CONNECTED SIMPLE SYSTEMS AND
THE CONLEY INDEX OF ISOLATED INVARIANT SETS

BY

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Dedicated to the memory of Charles C. Conley

ABSTRACT. The object of this paper is to present new and simplified proofs for most of the basic results in the index theory for flows. Simple, explicit formulae are derived for the maps which play a central role in the theory. The presentation is self-contained.

1. Introduction. Some dynamical processes in physics, chemistry and biology can be described by differential equations depending on parameters which cannot be determined with an arbitrary degree of precision. For the study of such systems it is important to determine those structural properties which remain invariant under (small) perturbations. Many of these properties can be described in terms of an index theory which has been developed by Conley [3]. Although the basic ideas have been developed over many years, complete proofs for some of the central theorems are only recently available (see e.g. Kurland [6, 7, 8], Conley and Zehnder [4] and Franzosa [5]).

The object of this paper is to present new and simplified proofs for a number of the basic results in the index theory for isolated invariant sets in flows. Furthermore, explicit and simple formulae are derived for those maps which play a central role in the theory, in particular for the identification map between index spaces (formula (4.3)), for the connection map in the coexact sequence (formulae (5.9) and (5.6)) and for the homotopy equivalence in the continuation theorem (formula (6.19)). In previous papers only the existence of these maps has been proved and the available proofs are widely spread in the literature and much more complicated. For the purpose of completeness, this paper gives a self-contained presentation of the basic results in the index theory for flows.

In two preliminary sections we collect some elementary notions and results from homotopy theory (§2) and from the general theory of flows on topological spaces (§3). In the main part of this paper we introduce the fundamental concepts in the index theory for isolated invariant sets (§4), prove the existence and uniqueness of a
long coexact sequence associated with an attractor-repeller pair (§5) and establish the basic continuation results for the Conley index (§6).

The starting point for this work was an essential simplification of the proof that any two index pairs for a given isolated invariant set are homotopically equivalent after collapsing the exit set (Lemma 4.7). This result allows a very simple proof of the fact that the Conley index of an isolated invariant set is a connected simple system (Lemma 4.8 and Theorem 4.10) and leads to further simplifications in the §§5 and 6.

A unique coexact sequence for an attractor-repeller pair can be obtained in two steps. The first step is to show that any index pair can be transformed into an NDR-pair (§5.1) so that general results from homotopy theory can be applied to obtain the existence of a long coexact sequence of index spaces. The second step is then to show that all the maps in this sequence induce morphisms of connected simple systems which are independent of the choice of the index pair (Theorem 5.7).

In §6 we begin with some general results on parametrized local flows $X \times \Lambda$ and in particular we make precise what we mean by a continuous family $\sigma(\lambda)$ of isolated invariant sets in $X \times \lambda$ (§6.1). The continuation theorem is then phrased for such a family $\sigma(\lambda)$ and consists of three parts. The first part is to show that the injection map of an index space for $\sigma(\lambda)$ in $X \times \lambda$ into the corresponding index space for the global isolated invariant set $S = \bigcup_{\lambda \in \Lambda} \sigma(\lambda)$ in $X \times \Lambda$ induces a morphism between connected simple systems which is independent of the choice of the index pair (Proposition 6.5). The second step is to show that this injection map is locally a homotopy equivalence and the corresponding morphism of connected simple systems is therefore an isomorphism (Theorem 6.7). This local result allows a global continuation of the Conley index in every compact connected component of the parameter space $\Lambda$ by means of a sequence of compact subsets of $\Lambda$ to each of which the local continuation theorem applies. However, different sequences may lead to different identifications between "far away" index spaces. We show that any two of these connecting equivalences between index spaces are in fact homotopic if $\Lambda$ is simply connected. This means that the "global Conley index" $I(\sigma, X, \Lambda)$ consisting of the index spaces for $\sigma(\lambda)$ in $X \times \lambda$ together with the above connecting equivalences is a connected simple system provided that $\Lambda$ is simply connected (Theorem 6.9). Finally, things are put together to obtain a long coexact sequence for the global Conley index associated with an attractor-repeller pair in the case that $\Lambda$ is simply connected (Theorem 6.10).

2. Homotopy theory. In this preliminary section we recall some basic concepts and results from homotopy theory. We will work in the category of pointed topological spaces and continuous, base point preserving maps. In order to avoid unnecessary complications, we will assume that all the spaces under consideration are metrizable and therefore in particular compactly generated. Standard references are Spanier [12] and Whitehead [13].

For any pair $(X, A)$ of topological spaces with $A \subset X$ we denote by

$$X/A = \left( (X \setminus A) \cup [A], [A] \right)$$
the pointed space which is obtained by collapsing $A$ to a single point denoted by $[A]$. A set $U \subset X/A$ is open if either $U$ is open in $X$ and $U \cap A = \emptyset$ or the set $(U \cap (X \setminus A)) \cup A$ is open in $X$.

For any two pointed (metric) spaces $(X, x_0)$ and $(Y, y_0)$ the product space $X \times Y$ is understood as a pointed space with base point $(x_0, y_0)$. Furthermore, we denote the sum and the smash product of $X$ and $Y$ by

$$X \vee Y = X \times y_0 \cup x_0 \times Y \subset X \times Y,$$

$$X \wedge Y = X \times Y / X \vee Y.$$  

For any two maps $f: X \to X'$, $g: Y \to Y'$ between pointed spaces, the sum $f \vee g: X \vee Y \to X' \vee Y'$ and the smash product $f \wedge g: X \wedge Y \to X' \wedge Y'$ are defined in an obvious manner. The (unique) constant map between pointed spaces $(X, x_0)$ and $(W, w_0)$ will always be denoted by $c: X \to W$, $c(x) = w_0$ for all $x \in X$, and the identity map by $1_x: X \to X$ or simply $1: X \to X$.

The suspension $\Sigma X$ of a pointed space $(X, x_0)$ is defined by

$\Sigma X = X \times [0, 1] / X \times 0 \cup x_0 \times [0, 1] \cup X \times 1.$

Hence $\Sigma X = X \wedge \Sigma^1$, where $\Sigma^1 = [0, 1]/\{0, 1\}$ is the pointed circle. The pointed $n$-sphere is given by $\Sigma^n = \Sigma \Sigma^{n-1} = \Sigma^1 \wedge \cdots \wedge \Sigma^1$ (n times). The suspension $\Sigma \varphi$ of a map $\varphi: X \to Y$ between pointed spaces is defined by $\Sigma \varphi = \varphi \wedge 1: \Sigma X \to \Sigma Y$.

For any two pointed spaces $(X, x_0)$ and $(W, w_0)$ we denote by $[X; W]$ the set of homotopy classes of continuous, base point preserving maps from $X$ to $W$. Then $[X; W]$ is a pointed set, the distinguished point being the class of the constant map. We denote by $[f]$ the homotopy class of the continuous, base point preserving map $f: X \to W$ and by $[X]$ the homotopy type of the pointed space $X$. If two maps $f_0: X \to W$ and $f_1: X \to W$ are homotopic we denote this by $f_0 \sim f_1$.

For any two pointed spaces $(X, x_0)$, $(Y, y_0)$ and any continuous, base point preserving map $\varphi: X \to Y$ the mapping cone $T_\varphi$ is given by

$$T_\varphi = X \times [0, 1] \cup \varphi Y / X \times 0 \cup x_0 \times [0, 1],$$

where the topological space $X \times [0, 1] \cup \varphi Y$ is obtained from the disjoint union of $X \times [0, 1]$ and $Y$ by identifying the pair $(x, 1) \in X \times [0, 1]$ with $\varphi(x) \in Y$ for every $x \in X$. Note that there is a natural injection of $Y$ into $T_\varphi$. The importance of this concept is based upon the following simple observation.

**Remark 2.1.** Let $\varphi: X \to Y$ and $g: Y \to W$ be continuous, base point preserving maps between pointed spaces. Then $g \circ \varphi \sim c: X \to W$ if and only if the following lifting problem has a solution:

$$\begin{array}{ccc}
Y & \xrightarrow{g} & W \\
\cap & \nearrow & \\
T_\varphi & &
\end{array}$$

Now let $(X, x_0)$, $(Y, y_0)$, $(W, w_0)$ be pointed spaces and let $\varphi: X \to Y$ be a continuous, base point preserving map. Then the induced map

$$\varphi^\#: [Y; W] \to [X; W]$$
is defined by \( \varphi^*[g] = [g \circ \varphi] \) for \( [g] \in [Y; W] \). The sequence

\[
X \overset{\varphi}{\to} Y \overset{\psi}{\to} Z
\]

of continuous, base point preserving maps between pointed spaces is said to be coexact if for every pointed space \((W, w_0)\) the induced sequence

\[
[X; W] \overset{\varphi^*}{\to} [Y; W] \overset{\psi^*}{\to} [Z; W]
\]

is exact. This means that \( \ker \varphi^* = \text{range } \psi^* \), where

\[
\ker \varphi^* = \{ [g] \in [Y; W] | g \circ \varphi \sim c : A^1 \to W \},
\]

\[
\text{range } \psi^* = \{ [h \circ \psi] \in [Y; W] | [h] \in [Z; W] \}.
\]

Choosing \( W = Z \) and \( h = 1_Z \) or, respectively, \( W = T_\varphi \) and \( g = j : Y \to T_\varphi \) the canonical injection, we obtain the following useful characterization for the sequence (2.1) to be coexact.

**Proposition 2.2.** The sequence (2.1) is coexact if and only if the following two conditions are satisfied.

(i) \( \psi \circ \varphi \sim c : X \to Z \), i.e. the lifting problem

\[
\begin{array}{ccc}
Y & \overset{\psi}{\to} & Z \\
\cap & \nearrow & \\
T_\varphi
\end{array}
\]

has a solution.

(ii) There exists a map \( h : Z \to T_\varphi \) such that \( h \circ \psi \sim j : Y \to T_\varphi \), \( j \) being the canonical injection of \( Y \) into \( T_\varphi \).

Now let the pointed space \((X, x_0)\) be a closed subspace of \((Y, x_0)\), let \( \iota : X \to Y \) denote the canonical injection and \( \pi : Y \to Y/X \) the canonical projection map, and consider the sequence

\[
(2.2) \quad X \overset{\iota}{\to} Y \overset{\pi}{\to} Y/X.
\]

Then \( \pi \circ \iota = c : X \to Y/X \). Hence it follows from Proposition 2.2 that a sufficient condition for the sequence (2.2) to be coexact is that the map \( \iota : X \to Y \) is a cofibration in the sense that the lifting problem

\[
\begin{array}{ccc}
Y \times 0 \cup X \times [0,1] & \overset{\varphi}{\to} & W \\
\cap & \nearrow & \\
Y \times [0,1]
\end{array}
\]

has a solution for every topological space \( W \) and every continuous map \( g : Y \times 0 \cup X \times [0,1] \to W \). Equivalently, \((X, Y)\) is an NDR-pair in the following sense.
**Definition 2.3 (NDR - pair).** Let $X$ be a closed subset of the metric space $Y$. Then $(X, Y)$ is said to be an NDR-pair if there exist continuous maps $r: Y \times [0, 1] \to Y$ and $\alpha: Y \to [0, 1]$ such that

1. $\alpha(y) = 0 \iff y \in X$,
2. $r(y, 0) = y \forall y \in Y$,
3. $r(x, \sigma) = x \forall x \in X, \forall \sigma \in [0, 1]$,
4. $r(y, 1) \in X \forall y \in Y$ with $\alpha(y) < 1$.

In fact, if $X, Y$ is an NDR-pair and the continuous maps $r: Y \times [0, 1] \to Y$ and $\alpha: Y \to [0, 1]$ satisfy the conditions of Definition 2.3, then the map

$$G: Y \times [0, 1] \to Y \times 0 \cup X \times [0, 1],$$

defined by

$$G(y, \sigma) = \begin{cases} (r(y, 1), \sigma - 2\alpha(y)), & 0 \leq \alpha(y) \leq \sigma/2, \\ (r(y, 2 - 2\alpha(y)/\sigma), 0), & \sigma/2 < \alpha(y) < \sigma, \\ (y, 0), & \sigma \leq \alpha(y) \leq 1, \end{cases}$$

for $y \in Y$ and $\sigma \in [0, 1]$, is continuous and satisfies $G(y, 0) = (y, 0)$ and $G(x, \sigma) = (x, \sigma)$ for all $y \in Y, x \in X, \sigma \in [0, 1]$. Therefore we have the following result.

**Proposition 2.4.** Let $(X, x_0)$ be a closed subspace of the pointed metric space $(Y, x_0)$. Then the following statements are equivalent.

(i) $i: X \to Y$ is a cofibration.

(ii) There exists a continuous map $G: Y \times [0, 1] \to Y \times 0 \cup X \times [0, 1]$ such that $G(y, 0) = (y, 0)$ and $G(x, \sigma) = (x, \sigma)$ for all $y \in Y, x \in X, \sigma \in [0, 1]$.

(iii) $X, Y$ is an NDR-pair.

If these conditions are satisfied, then the sequence (2.2) is coexact.

The map $G: Y \times [0, 1] \to Y \times 0 \cup X \times [0, 1]$ defined by (2.4) gives rise to a connection map $\delta: Y/X \to \Sigma X$ which leads to a long coexact sequence. More precisely, we have the following important result (see e.g. Whitehead [13, Theorem III.6.22]).

**Theorem 2.5.** Let $(X, x_0)$ be a closed subspace of the pointed metric space $(Y, x_0)$, suppose that $X, Y$ is an NDR-pair and let the maps $r: Y \times [0, 1] \to Y$ and $\alpha: Y \to [0, 1]$ satisfy the conditions of Definition 2.3. Let the connection map $\delta: Y/X \to \Sigma X$ be defined by

$$\delta([y]) = \begin{cases} (r(y, 1), 1 - 2\alpha(y)), & 0 < \alpha(y) < 1/2, \\ [X \times 0], & \text{otherwise} \end{cases}$$

for $y \in Y$. Then the sequence

$$X \buildrel i \over \to Y \buildrel \pi \over \to Y/X \buildrel \delta \over \to \Sigma X \buildrel \Sigma i \over \to \Sigma Y \buildrel \Sigma \pi \over \to \Sigma Y/X \buildrel \Sigma \delta \over \to \cdots$$

is coexact.
Proof. Let $p_X: \Sigma X \to \Sigma Y$ be the natural projection which collapses $Y \times 0 \cup X \times [0,1]$ to a single point. Then $p_X \circ G$ provides a homotopy between $c: \Sigma Y \to \Sigma X$ and $\delta \circ \pi: \Sigma Y \to \Sigma X$. Now let the maps

$$j: \Sigma X \to T_\pi = Y \times [0,1]/Y \times 0 \cup x_0 \times [0,1] \cup X \times 1$$

$$k: Y/X \to T_\pi, \quad k([y]) = [y,1],$$

be the natural injections. Then $j \circ \delta \sim k: Y/X \to T_\pi$ via the homotopy

$$H: Y/X \times [0,1] \to T_\pi$$

which is defined by

$$H([y], \sigma) = \begin{cases} [r(y,1), 1 - 2\alpha(y)], & 0 \leq \alpha(y) \leq \sigma/2, \\
[r(y,2 - 2\alpha(y)/\sigma), 1 - \sigma], & \sigma/2 < \alpha(y) < \sigma, \\
[y, 1 - \sigma], & \sigma \leq \alpha(y) \leq 1. \end{cases}$$

Hence it follows from Proposition 2.2 that the sequence $\Sigma Y \to Y/X \to \Sigma X$ is coexact.

Now let $p_Y: T_\pi \to \Sigma Y$ be the natural projection which collapses $Y \times 1$. Then the map $p_Y \circ H: Y/X \times [0,1] \to \Sigma Y$ provides a homotopy between $c: Y/X \to \Sigma Y$ and $\Sigma \iota \circ \delta: Y/X \to \Sigma Y$. Finally let us define the map

$$d: \Sigma Y \to T_\delta = Y/X \times [0,1] \cup \delta \Sigma X/[X] \times [0,1] \cup Y/X \times 0$$

by

$$d([y, \sigma]) = \begin{cases} [r(y,2 - 2\sigma)] \in Y/X \times [0,1], & 1/2 \leq \sigma \leq 1, \\
[r(y,1), 2\sigma - 2\alpha(y)] \in \Sigma X, & 0 \leq \alpha(y) \leq \sigma \leq 1/2, \\
[Y/X \times 0], & \sigma \leq \alpha(y) \leq 1, 0 \leq \sigma \leq 1/2, \end{cases}$$

for $[y, \sigma] \in \Sigma Y$. Then the map $d \circ \Sigma \iota: \Sigma X \to T_\delta$ is given by

$$d \circ \Sigma \iota([x, \sigma]) = \begin{cases} [x, 2\sigma], & 0 \leq \sigma \leq 1/2, \\
[Y/X \times 0], & \text{otherwise} \end{cases}$$

for $[x, \sigma] \in \Sigma X$. This map is homotopic to the canonical injection $l: \Sigma X \to T_\delta$ via the homotopy $\Phi: \Sigma X \times [0,1] \to T_\delta$ which is given by

$$\Phi([x, \sigma], \tau) = \begin{cases} [x, (1 + \tau)\sigma], & 0 \leq (1 + \tau)\sigma \leq 1, \\
[Y/X \times 0], & \text{otherwise} \end{cases}$$

for $[x, \sigma] \in \Sigma X$ and $\tau \in [0,1]$. Hence it follows from Proposition 2.2 that the sequence

$$Y/X \to \Sigma X \to \Sigma Y$$

is coexact.

Finally, Proposition 2.2 shows that if any sequence of the form (2.1) is coexact, then so is the sequence

$$\Sigma X \to \Sigma Y \to \Sigma Z$$

of the suspensions.
At the end of this section we introduce the extremely useful concept of a connected simple system which is due to Conley [3]. A connected simple system is a subcategory of the category of pointed spaces and homotopy classes of maps between these with the additional property that for any two objects there is a unique morphism between these (in each direction). More precisely, we make the following definition.

**Definition 2.6 (Connected Simple System).** A connected simple system consists of a collection $I_0$ of pointed spaces along with a collection $I_m$ of homotopy classes of maps between these such that

(i) $\text{hom}(X, \overline{X}) = \{[f] \in [X; \overline{X}]| [f] \in I_m\}$ is nonempty and consists of a single element for each ordered pair $X, \overline{X}$ of spaces in $I_0$,

(ii) if $X, \overline{X} \in I_0$ and $[f] \in \text{hom}(X, \overline{X})$, $[\tilde{f}] \in \text{hom}(\overline{X}, \overline{X})$, then $[\tilde{f} \circ f] \in \text{hom}(X, \overline{X})$,

(iii) $\text{hom}(X, X) = \{[1_X]\}$ for all $X \in I_0$.

Note that each morphism in a connected simple system is necessarily the homotopy class of a homotopy equivalence. Morphisms between connected simple systems are defined as follows.

**Definition 2.7.** A morphism $\Phi: I \to J$ between the connected simple systems $I = (I_0, I_m)$ and $J = (J_0, J_m)$ is a collection of homotopy classes of maps between spaces in $I_0$ and spaces in $J_0$ such that

(i) for every $X \in I_0$ and every $Y \in J_0$ the set $\Phi(X, Y) = \{[\varphi] \in [X; Y]| [\varphi] \in \Phi\}$ is nonempty and consists of a single element,

(ii) if $X, \overline{X} \in I_0$ and $Y, \overline{Y} \in J_0$ and if $[\varphi] \in \Phi(X, Y)$, $[f] \in \text{hom}(\overline{X}, X)$, $[g] \in \text{hom}(Y, \overline{Y})$, then $[g \circ \varphi \circ f] \in \Phi(\overline{X}, \overline{Y})$.

Of course, any single map $\varphi: X \to Y$, $X \in I_0$, $Y \in J_0$, induces a morphism between the connected simple systems $I$ and $J$ via property (ii) in the above definition. If a morphism $\Phi: I \to J$ consists of homotopy equivalences, then the homotopy inverses of these maps induce a morphism $\Phi^{-1}: J \to I$. Finally we mention that the suspension functor $\Sigma$ associates with any connected simple system $I = (I_0, I_m)$ the connected simple system $\Sigma I = (\Sigma I_0, \Sigma I_m)$ which is defined by

$$\Sigma I_0 = \{\Sigma X|X \in I_0\} , \quad \Sigma I_m = \{[\Sigma f]| [f] \in I_m\}.$$ 

3. Flows. In this section we collect some elementary properties of flows. Although the results are known we indicate at some places the main ideas of the proofs. Basic references are Birkhoff [2], Bhatia and Szegö [1] and Conley [3].

Let $\Gamma$ be a Hausdorff topological space and let the continuous map $(\gamma, t) \to \gamma \cdot t$ from $\Gamma \times \mathbb{R}$ into $\Gamma$ be a flow, that is $\gamma \cdot 0 = \gamma$ and $\gamma \cdot (t + s) = (\gamma \cdot t) \cdot s$ for every $\gamma \in \Gamma$ and all $t, s \in \mathbb{R}$.

We point out that the Hausdorff property for the flow $\Gamma$ is too strong for some dynamical systems. In particular the space of curves $\gamma: I \to X$ from an open interval $I \subset \mathbb{R}$ into a metric space $X$ is not Hausdorff in the compact-open topology, even if one considers only those curves whose graph is closed in $\mathbb{R} \times X$. The whole theory can also be developed in the more general situation that $\Gamma$ is not a Hausdorff space, but this causes some technical difficulties such as the definition of $\omega$-limit sets relative to a subset $X \subset \Gamma$. In order to avoid these difficulties and to make the main
ideas more transparent, we restrict ourselves to the case that $\Gamma$ is a Hausdorff space. A set $S \subset \Gamma$ is said to be invariant if $S \cdot R = S$. The maximal invariant subset of a set $N \subset \Gamma$ is given by

$$I(N) = \{ \gamma \in \Gamma | \gamma \cdot R \subset N \}.$$ 

If $N$ is closed then so is $I(N)$, since the closure of any invariant set is invariant. The $\omega$-limit sets of a set $Y \subset \Gamma$ are given by

$$\omega(Y) = I(c\Gamma(Y \cdot [0, \infty))) = \bigcap_{t>0} \cl(Y \cdot [t, \infty)),$$

$$\omega^*(Y) = I(c\Gamma(Y \cdot (-\infty, 0])) = \bigcap_{t>0} \cl(Y \cdot (-\infty, -t]).$$

Now let $S \subset \Gamma$ be a compact invariant set and let $Y \subset S$. Then $\omega(Y)$ and $\omega^*(Y)$ are compact invariant subsets of $S$ and they are connected if $Y$ is. Furthermore, if $U$ is a neighborhood of $\omega(Y)$, then there exists a $t > 0$ such that $Y \cdot [t, \infty) \subset U$. A similar statement holds for $\omega^*(Y)$. A compact invariant set $A \subset S$ is said to be an attractor in $S$ if there exists a neighborhood $U$ of $A$ in $S$ such that $A = \omega(U)$. A compact invariant set $A^* \subset S$ is said to be a repeller in $S$ if there exists a neighborhood $U$ of $A^*$ in $S$ such that $A^* = \omega^*(U)$. The following lemma gives a very useful characterization of attractors.

**Lemma 3.1.** Let $S \subset \Gamma$ be a compact invariant set. Then a compact invariant set $A \subset S$ is an attractor in $S$ if and only if there exists a neighborhood $U$ of $A$ in $S$ such that $\gamma \cdot (-\infty, 0] \not\subset U$ for all $\gamma \in U \setminus A$.

**Proof.** The necessity of the condition is clear since $\gamma \cdot (-\infty, 0] \subset U$ implies $\gamma \in \omega(U)$. If $U$ is a compact neighborhood of $\omega(Y)$, then there exists a $t > 0$ such that $Y \cdot [t, \infty) \subset U$. A similar statement holds for $\omega^*(Y)$. A compact invariant set $A \subset S$ is said to be an attractor in $S$ if there exists a neighborhood $U$ of $A$ in $S$ such that $A = \omega(U)$. A compact invariant set $A^* \subset S$ is said to be a repeller in $S$ if there exists a neighborhood $U$ of $A^*$ in $S$ such that $A^* = \omega^*(U)$. The following lemma gives a very useful characterization of attractors.

**Lemma 3.2.** Let $S \subset \Gamma$ be a compact invariant set and let $A$ be an attractor in $S$. Then the following statements hold.

(i) If $Y \in S$ and $\omega^*(Y) \cap A \neq \emptyset$, then $Y \in A$.
(ii) If $Y \in S$ and $\omega(Y) \cap A \neq \emptyset$, then $\omega(Y) \subset A$.
(iii) $A^* = \{ Y \in S | \omega(Y) \cap A = \emptyset \}$ is a repeller in $S$, called the complementary repeller of $A$.

(iv) $A = \{ Y \in S | \omega^*(Y) \cap A^* = \emptyset \}$.
(v) If $V$ is a compact neighborhood of $A$ in $S$ with $V \cap A^* = \emptyset$, then $A = \omega(V)$.
(vi) If $Y \in S$, then $\omega(Y) \cup \omega^*(Y) \subset A \cup A^*$.
(vii) If $A'$ is an attractor in $A$, then $A'$ is an attractor in $S$.

**Proof.** Let $U$ be an open neighborhood of $A$ in $S$ such that $\omega(U) = A$.

(i) If $\omega^*(Y) \cap A \neq \emptyset$, then $Y \cdot (-t_n) \in U$ for some sequence $t_n$ tending to $\infty$ and hence $\gamma \in \omega(U) = A$.

(ii) If $\omega(Y) \cap A \neq \emptyset$, then $\gamma \cdot t \in U$ for some $t \geq 0$ and therefore $\omega(\gamma) = \omega(\gamma \cdot t) \subset \omega(U) = A$. 

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(iii) Choose \( t^* > 0 \) such that \( \text{cl}(U \cdot [t^*, \infty)) \subset U \) and define
\[
U^* = S \setminus \text{cl}(U \cdot [t^*, \infty)).
\]
Then \( S = U \cup U^* \). Furthermore \( U^* \cdot (-\infty, -t^*] \subset S \setminus U \) and therefore \( U^* \) is a neighborhood of \( \omega^*(U^*) \subset S \setminus U \subset U^* \). Hence \( \omega^*(U^*) \) is a repeller in \( S \).

If \( \gamma \in \omega^*(U^*) \), then \( \omega(\gamma) \subset \omega^*(U^*) \). This implies \( \omega(\gamma) \cap A = \emptyset \) and therefore \( \gamma \in A^* \). If \( \gamma \in A^* \), then \( \gamma \cdot R \cap U = \emptyset \) since otherwise \( \omega(\gamma) \subset \omega(U) = A \). Hence \( \gamma \cdot R \subset U^* \) and therefore \( \gamma \in I(U^*) = \omega^*(U^*) \). We conclude that \( A^* = \omega^*(U^*) \) is a repeller.

(iv) The dual arguments of the preceding ones show that \( A = \omega(U) = \{ \gamma \in S | \omega^*(\gamma) \cap A^* = \emptyset \} \).

(v) Let \( U^* \) be an open neighborhood of \( A^* \) in \( S \) such that \( A^* = \omega^*(U^*) \) and \( U^* \cap V = \emptyset \). Choose \( t^* > 0 \) such that \( U^* \cdot (-\infty, -t^*] \subset U^* \subset S \setminus V \). Then \( V \cdot [t^*, \infty) \subset S \setminus U^* \) and therefore \( \omega(V) \subset S \setminus U^* \). By (iv), this implies \( \omega(V) = A \).

(vi) Follows from (i)–(iv).

(vii) Let \( U^* \) be a neighborhood of \( A^* \) in \( S \) such that \( U^* \subset U \) and \( \omega(U^* \cap A) = A^* \). Let \( \gamma \in U^* \) such that \( \gamma \cdot (-\infty, 0] \subset U^* \). Then \( \gamma \cdot (-\infty, 0] \subset U \) and therefore \( \gamma \in \omega(U) = A \). Hence \( \gamma \cdot (-\infty, 0] \subset U^* \cap A \) and therefore \( \gamma \in \omega(U^* \cap A) = A^* \). By Lemma 3.1, this implies that \( A^* \) is an attractor in \( S \). □

Let \( A_1 \) and \( A_2 \) be attractors in a compact, invariant set \( S \subset \Gamma \). Then it follows from Lemma 3.1 that \( A_1 \cap A_2 \) is an attractor in \( S \) and from Lemma 3.2(iii) that \( A_1^* \cup A_2^* \) is its complementary repeller. By duality, \( A_1 \cup A_2 \) is an attractor in \( S \) and \( A_1^* \cap A_2^* \) is its complementary repeller.

We are now going to introduce the concept of a Morse decomposition of an invariant set \( S \). This concept serves as a tool to generalize the classical Morse theory for gradient flows on compact manifolds with finitely many critical points to arbitrary flows and isolated invariant sets. One of the essential features of the general approach is the continuation theorem which cannot be derived in the context of the classical theory. Also, in the classical theory there are no means to define an index for invariant sets other than critical points such as periodic solutions or invariant tori.

**Definition 3.3 (Morse decomposition).** Let \( S \subset \Gamma \) be a compact, invariant set. Then a finite collection \( \{ M(\pi) | \pi \in P \} \) of compact invariant sets in \( S \) is said to be a Morse decomposition of \( S \) if there exists an ordering \( \pi_1, \ldots, \pi_n \) of \( P \) such that for every \( \gamma \in S \setminus \bigcup_{\pi \in P} M(\pi) \) there exist indices \( i, j \in \{1, \ldots, n\} \) such that \( i < j \) and
\[
\omega(\gamma) \subset M(\pi_i), \quad \omega^*(\gamma) \subset M(\pi_j).
\]

Every ordering of \( P \) with this property is said to be admissible. The sets \( M(\pi) \) are called Morse sets.

If \( S \) is a compact, invariant set in \( \Gamma \) and \( \{ M(\pi) | \pi \in P \} \) a Morse decomposition of \( S \), then for \( \pi, \pi^* \in P \) we define \( \pi < \pi^* \) if \( \pi \neq \pi^* \) and \( \pi \) comes before \( \pi^* \) in every admissible ordering of \( P \). This defines a partial order on \( P \). Clearly, any total ordering of \( P \) is admissible if and only if it preserves the partial order on \( P \). A subset \( I \subset P \) is said to be an interval if
\[
\pi' \in I, \quad \pi \in P, \quad \pi' < \pi < \pi'' \Rightarrow \pi \in I.
\]
For any interval $I$ we define the set
$$M(I) = \left\{ \gamma \in S | \omega(\gamma) \cup \omega^*(\gamma) \subseteq \bigcup_{\pi \in I} M(\pi) \right\}.$$ 

In the following proposition we collect some basic properties of the partially ordered set $(P, <)$.

**Proposition 3.4.** Let $S \subseteq \Gamma$ be a compact invariant set and let $\{M(\pi) | \pi \in P\}$ be a Morse decomposition of $S$ with the associated partial order "$<$" on $P$. Then the following statements hold.

(i) If $I \subset P$ is an interval, then there exists an admissible ordering $\pi_1, \ldots, \pi_n$ of $P$ and $i, j \in \{1, \ldots, n\}, i < j$, such that $I = \{\pi_i, \ldots, \pi_j\}$.

(ii) If $\{\pi, \pi^*\} \subset P$ is an interval, then $\pi < \pi^*$ if and only if there exists a $\gamma \in S$ such that $\omega(\gamma) \subseteq M(\pi)$ and $\omega^*(\gamma) \subseteq M(\pi^*)$.

(iii) Let $\pi, \pi^* \in P$. Then $\pi < \pi^*$ if and only if there exist sequences $\pi_0 = \pi, \pi_1, \ldots, \pi_k = \pi^* \in P$ and $\gamma_1, \ldots, \gamma_k \in S \setminus \bigcup\{M(\pi) | \pi \in P\}$ such that
$$\omega(\gamma_j) \subseteq M(\pi_{j-1}), \quad \omega^*(\gamma_j) \subseteq M(\pi_j), \quad j = 1, \ldots, k.$$ 

(iv) Let $I \subset P$ be an interval. Then $M(I)$ is an attractor in $S$ if and only if
$$\pi' \in P, \quad \pi \in I, \quad \pi < \pi' \Rightarrow \pi' \in I.$$ 

In this case $M(P \setminus I)$ is the complementary repeller of $M(I)$ in $S$ and $I$ is said to be an attractor interval and $P \setminus I$ a repeller interval.

(v) If $I \subset P$ is an interval, then $M(I)$ is a compact invariant set, $\{M(\pi) | \pi \in I\}$ is a Morse decomposition of $M(I)$ and $\{M(\pi) | \pi \in P \setminus I\} \cup \{M(I)\}$ is a Morse decomposition of $S$.

**Proof.** (i) Let $I \subset P$ be an interval. Then the sets $J = \{\pi \in P | \exists \pi' \in I \text{ with } \pi < \pi'\}$ and $K = P \setminus (I \cup J)$ are intervals and can be ordered in the form $J, I, K$, preserving the partial order on $P$. Now choose an ordering of $P$ which preserves the ordering of the sets $J, I, K$ and the partial order on $P$.

(ii) Let $\{\pi, \pi^*\}$ be an interval and suppose that $\pi < \pi^*$. Then, by (i), there exists an admissible ordering on $P$ such that $\pi^*$ follows immediately on $\pi$. Hence there exists a $\gamma \in S$ with $\omega(\gamma) \subseteq M(\pi)$ and $\omega^*(\gamma) \subseteq M(\pi^*)$, since otherwise one would get another admissible ordering by interchanging $\pi$ and $\pi^*$, contradicting $\pi < \pi^*$.

(iii) Suppose that $\pi < \pi^*$ and construct a sequence $\pi_0 = \pi < \pi_1 < \cdots < \pi_k = \pi^*$ such that there is no $\pi \in P$ and no $j \in \{1, \ldots, k\}$ with $\pi_{j-1} < \pi < \pi_j$. Then the sets $\{\pi_{j-1}, \pi_j\} \subset P$ are intervals and therefore (iii) follows from (ii).

(iv) If $I \subset P$ does not satisfy (3.1), then there exist $\pi \in P \setminus I, \pi^* \in I$ such that $\{\pi, \pi^*\}$ is an interval and $\pi < \pi^*$. Hence it follows from (ii) that $M(I)$ cannot be an attractor.

In order to prove the converse implication, let $\pi^* \in P$ satisfy
$$\pi^* \not< \pi, \quad \forall \pi \in P.$$ 

Then $I = P \setminus \{\pi^*\}$ is an interval with the property (3.1). Let $U^*$ be a neighborhood of $M(\pi^*)$ in $S$ with $\text{cl}(U^*) \cap M(\pi) = \emptyset$ for all $\pi \in I$ and let $\gamma \in U^* \setminus M(\pi^*)$. 

Then it follows from (iii) and (3.2) that $\omega(\gamma) \cap \text{cl}(U^*) = \emptyset$ and therefore $\gamma \cdot [0, \infty) \not\subset U^*$. Hence the dual result of Lemma 3.1 shows that $M(\pi^*)$ is a repeller in $S$. The complementary attractor of $M(\pi^*)$ is given by $M(I) = \{\gamma \in S|\omega^*(\gamma) \not\subset M(\pi^*)\}$. Therefore $M(I)$ is an attractor in $S$ and in particular a compact invariant set. Now statement (iv) follows by induction with $S$ replaced by $M(I)$.

Statement (v) is a direct consequence of (iv) and (i). □

The notion of an attractor-interval as well as the proof of the previous proposition are due to Franzosa [5].

The following concept has turned out to be very useful for the development of a theory which covers a wide range of applications.

DEFINITION 3.5 (LOCAL FLOW). A locally compact subset $X \subset \Gamma$ is said to be a local flow if for every $\gamma \in X$ there exists a neighborhood $U$ of $\gamma$ in $\Gamma$ and an $\varepsilon > 0$ such that $(X \cap U) \cdot [0, \varepsilon) \subset X$.

Whenever $Y \subset X$ we denote from now on by $\text{cl}(Y)$ its closure relative to $X$ and by $\text{int}(Y)$ its interior relative to $X$.

DEFINITION 3.6 (ISOLATED INVARIANT SET). Let $X \subset \Gamma$ be a local flow and let $S \subset X$ be a compact invariant set. Then $S$ is said to be an isolated invariant set if there exists a compact neighborhood $N$ of $S$ in $X$ such that $S = I(N)$. In that case $N$ is said to be an isolating neighborhood (for $S$ in $X$).

If $N_1$ and $N_2$ are isolating neighborhoods for the isolated invariant sets $S_1$ and $S_2$, respectively, in the local flow $X \subset \Gamma$, then $S_1 \cap S_2$ is an isolated invariant set in $X$ with the isolating neighborhood $N_1 \cap N_2$. Figure 1 shows that there is no corresponding statement for the union of isolated invariant sets.

LEMMA 3.7. If $N$ is an isolating neighborhood for the isolated invariant set $S$ in the metric local flow $X \subset \Gamma$, then there exists a neighborhood $\overline{N}$ of $N$ in $X$ which is still an isolating neighborhood for $S$.

PROOF. If the statement were false, then there would exist a sequence $\gamma_k \in X \setminus N$ such that $d(\gamma_k \cdot t, N) \leq 1/k$ for all $k \in \mathbb{N}$ and $t \in \mathbb{R}$. A limit point $\gamma$ of $\gamma_k$ would then satisfy $\gamma \in \text{cl}(X \setminus N) \cap I(N)$, a contradiction. □

If $S$ is an isolated invariant set in a local flow $X \subset \Gamma$ and $\{M(\pi)|\pi \in P\}$ is a Morse decomposition of $S$, then the Morse sets $M(\pi)$ are also isolated invariant sets in $X$.

The following compactness result has been established in Conley and Zehnder [4, Lemma 3.1]. For the sake of completeness we present a slightly simplified proof.

![Figure 1](https://www.ams.org/journal-terms-of-use)
Lemma 3.8. Let \( N \subset X \) be an isolating neighborhood for the isolated invariant set \( S \) in the metric local flow \( X \subset T \), let \( \{ M(\pi) | \pi \in P \} \) be a Morse decomposition of \( S \) and let "\(<\)" be the associated partial order on \( P \). Then the following statements hold.

(i) If \( \gamma \cdot [0, \infty) \subset N \), then there is a \( \pi \in P \) with \( \omega(\gamma) \subset M(\pi) \). If \( \gamma \cdot (-\infty, 0] \subset N \), then there is a \( \pi^* \in P \) with \( \omega^*(\gamma) \subset M(\pi^*) \).

(ii) If \( I \subset P \) is an attractor interval, then the sets

\[
M^-(I) = \{ \gamma \in N | \gamma \cdot (-\infty, 0] \subset N \text{ and } \omega^*(\gamma) \subset M(\pi) \text{ for some } \pi \in I \},
\]

\[
M^+(P \setminus I) = \{ \gamma \in N | \gamma \cdot [0, \infty) \subset N \text{ and } \omega(\gamma) \subset M(\pi) \text{ for some } \pi \in P \setminus I \}
\]

are compact.

Proof. Proposition 3.4 allows us to reduce both statements to the case \( P = \{ \pi, \pi^* \} \), where \( \{ \pi \} \) is an attractor interval, that is \( \pi^* < \pi \).

In order to prove statement (i), let us assume that \( \gamma \cdot [0, \infty) \subset N \) and \( \omega(\gamma) \subset M(\pi) \) and \( \omega(\gamma) \subset M(\pi^*) \). Since \( \omega(\gamma) \) is connected, this implies that \( \omega(\gamma) \subset M(\pi) \cup M(\pi^*) \) and hence there exists a \( \gamma' \in \omega(\gamma) \subset S \) with \( \gamma' \notin M(\pi) \cup M(\pi^*) \). Therefore \( \omega(\gamma') \subset M(\pi) \) and \( \omega^*(\gamma') \subset M(\pi^*) \). Making use of the fact that \( \gamma' \cdot R \subset \omega(\gamma) \), we obtain that \( M(\pi) \cap \omega(\gamma') \neq \emptyset \) and \( M(\pi^*) \cap \omega(\gamma') \neq \emptyset \). Now let us choose an open neighborhood \( U \) of \( \omega(\pi) \) in \( N \) such that \( \text{cl}(U) \cap M(\pi^*) = \emptyset \). Then there exists a sequence \( t_n \geq 0 \) tending to infinity such that \( \gamma \cdot t_n \subset U \), \( y_0 = \lim_{n \to \infty} \gamma \cdot t_n \in M(\pi) \) and \( \gamma \cdot [t_n, t_{n+1}] \subset U \). Hence there exists a sequence \( t'_n \in [t_n, t_{n+1}] \) with \( \gamma \cdot [t_n, t'_n] \subset \text{cl}(U) \) and \( \gamma \cdot t'_n \notin U \). Let \( \gamma_1 \) be any limit point of \( \gamma \cdot t'_n \). Then \( \gamma_1 \in N \setminus U \) and \( \gamma_1 \in \omega(\gamma) \subset S \). Furthermore the sequence \( t'_n - t_n \) has to be unbounded since otherwise \( \gamma_1 \in y_0 \cdot R \subset M(\pi) \). But this implies that \( \gamma_1 \cdot (-\infty, 0] \subset \text{cl}(U) \) and therefore \( \omega^*(\gamma_1) \subset I(U) = M(\pi) \). Since \( \gamma_1 \in M(\pi) \) we conclude that \( \omega(\gamma_1) \subset M(\pi^*) \), contradicting the fact that \( \pi^* < \pi \). This proves the first assertion in (i). The second assertion in (i) can be established by analogous arguments.

For statement (ii) it is enough to show that the respective subsets of \( N \) are closed since \( N \) is a compact Hausdorff space.

\( M^+(P) \) is closed: Let \( \gamma \in N \setminus M^+(P) \). Then by (i), there exists a \( t > 0 \) such that \( \gamma \cdot t \notin N \). This implies that \( \gamma' \cdot t \notin N \) for all \( \gamma' \) in some open neighborhood of \( \gamma \) in \( N \). Hence \( N \setminus M^+(P) \) is open in \( N \) and therefore \( M^+(P) \) is closed.

\( M^+(\pi^*) \) is closed: Let \( \gamma_n \in M^+(\pi^*) \subset M^+(P) \) converge to \( \gamma \in M^+(P) \) and suppose that \( \gamma \notin M^+(\pi^*) \). Then \( \omega(\gamma) \subset M(\pi) \) and \( \omega(\gamma_n) \subset M(\pi^*) \) for all \( n \in N \). Now let \( U \) be an open neighborhood of \( M(\pi^*) \) in \( X \) such that \( \text{cl}(U) \cap M(\pi) = \emptyset \). Since \( \omega(\gamma) \subset M(\pi) \), there exists a \( t > 0 \) such that \( \gamma \cdot t \notin \text{cl}(U) \) and therefore \( \gamma_n \cdot t \notin \text{cl}(U) \) for every sufficiently large \( n \in N \). For each of these \( n \in N \) there exists a \( t_n > 0 \) such that \( \gamma_n \cdot (t_n, \infty) \subset U \cap N \) and \( \gamma_n \cdot t_n \notin U \). Let us choose a subsequence such that \( \gamma_n \cdot t_n \) converges to \( \gamma^* \). Then \( \gamma^* \notin U \) and \( \gamma^* \cdot [0, \infty) \subset \text{cl}(U) \cap N \) which implies that \( \omega(\gamma^*) \subset M(\pi^*) \). Moreover, the sequence \( t_n \) has to be unbounded since otherwise \( \gamma^* \in \gamma \cdot R \) and thus \( \omega(\gamma^*) \subset M(\pi) \). Hence we obtain that \( \gamma^* \cdot t = \lim_{n \to \infty} \gamma_n \cdot (t_n + t) \in N \) for all \( t \in R \) and thus \( \gamma^* \in S \). Recalling that \( \gamma^* \notin U \), we conclude that \( \omega^*(\gamma^*) \subset M(\pi^*) \) and therefore \( \omega^*(\gamma^*) \subset M(\pi) \). But this is a contradiction to \( \pi^* < \pi \).
The closedness of $M^-(P)$ and $M^-(\pi)$ can be established by analogous arguments. □

At the end of this section we establish an important consequence of the local flow property.

**Lemma 3.9.** Let $X \subset \Gamma$ be a local flow and suppose that $\gamma \cdot [0, T] \subset X$. Furthermore, let $W$ be a neighborhood of $\gamma \cdot [0, T]$ in $X$. Then there exists a neighborhood $U$ of $\gamma$ in $\Gamma$ such that $(U \cap X) \cdot [0, T] \subset W$.

**Proof.** Let $W_0$ be a compact neighborhood of $\gamma \cdot [0, T]$ in $X$ and define $V = W \cap W_0$. Then $\partial V = \text{cl}(V) \cap \text{cl}(X \setminus V)$ is a compact set. Therefore $\partial V$ is closed in $\Gamma$ and $\gamma \cdot [0, T] \cap \partial V = \emptyset$. Hence it follows from the continuity of the flow together with the compactness of $[0, T]$ that there is a neighborhood $U$ of $\gamma$ in $\Gamma$ such that

$$U \cap X \subset V, \quad (U \cap X) \cdot [0, T] \subset \Gamma \setminus \partial V.$$ 

Now let $\gamma' \in U \cap X$ and suppose that $\gamma' \cdot [0, T] \not\subset V$. Then

$$t' = \sup \{ t > 0 | \gamma' \cdot [0, t] \subset V \} \in [0, T]$$

and $\gamma' \cdot t' \in \text{cl}(V) \subset X$. Since $X$ is a local flow, there exists an $\varepsilon > 0$ such that $\gamma' \cdot [t', t' + \varepsilon) \subset X$. But the definition of $t'$ implies that $\gamma' \cdot [t', t' + \delta) \not\subset V$ for any $\delta > 0$ and therefore $\gamma' \cdot t' \in \partial V$. This contradicts the definition of $U$. We conclude that $(U \cap X) \cdot [0, T] \subset V \subset W$. □

4. **Index theory.**

4.1. **Existence of index pairs.** The concept of an index pair plays a crucial role in the definition of the Conley index for isolated invariant sets. For the introduction of this concept we need the notion of positive invariance. Let $A$ be a compact subset of a local flow $X \subset \Gamma$. Then a subset $K \subset X$ is said to be positively invariant in $X$ if

$$y \in K, \quad t \geq 0, \quad y \cdot [0, t] \subset A \Rightarrow y \cdot t \in K.$$ 

**Definition 4.1 (Index pairs).** Let $X \subset \Gamma$ be a local flow and let $S \subset X$ be an isolated invariant set. Then a pair $(N_1, N_0)$ of compact sets in $X$ is said to be an index pair for $S$ in $X$ if $N_0 \subset N_1$ and

(i) $N_1 \setminus N_0$ is a neighborhood of $S$ in $X$ and $S = I(\text{cl}(N_1 \setminus N_0))$,

(ii) $N_0$ is positively invariant in $N_1$, and

(iii) if $\gamma \in N_1$ and $\gamma \cdot [0, \infty) \not\subset N_1$, then there exists a $t \geq 0$ with $\gamma \cdot [0, t] \subset N_1$ and $\gamma \cdot t \in N_0$.

The crucial property (iii) of an index pair $(N_1, N_0)$ says that every orbit which leaves $N_1$ in forward time has to go through the exit set $N_0$ before leaving $N_1$.

For any subset $K \subset N$ we define the minimal positively invariant set in $N$ which contains $K$ by

$$P(K, N) = \{ y \in N | \exists t \geq 0 \text{ with } y \cdot [-t, 0] \subset N, y \cdot (-t) \in K \}.$$ 

The whole difficulty for proving the existence of index pairs lies in the fact that $P(K, N)$ need not be closed, even if $K$ is closed, and that its closure need not be positively invariant. This is illustrated by Figure 2 in which the (positively invariant) exit set $N^- = \{ y \in N | \gamma \cdot [0, \varepsilon) \not\subset N \text{ for every } \varepsilon > 0 \}$ is not closed.
This difficulty can be overcome by means of the following lemma which is due to Conley and Zehnder [4, Lemma 3.2]. However, there is a mistake in the proof of this result in [4]. We present a (hopefully) correct proof using an argument in Conley [3, p. 47].

**Lemma 4.2.** Let $X \subset \Gamma$ be a metric local flow, let $N \subset X$ be an isolating neighborhood of the isolated invariant set $S \subset X$ and let $\{M(\pi) | \pi \in P\}$ be a Morse decomposition of $S$ with the associated partial ordering "$<$" on $P$. Then the following statements hold.

(i) If $K \subset N$ is a compact set with $K \cap M^+(P) = \emptyset$, then $P(K, N)$ is compact.

(ii) For every attractor interval $I \subset P$ and every open neighborhood $U$ of $M^-(I)$ in $\Gamma$ there exists a compact neighborhood $N_I$ of $M^-(I)$ in $N$ such that $N_I \subset U$ and $N_I$ is positively invariant in $N$.

**Proof.**

(i) Let $\gamma_n \in P(K, N)$ converge to $\gamma$ and let $t_n \geq 0$ be chosen such that $\gamma_n \cdot [-t_n, 0] \subset N$ and $\gamma_n \cdot (-t_n) \in K$. Then the sequence $t_n$ has to be bounded since otherwise any limit point $\gamma^*$ of $\gamma_n \cdot (-t_n)$ satisfies $\gamma^* \in K$ and $\gamma^* \cdot [0, \infty) \subset N$, contradicting $K \cap M^+(P) = \emptyset$. Hence the sequence $t_n$ has a limit point $t \geq 0$ and we get $\gamma \cdot [-t, 0] \subset N$, $\gamma \cdot (-t) \in K$, and therefore $\gamma \in P(K, N)$.

(ii) We prove this statement in four steps. Let us first choose any compact neighborhood $W$ of $M(P \setminus I)$ in $N$ such that $W \cap M^-(I) = \emptyset$.

**Step 1.** If $K \subset N$ is a compact set such that $M^-(I) \subset P(K, N) \subset U \cap (N \setminus W)$, then $P(K, N)$ is compact.

**Proof.** Let $\gamma_n \in P(K, N)$ converge to $\gamma$ and choose $t_n \geq 0$ such that $\gamma_n \cdot [-t_n, 0] \subset N$ and $\gamma_n \cdot (-t_n) \in K$. Then $\gamma_n \cdot [-t_n, 0] \subset P(K, N) \subset U \cap (N \setminus W)$ for all $n \in N$. If $t_n$ is an unbounded sequence, then we obtain $\gamma \cdot (-\infty, 0] \subset \text{cl}(U \cap (N \setminus W))$ which implies $\omega*(\gamma) \subset M(\pi)$ for some $\pi \in I$ and therefore $\gamma \in M^-(I) \subset P(K, N)$. If the sequence $t_n$ is bounded and $t \geq 0$ is a limit point of $t_n$, then we conclude that $\gamma \cdot [-t, 0] \subset N$, $\gamma \cdot (-t) \in K$ and therefore $\gamma \in P(K, N)$.

**Step 2.** There exists a $t^* > 0$ such that $\gamma \cdot [-t^*, 0] \subset \text{cl}(N \setminus W) \Rightarrow \gamma \in U \cap (N \setminus W)$. 

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Proof. If this implication would not hold, then there would exist sequences \( \gamma_n \in N \) and \( t_n \geq 0 \) such that \( t_n \) tends to infinity, \( \gamma_n \cdot [-t_n,0] \subset \text{cl}(N \setminus W) \) and \( \gamma_n \not\in U \cap (N \setminus W) \). Any limit point \( \gamma \) of \( \gamma_n \) would then satisfy \( \gamma \not\in U \cap (N \setminus W) \) and \( \gamma \cdot (-\infty,0] \subset \text{cl}(N \setminus W) \). But this would imply \( \omega^*(\gamma) \subset M(I) \) and therefore \( \gamma \in \mathcal{M}^-(I) \subset U \cap (N \setminus W) \) which would be a contradiction.

Step 3. Construction of \( N_I \). Let us define the sets

\[
A = \{ \gamma \in \mathcal{M}^-(I) | \gamma \cdot [0, t^*] \subset N \}, \quad B = \{ \gamma \in \mathcal{M}^-(I) | \gamma \cdot [0, t^*] \not\in N \}.
\]

Then for every \( \gamma \in A \) there exists an open neighborhood \( U(\gamma) \) of \( \gamma \) in \( \Gamma \) such that \( U(\gamma) \cdot [0, t^*] \subset U \cap (\Gamma \setminus W) \). For every \( \gamma \in B \) there exists a \( t(\gamma) > 0 \) such that \( \gamma \cdot [0, t(\gamma)] \subset U \cap (\Gamma \setminus W) \) and \( \gamma \cdot t(\gamma) \not\in N \) which enables us to choose an open neighborhood \( U(\gamma) \) of \( \gamma \) in \( \Gamma \) such that \( U(\gamma) \cdot [0, t(\gamma)] \subset U \cap (\Gamma \setminus W) \) and \( U(\gamma) \cdot t(\gamma) \cap N = \emptyset \). Since \( \mathcal{M}^-(I) \) is compact, there exist finitely many \( \gamma_1, \ldots, \gamma_k \in \mathcal{M}^-(I) \) such that the sets \( (\gamma_j) \), \( j = 1, \ldots, k \), cover \( \mathcal{M}^-(I) \). We choose a compact neighborhood \( K \) of \( \mathcal{M}^-(I) \) in \( N \) such that \( K \subset \bigcup_{j=1}^k U(\gamma_j) \) and define \( N_I = P(K, N) \).

Step 4. \( N_I \subset U \cap (N \setminus W) \).

Proof. Let \( \gamma \in N_I \) and let \( t \geq 0 \) with \( \gamma \cdot [-t,0] \subset N \) and \( \gamma \cdot (-t) \in K \). Then \( \gamma \cdot (-t) \in U(\gamma_j) \) for some \( j \in \{1, \ldots, k\} \). Suppose that \( \gamma \not\in U \cap (\Gamma \setminus W) \). If \( \gamma \in A \), then \( \gamma \cdot [-t, t^* - t] \subset U \cap (\Gamma \setminus W) \) and therefore \( t^* < t \). Hence there exists a \( \gamma' \in [0, t - t^*] \) such that \( \gamma \cdot [-t', t^* - t'] \subset U \cap (N \setminus W) \) and \( \gamma \cdot (-t') \not\in U \cap (N \setminus W) \), contradicting Step 2. If \( \gamma \in B \), then \( \gamma \cdot [-t, t(\gamma_j) - t] \subset U \cap (\Gamma \setminus W) \) and \( \gamma \cdot (t(\gamma_j) - t) \not\in N \). From \( \gamma \cdot [-t,0] \subset N \) we obtain \( t(\gamma) > t \) and from \( \gamma \not\in U \cap (\Gamma \setminus W) \) we obtain \( t(\gamma) < t \). A contradiction. We conclude that \( \gamma \in N \cap U \cap (\Gamma \setminus W) = U \cap (N \setminus W) \) which proves Step 4.

By definition, the set \( N_I \) constructed in Step 3 is a neighborhood of \( \mathcal{M}^-(I) \) in \( N \) which is positively invariant in \( N \). Furthermore \( N_I = P(K, N) \subset U \cap (N \setminus W) \) (Step 4) and hence \( N_I \) is compact (Step 1). □

Now we are in the position to establish the following important existence result for index pairs (compare Conley and Zehnder [4, Lemma 3.3]).

Theorem 4.3 (Existence of Index Pairs). Let \( X \subset \Gamma \) be a metric local flow, let \( N \subset X \) be an isolating neighborhood of the isolated invariant set \( S \subset X \) and let \( U \) be any neighborhood of \( S \) in \( \Gamma \). Then there exists an index pair \((N_1, N_0)\) for \( S \) in \( X \) such that \( N_1 \) and \( N_0 \) are positively invariant in \( N \) and \( \text{cl}(N_1 \setminus N_0) \subset U \).

Proof. By Lemma 3.7, the sets

\[
M^+ = \{ \gamma \in N | \gamma \cdot [0, \infty) \subset N \}, \quad M^- = \{ \gamma \in N | \gamma \cdot (-\infty,0] \subset N \}
\]

are compact and \( S = M^+ \cap M^- \). Hence there exist open neighborhoods \( U^+ \) of \( M^+ \) in \( N \) and \( U^- \) of \( M^- \) in \( N \) such that

\[
\text{cl}(U^+ \cap U^-) \subset U \cap \text{int} N.
\]

By Lemma 4.2 there exists a compact, positively invariant set \( N'_1 \) in \( N \) such that \( N'_1 \subset U^- \) and \( N'_1 \) is a neighborhood of \( M^- \) in \( N \). Now define

\[
N_0 = P(N \setminus U^+, N), \quad N_1 = N'_1 \cup N_0.
\]
Then $N_0$ and $N_1$ are positively invariant in $N$ and $N_1 \setminus N_0 \subset U^+ \cap U^-$ and hence $\text{cl}(N_1 \setminus N_0) \subset U$. Furthermore $N_0$ is compact (Lemma 4.2(i)) and $N_0 \cap S = \emptyset$. Therefore $N_1 \setminus N_0$ is a neighborhood of $S$. Clearly $S = I(\text{cl}(N_1 \setminus N_0))$, since $S \subset \text{cl}(N_1 \setminus N_0) \subset N$. It remains to show that $N_0$ is the exit set of $N_1$.

For this purpose let $\gamma \in N_1$ such that $\gamma \cdot [0, \infty) \subset N_1$ and suppose that $\gamma \notin N_0$. Define $t^* = \sup\{t > 0 | \gamma \cdot [0, t] \subset N \setminus N_0\}$. Then

$$\gamma \cdot t^* \in \text{cl}(N_1 \setminus N_0) \subset \text{cl}(U^+ \cap U^-) \subset \text{int} N.$$  

Since $X$ is a local flow there exists an $\epsilon > 0$ such that $\gamma \cdot [t^*, t^* + \epsilon] \subset \text{int} N$. Since $\gamma \cdot t^* \in N_1$ we conclude that $\gamma \cdot [t^*, t^* + \epsilon] \subset N_1$ and $\gamma \cdot [t^*, t^* + \epsilon] \cap N_0 = \emptyset$. □

The next result shows the existence of a filtration of index pairs associated with a Morse decomposition of $S$ (compare Conley and Zehnder [4, Theorem 3.1]).

**Corollary 4.4.** Let $X \subset \Gamma$ be a metric local flow, let $S \subset X$ be an isolated invariant set and let $\{ M(\pi), \pi \in P \}$ be a Morse decomposition of $S$ with an admissible ordering $\pi_1, \ldots, \pi_n$ of $P$. Furthermore let $(N_n, N_0)$ be an index pair for $S$ in $X$. Then there exists a filtration $N_0 \subset N_1 \subset \cdots \subset N_{n-1} \subset N_n$ of compact sets such that $(N_k, N_{j-1})$ is an index pair for

$$M_{kj} = \left\{ \gamma \in S | \omega(\gamma) \cup \omega^*(\gamma) \subset \bigcup_{i=j}^k M(\pi_i) \right\}$$

whenever $1 \leq j \leq k \leq n$.

**Proof.** Define $N = \text{cl}(N_n \setminus N_0)$. Then, by Lemma 3.7, for any $j \in \{1, \ldots, n\}$ the sets

$$M_j^+ = \left\{ \gamma \in N | \gamma \cdot [0, \infty) \subset N, \omega(\gamma) \subset M_{nj} \right\},$$

$$M_j^- = \left\{ \gamma \in N | \gamma \cdot (-\infty, 0] \subset N, \omega^*(\gamma) \subset M_{j1} \right\}$$

are compact. Now let $N'_j = N \setminus N_j$ and define $N'_j \subset N$ recursively such that $N'_j$ is a compact neighborhood of $M_j^-$ in $N$ which is positively invariant in $N_{j+1}'$ and satisfies $N_j' \cap M_{j+1}^+ = \emptyset$ (Lemma 4.2), $j = n - 1, \ldots, 1$. Then the sets $N_j = N_j' \cup N_0$ satisfy the requirements of the corollary. □

**Remark 4.5.** A very nice refinement of the previous result has recently been established by Franzosa [5]. Let $N \subset X$ be an isolating neighborhood of the isolated invariant set $S$ in the metric local flow $X \subset \Gamma$ and let $\{ M(\pi) | \pi \in P \}$ be a Morse decomposition of $S$ with the associated partial order “$<$” on $P$. Let $\mathcal{J}$ denote the set of attractor intervals in $P$. Then Franzosa has shown in [5] that there exists a family $\{ N(I) | I \in \mathcal{J} \}$ of compact, positively invariant sets in $N$ such that

(i) $(N(J), N(I))$ is an index pair for $M(J \setminus I)$ for all $I, J \in \mathcal{J}$ with $I \subset J$, and

(ii) $N(I \cap J) = N(I) \cap N(J), N(I \cup J) = N(I) \cup N(J)$ for all $I, J \in \mathcal{J}$.

The proof is not easy. The essential difficulty is the requirement that both the intersection and the union property have to be satisfied simultaneously.

4.2. **Equivalence of index pairs.** The most important property of index pairs is that the homotopy type of the pointed space $N_1/N_0$ is independent of the choice of the index pair and therefore depends only on the behavior of the flow near the isolated
invariant set \(S\) (Conley and Zehnder [4] and Kurland [6]). We present a highly simplified proof of this fact. More precisely, we will show that for any isolated invariant set \(S\) in a local flow \(X\) the collection
\[
\{ N_1/N_0 | (N_1, N_0) \text{ is an index pair for } S \text{ in } X \}
\]
along with a certain collection of homotopy classes of flow induced maps is a connected simple system in the sense of Definition 2.6. The proof consists of the following three lemmas.

**Lemma 4.6.** Let \(N\) be an isolating neighborhood for the isolated invariant set \(S\) in the metric local flow \(X \subset \Gamma\) and let \(U\) be a neighborhood of \(S\) in \(X\). Then there exists a \(t > 0\) such that \(\gamma \cdot [-t, t] \subset N \Rightarrow \gamma \in U\).

**Proof.** If there would exist sequences \(\gamma_k \subset X \setminus U\) and \(t_k \geq 0\) such that \(t_k\) tends to infinity and \(\gamma_k \cdot [-t_k, t_k] \subset N\) for all \(k \in \mathbb{N}\), then any limit point \(\gamma\) of \(\gamma_k\) would satisfy \(\gamma \in \text{cl}(X \setminus U)\) and \(\gamma \cdot \mathbb{R} \subset N\). This would imply \(\gamma \in S \cap \text{cl}(X \setminus U)\), a contradiction. \(\square\)

The next lemma defines a flow induced map from \(N_1/N_0\) into \(\bar{N}_1/\bar{N}_0\) for any two index pairs \((N_1, N_0), (\bar{N}_1, \bar{N}_0)\) of \(S\) in \(X\).

**Lemma 4.7.** Let \((N_1, N_0)\) and \((\bar{N}_1, \bar{N}_0)\) be index pairs for the isolated invariant set \(S\) and choose \(T > 0\) such that the following implications hold for \(t > T\):
\[\gamma \cdot [-t, t] \subset N_1 \setminus N_0 \Rightarrow \gamma \in \bar{N}_1 \setminus \bar{N}_0,\]
\[\gamma \cdot [-t, t] \subset \bar{N}_1 \setminus \bar{N}_0 \Rightarrow \gamma \in N_1 \setminus N_0.\]

Then the map \(f: N_1/N_0 \times [T, \infty) \to \bar{N}_1/\bar{N}_0\) defined by
\[(\gamma, t) \mapsto \gamma \cdot t \in N_1 \setminus N_0,\]
for \(\gamma \in N_1\) and \(t \geq T\), is continuous.

**Proof.** 1st case. \(\gamma \cdot [t, 3t] \not\subset \text{cl}(\bar{N}_1 \setminus \bar{N}_0)\). In this case \(\gamma \cdot t* \not\subset \text{cl}(\bar{N}_1 \setminus \bar{N}_0)\) for some \(t*\) with \(t < t* < 3t\). Hence there exists a neighborhood \(U\) of \(\gamma \cdot t*\) in \(\Gamma\) such that \(U \cap \text{cl}(\bar{N}_1 \setminus \bar{N}_0) = \emptyset\). By the continuity of the flow, this implies the existence of a neighborhood \(W\) of \((\gamma, t)\) in \(\Gamma \times [T, \infty)\) such that, whenever \((\gamma', t') \in W\), then \(\gamma' \cdot t* \in U\) and \(t' < t* < 3t'.\) We conclude that \(\gamma' \cdot [t', 3t'] \not\subset \bar{N}_1 \setminus \bar{N}_0\) and hence \(f((\gamma'), t') = [\bar{N}_0]\) for every \((\gamma', t') \in W\) with \(\gamma' \in N_1\).

Note that the case \(\gamma \cdot [0, 2t] \not\subset \text{cl}(N_1 \setminus N_0)\) can be treated in a strictly analogous manner. Hence we can assume from now on that
\[
\gamma \cdot [0, 2t] \subset \text{cl}(N_1 \setminus N_0), \quad \gamma \cdot [t, 3t] \subset \text{cl}(\bar{N}_1 \setminus \bar{N}_0).
\]

2nd case. \(\gamma \cdot [t, 3t] \intersection \bar{N}_0 = \emptyset\). In this case it follows from (4.4) that \(\gamma \cdot [t, 3t] \subset \bar{N}_1 \setminus \bar{N}_0\). By (4.2), this implies \(\gamma \cdot 2t \in N_1 \setminus N_0\) and hence \(\gamma \cdot [0, 2t] \subset N_1 \setminus N_0\). Therefore \(f((\gamma), t) = \gamma \cdot 3t \in \bar{N}_1 \setminus \bar{N}_0\).
Now let $U$ be a neighborhood of $y \cdot 3t$ in $\Gamma$. Then, by the continuity of the flow, there exists a neighborhood $W$ of $(y, t)$ in $\Gamma \times [T, \infty)$ such that, whenever $(y', t') \in W$, then

$$y' \cdot [0, 2t'] \cap N_0 = \emptyset, \quad y' \cdot [t', 3t'] \cap \overline{N_0} = \emptyset, \quad y' \cdot 3t' \in U.$$  

If $y' \in N_1$, then we obtain $y' \cdot [0, 2t'] \subset N_1 \setminus N_0$ which, by (4.1), implies $y' \cdot t' \in \overline{N_1} \setminus \overline{N_0}$ and hence $y' \cdot [t', 3t'] \subset \overline{N_1} \setminus \overline{N_0}$. Therefore $f([y'], t') = [y' \cdot 3t'] = y' \cdot 3t' \in U$ for every $(y', t') \in W$ with $y' \in N_1$.

3rd case. $y \cdot [t, 3t] \cap \overline{N_0} \neq \emptyset$. In this case it follows from (4.4) that $y \cdot 3t \in \overline{N_0}$. Now let $[U]$ be any neighborhood of $f((y, t)) = [\overline{N_0}]$ in $\overline{N_1}/\overline{N_0}$ and define

$$U = ([U] \cap \overline{N_1} \setminus \overline{N_0}) \cup (\Gamma \setminus \overline{N_0}) \cup \overline{N_0}.$$  

Then $U$ is a neighborhood of $\overline{N_0}$ in $\Gamma$ and

$$[U] = (U \cap \overline{N_1} \setminus \overline{N_0}) \cup [\overline{N_0}].$$  

By the continuity of the flow, there exists a neighborhood $W$ of $(y, t)$ in $\Gamma \times [T, \infty)$ such that, whenever $(y', t') \in W$, then $y' \cdot 3t' \in U$. This implies that

$$f([y'], t') \in ([y' \cdot 3t'], [\overline{N_0}]) \subset (U \cap \overline{N_1} \setminus \overline{N_0}) \cup [\overline{N_0}] = [U]$$  

for every $(y', t') \in W$ with $y' \in N_1$.  

**Lemma 4.8.** Let $(N_1, N_0), (\overline{N_1}, \overline{N_0}), (\overline{N_1}, \overline{N_0})$ be index pairs for $S$. Choose $T > 0$ such that (4.1) and (4.2) are satisfied for $t > T$ and suppose that the implications

$$(4.5) \quad y \cdot [-t, t] \subset \overline{N_1} \setminus \overline{N_0} \Rightarrow y \in \overline{N_1} \setminus \overline{N_0},$$  

$$(4.6) \quad y \cdot [-t, t] \subset \overline{N_1} \setminus \overline{N_0} \Rightarrow y \in \overline{N_1} \setminus \overline{N_0}$$  

hold for $t \geq T$. Finally, let $f: N_1/N_0 \times [T, \infty) \rightarrow \overline{N_1}/\overline{N_0}$ be defined by (4.3) and $\overline{f}: \overline{N_1}/\overline{N_0} \times [\overline{T}, \infty) \rightarrow \overline{N_1}/\overline{N_0}$ analogously. Then the following equation holds for $t \geq \max\{T, \overline{T}\}$:

$$\overline{f}(f((y, t)), t) = \begin{cases} [y \cdot 6t], & y \cdot [0, 4t] \subset N_1 \setminus N_0, \quad y \cdot [2t, 6t] \subset \overline{N_1} \setminus \overline{N_0}, \\ [\overline{N_0}], & \text{otherwise}, \quad y \in N_1. \end{cases}$$  

**Proof.** We have to show that

$$y \cdot [0, 2t] \subset N_1 \setminus N_0, \quad y \cdot [t, 5t] \subset \overline{N_1} \setminus \overline{N_0}, \quad y \cdot [4t, 6t] \subset \overline{N_1} \setminus \overline{N_0}$$  

is equivalent to

$$y \cdot [0, 4t] \subset N_1 \setminus N_0, \quad y \cdot [2t, 6t] \subset \overline{N_1} \setminus \overline{N_0}.$$  

But this follows immediately from (4.1), (4.2) and (4.5), (4.6). □

Now we are in the position to define the index of an isolated invariant set.

**Definition 4.9 (Index).** Let $X \subset \Gamma$ be a metric local flow and let $S$ be an isolated invariant set in $X$. Then the homotopy type $h(S) = [N_1/N_0]$ of the pointed space $N_1/N_0$, $(N_1, N_0)$ being an index pair for $S$ in $X$, is said to be the homotopy index of $S$ in $X$.  

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The Conley index of $S$ in $X$ is the pair $I(S) = I(S, X) = (I_0, I_m)$, where
\[ I_0 = \{ \frac{N_1}{N_0} \mid (N_1, N_0) \text{ is an index pair for } S \text{ in } X \}, \]
\[ I_m = \{ [f']|_{\frac{N_1}{N_0}}, \frac{N_1}{N_0} \in I_0 \text{ and } f': \frac{N_1}{N_0} \to \frac{N_1}{N_0} \} \]
is the map defined in Lemma 4.7.

**Theorem 4.10.** Let $X \subset \Gamma$ be a metric local flow and let $S$ be an isolated invariant set in $X$. Then $h(S)$ is independent of the choice of the index pair and $I(S, X)$ is a connected simple system.

**Proof.** The existence of a homotopy class of maps in $I_m$ between any two spaces $N_1/N_0, \overline{N}_1/\overline{N}_0$ in $I_0$ follows from Lemma 4.7. Lemma 4.8 shows that the composition of any two morphisms in $I_m$ is still in $I_m$. Finally, it follows from Lemma 4.7 with $N_1 = \overline{N}_1, N_0 = \overline{N}_0, T = 0$ that $[1_{N_1/N_0}] \in I_m$ for every $N_1/N_0 \in I_0$. This shows that $I(S, X)$ is a connected simple system. Therefore the morphisms in $I_m$ are homotopy equivalences and hence $h(S)$ in independent of the choice of the index pair. □

Note that the previous theorem summarizes the paper [6] of Kurland and one of the main results in Conley and Zehnder [4, Theorem 3.2].

The Conley index is a very powerful and elegant tool for studying the structure of isolated invariant sets. A first conclusion is formulated in the corollary below.

**Corollary 4.11.** Let $X \subset \Gamma$ be a metric local flow and let $S \subset X$ be an isolated invariant set such that $h(S) \neq 0$ (the homotopy class of the one point pointed space). Then $S \neq \emptyset$.

**Proof.** If $(N_1, N_0)$ is an index pair for $S = \emptyset$, then for every $\gamma \in N_1$ there exists a $t > 0$ such that $\gamma \cdot [0, t] \subset \text{cl}(N_1 \setminus N_0)$. Since $N_1$ is compact, this implies that there exists a $T > 0$ with $\gamma \cdot [0, T] \cap N_0 \neq \emptyset$ for all $\gamma \in N_1$. Hence the map $f': \frac{N_1}{N_0} \to \frac{N_1}{N_0}$ given by

\[ f'([\gamma]) = \begin{cases} [\gamma \cdot t], & \text{if } \gamma \cdot [0, t] \subset N_1 \setminus N_0, \\ [N_0], & \text{otherwise}, \end{cases} \]

for $\gamma \in N_1$ and $t \in [0, T]$, defines a homotopy between the zero map $f^T$ and the identity $f^0$ (Lemma 4.7). This shows that $h(S) = 0$. □

5. A coexact sequence for attractor-repeller pairs. The purpose of this section is to establish a coexact sequence for the Conley index of an attractor-repeller pair along the lines of Theorem 2.5. The first step in this direction is to show that any given index pair can be modified in such a way that it becomes an NDR-pair (§5.1). Secondly, we have to show that all the maps between index pairs which are involved in the coexact sequence induce morphisms between the corresponding connected simple systems which are independent of the choice of the particular filtration of index pairs (§5.2).
5.1. Regularization of index pairs. We will show that an index pair is an NDR-pair if it is regular in the following sense.

**Definition 5.1 (Regular Index Pair).** An index pair \((N_1, N_0)\) for an isolated invariant set \(S\) in a local flow \(X \subset \Gamma\) is said to be regular if the function \(\tau: N_1 \to [0, \infty]\) defined by

\[
\tau(\gamma) = \begin{cases} 
\sup \{ t > 0 | \gamma \cdot [0, t] \subset N_1 \setminus N_0 \}, & \gamma \in N_1 \setminus N_0, \\
0, & \gamma \in N_0,
\end{cases}
\]

is continuous.

Figure 3 illustrates an index pair which is not regular.

The next lemma gives a sufficient condition for an index pair to be regular. We were not able to prove that this condition is also necessary and leave this as a conjecture.

**Lemma 5.2.** Let \((N_1, N_0)\) be an index pair for the isolated invariant set \(S\) in the local flow \(X \subset \Gamma\) and suppose that

\[
(\gamma \cdot [0, \varepsilon] \not\subset \text{cl}(N_1 \setminus N_0) \quad \forall \gamma \in N_0, \forall \varepsilon > 0.
\]

Then the index pair \((N_1, N_0)\) is regular.

**Proof.** Let \(\tau: N_1 \to [0, \infty]\) be defined by (5.1) and let \(\gamma \in N_1\) be given.

First assume that \(0 < \tau(\gamma) < \infty\) and choose \(T \in (0, \tau(\gamma))\). Then \(\gamma \cdot [0, T] \subset N_1 \setminus N_0\) and thus there exists a neighborhood \(U\) of \(\gamma\) in \(\Gamma\) such that \(U \cdot [0, T] \cap N_0 = \emptyset\). Hence \(\gamma' \cdot [0, T] \subset N_1 \setminus N_0\) for all \(\gamma' \in U \cap N_1\) and therefore \(\tau(\gamma') > T\) for all \(\gamma' \in U \cap N_1\).

Secondly, suppose that \(0 \leq \tau(\gamma) < \infty\) and choose \(T \in (\tau(\gamma), \infty)\). Then it follows from (5.2) that \(\gamma \cdot t \not\subset \text{cl}(N_1 \setminus N_0)\) for some \(t \in [\tau(\gamma), T]\). This implies that there exists a neighborhood \(U\) of \(\gamma\) in \(\Gamma\) with \(U \cdot t \cap \text{cl}(N_1 \setminus N_0) = \emptyset\). We conclude that \(\tau(\gamma') \leq t \leq T\) for all \(\gamma' \in U \cap N_1\). This proves the continuity of \(\tau\).

In order to transform a given index pair into a regular one we prove the existence of a Lyapunov function (compare Conley [3, p. 33]).

**Lemma 5.3.** Let \((N_1, N_0)\) be an index pair for the isolated invariant set \(S\) in the metric local flow \(X \subset \Gamma\). Then there exists a continuous (Lyapunov) function \(g: N_1 \to [0, 1]\) such that

\[
g(\gamma) \leq \tau(\gamma) \quad \forall \gamma \in N_1.
\]
(5.3) \[ g(\gamma) = 1 \Leftrightarrow \gamma \cdot [0, \infty) \subset N_1 \quad \text{and} \quad \omega(\gamma) \subset S, \]

(5.4) \[ g(\gamma) = 0 \Leftrightarrow \gamma \in N_0, \]

(5.5) \[ t > 0, \quad 0 < g(\gamma) < 1, \quad \gamma \cdot [0, t] \subset N_1 \Rightarrow g(\gamma \cdot t) < g(\gamma). \]

**Proof.** Following the lines of Conley [3, p. 33] we construct the Lyapunov function \( g: N_1 \to [0, 1] \) in three steps.

**Step 1.** The function \( l: N_1 \to [0, 1] \) defined by

\[
l(\gamma) = \frac{d(\gamma, N_0)}{d(\gamma, N_0) + d(\gamma, S)}, \quad \gamma \in N_1,
\]

is continuous and satisfies \( N_0 = l^{-1}(0) \) and \( S = l^{-1}(1) \).

**Step 2.** The function \( k: N_1 \to [0, 1] \) defined by

\[
k(\gamma) = \sup \{ l(\gamma \cdot t) | t > 0, \gamma \cdot [0, t] \subset N_1 \}
\]

is continuous and satisfies

\[
k(\gamma) = 1 \Leftrightarrow \gamma \cdot [0, \infty) \subset N_1, \omega(\gamma) \subset S,
\]

\[
k(\gamma) = 0 \Leftrightarrow \gamma \in N_0,
\]

\[
\gamma \cdot [0, t] \subset N_1 \Rightarrow k(\gamma \cdot t) \leq k(\gamma).
\]

**Proof.** The only nontrivial property of \( k \) is the continuity.

Let \( \gamma \in N_1 \) be given, assume first that \( 0 < k(\gamma) < 1 \) and choose \( \epsilon \in (0, k(\gamma)) \). Then there exists a \( t > 0 \) such that \( \gamma \cdot [0, t] \subset N_1 \) and \( l(\gamma \cdot t) > k(\gamma) - \epsilon \). Then, of course, \( \gamma \cdot [0, t] \subset N_1 \setminus N_0 \) and hence there exists a neighborhood \( U \) of \( \gamma \) in \( \Gamma \) such that \( U \cdot [0, t] \cap N_0 = \emptyset \) and \( l(\gamma' \cdot t) > k(\gamma) - \epsilon \) for all \( \gamma' \in U \cap N_1 \). This implies \( k(\gamma') > k(\gamma) - \epsilon \) for all \( \gamma' \in U \cap N_1 \).

Secondly, suppose that \( 0 < k(\gamma) < 1 \) and choose \( \epsilon \in (0, 1 - k(\gamma)) \). Furthermore, assume that there is a sequence \( \gamma_n \in N_1 \) such that \( \gamma = \lim_{n \to \infty} \gamma_n \) and \( k(\gamma_n) > k(\gamma) + \epsilon \) for all \( n \in \mathbb{N} \). Then there is a sequence \( t_n > 0 \) such that \( \gamma_n \cdot [0, t_n] \subset N_1 \setminus N_0 \) and \( l(\gamma_n \cdot t_n) > k(\gamma) + \epsilon \). The sequence \( t_n \) has to be bounded since otherwise \( \gamma \cdot [0, \infty) \subset N_1 \setminus N_0 \), contradicting \( k(\gamma) < 1 \). Hence the sequence \( t_n \) has a limit point \( t \) and we obtain \( \gamma \cdot [0, t] \subset \text{cl}(N_1 \setminus N_0) \) and \( l(\gamma \cdot t) \geq k(\gamma) + \epsilon \), again a contradiction. We conclude that there exists a neighborhood \( U \) of \( \gamma \) in \( \Gamma \) such that \( k(\gamma') \leq k(\gamma) + \epsilon \) for all \( \gamma' \in U \cap N_1 \). This proves the continuity of \( k \).

**Step 3.** The function \( g: N_1 \to [0, 1] \) defined by

\[
g(\gamma) = \int_0^{t(\gamma)} e^{-t} k(\gamma \cdot \xi) \, d\xi, \quad t(\gamma) = \sup \{ t > 0 | \gamma \cdot [0, t] \subset N_1 \},
\]

satisfies the requirements of the lemma.

**Proof.** The conditions (5.3) and (5.4) are obviously satisfied. In order to establish (5.5), let \( \gamma \in N_1 \) satisfy \( 0 < g(\gamma) < 1 \) and suppose that

\[
0 < t \leq t^* = \sup \{ \xi > 0 | \gamma \cdot [0, \xi] \subset N_1 \setminus N_0 \} < \infty.
\]

Then

\[
g(\gamma \cdot t) = \int_0^{t^* - t} e^{-\xi} k(\gamma \cdot (t + \xi)) \, d\xi \leq \int_0^{t^*} e^{-\xi} k(\gamma \cdot \xi) \, d\xi
\]

\[
< \int_0^{t^*} e^{-\xi} k(\gamma \cdot \xi) \, d\xi = g(\gamma).
\]
Now we prove the continuity of \( g \) at \( y \in N_1 \). If \( y \in N_0 \) this follows from the fact that \( g(y') \leq k(y') \) for all \( y' \in N_1 \). If \( y \cdot [0, \infty) \subset N_1 \setminus N_0 \), then the continuity is a consequence of the inequality

\[
|g(y') - g(y)| \leq \int_0^T |k(y' \cdot \xi) - k(y \cdot \xi)| \, d\xi + 2 \int_T^\infty e^{-\xi} \, d\xi
\]

for \( T \) large and \( y' \cdot [0, T] \subset N_1 \setminus N_0 \). If \( y \in N_1 \setminus N_0 \) and \( y \cdot [0, \infty) \cap N_0 \neq \emptyset \), then for every \( \varepsilon > 0 \) there exists a \( T > 0 \) such that \( y \cdot [0, T] \subset N_1 \setminus N_0 \) and \( k(y \cdot T) < \varepsilon \). Hence the following inequality holds for all \( y' \in N_1 \) with \( y' \cdot [0, T] \subset N_1 \setminus N_0 \) and \( k(y' \cdot T) < 2\varepsilon \):

\[
|g(y') - g(y)| \leq \int_0^T |k(y' \cdot \xi) - k(y \cdot \xi)| \, d\xi + 3\varepsilon.
\]

Thus the continuity of \( g \) follows from that of \( k \). This completes the proof of Lemma 5.3. \( \square \)

**Remark 5.4.** Let \((N_1, N_0)\) be an index pair for the isolated invariant set \( S \) in the metric local flow \( X \subset \Gamma \) and let \( g: N_1 \to [0, 1] \) be the Lyapunov function of Lemma 5.3. Then we can replace \( N_0 \) by \( N_1 = \{ y \in N_1 | g(y) \leq \varepsilon \} \) and it follows from Lemma 5.2 that \((N_1, N_1)\) is a regular index pair for \( S \) in \( X \) in the sense of Definition 5.1.

**5.2. A coexact sequence.** Let \( S \) be an isolated invariant set in the metric local flow \( X \subset \Gamma \), let \( A \) be an attractor in \( S \) and let \( A^* \) be the complementary repeller. Then it follows from Corollary 4.4 that there exists a filtration \( N_0 \subset N_1 \subset N_2 \) of compact sets in \( X \) such that \((N_2, N_0)\) is an index pair for \( S \), \((N_1, N_0)\) is an index pair for \( A \) and \((N_2, N_1)\) is an index pair for \( A^* \). By Remark 5.4, we can assume without loss of generality that the index pair \((N_2, N_1)\) is regular. Hence the function \( \tau: N_2 \to [0, \infty) \) defined by

\[
\tau(y) = \begin{cases} 
\sup\{ t > 0 | y \cdot [0, t] \subset N_2 \setminus N_1 \}, & y \in N_2 \setminus N_1, \\
0, & y \in N_1,
\end{cases}
\]

for \( y \in N_2 \), is continuous and the pair \( N_2/N_0, N_1/N_0 \) of pointed spaces with the natural inclusion \( \iota: N_1/N_0 \to N_2/N_0 \) is an NDR-pair. In fact, the functions \( r: N_2/N_0 \times [0, 1] \to N_2/N_0 \) and \( \alpha: N_2/N_0 \to [0, 1] \) defined by

\[
(5.7) \quad r([y], \sigma) = \begin{cases} 
[y \cdot \sigma \tau(y)], & 0 \leq \tau(y) \leq c, \\
[y \cdot \sigma c], & c \leq \tau(y) \leq \infty,
\end{cases}
\]

and

\[
(5.8) \quad \alpha([y]) = \begin{cases} 
\tau(y)/c, & 0 \leq \tau(y) \leq c, \\
1, & c \leq \tau(y) \leq \infty,
\end{cases}
\]

for \( y \in N_2 \) and \( \sigma \in [0, 1] \), satisfy the requirements of Definition 2.3 (the constant \( c > 0 \) is merely a scaling factor). With these functions the connection map \( \delta: N_2/N_1 \to \Sigma N_1/N_0 \) defined by equation (2.5) takes the form

\[
(5.9) \quad \delta([y]) = \begin{cases} 
[y \cdot \tau(y), 1 - \tau(y)], & 0 \leq \tau(y) \leq 1, \\
[N_0 \times 0], & 1 \leq \tau(y) \leq \infty,
\end{cases}
\]

for \( y \in N_2 \) (we have chosen \( c = 2 \)). Hence Theorem 2.5 yields the following result.
Corollary 5.5. Let $A, A^*$ be an attractor-repeller pair for the isolated invariant set $S$ in the metric local flow $X \subset \Gamma$. Furthermore, let $N_0 \subset N_1 \subset N_2$ be a filtration of compact sets in $X$ such that $(N_2, N_0)$ and $(N_1, N_0)$ are index pairs for $S$ and $A$, respectively, and $(N_2, N_1)$ is a regular index pair for $A^*$. Finally, let $i: N_1/N_0 \to N_2/N_0$ and $\pi: N_2/N_0 \to N_2/N_1$ be the natural maps and let $\delta: N_2/N_1 \to \Sigma N_1/N_0$ be defined by (5.9) and (5.6). Then the following sequence is coexact:

\[
N_1/N_0 \xrightarrow{i} N_2/N_0 \xrightarrow{\pi} N_2/N_1 \xrightarrow{\delta} \Sigma N_1/N_0 \xrightarrow{\Sigma i} \Sigma N_2/N_0 \xrightarrow{\Sigma \pi} \cdots .
\]

Remark 5.6. Given an index pair $(N_1, N_0)$ for the isolated invariant set $S$ in a local flow $X \subset \Gamma$, the pointed space $\Sigma N_1/N_0$ can be identified with the space $\tilde{N}_1/\tilde{N}_0$, where

\[
\tilde{N}_1 = N_1 \times [-1,1], \quad \tilde{N}_0 = N_0 \times [-1,1] \cup N_1 \times \{-1,1\}.
\]

These two spaces define an index pair for the isolated invariant set $\tilde{S} = S \times 0$ in the local flow $\tilde{X} = X \times \mathbb{R} \subset \tilde{\Gamma} = \Gamma \times \mathbb{R}$, where the flow on $\tilde{\Gamma}$ is defined by $(\gamma, \xi) \cdot t = (\gamma \cdot t, \xi e^t)$ for $\gamma \in \Gamma$ and $\xi, t \in \mathbb{R}$.

Note that each of the maps in the sequence (5.10) induces a morphism between the corresponding connected simple systems. We denote these morphisms still by $i: I(A) \to I(S)$, $\pi: I(S) \to I(A^*)$ and $\delta: I(A^*) \to \Sigma I(A)$, respectively. Hence we get the following coexact sequence of connected simple systems:

\[
I(A) \xrightarrow{i} I(S) \xrightarrow{\pi} I(A^*) \xrightarrow{\delta} \Sigma I(A) \xrightarrow{\Sigma i} \Sigma I(S) \xrightarrow{\Sigma \pi} \cdots .
\]

The whole point in this section is that this sequence is independent of the choice of the particular index filtration. More precisely, we prove the following theorem (compare Kurland [7]).

Theorem 5.7. Let $A, A^*$ be an attractor-repeller for the isolated invariant set $S$ in the metric local flow $X \subset \Gamma$. Furthermore, let $N_0 \subset N_1 \subset N_2$ be a filtration of compact sets in $X$ such that $(N_2, N_0)$ and $(N_1, N_0)$ are index pairs for $S$ and $A$, respectively, and $(N_2, N_1)$ is a regular index pair for $A^*$. Then

(i) the injection $i: N_1/N_0 \to N_2/N_0$ induces a morphism between $I(A, X)$ and $I(S, X)$ which is independent of the choice of the filtration,

(ii) the projection $\pi: N_2/N_0 \to N_2/N_1$ induces a morphism between $I(S, X)$ and $I(A^*, X)$ which is independent of the choice of the filtration, and

(iii) the connection map $\delta: N_2/N_1 \to \Sigma N_1/N_0$ defined by (5.9) and (5.6) induces a morphism between $I(A^*, X)$ and $\Sigma I(A, X)$ which is independent of the choice of the filtration.

Proof. Let $\bar{N}_0 \subset \bar{N}_1 \subset \bar{N}_2$ be another filtration of compact sets in $X$ such that $(\bar{N}_2, \bar{N}_0)$ and $(\bar{N}_1, \bar{N}_0)$ are index pairs for $S$ and $A$, respectively, and $(\bar{N}_2, \bar{N}_1)$ is a regular index pair for $A^*$. Furthermore, let $\tilde{i}: \bar{N}_1/\bar{N}_0 \to \bar{N}_2/\bar{N}_0$, $\tilde{\pi}: \bar{N}_2/\bar{N}_0 \to \bar{N}_2/\bar{\bar{N}_1}$, $\tilde{\delta}: \bar{N}_2/\bar{N}_1 \to \Sigma \bar{N}_1/\bar{N}_0$ denote the associated maps and let $\tilde{\tau}: \bar{N}_2 \to [0, \infty]$ denote the “entrance-time” for the subset $\bar{N}_1$, defined analogously to (5.6).
In order to prove statement (i), choose $T > 0$ such that the implications
\begin{align*}
(5.12) & \quad \gamma \cdot [-T, T] \subset N_1 \setminus N_0 \Rightarrow \gamma \in \overline{N}_1 \setminus \overline{N}_0, \\
(5.13) & \quad \gamma \cdot [-T, T] \subset \overline{N}_1 \setminus \overline{N}_0 \Rightarrow \gamma \in N_1 \setminus N_0, \\
(5.14) & \quad \gamma \cdot [-T, T] \subset N_2 \setminus N_0 \Rightarrow \gamma \in \overline{N}_2 \setminus \overline{N}_0, \\
(5.15) & \quad \gamma \cdot [-T, T] \subset \overline{N}_2 \setminus \overline{N}_0 \Rightarrow \gamma \in N_2 \setminus N_0
\end{align*}
are satisfied and let $f' : N_1/N_0 \to \overline{N}_1/\overline{N}_0$ and $g' : \overline{N}_2/\overline{N}_0 \to N_2/N_0$ be defined by
\begin{align*}
(5.16) & \quad f'([\gamma]) = \begin{cases} 
[\gamma \cdot 3t], & \gamma \cdot [0, 2t] \subset N_1 \setminus N_0, \gamma \cdot [t, 3t] \subset \overline{N}_1 \setminus \overline{N}_0, \\
[\overline{N}_0], & \text{otherwise, } \gamma \in N_1,
\end{cases} \\
(5.17) & \quad g'([\gamma]) = \begin{cases} 
[\gamma \cdot 3t], & \gamma \cdot [0, 2t] \subset \overline{N}_2 \setminus \overline{N}_0, \gamma \cdot [t, 3t] \subset N_2 \setminus N_0, \\
[\overline{N}_0], & \text{otherwise, } \gamma \in \overline{N}_2,
\end{cases}
\end{align*}
both for $t \geq T$. Then we have to show that $g' \circ i \circ f' : N_1/N_0 \to N_2/N_0$ is homotopic to the canonical injection $i : N_1/N_0 \to N_2/N_0$. In fact, it follows from (5.12)–(5.15) that for every $\gamma \in N_1$ and every $t \geq T$
\begin{align*}
& \gamma \cdot [0, 2t] \subset N_1 \setminus N_0, \quad \gamma \cdot [t, 3t] \subset \overline{N}_1 \setminus \overline{N}_0, \\
& \gamma \cdot [3t, 5t] \subset \overline{N}_2 \setminus \overline{N}_0, \quad \gamma \cdot [4t, 6t] \subset N_2 \setminus N_0
\end{align*}
is equivalent to $\gamma \cdot [0, 6t] \subset N_2 \setminus N_0$. Hence
\begin{align*}
g' \circ i \circ f'([\gamma]) = \begin{cases} 
[\gamma \cdot 6t], & \gamma \cdot [0, 6t] \subset N_2 \setminus N_0, \\
[\overline{N}_0], & \text{otherwise, } \gamma \in N_1.
\end{cases}
\end{align*}
It follows from Lemma 4.7 that this map is homotopic to $i : N_1/N_0 \to N_2/N_0$. Thus we have established (i).

In order to prove (ii), suppose that the implications (5.14), (5.15) and
\begin{align*}
(5.18) & \quad \gamma \cdot [-T, T] \subset N_2 \setminus N_1 \Rightarrow \gamma \in \overline{N}_2 \setminus \overline{N}_1, \\
(5.19) & \quad \gamma \cdot [-T, T] \subset \overline{N}_2 \setminus \overline{N}_1 \Rightarrow \gamma \in N_2 \setminus N_1
\end{align*}
are satisfied, let $g' : \overline{N}_2/\overline{N}_0 \to N_2/N_0$ be defined by (5.17) and $h' : N_2/N_1 \to \overline{N}_2/\overline{N}_1$ by
\begin{align*}
(5.20) & \quad h'([\gamma]) = \begin{cases} 
[\gamma \cdot 3t], & \gamma \cdot [0, 2t] \subset N_2 \setminus N_1, \gamma \cdot [t, 3t] \subset \overline{N}_2 \setminus \overline{N}_1, \\
[\overline{N}_1], & \text{otherwise, } \gamma \in N_2,
\end{cases}
\end{align*}
both for $t \geq T$. Then we have to show that $h' \circ \pi \circ g' : \overline{N}_2/\overline{N}_0 \to \overline{N}_2/\overline{N}_1$ is homotopic to the canonical projection $\overline{\pi} : \overline{N}_2/\overline{N}_0 \to \overline{N}_2/\overline{N}_1$. In fact, it follows from (5.14), (5.15) and (5.18), (5.19) that for every $\gamma \in \overline{N}_2$ and every $t \geq T$
\begin{align*}
& \gamma \cdot [0, 2t] \subset \overline{N}_2 \setminus \overline{N}_0, \quad \gamma \cdot [t, 3t] \subset N_2 \setminus N_0, \\
& \gamma \cdot [3t, 5t] \subset N_2 \setminus N_1, \quad \gamma \cdot [4t, 6t] \subset \overline{N}_2 \setminus \overline{N}_1
\end{align*}
is equivalent to $\gamma \cdot [0, 6t] \subset \overline{N}_2 \setminus \overline{N}_1$. Hence
\begin{align*}
h' \circ \pi \circ g'([\gamma]) = \begin{cases} 
[\gamma \cdot 6t], & \gamma \cdot [0, 6t] \subset \overline{N}_2 \setminus \overline{N}_1, \\
[\overline{N}_1], & \text{otherwise, } \gamma \in \overline{N}_2.
\end{cases}
\end{align*}
It follows again from Lemma 4.7 that this map is homotopic to \( \bar{\pi} : \bar{N}_2/\bar{N}_0 \to \bar{N}_2/\bar{N}_1 \). This proves statement (ii).

In order to prove statement (iii), choose \( T > 0 \) such that the implications (5.12)–(5.15) as well as (5.18), (5.19) are satisfied, let \( h' : N_2/N_1 \to \bar{N}_2/\bar{N}_1 \) be defined by (5.20) and \( f' : \bar{N}_1/\bar{N}_0 \to N_1/N_0 \) by

\[
(5.21) \quad f'(\gamma) = \begin{cases} 
[\gamma \cdot 3t], & \gamma \cdot [0, 2t] \subset \bar{N}_1 \setminus \bar{N}_0, \\
[0, 3t], & \gamma \cdot [t, 3t] \subset N_1 \setminus N_0, \\
[N_0 \setminus 0], & \text{otherwise}, \gamma \in \bar{N}_1,
\end{cases}
\]

both for \( t \geq T \). Then we have to show that \( \Sigma f' \circ \delta \circ h' : N_2/N_1 \to \Sigma N_1/N_0 \) is homotopic to \( \delta \). First of all, it follows from Lemma 4.7 that the map \( \delta = \delta^0 \) is homotopic to the map \( \delta' : N_2/N_1 \to \Sigma N_1/N_0 \) which is defined by

\[
\delta'(\gamma) = \begin{cases} 
[\gamma \cdot (6t + \tau(\gamma \cdot 3t)), 1 - \tau(\gamma \cdot 3t)], & \text{if } \gamma \cdot [0, 3t] \subset N_2 \setminus N_1, \\
0 < \tau(\gamma \cdot 3t) < 1 \text{ and } \gamma \cdot [0, 6t + \tau(\gamma \cdot 3t)] \subset N_2 \setminus N_0, \\
[N_0 \setminus 0], & \text{otherwise}, \gamma \in N_2.
\end{cases}
\]

A homotopy between \( \Sigma f' \circ \delta \circ h' \) and \( \delta' \) is given by the family of maps \( F^\sigma : N_2/N_1 \to \Sigma N_1/N_0 \), \( 0 \leq \sigma \leq 1 \), defined by

\[
F^\sigma(\gamma) = \begin{cases} 
[\gamma \cdot (6t + \sigma(\gamma)), 1 - \sigma(\gamma)], & \text{if } \gamma \cdot [0, 2t] \subset N_2 \setminus N_1, \\
0 < \sigma(\gamma) < 1 \text{ and } \gamma \cdot [0, 6t + \sigma(\gamma)] \subset N_2 \setminus N_0, \\
[N_0 \setminus 0], & \text{otherwise}, \gamma \in N_2,
\end{cases}
\]

where

\[
\sigma(\gamma) = (1 - \sigma) \tau(\gamma \cdot t) + \sigma \cdot \tau(\gamma \cdot t) - 2t, \quad \gamma \cdot [0, 2t] \subset N_2 \setminus N_1.
\]

Note that \( \tau(\gamma \cdot t) \) makes sense since \( \gamma \cdot [0, 2t] \subset N_2 \setminus N_1 \) implies that \( \gamma \cdot t \in \bar{N}_2 \setminus \bar{N}_1 \). Of course, \( F^1 = \delta' \). Furthermore it follows from (5.13)–(5.15) and (5.18) that for all \( \gamma \in N_2 \) and all \( t \geq T \)

\[
\gamma \cdot [0, 2t] \subset N_2 \setminus N_1, \quad 2t < \tau(\gamma \cdot t) < 2t + 1, \quad \gamma \cdot [0, 6t + \tau(\gamma \cdot 3t)] \subset N_2 \setminus N_0
\]
is equivalent to

\[
\gamma \cdot [0, 2t] \subset N_2 \setminus N_1, \quad \gamma \cdot [t, 3t] \subset \bar{N}_2 \setminus \bar{N}_1, \\
0 < \tau(\gamma \cdot 3t) < 1, \quad \gamma \cdot [3t + \tau(\gamma \cdot 3t), 5t + \tau(\gamma \cdot 3t)] \subset \bar{N}_1 \setminus \bar{N}_0, \\
\gamma \cdot [4t + \tau(\gamma \cdot 3t), 6t + \tau(\gamma \cdot 3t)] \subset N_1 \setminus N_0.
\]

This implies that \( F^0 = \Sigma f' \circ \delta \circ h' \). Hence it remains to show that \( F^\sigma \) is continuous on the domain \( N_2/N_1 \times [0, 1] \). We prove this for the case \( t > 2T \) and \( t \geq 1 \) in seven steps.

**Step 1.** If \( \gamma \cdot [0, 2t] \subset N_2 \setminus N_1 \) and \( t \geq 2T \), then \( |\tau(\gamma \cdot t) - \tau(\gamma \cdot t)| \leq T \).

**Proof.** First, \( \gamma \cdot [0, t + \tau(\gamma \cdot t)] \subset N_2 \setminus N_1 \) and hence \( \gamma \cdot [T, t - T + \tau(\gamma \cdot t)] \subset \bar{N}_2 \setminus \bar{N}_1 \), by (5.18). This implies \( \tau(\gamma \cdot t) \geq \tau(\gamma \cdot t) - T > T \). Furthermore, \( \gamma \cdot [T, t + \tau(\gamma \cdot t)] \subset \bar{N}_2 \setminus \bar{N}_1 \) and hence \( \gamma \cdot [2T, t - T + \tau(\gamma \cdot t)] \subset N_2 \setminus N_1 \), by (5.19). This shows that \( \tau(\gamma \cdot t) \geq \tau(\gamma \cdot t) - T \).
Step 2. If \( t > 2T, \gamma \cdot [0, 2t] \subset N_2 \setminus N_1 \) and \( 0 < \tau^\sigma(\gamma) < 1 \), then

\[
2t - (1 - \sigma)T < \tau(\gamma \cdot t) < 2t + (1 - \sigma)T + 1,
\]

\[
2t - \sigma T < \bar{\tau}(\gamma \cdot t) < 2t + \sigma T + 1.
\]

Proof. Since \( \tau(\gamma \cdot t) \leq \bar{\tau}(\gamma \cdot t) + T \) (Step 1), we have

\[
0 < \tau^\sigma(\gamma) \leq (1 - \sigma)(\tau(\gamma \cdot t) - T) + \sigma \tau(\gamma \cdot t) - 2t = \tau(\gamma \cdot t) - (1 - \sigma)T - 2t.
\]

Since \( \tau(\gamma \cdot t) \geq \bar{\tau}(\gamma \cdot t) - T \), we get

\[
1 > \tau^\sigma(\gamma) \geq (1 - \sigma)(\tau(\gamma \cdot t) - T) + \sigma (\bar{\tau}(\gamma \cdot t) - T) - 2t = \bar{\tau}(\gamma \cdot t) - 2t - \sigma T.
\]

Step 3. If \( \tau(\gamma) < 3t - (1 - \sigma)T \), then \( F^\sigma: N_2/N_1 \to \Sigma N_1/N_0 \) is continuous at \(([\gamma], \sigma)\).

Proof. Choose a neighborhood \( W \) of \((\gamma, \sigma)\) in \( N_2 \times [0, 1] \) such that, whenever \((\gamma', \sigma') \in W\), then \( \tau(\gamma') < 3t - (1 - \sigma')T \). Then it follows from Step 2 that either \( \gamma' \cdot [0, 2t] \subset N_2 \setminus N_1 \) or \( \tau^\sigma(\gamma') \not\in (0, 1) \). Hence \( F^\sigma([\gamma']) = [N_0 \times 0] \) for all \((\gamma', \sigma') \in W\).

Step 4. From now on we can assume that \( \tau(\gamma) \geq 3t - (1 - \sigma)T \) and hence (5.22)

\[
\gamma \cdot [0, 2t] \subset N_2 \setminus N_1.
\]

If (5.22) is satisfied and \( \tau^\sigma(\gamma) \not\in (0, 1) \), then the function \( F \) is continuous at \(([\gamma], \sigma)\).

Proof. First note that \( F^\sigma([\gamma]) = [N_0 \times 0] \). Secondly, note that the function \( \tau^\sigma(\gamma) \) is continuous on the domain \( \{(\gamma, \sigma) \in N_2 \times [0, 1]|\gamma \cdot [0, 2t] \cap N_1 = \emptyset \} \). Hence for every \( \varepsilon > 0 \), there exists a neighborhood \( W \) of \((\gamma, \sigma)\) in \( N_2 \times [0, 1] \) such that, whenever \((\gamma', \sigma') \in W\), then \( \gamma' \cdot [0, 2t] \cap N_1 = \emptyset \) and \( \tau^\sigma(\gamma') \not\in [\varepsilon, 1 - \varepsilon] \). This proves Step 4.

Step 5. From now on we can assume that (5.22) is satisfied and

(5.23)

\[
0 < \tau^\sigma(\gamma) < 1.
\]

If moreover \( \gamma \cdot [0, 6T + \tau^\sigma(\gamma)] \not\subset \text{cl}(N_2 \setminus N_0) \), then \( F \) is continuous at \(([\gamma], \sigma)\).

Proof. There is a \( t^* < 6t + \tau^\sigma(\gamma) \not\in \text{cl}(N_2 \setminus N_0) \). Hence there is a neighborhood \( W \) of \((\gamma, \sigma)\) in \( N_2 \times [0, 1] \) such that, whenever \((\gamma', \sigma') \in W\), then \( \gamma' \cdot [0, 2t] \subset N_2 \setminus N_1, 0 < \tau^\sigma(\gamma') < 1, t^* < 6t + \tau^\sigma(\gamma'), \) and \( \gamma' \cdot t^* \not\in \text{cl}(N_2 \setminus N_0) \). Hence \( F^\sigma([\gamma']) = [N_0 \times 0] \) for all \((\gamma', \sigma') \in W\).

Step 6. If (5.22) and (5.23) are satisfied and if \( \gamma \cdot [0, 6T + \tau^\sigma(\gamma)] \subset N_2 \setminus N_0 \), then \( F \) is continuous at \(([\gamma], \sigma)\).
Proof. First note that, by Step 2, \( \tau(\gamma) < 3t + (1 - \sigma)T + 1 < 4t + 1 \) and therefore \( \gamma \cdot (6t + \tau^a(\gamma)) \in N_1 \) (recall that \( t \geq 1 \)). Now let \( U \) be a neighborhood of \( \gamma \cdot (6t + \tau^a(\gamma)) \) in \( \Gamma \). Moreover, choose a neighborhood \( V \) of \( \gamma \cdot (6t + \tau^a(\gamma)) \) in \( \Gamma \) and an \( \varepsilon > 0 \) such that

\[
V \cdot [-\varepsilon, \varepsilon] \subset U, \quad \gamma \cdot [0, 6t + \tau^a(\gamma) + \varepsilon] \subset N_2 \setminus N_0,
\]

\[
[\tau^a(\gamma) - \varepsilon, \tau^a(\gamma) + \varepsilon] \subset (0, 1).
\]

Then there exists a neighborhood \( W \) of \( (\gamma, \sigma) \) in \( N_2 \times [0, 1] \), such that, whenever \( (\gamma', \sigma') \in W \), then

\[
\gamma' \cdot [0, 2t] \subset N_2 \setminus N_1, \quad \gamma' \cdot [0, 6t + \tau^a(\gamma) + \varepsilon] \subset N_2 \setminus N_0,
\]

\[
|\tau^a(\gamma') - \tau^a(\gamma)| < \varepsilon, \quad \gamma' \cdot (6t + \tau^a(\gamma)) \in V.
\]

Then we get \( \gamma' \cdot [0, 2t] \subset N_2 \setminus N_1, \quad 0 < \tau^a(\gamma') < 1, \quad \gamma' \cdot [0, 6t + \tau^a(\gamma')] \subset N_2 \setminus N_0 \) and \( \gamma' \cdot (6t + \tau^a(\gamma')) \in U, \quad |\tau^a(\gamma') - \tau^a(\gamma)| < \varepsilon \) for all \( (\gamma', \sigma') \in W \) and hence

\[
F^a([\gamma']) = \left[ \gamma' \cdot (6t + \tau^a(\gamma')), 1 - \tau^a(\gamma') \right] \in (U \cap N_1) \times [1 - \tau^a(\gamma) - \varepsilon, 1 - \tau^a(\gamma) + \varepsilon].
\]

This proves Step 6.

Step 7. If (5.22) and (5.23) are satisfied and if \( \gamma \cdot [0, 6t + \tau^a(\gamma)] \subset \text{cl}(N_2 \setminus N_0), \gamma \cdot (6t + \tau^a(\gamma)) \in N_0 \), then \( F \) is continuous at \( ([\gamma], \sigma) \).

Proof. Note that \( F^a([\gamma]) = [N_0 \times 0] \) and choose a neighborhood \( [U] \) of \( [N_0] \) in \( N_1 \setminus N_0 \). Then

\[
U = ([U] \cap N_1 \setminus N_0) \cup N_0 \cup (\Gamma \setminus N_1)
\]

is a neighborhood of \( N_0 \) in \( \Gamma \) and satisfies

\[
[U] = (U \cap N_1 \setminus N_0) \cup [N_0].
\]

Now choose a neighborhood \( V \) of \( N_0 \) in \( \Gamma \) and an \( \varepsilon > 0 \) such that \( V \cdot [-\varepsilon, \varepsilon] \subset U \). Then there exists a neighborhood \( W \) of \( (\gamma, \sigma) \) in \( N_2 \times [0, 1] \) such that whenever \( (\gamma', \sigma') \in W \), then

\[
\gamma' \cdot [0, 2t] \subset N_2 \setminus N_1, \quad 0 < \tau^a(\gamma') < 1,
\]

\[
|\tau^a(\gamma') - \tau^a(\gamma)| < \varepsilon, \quad \gamma' \cdot (6t + \tau^a(\gamma)) \in V.
\]

Hence we obtain \( \gamma' \cdot [0, 2t] \subset N_2 \setminus N_1, \quad 0 < \tau^a(\gamma') < 1, \quad \gamma' \cdot (6t + \tau^a(\gamma')) \in U \) and therefore

\[
F^a([\gamma']) \in \left\{ \left[ \gamma' \cdot (6t + \tau^a(\gamma')) \right], 1 - \tau^a(\gamma') \right\} \subset [N_0 \times 0]
\]

\[
= [U] \times [0, 1]
\]

for all \( (\gamma', \sigma') \in W \). This proves Theorem 5.7. \( \Box \)

The final result of this section shows an interesting relation between the coexact sequence (5.11) and the structure of the isolated invariant set \( S \) (see Conley [3, p. 62]).
**Theorem 5.8.** Let $A, A^*$ be an attractor-repeller pair for the isolated invariant set $S$ in the metric local flow $X \subset \Gamma$ and suppose that $S = A \cup A^*$. Then $h(S) = h(A) \vee h(A^*)$ and the connection map $\delta$ defined by (5.9) and (5.6) is homotopic to the constant map.

**Proof.** If $S = A \cup A^*$, then there exist index pairs $(N_1, N_0)$ and $(N_1^*, N_0^*)$ for $A$ and $A^*$, respectively, such that $N_1 \cap N_1^* = \emptyset$. In this case $(N_1 \cup N_1^*, N_0 \cup N_0^*)$ is an index pair for $S$ and hence

$$h(S) = [N_1 \cup N_1^*/N_0 \cup N_0^*] = [N_1/N_0] \vee [N_1^*/N_0^*] = h(A) \vee h(A^*).$$

Now let $N_0 \subset N_1 \subset N_2$ be a filtration of compact sets in $X$ such that $(N_2, N_0)$ and $(N_1, N_0)$ are index pairs for $S$ and $A$, respectively, and $(N_2, N_1)$ is a regular index pair for $A^*$. Then there exists a $T > 0$ such that

$$(5.24) \quad \gamma \cdot [-T, 0] \subset \text{cl}(N_2 \setminus N_1), \quad \gamma \in N_1 \Rightarrow \gamma \cdot [0, T] \cap N_0 \neq \emptyset.$$

Otherwise, there would exist sequences $\gamma_n \in N_1, t_n > 0$, such that $t_n$ tends to infinity and $\gamma_n \cdot [-t_n, 0] \subset \text{cl}(N_2 \setminus N_1), \gamma_n \cdot [0, t_n] \cap N_0 = \emptyset$. Any limit point $\gamma$ of $\gamma_n$ would then satisfy $\gamma \cdot (-\infty, 0] \subset \text{cl}(N_2 \setminus N_1), \gamma \cdot [0, \infty) \subset \text{cl}(N_1 \setminus N_0)$ and therefore $\omega^*(\gamma) \subset A^*, \omega(\gamma) \subset A, \gamma \cdot R \subset \text{cl}(N_2 \setminus N_0)$. But this would imply $\gamma \in S \setminus (A \cup A^*)$, contradicting $S = A \cup A^*$.

Now let $\delta: N_2/N_1 \to \Sigma N_1/N_0$ be given by (5.9) and (5.6) and let us define the maps $\delta_i: N_2/N_1 \to \Sigma N_1/N_0, f_i: N_1/N_0 \to N_1/N_0$ by

$$\delta_i([\gamma]) = \begin{cases} [\gamma \cdot \tau(\gamma), t + 1 - \tau(\gamma)], & t < \tau(\gamma) < t + 1, \\ [N_0 \times 0], & \text{otherwise}, \end{cases}$$

$$f_i([\gamma]) = \begin{cases} [\gamma \cdot t], & \text{if } \gamma \cdot [0, t] \subset N_1 \setminus N_0, \\ [N_0], & \text{otherwise}, \end{cases}$$

for $0 \leq t \leq T$. Then $\delta_0 = \delta, f_0$ is the identity map, and it follows from (5.24) that $\Sigma f_T \circ \delta_T$ is the constant map. Hence the continuous family of maps $\Sigma f_t \circ \delta_t, 0 \leq t \leq T$, defines a homotopy between $\delta = \Sigma f_0 \circ \delta_0$ and $c = \Sigma f_T \circ \delta_T$. □

**6. Continuation.** The aim of this section is to establish the invariance of the Conley index for isolated invariant sets under (small) perturbations of the flow. For this purpose we first collect some elementary properties of parametrized flows and, in particular, make precise what we mean by continuation of isolated invariant sets (compare Conley [3, Chapter IV.1]).

**6.1. Parametrized flows.** Throughout this section we shall assume that $\Lambda$ is a compact, locally contractible, connected, metric space and $X$ is a locally compact metric space. Furthermore, we assume that $\Gamma$ is a flow and $X \times \Lambda \subset \Gamma$ is a local flow with the property that if $(x, \lambda) \cdot t \in X \times \lambda$, then $(x, \lambda) \cdot t \in X \times \lambda$ for all $x \in X, \lambda \in \Lambda, t \in R$. Then, of course $X \times \Lambda \subset \Gamma$ is a local flow for every $\lambda \in \Lambda$. We will always denote by

$$\pi_X: X \times \Lambda \to X, \quad \pi_\Lambda: X \times \Lambda \to \Lambda$$

the canonical projection maps.
Lemma 6.1. For any compact set \( N \subset X \) the set \( \Lambda(N) = \{ \lambda \in \Lambda \mid N \times \lambda \text{ is an isolating neighborhood in } X \times \lambda \} \) is open in \( \Lambda \).

Proof. Suppose that there is a \( \lambda \in \Lambda \), a sequence \( \lambda_k \in \Lambda \) converging to \( \lambda \) and a compact set \( N \subset X \) such that \( N \times \lambda \) is an isolating neighborhood in \( X \times \lambda \) but \( N \times \lambda_k \) is not an isolating neighborhood in \( X \times \lambda_k \). Then there exists a sequence \( x_k \in N \cap \text{cl}(X \setminus N) \) such that \( (x_k, \lambda_k) \cdot \mathbb{R} \subset N \times \lambda_k \) for all \( k \in \mathbb{N} \). Any limit point \( x \in N \cap \text{cl}(X \setminus N) \) of \( x_k \) satisfies \( (x, \lambda) \cdot \mathbb{R} \subset N \times \lambda \), contradicting the fact that \( N \times \lambda \) is an isolating neighborhood in \( X \times \lambda \). \( \square \)

Let us now introduce the set \( \mathcal{S} = \{ S \times \lambda \mid \lambda \in \Lambda, S \subset X \text{ compact}, S \times \lambda \text{ is an isolated invariant set in } X \times \lambda \} \) of isolated invariant sets in \( X \times \lambda \). For every compact set \( N \subset X \) let us define the map

\[
\sigma_N : \Lambda(N) \to \mathcal{S}, \quad \sigma_N(\lambda) = I(N \times \lambda).
\]

Then we consider on the space \( \mathcal{S} \) the topology which is generated by the sets \( \{ \sigma_N(U) \mid N \subset X \text{ compact}, U \subset \Lambda(N) \text{ open} \} \). Note that \( \mathcal{S} \) is not necessarily Hausdorff as Figure 4 shows.

Lemma 6.2. Let \( N, \overline{N} \) be compact subsets of \( X \) and let \( U \subset \Lambda(N) \) and \( \overline{U} \subset \Lambda(N) \) be open. Then the following statements hold.

(i) \( \Lambda(N, \overline{N}) = \{ \lambda \in \Lambda(N) \cap \Lambda(N) \mid I(N \times \lambda) = I(\overline{N} \times \lambda) \} \) is open in \( \Lambda \).

(ii) \( \sigma_N(U) \cap \sigma_N(\overline{U}) = \sigma_N(U \cap \overline{U} \cap \Lambda(N, \overline{N})) \).

(iii) \( \sigma_N : \Lambda(N) \to \mathcal{S} \) is continuous.

Proof. (i) Let \( \lambda \in \Lambda(N) \cap \Lambda(N) \) such that \( I(N \times \lambda) = I(\overline{N} \times \lambda) \) and suppose that there exists a sequence \( \lambda_k \) converging to \( \lambda \) with \( \lambda_k \in \Lambda(N) \cap \Lambda(N) \) and \( I(N \times \lambda_k) \subset I(\overline{N} \times \lambda_k) \). Let \( x_k \in X \) such that \( (x_k, \lambda_k) \in I(\overline{N} \times \lambda_k) \setminus I(N \times \lambda_k) \). Let \( t_k \in \mathbb{R} \) such that \( (x_k, \lambda_k) \cdot t_k \notin N \times \lambda_k \). Let \( y \in X \) be chosen such that \( (y, \lambda) \) is a limit point of \( (x_k, \lambda_k) \cdot t_k \). Then \( (y, \lambda) \cdot \mathbb{R} \subset \overline{N} \times \lambda \) and hence \( (y, \lambda) \cdot \mathbb{R} \subset N \times \lambda \) since \( I(\overline{N} \times \lambda) = I(N \times \lambda) \). But since \( (x_k, \lambda_k) \cdot t_k \notin N \times \lambda_k \), we have \( y \in N \cap \text{cl}(X \setminus N) \) contradicting \( \lambda \in \Lambda(N) \).

(ii) Follows from the definitions.

(iii) If \( \overline{N} \subset X \) is compact and \( \overline{U} \subset \Lambda(\overline{N}) \) open, then

\[
\sigma_N^{-1}(\sigma_N(\overline{U})) = \overline{U} \cap \Lambda(N, \overline{N})
\]

is open in \( \Lambda \). \( \square \)
The previous lemma shows that the canonical projection map $\pi_\Lambda: \mathcal{S} \to \Lambda$ is a local homeomorphism. If $S \times \lambda \in \mathcal{S}$ and $N \times \lambda$ is an isolating neighborhood for $S \times \lambda$ in $X \times \lambda$, then the map $\sigma_N: \Lambda(N) \to \mathcal{S}$ is an inverse of the restriction of $\pi_\Lambda: \mathcal{S} \to \Lambda$ to the neighborhood $\sigma_N(\Lambda(N))$ of $S \times \lambda$ in $\mathcal{S}$.

**Remark 6.3.** Let $\sigma: \Lambda \to \mathcal{S}$ be a continuous map with $\pi_\Lambda \circ \sigma = 1_\Lambda$ and let $N \subset X$ be a compact set. Then the set

$$
\Lambda(N, \sigma) = \sigma^{-1}(\sigma_N(\Lambda(N))) = \{ \lambda \in \Lambda(N) | \sigma(\lambda) = I(N \times \lambda) \}
$$

is open in $\Lambda$.

Whenever $N \subset X \times \Lambda$ and $K \subset \Lambda$ are compact sets we define

$$
N(K) = N \cap X \times K.
$$

If $N$ is an isolating neighborhood for the isolated invariant set $S$ in $X \times \Lambda$, then $N(K)$ is an isolating neighborhood for $S(K)$ in $X \times K$.

**Lemma 6.4.** (i) Let the function $\sigma: \Lambda \to \mathcal{S}$ satisfy $\pi_\Lambda \circ \sigma = 1_\Lambda$. Then $\sigma$ is continuous if and only if

$$
S = \bigcup_{\lambda \in \Lambda} \sigma(\lambda)
$$

is an isolated invariant set in $X \times \Lambda$.

(ii) Let $\sigma: \Lambda \to \mathcal{S}$ and $\tau: \Lambda \to \mathcal{S}$ be continuous functions with $\pi_\Lambda \circ \sigma = 1_\Lambda$ and $\pi_\Lambda \circ \tau = 1_\Lambda$. Then the function $\sigma \cap \tau: \Lambda \to \mathcal{S}$ which sends $\lambda \in \Lambda$ into $\sigma(\lambda) \cap \tau(\lambda) \in \mathcal{S}$ is continuous.

(iii) Let $\sigma: \Lambda \to \mathcal{S}$ and $\alpha: \Lambda \to \mathcal{S}$ be continuous functions such that $\pi_\Lambda \circ \sigma = 1_\Lambda$ and $\alpha(\lambda)$ is an attractor in $\sigma(\lambda)$. Furthermore, let $\alpha^*(\lambda)$ denote the complementary repeller of $\alpha(\lambda)$ in $\sigma(\lambda)$ and let $S \subset X \times \Lambda$ be defined by (6.1). Then $\alpha^*: \Lambda \to \mathcal{S}$ is continuous and the sets

$$
A = \bigcup_{\lambda \in \Lambda} \alpha(\lambda), \quad A^* = \bigcup_{\lambda \in \Lambda} \alpha^*(\lambda)
$$

form an attractor-repeller pair in $S$.

**Proof.** (i) Let us first assume that $S$ is an isolated invariant set, let $N$ be an isolating neighborhood for $S$ in $X \times \Lambda$ and let $N_0 \times \lambda_0$ be an isolating neighborhood for $\sigma(\lambda_0)$ in $X \times \lambda_0$ such that $N_0 \times \lambda_0 \subset (X \times \Lambda) \setminus \text{cl}(X \times \Lambda) \setminus N$. Then there exists a compact neighborhood $K_0$ of $\lambda_0$ in $\Lambda$ such that $N_0 \times K_0 \subset N$ and $K_0 \subset \Lambda(N_0)$. Furthermore we can choose $K_0$ small enough such that $S(K_0) \subset N_0 \times K_0$ since otherwise there would exist a sequence $(x_k, \lambda_k) \in S$ such that $\lambda_k$ converges to $\lambda_0$ and $x_k \in X \setminus N_0$ which would imply that $(x_0, \lambda_0) \in \sigma(S_0) \cap \text{cl}(X \setminus N_0 \times \lambda_0)$ for any limit point $x_0$ of $x_k$. We conclude that $N_0 \times \lambda$ is an isolating neighborhood for $S(\lambda)$ in $X \times \lambda$ whenever $\lambda \in K_0$ and hence $S(\lambda) = \sigma_{N_0}(\lambda)$ for all $\lambda \in K_0$. Now the continuity follows from Lemma 6.2(iii).

Conversely suppose that $\sigma: \Lambda \to \mathcal{S}$ is a continuous function with $\pi_\Lambda \circ \sigma = 1_\Lambda$. Then there exists an isolating neighborhood $N(\lambda) \times \lambda$ for $\sigma(\lambda)$ in $X \times \lambda$ for every $\lambda \in \Lambda$. Furthermore, it follows from Remark 6.3 that the set

$$
\Lambda(N(\lambda), \sigma) = \{ \mu \in \Lambda(N(\lambda)) | \sigma(\mu) = I(N(\lambda) \times \mu) \}
$$
is open in $\Lambda$ for every $\lambda \in \Lambda$ and hence there exists an open neighborhood $U(\lambda)$ of $\lambda$ in $\Lambda$ such that $N(\lambda) \times \mu$ is an isolating neighborhood for $\sigma(\mu)$ in $X \times \mu$ whenever $\mu \in \text{cl}(U(\lambda))$. Since $\Lambda$ is compact, there exists a finite subcover $U(\lambda_1), \ldots, U(\lambda_n)$ of $\Lambda$. Now define the set

$$N = \left\{ (x, \mu) \in X \times \Lambda | \mu \in U(\lambda_j) \Rightarrow x \in N(\lambda_j) \right\}.$$  

Then $N$ is a closed subset of $\bigcup_{j=1}^n N(\lambda_j) \times \Lambda$ and therefore $N$ is compact. Moreover, if $(x, \mu) \in S$, then

$$U = \bigcap_{\mu \notin \text{cl}(U(\lambda_j))} \Lambda \setminus U(\lambda_j)$$

is a neighborhood of $\mu$ in $\Lambda$,

$$W = \bigcap_{\mu \in \text{cl}(U(\lambda_j))} N(\lambda_j)$$

is a neighborhood of $x$ in $X$ and $W \times U \subset N$. Therefore $N$ is a neighborhood of $S$ in $X \times \Lambda$. Finally, $S = f(N)$ since $(x, \mu) \cdot R \subset N$ and $\mu \in U(\lambda_j)$ imply that $(x, \mu) \cdot R \subset N(\lambda_j) \times \mu$ and thus $(x, \mu) \in \sigma(\mu)$.

(ii) Choose compact sets $A_1 \subset X$ and $A_2 \subset X$ such that $N_1 \times \lambda_0$ and $N_2 \times \lambda_0$ are isolating neighborhoods for $\sigma(\lambda_0)$ and $\tau(\lambda_0)$, respectively, in $X \times \lambda_0$. By Remark 6.3, there exists a compact neighborhood $K_0$ of $\lambda_0$ in $\Lambda$ such that $K_0 \subset \Lambda(\lambda_0, \sigma) \cap \lambda(\lambda_0, \tau)$. Hence $N_1 \cap N_2 \times \lambda$ is an isolating neighborhood for $\sigma(\lambda) \cap \tau(\lambda)$ in $X \times \lambda$ whenever $\lambda \in K_0$. This implies that $\sigma \cap \tau(\lambda) = \sigma_{N_1 \cap N_2}(\lambda)$ for every $\lambda \in K_0$ and thus the continuity follows from Lemma 6.2.

(iii) It follows from (i) that $A$ is a compact subset of $S$. We show that $\text{cl}(A^*) \cap A = \emptyset$. For this purpose let $N \times \lambda$ be an isolating neighborhood of $\alpha(\lambda)$ in $X \times \lambda$ with $N \times \lambda \cap A^*(\lambda) = \emptyset$. Suppose that there exists a sequence $(x_k, \lambda_k) \in A^*(\lambda_k)$ converging to $(x, \lambda) \in A^*(\lambda)$ with $x_k \in N$, $\lambda_k \in \Lambda(N, \alpha)$. Then $\omega(x_k, \lambda_k) \cap A^*(\lambda_k) = \emptyset$ and hence $(x_k, \lambda_k) \cdot [0, \infty) \subset N \times \lambda_k$. Let $t_k > 0$ be the maximal time with $(x_k, \lambda_k) \cdot [0, t_k] \subset N \times \lambda_k$ and let $(y, \lambda) \in \sigma(\lambda)$ be any limit point of $(x_k, \lambda_k) \cdot t_k$. Then $y \notin \text{int} N$ and hence $(y, \lambda) \in \alpha(\lambda)$. But if the sequence $t_k$ is bounded then $(y, \lambda) \in (x, \lambda) \cdot R \subset \alpha(\lambda)$ and if the sequence is unbounded then $(y, \lambda) \cdot (\infty, 0) \subset N \times \lambda$ and therefore $(y, \lambda) \in \omega(N \times \lambda \cap \sigma(\lambda)) = \alpha(\lambda)$, a contradiction. We conclude that $\text{cl}(A^*) \cap A = \emptyset$. Hence there exists a neighborhood $U$ of $A$ in $S$ such that $\text{cl}(U) \cap A^* = \emptyset$. If $(x, \lambda) \cdot (-\infty, 0] \subset U$, then $(x, \lambda) \in \sigma(\lambda)$ and $\omega^*(x, \lambda) \cap A^*(\lambda) = \emptyset$ and therefore $(x, \lambda) \in \alpha(\lambda) \subset A$ (Lemma 3.2). By Lemma 3.1, this implies that $A$ is an attractor in $S$. It follows again from Lemma 3.2 that its complementary repeller is given by

$$A^* = \bigcup_{\lambda \in \Lambda} \alpha^*(\lambda) = \{ (x, \lambda) \in S | \omega(x, \lambda) \cap A = \emptyset \}.$$  

In some situations it might be useful to consider general maps $\tau: \Delta \rightarrow \mathcal{S}$ such that $\pi_\Lambda \circ \tau: \Delta \rightarrow \Lambda$ is not necessarily injective. This can be reformulated within the framework of this section by considering $X \times \Delta$ as a local flow in $\Gamma \times \Delta$, where $(x, \xi) \in X \times \Delta$ is identified with the triple $(x, \pi_\Lambda \circ \tau(\xi), \xi) \in X \times \Lambda \times \Delta \subset \Gamma \times \Delta$. 

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Introducing the space

\[ \mathcal{S}_\Delta = \{ S \times \lambda \times \xi | \xi \in \Delta, S \times \lambda \in \mathcal{S}, \lambda = \pi_\Delta \circ \tau(\xi) \} \]

endowed with an analogous topology as \( \mathcal{S} \), it is then easy to see that the map \( \tau_\Delta: \Delta \to \mathcal{S}_\Delta \) defined by \( \tau_\Delta(\xi) = \tau(\xi) \times \xi \) for \( \xi \in \Delta \) is continuous.

At the end of this section we point out that some (global) phenomena cannot be described within the framework of product flows \( X \times \Lambda \). An example for such a situation is the flow on a Moebius strip which is illustrated in Figure 5 and involves a change of orientation in the space \( X \). In such cases it might be useful to consider a local flow on a (locally trivial) fibration instead of the product space \( X \times \Lambda \). This could be a problem for future investigations.

6.2. Local continuation. In this section we are going to prove a local continuation theorem for the Conley index of isolated invariant sets. The result has been formulated in Conley [3] but the proof is only roughly sketched. A complete but rather complicated proof can be found in Kurland [8]. We present a simplified proof which is based on the results in §4.2.

Throughout this section we will adopt the notation of §6.1 and assume in addition that \( \sigma: \Lambda \to \mathcal{S} \) is a continuous map with \( \pi_\Lambda \circ \sigma = 1_\Lambda \) and that the isolated invariant set \( S \) in \( X \times \Lambda \) is defined by (6.1). Note that for any index pair \( (N_1, N_0) \) for \( S \) in \( X \times \Lambda \) and for any compact set \( K \subset \Lambda \) the sets \( (N_1(K), N_0(K)) \) form an index pair for the isolated invariant set \( S(K) \) in \( X \times K \).

The local continuation theorem now consists of two parts. The first and easy part is to show that for any index pair \( (N_1, N_0) \) for \( S \) in \( X \times \Lambda \) the canonical injection map \( j(\lambda): N_1(\lambda)/N_0(\lambda) \to N_1/N_0 \) induces a morphism between the corresponding connected simple systems which is independent of the choice of the index pair (Proposition 6.5). The main part is then to show that this morphism is in fact a local isomorphism (Theorem 6.7). These facts will then be used to obtain a continuation result for the coexact sequence of §5 which is associated with an attractor-repeller pair in \( S \) (§6.4).

**Proposition 6.5.** Let \( (N_1, N_0) \) be an index pair for \( S \) in \( X \times \Lambda \). Then the canonical injection map \( j(\lambda): N_1(\lambda)/N_0(\lambda) \to N_1/N_0 \) induces a morphism between the connected simple systems \( I(\sigma(\lambda), X \times \lambda) \) and \( I(S, X \times \Lambda) \) which is independent of the choice of the index pair.
PROOF. Let \((N_1, N_0)\) be another index pair for \(S\) in \(X \times \Lambda\), choose \(T > 0\) such that
\[
(x, \mu) \cdot [-T, T] \subset N_1 \setminus N_0 \Rightarrow (x, \mu) \in \overline{N_1} \setminus \overline{N_0},
\]
\[
(x, \mu) \cdot [-T, T] \subset \overline{N_1} \setminus \overline{N_0} \Rightarrow (x, \mu) \in N_1 \setminus N_0
\]
and define the maps \(f(\lambda)' : N_1(\lambda)/N_0(\lambda) \to \overline{N_1}(\lambda)/\overline{N_0}(\lambda)\) and \(g' : \overline{N_1}/\overline{N_0} \to N_1/N_0\) by
\[
f(\lambda)'[x, \lambda] = \begin{cases} (x, \lambda) \cdot 3t, & (x, \lambda) \cdot [0, 2t] \subset N_1 \setminus N_0, \ (x, \lambda) \cdot [t, 3t] \subset \overline{N_1} \setminus \overline{N_0}, \\ \overline{N_0}(\lambda), & \text{otherwise}, \ (x, \lambda) \in N_1(\lambda), \end{cases}
\]
\[
g'[x, \mu] = \begin{cases} (x, \mu) \cdot 3t, & (x, \mu) \cdot [0, 2t] \subset \overline{N_1} \setminus \overline{N_0}, \ (x, \mu) \cdot [t, 3t] \subset N_1 \setminus N_0, \\ N_0, & \text{otherwise}, \ (x, \mu) \in \overline{N_1}, \end{cases}
\]
for \(t \geq T\). Then the composed map \(g' \circ j(\lambda) \circ f(\lambda)' : N_1(\lambda)/N_0(\lambda) \to N_1/N_0\) is given by
\[
g' \circ j(\lambda) \circ f(\lambda)'[x, \lambda] = \begin{cases} (x, \lambda) \cdot 6t, & (x, \lambda) \cdot [0, 6t] \subset N_1 \setminus N_0, \\ N_0, & \text{otherwise}, \end{cases}
\]
for \((x, \lambda) \in N_1(\lambda)\) and hence is homotopic to the injection \(j(\lambda) : N_1(\lambda)/N_0(\lambda) \to N_1/N_0\). □

The next lemma provides the crucial step in proving that the injection map \(j(\lambda) : N_1(\lambda)/N_0(\lambda) \to N_1/N_0\) is (locally) a homotopy equivalence.

**Lemma 6.6.** Let \((N_1, N_0)\) be an index pair for \(S\) in \(X \times \Lambda\) and let \(\lambda_0 \in \Lambda\) be given. Then there exists a compact neighborhood \(K\) of \(\lambda_0\) in \(\Lambda\) and times \(T_1 > 2T_0 > 0\) such that the following statements hold.

(i) \(N \times K\) is an isolating neighborhood of \(S(K)\) and \(U \times K\) is a neighborhood of \(S(K)\) in \(X \times K\), where the sets \(N \subset X\) and \(U \subset X\) are defined by

\[
N = \text{cl}(\pi_X(N_1(\Lambda) \setminus N_0(\Lambda))) = \pi_X(\text{cl}(N_1(\Lambda) \setminus N_0(\Lambda))),
\]
\[
U = \text{int} \bigcap_{\lambda \in K} \pi_X(N_1(\lambda) \setminus N_0(\lambda)) \quad \text{rel } X.
\]

(ii) For all \(x \in X\) and \(\lambda, \mu \in K\) and \(T \geq T_1\) the following implications hold.

\[
(x, \mu) \cdot [-T_0, T_0] \subset N \times K \Rightarrow x \in U,
\]
\[
(x, \mu) \cdot [T_0, T] \subset U \times K \Rightarrow \pi_X((x, \mu) \cdot T), \lambda) \cdot [0, T] \cap N_0 \neq \emptyset.
\]

**Proof.** In order to prove statement (i) let us choose isolating neighborhoods \(N\) and \(\overline{N}\) for \(S\) in \(X \times \Lambda\) such that \(N_1 \setminus N_0\) is a neighborhood of \(N\) in \(X \times \Lambda\) and \(\overline{N}\) is a neighborhood of \(\text{cl}(N_1 \setminus N_0)\) in \(X \times \Lambda\) (Lemma 3.7). By Remark 6.3, there exists a compact neighborhood \(K\) of \(\lambda_0\) in \(\Lambda\) such that
\[
K \subset \Lambda\left(\pi_X(N_0(\lambda_0)), \sigma\right) \cap \Lambda\left(\pi_X(\overline{N}(\lambda_0)), \sigma\right).
\]
This implies that
\[ \pi_X(N(\lambda_0)) \times K, \quad \pi_X(\overline{N}(\lambda_0)) \times K \]
are isolating neighborhoods for \( S(K) \) in \( X \times K \). Furthermore we can choose \( K \) small enough such that
\[ \pi_X(N(\lambda_0)) \times K \subset N_1 \setminus N_0, \]
\[ \pi_X(N_1(\lambda) \setminus N_0(\lambda)) \subset \pi_X(\overline{N}(\lambda_0)) \quad \forall \lambda \in K. \]

The first inclusion is obvious since \( N(\lambda_0) \) is contained in the interior of \( N_1 \setminus N_0 \) relative \( X \times \Lambda \). If (6.8) would not hold for any neighborhood \( K \) of \( \lambda_0 \), then there would exist a sequence \((x_k, \lambda_k) \in N_1 \setminus N_0\) such that \( \lambda_k \) tends to \( \lambda_0 \) and \((x_k, \lambda_0) \notin N\). But then any limit point \( x_0 \) of \( x_k \) would satisfy \((x_0, \lambda_0) \in \text{cl}(N_1 \setminus N_0)\), and \((x_0, \lambda_0) \in \text{cl}((X \times \Lambda) \setminus \overline{N})\), contradicting the fact that \( N \) is a neighborhood of \( \text{cl}(N_1 \setminus N_0) \) in \( X \times \Lambda \). From (6.7) and (6.8) we conclude that
\[ \pi_X(N(\lambda_0)) \subset \pi_X(N_1(\lambda) \setminus N_0(\lambda)) \subset \pi_X(\overline{N}(\lambda_0)) \]
for all \( \lambda \in K \). This proves statement (i).

In order to prove statement (ii), let us choose the compact neighborhood \( K \) of \( \lambda_0 \) in \( \Lambda \) as in (i). Then it follows from Lemma 4.6 that (6.5) holds for some \( T_0 > 0 \). Furthermore note that once (6.6) is satisfied for some \( T = T_1 > 2T_0 \), then it holds for all \( T \geq T_1 \) since the first condition in (6.6) together with (6.5) guarantees that \((x, \mu) \cdot [T_0, T - T_0] \subset C U \times K\). Now suppose that (6.6) does not hold for any \( T = T_1 > 0 \) and any neighborhood of \( \lambda_0 \) in \( \Lambda \). Then there would exist sequences \( x_k \in X \), \( \lambda_k \in K \), \( \mu_k \in K \), \( T_k > 2T_0 \), \( t_k \in [T_0, T_k] \) such that \( T_k \) tends to infinity, \( \lambda_k \) and \( \mu_k \) tend to \( \lambda_0 \) and
\[ (\pi_X((x_k, \mu_k) \cdot [0, T_k]), \lambda_k) \subset \text{cl}(N_1(K) \setminus N_0(K)), \]
\[ (x_k, \mu_k) \cdot t_k \notin U \times K, \]
\[ (\pi_X((x_k, \mu_k) \cdot T_k), \lambda_k) \cdot [0, T_k] \subset N_1 \setminus N_0. \]
It follows from (6.9) and (6.5) that \((x_k, \mu_k) \cdot [T_0, T_k - T_0] \subset U \times K\) and therefore \( T_k \geq T_k - T_0 \). Now let \( x_0 \in N \) be a limit point of \( \pi_X((x_k, \mu_k) \cdot T_k) \) and let \( \tau \geq 0 \) be a limit point of \( T_k - t_k \). Then it follows from (6.9) and (6.11) that \((x_0, \lambda_0) \cdot R \subset \text{cl}(N_1 \setminus N_0)\) and hence \((x_0, \lambda_0) \in S\). But it follows from (6.10) that \((x_0, \lambda_0) \cdot (-\tau) \notin U \times K\), contradicting the fact that \( S(K) \subset U \times K \). □

**Theorem 6.7.** Let \((N_1, N_0)\) be an index pair for \( S \) in \( X \times \Lambda \), let \( \lambda_0 \in \Lambda \) be given and let \( K \) be a compact, contractible neighborhood of \( \lambda_0 \) in \( \Lambda \) which satisfies the conditions of Lemma 6.6 for \( T_1 > 2T_0 > 0 \). Then the injection map
\[ j(\lambda) = j_K(\lambda): N_1(\lambda)/N_0(\lambda) \to N_1(K)/N_0(K) \]
is a homotopy equivalence for every \( \lambda \in K \) and the map \( f(\lambda) = f_K(\lambda): N_1(K)/N_0(K) \rightarrow N_1(\lambda)/N_0(\lambda) \), defined by

\[
(6.12) \quad f_K(\lambda)[x, \mu] = \begin{cases} 
[(\pi_x((x, \mu) \cdot 3T), \lambda) \cdot T], & \text{if } (x, \mu) \cdot [0, 2T] \subset N_1 \setminus N_0, \\
(\pi_x((x, \mu) \cdot [T, 3T]), \lambda) \subset N_1 \setminus N_0, \\
(\pi_x((x, \mu) \cdot 3T), \lambda) \cdot [0, T] \subset N_1 \setminus N_0, \\
[N_0(\lambda)], & \text{otherwise},
\end{cases}
\]

for \( (x, \mu) \in N_1(K) \), is a homotopy inverse of \( j(\lambda) \).

**Proof.** First note that the composed map \( f(\lambda) \circ j(\lambda): N_1(\lambda)/N_0(\lambda) \rightarrow N_1(\lambda)/N_0(\lambda) \) is given by

\[
f(\lambda) \circ j(\lambda)[x, \lambda] = \begin{cases} 
[(x, \lambda) \cdot 4T], & \text{if } (x, \lambda) \cdot [0, 4T] \subset N_1 \setminus N_0, \\
[N_0(\lambda)], & \text{otherwise},
\end{cases}
\]

for \( (x, \lambda) \in N_1(\lambda) \) and it follows from Lemma 4.7 that this map is homotopic to the identity. In order to show that \( j(\lambda) \circ f(\lambda) \) is also homotopic to the identity we make use of the fact that \( K \) is contractible which means that there exists a function \( r: K \times [0,1] \rightarrow K \) such that

\[
r(\mu, 0) = \mu, \quad r(\mu, 1) = \lambda \quad \forall \mu \in K.
\]

(6.13)

Now we define the map \( F: N_1(K)/N_0(K) \times [0,1] \rightarrow N_1(K)/N_0(K) \) by

\[
F((x, \mu), [0,1]) = \begin{cases} 
[(\pi_x((x, \mu) \cdot 3T), r(\mu, \xi)) \cdot T], & \text{if } (x, \mu) \cdot [0, 2T] \subset N_1 \setminus N_0, \\
(\pi_x((x, \mu) \cdot [T, 3T]), r(\mu, \xi)) \subset N_1 \setminus N_0, \\
(\pi_x((x, \mu) \cdot 3T), r(\mu, \xi)) \cdot [0, T] \subset N_1 \setminus N_0, \\
[N_0(K)], & \text{otherwise},
\end{cases}
\]

for \( (x, \mu) \in N_1(K) \) and \( \xi \in [0,1] \). Then it follows from (6.13) and (6.12) that \( F(\cdot, 1) = j(\lambda) \circ f(\lambda) \) and that \( F(\cdot, 0): N_1(K)/N_0(K) \rightarrow N_1(K)/N_0(K) \) is given by

\[
F((x, \mu), 0) = \begin{cases} 
[(x, \mu) \cdot 4T], & \text{if } (x, \mu) \cdot [0, 4T] \subset N_1 \setminus N_0, \\
[N_0(K)], & \text{otherwise},
\end{cases}
\]

for \( (x, \mu) \in N_1(K) \) and therefore is homotopic to the identity (Lemma 4.7). It remains to show that \( F \) is continuous.

In the following cases the continuity can be obtained by standard arguments as in the proof of Lemma 4.7 or Theorem 5.7(iii).

1. \( (x, \mu) \cdot [0,2T] \not\subset \text{cl}(N_1(K) \setminus N_0(K)) \),
2. \( (\pi_x((x, \mu) \cdot [T, 3T]), r(\mu, \xi)) \not\subset \text{cl}(N_1(K) \setminus N_0(K)) \),
3. \( (\pi_x((x, \mu) \cdot 3T), r(\mu, \xi)) \cdot [0, T] \not\subset \text{cl}(N_1(K) \setminus N_0(K)) \),
4. \( (\pi_x((x, \mu) \cdot 3T), r(\mu, \xi)) \cdot T \subset N_0 \).

Therefore we can assume from now on that

\[
(6.14) \quad (x, \mu) \cdot [0,2T] \subset \text{cl}(N_1(K) \setminus N_0(K)),
\]

\[
(6.15) \quad (\pi_x((x, \mu) \cdot [T, 3T]), r(\mu, \xi)) \subset \text{cl}(N_1(K) \setminus N_0(K)),
\]

\[
(6.16) \quad (\pi_x((x, \mu) \cdot 3T), r(\mu, \xi)) \cdot [0, T] \subset N_1 \setminus N_0.
\]
Now Lemma 6.7 comes in. First of all, since $T > 2T_0$ it follows from (6.14) and (6.5) that $(x, \mu) \cdot [T, T + T_0] \subset U \times K$, where $U \subset X$ is defined by (6.4). Secondly, it follows from (6.15), (6.16) and (6.6) that $(x, \mu) \cdot [T + T_0, 3T] \subset U \times K$. In particular $(x, \mu) \cdot 2T \not\in N_0$. Therefore the conditions (6.14) and (6.15) can be replaced by

\begin{equation}
(x, \mu) \cdot [0, 2T] \subset N_1 \setminus N_0,
\end{equation}

\begin{equation}
(x, \mu) \cdot [T, 3T] \subset U \times K.
\end{equation}

But the conditions (6.16), (6.17) and (6.18) together are stable with respect to small variations in $(x, \mu) \in N_1(K)$ and $\xi \in [0, 1]$. This proves the continuity of $F$. \qed

Since $\Lambda$ is a connected space, we obtain as an immediate consequence of Theorem 6.7 that the homotopy index $h(\sigma(\lambda))$ of the isolated invariant set $\sigma(\lambda)$ in $X \times \lambda$ is independent of $\lambda$. In fact, it depends only on the path-component of $\sigma(\lambda)$ in $\mathcal{S}$ (Lemma 6.4 together with Theorem 6.7). Furthermore, combining Theorem 6.7 with Proposition 6.5, we obtain that there is locally a unique isomorphism between the connected simple systems $I(\sigma(\lambda), X \times \lambda)$ and $I(\sigma(\mu), X \times \mu)$. If $\Lambda$ is connected, then such an isomorphism exists for any two $\lambda, \mu \in \Lambda$. However, we will see in the next section that globally this isomorphism need no longer be unique.

6.3. Global continuation. We first point out that the global isolated invariant set $S$ in $X \times \Lambda$ may have a much richer structure than the isolated invariant set $\sigma(\lambda)$ in a single fiber $X \times \lambda$. This is illustrated by Figure 6 in which the flow on $\Gamma = X \times \Lambda = R \times S^1$ is given by $(x, \lambda) \cdot t = (xe^t, \lambda)$ for $x \in R$ and $\lambda \in S^1$. Then the homotopy index of $\sigma(\lambda) = (0, \lambda)$ is $h(\sigma(\lambda)) = \Sigma^1$ but $h(S) = \Sigma^2 \vee \Sigma^1$. Hence the global injection $j(\lambda): N_1(\lambda)/N_0(\lambda) \to N_1/N_0$ cannot be a homotopy equivalence in this case. However, if $\Lambda$ is a contractible space, one might expect that this global injection is indeed a homotopy equivalence. We leave this as an open problem.

In order to obtain an isomorphism between any two connected simple systems $I(\sigma(\lambda), X \times \lambda)$ and $I(\sigma(\mu), X \times \mu)$ it is useful to rephrase the statement of Theorem 6.7 as follows.

**Corollary 6.8.** Let $(N_1, N_0)$ be an index pair for $S$ in $X \times \Lambda$ and let $K \subset \Lambda$ be a compact, contractible set which satisfies the conditions of Lemma 6.6 for $T_1 > 2T_0 > 0$. For $\lambda, \mu \in K$ and $T \geq T_1$ let the map $F(\lambda, \mu) = F_K(\lambda, \mu): N_1(\mu)/N_0(\mu) \to N_1(\lambda)/N_0(\lambda)$ be defined by

\begin{equation}
F_K(\lambda, \mu)[x, \mu] = \begin{cases}
\left[\left(\pi_X((x, \mu) \cdot 3T), \lambda \cdot T\right), \text{if } (x, \mu) \cdot [0, 2T] \subset N_1 \setminus N_0,
\left(\pi_X((x, \mu) \cdot [T, 3T]), \lambda\right) \subset N_1 \setminus N_0,
\left(\pi_X((x, \mu) \cdot 3T), \lambda \right) \cdot [0, T] \subset N_1 \setminus N_0,
[N_1(\lambda)], \text{otherwise},
\end{cases}
\end{equation}
for \((x, \mu) \in N_1(\mu)\). Then for all \(\lambda, \mu, \nu \in K\)

\[
(6.20) \quad F_K(\lambda, \mu) \circ F_K(\mu, \nu) \sim F_K(\lambda, \nu),
\]

\[
(6.21) \quad F_K(\lambda, \lambda) \sim 1.
\]

In particular, \(F_K(\lambda, \mu)\) is a homotopy equivalence with homotopy inverse \(F_K(\mu, \lambda)\).

Furthermore, if \((\overline{N}_1, \overline{N}_0)\) is another index pair for \(S\) in \(X \times \Lambda\) with respect to which \(K\) satisfies the conditions of Lemma 6.6 and if \(\overline{F}_K(\lambda, \mu): \overline{N}_1(\mu) / \overline{N}_0(\mu) \to \overline{N}_1(\lambda) / \overline{N}_0(\lambda)\) is defined analogously to (6.19), then the maps \(\overline{F}_K(\lambda, \mu)\) and \(F_K(\lambda, \mu)\) induce the same isomorphism between the connected simple systems \(I(\sigma(\mu), X \times \mu)\) and \(I(\sigma(\lambda), X \times \lambda)\).

**Proof.** With the notation of Theorem 6.7 we have \(F_K(\lambda, \mu) = f_K(\lambda) \circ j_K(\mu)\). Therefore (6.20) and (6.21) follow from the fact that \(f_K(\lambda) \circ j_K(\lambda)\) and \(j_K(\lambda) \circ f_K(\lambda)\) are homotopic to the respective identity maps for every \(\lambda \in K\). The remainder of the corollary is a consequence of Proposition 6.5. □

If \(\Lambda\) is a compact, connected space we can connect any two points \(\mu \in \Lambda\) and \(\lambda \in \Lambda\) by a finite sequence of compact sets \(K\) each of which satisfies the conditions of Lemma 6.6. Any such sequence induces an isomorphism between the connected simple systems \(I(\sigma(\mu), X \times \mu)\) and \(I(\sigma(\lambda), X \times \lambda)\). This motivates the introduction of the following subcategory of pointed spaces and homotopy classes of maps associated with a continuous function \(\sigma: \Lambda \to \mathcal{S}\) satisfying \(\pi_1 \circ \sigma = 1_\Lambda\). This category may be considered as the **global Conley index** of \(\sigma\) in \(X \times \Lambda\) and is defined by

\[
(6.22;1) \quad I(\sigma, X, \Lambda) = (I_0, I_m),
\]

where

\[
(6.22;2) \quad I_0 = \{ N_1(\lambda) / N_0(\lambda) | \lambda \in \Lambda \text{ and } N_1(\lambda), N_0(\lambda) \text{ is an index pair for } \sigma(\lambda) \text{ in } X \times \lambda \},
\]

\[
(6.22;3) \quad I_m = \{ [f] N_1(\lambda) / N_0(\lambda) \in I_0, N_1(\mu) / N_0(\mu) \in I_0 \text{ and } f: N_1(\mu) / N_0(\mu) \to N_1(\lambda) / N_0(\lambda) \text{ is a finite composition of maps defined in Lemma 4.7 and Corollary 6.8} \}.
\]

The global Conley index \(I(\sigma, X, \Lambda)\) of \(\sigma\) in \(X \times \Lambda\) has to be well distinguished from the Conley index \(I(S, X \times \Lambda)\) of the global isolated invariant set \(S\) in \(X \times \Lambda\). If \(\Lambda\) is connected, then the category \(I(\sigma, X, \Lambda)\) has the property that there is at least one morphism between any two objects and that every morphism is an equivalence. However, \(I(\sigma, X, \Lambda)\) is in general not a connected simple system since there may be different isomorphisms between the same objects. This is the case in the parameterized flow illustrated in Figure 7. However, if \(\Lambda\) is simply connected (every closed arc is homotopic to a constant where the end points are fixed), then we will show that \(I(\sigma, X, \Lambda)\) is a connected simple system. This result has first been stated in terms of the cohomology of the isolated invariant sets and is due to Montgomery [9].

The corresponding theorem in Conley [3] has been phrased in terms of continuation along arcs.
Theorem 6.9. Suppose that $\Lambda$ is simply connected and let $\sigma: \Lambda \to \mathcal{P}$ be a continuous map with $\pi_\Lambda \circ \sigma = 1_\Lambda$. Then $I(\sigma, X, \Lambda)$ is a connected simple system.

Proof. We have to prove that every morphism in $I_m$ with the same domain and range is in the class of the identity map. Using the second part of Corollary 6.8 one can first show that every map $f: N_1(\lambda)/N_0(\lambda) \to N_1(\lambda)/N_0(\lambda)$ with $[f] \in I_m$ is homotopic to a finite composition of maps defined by (6.19) and associated with a single index pair $(N_1, N_0)$ for $S$ in $X \times \Lambda$. Hence we can assume that there are finitely many compact contractible sets $K_0, \ldots, K_k$ in $\Lambda$ satisfying the conditions of Lemma 6.6 and points $\lambda_j \in K_{j-1} \cap K_j$, $j = 1, \ldots, k$, $\lambda_0 = \lambda_{k+1} = \lambda \in K_0 \cap K_k$ such that

$$f = F_k(\lambda_{k+1}, \lambda_k) \circ F_{k-1}(\lambda_k, \lambda_{k-1}) \circ \cdots \circ F_0(\lambda_1, \lambda_0),$$

where the maps $F_j = F_{K_j}$ are defined by (6.19). Let us extend $(K_0, \ldots, K_k)$ to a collection of compact, contractible sets $K_0, \ldots, K_n$ which satisfy the conditions of Lemma 6.6 for $T \geq T_1 > 2T_0 > 0$ and are chosen such that the sets $\text{int } K_j = \Lambda \setminus \text{cl}(\Lambda \setminus K_j)$ cover $\Lambda$. Using (6.20) we can assume without loss of generality that $\lambda_j \in \text{int } K_{j-1} \cap \text{int } K_j$ for $j = 1, \ldots, k$ and $\lambda_0 \in \text{int } K_0 \cap \text{int } K_k$. Since the sets $K_j$ are contractible, there exists an arc $\alpha_j: [0, 1] \to \bigcup_{j=0}^k \text{int } K_j$ such that $\alpha_1(0) = \alpha_1(1) = \lambda_0$ and $\lambda_j = \alpha_1(\xi_j)$, $\alpha_1([\xi_j, \xi_{j+1}]) \subset \text{int } K_j$ for $j = 0, \ldots, k$. Now we make use of the fact that $\Lambda$ is simply connected and conclude that there exists a continuous family of arcs $\alpha_t: [0, 1] \to \Lambda$, $0 \leq t \leq 1$, such that $\alpha_t(0) = \alpha_t(1) = \lambda_0$ for all $t \in [0, 1]$ and $\alpha_0(\xi) = \lambda_0$. With every arc $\alpha_t$, we can associate a sequence of maps $F_{\nu(j)}(\mu_{j+1}, \mu_j)$, $j = 0, \ldots, l$, defined by (6.19) and such that $\mu_j = \alpha_t(\xi_j)$, $0 = \xi_0 < \xi_1 < \cdots < \xi_{l+1} = 1$, and $\alpha_t([\xi_j, \xi_{j+1}]) \subset \text{int } K_{\nu(j)}$, $j = 0, \ldots, l$. Let $f_t: N_1(\lambda)/N_0(\lambda) \to N_1(\lambda)/N_0(\lambda)$ denote the composition of these maps. Then it follows from (6.20) that the homotopy class of $f_t$ is independent of the choice of the points $\xi_j$ and the indices $\nu(j)$. This fact together with the continuous dependence of the condition $\alpha_t([\xi_j, \xi_{j+1}]) \subset \text{int } K_{\nu(j)}$ on $t$ shows that $[f_t]$ is independent of $t \in [0, 1]$. Finally, it follows from (6.20) and (6.21) that $f_0$ is homotopic to the identity on $N_1(\lambda)/N_0(\lambda)$.

6.4. Continuation of attractor-repeller pairs. It is the purpose of this section to combine the continuation results of §§6.1–6.3 with the coexact sequence of §5 associated with an attractor-repeller pair.
In addition to the notation and assumptions of §6.1 we will assume throughout this section that $\sigma: \Lambda \to \mathcal{S}$ and $\alpha: \Lambda \to \mathcal{S}$ are continuous maps such that $\pi_\Lambda \circ \sigma = 1_\Lambda$ and $\alpha(\lambda)$ is an attractor in $\sigma(\lambda)$. Then the complementary repeller $\alpha^*(\lambda)$ of $\alpha(\lambda)$ in $\sigma(\lambda)$ also defines a continuous function from $\Lambda$ into $\mathcal{S}$ and the sets $A$, $A^*$ defined by (6.2) form an attractor-repeller pair for the isolated invariant set $S$ defined by (6.1) in $X \times \Lambda$ (Lemma 6.4).

Now let $N_0 \subset N_1 \subset N_2$ be a filtration of compact sets in $X \times \Lambda$ such that $(N_2, N_0)$ and $(N_1, N_0)$ are index pairs for $S$ and $A$, respectively, and $(N_2, N_1)$ is a regular index pair for $A^*$. Furthermore, let $\iota: N_1/N_0 \to N_2/N_0$ and $\pi: N_2/N_0 \to N_2/N_1$ be the natural maps and let the connection map $\delta: N_2/N_1 \to \Sigma N_1/N_0$ be defined by (5.9) and (5.6). For any $\lambda \in \Lambda$ let the corresponding maps be denoted by $\iota(\lambda): N_1(N)/N_0(N) \to N_2(N)/N_0(N)$, $\pi(\lambda): N_2(N)/N_0(N) \to N_2(N)/N_1(N)$, $\delta(\lambda): N_2(N)/N_1(N) \to \Sigma N_1(N)/N_0(N)$. Then the diagram

$$(6.23)$$

\[
\begin{array}{cccccc}
N_1/N_0 & \xrightarrow{\iota} & N_2/N_0 & \xrightarrow{\pi} & N_2/N_1 & \xrightarrow{\delta} & \Sigma N_1/N_0 \\
\uparrow \iota(\lambda) & & \uparrow \pi(\lambda) & & \uparrow \delta(\lambda) & & \uparrow \Sigma \iota(\lambda) \\
N_1(\lambda)/N_0(\lambda) & \xrightarrow{\iota(\lambda)} & N_2(\lambda)/N_0(\lambda) & \xrightarrow{\pi(\lambda)} & N_2(\lambda)/N_1(\lambda) & \xrightarrow{\delta(\lambda)} & \Sigma N_1(\lambda)/N_0(\lambda)
\end{array}
\]

commutes, where $i(\lambda), j(\lambda)$ and $k(\lambda)$ are the natural inclusion maps. It follows from Theorem 5.7 and Proposition 6.5 that all the maps in diagram (6.23) induce morphisms of the corresponding connected simple systems which are independent of the choice of the index filtration $N_0 \subset N_1 \subset N_2$. Therefore we obtain the following commuting diagram of connected simple systems in which the rows are coexact.

$$(6.24)$$

\[
\begin{array}{cccccc}
I(A(K)) & \xrightarrow{\iota} & I(S(K)) & \xrightarrow{\pi} & I(A^*(K)) & \xrightarrow{\delta} & \Sigma I(A(K)) & \rightarrow & \cdots \\
\uparrow \iota(\lambda) & & \uparrow \pi(\lambda) & & \uparrow \delta(\lambda) & & \uparrow \Sigma \iota(\lambda) \\
I(\alpha(\lambda)) & \xrightarrow{\iota(\lambda)} & I(\sigma(\lambda)) & \xrightarrow{\pi(\lambda)} & I(\alpha^*(\lambda)) & \xrightarrow{\delta(\lambda)} & \Sigma I(\alpha(\lambda)) & \rightarrow & \cdots
\end{array}
\]

Here we have replaced $\Lambda$ by any compact subset $K \subset \Lambda$. If this set is contractible and satisfies the requirements of Lemma 6.6 for each of the index pairs $(N_1, N_0)$, $(N_2, N_0)$, $(N_2, N_1)$, then it follows from Theorem 6.7 that the vertical maps in diagram (6.24) are equivalences for every $\lambda \in K$. The homotopy inverses of these equivalences define, of course, again morphisms between the respective connected simple systems and make the (vertically reverse) diagram commute. This implies that for any two points $\lambda, \mu$ in the same connected component of $\Lambda$ and any connecting sequence of compact contractible sets $K_j \subset \Lambda$ which satisfy the conditions of Lemma 6.6 there is a (unique) commuting diagram of the form

$$(6.25)$$

\[
\begin{array}{cccccc}
I(\alpha(\mu)) & \xrightarrow{\iota(\mu)} & I(\sigma(\mu)) & \xrightarrow{\pi(\mu)} & I(\alpha^*(\mu)) & \xrightarrow{\delta(\mu)} & \Sigma I(\alpha(\mu)) & \rightarrow & \cdots \\
\downarrow F(\lambda, \mu) & & \downarrow G(\lambda, \mu) & & \downarrow H(\lambda, \mu) & & \downarrow \Sigma F(\lambda, \mu) \\
I(\alpha(\lambda)) & \xrightarrow{\iota(\lambda)} & I(\sigma(\lambda)) & \xrightarrow{\pi(\lambda)} & I(\alpha^*(\lambda)) & \xrightarrow{\delta(\lambda)} & \Sigma I(\alpha(\lambda)) & \rightarrow & \cdots
\end{array}
\]
where the vertical morphisms are equivalences. Finally, it follows from Theorem 6.9 that the vertical morphisms in (6.25) are independent of the choice of the connecting sequence $K_j$ if $\Lambda$ is simply connected. This proves the following result (compare Kurland [8]).

**Theorem 6.10.** If $\Lambda$ is simply connected, then the maps $\iota(\lambda): I(\alpha(\lambda)) \to I(\sigma(\lambda))$, $\pi(\lambda): I(\sigma(\lambda)) \to I(\alpha^{*}(\lambda))$, $\delta(\lambda): I(\alpha^{*}(\lambda)) \to \Sigma I(\alpha(\lambda))$ of §5 induce the following coexact sequence of connected simple systems:

\begin{equation}
I(\alpha, X, \Lambda) \xrightarrow{i} I(\sigma, X, \Lambda) \xrightarrow{\pi} I(\alpha^{*}, X, \Lambda) \xrightarrow{\delta} \Sigma I(\alpha, X, \Lambda) \to \cdots.
\end{equation}

7. **Conclusions.** In this paper we have given complete and simplified proofs for most of the basic abstract results in the index theory of isolated invariant sets. Of course, there are many questions left open.

One of them is to develop a continuation theorem for flows on fibrations rather than product spaces $X \times \Lambda$. Another problem is the relation between the global Conley index $I(\sigma, X, \Lambda)$ and the Conley index $I(S, X \times \Lambda)$ of the global isolated invariant set $S = \bigcup_{\lambda \in \Lambda} \sigma(\lambda)$ in the parametrized flow $X \times \Lambda$. For example, there is the question whether $I(\sigma, X, \Lambda)$ is isomorphic to $I(S, X \times \Lambda)$ if $\Lambda$ is simply connected.

Several other questions have been indicated by Conley [3]. Among these there is the observation that information gets lost by collapsing the exit set $N_0$ in the index pair $(N_1, N_0)$. This leads to the question whether a sequence of index pairs which collapse to $S$ gives more information which can be used in a nice way for the definition of algebraic invariants. Another possible refinement of the Conley index might be to consider only special classes of homotopies since all the maps and homotopies in the theory are given by flow induced maps.

Furthermore, there is a duality in homotopy theory between fibrations (mapping fibration, loop functor, exact sequence) and cofibrations (mapping cone, suspension functor, coexact sequence). A very nice presentation of these duality relations can be found in Whitehead [13]. Since index pairs only give rise to a coexact sequence there arises the question whether there is some kind of a dual concept.

Of course, there is a big area of open questions when it comes to the point of applying the index theory to obtain results for concrete differential equations. Despite the fact that the Conley index has proven to be a very useful tool for many problems, there is the question under which conditions infinite dimensional systems can be formulated in the framework of §3. For some cases this has been done, e.g. by Smoller [11]. If this is not possible then there arises the question what one can do if $X$ is not locally compact and $\Gamma$ is only a semiflow. Some steps in this direction have been taken by Rybakowski and Zehnder [10]. Another possibility might be to go to finite dimensional approximations (see for example Conley and Zehnder [4]).

We stop at this place since the list of open questions has no end.

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