

# A GENERALIZATION OF THE RIESZ THEORY OF COMPLETELY CONTINUOUS TRANSFORMATIONS<sup>(1)</sup>

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The classical theory, due to F. Riesz, of completely continuous transformations deals with a family  $T_c = I - cK$  of linear continuous transformations of a Banach space  $\mathfrak{X}$  into itself, where  $I$  is the identity and  $K$  is completely continuous. The transformation  $T_c$  is then one-to-one, except for the "proper" values of  $c$ . In this paper we consider cases where the one-to-oneness no longer holds. The identity transformation  $I$  is replaced by a transformation  $E$  which maps  $\mathfrak{X}$  onto the whole of another Banach space  $\mathfrak{Y}$ , but *not* one-to-one. Then when  $K$  is completely continuous, the transformation  $T_c = E - cK$  maps  $\mathfrak{X}$  onto  $\mathfrak{Y}$  except for a countable set of proper values  $c_i$  which have no finite accumulation point. When  $\mathfrak{B}_1 = T_c \mathfrak{X} \neq \mathfrak{Y}$ ,  $c$  is said to be a *proper value* for  $K$ . We can no longer iterate the transformation  $T_c$ , but we can apply  $T_c$  to  $E^{-1}T_c \mathfrak{X}$  and obtain a linear closed space  $\mathfrak{B}_2 \subset \mathfrak{B}_1$ . After a finite number of repetitions of this process, we find a space  $\mathfrak{B}_\nu = \mathfrak{B}_{\nu+1}$ . Then  $T_c$  transforms  $E^{-1}\mathfrak{B}_\nu$  onto  $\mathfrak{B}_\nu$ , which takes the place of the invariant subspace of the Riesz theory.

In the one-to-one case, there is associated with the transformation  $I - cK$  a resolvent  $R_c$ , which has a pole of order  $\nu$  at a proper value  $c_0$ , and the Laurent expansion of  $R_c$  about  $c_0$  leads to a decomposition of  $K$  into two mutually orthogonal parts. In the many-to-one case, the adjoint transformation  $T_c^*$  is one-to-one except when  $c$  is a proper value, but the range of  $T_c^*$  varies with  $c$ , so that it is not possible to define the order of a pole of the resolvent in the usual way. However a substitute definition has been found, as well as a decomposition  $K = G + H$ , where  $G$  has only one proper value  $c_0$ , and  $H$  has only the remaining proper values of  $K$ , and  $H$  is semi-orthogonal to  $G$  in a suitable sense.

**1. Notations and definitions.** We shall let  $\mathfrak{X}$  and  $\mathfrak{Y}$  denote Banach spaces of infinitely many dimensions, with complex scalars. The adjoint spaces of  $\mathfrak{X}$  and  $\mathfrak{Y}$  will be denoted by  $\mathfrak{X}^*$  and  $\mathfrak{Y}^*$  respectively. Two subsets  $\mathfrak{X}_0$  of  $\mathfrak{X}$  and  $\mathfrak{X}_0^*$  of  $\mathfrak{X}^*$  are said to be *orthogonal* in case  $x^*(x) = 0$  for all  $x$  in  $\mathfrak{X}_0$  and  $x^*$  in  $\mathfrak{X}_0^*$ . The *orthogonal complement* of a subset  $\mathfrak{X}_0$ , denoted by  $O\mathfrak{X}_0$ , is the maximal set  $\mathfrak{X}_0^*$  orthogonal to  $\mathfrak{X}_0$ . It is easily seen that  $O\mathfrak{X}_0$  always exists (possibly void) and is a linear closed set. A corresponding statement holds for  $O\mathfrak{X}_0^*$ .

A linear transformation  $A$  mapping  $\mathfrak{X}$  into  $\mathfrak{Y}$  has an *adjoint*  $A^*$  mapping  $\mathfrak{Y}^*$  into  $\mathfrak{X}^*$ , defined by  $x^* = A^*y^*$  where  $x^*(x) = y^*Ax$  for each  $x$ . We shall

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deal only with continuous linear transformations  $A$ . Such a transformation  $A$  is said to be *completely continuous* in case the transform  $A(\mathfrak{X}_0)$  of every bounded set  $\mathfrak{X}_0$  is compact (in the sense that every sequence  $(y_n)$  chosen from  $A(\mathfrak{X}_0)$  has a convergent subsequence).

We shall use the letter  $E$  to denote a linear continuous transformation mapping  $\mathfrak{X}$  onto the whole space  $\mathfrak{Y}$ , and shall use  $K$ ,  $G$ , and  $H$  to denote completely continuous linear transformations of  $\mathfrak{X}$  into  $\mathfrak{Y}$ . We also set  $T_c = E - cK$ , where  $c$  is a complex parameter. When it is convenient to set  $c = 1$ , we shall write  $T$  for  $T_c$ .

A *projection*  $P$  is a linear continuous transformation of  $\mathfrak{X}$  onto a closed linear subset  $\mathfrak{X}_0$ , which equals the identity on  $\mathfrak{X}_0$ , i.e.,  $P^2 = P$ .

For a given linear continuous transformation  $A$  of  $\mathfrak{X}$  into  $\mathfrak{Y}$  we shall set

$$\beta(A, y) = \text{g.l.b. } [\|x\| \mid Ax = y]$$

for each  $y$ , and

$$I(A) = \text{l.u.b. } [\beta(A, y) \mid y \in A\mathfrak{X}, \|y\| = 1].$$

When the transformation  $A$  is one-to-one, obviously  $I(A) = \|A^{-1}\|$ . (We are admitting  $+\infty$  as a value for  $\|A^{-1}\|$ .)

We shall use  $\mathfrak{N}(A)$  to denote the null space of  $A$ , that is

$$\mathfrak{N}(A) = [x \mid Ax = 0].$$

Similarly  $\mathfrak{N}(A^*)$  denotes the null space of  $A^*$ .

## 2. Preliminary lemmas.

LEMMA 1. *If  $\mathfrak{X}_0$  is a finite-dimensional linear subspace of  $\mathfrak{X}$ , with basis  $\{x_1, \dots, x_n\}$ , there exist  $n$  elements  $x_i^*$  of  $\mathfrak{X}^*$  such that  $x_i^*(x_j) = \delta_{ij}$ , and  $P(x) = \sum_{i=1}^n x_i^*(x)x_i$  is a projection of  $\mathfrak{X}$  onto  $\mathfrak{X}_0$ . A similar result holds for  $\mathfrak{X}_0^* \subset \mathfrak{X}^*$ , with  $Q(x^*) = \sum_{i=1}^n x^*(x_i)x_i^*$ .*

The first part follows at once from the Hahn-Banach theorem, and the second part follows from more elementary considerations. Note that if the sets  $\{x_1, \dots, x_n\}$  and  $\{x_1^*, \dots, x_n^*\}$  are the same in the two cases, then  $Q = P^*$ .

LEMMA 2. *For each linear closed subspace  $\mathfrak{X}_0$  of  $\mathfrak{X}$ ,  $OO\mathfrak{X}_0 = \mathfrak{X}_0$ .*

This follows from the lemma in Banach [1, p. 57]. The corresponding result for subsets  $\mathfrak{X}_0^*$  of  $\mathfrak{X}^*$  does not hold in general, as Banach shows in [1, p. 115]. However, by an easy proof we have

LEMMA 3. *If  $\mathfrak{X}_0^*$  is a finite-dimensional linear subspace of  $\mathfrak{X}^*$ , then  $OO\mathfrak{X}_0^* = \mathfrak{X}_0^*$ .*

LEMMA 4. *If  $\{x_1^*, \dots, x_n^*\}$  is a basis for  $\mathfrak{X}_0^*$ ,  $x_i^*(x_j) = \delta_{ij}$ , and*

$P(x) = \sum_{i=1}^n x_i^*(x)x_i$ , then  $\mathfrak{X}$  is the direct sum of  $O\mathfrak{X}_0^*$  and the finite-dimensional space  $P\mathfrak{X}$ .

To prove this, we observe that  $x - P(x)$  is always in  $O\mathfrak{X}_0^*$ , and that if  $x$  lies in  $O\mathfrak{X}_0^*$ , then  $Px = 0$ .

LEMMA 5. *A linear transformation  $A$  of  $\mathfrak{X}$  into  $\mathfrak{Y}$  is (completely) continuous if and only if its adjoint  $A^*$  is (completely) continuous.*

**Proof.** This follows from Theorems 3 and 4 in Banach [1, p. 100]. To show that  $A$  is completely continuous whenever  $A^*$  is, we note that  $A^{**}$ , when restricted to  $\mathfrak{X}$ , reduces to  $A$ , so by Theorem 4 of Banach,  $A$  transforms bounded sets in  $\mathfrak{X}$  into sets in  $\mathfrak{Y}$  which are compact in  $\mathfrak{Y}^{**}$ . But  $\mathfrak{Y}$  is closed in  $\mathfrak{Y}^{**}$ .

LEMMA 6. *The range  $A\mathfrak{X}$  of a linear continuous transformation  $A$  of  $\mathfrak{X}$  into  $\mathfrak{Y}$  is closed if and only if  $I(A) < \infty$ .*

**Proof.** When  $A\mathfrak{X}$  is closed it constitutes a Banach space, so the necessity of the condition follows from Banach [1, p. 38]. To see that the condition is sufficient, suppose  $y_n = Ax_n$ , and  $\lim y_n = y$ . By choosing a subsequence we may suppose that  $\|y_{n+1} - y_n\| < 1/2^n$ . Then after  $x_n$  has been suitably chosen,  $x_{n+1}$  may be modified (still satisfying  $y_{n+1} = Ax_{n+1}$ ) so that  $\|x_{n+1} - x_n\| \leq I(A)/2^n$ . Hence the modified sequence  $(x_n)$  has a limit  $x$ , and  $Ax_n$  converges to  $Ax = y$ .

COROLLARY. *If  $A\mathfrak{X}$  is closed, and  $\lim Ax_n = Ax$ , there exists a sequence  $(x'_n)$  such that  $Ax'_n = Ax_n$  and  $\lim x'_n = x$ .*

**Proof.** From the definition of  $I(A)$  we may choose  $x'_n$  so that  $A(x'_n - x) = A(x_n - x)$  and  $\|x'_n - x\| \leq (I(A) + 1)\|A(x_n - x)\|$ . (Compare Banach [1, p. 40, Theorem 4].)

LEMMA 7. *If  $A$  is linear and continuous,  $A\mathfrak{X}$  is closed if and only if  $A^*\mathfrak{Y}^*$  is closed, and then  $A^*\mathfrak{Y}^* = O\mathfrak{N}(A)$ ,  $A\mathfrak{X} = O\mathfrak{N}(A^*)$ , where  $\mathfrak{N}(A)$  and  $\mathfrak{N}(A^*)$  are the null spaces of  $A$  and of  $A^*$ .*

For the proof, see Banach [1, pp. 149, 150, Theorems 8 and 9].

LEMMA 8. *If  $A$  is linear and continuous, then  $A$  maps  $\mathfrak{X}$  onto the whole of the space  $\mathfrak{Y}$  if and only if  $A^*$  has a continuous inverse. Likewise  $A$  has a continuous inverse if and only if  $A^*$  maps  $\mathfrak{Y}^*$  onto  $\mathfrak{X}^*$ .*

For the proof, see Banach [1, pp. 146-148, Theorems 1-4].

LEMMA 9. *If  $\mathfrak{X}_1$  and  $\mathfrak{X}_2$  are two closed linear subspaces of  $\mathfrak{X}$ ,  $\mathfrak{X}_2$  being finite-dimensional, then  $\mathfrak{X}_1 + \mathfrak{X}_2$  (the linear space spanned by  $\mathfrak{X}_1$  and  $\mathfrak{X}_2$ ) is also closed.*

This is readily proved by induction on the dimension of  $\mathfrak{X}_2$ .

LEMMA 10. *Suppose  $\mathfrak{X}_1$  and  $\mathfrak{X}_2$  satisfy the conditions of Lemma 9, and also that  $\mathfrak{X}_1 + \mathfrak{X}_2 = \mathfrak{X}$ . Let  $E$  be a linear continuous transformation of  $\mathfrak{X}$  onto the whole of  $\mathfrak{Y}$ . Then  $E\mathfrak{X}_1$  is closed.*

**Proof.** The space  $\mathfrak{X}_3 = E^{-1}E\mathfrak{X}_1$  equals  $\mathfrak{X}_1 + \mathfrak{X}_4$  where  $\mathfrak{X}_4 \subset \mathfrak{X}_2$ , so  $\mathfrak{X}_3$  is closed by Lemma 9. Let  $E_3$  denote the restriction of  $E$  to  $\mathfrak{X}_3$ . Then clearly  $I(E_3) \leqq I(E)$ . By Lemma 6,  $I(E) < \infty$ , and by the same Lemma 6,  $E_3\mathfrak{X}_3 = E\mathfrak{X}_1$  is closed.

**3. Proper values of a completely continuous transformation.** In this section we develop some properties of the family of transformations  $T_c = E - cK$ , described in §1. A complex number  $c$  is called a *proper value* of  $K$  in case the range of  $T_c$  is a proper subset of  $\mathfrak{Y}$ , or equivalently, in case  $T_c^*$  does not have an inverse.

In case  $c = 1$  is a proper value, the null space  $\mathfrak{N}_1^* = \mathfrak{N}(T^*)$  is not null, and the range  $\mathfrak{B}_1 = T\mathfrak{X} \neq \mathfrak{Y}$ . We set  $\mathfrak{M}_1^* = E^*\mathfrak{N}_1^*$ , and define  $\mathfrak{Z}_1$  as the maximal subspace of  $\mathfrak{X}$  satisfying  $E\mathfrak{Z}_1 = \mathfrak{B}_1$ . This is the start of an iterative definition of four sequences of linear spaces  $\mathfrak{N}_k^*, \mathfrak{M}_k^*, \mathfrak{B}_k, \mathfrak{Z}_k$ , by means of the relations

$$\begin{aligned} T^*\mathfrak{N}_k^* &\subset \mathfrak{M}_{k-1}^* && (\mathfrak{N}_k^* \text{ maximal}), \\ \mathfrak{M}_k^* &= E^*\mathfrak{N}_k^*, \\ \mathfrak{B}_k &= T\mathfrak{Z}_{k-1}, \\ E\mathfrak{Z}_k &= \mathfrak{B}_k && (\mathfrak{Z}_k \text{ maximal}). \end{aligned}$$

It is obvious that

$$\begin{aligned} \mathfrak{N}_k^* &\supset \mathfrak{N}_{k-1}^*, & \mathfrak{M}_k^* &\supset \mathfrak{M}_{k-1}^*, \\ \mathfrak{B}_k &\subset \mathfrak{B}_{k-1}, & \mathfrak{Z}_k &\subset \mathfrak{Z}_{k-1}. \end{aligned}$$

**THEOREM 1.** *The spaces  $\mathfrak{N}_k^*$  and  $\mathfrak{M}_k^*$  are all finite-dimensional, and  $\mathfrak{B}_k$  and  $\mathfrak{Z}_k$  are closed, and  $\mathfrak{B}_k = O\mathfrak{N}_k^*$ ,  $\mathfrak{Z}_k = O\mathfrak{M}_k^*$ .*

**Proof.** Let  $\mathfrak{B}$  be a bounded subset of  $\mathfrak{N}_1^*$ . Then  $E^*\mathfrak{B} = K^*\mathfrak{B}$  is compact, since  $K^*$  is completely continuous. Since  $E^*$  has a bounded inverse,  $\mathfrak{B}$  is compact. Thus  $\mathfrak{N}_1^*$  is finite-dimensional, since every bounded subset is compact. (See Banach [1, p. 84, Theorem 8].) If  $\mathfrak{M}_{k-1}^*$  is finite-dimensional, then  $\mathfrak{N}_k^*$  is also. To show that  $\mathfrak{B}_1 = T\mathfrak{X}$  is closed, we shall show that  $T^*\mathfrak{Y}^*$  is closed, and apply Lemma 7. Since  $\mathfrak{N}_1^*$  is finite-dimensional, there is a projection  $P$  of  $\mathfrak{Y}^*$  onto  $\mathfrak{N}_1^*$ . If  $T^*y_n^*$  tends to  $x_0^*$ , we may assume  $Py_n^* = 0$ . If the sequence  $(y_n^*)$  is bounded, we may (by choice of a subsequence) require that  $K^*y_n^*$  converges, say to  $x_1^*$ . Then  $E^*y_n^*$  tends to  $x_0^* + x_1^*$  which must equal  $E^*y_0^*$  for some  $y_0^*$ , since the range of  $E^*$  is closed by Lemma 7. Then by Lemma 8,  $y_n^*$  tends to  $y_0^*$ , so  $K^*y_0^* = x_1^*$ , and  $T^*y_0^* = x_0^*$ . The sequence  $(y_n^*)$  must be bounded, since if  $\|y_n^*\|$  tends to infinity, the sequence  $y_{1n}^* = y_n^*/\|y_n^*\|$  satisfies the preceding conditions with  $x_0^* = 0$ . Hence we would have  $y_{1n}^*$  approaching  $y_0^*$  with  $\|y_0^*\| = 1$ ,  $P(y_0^*) = 0$ ,  $T^*y_0^* = 0$ , and so  $y_0^* = P(y_0^*)$ , which is a con-

tradition. Thus  $T^*\mathfrak{Y}^*$  is closed, so  $\mathfrak{B}_1 = T\mathfrak{X}$  is closed, and  $\mathfrak{Z}_1 = E^{-1}\mathfrak{B}_1$  is also closed. Lemma 7 yields the further information that  $\mathfrak{B}_1 = O\mathfrak{N}_1^*$ , and it follows readily that  $\mathfrak{Z}_1 = O\mathfrak{M}_1^*$ .

Now suppose that  $\mathfrak{Z}_k = O\mathfrak{M}_k^*$ . Then  $\mathfrak{Z}_k$  is closed, and since  $\mathfrak{M}_k^*$  is finite-dimensional,  $\mathfrak{X}$  is the direct sum of  $\mathfrak{Z}_k$  and a finite dimensional space, by Lemma 4. Now  $T$  maps  $\mathfrak{X}$  onto the closed space  $\mathfrak{B}_1$ , so  $\mathfrak{B}_{k+1} = T\mathfrak{Z}_k$  is closed, by Lemma 10 with  $\mathfrak{X}_1$  replaced by  $\mathfrak{Z}_k$ ,  $E$  by  $T$ , and  $\mathfrak{Y}$  by  $\mathfrak{B}_1$ . Then  $\mathfrak{Z}_{k+1} = E^{-1}\mathfrak{B}_{k+1}$  is also closed and by a sequence of steps the relations  $\mathfrak{N}_{k+1}^* = O\mathfrak{B}_{k+1}$ ,  $\mathfrak{B}_{k+1} = O\mathfrak{N}_{k+1}^*$ ,  $\mathfrak{Z}_{k+1} = O\mathfrak{M}_{k+1}^*$  are readily obtained. This completes the induction.

**THEOREM 2.** *There exists a least integer  $\nu$  such that  $\mathfrak{B}_{\nu+1} = \mathfrak{B}_\nu$ , and then  $\mathfrak{B}_{\nu+k} = \mathfrak{B}_\nu$  for all  $k$ .*

**Proof.** From the preceding theorem and the fact that  $\mathfrak{N}_k^*$  and  $\mathfrak{M}_k^*$  are in one-to-one correspondence, it is clear that  $\mathfrak{B}_{\nu+1} = \mathfrak{B}_\nu$ ,  $\mathfrak{Z}_{\nu+1} = \mathfrak{Z}_\nu$ ,  $\mathfrak{N}_{\nu+1}^* = \mathfrak{N}_\nu^*$ ,  $\mathfrak{M}_{\nu+1}^* = \mathfrak{M}_\nu^*$  all happen for the same index  $\nu$ . We make the proof by considering the nondecreasing sequence of finite-dimensional spaces  $\mathfrak{M}_k^*$ . If  $\mathfrak{M}_{k+1}^* \neq \mathfrak{M}_k^*$  for every  $k$ , there exists a unit vector  $x_{k+1}^* \in \mathfrak{M}_{k+1}^*$  whose distance from  $\mathfrak{M}_k^*$  is unity. For each  $k$  there is a point  $y_k^* \in \mathfrak{N}_k^*$  with  $E^*y_k^* = x_k^*$ ,  $\|y_k^*\| \leq I(E^*)$ . Then when  $m > k$ ,  $x_m^* - x_k^* = E^*y_m^* - E^*y_k^* = T^*y_m^* - T^*y_k^* + K^*y_m^* - K^*y_k^*$ , and  $T^*y_m^* \in \mathfrak{M}_{m-1}^*$ ,  $T^*y_k^* \in \mathfrak{M}_{k-1}^* \subset \mathfrak{M}_{m-1}^*$ , so  $\|K^*y_m^* - K^*y_k^*\| \geq 1$  while  $\|y_k^*\|$  is bounded, which contradicts the complete continuity of  $K^*$ .

We note that the space  $\mathfrak{Z}_\nu$  is mapped onto  $\mathfrak{B}_\nu$  by both  $E$  and  $T$ . This pair of subspaces replaces the invariant subspace of the classical theory of Riesz.

We remark also that if we consider the sequence of spaces defined by the relations:

$$\begin{aligned} \mathfrak{N}_1 &= \mathfrak{N}(T), & \mathfrak{M}_k &= E\mathfrak{N}_k, \\ & & T\mathfrak{M}_{k+1} &\subset \mathfrak{M}_k, & (\mathfrak{N}_{k+1} \text{ maximal}), \end{aligned}$$

we may have  $\mathfrak{N}_{k+1} \neq \mathfrak{N}_k$  for every  $k$ . For example, let  $\mathfrak{X}$  and  $\mathfrak{Y}$  be classical Hilbert space, and let the transformation  $y = Ex$  be defined by  $y_i = x_{i+3}$  while  $y = Kx$  is defined by

$$y_1 = x_4, \quad y_2 = x_5 - x_2, \quad y_{i+2} = x_{i+4}/(i + 4).$$

Then a basis for  $\mathfrak{N}_k$  is composed of  $\delta_1, \delta_3, \delta_4, \alpha_1, \dots, \alpha_k$ , where  $\delta_i$  has only its  $i$ th component different from zero,  $\alpha_1$  has its  $i$ th component equal to  $1/(i-1)!$  except the first four, which are zero, and  $E\alpha_j = T\alpha_{j+1}$ .

**THEOREM 3.** *Let  $(c_j)$  be a sequence (finite or infinite) of distinct proper values of  $K$ . Let  $\mathfrak{N}^{*(i)}$  denote the null space of  $T_{c_j}^*$ , and let  $\mathfrak{B}^{(i)} = T_{c_j}\mathfrak{X}$ . Let  $[y_{ij}^*]_{i=1, \dots, k_j}$  be a basis for  $\mathfrak{N}^{*(i)}$ . Then the functionals  $y_{ij}^*$  are finitely linearly independent, and there exists a system  $[y_{ij}]$  of elements of  $\mathfrak{Y}$  such that:*

- (a) for each  $j$ ,  $\mathfrak{B}^{(j)}$  and  $[y_{ij}]_{i=1, \dots, k_j}$  span the space  $\mathfrak{Y}$ ;

- (b)  $y_{ii}^*(y_{kj}) = \delta_{ik}\delta_{lj}$  for  $l \leq j$ ;
- (c)  $y_{kj}$  lies in  $\mathfrak{B}^{(l)}$  for  $l < j$ ;
- (d) the elements  $y_{ij}$  are finitely linearly independent.

**Proof.** Suppose

$$\sum_{j=1}^n \sum_{i=1}^{k_j} a_{ij} y_{ij}^* = 0.$$

Then

$$\begin{aligned} 0 &= \sum_{j=1}^{n-1} \sum_i^* (E - c_n K^*) a_{ij} y_{ij}^* \\ &= E^* \sum_{j=1}^{n-1} \left(1 - \frac{c_n}{c_j}\right) \sum_i^* a_{ij} y_{ij}^* \end{aligned}$$

and since  $E^*$  is one-to-one, this gives a relation involving only  $n-1$  of the spaces  $\mathfrak{N}^{*(i)}$ . Hence by descent we arrive at a contradiction. By Theorem 1 for  $k=1$ , and Lemmas 1 and 4 we obtain (a) and (b) for  $j=1, l=1$ . Suppose that the system  $[y_{ij}]$  has been determined so as to satisfy (a), (b), and (c) for  $j < n$ . Then the intersection  $\mathfrak{B}^{(n-1)}$  of  $\mathfrak{B}^{(1)}, \dots, \mathfrak{B}^{(n-1)}$  is the orthogonal complement of the union of  $\mathfrak{N}^{*(1)}, \dots, \mathfrak{N}^{*(n-1)}$  and since the  $y_{ij}^*$  are linearly independent, there are points  $y_{in}$  in  $\mathfrak{B}^{(n-1)}$  such that (b) holds for  $l=j=n$ . Property (a) holds for  $j=n$ , by the same argument as before. Property (d) follows at once from (b).

**THEOREM 4.** *The proper values of  $K$  have no finite accumulation point.*

**Proof.** Suppose  $(c_n)$  is a bounded infinite sequence of distinct proper values. Let  $\mathfrak{S}_n^*$  be the space spanned by  $\mathfrak{N}^{*(1)}, \dots, \mathfrak{N}^{*(n)}$ . Then  $(\mathfrak{S}_n^*)$  is a properly increasing sequence of finite-dimensional linear spaces, so each  $\mathfrak{S}_n^*$  contains a unit vector  $v_n^*$  at unit distance from  $\mathfrak{S}_{n-1}^*$ . The sequence  $(c_n v_n^*)$  is bounded, so  $(c_n K^* v_n^*)$  is compact. If  $y^*$  is in  $\mathfrak{N}^{*(i)}$ ,  $T_c^* y^* = E^*(1 - c/c_j)y^*$ , which is zero if  $c = c_j$ , so

$$(1) \quad T_{c_p}^* \mathfrak{S}_p^* \subset E^* \mathfrak{S}_{p-1}^*$$

Now for  $p > q$ , let

$$d_{pq} = \|c_p K^* v_p^* - c_q K^* v_q^*\| = \|E^* v_p^* - T_{c_p}^* v_p^* - E^* v_q^* + T_{c_q}^* v_q^*\|,$$

so by (1)

$$d_{pq} = \|E^* v_p^* - E^* u^*\|, \quad \text{where } u^* \text{ is in } \mathfrak{S}_{p-1}^* \text{ and } \|v_p^* - u^*\| = 1.$$

Since the inverse of  $E^*$  is bounded, by Lemma 8, this contradicts the compactness of  $(c_n K^* v_n^*)$ .

Since the range of  $T_c^*$  may vary with  $c$ , we state properties of the inverse of  $T_c^*$  as follows.

**THEOREM 5.** *If  $c_0$  is not a proper value of  $K$ , and  $(c_n)$  and  $(y_n^*)$  are sequences such that  $\lim c_n = c_0$ ,  $\lim T_{c_n}^* y_n^* = x_0^*$ , then  $y_n^*$  tends to the unique solution  $y_0^*$  of  $T_{c_0}^* y^* = x_0^*$ . Consequently if  $T_c^* y^*(c) = x^*(c)$ , and  $x^*(c)$  is continuous (differentiable) at  $c_0$ , then  $y^*(c)$  is continuous (differentiable) at  $c_0$ .*

**Proof.** Suppose first that  $(y_n^*)$  is bounded. Then  $\lim (T_{c_n}^* y_n^* - T_{c_0}^* y_n^*) = 0$  so  $\lim T_{c_0}^* y_n^* = x_0^*$ , and hence  $\lim y_n^* = R x_0^*$ , where  $R$  is the inverse of  $T_{c_0}^*$ . If  $\lim \|y_n^*\| = \infty$ , set  $v_n^* = y_n^* / \|y_n^*\|$ . Then  $\lim T_{c_n}^* v_n^* = 0$ , so by the first case  $\lim v_n^* = 0$ , which is a contradiction.

With the help of the last theorem we see that a necessary and sufficient condition for  $c_0$  to be a proper value of  $K$  is that there exist sequences  $(c_n)$  and  $(y_n^*)$  such that:

- (a)  $\lim c_n = c_0$ ,
- (b)  $\|y_n^*\| = 1$ ,
- (c)  $\lim T_{c_n}^* y_n^* = 0$ .

This suggests the following definitions:

- (I)  $c = \infty$  is a *singular value* for  $K$  in case there exist sequences  $(c_n)$  and  $(y_n^*)$  such that (a'), (b), and (c) hold, where (a') means:  $\lim c_n = \infty$ .
- (II)  $c_0$  is a *proper value of order  $\mu$*  for  $K$  in case  $\mu$  is the maximum order of vanishing of  $T_c^* y^*(c)$ , where  $y^*(c)$  is a polynomial in  $c$ , not vanishing at  $c_0$ .

**THEOREM 6.** *If  $c = 1$  is a proper value for  $K$ , it is a proper value of order  $\nu$ , where  $\nu$  is the integer given by Theorem 2.*

**Proof.** It is readily verified by induction that  $K^*$  (as well as  $E^*$ ) maps  $\mathfrak{N}_k^*$  onto  $\mathfrak{N}_k^*$  one-to-one. Denoting by  $D$  the operation of differentiation with respect to  $c$ , we have

$$D^k T_c^* y^*(c) = T_c^* D^k y^*(c) - k K^* D^{k-1} y^*(c).$$

Hence if  $c = 1$  is a proper value of order  $\mu$ , there is a polynomial  $y^*(c)$  such that  $0 \neq y^*(1) \in \mathfrak{N}_1^*$ , and by induction  $D^k y^*(1) \in \mathfrak{N}_{k+1}^* - \mathfrak{N}_k^*$  for  $k < \mu$ . Hence  $\mu \leq \nu$ . To show that  $\mu = \nu$ , we set  $y^*(c) = \sum_{j=1}^{\nu} (c-1)^{j-1} \eta_j^*$ , where  $\eta_j^* \in \mathfrak{N}_j^* - \mathfrak{N}_{j-1}^*$  and  $T_1^* \eta_j^* = K^* \eta_{j-1}^*$ , so that no  $\eta_j^* = 0$ , and  $T_c^* y^*(c) = -(c-1)^\nu K^* \eta_\nu^*$ .

We next consider a decomposition of  $K$  relative to a proper value, which we take for convenience to be  $c = 1$ . In view of the definition of the spaces  $\mathfrak{N}_i^*$ , there exists a basis  $[\theta_{ij}^* | j = 1, \dots, p_i; i = 1, \dots, \nu]$  for  $\mathfrak{N}_\nu^*$  such that  $[\theta_{ij}^* | j = 1, \dots, p_i; i = 1, \dots, k]$  is a basis for  $\mathfrak{N}_k^*$ , and moreover

$$(2) \quad (E^* - K^*) \theta_{i+1,j}^* = E^* \theta_{ij}^* \quad \text{for } j = 1, \dots, p_{i+1}, i = 1, \dots, \nu - 1.$$

Note that when the basis  $[\theta_{ij}^*]$  is displayed by columns, the index  $i$  ranges from 1 to  $q_j$ , and  $j$  ranges from 1 to  $p_1$ . Choose  $\eta_{ij}$  from  $\mathfrak{N}_j$  so that

$$(3) \quad \theta_{ij}^*(\eta_{kl}) = \delta_{ik}\delta_{jl},$$

and set

$$Q_j(y) = \sum_{i=1}^{q_j} \theta_{ij}^*(y)\eta_{ij}, \quad Q = \sum_{j=1}^{p_1} Q_j,$$

$$Q_j^*(y^*) = \sum_{i=1}^{q_j} y^*(\eta_{ij})\theta_{ij}^*,$$

$$(4) \quad G_j = Q_jK, \quad G = \sum_{j=1}^{p_1} G_j, \quad H = K - G.$$

Then clearly  $Q^*$  projects  $\mathfrak{Y}^*$  onto  $\mathfrak{N}_r^*$ , and  $Q_j^*$  projects  $\mathfrak{Y}^*$  onto the subspace of  $\mathfrak{N}_r^*$  corresponding to a single proper vector  $\theta_{1j}^*$  by means of the relations (2).

**THEOREM 7.** *The decomposition of  $K$  given in (4) has the following properties:*

- (a) each  $G_j$  has only one independent proper vector  $\theta_{1j}^*$ , which corresponds to the proper value  $c=1$ ;
- (b)  $G$  has only the proper value  $c=1$ , and the null-spaces  $\mathfrak{N}_k^*$  for  $G$  are the same as those for  $K$ ;
- (c)  $c = \infty$  is not a singular value for  $G$ ;
- (d)  $c=1$  is not a proper value for  $H$ ;
- (e)  $G_i^*y^*=0$  for every  $y^*$  satisfying  $E^*y^*=G^*y_i^*$  for some  $y_i^*$  and some  $j \neq i$ ;
- (f)  $H^*y^*=0$  for every  $y^*$  satisfying  $E^*y^*=G^*y_i^*$  for some  $y_i^*$ ;
- (g) if  $c$  is a proper value for  $K$  and  $c \neq 1$ , then  $c$  is a proper value for  $H$ , and conversely.

**Proof.** If  $(E^* - cG^*)y^* = 0$ , it follows from (2) and the fact that  $E^*$  is one-to-one that  $y^*$  is a linear combination of  $\theta_{1j}^*, \dots, \theta_{q_j, j}^*$ , and by another application of (2) that  $c=1$  and  $y^*$  is a multiple of  $\theta_{1j}^*$ . This proves (a). To prove (b), we observe that  $Q^*$  projects  $\mathfrak{Y}^*$  onto  $\mathfrak{N}_r^*$ , and from (2) that  $K^*$  maps  $\mathfrak{N}_r^*$  onto  $\mathfrak{M}_r^*$  one-to-one, so  $G^*$  maps  $\mathfrak{Y}^*$  onto  $\mathfrak{M}_r^*$ , and  $G^* = K^*$  on  $\mathfrak{N}_r^*$ . Thus if  $(E^* - cG^*)y^* = 0$ ,  $y^*$  is in  $\mathfrak{N}_r^*$ , and  $(c-1)E^*y^* = c(E^* - G^*)y^* = c(E^* - K^*)y^*$ , so if  $c \neq 1$ ,  $y^*$  is in  $\mathfrak{N}_{r-1}^*$ . Proceeding by descent, we finally find  $y^* = 0$ . The remainder of (b) follows readily. If we suppose that  $c = \infty$  is a singular value for  $G$ , there must exist sequences  $(c_n)$  and  $(y_n^*)$  with  $\lim c_n = \infty$ ,  $\|y_n^*\| = 1$ ,  $\lim (E^* - c_n G^*)y_n^* = 0$ . Since the sequence  $(E^*y_n^*)$  is bounded,  $(c_n G^*y_n^*)$  is likewise bounded and lies in the finite-dimensional space  $\mathfrak{M}_r^*$ , so we may suppose that it converges to a point  $x^*$  in  $\mathfrak{M}_r^*$ . Then  $x^* = E^*y^*$  where  $y^*$  is in  $\mathfrak{N}_r^*$ , and since  $E^*$  has a continuous inverse,  $\lim y_n^* = y^*$ , so  $\|y^*\| = 1$ . But  $\lim G^*y_n^* = 0 = G^*y^*$ , and since  $G^*$  gives a one-to-one correspondence between  $\mathfrak{N}_r^*$  and  $\mathfrak{M}_r^*$ , we have  $y^* = 0$ , which is a contradiction. This proves (c). To secure (d) we observe that if  $0 = (E^* - H^*)y^* = (E^* - K^*)y^* + G^*y^*$ , then  $y^*$  is in  $\mathfrak{N}_r^*$  since  $G^*y^*$  is in  $\mathfrak{M}_r^*$ , so  $H^*y^* = 0$ ,  $E^*y^* = 0$ ,

$y^* = 0$ . We next prove (e) and (f). If  $E^*y^* = G_j^*y_1^*$ , we have from (2) (setting  $\theta_{0j}^* = 0$ )

$$(5) \quad y^* = \sum_{i=1}^{q_j} y_1^*(\eta_{ij}) (\theta_{ij}^* - \theta_{i-1,j}^*),$$

since  $E^*$  is one-to-one, and

$$(6) \quad G_j^*y_1^* = \sum_{i=1}^{q_j} y_1^*(\eta_{ij}) K^* \theta_{ij}^*.$$

So by (5) and (6) and (3),

$$G^*y^* = \sum_{i=1}^{q_j} \sum_{m=1}^{q_i} y_1^*(\eta_{ij}) [\theta_{ij}^*(\eta_{mi}) - \theta_{i-1,j}^*(\eta_{mi})] K^* \theta_{mi}^* = \delta_{ji} K^* y^*,$$

and hence  $H^*y^* = 0$ . Property (f) follows immediately. Finally, to prove (g), we observe that if  $c \neq 1$ ,  $y^* \neq 0$ , and  $(E^* - cK^*)y^* = 0$ ,  $G^*y^* = E^*y_1^*$ , where  $y_1^*$  is in  $\mathfrak{N}_r^*$ , and so  $H^*y_1^* = 0$ , by (f). Hence

$$\begin{aligned} 0 &= E^*y^* - cG^*y^* - cH^*y^* = E^*y^* - cE^*y_1^* - cH^*y^* + c^2H^*y_1^* \\ &= (E^* - cH^*)(y^* - cy_1^*). \end{aligned}$$

Now if  $y^* = cy_1^*$  we would have  $0 = (E^* - cK^*)y_1^* = (E^* - cG^*)y_1^*$ , and this cannot happen for  $c \neq 1$  by part (b) of the theorem. So  $c$  is a proper value of  $H$ . For the converse, let  $(E^* - cH^*)y^* = 0$  with  $y^* \neq 0$ . Then  $y^*$  is not in  $\mathfrak{N}_r^*$ , and there is a finite sequence  $y_1^*, \dots, y_k^*$ , such that  $G^*y^* = E^*y_1^*$ ,  $(E^* - K^*)y_i^* = E^*y_{i+1}^*$  for  $i = 1, \dots, k-1$ , each  $y_i^*$  is in  $\mathfrak{N}_r^*$ ,  $y_k^*$  is in  $\mathfrak{N}_1^*$ , and so

$$(E^* - cK^*) \left( y^* + \sum_{i=1}^k \alpha_i y_i^* \right) = E^* \left[ -cy_1^* + (1-c) \sum_{i=1}^k \alpha_i y_i^* + c \sum_{i=1}^{k-1} \alpha_i y_{i+1}^* \right].$$

The expression in square brackets vanishes if  $(1-c)\alpha_1 = c$ ,  $(1-c)\alpha_i = -c\alpha_{i-1}$  for  $i = 2, \dots, k$ .

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