

A TOPOLOGICAL PERSISTENCE THEOREM FOR NORMALLY HYPERBOLIC MANIFOLDS VIA THE CONLEY INDEX

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ABSTRACT. We prove that the cohomology ring of a normally hyperbolic manifold of a diffeomorphism f persists under perturbation of f . We do not make any quantitative assumptions on the expansion and contraction rates of Df on the normal and the tangent bundles of N .

1. INTRODUCTION

In this paper, we shall apply C. Conley's homotopy index theory for invariant sets of flows to discrete dynamical systems. In particular, we prove a homotopy version of the persistence theorem for normally hyperbolic invariant manifolds.

Let M be a smooth i.e. \mathcal{C}^2 manifold and let $f: M \rightarrow M$ be a diffeomorphism which restricts to a diffeomorphism of a compact \mathcal{C}^2 submanifold N onto itself. One calls N normally hyperbolic with respect to f if it satisfies a certain nondegeneracy condition on a normal bundle of N in M . In This paper, we will use the following definition:

Definition 1. N is called normally hyperbolic with respect to f if the tangent bundle of M over N splits into smooth subbundles

$$(1.1) \quad TM|_N = E^+ \oplus TN \oplus E^-$$

which are invariant under $Df: TM \rightarrow TM$ such that Df contracts E^- and expands E^+ . Here we say that a vector bundle isomorphism $\psi: E \rightarrow E$ contracts E if for every $\xi \in E$, the sequence $\psi^n \xi$ converges to the zero section of E . We say that ψ expands E if ψ^{-1} contracts E .

N. Fenichel [2] examined the question under which conditions a normally hyperbolic manifold persists under small perturbations of f . In fact, he proves that if Df contracts E^- and expands E^+ stronger than any vector in TN , then every \mathcal{C}^1 -small perturbation of f has a normally hyperbolic manifold \mathcal{C}^1 -diffeomorphic to N (see also [6, Theorem 4.1] for more persisting properties of N). Here, the expansion and contraction rates have to be measured by some metric on M . In order to illustrate the importance of this quantitative

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hypothesis, consider on N an attracting fixed point such that the rate of approach in the direction of TN is greater than in the normal direction. At such a point, a cusp may develop under perturbation (see [2, 8, and 4, pp. 239, 251]). There are also examples (see Jarnik and Kurzweil, [7]), where a normally hyperbolic manifold changes under arbitrarily small perturbations into an invariant set which is not even a topological manifold. In this paper, we shall prove that if N is normally hyperbolic in the sense of Definition 2, i.e. without any additional quantitative conditions, then the cohomology of N persists under \mathcal{C}^0 small perturbations of f :

Theorem 1. *Let $f: M \rightarrow M$ be a diffeomorphism and let N be a smooth compact normally hyperbolic invariant submanifold with respect to f . Let $\{f_\lambda\}_{\lambda \in \mathbb{R}}$ be a family of homeomorphisms of M , continuous in the compact-open topology, with $f_0 = f$. Then for λ small enough, f_λ has an isolated invariant set T_λ whose cohomology ring contains $H^*(N)$ as a subring. In fact, for every neighborhood U admitting a retraction $r: U \rightarrow N$, we have $T_\lambda \subset U$ for λ small enough, and*

$$(1.2) \quad (r|T_\lambda^*): H^*(N) \rightarrow H^*(T_\lambda)$$

is injective. Here, coefficients are arbitrary if N and E^+ are oriented and $f|N$ and $Df|_{E^+}$ are orientation preserving and in \mathbb{Z}_2 otherwise.

The notion of an isolated invariant set will be defined in the following section.

In analogy to [3, Theorem 2], one also has a global persistence result for certain normally hyperbolic manifolds N , which does not assume that the perturbation is small. Instead, one has to assume, in addition, that N is a retract of M by a retraction which commutes with f up to homotopy. This means that there exists a continuous map

$$(1.3) \quad r: M \rightarrow N$$

such that $r|N$ is homotopic to the identity and so that $f|N \circ r$ and $r \circ f$ are homotopic as maps from M to N .

Theorem 2. *Let $N \subset M$ be a compact normally hyperbolic invariant manifold of the diffeomorphism f and let $r: M \rightarrow N$ be a retraction commuting with f up to homotopy. Then for every invariant set T of a homeomorphism f' which is related to (N, f) by continuation, r induces injective homomorphisms*

$$(1.4) \quad (r|T)^*: H^*(N) \rightarrow H^*(T)$$

with coefficients as in Theorem 1.

The notion of continuation will be defined in the following section. The proof of Theorems 1 and 2 uses the index theory for topological flows developed by C. Conley (see [1]). By a suspension procedure (§2) we construct a flow on a bundle M_f over S^1 with fibre M whose time 1 map equals f . In §3, we show that a normally hyperbolic submanifold N of M for f corresponds to a

normally hyperbolic submanifold N_f of M_f of the flow. In this situation, we can apply Theorem 2 of [3] to continue N_f under a perturbation of the flow. In §4, we show that this proves the perturbation result for the map f on N .

2. MAPS AND FLOWS

We will denote by $\mathcal{F}(M)$ the space of all homeomorphisms from a locally compact Hausdorff space M onto itself. In some applications, one also considers an operation ρ of a compact topological group G on M , i.e. a continuous map

$$(2.1) \quad \rho: G \times M \rightarrow M, \quad (g, x) \mapsto gx$$

such that $(g \circ h)x = g(hx)$. In such a situation, we may restrict ourselves to the subset $\mathcal{F}_\rho \subset \mathcal{F}(M)$ of homeomorphisms commuting with $\rho(g)$ for all $g \in G$, i.e. of equivariant homeomorphisms. Let \mathcal{F}_ρ be equipped with any Hausdorff topology so that the inverse map

$$(2.2) \quad \mathcal{F} \rightarrow \mathcal{F}: f \mapsto f^{-1}$$

is continuous, for example, we can take the compact open topology. In analogy to [3, Definition 1], we can introduce the notion of an isolated invariant set

Definition 2.1. For any ρ -invariant subset U of M , and for $f \in \mathcal{F}_\rho$, define

$$(2.3) \quad T_-^f(U) = \{x \in U | f^n(x) \subset U \text{ for all } n \geq 0\},$$

$$(2.4) \quad T_+^f(U) = \bigcap_{n \geq 0} f^n(U).$$

The maximal invariant set is defined by

$$(2.5) \quad T^f(U) = T_-^f(U) \cap T_+^f(U).$$

We call U isolating, if the closure of $T^f(U)$ is contained in the interior of U . In this case, $T^f(U)$ is called an isolated invariant set.

Next we define the notion of continuation. Define the set

$$(2.6) \quad \mathcal{T} = \{(T, f) | f \in \mathcal{F}_\rho \text{ and } T \text{ is a nonempty compact isolated invariant set of } f \text{ in } M\}.$$

On \mathcal{T} , consider the topology generated by the open sets

$$(2.7) \quad \theta_U = \{(T, f) | U \text{ is isolated with respect to } f \text{ with nonempty maximal invariant set } T = T^f(U)\},$$

where U is any open (ρ -invariant) subset of M .

Definition 2.2. Two elements (T, f) and (T', f') of \mathcal{T} are called related by continuation, if they are connected to \mathcal{T} by a continuous path.

We want to define a topological index for isolated invariant sets of maps f on M which is invariant under continuation, i.e. which only depends on the

path components in \mathcal{F} . Therefore, we use the index theory for flows developed by C. Conley. A flow on a topological space Γ is defined as a continuous map

$$(2.8) \quad \chi: \Gamma \times \mathbb{R}_+ \supset U_\Gamma \rightarrow \Gamma: (x, t) \rightarrow \chi(x, t) = x \cdot t,$$

where U_Γ is a neighborhood of $\Gamma \times \{0\}$ in $\Gamma \times \mathbb{R}_+$ with the following property: If (x, t) and $(x \cdot t, x) \in U_\Gamma$, then $(x, t + s) \in U_\Gamma$ and

$$(2.9) \quad (x \cdot t) \cdot s = x \cdot (t + s).$$

Again, we can assume that the flow is equivariant with respect to some operation ρ of a compact group G on Γ , i.e. that U_Γ is ρ -invariant and that

$$\rho(x) \cdot t = \rho(x \cdot t) \quad \text{for } (x, t) \in U_\Gamma.$$

Moreover, we can define isolated invariant sets (see, for example [3, Definition 1]),

Definition 2.3. For any (ρ -invariant) subset U of Γ , define

$$(2.10) \quad U_{-\infty} = \{x \in U \mid x \cdot \mathbb{R}_+ \subset U\},$$

$$(2.11) \quad U_\infty = \bigcap_{t \geq 0} U \cdot t$$

and the maximal invariant set

$$(2.12) \quad S(U) = U_\infty \cap U_{-\infty}.$$

We are concerned with the following family of flows:

Definition 2.4. Consider the quotient

$$(2.13) \quad M_{\mathcal{F}} = p(M \times \mathcal{F}_\rho \times (-1, 1)),$$

where p is the projection map corresponding to the equivalence relation generated by

$$(2.14) \quad (x, f, t - 1) \sim (f(x), f, t)$$

for $t \in (0, 1)$. On $M_{\mathcal{F}}$, consider the flow χ defined by the map

$$(2.15) \quad \chi^\tau(x, f, t) = (x, f, t - \tau)$$

for $\tau, t \in [0, 1)$.

We can define an operator ρ on $M_{\mathcal{F}}$ commuting with the flow by

$$(2.16) \quad \rho(g)(x, f, t) = (\rho(g)x, f, t).$$

Clearly, the flow χ on $M_{\mathcal{F}}$ restricts to a continuous flow χ_f on every leaf

$$(2.17) \quad M_f := p_f(M \times (-1, 1)),$$

where p_f is the restriction of p to $M \times (-1, 1) \cong M \times \{f\} \times (-1, 1)$. The flow χ_f is also called the suspension of the map f .

Proposition 1. *The flow invariant map*

$$(2.18) \quad M_{\mathcal{F}} \rightarrow \mathcal{F}(M): (x, f, t) \mapsto f$$

defined a (ρ -invariant) local product parametrization in the sense of [3, Definition 3].

Proof. It suffices to show that the map

$$(2.19) \quad \begin{aligned} M \times \mathcal{F}_\rho \times \mathbb{R} &\rightarrow M \times \mathcal{F}_\rho \times \mathbb{R}, \\ (x, f, t) &\mapsto (f(x), f, t + 1) \end{aligned}$$

is a homeomorphism. In fact, in this case, we have $M_{\mathcal{F}} = (M \times \mathcal{F}_\rho \times \mathbb{R})/\mathbb{Z}$, where the operation of \mathbb{Z} is generated by the map (2.19). Since $M \times \mathcal{F}_\rho \times \mathbb{R}$ is a product space, this proves that M has the required local product structure.

Obviously, the map (2.19) is bijective and continuous, $f \in \mathcal{F}_\rho$ is a homeomorphism and the evaluation map $\mathcal{F}_\rho \times M \rightarrow M$ is continuous. But also the inverse

$$(2.20) \quad (x, f, t) \mapsto (f^{-1}(x), f, t - 1),$$

is continuous, since the map (2.1) was assumed to be continuous on \mathcal{F}_ρ . \square

We now can define the notion of continuation in M . Following [1, Section 4] and [3, Section 2], we consider the set

$$(2.21) \quad \mathcal{S} = \{(S, f) \mid f \in \mathcal{F}_\rho(M) \text{ and } S \text{ is a nonempty compact isolated invariant (and } \rho\text{-invariant) set in } M_f\}.$$

The topology is generated by the open sets

$$(2.22) \quad \Sigma_U = \{(S, f) \mid U \cap M^f \text{ is isolating in } M_f \text{ with maximal invariant set } S\},$$

where U is any open (ρ -invariant) subset of $M_{\mathcal{F}}$.

Proposition 2. *The map*

$$(2.23) \quad \Psi: \mathcal{F} \rightarrow \mathcal{S}: (T, f) \mapsto (T_f, f)$$

is a homeomorphism.

Proof. First, note that every nonempty invariant set of χ_f on M_f is of the form T_f , where T is an invariant set of f . We now show that for every open set $U \subset M$ and for every $f \in \mathcal{F}$, the set U_f is isolating for the flow χ_f if and only if U is isolating for f . In fact, it is easy to see that $x \in T_f^+(U)$ if and only if $p_f(x, t) \in U_\infty^f$ for all $t \in (-1, 1)$. Similarly, $x \in \mathcal{F}^-(U, f)$ if and only if $p_f(x, t) \in U_{-\infty}^f$ for all $t \in I$.

This shows that T is isolated in U if and only if T^f is isolated in U^f . Moreover, if \tilde{U} is any isolating neighborhood of T^f in M_f , then it contains a neighborhood of the form U^f for some neighborhood U of T in M . Hence the map Ψ of Proposition 2 is bijective.

In order to show that it is also a homeomorphism, note that the topology of $\mathcal{S} \times M$ is generated by sets $U = U_m \times U_{\mathcal{S}}$, where $U_{\mathcal{S}}$ is open in \mathcal{S} and U_M is open in M . Similarly, the topology of $M_{\mathcal{S}}$ is generated by sets $p(U_M \times U_{\mathcal{S}} \times I)$, where, in addition, $I \subset (-1, 1)$ is open. However, since we are only interested in neighborhoods U of $(S, f) \in \mathcal{S}$ for which $S = S^f(U)$ is nonempty, we can restrict ourselves to those open sets where $I = (-1, 1)$. Then by the above,

$$\Sigma_{p(U_M \times U_{\mathcal{S}} \times I)} = \{(S^f, f) | (S, f) \in \Theta_{U_M \times U_{\mathcal{S}}}\} = \Psi(\theta(U_M \times U_{\mathcal{S}})),$$

which completes the proof of Proposition 2. \square

We can use the map Ψ and the Conley index for flows (see [1 and 3]) to define a topological index on T .

Definition 2.5. For $(T, f) \in \mathcal{S}$, define

$$(2.24) \quad I_{\rho}^*(T, f) := H_{\rho}^*(X, A)$$

where (X, A) is any (ρ -invariant) index pair for $\mathcal{S}_f \subset M_f$ and H_{ρ}^* denotes the equivariant Alexander-Spanier cohomology with values in some ring with unit. Moreover, with $\pi: M_f \rightarrow S^1$ given by $\pi(x, t) = t$ and for the standard generator e of $H^1(S^1)$, define

$$(2.25) \quad \theta_{(T, f)}: I_{\rho}^*(T, f) \rightarrow I_{\rho}^*(T, f): \alpha \mapsto \alpha \cup (\pi|_x)^* e.$$

The continuation invariance of the index $I_{\rho} = (I_{\rho}^*, \theta)$ on \mathcal{S} then follows immediately from Proposition 2 and from Theorem 1 of [3].

Theorem 3. $I_{\rho}^*(T, f)$ does not depend on the choice of the index pair (X, A) . Moreover, if (T, f) is related to (T', f') by continuation, then there exists an isomorphism $i: I_{\rho}^*(T, f) \rightarrow I_{\rho}^*(T', f')$ such that

$$(2.26) \quad \theta_{(T, f)} \circ i = i \circ \theta_{(T', f')}.$$

3. SUSPENDING NORMALLY HYPERBOLIC MANIFOLDS

In this section, we prove the following proposition.

Proposition 3. If $N \subset M$ is a normally hyperbolic invariant submanifold with respect to a smooth map f , then N_f is a normally hyperbolic invariant submanifold of M_f with respect to the suspended flow in the sense of [3, Proposition 1].

Note therefore that, by Definition 1, f is in fact a diffeomorphism from some neighborhood O of $N \subset M$ onto its image. Therefore,

$$(3.1) \quad O_f := p_f(O \times (-1, 1)) \subset M_f$$

is a smooth open manifold with a smooth submanifold $N_f = p_f(N \times (-1, 1))$. Now consider on N_f the vector bundles

$$(3.2) \quad E_f^{\pm} = p_{Df}(E^{\pm} \times (-1, 1)),$$

where p_{Df} identifies $(\xi, t - 1)$ with $(f_*\xi, t) = (Df\xi, t)$ for $t \in (0, 1)$. This is well defined, since f_* leaves E^\pm invariant. Moreover, (3.2) constitutes a decomposition of the normal bundle of N_f in O_f . The flow on O_f is generated by the vector field

$$(3.3) \quad \eta := (p_f)_* \frac{\partial}{\partial t},$$

which is also well defined on O_f . In order to show that N_f satisfies the conditions of Proposition 1 of [3], we have to find a metric \bar{g} on O_f so that for every $v \in N$, the linear operator

$$(3.4) \quad L: T_v(M) \rightarrow T_v M: \xi \mapsto \xi \cdot \nabla_{\bar{g}} \eta$$

leaves the bundles $E^\pm f$ invariant and satisfies

$$(3.5) \quad \langle \xi, L\xi \rangle \geq m|\xi|^2 \quad \text{for } \xi \in E_f^+,$$

$$(3.6) \quad \langle \xi, L\xi \rangle \leq -m|\xi|^2 \quad \text{for } \xi \in E_f^-$$

for some constant $m > 0$. In (3.4), $\xi \cdot \nabla_{\bar{g}}$ denotes the covariant derivative with respect to the metric \bar{g} in the direction of ξ .

The first step towards the construction of the metric \bar{g} is

Lemma 3.1. *Let ψ be a contracting bundle map on the vector bundle E . For any metric g_0 on E , define $g_k = (f^*)^k g_0$ for $K \in \mathbb{N}$. Then the series*

$$(3.7) \quad g = \sum_{k=0}^{\infty} g_k$$

converges to a metric on E with

$$(3.8) \quad |\xi|_g^2 - |f_*\xi|_g^2 = |\xi|_{g_0}^2.$$

Proof. Set $B_\alpha = \{\xi \in E^- | g_0(\xi, \xi) \leq \alpha^2\}$. Since B_1 is compact, the contracting property of Df on E^- implies that there exists an $n \in \mathbb{N}$ with

$$(3.9) \quad f_*^n B_1 \subset B_{1/2}.$$

Consequently, we have

$$(3.10) \quad |f_*^{k \cdot n} \xi|_{g_0} \leq 2^{-k} |\xi|_{g_0},$$

and hence for some \mathcal{C} independent of $x \in N$:

$$(3.11) \quad [(f_*^{k \cdot n})^* \gamma]_{ij} \leq \mathcal{C} 2^{-k}.$$

Hence the sum of (3.7) converges and (3.8) holds. Moreover, g is positive as a sum of positive metrics. \square

We apply Lemma 3.1 to the contracting bundle maps Df on E^- and $(Df)^{-1}$ on E^+ to obtain metrics g^\pm on E^\pm with

$$(3.12) \quad \langle \xi, \xi \rangle_{g^\pm} - \langle f_*\xi, f_*\xi \rangle_{g^\pm} = \mp \langle \xi, \xi \rangle_{g_0}.$$

We can extend these metrics to a Riemannian metric g on M such that $\langle \xi^-, \xi^+ \rangle_g = 0$ for $\xi^\pm \in E^\pm$. Now \bar{g} is defined as the unique metric on M_f satisfying

$$(3.13) \quad i_t^* \bar{g} = tg + (1 - t)f^* g,$$

$$(3.14) \quad |\eta|_{\bar{g}} \equiv 1,$$

$$(3.15) \quad \langle \eta, i_t^* \xi \rangle_{\bar{g}} = 0 \quad \text{for } \xi \in TM$$

where $i_t: M \rightarrow M_f$ is given by $i_t(x) = p_f(x, t)$. Note that $i_1 = i_0 \circ f$, so that condition (3.13) is compatible for $t = 0, 1$.

To calculate the linear operator L of (3.4), note that for any $(x, t) \in M_f$ there exists a neighborhood which is naturally isomorphic by the flow f^t to $I \times U$, where $I \subset \mathbb{R}$ and $U \subset M$ are open sets. Choose any chart of M at x . Let the index O denote the direction of t , so that η corresponds to the constant vector field e^O on the chart. With i, j , and k running from O to $\dim M$, the covariant derivative of e^O can now be expressed in terms of Christoffel symbols (see [5])

$$(3.16) \quad (L\xi)^i = (\xi \cdot \nabla_{\bar{g}} e^O)^i = \Gamma_{jk} \xi^k (e^O)^j = \Gamma_{ok}^i \xi^k.$$

By [5], we have therefore $\bar{g}_{ij}(L\xi)^j = \Gamma_{i,ok} \xi^k$ with

$$(3.17) \quad \begin{aligned} T_{ok,j} &= \frac{\partial}{\partial x^k} \bar{g}_{jo} + \frac{\partial}{\partial x^0} \bar{g}_{jk} - \frac{\partial}{\partial x^j} \bar{g}_{ok} \\ &= \frac{\partial}{\partial t} (tg_{jk} + (1 - t)(f^* g)_{jk}) \\ &= (g - f^* g)_{jk}, \end{aligned}$$

whereas $\Gamma_{ok,j} = 0$ for $k = 0$ or $j = 0$. Hence we have for $\xi, \zeta \in T_{(x,t)} \bar{M}$:

$$(3.18) \quad \langle \xi, L\zeta \rangle_{\bar{g}} = \langle \pi_* \xi, \pi_* \zeta \rangle_g - \langle f_* \pi_* \xi, f_* \pi_* \zeta \rangle_g$$

where $\pi: U \times I \rightarrow U$ is the projection. This immediately shows that L leaves the mutually orthogonal subspaces E^\pm and TN_f invariant. Moreover, choosing $\xi = \zeta \in E^+$ or E^- and using (3.8) proves (3.5) and (3.6).

4. PROOF OF THE CONTINUATION RESULTS

In this section we will complete the proof of Theorems 1 and 2. Let us first consider the situation of Theorem 2. Since it can be done without much additional work, we will always assume that $f \in \mathcal{F}_\rho$ for some operation ρ of a compact group G . Theorem 2 is obtained by considering $G = \{1\}$.

Theorem 4. *Let ρ, M, f, N be as in Proposition 3. Let $r: M \rightarrow N$ be a ρ -equivariant retraction such that there is a ρ -equivariant homotopy between $f|_N \circ r$ and $r \circ f$. Then if T is a ρ -invariant isolated invariant set of a map $f \in \mathcal{F}_\rho$ and (T, f') is related to (N, f) by continuation,*

$$(4.1) \quad (r|_T)^*: H_\rho^*(N) \rightarrow H_\rho^*(T)$$

is injective. Here H_ρ^* denotes the ρ -equivariant cohomology with coefficients as in Theorem 1.

Proof. By Proposition 3, N_f is a normally hyperbolic submanifold of $O_f \subset M_f$. It is therefore by Proposition 1 of [3] a $*$ -hyperbolic invariant set of the flow χ_f in M_f (see [3, Definition 4]). We now construct a homotopy retraction from M_f to N_f . Let us therefore restrict our attention to a continuous family $f_\tau, \tau \in \mathbb{R}$, with $f_0 = f$. Set

$$(4.2) \quad M_{\mathbb{R}} = p_{\mathbb{R}}(M \times \mathbb{R} \times (-1, 1))$$

where $p_{\mathbb{R}}$ is uniquely defined by

$$(4.3) \quad p_{\mathbb{R}}(x, \tau, t) = p_{\mathbb{R}}(f_\tau(x), \tau, t + 1),$$

for $t \in (-1, 0)$. There is a continuous map

$$(4.4) \quad H: \mathbb{R} \times M \times [0, 1] \rightarrow M: (\tau, x, t) \mapsto H_\tau(x, t)$$

such that $H_\tau(x, 0) = r(f_\tau(x))$ and $H_\tau(x, 1) = f(r(x))$. Define for $t \in [0, 1]$

$$(4.5) \quad r_{\mathbb{R}}(p_{\mathbb{R}}(x, \tau, t)) = p_f(H_\tau(x, t), t).$$

This defines a continuous map $r_{\mathbb{R}}: M_{\mathbb{R}} \rightarrow N_f$, since

$$(4.6) \quad \begin{aligned} r_{\mathbb{R}}(p_{\mathbb{R}}(x, \tau, 0)) &= p_f(H_\tau(x, 0), 0) = p_f(r(f_\tau(x)), 0) \\ &= p_f(f(r(f_\tau(x))), 1) = p_f(H_\tau(f_\tau(x), 1), 1) \\ &= r_{\mathbb{R}}(f_\tau(x), \tau, 1). \end{aligned}$$

The following lemma summarizes the properties of this construction.

Lemma 4.1. *If $f: X \rightarrow X$ is a homeomorphism, then there exists an exact sequence*

$$(4.7) \quad H^*(X_f) \rightarrow H^*(X) \xrightarrow{f^* - \text{id}} H^*(X) \xrightarrow{\delta} H^{*+1}(X_f).$$

Moreover, if $r: X \rightarrow Y$ is a map which homotopy commutes with $f: X \rightarrow X, Y \rightarrow Y$, and $r_f: X_f \rightarrow Y_f$ is defined by (4.5) restricted to the set $\{\tau = 0\}$, then the following diagram commutes

$$(4.8) \quad \begin{array}{ccccccc} H^*(Y_f) & \longrightarrow & H^*(Y) & \xrightarrow{f^* - \text{id}} & H^*(Y) & \xrightarrow{\delta} & H^{*+1}(Y_f) \\ \downarrow r_f^* & & \downarrow r^* & & \downarrow r^* & & \downarrow r_f^* \\ H^*(X_f) & \longrightarrow & H^*(X) & \xrightarrow{f^* - \text{id}} & H^*(X) & \xrightarrow{\delta} & H^{*+1}(X_f). \end{array}$$

Proof. We consider the Mayer Vietoris sequence (see [9]) for

$$(4.9) \quad X_f = p_f(X \times [0, \frac{1}{2}]) \cup p_f(X \times [\frac{1}{2}, 1])$$

which is given by

$$(4.10) \quad \begin{aligned} \xrightarrow{\delta} H^*(X_f) &\rightarrow H^*(p_f(X \times [0, \frac{1}{2}])) \oplus H^*(p_f(X \times [\frac{1}{2}, 1])) \\ &\xrightarrow{i_1^* + i_2^*} H^*(p_f(X \times \{0\})) \oplus H^*(p_f(X \times \{\frac{1}{2}\})) \xrightarrow{\delta} . \end{aligned}$$

Applying the homotopy equivalence $\pi_X \circ p_f^{-1}$, we obtain the exact sequence

$$(4.11) \quad H^*(X_f) \rightarrow (H^*(X))^2 \xrightarrow{\theta} (H^*(X))^2 \rightarrow H^{*+1}(X_f)$$

with $\theta(\alpha, \beta) = (f^*\alpha + \beta, \alpha + \beta)$. Now define the isomorphism $j_1(x, y) = (x - y, y)$ and $j_2(\gamma, \delta) = (\gamma, \delta - \gamma)$ of $(H^*(X))^2$. Since

$$(4.12) \quad j_1 \circ \theta \circ j_2(\alpha, \beta) = (f^*\alpha - \alpha, \beta),$$

we can eliminate the factor $H^*(X)$ in (4.11) and obtain the sequence (4.7).

If we set up the same sequence for X replaced by Y , then the maps $R_f^*: H^*(Y_f) \rightarrow H^*(X_f)$ and $f^*r^* \oplus f^*r^*: (H^*(Y))^2 \rightarrow (H^*(X))^2$ commute with the exact sequences. Moreover, the latter homomorphism commutes with j_1 and j_2 , as one readily verifies. Hence eliminating one factor $H^*(X)$ as before, we obtain the commuting diagram (4.8). \square

Setting $X = Y = N$ in (4.8), we conclude by the five lemma (see [9]) that $f_f: M_f \rightarrow N_f$ induces isomorphisms in cohomology when restricted to N_f . Now the proof of [3, Theorem 2] applies to this situation and we can conclude that under the hypothesis of Theorem 3,

$$(4.13) \quad (r_f|_{T_f})^*: H_\rho^*(N_f) \rightarrow H_\rho^*(T_f)$$

is injective. In fact, although Theorem 2 of [3] formally requires r_f to be a retraction, the proof depends only on the fact that $(r_f|_{N_f})^*$ is injective.

We now have to pass from T_f to the fibre T . Note that in order to prove the injectivity of (4.1), it suffices to prove that

$$(4.14) \quad r^*[N] \neq 0,$$

where $[N] \in H_\rho^d(N)$, $d = \dim N$, is the fundamental class. In fact, it then follows from Poincaré duality (see [9]) that for every $x \in H_\rho^*(N)$, $x \neq 0$, there exists a class $y \in H_\rho^*(N)$ with $x \cup y = [N]$. Then $(r^*x) \cup (r^*y) = r^*[N] \neq 0$ implies that $r^*x \neq 0$.

To prove (4.14), we apply (4.8) of Lemma 4.1 to $X = N$ and $Y = T$. Since $f: N \rightarrow N$ is a diffeomorphism, we conclude that for coefficients as in Theorem 1, $f^*[N] = [N]$. Therefore, $f^* - \text{id}$, so that $\delta[N] \neq 0$. Hence $r_f^*\delta[N] \neq 0$ by injectivity of (4.13). Since (4.8) is commutative, we also have $\delta \circ f^* \circ r^*[N] \neq 0$, which proves (4.14). This completes the proof of Theorem 3.

In order to obtain a perturbation result, choose a (ρ -invariant) neighborhood U of N in M with a (ρ -invariant) retraction r . For example, we can use the metric g on M defined in §3 to define a diffeomorphism of the disc bundle $D_\epsilon \subset E^+ \oplus E^-$ onto $U := \exp_g(D_\epsilon)$ by means of

$$\exp_g: D_\epsilon \rightarrow U.$$

We can define a retraction r which corresponds to the bundle projection $D_\epsilon \rightarrow N$ under \exp_g . It is homotopic to $f^{-1}|_N \circ r \circ f$, since all retractions

$D_\varepsilon \rightarrow N$ are homotopic to the projection as is easily verified. Choosing such a homotopy H , we can define r_f as in (4.5). Now we apply Theorem 2 of [3] to the flow on the open set $U_f = p_f(U \times (-1, 1)) \subset M_f$.

Moreover, it is known that if U_f is isolating for flow χ_f , then this is true for all f_λ for λ small enough as in Theorem 1. For example, this is shown in [1, III.3]. In this case, U is also isolating for f' by Proposition 2. We can now apply Theorem 2 to the manifold U and the retraction r in order to conclude that the maximal invariant set $T = T_{f'}(U)$ satisfies the assertion of Theorem 1. This completes the proof of Theorem 1.

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