n , this remark shows that the variables (32.7) may be replaced by combinations of $K^h{}_{ijk}$ and its successive conformal derivatives⁽⁶⁴⁾.

We now show that $y^\alpha, G^\alpha{}_{(i_0)}, \psi, \psi_i, \mu^\alpha, a_{\alpha\beta}, \partial a_{\alpha\beta}/\partial y^\gamma, \partial^2 a_{\alpha\beta}/\partial y^\delta \partial y^\gamma, \dots$ cannot be present in $T_{(i_0)}$ as effective independent variables. In R_m , the coordinates y^α may be chosen so that they belong to a rectangular cartesian coordinate system \mathcal{W} such that $a_{\alpha\beta} = \delta_{\alpha\beta}, \partial a_{\alpha\beta}/\partial y^\gamma = 0, \partial^2 a_{\alpha\beta}/\partial y^\delta \partial y^\gamma = 0, \dots$ throughout a region of R_m containing any point \mathcal{P} of V_n and at $\mathcal{P}, y^\alpha = 0, G^\alpha{}_{(i_0)} = G^\alpha{}_{(i_0)0}$. Here the $G^\alpha{}_{(i_0)0}$ are any fixed set of numbers which satisfy the B -conditions (29.7). If R_m is subjected to a conformal transformation⁽⁶⁵⁾

$$y^\alpha = y^\alpha(\bar{y}^1, \bar{y}^2, \dots, \bar{y}^m), \quad \bar{y}^\alpha = \bar{y}^\alpha(y^1, y^2, \dots, y^m)$$

belonging to \mathcal{G} , V_n is mapped on another subspace \bar{V}_n in R_m and \mathcal{P} corresponds to $\bar{\mathcal{P}}$. In this transformation, the \bar{y}^α have been chosen so that they belong to a rectangular cartesian coordinate system $\bar{\mathcal{W}}$ such that $\bar{a}_{\alpha\beta} = \delta_{\alpha\beta}, \partial \bar{a}_{\alpha\beta}/\partial \bar{y}^\gamma = 0, \partial^2 \bar{a}_{\alpha\beta}/\partial \bar{y}^\delta \partial \bar{y}^\gamma = 0, \dots$ throughout a region of R_m containing $\bar{\mathcal{P}}$ and at $\bar{\mathcal{P}}, \bar{y}^\alpha = 0, \bar{G}^\alpha{}_{(i_0)} = G^\alpha{}_{(i_0)0}$. It is clear that in the coordinate systems \mathcal{W} and $\bar{\mathcal{W}}$, the values of the $a_{\alpha\beta}$ and their derivatives as well as of $G^\alpha{}_{(i_0)}$ at \mathcal{P} remain unchanged by conformal transformations of \mathcal{G} . Of course, the conformal Riemann tensor and the conformal fundamental tensors of V_n and their conformal derivatives also remain constant. Hence, in these coordinate systems, the only possible variables of (32.1) are ψ, ψ_i, μ^α .

As a result of Theorem 30.2, a conformal transformation of G exists which leaves the values at \mathcal{P} of $y^\alpha, G^\alpha{}_{(i_0)}$ unaltered and which transforms the set ψ, ψ_i, μ^α at \mathcal{P} into any other set $\bar{\psi}, \bar{\psi}_i, \bar{\mu}^\alpha$ [subject to the last equations of (29.7)]. Hence ψ, ψ_i, μ^α behave like independent variables with respect to conformal transformations of \mathcal{G} . It follows that if any of ψ, ψ_i, μ^α are effective variables, (32.1) cannot remain invariant at \mathcal{P} . This contradiction shows that (32.1) is independent of ψ, ψ_i, μ^α at each point of V_n . Hence in the coordinate systems $\mathcal{W}, \bar{\mathcal{W}}, T_{(i_0)}$ is a tensor function of the conformal Riemann tensor and conformal fundamental tensors of V_n as well as their various conformal derivatives. Hence $T_{(i_0)}$ may be written as

$$(32.9) \quad T_{(i_0)} = T[G_{ij}, K^h{}_{ijk}, K^h{}_{ijk:l}, \dots, E_{ij}, E_{ij:k}, E_{ij:kl}, \dots, G_{(i_2)(i_2)}, G_{(i_2)(i_2):k}, G_{(i_2)(i_2):kl}, \dots, \dots, G_{(i_M)(i_M)}, G_{(i_M)(i_M):k}, G_{(i_M)(i_M):kl}, \dots]$$

in the coordinate systems $\mathcal{W}, \bar{\mathcal{W}}$.

Since (32.9) is a tensor equation, it follows that (32.9) is valid for any allowable coordinate system in R_m . This observation proves the theorem for

⁽⁶⁴⁾ This result also follows from the replacement theorem of Thomas [15, p. 109].

⁽⁶⁵⁾ In this proof, we no longer assume that points with the same coordinates correspond as was done previously.

subspaces in R_m and conformal transformations which belong to \mathcal{G} . But all the tensors of both members of (32.9) are conformal tensors and are unchanged by any conformal mapping of R_m on an \bar{R}_m . By means of this map, V_n in R_m becomes an n -dimensional subspace \bar{V}_n in \bar{R}_m . Also all n -dimensional subspaces of \bar{R}_m may be obtained as conformal images of V_n 's in R_m . Consequently (32.9) is valid for any subspace of \bar{R}_m . This remark concludes the proof of Theorem 32.1.

It is clear that a similar proof in ordinary Riemannian geometry would establish the known theorem that every metric differential form of a subspace V_n ($n > 1$) in an R_m or S_m is a differential form whose coefficients are tensor functions of the (metric) fundamental tensors and Riemann curvature tensor of V_n and of their covariant derivatives, and conversely. Finally, we note that Theorem 32.1 is probably false in any enveloping Riemann space V_m which is not conformally euclidean. A proof of this statement would probably be analogous to the one for curves which has already been given by the author [8, pp. 477-478] and would be based upon the nonzero conformal tensor $\rho_{\alpha\beta\gamma}$ if $m = 3$ or $C^{\alpha}_{\beta\gamma\delta}$ if $m > 3$.

VII. EXCEPTIONAL SUBSPACES

33. Conformal null subspaces. The results of the preceding chapters are meaningless in the case of a subspace V_n , contained in a general Riemann space V_m , whose relative conformal curvature Λ vanishes identically. In this case the conformal measure tensors G_{ij} , $A_{\alpha\beta}$ are zero tensors, and conversely. This means that the conformal length of any curve on V_n or of any surface or space vector defined at any point of V_n is zero. For this reason, we call any V_n ($n > 1$) with $\Lambda \equiv 0$ which is a subspace of V_m a *conformal null subspace*⁽⁶⁶⁾. We impose the condition $n > 1$ since, according to Theorem 6.1, $\Lambda \equiv 0$ if $n = 1$. The remaining case, $n = 1$ (curve), is considered in the next section. We now derive a number of simple properties of these subspaces. The first of these is the theorem:

THEOREM 33.1. *The conformal image of a conformal null subspace is a conformal null subspace.*

This is an immediate consequence of the definition and (6.13). Also, according to Theorem 6.1, it follows that V_n is a *conformal null subspace of V_m if and only if all its points are umbilical points*. As a consequence of this statement, we note that (1) A V_m admits conformal null subspaces at each point and for every initial set of values for G^{α}_i , μ^{α} if and only if⁽⁶⁷⁾ V_m is an⁽⁶⁸⁾ \bar{R}_m .

⁽⁶⁶⁾ In the following discussion, we do not consider the non-real null subspaces which are solutions of $ds'^2 = a_{\alpha\beta} dy^{\alpha} dy^{\beta} = 0$. A prerequisite for the investigation of these subspaces is the extension (if possible) of the region of definition of the metric tensor $a_{\alpha\beta}$ from the m -dimensional real number space to the $2m$ -dimensional complex number space.

⁽⁶⁷⁾ A proof of this statement may be based upon the discussion in [3, pp. 144-145].

⁽⁶⁸⁾ On the other hand, conformal null curves exist at each point and for every initial set of values for G^{α}_i , μ^{α} in any enveloping space V_m . For a proof of this statement, see [8, §10].

(2) In contrast to the case of Riemannian geometry, real null subspaces may exist in V_m even when its Riemannian metric is positive definite. Now, from Theorem 9.3, every V_n is conformally equivalent to a minimal subspace. Hence if V_n is a conformal null subspace, it may be transformed into an umbilical subspace of zero mean curvature. The converse of this statement is immediate. These remarks prove the following theorem.

THEOREM 33.2. *A subspace V_n ($n > 1$) in a V_m is a conformal null subspace if and only if a Riemann space \bar{V}_m and a conformal transformation of V_m on \bar{V}_m exist such that V_n is mapped by this transformation on a totally geodesic subspace of \bar{V}_m .*

It is easy to see that a V_n in an R_m is umbilical if and only if V_n is an n -dimensional plane or sphere. It is also clear that a conformal map (belonging to \mathcal{G}) of R_m on itself exists so that any n -sphere transforms into an n -plane. Furthermore, if an \bar{R}_m is mapped conformally on R_m , any conformal null subspace of \bar{R}_m is transformed into a conformal null subspace of R_m and hence is conformally equivalent to an n -plane in R_m . We state these results in the following theorem.

THEOREM 33.3. *Every conformal null subspace V_n of R_m is an n -plane or an n -sphere, and conversely. The necessary and sufficient condition that a subspace V_n ($n > 1$) in an \bar{R}_m be a conformal null subspace is that V_n be the conformal image of an n -plane in R_m . All n -dimensional null subspaces in \bar{R}_m 's are conformally equivalent.*

34. Conformal curve theory. The conformal theory developed in this paper does not apply to one-dimensional subspaces of V_m (curves) since Λ is identically zero in this case. The conformal geometry of a curve was obtained in a previous paper by the author [8], using "conformetric" vectors. As was indicated in that paper, the use of conformetric vectors is not essential and the entire theory may be developed in terms of conformal geometric objects. In this section, we show how this may be done, utilizing the methods of the present paper. The method which appears below is contained, in essence, in our previous paper⁽⁶⁹⁾ [8].

We consider a curve V_1 of class C^r with $r \geq 3$ in a Riemann space V_m . The equations (4.3) of V_1 may be written as

$$y^\alpha = y^\alpha(x^1)$$

where, according to our assumptions of §4, $dy^\alpha/dx^1 \neq 0$. The metric tensor of V_1 is given by the formula

$$g_{11} = a_{\alpha\beta} g^\alpha_1 g^\beta_1$$

⁽⁶⁹⁾ For purposes of comparison, we note that y^α , $a_{\alpha\beta}$, $(v)V^\alpha$, μ^α , $\sigma_{,\alpha}$, $\sigma_{\alpha\beta}$, ρ , $\rho_{\alpha\beta}$, Ω , v , ζ^α , $(v)k$, $(v)Z^\alpha$, $\Gamma^\alpha_{\beta\gamma}$, $(v)J$ of this section appear in [8] as x^i , g_{ij} , $(\alpha)V^i$, μ^i , $\sigma_{,i}$, σ_{ij} , R , R_{ij} , J , K , η^i , k_α , $(\alpha)\lambda^i$, $\Gamma^i_{j,k}$, J_α respectively.

where $g^\alpha_1 = dy^\alpha/dx^1$. It is convenient to introduce the parameter s by means of the allowable parameter transformation

$$s = \int (g_{11})^{1/2} \cdot dx^1.$$

The parameter s is an *arc length parameter* determined up to an additive constant and a choice of sign. For this parameter system, we find that⁽⁷⁰⁾

$$(34.1) \quad g_{11} = 1, \quad \left\{ \begin{matrix} 1 \\ 11 \end{matrix} \right\} = 0,$$

so that g^α_1 is a unit vector. In this case, we write g^α_1 as ${}_{(1)}\nu^\alpha$. It is the *unit tangent vector* of V_1 .

According to the definition of the mean curvature normal given by (5.9),

$$(34.2) \quad \nu^{\alpha, s} = \mu^\alpha$$

where the subscript s indicates that the parameter x^1 is s . The vector μ^α is usually called the *principal normal* of V_1 . We may write μ^α as

$$(34.3) \quad \mu^\alpha = {}_{(1)}k {}_{(2)}\nu^\alpha$$

where ${}_{(1)}k$ is the *first curvature* of V_1 and ${}_{(2)}\nu^\alpha$ is the *first unit normal* of V_1 . Differentiation of ${}_{(2)}\nu^\alpha$ and use of the fact that ${}_{(1)}\nu^\alpha$, ${}_{(2)}\nu^\alpha$ are orthogonal unit vectors leads to the equations

$$(34.4) \quad {}_{(2)}\nu^{\alpha, s} = - {}_{(1)}k {}_{(1)}\nu^\alpha + {}_{(2)}k {}_{(3)}\nu^\alpha$$

where ${}_{(2)}k$ is the *second curvature* of V_1 and ${}_{(3)}\nu^\alpha$ is the *second unit normal* of V_1 . Equations (34.2) and (34.4) are the first two sets of the familiar *Frenet equations* of V_1 . The general equations

$$(34.5) \quad {}_{(v)}\nu^{\alpha, s} = - {}_{(v-1)}k {}_{(v-1)}\nu^\alpha + {}_{(v)}k {}_{(v+1)}\nu^\alpha, \quad {}_{(0)}k = {}_{(m)}k = 0, \quad v = 1, 2, \dots, m,$$

may easily be derived by mathematical induction if the successive unit normals are of class C^1 .

The relationship between the principal normals of V_1 in V_m and of its conformal image \bar{V}_1 in \bar{V}_m is given by (6.7). If (6.7) is differentiated covariantly and use is made of

$$(34.6) \quad {}_{(1)}\bar{\nu}^\alpha = e^{-\sigma} {}_{(1)}\nu^\alpha$$

and of (2.4), (2.6), (6.3), (34.2), (34.3) and (34.4), we find that

$$(34.7) \quad \begin{aligned} & (d_{{}_{(1)}\bar{k}}/d\bar{s}) {}_{(2)}\bar{\nu}^\alpha + {}_{(1)}\bar{k} {}_{(2)}\bar{k} {}_{(3)}\bar{\nu}^\alpha \\ & = e^{-3\sigma} [(d_{{}_{(1)}k}/ds) {}_{(2)}\nu^\alpha + {}_{(1)}k {}_{(2)}k {}_{(3)}\nu^\alpha - \sigma_{B\gamma} {}_{(1)}\nu^\gamma h^{\alpha\beta}] \end{aligned}$$

⁽⁷⁰⁾ The Christoffel symbols $\left\{ \begin{matrix} 1 \\ 11 \end{matrix} \right\}$, Γ^1_{11} which occur in this section are formed with respect to g_{ij} , G_{ij} respectively.

where, according to (4.10) and (4.12),

$$h^{\alpha\beta} = a^{\alpha\beta} - (1)\nu^\alpha (1)\nu^\beta.$$

Now, if $m > 2$, equations (11.3) may be solved for $\sigma_{\beta\gamma}$. If this result is substituted in (34.7) and use is made of (2.6) and (34.6), we obtain

$$(34.8) \quad \bar{\Omega}^2 \bar{\zeta}^\alpha = e^{-3\sigma} \Omega^2 \zeta^\alpha$$

where

$$(34.9) \quad \Omega^2 \zeta^\alpha = \frac{dk_1}{ds} (2)\nu^\alpha + k_1 k_2 (3)\nu^\alpha + \frac{1}{(m-2)} \rho_{\beta\gamma} (1)\nu^\gamma h^{\alpha\beta}$$

and $\bar{\Omega}^2 \bar{\zeta}^\alpha$ is defined by analogous equations and $a_{\alpha\beta} \zeta^\alpha \zeta^\beta = 1, \bar{a}_{\alpha\beta} \bar{\zeta}^\alpha \bar{\zeta}^\beta = 1$. It is clear that ζ^α is orthogonal to $(1)\nu^\alpha$. We assume that the members of (34.8) are not zero. Then the quantity Ω which is the unique positive root of Ω^2 is a relative conformal scalar having the transformation law

$$(34.10) \quad \bar{\Omega} = e^{-\sigma} \Omega.$$

In the conformal theory of a curve, the quantity Ω occupies the role that is played by Λ in the conformal theory of subspaces whose dimensionality exceeds 1. We therefore call Ω the *relative conformal curvature* of V_1 . The scalar Ω may be used to develop the curve theory in a manner analogous to the corresponding use of Λ in the theory of V_n with $n > 1$. The analogy applies to all methods and results which only depend upon the transformation law (6.13) of Λ and make no use of the actual definition of Λ . Because of the presence of the term $\rho_{\beta\gamma} (1)\nu^\gamma h^{\alpha\beta} / (m-2)$ in the definition of Ω the conformal geometry of a curve is simplified considerably if the enveloping V_m is an Einstein space. On the other hand, Einstein spaces do not occupy any special or preferred position in the conformal theory of a subspace V_n whose dimensionality n exceeds 1.

It follows from (2.6), (6.2) and (34.10) that the tensors

$$(34.11) \quad G_{11} = \Omega^2 g_{11}, \quad A_{\alpha\beta} = \Omega^2 a_{\alpha\beta}$$

are positive definite tensors which remain unchanged by conformal transformations of V_m . We call them the *conformal measure tensors* of V_1 and V_m respectively and measure *conformal length* by means of these tensors. The *conformal coefficients of connection* analogous to (8.5) and (8.11) are

$$(34.12) \quad \Gamma_{11} = \left\{ \begin{matrix} 1 \\ 11 \end{matrix} \right\} + [\log \Omega]_{,1} = [\log (g_{11})^{1/2} \cdot \Omega]_{,1},$$

$$\Gamma^{\alpha}_{\beta\gamma} = \left\{ \begin{matrix} \alpha \\ \beta\gamma \end{matrix} \right\} + a^{\alpha\beta} \left[\mu_\gamma + (1)\nu_\gamma \frac{d \log \Omega}{ds} \right]$$

$$+ a^{\alpha\gamma} \left[\mu_\beta + (1)\nu_\beta \frac{d \log \Omega}{ds} \right] - a_{\beta\gamma} \left[\mu^\alpha + (1)\nu^\alpha \frac{d \log \Omega}{ds} \right].$$

Conformal differentiation with respect to x^1 is defined by means of these coefficients as in (8.1). The various italicized statements of §8 are also true in the curve theory.

We define S (up to an additive constant and choice of sign) by the equation

$$(34.13) \quad S = \int (G_{11})^{1/2} dx^1 = \int \Omega ds.$$

It is clear that S remains invariant under conformal transformations and is a conformal scalar. We call S a *conformal arc length parameter* of V_1 . If the values of the same arc length parameter are S_1 and S_2 at two points \mathcal{P}_1 and \mathcal{P}_2 of V_1 , we call $|S_1 - S_2|$ the *conformal arc length* of the arc $\mathcal{P}_1\mathcal{P}_2$ (or $\mathcal{P}_2\mathcal{P}_1$) of V_1 . It is clear that the conformal arc length is independent of the choice of conformal arc length parameter and remains unchanged by conformal transformations of V_m . It follows from (34.11) and (34.12) that if $x^1 = S$,

$$(34.14) \quad G_{11} = 1, \quad \Gamma^1_{11} = 0,$$

so that conformal differentiation with respect to S is defined by means of $\Gamma^{\alpha}_{\beta\gamma}$ alone. If we use the symbol $\vartheta/\vartheta S$ to denote conformal differentiation with respect to S ,

$$\begin{aligned} \frac{\vartheta}{\vartheta S} T^{\alpha_1 \cdots \alpha_w \beta_1 \cdots \beta_v} &= \frac{d}{dS} T^{\alpha_1 \cdots \alpha_w \beta_1 \cdots \beta_v} + \sum_{\alpha=1}^w T^{\alpha_1 \cdots \alpha_{\alpha-1} \gamma \alpha_{\alpha+1} \cdots \alpha_w \beta_1 \cdots \beta_v} \Gamma^{\alpha}_{\alpha\gamma} \frac{dy^\delta}{dS} \\ &\quad - \sum_{b=1}^v T^{\alpha_1 \cdots \alpha_w \beta_1 \cdots \beta_{b-1} \gamma \beta_{b+1} \cdots \beta_v} \Gamma^{\gamma}_{\beta\gamma} \frac{dy^\delta}{dS}. \end{aligned}$$

The vector ${}_{(1)}Z^\alpha$ defined by

$${}_{(1)}Z^\alpha = \Omega^{-1} {}_{(1)}\zeta^\alpha$$

is a conformal vector of unit conformal length. We call ${}_{(1)}Z^\alpha$ the *first conformal normal* of V_1 . Suppose that the class of ${}_{(1)}Z^\alpha$ is C^1 and that this is also true of each successive unit conformal vector ${}_{(2)}Z^\alpha, {}_{(3)}Z^\alpha, \dots, {}_{(u)}Z^\alpha$ obtained from ${}_{(1)}Z^\alpha$ by the Frenet process⁽⁷¹⁾ coupled with conformal differentiation. Then one readily proves, using the usual argument by mathematical induction, that there exists a set of scalars ${}_{(1)}J, {}_{(2)}J, \dots, {}_{(u-1)}J$ ($u \leq n - 1$) such that

$$(34.15) \quad \begin{aligned} \frac{\vartheta({}_{(v)}Z^\alpha}{\vartheta S} &= -{}_{(v-1)}J {}_{(v-1)}Z^\alpha + {}_{(v)}J {}_{(v+1)}Z^\alpha, \quad {}_{(0)}J = {}_{(u)}J = 0, \quad v = 1, 2, \dots, u, \\ A_{\alpha\beta}({}_{(v)}Z^\alpha) {}_{(w)}Z^\beta &= \delta^v_w, \quad v, w = 1, 2, \dots, u, \\ A_{\alpha\beta}({}_{(v)}Z^\alpha) {}_{(1)}\nu^\beta &= 0. \end{aligned}$$

(71) The application of the Frenet process to the unit conformal tangent vector (in a manner analogous to that used in Riemannian geometry as well as in the conformal theory of a sub-space V_n with $n > 2$) is unfruitful. For it is easy to verify that $\vartheta(\Omega^{-1}({}_{(1)}\nu^\alpha))/\vartheta S = 0$.

The conformal unit vector ${}_{(v)}Z^\alpha$ is called the *vth conformal normal* of V_1 and the conformal scalar ${}_{(v)}J$ is called the *vth conformal curvature* of V_1 . Equations (34.15) are called the *conformal Frenet equations* of V_1 . If $V_m \rightleftharpoons \bar{V}_m$, $V_1 \rightleftharpoons \bar{V}_1$ by a conformal transformation, all the quantities in (34.15) remain unchanged and (34.15) are also valid for \bar{V}_1 in \bar{V}_m .

The conformal unit vectors

$$(34.16) \quad \Omega^{-1} {}_{(1)}\nu^\alpha, {}_{(1)}Z^\alpha, {}_{(2)}Z^\alpha, \dots, {}_{(u)}Z^\alpha$$

have roles analogous to the basis beins $G^\alpha_{(i_v)}$ of the general subspace theory. The conformal vector $\Omega^{-1} {}_{(1)}\nu^\alpha$ spans the tangent vector space of V_1 and each normal vector ${}_{(v)}Z^\alpha$ in (34.16) spans a one-dimensional vector space called the *vth conformal normal vector space* of V_1 . The successive conformal curvatures of V_1 take the place of the various conformal normal measure tensors $B_{(i_2)|(h_2)}$, $B_{(i_3)|(h_3)}$, \dots , $B_{(i_M)|(h_M)}$ of chapter IV.

Corresponding to the deviation tensor E_{ij} , we may construct the conformal tensor J_{ij} , defined analogously to (13.14), by the equation

$$(34.17) \quad \begin{aligned} J_{ij} = & (-\log \Omega)_{:ij} - (-\log \Omega)_{:i}(-\log \Omega)_{:j} + \mu_\alpha G^\alpha{}_{ij} \\ & - \frac{1}{(m-2)} \rho_{\alpha\beta} G^\alpha{}_{:i} G^\beta{}_{:j} + \frac{1}{2} \left[\Omega^{-2} \mu^2 + G^{hk} (-\log \Omega)_{:k} (-\log \Omega)_{:k} \right. \\ & \left. + \frac{\Omega^{-2} \rho}{(m-1)(m-2)} \right] G_{ij}. \end{aligned}$$

To obtain this equation, we simply replace Λ by Ω and E_{ij} by J_{ij} in (13.14). Since $i=j=1$, the tensor J_{ij} has only one component so that we may consider the equivalent conformal invariant $J_{ij}G^{ij}$: Since $G^\alpha{}_{ij} \equiv 0$ and $G_{ij}G^{ij} = 1$ for V_1 , we obtain from (34.17),

$$(34.18) \quad \begin{aligned} J_{ij}G^{ij} = & \Omega^{-2} \left[-\Omega \Delta_2 \Omega + \Delta_1 \Omega / 2 + \mu^2 / 2 \right. \\ & \left. + \frac{\rho}{2(m-1)(m-2)} - \frac{1}{(m-2)} \rho_{\alpha\beta} g^{\alpha\beta} \right] \end{aligned}$$

where $\Delta_2 \Omega = G^{ij} \Omega_{:ij}$, $\Delta_1 \Omega = G^{ij} \Omega_{:i} \Omega_{:j}$. If we choose $x^1 = S$ it is clear that $\Delta_2 \Omega = d^2 \Omega / dS^2$, $\Delta_1 \Omega = (d \Omega / dS)^2$. Also $g^{\alpha\beta} = {}_{(1)}\nu^\alpha {}_{(1)}\nu^\beta$. If these substitutions are made in (34.18), we find that

$$(34.19) \quad -2J_{ij}G^{ij} = {}_{(m-1)}J$$

where ${}_{(m-1)}J$ is the $(m-1)$ th conformal curvature of V_1 defined in our previous paper on curve theory as⁽⁷²⁾

$$(34.20) \quad {}_{(m-1)}J = \left[2\Omega \frac{d^2 \Omega}{dS^2} - \left(\frac{d\Omega}{dS} \right)^2 - (k^2_1 + v) \right] / \Omega^2$$

⁽⁷²⁾ Equation (34.20) corrects a misprint in our paper on curve theory [8, equation (5.10)].

where v is defined by the equation

$$(34.21) \quad v = (1/(m-1)(m-2))[\rho - 2(m-1)\rho_{\alpha\beta}{}^{(1)}v^\alpha{}^{(1)}v^\beta].$$

It follows from (34.19) and the invariance of $J_{ij}G^{ij}$ that ${}_{(m-1)}J$ is a conformal invariant of V_1 . $J_{ij}G^{ij}$ plays a role in the conformal theory of a curve exactly analogous to that of E_{ij} in the conformal geometry of V_n with $n > 1$.

The conformal invariants S , ${}_{(1)}J$, ${}_{(2)}J$, \dots , ${}_{(u-1)}J$, ${}_{(m-1)}J$ and the process of conformal differentiation constitute the foundation upon which the conformal geometry of a curve rests. While many of the results of §§10–17 and of chapter V of this paper are vacuous or trivial in the curve theory, the remaining portions of the paper are similar to the corresponding results obtained by similar proofs in the conformal geometry of a curve. For example, the analogue of Theorem 19.1 is: *If the conformal curvatures ${}_{(1)}J$, ${}_{(2)}J$, \dots , ${}_{(u-1)}J$, ${}_{(m-1)}J$ exist for a curve V_1 of class C^3 in a V_m ($m > 2$), then the conformal curvatures also exist for the conformal image curve \bar{V}_1 in \bar{V}_m . It is possible to choose a conformal arc length parameter S so that corresponding points of V_1 and \bar{V}_1 have the same value of S and the corresponding conformal curvatures are the same functions of S for V_1 and \bar{V}_1 .*

The existence theorem is true in a stronger form than obtains in the general subspace theory. For, if $n = 1$, the system of partial differential equations (29.4) is replaced by a system of ordinary differential equations. The continuity of the functions ${}_{(1)}J(S)$, ${}_{(2)}J(S)$, \dots , ${}_{(u-1)}J(S)$, ${}_{(m-1)}J(S)$ is then sufficient to insure the existence of a curve V_1 in any V_m which has these functions as its conformal curvatures and one of whose conformal arc length parameters is S . This curve is uniquely determined by a set of initial conditions which may be given explicitly. If V_m is an \bar{R}_m , analogues of the fundamental conformal equivalence theorem and the theorem on conformal differential invariants (Theorem 32.1) exist in the curve theory. Finally, we note that the assumption $m > 2$ may be waived for the curve theory if we restrict ourselves to Riemann spaces V_m and to special conformal transformations of V_m which have the property that any geodesic circle of V_m maps upon a geodesic circle⁽⁷³⁾ of \bar{V}_m . These transformations are generalizations of the inversive transformations of the plane R_2 . The reader is referred to our paper on the conformal theory of curves [8] for the detailed proofs of the various matters considered in this section as well as other subjects in the conformal geometry of a curve.

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(73) The conformal mapping function σ for a transformation of this kind is a solution of the partial differential equations $\sigma_{\alpha\beta} = f \cdot a_{\alpha\beta}$ where f is a point function. Some geometric properties of these transformations have been studied in [8, §§13–14] and [6].

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