DIFFERENTIALS AND METRICS ON RIEMANN SURFACES(1)

BY

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Introduction. In this paper we show how to finite-dimensional spaces of differentials on a Riemann surface can be associated a finite collection of Riemannian metrics whose curvatures are closely related to the zeros of the differentials on the surface. In particular, we show that the Weierstrass points of a compact Riemann surface can be characterized as points of zero curvature of certain "naturally defined" metrics on the surface. The main theorem and application are in Part II; in Part I we have collected all the preliminary details. In the conclusion we point out the origin of this study and a possible direction for further research.

Part I

Let \( X \) be a Riemann surface, \( A \) the family of admissible local coordinates on \( X \). Each \( \alpha \in A \) is a homeomorphism of an open set \( U_\alpha \subset X \) onto an open set \( D_\alpha \subset \mathbb{C} \) and if also \( \beta \in A, \beta: U_\beta \to D_\beta \), then \( \beta \circ \alpha^{-1} \) is a complex analytic homeomorphism of \( \alpha(U_\alpha \cap U_\beta) \) onto \( \beta(U_\alpha \cap U_\beta) \). We use the notation \( U_{\alpha\beta} = U_\alpha \cap U_\beta, \quad D_{\alpha\beta} = \alpha(U_\alpha \cap U_\beta) \) and \( t_{\alpha\beta} = \beta \circ \alpha^{-1} \) on \( D_{\alpha\beta} \). The analytic homeomorphism \( t_{\alpha\beta}: D_{\alpha\beta} \to D_{\beta\alpha} \) is the transition function from the \( \alpha \) coordinate to the \( \beta \) coordinate. Note that \( t'_{\alpha\beta}(z) \neq 0 \) for each \( z \in D_{\alpha\beta} \). Here, and in the sequel, \( ' \) denotes the derivative of an analytic function.

Let \( m \) be an arbitrary integer and \( N \) an integer \( \geq 1 \).

Definition. A differential \( \phi \) of weight \( m \) and dimension \( N \) on \( X \) is a collection \( \{ \phi_\alpha \}_{\alpha \in A} \) where each \( \phi_\alpha \) is a (vector-valued) analytic function \( \phi_\alpha: D_\alpha \to \mathbb{C}^N \) such that for each \( p \in U_{\alpha\beta}, \)

\[
(1) \quad \phi_\alpha(\alpha(p)) = \phi_\beta(\beta(p))(t'_{\alpha\beta}(\alpha(p)))^m
\]

or, more simply

\[
(2) \quad \phi_\alpha = (\phi_\beta \circ t_{\alpha\beta})(t'_{\alpha\beta})^m \text{ on } D_{\alpha\beta}.
\]

The function \( \phi_\alpha \) is usually called the "local expression for \( \phi \)" and (2) expressed by

\[
(3) \quad \phi(z) \, dz^m \text{ is invariant.}
\]

If \( \phi \) is a differential of weight \( m \) and dimension \( N \) it has \( N \) components \( \phi_1, \ldots, \phi_N \) each of which is a differential of weight \( m \) and dimension 1. We denote the \( j \)th component of \( \phi_\alpha \) (\( 1 \leq j \leq N \)) as \( \phi_{\alpha,j} \) so that \( \phi_{\alpha,j} = \phi_{j,\alpha} \) in our notation. If we refer to a differential without specifying the dimension it is understood that the dimension is 1.

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By (2) above, if \( \phi \) is a differential of weight \( m \) and dimension 1, the order of the analytic function \( \phi_a \) at \( \alpha(p) \) is the same as the order of \( \phi_\beta \) at \( \beta(p) \). This common order is called the order of \( \phi \) at \( p \) and is denoted \( v_p(\phi) \). Thus \( v_p(\phi) \) is always an integer \( \geq 0 \) except in the case that \( \phi = 0 \) (i.e. \( \phi \) is identically zero) in which case \( v_p(\phi) = \infty \) for all \( p \in X \). We recall two properties of the order function \( v_p \) which are a direct consequence of the corresponding statements for analytic functions in the plane:

4. \( v_p(\phi_1 + \phi_2) \leq \min (v_p(\phi_1), v_p(\phi_2)) \)
   with equality if \( v_p(\phi_1) = v_p(\phi_2) \).

5. If \( v_p(\phi_1) = v_p(\phi_2) = n < \infty \), there is a complex number \( c \) such that \( v_p(\phi_1 - c\phi_2) > n \).

If \( p \in U_a \), the analytic function \( \phi_a \) can be expanded in a convergent power series about \( z_0 = \alpha(p) \),

6. \( \phi_a(x) = \sum_{n=0}^{\infty} a_n(x - z_0)^n \),
   and \( a_n = 0 \) for \( n < v_p(\phi) \) while \( a_n \neq 0 \) if \( n = v_p(\phi) \).

**Definition.** \( \phi \) is normalized for \( p, \alpha \) if in (6) \( a_n > 0 \) when \( n = v_p(\phi) \).

Clearly, given any \( \phi, p, \alpha \) there is a number \( c, |c| = 1 \) so that \( c\phi \) is normalized for \( p, \alpha \).

If \( \phi \) is a differential of weight \( m \) and dimension \( N \) then the “derivatives of \( \phi \)” in general are not differentials. In fact, by (2) we have

7. \( \phi_a' = (\phi_\beta' \circ t_{\beta a})(t_{\beta a})^{m+1} + (\phi_\alpha' \circ t_{\alpha a})m(t_{\alpha a})^m t_{\beta a} \) on \( D_{a\beta} \).

By \( \phi_a' \) we understand the function obtained by differentiating each of the \( N \) components of \( \phi_a \). More generally, by the chain rule, if \( k \geq 1 \),

8. \( \phi_a^{(k)} = (\phi_\beta^{(k)} \circ t_{\beta a})(t_{\beta a})^{m+k} + \sum_{j=0}^{k-1} (\phi_\beta^{(j)} \circ t_{\beta a})L_j \),

where \( L_j \) is a polynomial in \( t_{\beta a}^{(1)}, \ldots, t_{\beta a}^{(j+k)} \) with integer coefficients.

However, the derivatives of differentials can be brought into this framework to a certain extent by the following construction. Let \( e_1, \ldots, e_N \) be the standard orthonormal basis of \( \mathbb{C}^N \), \( e_i \) has 1 in the \( i \)th place and 0 elsewhere. Let \( \wedge \) denote exterior product. Now \( \wedge^2 \mathbb{C}^N \) can, and will, be identified with \( \mathbb{C}^{N(N-1)/2} \) and the standard orthonormal basis is then \( e_{ij} = e_i \wedge e_j, 1 \leq i < j \leq N \).

Consider \( \phi_a \wedge \phi_a' = \sum_{i<j} M_{ij,a} e_{ij} \) where

\[
M_{ij,a} = \det \left( \begin{array}{cc} \phi_{i,a} & \phi_{i,a}' \\ \phi_{j,a} & \phi_{j,a}' \end{array} \right)
\]

and similarly \( \phi_\beta \wedge \phi_\beta' = \sum_{i<j} M_{ij,\alpha} e_{ij} \). By (8) with \( k = 1 \), on \( D_{a\beta} \),

9. \[
M_{ij,a} = \det \left( \begin{array}{cc} (\phi_{i,\beta} \circ t_{\beta a})(t_{\beta a})^m, & (\phi_{i,\beta} \circ t_{\beta a})(t_{\beta a})^m \\ (\phi_{j,\beta} \circ t_{\beta a})(t_{\beta a})^{m+1} + (\phi_{i,\beta} \circ t_{\beta a})L_0, & (\phi_{j,\beta} \circ t_{\beta a})(t_{\beta a})^{m+1} + (\phi_{j,\beta} \circ t_{\beta a})L_0 \end{array} \right)
\]

or

10. \[
M_{ij,a} = (M_{ij,\beta} \circ t_{\beta a})(t_{\beta a})^{m+(m+1)}.
\]
In other words, we can define a differential $\phi \wedge \phi'$ of weight $2m + 1$ and dimension $N(N-1)/2$ by $(\phi \wedge \phi')_{i_1,\ldots,i_N} = M_{i_1,\ldots,i_N}$. The same type of argument shows that if $s$ is an integer, $1 \leq s \leq N - 1$ then $\phi = \phi \wedge \phi' \wedge \cdots \wedge \phi^{(s)}$ is a differential of weight $m + (m + 1) + \cdots + (m + s) = (s + 1)(2m + s)/2$ and dimension $C_{N,s+1} = N(N-1)\cdots(N-s)/(s+1)!$.

The components of $\Phi$ are indexed by $(s+1)$-tuples $(i) = i_1 i_2 \cdots i_{s+1}$ where $1 \leq i_1 < i_2 < \cdots < i_{s+1} \leq N$ and in a local coordinate $\alpha$, $\Phi_{(i),\alpha} = M_{i_1}^{(i)}$, where

$$
(M_{(i)})_{"a} = \det (\phi_{i_{i_a}}^{(k-1)})_{1 \leq k \leq s+1; 1 \leq \alpha \leq s+1}.
$$

With a differential of dimension $N$ we can associate a Riemannian metric on the surface $X$. If $u, v \in \mathbb{C}^N$ we denote, as usual, $(u, v) = \sum u_i \bar{v}_i$ and $|u|^2 = (u, u)$. If $f, g$ are functions on a plane open set $D$ with values in $\mathbb{C}^N$, $(f, g), |f|^2$ are, respectively, given by $(f, g)(z) = (f(z), g(z)), |f|^2(z) = |f(z)|^2$ for each $z \in D$. Let $\phi$ be a differential of weight $m$ and dimension $N$, and $m \neq 0$. For each $\alpha \in A$ define $\rho_\alpha = |\phi_\alpha|^{2m} = (\phi_\alpha, \phi_\alpha)^{1/m}$. Thus $\rho_\alpha \geq 0$ for each $z \in D_\alpha$ and by (2),

$$
\rho_\alpha = (\rho_g \circ \phi_\alpha)^{|f_\alpha|^2},
$$

or "$\rho(z)|dz|^2$ is invariant." Thus $\rho = \{\rho_\alpha\}_{\alpha \in A}$ defines a Riemannian metric on $X$. More precisely, $\rho$ defines a Riemannian metric on $X-Z(\phi)$ where

$$Z(\phi) = \{p \in X \mid \phi_\alpha(\alpha(p)) = 0 \text{ if } p \in U_\alpha\},$$

since, for every $p \in X-Z(\phi)$, $\rho_\alpha(p) > 0$ if $p \in U_\alpha$. Since each $\phi_\alpha$ is analytic, as long as $\phi$ is not the differential which is identically 0, $Z(\phi)$ is a discrete subset of $X$ and $X-Z(\phi)$ is a surface. We now compute the Gaussian curvature $K$ of the metric $\rho$ associated with $\phi$. By a standard formula of differential geometry, if $p \in X-Z(\phi)$, $p \in U_\alpha$,

$$
K(p) = -\frac{1}{2\rho_\alpha} \Delta \log \rho_\alpha \text{ evaluated at } \alpha(p)
$$

where $\Delta$ is the Laplacian $\partial^2/\partial x^2 + \partial^2/\partial y^2, z = x + iy$ being the local variable in the plane open set $D_\alpha$. Introducing

$$
\partial/\partial z = \frac{1}{2}(\partial/\partial x - i(\partial/\partial y)), \quad \partial/\partial \bar{z} = \frac{1}{2}(\partial/\partial x + i(\partial/\partial y)),
$$

we have $\Delta = 4(\partial^2/\partial z \partial \bar{z})$. Now, if $f, g$ are analytic functions on a plane open set $D$ with values in $\mathbb{C}^N$, then $(\partial/\partial z)(f, g) = (f', g)$ and $(\partial/\partial \bar{z})(f, g) = (f, g')$. From this, and the definition of $\rho_\alpha = (\phi_\alpha, \phi_\alpha)^{1/m}$ we obtain from (13) that

$$
K \circ \alpha^{-1} = -(2/m)(\phi_\alpha, \phi_\alpha)^{-(2+1/m)^2}(\phi_\alpha, \phi_\alpha)(\phi_\alpha', \phi_\alpha') - (\phi_\alpha, \phi_\alpha')^2
$$

on $\alpha(U_\alpha - Z(\phi))$.

The quantity inside the braces is just $|\phi_\alpha \wedge \phi_\alpha'|^2$ so that we can symbolically write the curvature as

$$
K = -(2/m)|\phi|^{-(4 + 2/m)}|\phi' \wedge \phi'|^2.
$$

In particular we note the following: If $m > 0$ then $K \leq 0$ while if $m < 0$, $K \geq 0$, and in either case $K(p) = 0$ if and only if $\phi \wedge \phi'$ has a zero at $p$. 

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Part II

Let \( H \) be a (nonzero) finite-dimensional vector space (over \( \mathbb{C} \)) of differentials of weight \( m \) (and dimension \( 1 \)) on \( X \) and set \( N = \dim H \). For each \( p \in X \) consider the set of integers

\[
R_p = \{ r \mid r \geq 0, r = v_p(\phi) \text{ for some } \phi \in H \}.
\]

**Proposition.** For each \( p \in X \), \( R_p \) is a finite sequence of \( N \) integers \( R_p = \{ r_1 < r_2 < \cdots < r_N \} \). If \( \phi_1, \ldots, \phi_N \) are chosen in \( H \) such that \( v_p(\phi_i) = r_i \), then \( \{ \phi_1, \ldots, \phi_N \} \) is a basis of \( H \).

**Proof.** First we remark that if \( \{ \psi_j \} \) is an indexed family of nonzero elements of \( H \) and \( v_p(\psi_j) \neq v_p(\psi_k) \) for any two indices \( j \neq k \) and some fixed \( p \in X \), then \( \{ \psi_j \} \) is linearly independent. For, if \( \sum c_j \psi_j \) is a finite linear combination and \( c_k \neq 0 \) for some index \( k \), then, by the property (4) of the order function, \( v_p(\sum c_j \psi_j) \leq v_p(\psi_k) < \infty \) so that \( \sum c_j \psi_j \neq 0 \). In particular, since \( H \) has finite dimension \( N \), \( R_p \) is a finite sequence, \( r_1 < r_2 < \cdots < r_M \), \( M \leq N \). Choose \( \phi_i \in H \) such that \( v_p(\phi_i) = r_i \). We will show that every \( \phi \in H \) is a linear combination of \( \phi_1, \ldots, \phi_M \) which will prove the proposition. Given \( \phi \in H \), \( \phi \neq 0 \), \( v_p(\phi) = r \), for some \( j, 1 \leq j \leq M \). For a suitable constant \( c_j \) we have \( v_p(\phi - c_j \phi_j) > r \). Either \( \phi - c_j \phi_j = 0 \) or we can apply the same procedure to \( \phi - c_j \phi_j \). Eventually we obtain for suitable numbers \( c_i \),

\[
v_p\left( \phi - \sum c_i \phi_i \right) > r_M
\]

which gives \( \phi - \sum c_i \phi_i = 0 \), so that every element of \( H \) is a linear combination of \( \phi_1, \ldots, \phi_M \).

In addition to our original assumptions concerning \( H \), we now further assume that \( H \) is endowed with an inner product giving it the structure of a Hilbert space. In this case the above proposition can be sharpened.

**Proposition.** Let \( p \in X \), \( \alpha \) a local coordinate, \( p \in U_\alpha \), \( R_p = \{ r_1 < r_2 < \cdots < r_N \} \).

There is a unique basis \( \{ \phi_1, \ldots, \phi_N \} \) of \( H \) which is

(a) an orthonormal basis of \( H \),

(b) each \( \phi_i \) is normalized for \( p, \alpha \),

(c) \( v_p(\phi_i) = r_i \), \( 1 \leq i \leq N \).

**Proof.** Let \( \psi_1, \ldots, \psi_N \) be a basis of \( H \) such that \( v_p(\psi_i) = r_i \). Apply the Gram-Schmidt process to the sequence \( \psi_N, \ldots, \psi_1 \) to obtain an orthonormal basis \( \theta_N, \ldots, \theta_1 \) of \( H \). The \( \theta \)'s are given by

\[
\theta_N = c_{NN} \psi_N \\
\vdots \\
\theta_i = c_{iN} \psi_N + \cdots + c_{ii} \psi_i \\
\vdots
\]

and for each \( i \), \( c_i \neq 0 \). Hence \( v_p(\theta_i) = v_p(\psi_i) = r_i \). Now choose numbers \( d_i \), \( |d_i| = 1 \) so that \( \phi_i = d_i \theta_i \) is normalized for \( p, \alpha \). Then \( \{ \phi_1, \ldots, \phi_N \} \) is a basis of \( H \) satisfying
properties (a), (b), (c). To show uniqueness, suppose \( \lambda_1, \ldots, \lambda_N \) is another basis with these properties. Then \( \lambda_i = \sum_j u_{ij} \phi_j \) where \( (u_{ij}) \) is a unitary matrix. By (c) \( u_{ij} = 0 \) if \( j < i \) and \( u_{ii} \neq 0 \), while by (b) \( u_{ii} > 0 \). But such a unitary matrix is necessarily the identity matrix so that each \( \lambda_i = \phi_i \).

A basis with the properties (a), (b), (c) will be called a normalized \( p, \alpha \) basis of \( H \).

To study the sequence \( R_p = \{r_i(p)\}_{1 \leq i \leq N} \) we introduce, for \( 1 \leq j \leq N \),

\[
w_j(p) = \sum_{i=1}^{j} (r_i(p) - (i-1)) \quad \text{and} \quad W_j = \{ p \in X \mid w_j(p) > 0 \}.
\]

Clearly, \( W_1 \subset W_2 \subset \cdots \subset W_N \). Let \( W = W_N \), \( w(p) = w_N(p) \). The set \( W \) can be called the Weierstrass points of \( H \) and \( w(p) \) the multiplicity of \( p \) as a Weierstrass point. Indeed, if \( X \) is a compact Riemann surface and \( H \) the space of abelian differentials of the first kind (differentials of weight 1) then the set \( W \) of \( H \) is precisely the set of classical Weierstrass points as defined by Hurwitz (see [2, in particular pp. 395–402]).

Let \( \{\phi_1, \ldots, \phi_N\} \) be any orthonormal basis of \( H \). We now make the assumption that the weight \( m \) of the differentials in \( H \) is \( \neq 0 \). We associate to the orthonormal basis the \( N \)-dimensional differential \( \langle \phi_1, \ldots, \phi_N \rangle \) which in turn determines the metric \( \rho \), as in Part I. But this metric \( \rho \) depends only on \( H \), not on the orthonormal basis chosen. For if \( \{\psi_1, \ldots, \psi_N\} \) is another orthonormal basis determining the metric \( \sigma \), then in a local coordinate \( \alpha \) we have for \( z \in D_\alpha \),

\[
\rho_{\alpha}^m(z) = \sum_{j=1}^{N} |\phi_{j,\alpha}(z)|^2 \quad \text{and} \quad \sigma_{\alpha}^m(z) = \sum_{i=1}^{N} |\psi_{i,\alpha}(z)|^2.
\]

But \( \psi_i = \sum_{j=1}^{N} u_{ij} \phi_j \) for a suitable unitary \( (u_{ij}) \) hence

\[
\sigma_{\alpha}^m(z) = \sum_{i=1}^{N} \left( \sum_{j} u_{ij} \phi_j(z) \right) \left( \sum_{k} \bar{u}_{ik} \phi_k(z) \right) = \sum_{j,k} u_{ij} \bar{u}_{ik} \phi_j(z) \phi_k(z) = \rho_{\alpha}^m(z) \quad \text{and so } \sigma_{\alpha}(z) = \rho_{\alpha}(z).
\]

This metric depending only on \( H \) will be called \( \rho_0 = \rho_0(H) \) and the corresponding curvature function will be denoted \( K_0 \). We obtain further metrics \( \rho_s \), \( 0 \leq s \leq N-1 \), with corresponding curvatures \( K_s \) as follows. Let again \( \phi = (\phi_1, \ldots, \phi_N) \) be the \( N \)-dimensional differential obtained from an orthonormal basis. Then for each \( s \), \( 1 \leq s \leq N-1 \) we can form the \( C_{N+s+1} \)-dimensional differential \( \phi \wedge \phi' \wedge \cdots \wedge \phi^{(s)} \) of weight \( (s+1)(2m+s)/2 \) which again gives rise to a metric \( \rho_s \), provided \( 2m+s \neq 0 \), depending only on \( H \), not on the particular orthonormal basis—for the exterior powers of a unitary matrix are still unitary. We still have to make precise where the metrics are defined, as they are only defined in Part I on \( X-Z(\phi) \), \( Z(\phi) \) being the discrete set of zeros of the \( N \) dimensional differential \( \phi \). We summarize the main results in a theorem.
Theorem. Let $H$ be a finite-dimensional Hilbert space of differentials of weight $m$ on a Riemann surface $X$. Let $N = \dim H, 1 \leq N < \infty$. Suppose $2m + s \neq 0$ for $0 \leq s \leq N - 1$. Then to each integer $s, 0 \leq s \leq N - 1$, there is defined a Riemannian metric $\rho_s$ on $X - W_{s+1}$ where $W_1, \ldots, W_N$ are the Weierstrass points of $H$ on $X$. The curvature $K_s$ of $\rho_s$ satisfies $K_s \leq 0$ if $m > 0$ and $K_s \geq 0$ if $m < 0$ and furthermore $K_s(p) = 0$ if and only if $p \in W_{s+2} - W_{s+1}$.

Proof. Let $p \in X$, $\alpha$ a local coordinate, $p \in U_\alpha$. Choose $\phi_1, \ldots, \phi_N$ as the normalized $p, \alpha$ basis of $H$ and set $\phi = (\phi_1, \ldots, \phi_N)$. Thus, for $1 \leq i \leq N$,

$$\phi_{i,\alpha}(z) = \sum_{n=0}^{\infty} a_{in}(z-z_0)^n$$

the power series all converging for $z$ sufficiently near $z_0 = \alpha(p)$ in $D_\alpha$. By the normalization,

$$a_{in} = 0 \text{ if } n < r_i(p) \text{ and } a_{in} > 0 \text{ if } n = r_i(p).$$

From now on the coordinate $\alpha$ will be fixed and for greater clarity we will write simply $\phi_i$ instead of $\phi_{i,\alpha}$. Recall that $0 \leq r_1(p) < r_2(p) < \cdots < r_N(p)$ so that certainly $a_{in} = 0$ if $n < i-1$ and $a_{i,i-1} > 0$. Fix $s, 0 \leq s \leq N - 1$ and let $\phi = \phi \wedge \phi' \wedge \cdots \wedge \phi^{(s)}$. By (11) the $i$th component of $\Phi$ at $z_0 = \alpha(p)$ is

$$M_{i,ij}(z_0) = \det ((k-l)!a_{ik,k-1})$$

where $1 \leq k \leq s + 1$, $1 \leq j \leq s + 1$, $(i) = i_1 \cdots i_{s+1}$, $1 \leq i_1 < i_2 < \cdots < i_{s+1} \leq N$. If $i_{s+1} > s + 1$ then for all $k, 1 \leq k \leq s + 1$, $k < i_{s+1} - 1$ so that $a_{i_{s+1},k-1} = 0$ and $M_{i,ij}(z_0) = 0$. Thus the only possibly nonvanishing component of $\Phi$ at $z_0$ is $M_{1,2,\ldots,s+1}(z_0) = \det ((k-l)!a_{i_{s+1},k-1})$ which by the normalization is a triangular determinant with value $M_{1,2,\ldots,s+1}(z_0) = \prod_{k=1}^{s+1} (k-1)!a_{ik,k-1}$ which is $\geq 0$ and is $=0$ if and only if $a_{i_{s+1},k-1} = 0$ for some $k, 1 \leq k \leq s + 1$, but this is if and only if $r_{s+1}(p) > s$ or $p \in W_{s+1}$. Thus the metric $\rho_s$ fails to be positive at $p$ if and only if $p \in W_{s+1}$, hence $\rho_s$ defines a Riemannian metric on $X - W_{s+1}$.

This proves the first part of the theorem. The statement about the sign of the curvature was already observed in Part I. All that remains is to prove the statement about the vanishing of $K_s$. Keeping the notation introduced so far in the course of the proof, and by the formulas of Part I, we have, setting $b = (s+1)(2m+s)/2$, since this is the weight of $\Phi$,

$$K_s(p) = -\frac{2}{b} \langle \Phi, \Phi \rangle^{-(2+1/b)} \langle (\Phi, \Phi)(\Phi', \Phi') - (\Phi, \Phi')(\Phi', \Phi) \rangle$$

where all the quantities on the right are evaluated at $z_0 = \alpha(p)$.

We have already found

$$\langle \Phi, \Phi \rangle(z_0) = |M_{1,2,\ldots,s+1}(z_0)|^2$$

$$= \left( \prod_{k=1}^{s+1} (k-1)!a_{ik,k-1} \right)^2.$$
Now we compute the components of $\Phi'$ at $z_0$. These are just $M'_0(z_0)$ which, taking into account the rule for differentiating a determinant and the fact that if two rows are identical the determinant vanishes, we obtain

$$M'_0(z_0) = \det \begin{pmatrix} \phi_{1} & \cdots & \phi_{s+1} \\ \phi'_{1} & \cdots & \phi'_{s+1} \\ \vdots & & \vdots \\ \phi^{(s-1)} & \cdots & \phi^{(s-1)} \\ \phi^{(s+1)} & \cdots & \phi^{(s+1)} \\ \end{pmatrix}$$

evaluated at $z_0$.

Again, because of the normalization, in each of these determinants all terms above the diagonal vanish (at $z_0$) and the last column vanishes if $i_s + 1 > s + 2$. In case $i_s + 1 = s + 2$ then $(i) = 1, \ldots, j, \ldots, s + 2$ where the $j$th index is deleted, $1 \leq j \leq s + 1$. But if $j \neq s + 1$, the $(jj)$ entry along the diagonal is $\phi_{i_s+1,i_s-1}(z_0) = (j - 1) a_{j+1,j-1} = 0$ so that again the determinant vanishes. Thus the only possibly nonzero coordinates in $\Phi'(z_0)$ are

$$M'_{s+1}(z_0) = \left( \prod_{k=1}^{s} (k-1)! a_{k,k-1} \right) (s+1)! a_{s+1,s+1}$$

and

$$M'_{s+2}(z_0) = \left( \prod_{k=1}^{s} (k-1)! a_{k,k-1} \right) (s+1)! a_{s+2,s+1}.$$
Proof. Since $m = 1 > 0$ we know $K_0(p) \leq 0$ and $K_0(p) = 0$ if and only if $p \in W_2$, that is, there is an abelian differential with a simple zero at $p$ which by the Riemann-Roch theorem is equivalent to saying that there is a meromorphic function on $X$, analytic on $X - \{p\}$ and having a double pole at $p$, implying $X$ hyperelliptic and $p$ a Weierstrass point—and this argument is reversible. This proves the theorem.

At the opposite extreme to hyperelliptic surfaces are those “general surfaces” with $g^3 - g$ Weierstrass points each with $R_0 = 1, 2, \ldots, g - 1, g + 1$. In this case the metrics $p_0, \ldots, p_{g - 2}$ are everywhere defined on $X$ with everywhere negative curvature while $p_{g - 1}$ is also defined on all $X$ and the curvature vanishes precisely at the Weierstrass points. In other cases though, the situation is not so simple and we can only assert that each $p_s, 0 \leq s \leq g - 1$, is defined on $X - W_{s + 1}$ and the curvature vanishes at $W_{s + 2} - W_{s + 1}$.

Conclusion. We conclude by remarking on the original motivation for the study of these metrics. If $X$ is a compact Riemann surface of genus $g \geq 2$ then “in general” $X$ has no automorphisms other than the identity and in any case there are at most $84(g - 1)$, see [2]. The group of automorphisms of $X$ is studied by considering the linear unitary representation afforded by the space $H$ of abelian differentials of the first kind, [3]. Since this representation is unitary, all automorphisms induce isometries on $X$ with respect to the metrics $p_s, 0 \leq s \leq g - 1$ and so the curvatures $K_s$ are invariant.

In particular, the maxima, minima and other critical points of $K_s$ are invariant so that if certain information were available concerning the critical points, e.g. are they nondegenerate, isolated, etc., this would perhaps shed new light on the group of automorphisms. However, the study of the critical points of $K_s$ seems to be difficult and at present no definitive statements can be made.

Bibliography


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