

HOLOMORPHIC QUADRATIC DIFFERENTIALS AND THE BERNSTEIN PROBLEM IN HEISENBERG SPACE

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ABSTRACT. We classify the entire minimal vertical graphs in the Heisenberg group Nil_3 endowed with a Riemannian left-invariant metric. This classification, which provides a solution to the Bernstein problem in Nil_3 , is given in terms of the Abresch-Rosenberg holomorphic differential for minimal surfaces in Nil_3 .

1. INTRODUCTION

A recent major achievement in the theory of constant mean curvature (CMC) surfaces in Riemannian 3-manifolds has been the discovery by Abresch and Rosenberg [AbRo1, AbRo2] of a holomorphic quadratic differential for every CMC surface in any homogeneous 3-manifold with a 4-dimensional isometry group. The most remarkable consequence of this construction is the classification given in [AbRo1, AbRo2] of the immersed CMC spheres in these homogeneous spaces as embedded rotational ones, thus solving an open problem proposed in [HsHs].

Our purpose in this paper is to solve by means of the Abresch-Rosenberg differential another popular open problem in the theory of CMC surfaces in homogeneous spaces, namely, the Bernstein problem in the Riemannian Heisenberg 3-space Nil_3 , i.e. the classification of the entire minimal vertical graphs in Nil_3 .

Let us fix some terminology. By using exponential coordinates and up to re-scaling, we shall regard the *Heisenberg space* Nil_3 as \mathbb{R}^3 endowed with the Riemannian metric

$$d\sigma^2 := dx^2 + dy^2 + \left(dz + \frac{1}{2}(ydx - xdy) \right)^2.$$

This Riemannian metric is left-invariant for the Lie group structure of Heisenberg space. In this way Nil_3 becomes one of the five simply connected canonical homogeneous 3-manifolds with a 4-dimensional isometry group.

A (vertical) graph $z = f(x, y)$ in Nil_3 is said to be minimal if its mean curvature vanishes identically, and *entire* if it is defined for every $(x, y) \in \mathbb{R}^2$. The *Bernstein*

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problem in Nil_3 asks for the classification of all entire vertical minimal graphs of Nil_3 . Equivalently, we wish to find all the C^2 solutions globally defined on \mathbb{R}^2 of the quasilinear elliptic PDE

$$(1.1) \quad (1 + \beta^2)f_{xx} - 2\alpha\beta f_{xy} + (1 + \alpha^2)f_{yy} = 0,$$

where $\alpha := f_x + y/2$ and $\beta := f_y - x/2$ (see [ADR, IKOS] for instance).

The simplest entire solutions to (1.1) are the linear ones, which give rise to entire minimal graphs in Nil_3 that are called *horizontal umbrellas* [AbRo2]. In this model they are just non-vertical planes, but they are not totally geodesic. Another simple solution is $f(x, y) = xy/2$, and more generally, the 1-parameter family [FMP]

$$(1.2) \quad f(x, y) = \frac{xy}{2} - c \left(y\sqrt{1+y^2} + \log \left(y + \sqrt{1+y^2} \right) \right), \quad c \in \mathbb{R}.$$

The resulting entire minimal graphs are called *saddle-type minimal examples* [AbRo2]. There are other explicit entire solutions to (1.1) foliated by Euclidean straight lines (see [Dan2]), which suggests that the class of entire minimal graphs in Nil_3 is quite large.

The Bernstein problem in Nil_3 is a usual discussion topic among people working on CMC surfaces in homogeneous spaces, and appears explicitly as an open problem in several works such as [FMP, AbRo2, Dan2, IKOS, MMP]. Let us also point out that the Bernstein problem in the sub-Riemannian Heisenberg space \mathbb{H}^1 has been intensely studied in the last few years (see [BSV, CHMY, GaPa, RiRo] and the references therein).

In this work we show that the moduli space of entire minimal graphs in Nil_3 can be parametrized in terms of their Abresch-Rosenberg differentials. Specifically, we prove:

Theorem 1 (Main Theorem). *Let Qdz^2 be a holomorphic quadratic differential in $\Sigma \equiv \mathbb{C}$ or \mathbb{D} which is not identically zero if $\Sigma \equiv \mathbb{C}$. Then there exists a 2-parameter family of (generically non-congruent) entire minimal graphs in Nil_3 whose Abresch-Rosenberg differential is Qdz^2 .*

Conversely, any entire minimal graph in Nil_3 is one of the above examples.

It is worth mentioning that if two holomorphic quadratic differentials on \mathbb{C} or \mathbb{D} only differ by a global conformal change of parameter, then the families of minimal graphs that they induce are the same (the corresponding immersions differ by this conformal global change of parameter).

We also remark that the conformally immersed minimal surfaces $X : \Sigma \rightarrow \text{Nil}_3$ with $\Sigma \equiv \mathbb{C}$ and Abresch-Rosenberg differential $Qdz^2 = cdz^2$, $c \neq 0$, are exactly the saddle-type minimal examples (1.2); see Section 2. In that case some of the elements of the 2-parameter family are mutually congruent. On the other hand, the minimal surfaces in Nil_3 with vanishing Abresch-Rosenberg differential on $\Sigma = \mathbb{C}$ are the vertical planes, which are not entire graphs.

The solution to the Bernstein problem exposed in Theorem 1 is sharp, in the following sense. First, it tells us that the space of entire solutions to (1.1) is extremely large. So, as these solutions will not be explicit in general, the most reasonable answer to the Bernstein problem in Nil_3 that one can look for is a description of the moduli space of entire minimal graphs in terms of some already-known class of objects. With this, Theorem 1 tells us that the space of entire minimal graphs in Nil_3 can be described by the space of holomorphic quadratic differentials on \mathbb{C} or \mathbb{D} , which is a well-known class.

The proof of Theorem 1 is based on four pillars. The first is the Abresch-Rosenberg holomorphic differential, whose role is substantial since it is the classifying object in the solution to the Bernstein problem. The second is the construction by the authors in [FeMi1] of a harmonic Gauss map into the hyperbolic plane \mathbb{H}^2 for CMC surfaces with $H = 1/2$ in $\mathbb{H}^2 \times \mathbb{R}$, and the global implications of this construction. Actually, the present paper may be regarded as a natural continuation of our previous work [FeMi1] in many aspects. The third pillar is the Lawson-type isometric correspondence by Daniel [Dan1] between minimal surfaces in Nil_3 and $H = 1/2$ surfaces in $\mathbb{H}^2 \times \mathbb{R}$. Fourthly, we will use some deep results by Wan-Au [Wan, WaAu] on the (at a first sight unrelated) classification of the complete spacelike CMC surfaces in the Lorentz-Minkowski 3-space \mathbb{L}^3 .

We have organized the paper as follows. Section 2 will be devoted to analyzing in detail the behavior of a large family of complete minimal surfaces constructed in [FeMi1] that are local graphs in Nil_3 . We shall call them *canonical examples* in Nil_3 . For that, we will revise all the basic machinery of the Abresch-Rosenberg differential, the Lawson-type correspondence in [Dan1] and the harmonic Gauss map for $H = 1/2$ surfaces in $\mathbb{H}^2 \times \mathbb{R}$.

In Section 3 we will prove that these canonical examples are precisely the entire minimal graphs in Nil_3 . This result and the constructions of Section 2 imply Theorem 1 and thus solve the Bernstein problem in Nil_3 .

Finally, in Section 4 we shall give a large family of entire vertical graphs with $H = 1/2$ in $\mathbb{H}^2 \times \mathbb{R}$, which can be seen as an advance in the problem of classifying all such entire graphs.

2. SETUP: THE CANONICAL EXAMPLES IN Nil_3

In this section we introduce the Heisenberg space Nil_3 and the product space $\mathbb{H}^2 \times \mathbb{R}$ as Riemannian homogeneous 3-spaces with a 4-dimensional group of isometries and we describe some basic facts about the theory of surfaces in these spaces that will be useful for our purposes. We shall also analyze the *canonical examples*, which will be characterized in Section 3 as the only entire minimal graphs in Nil_3 . In order to do that, we will recall the correspondence between minimal surfaces in Nil_3 and CMC $1/2$ surfaces in $\mathbb{H}^2 \times \mathbb{R}$, as well as the notion of *hyperbolic Gauss map* for surfaces in $\mathbb{H}^2 \times \mathbb{R}$ and its basic properties. For more details about these matters we refer to [AbRo2, Dan1, Dan2, FeMi1, FeMi2] and the references therein.

Surfaces in homogeneous 3-spaces. We will label as $\mathcal{M}^2(\kappa)$ the unique 2-dimensional Riemannian space form of constant curvature κ . Thus, $\mathcal{M}^2(\kappa) = \mathbb{R}^2, \mathbb{S}^2$ or \mathbb{H}^2 when $\kappa = 0, 1$ or -1 , respectively.

Any simply connected homogeneous 3-manifold with a 4-dimensional group of isometries can be described as a Riemannian fibration over some $\mathcal{M}^2(\kappa)$. Translations along the fibers are isometries and therefore they generate a Killing field, ξ , also called the *vertical field*. The *bundle curvature* of the space is the number $\tau \in \mathbb{R}$ with $\kappa \neq 4\tau^2$ such that $\overline{\nabla}_X \xi = \tau X \times \xi$ holds for any vector field X on the manifold. Here $\overline{\nabla}$ is the Levi-Civita connection of the manifold and \times denotes the cross product. When $\tau = 0$ this fibration becomes trivial and thus we get the product spaces $\mathcal{M}^2(\kappa) \times \mathbb{R}$. When $\tau \neq 0$ the manifolds have the isometry group of the Heisenberg space if $\kappa = 0$, of the Berger spheres if $\kappa > 0$, or the one of the universal covering of $\text{PSL}(2, \mathbb{R})$ when $\kappa < 0$.

In what follows $\mathbb{E}^3(\kappa, \tau)$ will represent a simply connected homogeneous 3-manifold with isometry group of dimension 4, where κ and τ are the real numbers described above.

For an immersion $X : \Sigma \rightarrow \mathbb{E}^3(\kappa, \tau)$, we will define its *vertical projection* as $F := \pi \circ \psi : \Sigma \rightarrow \mathcal{M}^2(\kappa)$, where $\pi : \mathbb{E}^3(\kappa, \tau) \rightarrow \mathcal{M}^2(\kappa)$ is the canonical submersion of the homogeneous space. A surface in $\mathbb{E}^3(\kappa, \tau)$ is a (vertical) entire graph when its vertical projection is a global diffeomorphism. From now on, by a *graph* we will always mean a vertical one.

Remark 2. The case we are mostly interested in is, up to rescaling, when $\kappa = 0$ and $\tau = 1/2$. This corresponds to the Heisenberg space, that will be denoted by Nil_3 . This space can be seen as $\text{Nil}_3 = (\mathbb{R}^3, d\sigma^2)$ where $d\sigma^2$ is the Riemannian metric

$$d\sigma^2 := dx_1^2 + dx_2^2 + \left(dx_3 + \frac{1}{2}(x_2 dx_1 - x_1 dx_2) \right)^2.$$

In this model the Riemannian submersion π is just the usual projection of \mathbb{R}^3 onto the plane $x_3 = 0$,

$$\pi : \text{Nil}_3 \rightarrow \mathbb{R}^2, \quad \pi(x_1, x_2, x_3) = (x_1, x_2).$$

Let $X : \Sigma \rightarrow \mathbb{E}^3(\kappa, \tau)$ be an immersed surface with unit normal vector η . Given a conformal parameter z for X let us write its induced metric as $\lambda|dz|^2$. We also label H as the mean curvature of the surface and $p dz^2$ as its Hopf differential, i.e. $p = -\langle X_z, \eta_z \rangle$. The *angle function* is defined as the normal component of the vertical field, $u = \langle \eta, \xi \rangle$. Finally, we define the complex-valued function A as $A = \langle \xi, X_z \rangle = \langle T, \partial_z \rangle$, where $T \in \mathfrak{X}(\Sigma)$ is given by $dX(T) = \xi - u\eta$. We will call $\{\lambda, u, H, p, A\} \in \mathbb{R}^+ \times [-1, 1] \times \mathbb{R} \times \mathbb{C}^2$ the *fundamental data* of the surface $X : \Sigma \rightarrow \mathbb{E}^3(\kappa, \tau)$.

The integrability conditions of surfaces in $\mathbb{E}^3(\kappa, \tau)$ can be expressed in terms of some equations involving these fundamental data (see [Dan1, FeMi2]). Of these, in this paper we will only need the relation

$$(C.4) \quad \frac{4|A|^2}{\lambda} = 1 - u^2.$$

With the above notation, if $F : \Sigma \rightarrow \mathcal{M}^2(\kappa)$ is the vertical projection of $X : \Sigma \rightarrow \mathbb{E}^3(\kappa, \tau)$, then

$$(2.1) \quad F_z = X_z - A\xi.$$

Notice also that when $\tau = 0$ (i.e., $\mathbb{E}^3(\kappa, \tau) = \mathcal{M}^2(\kappa) \times \mathbb{R}$) the vertical field ξ is nothing but $\xi = (0, 1) \in \mathfrak{X}(\mathcal{M}^2(\kappa)) \times \mathbb{R}$. Therefore, if we write $X = (N, h) : \Sigma \rightarrow \mathcal{M}^2(\kappa) \times \mathbb{R}$, then the vertical projection is N and $A = h_z$. The function h will be called the *height function*.

The Abresch-Rosenberg differential. The Abresch-Rosenberg differential for an immersed surface $X : \Sigma \rightarrow \mathbb{E}^3(\kappa, \tau)$ is defined as the quadratic differential

$$Qdz^2 = (2(H + i\tau)p - (\kappa - 4\tau^2)A^2) dz^2.$$

Its importance is given by the following result.

Theorem 3 ([AbRo1, AbRo2]). *The Abresch-Rosenberg differential Qdz^2 is a holomorphic quadratic differential on any CMC surface in $\mathbb{E}^3(\kappa, \tau)$.*

Unlike the case of \mathbb{R}^3 , where the holomorphicity of the Hopf differential necessarily implies the constancy of the mean curvature, there exist non-CMC surfaces in some homogeneous spaces $\mathbb{E}^3(\kappa, \tau)$ with holomorphic Abresch-Rosenberg differential. A detailed discussion of this converse problem can be found in [FeMi2].

In [Dan1], B. Daniel established a local isometric Lawson-type correspondence between simply connected CMC surfaces in the homogeneous spaces $\mathbb{E}^3(\kappa, \tau)$. Surfaces related by this correspondence are usually called *sister surfaces*.

As a particular case this isometric correspondence relates minimal surfaces in Nil_3 and $H = 1/2$ surfaces in $\mathbb{H}^2 \times \mathbb{R}$. In terms of their fundamental data the correspondence is given as follows: given a simply connected minimal surface in Nil_3 with fundamental data

$$(2.2) \quad \{\lambda, u, H = 0, p, A\}$$

its sister $H = 1/2$ surface in $\mathbb{H}^2 \times \mathbb{R}$ (which is unique up to isometries of $\mathbb{H}^2 \times \mathbb{R}$ preserving the orientation of both base and fiber) has fundamental data

$$(2.3) \quad \{\lambda, u, H = 1/2, -ip, -iA\}.$$

In particular, their respective Abresch-Rosenberg differentials are opposite to one another. Moreover, the two sister surfaces have the same induced metric, and one of them is a local graph if and only if its sister immersion is also a local graph (if and only if $u \neq 0$). We remark that in this paper we shall prove that the sister surface of an entire minimal graph in Nil_3 is always an entire $H = 1/2$ graph in $\mathbb{H}^2 \times \mathbb{R}$ (see Proposition 14).

The hyperbolic Gauss map in $\mathbb{H}^2 \times \mathbb{R}$. One of the key tools of this work is the existence of a Gauss-type map for surfaces in $\mathbb{H}^2 \times \mathbb{R}$ with special properties, introduced in [FeMi1]. Next, we analyze in more detail than in [FeMi1] the geometrical meaning of this Gauss map.

First, let \mathbb{L}^4 denote the Minkowski 4-space with canonical coordinates (x_0, x_1, x_2, x_3) and the Lorentzian metric $\langle, \rangle = -dx_0^2 + \sum_{i=1}^3 dx_i^2$. We shall regard as hyperquadrics in \mathbb{L}^4 in the usual way the hyperbolic 3-space \mathbb{H}^3 , the de Sitter 3-space \mathbb{S}_1^3 , the positive null cone \mathbb{N}^3 , and the product space $\mathbb{H}^2 \times \mathbb{R}$ (see [FeMi1]).

Let \mathbb{S}_∞^2 denote the ideal boundary of \mathbb{H}^3 . We have the usual identifications (see [Bry, GaMi] for instance)

$$\mathbb{S}_\infty^2 \equiv \mathbb{N}^3/\mathbb{R}_+ \equiv \mathbb{N}^3 \cap \{x_0 = 1\} \equiv \{1\} \times \mathbb{S}^2 \equiv \mathbb{S}^2 \subset \mathbb{R}^3.$$

Let $\psi = (N, h) : \Sigma \rightarrow \mathbb{H}^2 \times \mathbb{R}$ be an immersed surface, and let $\eta : \Sigma \rightarrow \mathbb{S}_1^3$ denote its unit normal. Then $\eta + N$ takes its values in \mathbb{N}^3 , and $[\eta + N] \in \mathbb{N}^3/\mathbb{R}_+ \equiv \mathbb{S}_\infty^2$ is the point at infinity reached by the unique geodesic of \mathbb{H}^3 starting at N with initial speed η .

If ψ has regular vertical projection (i.e. $N : \Sigma \rightarrow \mathbb{H}^2$ is a local diffeomorphism), and if u denotes the last coordinate of η , it turns out that $u \neq 0$ at every point (we assume thus that $u > 0$ up to a change of orientation). Consequently, the map

$$\xi = \frac{1}{u}(\eta + N) : \Sigma \rightarrow \mathbb{L}^4$$

takes its values in $\mathbb{N}^3 \cap \{x_3 = 1\}$. Thus, there exists some $G : \Sigma \rightarrow \mathbb{H}^2$ with $\xi = (G, 1)$.

Now, observe that as $u > 0$, it happens that $[\eta + N] = [\xi]$ takes its values in the hemisphere

$$\mathbb{S}_{\infty,+}^2 \equiv (\mathbb{N}^3 \cap \{x_3 > 0\})/\mathbb{R}_+ \equiv (\{1\} \times \mathbb{S}^2) \cap \{x_3 > 0\} \equiv \mathbb{S}^2 \cap \{x_3 > 0\}.$$

So, if we write $G = (G_0, G_1, G_2)$ and $[\eta + N] = (1, y_1, y_2, y_3) \equiv (y_1, y_2, y_3)$, we have that, using the projective structure of \mathbb{N}^3 ,

$$(y_1, y_2, y_3) = [\eta + N] = [\xi] = \frac{1}{G_0}(G_1, G_2, 1) \in \mathbb{S}_+^2 := \mathbb{S}^2 \cap \{x_3 > 0\}.$$

Composing finally with the vertical projection $\mathbb{S}_+^2 \rightarrow \mathbb{D}$ we obtain a map

$$z \in \Sigma \mapsto (G_0, G_1, G_2)(z) \in \mathbb{H}^2 \subset \mathbb{L}^3 \mapsto \left(\frac{G_1}{G_0}, \frac{G_2}{G_0} \right) (z) \in \mathbb{D}.$$

This last coordinate relation is the usual identification between the Minkowski model $\mathcal{H}^2 = \{x \in \mathbb{L}^3 : \langle x, x \rangle = -1, x_0 > 0\}$ and the Klein (or projective) model (\mathbb{D}, ds_K^2) of the hyperbolic space \mathbb{H}^2 .

In other words, $G : \Sigma \rightarrow \mathbb{H}^2$ can be seen as the map sending each point (N_0, h_0) of the surface to the positive hemisphere at infinity $\mathbb{S}_{\infty,+}^2$ of \mathbb{H}^3 endowed with the Klein metric of \mathbb{H}^2 (after vertical projection), by considering the unique geodesic of \mathbb{H}^3 starting at N_0 with initial speed η (the unit normal at the point).

Definition 4. The above map $G : \Sigma \rightarrow \mathbb{H}^2$ will be called the *hyperbolic Gauss map* of the surface with regular vertical projection $\psi : \Sigma \rightarrow \mathbb{H}^2 \times \mathbb{R}$.

This interpretation of the hyperbolic Gauss map in terms of the ideal boundary of \mathbb{H}^3 enables us to visualize it directly in the cylindrical model of $\mathbb{H}^2 \times \mathbb{R}$. This might be useful for a better understanding of the geometrical information carried by this hyperbolic Gauss map.

So, let us view $\mathbb{H}^2 \times \mathbb{R}$ in its cylindrical model $(\mathbb{D}, ds_P^2) \times \mathbb{R}$, where

$$ds_P^2 = \frac{4}{(1 - |z|^2)^2} |dz|^2, \quad z \in \mathbb{D} = \{z \in \mathbb{C} : |z| < 1\},$$

is the Poincaré metric of \mathbb{H}^2 . We consider as before an immersed surface $\psi : \Sigma \rightarrow \mathbb{H}^2 \times \mathbb{R}$ with regular vertical projection and upwards pointing unit normal. Let $z_0 \in \Sigma$ and write $\psi(z_0) = (N_0, h_0)$. Then we can visualize the hyperbolic 3-space \mathbb{H}^3 (in its Poincaré ball model) *inside* the cylinder $\mathbb{H}^2 \times \mathbb{R}$ with equator at $\mathbb{H}^2 \times \{0\}$ (see Figure 1). We now consider the unique oriented geodesic γ in \mathbb{H}^3 starting at $(N_0, 0)$ with tangent vector $\eta(z_0)$. Label $G(z_0) \in \partial_\infty \mathbb{H}^3$ as the limit point of γ in the asymptotic boundary of \mathbb{H}^3 , $\partial_\infty \mathbb{H}^3 \equiv \mathbb{S}^2$. Let us observe that, since we have chosen η upwards pointing, $G(z_0)$ actually lies in the upper hemisphere of the sphere at infinity \mathbb{S}_+^2 . At last, we project \mathbb{S}_+^2 into \mathbb{D} , and we endow \mathbb{D} with the Klein metric (thus $(\mathbb{D}, ds_K^2) \equiv \mathbb{H}^2$).

The result of this is a map $G : \Sigma \rightarrow (\mathbb{D}, ds_K^2) \equiv \mathbb{H}^2$, which is the *hyperbolic Gauss map* of ψ . Its most remarkable property is that it is harmonic for $H = 1/2$ surfaces, as we explain next.

CMC one-half surfaces in $\mathbb{H}^2 \times \mathbb{R}$. The existence of the *canonical examples* of minimal surfaces in Nil_3 will be shown in terms of their sister surfaces in $\mathbb{H}^2 \times \mathbb{R}$, so let us first recall some facts about surfaces with $H = 1/2$ in $\mathbb{H}^2 \times \mathbb{R}$.

To start, let $G : \Sigma \rightarrow \mathbb{H}^2$ denote a harmonic map from the Riemann surface Σ into \mathbb{H}^2 . Then the quadratic differential $\langle G_z, G_z \rangle dz^2$ is holomorphic on Σ , and it is

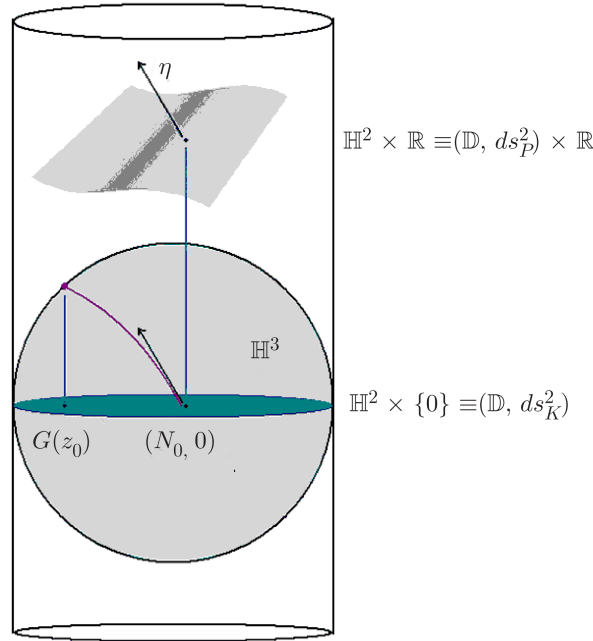


FIGURE 1. The hyperbolic Gauss map for surfaces in $\mathbb{H}^2 \times \mathbb{R}$

called the *Hopf differential* of the harmonic map G . Following [FeMi1], we say that a harmonic map *admits Weierstrass data* $\{Q, \tau_0\}$ if there exists $\tau_0 : \Sigma \rightarrow (0, \infty)$ a smooth positive function such that

$$\langle dG, dG \rangle = Qdz^2 + \left(\frac{\tau_0}{4} + \frac{4|Q|^2}{\tau_0} \right) |dz|^2 + \bar{Q}d\bar{z}^2.$$

The connection between $H = 1/2$ surfaces in $\mathbb{H}^2 \times \mathbb{R}$ and harmonic maps into \mathbb{H}^2 was studied in [FeMi1]. We condense the most relevant features of this connection in the following result.

Convention: From now on, a surface in $\mathbb{H}^2 \times \mathbb{R}$ with r.v.p. will always be assumed to be *canonically oriented*, meaning that its unit normal is upwards pointing.

Theorem 5 ([FeMi1]). *The hyperbolic Gauss map $G : \Sigma \rightarrow \mathbb{H}^2$ of an $H = 1/2$ surface $\psi : \Sigma \rightarrow \mathbb{H}^2 \times \mathbb{R}$ with regular vertical projection is harmonic. Moreover, if $-Qdz^2$ denotes the Abresch-Rosenberg differential of the surface, $\lambda|dz|^2$ its metric and u its angle function, then the quantities $\{Q, \lambda u^2\}$ are Weierstrass data for G . In particular the Hopf differential of G is Qdz^2 .*

Conversely, let Σ be a simply connected Riemann surface and $G : \Sigma \rightarrow \mathbb{H}^2$ be a harmonic map admitting Weierstrass data $\{Q, \tau_0\}$. Then

- (1) *If G is singular on an open subset of Σ , then it parametrizes a piece of a geodesic in \mathbb{H}^2 . Moreover, there exists a 1-parameter family of $H = 1/2$ graphs in $\mathbb{H}^2 \times \mathbb{R}$, invariant under a 1-parameter subgroup of isometries, such that G is the hyperbolic Gauss map of any of them. These surfaces*

are described in [Sa] (see also [FeMi1, Dan2]), and they are open pieces of the sister surfaces of the saddle-type minimal graphs in Nil_3 .

(2) If not, let $z_0 \in \Sigma$ be a regular point of G . Then for any $\vartheta_0 \in \mathbb{C}$ there exists a unique $H = 1/2$ surface $\psi = (N, h) : \Sigma \rightarrow \mathbb{H}^2 \times \mathbb{R}$ with r.v.p., having G as its hyperbolic Gauss map and satisfying:

(a) $\tau_0 = \lambda u^2$, where λ is the conformal factor of the metric of ψ and u its angle function,

(b) $h_z(z_0) = \vartheta_0$.

Moreover,

$$N = \frac{8 \operatorname{Re} \left(G_z (\tau_0 h_{\bar{z}} - 4\bar{Q} h_z) \right)}{\tau_0^2 - 16|Q|^2} + G \sqrt{\frac{\tau_0 + 4|h_z|^2}{\tau_0}},$$

and $h : \Sigma \rightarrow \mathbb{R}$ is the unique (up to additive constants) solution to the differential system below such that $h_z(z_0) = \vartheta_0$:

$$(2.4) \quad \begin{cases} h_{zz} &= (\log \tau_0)_z h_z - Q \sqrt{\frac{\tau_0 + 4|h_z|^2}{\tau_0}}, \\ h_{z\bar{z}} &= \frac{1}{4} \sqrt{\tau_0(\tau_0 + 4|h_z|^2)}. \end{cases}$$

Remark 6. A straightforward consequence of the definition of the hyperbolic Gauss map is that if two surfaces in $\mathbb{H}^2 \times \mathbb{R}$ with r.v.p. are congruent by an isometry preserving the orientation of the fibers, then their respective hyperbolic Gauss maps differ by an isometry of \mathbb{H}^2 . As a result, if two harmonic maps G_1, G_2 into \mathbb{H}^2 differ by an isometry, then the two families of $H = 1/2$ surfaces obtained from G_1 and G_2 via Theorem 5 just differ by an isometry of $\mathbb{H}^2 \times \mathbb{R}$ preserving the orientation of the fibers. This is a consequence of the uniqueness part of Theorem 5.

The canonical examples in Nil_3 . In what follows, Σ will denote a simply connected open Riemann surface, that will be assumed without loss of generality to be $\Sigma = \mathbb{C}$ or $\Sigma = \mathbb{D}$.

In [FeMi1] we proved the existence of a large family of complete minimal surfaces in Nil_3 that are local vertical graphs. More specifically, we showed:

Theorem 7 ([FeMi1]). *Let Qdz^2 denote a holomorphic quadratic differential on Σ , which is non-zero if $\Sigma = \mathbb{C}$. Then there exists (at least) a complete minimal surface with regular vertical projection in Nil_3 whose Abresch-Rosenberg differential is Qdz^2 .*

It is relevant for our purposes to explain how these examples are constructed. Let Qdz^2 be a holomorphic quadratic differential as above. By [Wan, WaAu] there exists a complete spacelike CMC $1/2$ surface $f : \Sigma \rightarrow \mathbb{L}^3$ in the Lorentz-Minkowski 3-space \mathbb{L}^3 whose Hopf differential is Qdz^2 . Here, recall that \mathbb{L}^3 is just \mathbb{R}^3 endowed with the Lorentzian metric $\langle \cdot, \cdot \rangle = dx_1^2 + dx_2^2 - dx_3^2$ in canonical coordinates, and that an immersed surface $f : \Sigma \rightarrow \mathbb{L}^3$ is called *spacelike* if its induced metric $\langle df, df \rangle$ is Riemannian.

Let $\nu : \Sigma \rightarrow \mathbb{H}^2 \cup \mathbb{H}^2_- \subset \mathbb{L}^3$ denote its Gauss map, which is well known to be harmonic. Now let $G : \Sigma \rightarrow \mathbb{H}^2$ denote the harmonic map given by $G = \nu$ if ν is future-pointing, or by the vertical symmetry of ν in \mathbb{L}^3 otherwise. Thus, if $\langle df, df \rangle = \tau_0 |dz|^2$ denotes the induced metric of f , it turns out (see [FeMi1])

that $\{Q, \tau_0\}$ are Weierstrass data for G . Then the $H = 1/2$ surfaces in $\mathbb{H}^2 \times \mathbb{R}$ constructed from G and τ_0 via Theorem 5 are complete (since $\tau_0|dz|^2 = \lambda u^2|dz|^2$ is complete), have regular vertical projection, and Abresch-Rosenberg differential $-Qdz^2$. Consequently, the sister surfaces of these examples are complete minimal surfaces in Nil_3 with regular vertical projection and whose Abresch-Rosenberg differential is Qdz^2 .

Let us mention that $f : \Sigma \rightarrow \mathbb{L}^3$ is unique, in the sense that if $\tilde{f} : \Sigma \rightarrow \mathbb{L}^3$ is another complete spacelike $H = 1/2$ surface with Hopf differential Qdz^2 , then $\tilde{f} = \Phi \circ f$ for some positive rigid motion Φ of \mathbb{L}^3 . Thereby, if we start with some \tilde{f} different from (but congruent to) f , the harmonic map $\tilde{G} : \Sigma \rightarrow \mathbb{H}^2$ we obtain following the process above differs from G at most by an isometry of \mathbb{H}^2 .

Thus, bearing in mind Remark 6 we conclude that the families of $H = 1/2$ surfaces in $\mathbb{H}^2 \times \mathbb{R}$ obtained, respectively, from f and \tilde{f} , differ at most by an isometry of $\mathbb{H}^2 \times \mathbb{R}$ that preserves the orientation of the fibers. This means by the sister correspondence that no new examples in Nil_3 appear if in the above process we consider $\Phi \circ f$ instead of f for any positive rigid motion Φ of \mathbb{L}^3 .

Finally, let us comment on some properties of these minimal examples in Nil_3 , that one should keep in mind for what follows.

- By Theorem 5 and the uniqueness property we have just pointed out, the above procedure yields in the generic case (i.e. in the case where the Gauss map G does not have a 1-parameter symmetry group) a 2-parameter family of non-congruent complete minimal surfaces in Nil_3 with the same Abresch-Rosenberg differential. These two continuous parameters come from the variation of the initial condition $h_z(z_0) = \vartheta_0$. Although the elements of this family are non-congruent in general (e.g., if the Gauss map has no symmetries), it happens that for minimal surfaces in Nil_3 invariant under a 1-parameter subgroup of isometries many of the elements of the 2-parameter family are congruent to each other. A detailed discussion on this topic can be found on page 1165 of [FeMi1] (see also [Dan2]).
- The only minimal surfaces in Nil_3 with $Q = 0$ and $\Sigma = \mathbb{C}$ are vertical planes, which do not have regular vertical projection. Besides, the minimal surfaces with $Q = 0$ and $\Sigma = \mathbb{D}$ are the horizontal minimal umbrellas [AbRo2, Dan1].
- When $\Sigma = \mathbb{C}$ and $Qdz^2 = c dz^2$, $c \in \mathbb{C} \setminus \{0\}$, the spacelike surface $f : \Sigma \rightarrow \mathbb{L}^3$ defined above is the hyperbolic cylinder, whose Gauss map parametrizes a piece of a geodesic in \mathbb{H}^2 . This corresponds to Case 1 in Theorem 5, and therefore, the corresponding family of canonical examples is the 1-parameter family of saddle type surfaces, as stated in the introduction.
- Any of the minimal surfaces in Nil_3 given by Theorem 7 verifies that $u^2 g$ is a complete Riemannian metric, where here g and u stand, respectively, for the induced metric and the angle function of the minimal surface.

Definition 8 (Canonical examples). A minimal surface $X : \Sigma \rightarrow \text{Nil}_3$ will be called a *canonical example* if it is one of the complete minimal surfaces with regular vertical projection given by Theorem 7.

We will show in the next section that the canonical examples in Nil_3 are exactly the entire minimal graphs in Nil_3 . This justifies the terminology we have used.

3. SOLUTION TO THE BERNSTEIN PROBLEM IN Nil_3

This section is devoted to the proof of Theorem 1. First of all, we prove that any canonical example is an entire graph. This will be obtained as a consequence of the following lemma.

Lemma 9. *Let $X : \Sigma \rightarrow \mathbb{E}^3(\kappa, \tau)$ be a surface in the homogeneous 3-manifold $\mathbb{E}^3(\kappa, \tau)$. Denote by $F : \Sigma \rightarrow \mathcal{M}^2(\kappa)$ its vertical projection and by g_F the induced metric of F in Σ . Then, for every $v \in \mathfrak{X}(\Sigma)$,*

$$(3.1) \quad u^2 g(v, v) \leq g_F(v, v) \leq g(v, v),$$

where g denotes the induced metric of the immersion X and u is the angle function.

Proof. Let z be a conformal parameter for X so that the induced metric on Σ is written as $g = \lambda|dz|^2$. Keeping the notation introduced in Section 2 we have by (2.1) that the metric of the vertical projection is written with respect to z as

$$(3.2) \quad g_F = -A^2 dz^2 + (\lambda - 2|A|^2)|dz|^2 - \bar{A}^2 d\bar{z}^2.$$

Then the eigenvalues $\rho_1 \geq \rho_2$ of the symmetric bilinear form g_F with respect to the flat metric $|dz|^2$ are the solutions of the equation $\det[g_F - \rho \text{Id}] = 0$, which by (C.4) yields

$$\rho_1 = \lambda, \quad \rho_2 = \lambda - 4|A|^2 = \lambda u^2.$$

From this we obtain (3.1) immediately. \square

From this lemma we can now prove that canonical examples are entire minimal graphs. Indeed, if $X : \Sigma \rightarrow \text{Nil}_3$ is a canonical example with angle function u and induced metric g on Σ , the metric $u^2 g$ is complete, and thus Lemma 9 gives the completeness of g_F . As a consequence, $F : (\Sigma, g_F) \rightarrow \mathbb{R}^2$ is a local isometry with (Σ, g_F) complete. In these conditions, F must necessarily be a (surjective) covering map. Hence, the vertical projection $F : \Sigma \rightarrow \mathbb{R}^2$ is a global diffeomorphism and X is an entire graph.

This fact together with the comments in Section 2 regarding the canonical examples in Nil_3 proves the existence part of Theorem 1.

Once here, in order to complete the proof of Theorem 1, it remains only to check that any entire minimal graph in Nil_3 is one of the canonical examples. For that, let us first provide a geometric interpretation of the differential system (2.4).

From now on, Σ will denote an open simply connected Riemann surface.

Let $f : \Sigma \rightarrow \mathbb{L}^3$ denote a spacelike surface with future-pointing Gauss map, with induced metric $\tau_0|dz|^2$ and Hopf differential Qdz^2 . Then:

- (1) If $H = 1/2$, its Gauss map $G : \Sigma \rightarrow \mathbb{H}^2$ is harmonic and admits the Weierstrass data $\{Q, \tau_0\}$. In addition, Q, τ_0 verify the Gauss-Codazzi equations in \mathbb{L}^3 for $H = 1/2$, i.e.

$$(3.3) \quad (\log \tau_0)_{z\bar{z}} = \frac{\tau_0}{8} - \frac{2|Q|^2}{\tau_0}, \quad Q_{\bar{z}} = 0.$$

- (2) Conversely, if a harmonic map $G : \Sigma \rightarrow \mathbb{H}^2$ admits Weierstrass data $\{Q, \tau_0\}$, then by [FeMi1, Lemma 4] the pair Q, τ_0 satisfy (3.3). Therefore there exists some (unique up to positive isometries) spacelike $H = 1/2$ surface $f : \Sigma \rightarrow \mathbb{L}^3$ with metric $\tau_0|dz|^2$ and Hopf differential Qdz^2 .

Bearing these facts in mind, we have

Lemma 10. *Let $\{Q, \tau_0\}$ be Weierstrass data of a harmonic map $G : \Sigma \rightarrow \mathbb{H}^2$, and let $f : \Sigma \rightarrow \mathbb{L}^3$ denote an arbitrary spacelike $H = 1/2$ surface in \mathbb{L}^3 with Hopf differential $-Qdz^2$ and metric $\tau_0|dz|^2$ (which is unique up to positive isometries of \mathbb{L}^3).*

Then a function $h : \Sigma \rightarrow \mathbb{R}$ is a solution to (2.4) if and only if $h = -\langle f, a \rangle$, where $a \in \mathbb{L}^3$ verifies $\langle a, a \rangle = -1$ and belongs to the connected component of the two-sheeted hyperboloid $\mathbb{H}^2 \cup \mathbb{H}_-^2 \subset \mathbb{L}^3$ where the Gauss map of f lies.

Proof. Let us first of all prove that $h := -\langle f, a \rangle$ as above solves (2.4). For that, we first rewrite (2.4) as

$$(3.4) \quad \begin{cases} h_{zz} &= (\log \tau_0)_z h_z - \frac{4Q}{\tau_0} h_{z\bar{z}}, \\ h_{z\bar{z}} &= \frac{1}{4} \sqrt{\tau_0(\tau_0 + 4|h_z|^2)}. \end{cases}$$

On the other hand, by the structure equations for f in \mathbb{L}^3 we have

$$(3.5) \quad f_{zz} = (\log \tau_0)_z f_z - QG_f, \quad f_{z\bar{z}} = \frac{\tau_0}{4} G_f,$$

where $G_f : \Sigma \rightarrow \mathbb{H}^2 \cup \mathbb{H}_-^2$ is the Gauss map of f . So, it is clear by (3.5) that $h = -\langle f, a \rangle$ verifies the first equation in (3.4) for every $a \in \mathbb{L}^3$. To see that h also verifies the second one we first observe that, by (3.5),

$$(3.6) \quad h_{z\bar{z}} = -\frac{\tau_0}{4} \langle a, G_f \rangle.$$

Besides,

$$a = \frac{2\langle a, f_{\bar{z}} \rangle}{\tau_0} f_z + \frac{2\langle a, f_z \rangle}{\tau_0} f_{\bar{z}} - \langle a, G_f \rangle G_f,$$

so from $\langle a, a \rangle = -1$ we obtain

$$(3.7) \quad \langle a, G_f \rangle^2 = 1 + \frac{4|\langle a, f_z \rangle|^2}{\tau_0}.$$

Putting together (3.6), (3.7) and taking into account that $\langle a, G_f \rangle < 0$ by hypothesis, we conclude that

$$h_{z\bar{z}} = \frac{\tau_0}{4} \sqrt{1 + \frac{4|\langle a, f_z \rangle|^2}{\tau_0}} = \frac{1}{4} \sqrt{\tau_0(\tau_0 + 4|h_z|^2)},$$

i.e. that h also satisfies the second equation of (3.4), and therefore (2.4) as claimed.

Finally, in order to see that all the solutions of (2.4) are of this form, we will see that for every $\vartheta_0 \in \mathbb{C}$ there is some $a \in \mathbb{H}^2 \cup \mathbb{H}_-^2$ in the connected component of $G(\Sigma)$ such that

$$(3.8) \quad -\langle f_z(z_0), a \rangle = \vartheta_0$$

for a fixed point $z_0 \in \Sigma$. Once this is done, the result will follow by the uniqueness (up to additive constants) of solutions to (2.4) with the initial condition $h_z(z_0) = \vartheta_0$.

To prove this claim, observe first that (3.8) is a linear system of two equations for $a = (a_1, a_2, a_3)$. So, as df is spacelike and regular, the solution to the system above is an affine timelike line in \mathbb{L}^3 . This line meets both \mathbb{H}^2 and \mathbb{H}_-^2 , which ensures the existence of some a with $\langle a, a \rangle = -1$ in the connected component of $G(\Sigma)$ that fulfills the initial condition (3.8). \square

The next lemma is the key ingredient to proving this classification result. We also think that this result has importance by itself beyond the use that we give it here. In particular, it may allow us to construct a Sym-Bobenko-type formula for $H = 1/2$ surfaces in $\mathbb{H}^2 \times \mathbb{R}$ and for minimal surfaces in Nil_3 .

Lemma 11. *Let $\psi = (N, h) : \Sigma \rightarrow \mathbb{H}^2 \times \mathbb{R}$ be an $H = 1/2$ surface with regular vertical projection, and let $-Qdz^2$ denote its Abresch-Rosenberg differential. Let $X = (F, t) : \Sigma \rightarrow \text{Nil}_3$ be any of its sister minimal surfaces in Nil_3 .*

Then there is some $\varepsilon = \pm 1$ such that $f := (F, \varepsilon h) : \Sigma \rightarrow \mathbb{L}^3$ is the unique (up to positive isometries) spacelike surface with $H = 1/2$ in \mathbb{L}^3 with induced metric u^2g and Hopf differential $-Qdz^2$. Here g, u are, respectively, the metric and the angle function of X (and of ψ).

Proof. Let z denote a conformal parameter on Σ , and write $g = \lambda|dz|^2$ for the common induced metric of both ψ and X . Let us point out that Qdz^2 is the Hopf differential of the (harmonic) hyperbolic Gauss map $G : \Sigma \rightarrow \mathbb{H}^2$ of ψ , and that G admits the Weierstrass data $\{Q, \tau_0 := \lambda u^2\}$. Thus $\{-Q, \tau_0\}$ verify the Gauss-Codazzi equations (3.3), and there exists a unique (up to positive isometries of \mathbb{L}^3) spacelike $H = 1/2$ immersion $f_0 : \Sigma \rightarrow \mathbb{L}^3$ with induced metric $\tau_0|dz|^2$ and Hopf differential $-Qdz^2$.

Let us denote $f_0 = (P, r) : \Sigma \rightarrow \mathbb{L}^3$. Then by Lemma 10 any solution to (2.4) is of the form $-\langle f_0, a \rangle$ for some $a \in \mathbb{H}^2 \cup \mathbb{H}_-^2$. In particular, the height function h of $\psi = (N, h)$ is of this form, by Theorem 5. Thus, by composing with an adequate positive isometry of \mathbb{L}^3 if necessary, we may assume that $h = r$.

With this, the metric of the projection P is

$$\langle dP, dP \rangle = h_z^2 dz^2 + (\tau_0 + 2|h_z|^2) |dz|^2 + h_{\bar{z}}^2 d\bar{z}^2.$$

On the other hand, let $X = (F, t)$ be an arbitrary sister minimal surface in Nil_3 of $\psi = (N, h)$. Then, by (2.2) and (2.3) we have that $A = ih_z$, where A belongs to the fundamental data of X . Now, using this together with (3.2) and formula (C.4) we infer that

$$\begin{aligned} \langle dF, dF \rangle &= -A^2 dz^2 + (\lambda - 2|A|^2) |dz|^2 - \bar{A}^2 d\bar{z}^2 \\ &= h_z^2 dz^2 + (\lambda u^2 + 2|h_z|^2) |dz|^2 + h_{\bar{z}}^2 d\bar{z}^2 \\ &= h_z^2 dz^2 + (\tau_0 + 2|h_z|^2) |dz|^2 + h_{\bar{z}}^2 d\bar{z}^2, \end{aligned}$$

i.e., $\langle dF, dF \rangle = \langle dP, dP \rangle$. Then $F = \Phi \circ P$ for some isometry $\Phi : \mathbb{R}^2 \rightarrow \mathbb{R}^2$. Now, this isometry can be extended to a positive rigid motion Ψ of \mathbb{L}^3 , which may possibly reverse time-orientation. So, we can conclude the existence of some $\varepsilon = \pm 1$ such that $\Psi \circ f_0 = (F, \varepsilon h) =: f$. This concludes the proof of Lemma 11. \square

Once here we can finish the proof of Theorem 1. For that, let us consider $X = (F, t) : \Sigma \rightarrow \text{Nil}_3$ to be an entire minimal graph with Abresch-Rosenberg differential Qdz^2 . First, take its sister $H = 1/2$ immersion $\psi = (N, h) : \Sigma \rightarrow \mathbb{H}^2 \times \mathbb{R}$, which has Abresch-Rosenberg differential $-Qdz^2$, induced metric $\lambda|dz|^2$, angle function u (we shall assume that $u > 0$ without loss of generality), and is defined up to isometries of $\mathbb{H}^2 \times \mathbb{R}$ preserving the orientations of both base and fibers. Let $G : \Sigma \rightarrow \mathbb{H}^2$ denote the (harmonic) hyperbolic Gauss map of one of such sister immersions ψ . Then $X : \Sigma \rightarrow \text{Nil}_3$ will be a canonical example if G differs at most by a rigid motion of \mathbb{L}^3 from the Gauss map $\nu : \Sigma \rightarrow \mathbb{H}^2 \cup \mathbb{H}_-^2 \subset \mathbb{L}^3$ of some complete spacelike surface $f_0 : \Sigma \rightarrow \mathbb{L}^3$ with $H = 1/2$. This is just a consequence of the proper construction of the canonical examples.

But now, by Theorem 5, the hyperbolic Gauss map G admits the Weierstrass data $\{Q, \lambda u^2\}$. This means that there is a unique (up to positive rigid motions) spacelike surface $f_0 : \Sigma \rightarrow \mathbb{L}^3$ with $H = 1/2$, induced metric $\lambda u^2 |dz|^2$ and Hopf differential $Q dz^2$. By composing if necessary with a positive isometry of \mathbb{L}^3 that reverses time-orientation, we can assume that the Gauss map of f_0 is future-pointing. Moreover, it has the Weierstrass data $\{Q, \lambda u^2\}$. Now by [FeMi1, Lemma 6] this Gauss map differs from G at most by a rigid motion.

So, we only need to check that f_0 is complete, i.e., that $\lambda u^2 |dz|^2$ is complete for $X = (F, t) : \Sigma \rightarrow \text{Nil}_3$. By Lemma 11 we know the existence of some spacelike $H = 1/2$ surface $f = (P, r) : \Sigma \rightarrow \mathbb{L}^3$ such that $P = F$. Thus, f is an entire spacelike graph in \mathbb{L}^3 . Now, a result in [ChYa] establishes that all spacelike entire CMC graphs in \mathbb{L}^3 have complete induced metric (here the CMC assumption is essential). In particular f is complete. But again by Lemma 11, the induced metric of f is $\lambda u^2 |dz|^2$. Thus, this metric is complete and X must be a canonical example.

We have then proved:

Theorem 12. *A minimal surface in Nil_3 is an entire vertical graph if and only if it is a canonical example.*

From this result and the description of the canonical examples in Section 2 we obtain Theorem 1. Moreover, as a byproduct of our proof we get the following characterization of the entire minimal graphs in Nil_3 .

Corollary 13. *Let X be a minimal surface in Nil_3 with metric g and angle function u . Then X is an entire graph if and only if $u^2 g$ is a complete Riemannian metric.*

Observe that if $u^2 g$ is a complete metric for an arbitrary surface in any homogeneous space $\mathbb{E}^3(\kappa, \tau)$ (not necessarily with CMC), then the surface must be an entire graph by Lemma 9. However, the converse is not true in general. For instance, the entire graph

$$x_3(x_1, x_2) = x_2 e^{1/(1-x_1^2-x_2^2)}, \quad x_1^2 + x_2^2 < 1,$$

in $\mathbb{H}^2 \times \mathbb{R} \equiv (\mathbb{D}, ds_P^2) \times \mathbb{R}$, has non-complete $u^2 g$ metric. Indeed, it is an elementary computation to check that the divergent curve $\alpha(t) := (t, 0, x_3(t, 0))$, $0 \leq t < 1$, lies on the graph and has finite $u^2 g$ length.

4. SURFACES WITH $H = 1/2$ IN $\mathbb{H}^2 \times \mathbb{R}$ AND FURTHER RESULTS

In view of the results of the present paper and Daniel’s Lawson-type correspondence, it is a natural problem to ask for the classification of the entire vertical graphs with $H = 1/2$ in the product space $\mathbb{H}^2 \times \mathbb{R}$ (see [FeMi1, Sa]). The following result, which constitutes an improvement of [FeMi1, Theorem 16], shows that the class of solutions to such a Bernstein-type problem in $\mathbb{H}^2 \times \mathbb{R}$ is at least as large as the class of entire minimal graphs in Nil_3 .

Proposition 14. *The sister surface of an entire minimal graph in Nil_3 is an entire $H = 1/2$ graph in $\mathbb{H}^2 \times \mathbb{R}$.*

Consequently, given a holomorphic quadratic differential $Q dz^2$ on $\Sigma \equiv \mathbb{C}$ or \mathbb{D} which is not identically zero if $\Sigma \equiv \mathbb{C}$, there exists a 2-parameter family of (generically non-congruent) entire $H = 1/2$ graphs in $\mathbb{H}^2 \times \mathbb{R}$ whose Abresch-Rosenberg differential is $Q dz^2$.

Proof. The proof follows directly from Corollary 13, Lemma 9 and the fact that the metric $\lambda u^2 |dz|^2$ is invariant by the sister correspondence. \square

Remark 15. By Corollary 13, the entire $H = 1/2$ graphs in Proposition 14 are characterized by the fact that u^2g is a complete metric. It is natural to ask if these are the only entire $H = 1/2$ graphs in $\mathbb{H}^2 \times \mathbb{R}$. Unfortunately, we cannot proceed in this setting as we did for minimal graphs in Nil_3 , since we do not have a good control on the vertical projection for $H = 1/2$ surfaces in $\mathbb{H}^2 \times \mathbb{R}$. Let us also point out that the existence of an entire $H = 1/2$ graph in $\mathbb{H}^2 \times \mathbb{R}$ for which u^2g is not complete remains unknown.

Another interesting application of the arguments used in the proof of Theorem 1 is the following.

Corollary 16. *Let $\psi : \Sigma \rightarrow \mathbb{H}^2 \times \mathbb{R}$ denote an $H = 1/2$ surface with regular vertical projection such that its hyperbolic Gauss map $G : \Sigma \rightarrow \mathbb{H}^2$ is a global diffeomorphism. Assume additionally that its Abresch-Rosenberg differential vanishes somewhere. Then ψ is one of the entire graphs given in Proposition 14.*

Proof. By Theorem 5, G has Weierstrass data $\{-Q, \lambda u^2\}$, where Qdz^2 is the Abresch-Rosenberg differential of ψ . Thus

$$\langle dG, dG \rangle = -Qdz^2 + \left(\frac{\lambda u^2}{4} + \frac{4|Q|^2}{\lambda u^2} \right) |dz|^2 - \bar{Q}d\bar{z}^2.$$

If we now compute the eigenvalues $\rho_1 \geq \rho_2$ of $\langle dG, dG \rangle$ with respect to the flat metric $|dz|^2$, we obtain

$$\rho_1 = \frac{\lambda u^2}{4}(1 + d_G)^2, \quad \rho_2 = \frac{\lambda u^2}{4}(1 - d_G)^2, \quad d_G := \frac{4|Q|}{\lambda u^2}.$$

Hence, as $\langle dG, dG \rangle$ is complete by hypothesis, the metric $\rho_1|dz|^2$ is complete. But since $\langle dG, dG \rangle$ is regular, we infer that $4|Q| \neq \lambda u^2$ at every point. So, as Q vanishes somewhere we get $d_G \in [0, 1)$. By this fact and the completeness of $\rho_1|dz|^2$ we conclude that $\lambda u^2|dz|^2$ is a complete metric, and hence by Corollary 13 that ψ is one of the entire graphs of Proposition 14. \square

Remark 17. If $G : \Sigma \rightarrow \mathbb{H}^2$ admits Weierstrass data $\{Q, \tau_0\}$ such that Q never vanishes, then there is a second set of Weierstrass data $\{Q, \tau^\# := 16|Q|^2/\tau_0\}$ available for G . These two sets of data give rise to *parallel-like* $H = 1/2$ surfaces $\psi, \psi^\#$ in $\mathbb{H}^2 \times \mathbb{R}$ with the same hyperbolic Gauss map G (see [FeMi1, Theorem 19]). Under these conditions, we can still say that if G is a global diffeomorphism, then one of $\psi, \psi^\#$ is an entire graph of Proposition 14. This follows by a simple modification of the last part of the above proof.

Remark 18. The existence of harmonic diffeomorphisms from \mathbb{C} onto \mathbb{H}^2 has been recently proved by Collin and Rosenberg in [CoRo].

It is interesting to observe that Corollary 16 has a counterpart for minimal surfaces in Nil_3 . Indeed, in [Dan2] Daniel gave an extension to the case of minimal surfaces in Nil_3 of the harmonicity theory for the hyperbolic Gauss map of $H = 1/2$ surfaces in $\mathbb{H}^2 \times \mathbb{R}$. In this Nil_3 setting, the harmonic Gauss map is simply the usual Gauss map of a surface with regular vertical projection (taking values on the upper hemisphere of the Lie algebra of Nil_3), composed with stereographic projection. This gives a Gauss map $g : \Sigma \rightarrow \mathbb{D}$ which is harmonic for minimal surfaces when we endow \mathbb{D} with the Poincaré metric. See [Dan2] for more details.

Taking these facts into consideration, one can see that the proof of Corollary 16 also works in Nil_3 , and so we obtain:

Corollary 19. *Let $X : \Sigma \rightarrow \text{Nil}_3$ denote a minimal surface with regular vertical projection, and whose Abresch-Rosenberg differential vanishes somewhere. Assume that its usual Gauss map is a global diffeomorphism onto the upper hemisphere \mathbb{S}_+^2 . Then X is a canonical example.*

We end with two closing remarks regarding our results. The study of the Bernstein problem in Nil_3 presented here makes constant use of the theory of $H = 1/2$ surfaces in $\mathbb{H}^2 \times \mathbb{R}$, for instance, for the construction of the canonical examples. It is nonetheless very likely that our arguments can be modified in certain aspects to give an alternative proof of Theorem 1 without using $\mathbb{H}^2 \times \mathbb{R}$ at all. This possibility is given by the harmonicity of the Gauss map for minimal surfaces in Nil_3 [Dan2]. We have followed here the path across $\mathbb{H}^2 \times \mathbb{R}$ to give a natural continuation of the work [FeMi1], which is where the canonical examples were first constructed, and also because we believe that this more flexible perspective may give a clearer global picture of CMC surface theory in homogeneous 3-manifolds. Lemma 11 is an example of the benefits that this perspective can have.

Let us finally point out that there are still relevant problems regarding the global geometry of entire minimal graphs in Nil_3 . For instance, the problem of describing the global behavior of canonical examples in Nil_3 is especially interesting. Another interesting inquiry line is to give concrete geometric conditions that characterize the horizontal umbrellas or the saddle-type minimal graphs among all canonical examples (let us point out that these minimal surfaces are the only examples invariant by a 1-parameter isometry subgroup).

Added after revision. Very recently, L. Hauswirth, H. Rosenberg and J. Spruck [HRS] have proved that any complete local graph with mean curvature one half in $\mathbb{H}^2 \times \mathbb{R}$ must be an entire graph. After that work, the analogous result for minimal surfaces in Nil_3 was proved by B. Daniel and L. Hauswirth [DaHa].

As a consequence, it was obtained in [DaHa] that any entire graph with $H = 1/2$ in $\mathbb{H}^2 \times \mathbb{R}$ must be the sister surface of a canonical example in Nil_3 . This result gives a classification of the entire $H = 1/2$ graphs in $\mathbb{H}^2 \times \mathbb{R}$, proving that any such entire graph is one of the examples given in Proposition 14.

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