

A GENERALIZATION OF THE RIESZ THEORY OF COMPLETELY CONTINUOUS TRANSFORMATIONS⁽¹⁾

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The classical theory, due to F. Riesz, of completely continuous transformations deals with a family $T_c = I - cK$ of linear continuous transformations of a Banach space \mathfrak{X} into itself, where I is the identity and K is completely continuous. The transformation T_c is then one-to-one, except for the "proper" values of c . In this paper we consider cases where the one-to-oneness no longer holds. The identity transformation I is replaced by a transformation E which maps \mathfrak{X} onto the whole of another Banach space \mathfrak{Y} , but *not* one-to-one. Then when K is completely continuous, the transformation $T_c = E - cK$ maps \mathfrak{X} onto \mathfrak{Y} except for a countable set of proper values c_i which have no finite accumulation point. When $\mathfrak{B}_1 = T_c \mathfrak{X} \neq \mathfrak{Y}$, c is said to be a *proper value* for K . We can no longer iterate the transformation T_c , but we can apply T_c to $E^{-1}T_c \mathfrak{X}$ and obtain a linear closed space $\mathfrak{B}_2 \subset \mathfrak{B}_1$. After a finite number of repetitions of this process, we find a space $\mathfrak{B}_\nu = \mathfrak{B}_{\nu+1}$. Then T_c transforms $E^{-1}\mathfrak{B}_\nu$ onto \mathfrak{B}_ν , which takes the place of the invariant subspace of the Riesz theory.

In the one-to-one case, there is associated with the transformation $I - cK$ a resolvent R_c , which has a pole of order ν at a proper value c_0 , and the Laurent expansion of R_c about c_0 leads to a decomposition of K into two mutually orthogonal parts. In the many-to-one case, the adjoint transformation T_c^* is one-to-one except when c is a proper value, but the range of T_c^* varies with c , so that it is not possible to define the order of a pole of the resolvent in the usual way. However a substitute definition has been found, as well as a decomposition $K = G + H$, where G has only one proper value c_0 , and H has only the remaining proper values of K , and H is semi-orthogonal to G in a suitable sense.

1. Notations and definitions. We shall let \mathfrak{X} and \mathfrak{Y} denote Banach spaces of infinitely many dimensions, with complex scalars. The adjoint spaces of \mathfrak{X} and \mathfrak{Y} will be denoted by \mathfrak{X}^* and \mathfrak{Y}^* respectively. Two subsets \mathfrak{X}_0 of \mathfrak{X} and \mathfrak{X}_0^* of \mathfrak{X}^* are said to be *orthogonal* in case $x^*(x) = 0$ for all x in \mathfrak{X}_0 and x^* in \mathfrak{X}_0^* . The *orthogonal complement* of a subset \mathfrak{X}_0 , denoted by $O\mathfrak{X}_0$, is the maximal set \mathfrak{X}_0^* orthogonal to \mathfrak{X}_0 . It is easily seen that $O\mathfrak{X}_0$ always exists (possibly void) and is a linear closed set. A corresponding statement holds for $O\mathfrak{X}_0^*$.

A linear transformation A mapping \mathfrak{X} into \mathfrak{Y} has an *adjoint* A^* mapping \mathfrak{Y}^* into \mathfrak{X}^* , defined by $x^* = A^*y^*$ where $x^*(x) = y^*Ax$ for each x . We shall

Presented to the Society, May 1, 1954; received by the editors April 5, 1954.

(¹) This work was done under a contract with the Office of Ordnance Research.

deal only with continuous linear transformations A . Such a transformation A is said to be *completely continuous* in case the transform $A(\mathfrak{X}_0)$ of every bounded set \mathfrak{X}_0 is compact (in the sense that every sequence (y_n) chosen from $A(\mathfrak{X}_0)$ has a convergent subsequence).

We shall use the letter E to denote a linear continuous transformation mapping \mathfrak{X} onto the whole space \mathfrak{Y} , and shall use K , G , and H to denote completely continuous linear transformations of \mathfrak{X} into \mathfrak{Y} . We also set $T_c = E - cK$, where c is a complex parameter. When it is convenient to set $c = 1$, we shall write T for T_c .

A *projection* P is a linear continuous transformation of \mathfrak{X} onto a closed linear subset \mathfrak{X}_0 , which equals the identity on \mathfrak{X}_0 , i.e., $P^2 = P$.

For a given linear continuous transformation A of \mathfrak{X} into \mathfrak{Y} we shall set

$$\beta(A, y) = \text{g.l.b. } [\|x\| \mid Ax = y]$$

for each y , and

$$I(A) = \text{l.u.b. } [\beta(A, y) \mid y \in A\mathfrak{X}, \|y\| = 1].$$

When the transformation A is one-to-one, obviously $I(A) = \|A^{-1}\|$. (We are admitting $+\infty$ as a value for $\|A^{-1}\|$.)

We shall use $\mathfrak{N}(A)$ to denote the null space of A , that is

$$\mathfrak{N}(A) = [x \mid Ax = 0].$$

Similarly $\mathfrak{N}(A^*)$ denotes the null space of A^* .

2. Preliminary lemmas.

LEMMA 1. *If \mathfrak{X}_0 is a finite-dimensional linear subspace of \mathfrak{X} , with basis $\{x_1, \dots, x_n\}$, there exist n elements x_i^* of \mathfrak{X}^* such that $x_i^*(x_j) = \delta_{ij}$, and $P(x) = \sum_{i=1}^n x_i^*(x)x_i$ is a projection of \mathfrak{X} onto \mathfrak{X}_0 . A similar result holds for $\mathfrak{X}_0^* \subset \mathfrak{X}^*$, with $Q(x^*) = \sum_{i=1}^n x^*(x_i)x_i^*$.*

The first part follows at once from the Hahn-Banach theorem, and the second part follows from more elementary considerations. Note that if the sets $\{x_1, \dots, x_n\}$ and $\{x_1^*, \dots, x_n^*\}$ are the same in the two cases, then $Q = P^*$.

LEMMA 2. *For each linear closed subspace \mathfrak{X}_0 of \mathfrak{X} , $OO\mathfrak{X}_0 = \mathfrak{X}_0$.*

This follows from the lemma in Banach [1, p. 57]. The corresponding result for subsets \mathfrak{X}_0^* of \mathfrak{X}^* does not hold in general, as Banach shows in [1, p. 115]. However, by an easy proof we have

LEMMA 3. *If \mathfrak{X}_0^* is a finite-dimensional linear subspace of \mathfrak{X}^* , then $OO\mathfrak{X}_0^* = \mathfrak{X}_0^*$.*

LEMMA 4. *If $\{x_1^*, \dots, x_n^*\}$ is a basis for \mathfrak{X}_0^* , $x_i^*(x_j) = \delta_{ij}$, and*

$P(x) = \sum_{i=1}^n x_i^*(x)x_i$, then \mathfrak{X} is the direct sum of $O\mathfrak{X}_0^*$ and the finite-dimensional space $P\mathfrak{X}$.

To prove this, we observe that $x - P(x)$ is always in $O\mathfrak{X}_0^*$, and that if x lies in $O\mathfrak{X}_0^*$, then $Px = 0$.

LEMMA 5. *A linear transformation A of \mathfrak{X} into \mathfrak{Y} is (completely) continuous if and only if its adjoint A^* is (completely) continuous.*

Proof. This follows from Theorems 3 and 4 in Banach [1, p. 100]. To show that A is completely continuous whenever A^* is, we note that A^{**} , when restricted to \mathfrak{X} , reduces to A , so by Theorem 4 of Banach, A transforms bounded sets in \mathfrak{X} into sets in \mathfrak{Y} which are compact in \mathfrak{Y}^{**} . But \mathfrak{Y} is closed in \mathfrak{Y}^{**} .

LEMMA 6. *The range $A\mathfrak{X}$ of a linear continuous transformation A of \mathfrak{X} into \mathfrak{Y} is closed if and only if $I(A) < \infty$.*

Proof. When $A\mathfrak{X}$ is closed it constitutes a Banach space, so the necessity of the condition follows from Banach [1, p. 38]. To see that the condition is sufficient, suppose $y_n = Ax_n$, and $\lim y_n = y$. By choosing a subsequence we may suppose that $\|y_{n+1} - y_n\| < 1/2^n$. Then after x_n has been suitably chosen, x_{n+1} may be modified (still satisfying $y_{n+1} = Ax_{n+1}$) so that $\|x_{n+1} - x_n\| \leq I(A)/2^n$. Hence the modified sequence (x_n) has a limit x , and Ax_n converges to $Ax = y$.

COROLLARY. *If $A\mathfrak{X}$ is closed, and $\lim Ax_n = Ax$, there exists a sequence (x'_n) such that $Ax'_n = Ax_n$ and $\lim x'_n = x$.*

Proof. From the definition of $I(A)$ we may choose x'_n so that $A(x'_n - x) = A(x_n - x)$ and $\|x'_n - x\| \leq (I(A) + 1)\|A(x_n - x)\|$. (Compare Banach [1, p. 40, Theorem 4].)

LEMMA 7. *If A is linear and continuous, $A\mathfrak{X}$ is closed if and only if $A^*\mathfrak{Y}^*$ is closed, and then $A^*\mathfrak{Y}^* = O\mathfrak{N}(A)$, $A\mathfrak{X} = O\mathfrak{N}(A^*)$, where $\mathfrak{N}(A)$ and $\mathfrak{N}(A^*)$ are the null spaces of A and of A^* .*

For the proof, see Banach [1, pp. 149, 150, Theorems 8 and 9].

LEMMA 8. *If A is linear and continuous, then A maps \mathfrak{X} onto the whole of the space \mathfrak{Y} if and only if A^* has a continuous inverse. Likewise A has a continuous inverse if and only if A^* maps \mathfrak{Y}^* onto \mathfrak{X}^* .*

For the proof, see Banach [1, pp. 146-148, Theorems 1-4].

LEMMA 9. *If \mathfrak{X}_1 and \mathfrak{X}_2 are two closed linear subspaces of \mathfrak{X} , \mathfrak{X}_2 being finite-dimensional, then $\mathfrak{X}_1 + \mathfrak{X}_2$ (the linear space spanned by \mathfrak{X}_1 and \mathfrak{X}_2) is also closed.*

This is readily proved by induction on the dimension of \mathfrak{X}_2 .

LEMMA 10. *Suppose \mathfrak{X}_1 and \mathfrak{X}_2 satisfy the conditions of Lemma 9, and also that $\mathfrak{X}_1 + \mathfrak{X}_2 = \mathfrak{X}$. Let E be a linear continuous transformation of \mathfrak{X} onto the whole of \mathfrak{Y} . Then $E\mathfrak{X}_1$ is closed.*

Proof. The space $\mathfrak{X}_3 = E^{-1}E\mathfrak{X}_1$ equals $\mathfrak{X}_1 + \mathfrak{X}_4$ where $\mathfrak{X}_4 \subset \mathfrak{X}_2$, so \mathfrak{X}_3 is closed by Lemma 9. Let E_3 denote the restriction of E to \mathfrak{X}_3 . Then clearly $I(E_3) \leqq I(E)$. By Lemma 6, $I(E) < \infty$, and by the same Lemma 6, $E_3\mathfrak{X}_3 = E\mathfrak{X}_1$ is closed.

3. Proper values of a completely continuous transformation. In this section we develop some properties of the family of transformations $T_c = E - cK$, described in §1. A complex number c is called a *proper value* of K in case the range of T_c is a proper subset of \mathfrak{Y} , or equivalently, in case T_c^* does not have an inverse.

In case $c = 1$ is a proper value, the null space $\mathfrak{N}_1^* = \mathfrak{N}(T^*)$ is not null, and the range $\mathfrak{B}_1 = T\mathfrak{X} \neq \mathfrak{Y}$. We set $\mathfrak{M}_1^* = E^*\mathfrak{N}_1^*$, and define \mathfrak{Z}_1 as the maximal subspace of \mathfrak{X} satisfying $E\mathfrak{Z}_1 = \mathfrak{B}_1$. This is the start of an iterative definition of four sequences of linear spaces $\mathfrak{N}_k^*, \mathfrak{M}_k^*, \mathfrak{B}_k, \mathfrak{Z}_k$, by means of the relations

$$\begin{aligned} T^*\mathfrak{N}_k^* &\subset \mathfrak{M}_{k-1}^* && (\mathfrak{N}_k^* \text{ maximal}), \\ \mathfrak{M}_k^* &= E^*\mathfrak{N}_k^*, \\ \mathfrak{B}_k &= T\mathfrak{Z}_{k-1}, \\ E\mathfrak{Z}_k &= \mathfrak{B}_k && (\mathfrak{Z}_k \text{ maximal}). \end{aligned}$$

It is obvious that

$$\begin{aligned} \mathfrak{N}_k^* &\supset \mathfrak{N}_{k-1}^*, & \mathfrak{M}_k^* &\supset \mathfrak{M}_{k-1}^*, \\ \mathfrak{B}_k &\subset \mathfrak{B}_{k-1}, & \mathfrak{Z}_k &\subset \mathfrak{Z}_{k-1}. \end{aligned}$$

THEOREM 1. *The spaces \mathfrak{N}_k^* and \mathfrak{M}_k^* are all finite-dimensional, and \mathfrak{B}_k and \mathfrak{Z}_k are closed, and $\mathfrak{B}_k = O\mathfrak{N}_k^*$, $\mathfrak{Z}_k = O\mathfrak{M}_k^*$.*

Proof. Let \mathfrak{B} be a bounded subset of \mathfrak{N}_1^* . Then $E^*\mathfrak{B} = K^*\mathfrak{B}$ is compact, since K^* is completely continuous. Since E^* has a bounded inverse, \mathfrak{B} is compact. Thus \mathfrak{N}_1^* is finite-dimensional, since every bounded subset is compact. (See Banach [1, p. 84, Theorem 8].) If \mathfrak{M}_{k-1}^* is finite-dimensional, then \mathfrak{N}_k^* is also. To show that $\mathfrak{B}_1 = T\mathfrak{X}$ is closed, we shall show that $T^*\mathfrak{Y}^*$ is closed, and apply Lemma 7. Since \mathfrak{N}_1^* is finite-dimensional, there is a projection P of \mathfrak{Y}^* onto \mathfrak{N}_1^* . If $T^*y_n^*$ tends to x_0^* , we may assume $Py_n^* = 0$. If the sequence (y_n^*) is bounded, we may (by choice of a subsequence) require that $K^*y_n^*$ converges, say to x_1^* . Then $E^*y_n^*$ tends to $x_0^* + x_1^*$ which must equal $E^*y_0^*$ for some y_0^* , since the range of E^* is closed by Lemma 7. Then by Lemma 8, y_n^* tends to y_0^* , so $K^*y_0^* = x_1^*$, and $T^*y_0^* = x_0^*$. The sequence (y_n^*) must be bounded, since if $\|y_n^*\|$ tends to infinity, the sequence $y_{1n}^* = y_n^*/\|y_n^*\|$ satisfies the preceding conditions with $x_0^* = 0$. Hence we would have y_{1n}^* approaching y_0^* with $\|y_0^*\| = 1$, $P(y_0^*) = 0$, $T^*y_0^* = 0$, and so $y_0^* = P(y_0^*)$, which is a con-

tradition. Thus $T^*\mathfrak{Y}^*$ is closed, so $\mathfrak{B}_1 = T\mathfrak{X}$ is closed, and $\mathfrak{Z}_1 = E^{-1}\mathfrak{B}_1$ is also closed. Lemma 7 yields the further information that $\mathfrak{B}_1 = O\mathfrak{N}_1^*$, and it follows readily that $\mathfrak{Z}_1 = O\mathfrak{M}_1^*$.

Now suppose that $\mathfrak{Z}_k = O\mathfrak{M}_k^*$. Then \mathfrak{Z}_k is closed, and since \mathfrak{M}_k^* is finite-dimensional, \mathfrak{X} is the direct sum of \mathfrak{Z}_k and a finite dimensional space, by Lemma 4. Now T maps \mathfrak{X} onto the closed space \mathfrak{B}_1 , so $\mathfrak{B}_{k+1} = T\mathfrak{Z}_k$ is closed, by Lemma 10 with \mathfrak{X}_1 replaced by \mathfrak{Z}_k , E by T , and \mathfrak{Y} by \mathfrak{B}_1 . Then $\mathfrak{Z}_{k+1} = E^{-1}\mathfrak{B}_{k+1}$ is also closed and by a sequence of steps the relations $\mathfrak{N}_{k+1}^* = O\mathfrak{B}_{k+1}$, $\mathfrak{B}_{k+1} = O\mathfrak{N}_{k+1}^*$, $\mathfrak{Z}_{k+1} = O\mathfrak{M}_{k+1}^*$ are readily obtained. This completes the induction.

THEOREM 2. *There exists a least integer ν such that $\mathfrak{B}_{\nu+1} = \mathfrak{B}_\nu$, and then $\mathfrak{B}_{\nu+k} = \mathfrak{B}_\nu$ for all k .*

Proof. From the preceding theorem and the fact that \mathfrak{N}_k^* and \mathfrak{M}_k^* are in one-to-one correspondence, it is clear that $\mathfrak{B}_{\nu+1} = \mathfrak{B}_\nu$, $\mathfrak{Z}_{\nu+1} = \mathfrak{Z}_\nu$, $\mathfrak{N}_{\nu+1}^* = \mathfrak{N}_\nu^*$, $\mathfrak{M}_{\nu+1}^* = \mathfrak{M}_\nu^*$ all happen for the same index ν . We make the proof by considering the nondecreasing sequence of finite-dimensional spaces \mathfrak{M}_k^* . If $\mathfrak{M}_{k+1}^* \neq \mathfrak{M}_k^*$ for every k , there exists a unit vector $x_{k+1}^* \in \mathfrak{M}_{k+1}^*$ whose distance from \mathfrak{M}_k^* is unity. For each k there is a point $y_k^* \in \mathfrak{N}_k^*$ with $E^*y_k^* = x_k^*$, $\|y_k^*\| \leq I(E^*)$. Then when $m > k$, $x_m^* - x_k^* = E^*y_m^* - E^*y_k^* = T^*y_m^* - T^*y_k^* + K^*y_m^* - K^*y_k^*$, and $T^*y_m^* \in \mathfrak{M}_{m-1}^*$, $T^*y_k^* \in \mathfrak{M}_{k-1}^* \subset \mathfrak{M}_{m-1}^*$, so $\|K^*y_m^* - K^*y_k^*\| \geq 1$ while $\|y_k^*\|$ is bounded, which contradicts the complete continuity of K^* .

We note that the space \mathfrak{Z}_ν is mapped onto \mathfrak{B}_ν by both E and T . This pair of subspaces replaces the invariant subspace of the classical theory of Riesz.

We remark also that if we consider the sequence of spaces defined by the relations:

$$\begin{aligned} \mathfrak{N}_1 &= \mathfrak{N}(T), & \mathfrak{M}_k &= E\mathfrak{N}_k, \\ & & T\mathfrak{M}_{k+1} &\subset \mathfrak{M}_k, & (\mathfrak{N}_{k+1} \text{ maximal}), \end{aligned}$$

we may have $\mathfrak{N}_{k+1} \neq \mathfrak{N}_k$ for every k . For example, let \mathfrak{X} and \mathfrak{Y} be classical Hilbert space, and let the transformation $y = Ex$ be defined by $y_i = x_{i+3}$ while $y = Kx$ is defined by

$$y_1 = x_4, \quad y_2 = x_5 - x_2, \quad y_{i+2} = x_{i+4}/(i + 4).$$

Then a basis for \mathfrak{N}_k is composed of $\delta_1, \delta_3, \delta_4, \alpha_1, \dots, \alpha_k$, where δ_i has only its i th component different from zero, α_1 has its i th component equal to $1/(i-1)!$ except the first four, which are zero, and $E\alpha_j = T\alpha_{j+1}$.

THEOREM 3. *Let (c_j) be a sequence (finite or infinite) of distinct proper values of K . Let $\mathfrak{N}^{*(i)}$ denote the null space of $T_{c_j}^*$, and let $\mathfrak{B}^{(i)} = T_{c_j}\mathfrak{X}$. Let $[y_{ij}^*] i=1, \dots, k_j]$ be a basis for $\mathfrak{N}^{*(i)}$. Then the functionals y_{ij}^* are finitely linearly independent, and there exists a system $[y_{ij}]$ of elements of \mathfrak{Y} such that:*

- (a) for each j , $\mathfrak{B}^{(i)}$ and $[y_{ij}] i=1, \dots, k_j]$ span the space \mathfrak{Y} ;

- (b) $y_{ii}^*(y_{kj}) = \delta_{ik}\delta_{lj}$ for $l \leq j$;
- (c) y_{kj} lies in $\mathfrak{B}^{(l)}$ for $l < j$;
- (d) the elements y_{ij} are finitely linearly independent.

Proof. Suppose

$$\sum_{j=1}^n \sum_{i=1}^{k_j} a_{ij} y_{ij}^* = 0.$$

Then

$$\begin{aligned} 0 &= \sum_{j=1}^{n-1} \sum_i^* (E - c_n K^*) a_{ij} y_{ij}^* \\ &= E^* \sum_{j=1}^{n-1} \left(1 - \frac{c_n}{c_j}\right) \sum_i a_{ij} y_{ij}^* \end{aligned}$$

and since E^* is one-to-one, this gives a relation involving only $n-1$ of the spaces $\mathfrak{N}^{*(i)}$. Hence by descent we arrive at a contradiction. By Theorem 1 for $k=1$, and Lemmas 1 and 4 we obtain (a) and (b) for $j=1, l=1$. Suppose that the system $[y_{ij}]$ has been determined so as to satisfy (a), (b), and (c) for $j < n$. Then the intersection $\mathfrak{B}^{(n-1)}$ of $\mathfrak{B}^{(1)}, \dots, \mathfrak{B}^{(n-1)}$ is the orthogonal complement of the union of $\mathfrak{N}^{*(1)}, \dots, \mathfrak{N}^{*(n-1)}$ and since the y_{ij}^* are linearly independent, there are points y_{in} in $\mathfrak{B}^{(n-1)}$ such that (b) holds for $l=j=n$. Property (a) holds for $j=n$, by the same argument as before. Property (d) follows at once from (b).

THEOREM 4. *The proper values of K have no finite accumulation point.*

Proof. Suppose (c_n) is a bounded infinite sequence of distinct proper values. Let \mathfrak{S}_n^* be the space spanned by $\mathfrak{N}^{*(1)}, \dots, \mathfrak{N}^{*(n)}$. Then (\mathfrak{S}_n^*) is a properly increasing sequence of finite-dimensional linear spaces, so each \mathfrak{S}_n^* contains a unit vector v_n^* at unit distance from \mathfrak{S}_{n-1}^* . The sequence $(c_n v_n^*)$ is bounded, so $(c_n K^* v_n^*)$ is compact. If y^* is in $\mathfrak{N}^{*(i)}$, $T_c^* y^* = E^*(1 - c/c_j)y^*$, which is zero if $c = c_j$, so

$$(1) \quad T_{c_p}^* \mathfrak{S}_p^* \subset E^* \mathfrak{S}_{p-1}^*.$$

Now for $p > q$, let

$$d_{pq} = \|c_p K^* v_p^* - c_q K^* v_q^*\| = \|E^* v_p^* - T_{c_p}^* v_p^* - E^* v_q^* + T_{c_q}^* v_q^*\|,$$

so by (1)

$$d_{pq} = \|E^* v_p^* - E^* u^*\|, \quad \text{where } u^* \text{ is in } \mathfrak{S}_{p-1}^* \text{ and } \|v_p^* - u^*\| = 1.$$

Since the inverse of E^* is bounded, by Lemma 8, this contradicts the compactness of $(c_n K^* v_n^*)$.

Since the range of T_c^* may vary with c , we state properties of the inverse of T_c^* as follows.

THEOREM 5. *If c_0 is not a proper value of K , and (c_n) and (y_n^*) are sequences such that $\lim c_n = c_0$, $\lim T_{c_n}^* y_n^* = x_0^*$, then y_n^* tends to the unique solution y_0^* of $T_{c_0}^* y^* = x_0^*$. Consequently if $T_c^* y^*(c) = x^*(c)$, and $x^*(c)$ is continuous (differentiable) at c_0 , then $y^*(c)$ is continuous (differentiable) at c_0 .*

Proof. Suppose first that (y_n^*) is bounded. Then $\lim (T_{c_n}^* y_n^* - T_{c_0}^* y_n^*) = 0$ so $\lim T_{c_0}^* y_n^* = x_0^*$, and hence $\lim y_n^* = R x_0^*$, where R is the inverse of $T_{c_0}^*$. If $\lim \|y_n^*\| = \infty$, set $v_n^* = y_n^* / \|y_n^*\|$. Then $\lim T_{c_n}^* v_n^* = 0$, so by the first case $\lim v_n^* = 0$, which is a contradiction.

With the help of the last theorem we see that a necessary and sufficient condition for c_0 to be a proper value of K is that there exist sequences (c_n) and (y_n^*) such that:

- (a) $\lim c_n = c_0$,
- (b) $\|y_n^*\| = 1$,
- (c) $\lim T_{c_n}^* y_n^* = 0$.

This suggests the following definitions:

- (I) $c = \infty$ is a *singular value* for K in case there exist sequences (c_n) and (y_n^*) such that (a'), (b), and (c) hold, where (a') means: $\lim c_n = \infty$.
- (II) c_0 is a *proper value of order μ* for K in case μ is the maximum order of vanishing of $T_c^* y^*(c)$, where $y^*(c)$ is a polynomial in c , not vanishing at c_0 .

THEOREM 6. *If $c = 1$ is a proper value for K , it is a proper value of order ν , where ν is the integer given by Theorem 2.*

Proof. It is readily verified by induction that K^* (as well as E^*) maps \mathfrak{N}_k^* onto \mathfrak{N}_k^* one-to-one. Denoting by D the operation of differentiation with respect to c , we have

$$D^k T_c^* y^*(c) = T_c^* D^k y^*(c) - k K^* D^{k-1} y^*(c).$$

Hence if $c = 1$ is a proper value of order μ , there is a polynomial $y^*(c)$ such that $0 \neq y^*(1) \in \mathfrak{N}_1^*$, and by induction $D^k y^*(1) \in \mathfrak{N}_{k+1}^* - \mathfrak{N}_k^*$ for $k < \mu$. Hence $\mu \leq \nu$. To show that $\mu = \nu$, we set $y^*(c) = \sum_{j=1}^{\nu} (c-1)^{j-1} \eta_j^*$, where $\eta_j^* \in \mathfrak{N}_j^* - \mathfrak{N}_{j-1}^*$ and $T_1^* \eta_j^* = K^* \eta_{j-1}^*$, so that no $\eta_j^* = 0$, and $T_c^* y^*(c) = -(c-1)^\nu K^* \eta_\nu^*$.

We next consider a decomposition of K relative to a proper value, which we take for convenience to be $c = 1$. In view of the definition of the spaces \mathfrak{N}_i^* , there exists a basis $[\theta_{ij}^* | j = 1, \dots, p_i; i = 1, \dots, \nu]$ for \mathfrak{N}_ν^* such that $[\theta_{ij}^* | j = 1, \dots, p_i; i = 1, \dots, k]$ is a basis for \mathfrak{N}_k^* , and moreover

$$(2) \quad (E^* - K^*) \theta_{i+1,j}^* = E^* \theta_{ij}^* \quad \text{for } j = 1, \dots, p_{i+1}, i = 1, \dots, \nu - 1.$$

Note that when the basis $[\theta_{ij}^*]$ is displayed by columns, the index i ranges from 1 to q_j , and j ranges from 1 to p_1 . Choose η_{ij} from \mathfrak{N}_j so that

$$(3) \quad \theta_{ij}^*(\eta_{kl}) = \delta_{ik}\delta_{jl},$$

and set

$$Q_j(y) = \sum_{i=1}^{q_j} \theta_{ij}^*(y)\eta_{ij}, \quad Q = \sum_{j=1}^{p_1} Q_j,$$

$$Q_j^*(y^*) = \sum_{i=1}^{q_j} y^*(\eta_{ij})\theta_{ij}^*,$$

$$(4) \quad G_j = Q_jK, \quad G = \sum_{j=1}^{p_1} G_j, \quad H = K - G.$$

Then clearly Q^* projects \mathfrak{Y}^* onto \mathfrak{N}_r^* , and Q_j^* projects \mathfrak{Y}^* onto the subspace of \mathfrak{N}_r^* corresponding to a single proper vector θ_{1j}^* by means of the relations (2).

THEOREM 7. *The decomposition of K given in (4) has the following properties:*

- (a) *each G_j has only one independent proper vector θ_{1j}^* , which corresponds to the proper value $c=1$;*
- (b) *G has only the proper value $c=1$, and the null-spaces \mathfrak{N}_k^* for G are the same as those for K ;*
- (c) *$c = \infty$ is not a singular value for G ;*
- (d) *$c=1$ is not a proper value for H ;*
- (e) *$G_i^*y^*=0$ for every y^* satisfying $E^*y^*=G^*y_i^*$ for some y_i^* and some $j \neq i$;*
- (f) *$H^*y^*=0$ for every y^* satisfying $E^*y^*=G^*y_i^*$ for some y_i^* ;*
- (g) *if c is a proper value for K and $c \neq 1$, then c is a proper value for H , and conversely.*

Proof. If $(E^* - cG^*)y^* = 0$, it follows from (2) and the fact that E^* is one-to-one that y^* is a linear combination of $\theta_{1j}^*, \dots, \theta_{q_j, j}^*$, and by another application of (2) that $c=1$ and y^* is a multiple of θ_{1j}^* . This proves (a). To prove (b), we observe that Q^* projects \mathfrak{Y}^* onto \mathfrak{N}_r^* , and from (2) that K^* maps \mathfrak{N}_r^* onto \mathfrak{M}_r^* one-to-one, so G^* maps \mathfrak{Y}^* onto \mathfrak{M}_r^* , and $G^* = K^*$ on \mathfrak{N}_r^* . Thus if $(E^* - cG^*)y^* = 0$, y^* is in \mathfrak{N}_r^* , and $(c-1)E^*y^* = c(E^* - G^*)y^* = c(E^* - K^*)y^*$, so if $c \neq 1$, y^* is in \mathfrak{N}_{r-1}^* . Proceeding by descent, we finally find $y^* = 0$. The remainder of (b) follows readily. If we suppose that $c = \infty$ is a singular value for G , there must exist sequences (c_n) and (y_n^*) with $\lim c_n = \infty$, $\|y_n^*\| = 1$, $\lim (E^* - c_n G^*)y_n^* = 0$. Since the sequence $(E^*y_n^*)$ is bounded, $(c_n G^*y_n^*)$ is likewise bounded and lies in the finite-dimensional space \mathfrak{M}_r^* , so we may suppose that it converges to a point x^* in \mathfrak{M}_r^* . Then $x^* = E^*y^*$ where y^* is in \mathfrak{N}_r^* , and since E^* has a continuous inverse, $\lim y_n^* = y^*$, so $\|y^*\| = 1$. But $\lim G^*y_n^* = 0 = G^*y^*$, and since G^* gives a one-to-one correspondence between \mathfrak{N}_r^* and \mathfrak{M}_r^* , we have $y^* = 0$, which is a contradiction. This proves (c). To secure (d) we observe that if $0 = (E^* - H^*)y^* = (E^* - K^*)y^* + G^*y^*$, then y^* is in \mathfrak{N}_r^* since G^*y^* is in \mathfrak{M}_r^* , so $H^*y^* = 0$, $E^*y^* = 0$,

$y^* = 0$. We next prove (e) and (f). If $E^*y^* = G_j^*y_1^*$, we have from (2) (setting $\theta_{0j}^* = 0$)

$$(5) \quad y^* = \sum_{i=1}^{q_j} y_1^*(\eta_{ij}) (\theta_{ij}^* - \theta_{i-1,j}^*),$$

since E^* is one-to-one, and

$$(6) \quad G_j^*y_1^* = \sum_{i=1}^{q_j} y_1^*(\eta_{ij}) K^* \theta_{ij}^*.$$

So by (5) and (6) and (3),

$$G^*y^* = \sum_{i=1}^{q_j} \sum_{m=1}^{q_i} y_1^*(\eta_{ij}) [\theta_{ij}^*(\eta_{mi}) - \theta_{i-1,j}^*(\eta_{mi})] K^* \theta_{mi}^* = \delta_{ji} K^* y^*,$$

and hence $H^*y^* = 0$. Property (f) follows immediately. Finally, to prove (g), we observe that if $c \neq 1$, $y^* \neq 0$, and $(E^* - cK^*)y^* = 0$, $G^*y^* = E^*y_1^*$, where y_1^* is in \mathfrak{N}_r^* , and so $H^*y_1^* = 0$, by (f). Hence

$$\begin{aligned} 0 &= E^*y^* - cG^*y^* - cH^*y^* = E^*y^* - cE^*y_1^* - cH^*y^* + c^2H^*y_1^* \\ &= (E^* - cH^*)(y^* - cy_1^*). \end{aligned}$$

Now if $y^* = cy_1^*$ we would have $0 = (E^* - cK^*)y_1^* = (E^* - cG^*)y_1^*$, and this cannot happen for $c \neq 1$ by part (b) of the theorem. So c is a proper value of H . For the converse, let $(E^* - cH^*)y^* = 0$ with $y^* \neq 0$. Then y^* is not in \mathfrak{N}_r^* , and there is a finite sequence y_1^*, \dots, y_k^* , such that $G^*y^* = E^*y_1^*$, $(E^* - K^*)y_i^* = E^*y_{i+1}^*$ for $i = 1, \dots, k-1$, each y_i^* is in \mathfrak{N}_r^* , y_k^* is in \mathfrak{N}_1^* , and so

$$(E^* - cK^*) \left(y^* + \sum_{i=1}^k \alpha_i y_i^* \right) = E^* \left[-cy_1^* + (1-c) \sum_{i=1}^k \alpha_i y_i^* + c \sum_{i=1}^{k-1} \alpha_i y_{i+1}^* \right].$$

The expression in square brackets vanishes if $(1-c)\alpha_1 = c$, $(1-c)\alpha_i = -c\alpha_{i-1}$ for $i = 2, \dots, k$.

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